Domain walls in neutron ³ *P***² superfluids in neutron stars**

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We work out domain walls in neutron ${}^{3}P_2$ superfluids realized in the core of neutron stars. Adopting the Ginzburg-Landau (GL) theory as a bosonic low-energy effective theory, we consider configurations of domain walls interpolating ground states, i.e., the uniaxial nematic (UN), D_2 -biaxial nematic (D_2 -BN), and D_4 -biaxial nematic (D4-BN) phases in the presence of zero, small and large magnetic fields, respectively. We solve the Euler-Lagrange equation from the GL free energy density, and calculate surface energy densities of the domain walls. We find that one extra Nambu-Goldstone mode is localized in the vicinity of a domain wall in the UN phase while a $U(1)$ symmetry restores in the vicinity of one type of domain wall in the D_2 -BN phase and all domain walls in the D_4 -BN phase. Considering a pile of domain walls in the neutron stars, we find that the most stable configurations are domain walls perpendicular to the magnetic fields piled up in the direction along the magnetic fields in the D_2 -BN and D_4 -BN phases. We estimate the energy released from the deconstruction of the domain walls in the edge of a neutron star, and show that it can reach an astrophysical scale such as glitches in neutron stars.

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I. INTRODUCTION

Domain walls or kinks are solitonic objects separating two discrete vacua or ground states of a system $[1-3]$ and play important roles in various subjects of physics from condensed matter physics [\[4\]](#page-18-0) to cosmology [\[5\]](#page-18-0) and supersymmetric field theories $[6]$. They are often created in phase transitions associated with symmetry breakings [\[7\]](#page-18-0). In cosmology, if they appear at a phase transition in the early Universe, then the so-called domain wall problem occurs [\[5\]](#page-18-0): The domain wall energy dominates Universe to make it collapse. In helium superfluids, such domain walls are created in a similar manner, thereby simulating cosmological phase transitions [\[8\]](#page-18-0). Here we focus on domain walls in neutron stars, more precisely those in nuclear matter.

Neutron stars are compact stars under extreme conditions, thereby serving as astrophysical laboratories for studying nuclear matter at high density, under rapid rotation and with a strong magnetic field (see Refs. $[9,10]$ for recent reviews). The recent progresses in astrophysical observations promote us to study the neutron stars more precisely, such as the recent reports on massive neutron stars whose masses are almost twice as large as the solar mass $[11,12]$ and the gravitational waves from a binary neutron star merger [\[13\]](#page-18-0).

Inside neutron stars, one of the most important key ingredients for understanding the inner structure is neutron superfluidity and proton superconductivity (see Refs. [\[14–16\]](#page-18-0) for recent reviews). Since the superfluid and superconducting components can alter excitation modes at low energy from the normal phase, their existence can affect several properties in neutron stars, such as neutrino emissivities and specific heats relevant to the long relaxation time after in the sudden speed-up events (glitches) of neutron stars [\[17–19\]](#page-18-0), and the enhancement of neutrino emission around the critical point of the superfluid transition $[20-25]$. Glitches in pulsars may also be explained by quantized vortices in superfluids [\[26,27\]](#page-18-0). The neutron superfluids are realized by the attraction between two neutrons at the low density in the ${}^{1}S_{0}$ channel. This channel becomes, however, repulsive in the high-density regime.¹ Instead, at higher density, neutron ${}^{3}P_{2}$ superfluids, in which neutron pairs possess the total angular momentum $J = 2$ with spin-triplet and *P* wave, become more relevant $[30-47]$ ². The 3 *P*² interaction originates from a strong spin-orbit (*LS*) force at large scattering energy, and thus the neutron ${}^{3}P_{2}$ superfluids are expected to be realized in the high-density regions in the inner cores of neutron stars. The neutron ${}^{3}P_{2}$ superfluids can survive in the neutron stars with strong magnetic fields, such as in the magnetars with the magnetic field 10^{15} – 10^{18} G, because the spin $\uparrow \uparrow$ or $\downarrow \downarrow$ pairs in the spin-triplet pairing cannot be broken by the Zeeman effects and hence the neutron $3P_2$ superfluids are tolerant against the strong magnetic field.³ The possible existence of neutron ${}^{3}P_{2}$ superfluids inside

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¹Although the ${}^{1}S_0$ superfluidity at low density was proposed in Ref. [\[28\]](#page-18-0), it was shown in Ref. [\[29\]](#page-18-0) that this channel turns to be repulsive due to the strong short-range repulsion at higher densities.

²It is noted that the interaction in the ³ P_0 and ³ P_1 channels are repulsive at high density, and hence they are irrelevant to the formation of superfluidity [\[48\]](#page-18-0).

³The origin of the strong magnetic fields in neutrons stars or in magnetars is still an open problem although there are many theoretical works: spin-dependent interactions [\[49–52\]](#page-18-0), pion domain walls [\[53,54\]](#page-18-0), spin polarizations in quark-matter in the neutron star

the neutron stars are pursued in astrophysical observations. It has been recently pointed out that the rapid cooling of the neutron star in Cassiopeia A may be explained by the enhancement of neutrino emissivities which is caused by the formation and dissociation of neutron ${}^{3}P_{2}$ Cooper pairs [\[23–25\]](#page-18-0). In the theoretical studies, it is known that neutron $3P_2$ superfluids have rich structures in the condensates due to a variety of combinations of spin-triplet and *P*-wave angular momentum in the Cooper pairs. The superfluid states with $J = 2$ are classified into nematic, cyclic, and ferromagnetic phases [\[59\]](#page-18-0), among which the nematic phase is the ground state in the weak coupling limit of ${}^{3}P_{2}$ superfluids [\[35,36,60–](#page-18-0) [65\]](#page-18-0). The nematic phase is continuously degenerated and consists of the three subphases: the uniaxial nematic (UN) and dihedral-two and dihedral-four biaxial nematic (D_2-BN) and D4-BN) phases according to the continuous/discrete symmetries of the ${}^{3}P_{2}$ order parameter: the U(1) symmetry in the UN phase and the D_2 and D_4 symmetries in the D_2 -BN and D_4 -BN phases, respectively.4

In terms of fermion dynamics, all these phases are accompanied by the Bogoliubov quasiparticles. The phase diagram on the plane spanned by the temperature and the magnetic field was drawn by solving the Bogoliubov de-Gennes (BdG) equation self-consistently with the Fermi liquid corrections, and it was shown that the UN phase exists at zero magnetic field, and the D_2 -BN and D_4 -BN phases appear in the weak and strong magnetic fields, respectively [\[68\]](#page-19-0). There are the first- and second-order transitions at the boundary between the D_2 -BN and D_4 -BN phases, and those two transitions meet at the (tri)critical endpoint (CEP). The existence of the CEP is important because the fluctuations can significantly affect the thermodynamical properties and the transport coefficients in neutron stars. The Bogoliubov quasiparticles in neutron ${}^{3}P_{2}$ superfluids are protected topologically against the perturbation. In terms of the general classifications, the nematic phase in the neutron ${}^{3}P_{2}$ superfluids is a class-DIII topological superconductor in the periodic table, inducing Majorana fermions on the edge of the superfluids [\[68\]](#page-19-0). The cyclic and ferromagnetic phases are nonunitary states, in which the time-reversal symmetry is broken, and they serve to host Weyl fermions in the bulk [\[68,69\]](#page-19-0).

The ${}^{3}P_2$ superfluids allow also bosonic excitations as collective modes [\[70–82\]](#page-19-0), which are considered to be relevant to cooling process by neutrino emissions from neutron stars.⁵ Bosonic excitations can be best discussed in terms of the Ginzburg-Landau (GL) theory as a bosonic effective theory around the critical point from the normal phase to the superfluid phase [\[35,36,60–67](#page-18-0)[,84–86\]](#page-19-0). The GL equation can be obtained by a systematic expansion of the functional with respect to the order parameter field and magnetic field, where the fermionic degrees of freedom are integrated out. We notice that, in the GL expansion up to the fourth order in terms of the order parameter, the ground state cannot be determined uniquely, because there exists a continuous degeneracy among the UN, D_2 -BN, and D_4 -BN phases.⁶ Instead, the ground state is determined uniquely in the GL expansion up to the sixth order [\[64\]](#page-18-0). However this is still not sufficient for the expansion order, because it is stable only locally and there exists the instability for a large value of the order parameter in the variational calculation. It was found recently that the eighth-order terms of the condensates ensure the stability of the ground state $[66]$. As a by-product, it was also shown that the eighth-order terms in the GL equation induce the CEP in the phase diagram, although the position of the CEP in the GL theory is different from that in the BdG equation [\[68\]](#page-19-0). With the GL expansion in Ref. [\[66\]](#page-18-0), we can adopt the GL equation to investigate the position dependence of the order parameter in the nonuniform system, and topological defects can be discussed. So far, the theoretical studies have been conducted in depth: spontaneously magnetized vortices [\[35,61,62,64\]](#page-18-0), solitonic excitations on a vortex [\[84\]](#page-19-0), and half-quantized non-Abelian vortices [\[65\]](#page-18-0) and topological defects on the boundary of ${}^{3}P_{2}$ superfluids [\[67\]](#page-18-0). Interestingly, the topological states in the ${}^{3}P_{2}$ share common properties in the condensed matter systems, such as *D*-wave superconductors $[59]$, *P*-wave superfluidity in ³He liquid [\[4,](#page-18-0)[88\]](#page-19-0), chiral *P*-wave superconductivity, e.g., in $Sr₂RuO₄$ [\[89\]](#page-19-0), spin-2 Bose-Einstein condensates [\[90\]](#page-19-0), and so on. For instance, topological defects on the boundary of the spin-2 Bose-Einstein condensate have been discussed [\[91\]](#page-19-0), as similar to those in ${}^{3}P_2$ superfluids in Ref. [\[67\]](#page-18-0).⁷

In the present study, we consider domain walls, i.e., kinks or one-dimensional solitons, which connect two different vacua in the bulk phase in the neutron ${}^{3}P_{2}$ superfluids. They are also called textures in analogy to those in crystal liquids, because the order parameter changes not only in the amplitude but also in the *directions* [\[92,93\]](#page-19-0). In the case of $3P_2$, orientations of domain walls are supplied by the spin and the angular momentum. They can be created via a phase transition and stay as quasistable states when the lifetime is longer than the typical timescale in the systems. 8 In the literature, the studies of domain walls have been extensively accomplished in the 3 He superfluidity $[94-98]$ (see also Refs. $[4,88]$ $[4,88]$ and the references therein).⁹ In analogy to the

core [\[55–57\]](#page-18-0), and so on. It may be worthwhile to mention that a negative result for the generation of strong magnetic fields was recently announced in a study in terms of the nuclear many-body calculations [\[58\]](#page-18-0).

 4 See, e.g., Appendix B in Refs. $[66, 67]$ for more information on the definitions of the UN, D_2 -BN, and D_4 -BN phases.

⁵It is discussed that the cooling process is related not only to lowenergy excitation modes but also to quantum vortices [\[83\]](#page-19-0).

 6 At the fourth order, there happens to exist an SO(5) symmetry in the potential term. This is an extended symmetry, which is absent in the original Hamiltonian. It is known that, in this case, the spontaneous breaking eventually generate a quasi-Nambu-Goldstone (NG) modes. However, such NG modes should be regarded as being irrelevant to the excitations in the true ground state [\[87\]](#page-19-0). This is nothing but the origin of the continuous degeneracy.

⁷See Ref. [\[92\]](#page-19-0) as a recent review for the topological defects in the boundary in liquid crystals.

⁸If the configurations of the solitons are protected topologically, then they keep to be the stable states against perturbation.

 9 The domain walls in in the 3 He superfluidity were called also the composite soliton instead of textures in Refs. [\[94–97\]](#page-19-0).

³He superfluids, we can expect that domain walls exist also in the neutron ${}^{3}P_{2}$ superfluids, because there are degenerate vacua which are separated by a barrier potential. Because the domain walls are the excited states which do not appear in the ground state, the domain walls can be produced through defect formations at a phase transition [\[7,8\]](#page-18-0). By adopting the GL theory, we consider domain walls in the bulk UN, D_2 -BN, and D_4 -BN phases in the zero, weak, and strong magnetic fields, respectively. We obtain the spatial configurations of the domain walls by solving the Euler-Lagrange (EL) equation from the GL effective potential. With those solutions, we estimate the energy of domain walls, i.e., the surface energy density, for supposing several different configurations and directions. We show that the domain wall configurations pass thorough different phases, and unbroken symmetries inside the domain walls are different from those in the bulk. As a result, for instance, one Nambu-Goldstone mode is trapped inside the domain wall in the bulk UN phase. We also find that the domain walls piled along the magnetic fields are more stable than those in the other directions. Such domain walls are likely to exist as quasistable states in the neutron stars. As a simple situation, we consider that a pile of domain walls may be deconstructed by moving to the north or south pole of the neutron star, and in the end they can release huge energy which can be detectable in the astrophysical observations.

The paper is organized as the followings. In Sec. II, we introduce the GL equation as the low-energy effective theory of the neutron ${}^{3}P_{2}$ superfluids and show the EL equations for describing the domain walls. In Sec. [III,](#page-5-0) we show the numerical results of the configurations of the domain walls in the one-dimensional directions for solving the EL equations by adopting appropriate boundary conditions. We also estimate the surface energy density for each domain wall and show that the domain walls piled along the magnetic field exist at the most stable states. In Sec. [IV,](#page-10-0) we will consider the situation that a pile of domain walls exist in the neutron stars, and they can release a huge energy as the astrophysical phenomena. The final section is devoted to our conclusion. In Appendix [A,](#page-13-0) we present the explicit forms of the EL equations for the domain walls. In Appendix B , we show the numerical results of the configurations of the domain walls.

II. FORMALISM

A. Ginzburg-Landau equation

The condensate of the neutron ${}^{3}P_{2}$ superfluidity can be expressed by a symmetric and traceless three-by-three-

dimensional tensor *A* as an order parameter which triggers the symmetry breaking. The components of *A* are denoted by A^{ab} with the indices $a = 1, 2, 3$ for the spin and $b = 1$, 2, 3 for three-dimensional momentum degrees of freedom. The GL theory is introduced by integrating out the neutron degrees of freedom as a loop expansion, supposing the small coupling strength in the ${}^{3}P_2$ interaction for two neutrons [\[35,36,60–66,](#page-18-0)[85\]](#page-19-0). The GL equation is valid in the region in which the temperature T is close to the critical temperature T_{c0} , $|1 - T/T_{c0}| \ll 1$, where the value of T_{c0} is determined at zero magnetic field. The concrete form of the GL free energy reads

$$
f[A] = f_0 + f_{\text{grad}}[A] + f_8^{(0)}[A] + f_2^{(\le 4)}[A] + f_4^{(\le 2)}[A] + \mathcal{O}(B^m A^n)_{m+n \ge 7},
$$
 (1)

as an expansion in terms of the condensate *A* and the magnetic field *B* with the magnitude $B = |B|$. Each term is explained as follows. The first term f_0 is the sum of the free part and the spin-magnetic coupling term, given by

$$
f_0 = -T \int \frac{d^3 \mathbf{p}}{(2\pi)^3} \ln[(1 + e^{-\xi_p^{-}/T})(1 + e^{-\xi_p^{+}/T})], \quad (2)
$$

with $\xi_p^{\pm} = \xi_p \pm |\mu_n||B|$ and $\xi_p = p^2/(2m) - \mu$ for the neutron three-dimensional momentum *p*, the neutron mass *m* and the neutron chemical potential μ . The bare magnetic moment of a neutron is $\mu_n = -(\gamma_n/2)\sigma$ with the gyromagnetic ratio $\gamma_n = 1.2 \times 10^{-13}$ MeV/T (in natural units, $\hbar = c = 1$) and the Pauli matrices for the neutron spin *σ*. The following terms include the condensate A : $f_{\text{grad}}[A]$ is the gradient term, $f_8^{(0)}[A]$ consists of the terms including the field *A* up to the eighth order with no magnetic field, $f_2^{(\leq 4)}[A]$ consists of the terms including the field *A* up to the second order with the magnetic field up to $|\mathbf{B}|^4$, and $f_4^{(\leq 2)}[A]$ consists of the terms including the field *A* up to the fourth order with the magnetic field up to $|\mathbf{B}|^2$. Their explicit expression can be given as follows:

$$
f_{\text{grad}}[A] = K^{(0)} \sum_{a,i,j=1}^{3} (\nabla_i A^{ja*} \nabla_i A^{aj} + \nabla_i A^{ia*} \nabla_j A^{aj}
$$

$$
+ \nabla_i A^{ja*} \nabla_j A^{ai}), \qquad (3)
$$

for the gradient term and

$$
f_8^{(0)}[A] = \alpha^{(0)}(\text{tr}A^*A) + \beta^{(0)}[(\text{tr}A^*A)^2 - (\text{tr}A^{*2}A^2]) + \gamma^{(0)}[-3(\text{tr}A^*A)(\text{tr}A^2)(\text{tr}A^{*2}) + 4(\text{tr}A^*A)^3 + 6(\text{tr}A^*A)(\text{tr}A^{*2}A^2)
$$

+ 12(\text{tr}A^*A)(\text{tr}A^*AA^*A) - 6(\text{tr}A^{*2})(\text{tr}A^*A^3) - 6(\text{tr}A^2)(\text{tr}A^{*3}A) - 12(\text{tr}A^{*3}A^3) + 12(\text{tr}A^{*2}A^2A^*A)
+ 8(\text{tr}A^*AA^*AA^*A)] + \delta^{(0)}[(\text{tr}A^{*2})^2(\text{tr}A^2)^2 + 2(\text{tr}A^{*2})^2(\text{tr}A^4) - 8(\text{tr}A^{*2})(\text{tr}A^*AA^*A)(\text{tr}A^2)
- 8(\text{tr}A^{*2})(\text{tr}A^*A)^2(\text{tr}A^2) - 32(\text{tr}A^{*2})(\text{tr}A^*A)(\text{tr}A^*A^3) - 32(\text{tr}A^{*2})(\text{tr}A^*AA^*A^3) - 16(\text{tr}A^{*2})(\text{tr}A^*A^2A^*A^2)
+ 2(\text{tr}A^{*4})(\text{tr}A^2)^2 + 4(\text{tr}A^{*4})(\text{tr}A^4) - 32(\text{tr}A^{*3}A)(\text{tr}A^*A)(\text{tr}A^2) - 64(\text{tr}A^{*3}A)(\text{tr}A^*A^3) - 32(\text{tr}A^{*3}A^*A)(\text{tr}A^2)
- 64(\text{tr}A^{*3}A^2A^*A^2) - 64(\text{tr}A^{*3}A^3)(\text{tr}A^*A) - 64(\text{tr}A^{*2}AA^*A^2A^3) - 64(\text{tr}A^{*2}AA^*A^2)(\text{tr}A^*A) + 16(\text{

+ 48(tr *A*∗*A*) 2(tr *^A*∗*AA*∗*A*) ⁺ 192(tr *^A*∗*A*)(tr *^A*∗*AA*∗² *^A*²) ⁺ 64(tr *^A*∗*A*)(tr *^A*∗*AA*∗*AA*∗*A*) [−] 128(tr *^A*∗*AA*∗³ *^A*³) ⁺ 64(tr *^A*∗*AA*∗² *AA*∗*A*²) ⁺ 24(tr *^A*∗*AA*∗*A*) ² ⁺ 128(tr *^A*∗*AA*∗*AA*∗² *^A*²) ⁺ 48(tr *^A*∗*AA*∗*AA*∗*AA*∗*A*)], *F*(-4) ² [*A*] ⁼ ^β(2)*B^t ^A*∗*A^B* ⁺ ^β(4)|*B*[|] 2 *Bt A*∗*AB*, *f* (-2) ⁴ [*A*] ⁼ ^γ (2)[−² [|]*B*[|] 2(tr *^A*²)(tr *^A*∗²) [−] ⁴ [|]*B*[|] 2(tr *A*∗*A*) ² ⁺ ⁴ [|]*B*[|] 2(tr *^A*∗*AA*∗*A*) ⁺ ⁸ [|]*B*[|] 2(tr *A*∗² *^A*²) ⁺ *^B^t A*2 *B*(tr *A*∗²) [−] ⁸*B^t ^A*∗*AB*(tr *^A*∗*A*) ⁺ *^B^t A*∗² *^B*(tr *^A*²) ⁺ ² *^B^t AA*∗² *^A^B* ⁺ ² *^B^t A*∗*A*² *^A*∗*^B* [−] ⁸*B^t ^A*∗*AA*∗*A^B* [−] ⁸*B^t A*∗² *A*2 *B*], (4)

for the potential and interaction terms. The trace (tr) is taken over the indices of spin and three-dimensional momentum in *A*. The coefficients are given by

$$
K^{(0)} = \frac{7 \zeta (3) N(0) p_T^4}{240 m^2 (\pi T_{c0})^2},
$$

\n
$$
\alpha^{(0)} = \frac{N(0) p_F^2 T - T_{c0}}{3} ,
$$

\n
$$
\beta^{(0)} = \frac{7 \zeta (3) N(0) p_F^4}{60 (\pi T_{c0})^2},
$$

\n
$$
\gamma^{(0)} = -\frac{31 \zeta (5) N(0) p_F^6}{13440 (\pi T_{c0})^4},
$$

\n
$$
\delta^{(0)} = \frac{127 \zeta (7) N(0) p_F^8}{387072 (\pi T_{c0})^6},
$$

\n
$$
\beta^{(2)} = \frac{7 \zeta (3) N(0) p_F^2 \gamma_n^2}{48(1 + F_0^{\alpha})^2 (\pi T_{c0})^2},
$$

\n
$$
\beta^{(4)} = -\frac{31 \zeta (5) N(0) p_F^2 \gamma_n^4}{768(1 + F_0^{\alpha})^4 (\pi T_{c0})^4},
$$

\n
$$
\gamma^{(2)} = \frac{31 \zeta (5) N(0) p_F^4 \gamma_n^2}{3840(1 + F_0^{\alpha})^2 (\pi T_{c0})^4}.
$$

\n(5)

We denote $N(0) = m p_F/(2\pi^2)$ for the state-number density at the Fermi surface and $|\mu_n^*| = (\gamma_n/2)/(1 + F_0^a)$ for the magnitude of the magnetic momentum of a neutron modified by the Landau parameter F_0^a .¹⁰ Notice that μ_n^* is different from the bare magnetic moment of the neutron μ_n due to the Fermi-liquid correction. We notice that the Landau parameter stems from the Hartree-Fock approximation which are not taken into account explicitly in the present mean-field approximation. Finally, in all the expressions, $\zeta(n)$ is the zeta function.

We comment the physical meanings of each term in Eq. (4) . The $\alpha^{(0)}$ term is the leading order, and the $\beta^{(0)}$ term is the nextto-leading order. However, those terms are not sufficient to determine uniquely the ground state, because the free energies in the UN, D_2 -BN, and D_4 -BN phases are degenerate at this order. The degeneracy is resolved by the $\gamma^{(0)}$ term which leads to only the local stability of the ground state, but the global stability is lost at this order. Finally, the global stability is restored by the $\delta^{(0)}$ term which was recently calculated in Ref. [\[66\]](#page-18-0). Therefore, the eighth order is minimally required to have the globally stable and unique ground state. Concerning the magnetic field, the $\beta^{(2)}$ term is the leading order, and the $\beta^{(4)}$ and $\gamma^{(2)}$ terms are the higher-order corrections. The effect of the latter terms was examined for investigating the phase diagrams in strong magnetic fields in magnetars, and it was shown that those terms supply the change of the transition line in the phase diagram by a few percentages at most [\[85\]](#page-19-0).

B. Euler-Lagrange equation of domain walls

We consider domain walls as nonuniform solutions in the GL equation. The domain wall is an extended object in the two-dimensional space, and it is regarded as a onedimensional solution, i.e., a kink along the direction perpendicular to the plane of the domain wall. We assume that the geometrical shape of the surface is flat by neglecting the curvature of the domain walls. For the direction of the domain wall, we denote the normal vector perpendicular to the surface: $\mathbf{n} = (x_1, x_2, x_3) / |\mathbf{x}| = (n_1, n_2, n_3)$ with the coordinate $\mathbf{x} = (x_1, x_2, x_3)$ as shown in Fig. [1.](#page-4-0) We use a polarangle parametrization $n_1 = \sin \theta \cos \varphi$, $n_2 = \sin \theta \sin \varphi$, and $n_3 = \cos \theta$ with the angles θ and φ . We also introduce the coordinate $d(-\infty < d < \infty)$ in the direction along *n* perpendicular to the domain wall.¹¹ Then the condensate *A* can be expressed by a matrix whose components are functions of *d* and *n*:

$$
A(d; \mathbf{n}) = \begin{bmatrix} -F_1(d; \mathbf{n}) & G_3(d; \mathbf{n}) & G_2(d; \mathbf{n}) \\ G_3(d; \mathbf{n}) & -F_2(d; \mathbf{n}) & G_1(d; \mathbf{n}) \\ G_2(d; \mathbf{n}) & G_1(d; \mathbf{n}) & F_1(d; \mathbf{n}) + F_2(d; \mathbf{n}) \end{bmatrix},
$$
\n(6)

where $F_\alpha(d; \mathbf{n})$ ($\alpha = 1, 2$) are the diagonal components and $G_{\beta}(d; \mathbf{n})$ ($\beta = 1, 2, 3$) are off-diagonal components with $F_{\alpha}(d; \mathbf{n})$ and $G_{\beta}(d; \mathbf{n})$ being complex numbers in general. We consider that static domain walls, neglecting the dynamical fluctuation on the surface. Thus, we regard that *d* is only the coordinate on which the configurations in *A* depend and that the angles θ and φ are simply the external parameters for fixing the direction of the domain wall. In the following discussion, setting *n* as a constant vector, we will investigate the angles which are favored to minimize the energy of the domain walls, for which the magnetic field is applied to the *x*² direction. For the short expression, instead of the above notations, we will use the simpler notations $A(d) = A(d; n)$,

¹⁰The interaction Hamiltonian between the neutron and the magnetic field (*B*) is modified to $-\mu_n^* \cdot B$.

 11 It should be noticed that d defined in the present discussion is different from *d* used in the previous study [\[67\]](#page-18-0).

FIG. 1. The directions of the domain walls W_i^{α} (*i* = 1, 2, 3) for several types $\alpha = 1, 2, 3$, and 13 are displayed. Left: W_1^{α} (x_1 direction). Middle: W_2^{α} (x_2 direction). Right: W_3^{α} (x_3 direction). The corresponding polar angles (θ , φ) are shown. The magnetic field is applied along the x_2 direction.

 F_α (*d*) = F_α (*d*; *n*), and G_β (*d*) = G_β (*d*; *n*) by omitting the normal vector n . With the above setup, we express the gradient terms in Eq. (3) as

$$
f_{\text{grad}}[A] = \frac{K^{(0)}}{4} [(2 - \sin^2 \theta \sin^2 \varphi)(\nabla_d F_1)^2
$$

+ $(2 - \sin^2 \theta \cos^2 \varphi)(\nabla_d F_2)^2$
+ $(1 + 2 \cos^2 \theta)(\nabla_d F_1)(\nabla_d F_2)$
+ $2 \cos \theta \sin \theta \sin \varphi (\nabla_d F_1)(\nabla_d G_1)$
+ $2 \cos \theta \sin \theta \cos \varphi (\nabla_d F_2)(\nabla_d G_2)$
- $2 \sin^2 \theta \cos \varphi \sin \varphi (\nabla_d F_1 + \nabla_d F_2)(\nabla_d G_3)$
+ $(2 - \sin^2 \theta \cos^2 \varphi)(\nabla_d G_1)^2$
+ $(2 - \sin^2 \theta \sin^2 \varphi)(\nabla_d G_2)^2 + (1 + \sin^2 \theta)(\nabla_d G_3)^2$
+ $2 \sin^2 \theta \cos \varphi \sin \varphi (\nabla_d G_1)(\nabla_d G_2)$
+ $2 \cos \theta \sin \theta (\cos \varphi \nabla_d G_1 + \sin \varphi \nabla_d G_2)\nabla_d G_3], (7)$

with $\nabla_d = \partial/\partial d$. We notice that the derivatives with respect to θ and φ are absent because \boldsymbol{n} is a constant vector. By adopting the stationary condition with respect to $F_\alpha(d)$ and $G_\beta(d)$ in Eq. (1) together with Eq. (7) , we then obtain the EL equations for *A*,

$$
-\nabla_d \frac{\delta f[A]}{\delta(\nabla_d F_\alpha)} + \frac{\delta f[A]}{\delta F_\alpha} = 0,\tag{8}
$$

$$
-\nabla_d \frac{\delta f[A]}{\delta(\nabla_d G_\beta)} + \frac{\delta f[A]}{\delta G_\beta} = 0,\tag{9}
$$

which provide the solutions of the domain walls.¹² As for the boundary condition for Eqs. (8) and (9) , we require that the domain wall approaches the bulk state at $d \to \pm \infty$. This means that the condensate values in *A* should satisfy $F_{\alpha}(d) \to F_{\alpha}^{\text{bulk}}$ and $G_{\beta}(d) \to 0$, where F_{α}^{bulk} are the values in the ground state in the bulk space. We will consider that the values F_{α}^{bulk} for $d \to \infty$ are not necessarily the same as those for $d \rightarrow -\infty$, because the domain walls are supposed to connect degenerate vacua that are considered to be different to each other.

In the following discussion, we restrict the configuration in the order parameter (6) to the diagonal form by setting the offdiagonal components to be zero.¹³ In this setting, we introduce the dimensionless forms by expressing the order parameter $A(d)$ by

$$
A(d) = \frac{T_{c0}}{p_F} \tilde{A}(\tilde{d}),\tag{10}
$$

with $\tilde{A}(\tilde{d})$ is the dimensionless function parametrized by

$$
\tilde{A}(\tilde{d}) = \begin{bmatrix} -f_1(\tilde{d}) & 0 & 0 \\ 0 & -f_2(\tilde{d}) & 0 \\ 0 & 0 & f_1(\tilde{d}) + f_2(\tilde{d}) \end{bmatrix}
$$

$$
= \begin{bmatrix} -f_1(\tilde{d}) & 0 & 0 \\ 0 & -f_2(\tilde{d}) & 0 \\ 0 & 0 & -f_3(\tilde{d}) \end{bmatrix}, \qquad (11)
$$

with $d = [p_F/(mT_{c0})]\tilde{d}$ for the dimensionless coordinate \tilde{d} $(-\infty < \tilde{d} < \infty)$. *f_i*(\tilde{d}) (*i* = 1, 2) is related to *F_i*(*d*) through $F_i(d) = (T_{c0}/p_F) f_i(\tilde{d})$. In the last equation in Eq. (11), we have introduced $f_3(\tilde{d}) = -f_1(\tilde{d}) - f_2(\tilde{d})$ for convenience of the calculation. Furthermore, we parametrize $f_i(\tilde{d})$ (*i* = 1, 2, 3) by

$$
f_1(\tilde{d}) = \left(\frac{\cos\phi(\tilde{d})}{\sqrt{2}} - \frac{\sin\phi(\tilde{d})}{\sqrt{6}}\right) f_0(\tilde{d}),
$$

\n
$$
f_2(\tilde{d}) = \sqrt{\frac{2}{3}} [\sin\phi(\tilde{d})] f_0(\tilde{d}),
$$

\n
$$
f_3(\tilde{d}) = \left[-\frac{\cos\phi(\tilde{d})}{\sqrt{2}} - \frac{\sin\phi(\tilde{d})}{\sqrt{6}} \right] f_0(\tilde{d}),
$$
\n(12)

¹²The concrete expressions of the left-hand sides are presented in detail in Appendix [A.](#page-13-0)

¹³We call an attention to the assumption that the off-diagonal components are set to be zero in the present analysis. In this case, the two different degenerate vacua can be distinguished. However, those two degenerate states can be connected by a symmetry transformation once the off-diagonal components are taken into account. See more discussions below.

where $f_0(\tilde{d})$ and $\phi(\tilde{d})$ are introduced for the *amplitude* and the *angle* as functions of \tilde{d} (for a fixed *n*) as a new parametrization of the condensate *A*. The range of the values are constrained to $f_0(\tilde{d}) \geq 0$ and $-\pi \leq \phi(\tilde{d}) \leq \pi$. In the following discussions, we will use either the three-dimensional vector $f(d) \equiv$ $(f_1(\tilde{d}), f_2(\tilde{d}), f_3(\tilde{d}))$ or the polar parametrization $f_0(\tilde{d})$ and $\phi(\vec{d})$ to express the order parameter *A*. We also introduce the dimensionless forms:

$$
f[A] = N(0)T_{c0}^{2} \tilde{f}[\tilde{A}], \quad x_{i} = \frac{p_{F}}{mT_{c0}} \tilde{x}_{i} \quad (i = 1, 2, 3),
$$

$$
t = \frac{T}{T_{c0}}, \quad \mathbf{B} = \frac{(1 + F_{0}^{a})T_{c0}}{\gamma_{n}} \mathbf{b}, \tag{13}
$$

for the thermodynamical potential, the coordinate in the real space, the temperature, and the magnetic field, respectively.

Before going to numerics, let us emphasize that the domain walls that we are considering are described only by the diagonal components in $A(d; n)$. Because of this restriction, configuration may be unstable or metastable in the full analysis including of the off-diagonal components. See Sec. [IV](#page-10-0) for a discussion in more detail.

III. NUMERICAL RESULTS

First, we present the UN, D_2 -BN, and D_4 -BN phases in the phase diagram in the bulk space. In the next, with noting that there exist several minima in the effective potential in each phase, we give the definitions of the domain walls connecting the different minima. Finally, we show the solution of the configurations of the domain walls, estimate their surface energy density, and discuss that multiple domain walls which are piled along the magnetic field can stably exist.

A. Phase diagram in bulk space

In the bulk space, the order parameter [\(6\)](#page-3-0) can be diagonalized as

$$
A \to U_{\text{diag}} A U_{\text{diag}}^{-1} = A_0 \begin{pmatrix} r & 0 & 0 \\ 0 & -1 - r & 0 \\ 0 & 0 & 1 \end{pmatrix}, \qquad (14)
$$

with an appropriate symmetry transformation U_{diag} of U(1) \times SO(3), where $A_0 \ge 0$ is the amplitude and *r* is a real parameter which can be restricted to $-1 \le r \le -1/2$ without loss of generality by the $U(1) \times SO(3)$ symmetry. The different values of *r* induce the different symmetries in the ground state: the UN phase for $r = -1/2$, the D₂-BN phase for $-1 <$ $r < -1/2$, and the D₄-BN phase for $r = -1$. Substituting Eq. (14) into Eq. (1) , we perform the variational calculation with respect A_0 and r and obtain the phase diagram as shown in Fig. 2. Roughly, there exist the UN phase at zero magnetic field, the D_2 -BN at weak magnetic field, and D_4 -BN phases at strong magnetic field. 14

FIG. 2. We show the phase diagram on the plane spanned by the dimensionless temperature *t* and the dimensionless magnetic field *b*. We will consider the three examples for the bulk phases at $t = 0.9$: $b = 0$ for the bulk UN phase (circle), $b = 0.1$ for the bulk D₂-BN phase (square), and $b = 0.2$ for the bulk D₄-BN phase (triangle). The phase boundary by the cyan line indicates the first-order phase transition [\[66\]](#page-18-0). The other phase boundaries are the second-order phase transition.

For convenience in the analysis, instead of Eq. (14) , we may express the order parameter in terms of f_0 and ϕ ,

$$
f_1 = \left(\frac{\cos\phi}{\sqrt{2}} - \frac{\sin\phi}{\sqrt{6}}\right) f_0, \quad f_2 = \sqrt{\frac{2}{3}} (\sin\phi) f_0,
$$

$$
f_3 = \left(-\frac{\cos\phi}{\sqrt{2}} - \frac{\sin\phi}{\sqrt{6}}\right) f_0,
$$
 (15)

by dropping \tilde{d} and \bf{n} in Eq. [\(12\)](#page-4-0). This is the parametrization that the three-dimensional vector $f \equiv (f_1, f_2, f_3)$ is confined on the plane by $f_1 + f_2 + f_3 = 0$, and ϕ is the rotation angle on this plane. We notice that the restriction of the range for ϕ to $0 \le \phi \le \pi/6$ recovers the parametrization in the diagonal form in Eq. (14) . We show the GL potential with the coordinate $(f_0 \cos \phi, f_0 \sin \phi)$ in Fig. [3,](#page-6-0) where we set the temperature $t = 0.9$ and the magnetic field $b = 0$ (the UN phase), $b = 0.1$ (the D₂-BN phase), and $b = 0.2$ (the D₄-BN phase). In each phase, there are several degenerate states in the ground state: six degenerate states in the UN phase, four degenerate states in the D_2 -BN phase, and two degenerate states in the D4-BN phase. Those degenerate states are more clearly seen by defining the GL free energy only with ϕ ,

$$
\tilde{f}_{\min}(\phi) = \min_{f_0 \ge 0} \tilde{f}(f_0, \phi),\tag{16}
$$

where the right-hand side means that a minimum value of $\hat{f}(f_0, \phi)$ is chosen in the variational calculation with respect

 14 We may notice that the D₄-BN phase is also extended at low temperature and small magnetic field. There, the first-order phase transition exists at small magnetic field, and there appears the CEP at the meeting point between the first-order and second-order phase

transitions. The first-order phase transition and the CEP is induced by the eighth-order term ($\delta^{(0)}$ term) in the GL equation [\[66\]](#page-18-0).

FIG. 3. Upper panels: We show the examples of the GL free energy on the plane with axes $f_0 \cos \phi$ and $f_0 \sin \phi$ for the bulk UN, D₂-BN, and D4-BN phases. The degenerate vacua are shown by the colorful points in each bulk phase (orange for the bulk UN phase, magenta for the bulk D₂-BN phase, and blue for the bulk D₄-BN phase), and they are connected by the domain walls W^{α} ($\alpha = 1, 2, 3, 13$). Lower panels: The three-dimensional vectors (f_1, f_2, f_3) with $f_1 + f_2 + f_3 = 0$ are shown by the colorful arrows for the bulk UN, D₂-BN, and D₄-BN phases. The domain walls are indicated by the arrows, W^2 , W^1 , and W^3 , for the bulk UN phase, W^2 and W^1 ³ for the bulk D₂-BN phase, and W^{13} for the bulk D₄-BN phase. The arrows lies on the plane for the traceless condition: $f_1 + f_2 + f_3 = 0$.

to f_0 . We show the result of $\tilde{f}_{min}(\phi)$ in Fig. 4. We confirm that the degenerate states: $\phi/\pi = \pm 1/6, \pm 1/2, \pm 5/6$ in the UN phase; $\phi/\pi = \pm 0.129$, ± 0.870 in the D₂-BN phase; and $\phi/\pi = 0$, 1 in the D₄-BN phase.

B. Domain walls: W_i^{α} (UN), W_i^{α} (D₂BN), and W_i^{α} (D₄BN)

We consider the domain walls that connect the vacua in the GL free energy, i.e., $\tilde{A}(+\infty; n)$ and $\tilde{A}(-\infty; n)$, where $\tilde{A}(\pm\infty; n)$ are the different (dimensionless) condensates in the degenerate ground states in the bulk space at $\tilde{d} \rightarrow \pm \infty$, respectively, along the line with the direction n [see Eq. [\(11\)](#page-4-0), and also Figs. 3 and 4]. We denote the domain wall by W^{α} , where α indicates the label to classify the domain walls, and explain our definitions of W^{α} in each bulk phase in the followings.

In the bulk UN phase (relevant for zero magnetic field), we consider the domain walls W^{α} ($\alpha = 1, 2, 3$)

FIG. 4. The GL free energy $\tilde{f}_{min} = \tilde{f}_{min}(\phi)$ as functions of the angle ϕ . The gray regions ($0 \le \phi/\pi < 1/6$) corresponds to the diagonal form parametrized in the right-hand side of Eq. [\(14\)](#page-5-0). The arrows indicate the domain walls connecting the different minima. The horizontal solid and dashed lines indicate the angle for the UN and D_4 -BN phases, respectively, and the regions between them correspond to the D_2 -BN phase.

which connect the neighboring degenerate states in the angles $(\phi \mod 2\pi)/\pi = -1/6$, 1/6, 1/2, 5/6, 7/6, 3/2,

and $11/2 = -1/6$ and denote them in the following way:

$$
W^{1}(\text{UN}) : \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \longleftrightarrow \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \longleftrightarrow \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \tag{17}
$$

between $(\phi \mod 2\pi)/\pi = 1/6$ and $1/2$ and between $(\phi \mod 2\pi)/\pi = 7/6$ and $3/2$, respectively;

$$
W^{2}(\text{UN}) : \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \longleftrightarrow \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}, \quad \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \longleftrightarrow \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \tag{18}
$$

between $(\phi \mod 2\pi)/\pi = 1/6$ and $1/2$ and between $(\phi \mod 2\pi)/\pi = 7/6$ and 3/2, respectively; and

$$
W^{3}(\text{UN}) : \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -1 \end{pmatrix} \longleftrightarrow \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \longleftrightarrow \frac{f_{0}}{\sqrt{6}} \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad (19)
$$

between $(\phi \mod 2\pi)/\pi = 1/2$ and 5/6 and between $(\phi \mod 2\pi)/\pi = 3/2$ and $11/6 = -1/6$, respectively. We notice that W^{α} $(\alpha =1, 2, 3)$ leaves the α th diagonal components unchanged and exchange the other two diagonal components up to the overall minus sign.

In the bulk D_2 -BN phase in setting $b = 0.1$, we consider the domain walls connecting the neighboring degenerate states in the angles (ϕ mod 2π)/ π = 0.129, 0.870, 1.129, and 1.870 and denote them in the following way:¹⁵

$$
W^{13}(\text{D}_2\text{BN}): f_0 \begin{pmatrix} 0.506 & 0 & 0 \\ 0 & 0.302 & 0 \\ 0 & 0 & -0.808 \end{pmatrix} \longleftrightarrow f_0 \begin{pmatrix} -0.808 & 0 & 0 \\ 0 & 0.302 & 0 \\ 0 & 0 & 0.506 \end{pmatrix}, \\ f_0 \begin{pmatrix} -0.506 & 0 & 0 \\ 0 & -0.302 & 0 \\ 0 & 0 & 0.808 \end{pmatrix} \longleftrightarrow f_0 \begin{pmatrix} 0.808 & 0 & 0 \\ 0 & -0.302 & 0 \\ 0 & 0 & -0.506 \end{pmatrix},
$$
 (20)

between (ϕ mod 2π)/ π = 0.120 and 0.870 and between (ϕ mod 2π)/ π = 1.120 and 1.870, respectively, and

$$
W^{2}(\text{D}_{2}BN): f_{0}\begin{pmatrix} 0.808 & 0 & 0 \ 0 & -0.302 & 0 \ 0 & 0 & -0.506 \end{pmatrix} \longleftrightarrow f_{0}\begin{pmatrix} 0.506 & 0 & 0 \ 0 & 0.302 & 0 \ 0 & 0 & -0.808 \end{pmatrix},
$$

$$
f_{0}\begin{pmatrix} -0.808 & 0 & 0 \ 0 & 0.302 & 0 \ 0 & 0 & 0.506 \end{pmatrix} \longleftrightarrow f_{0}\begin{pmatrix} -0.506 & 0 & 0 \ 0 & -0.302 & 0 \ 0 & 0 & 0.808 \end{pmatrix},
$$
(21)

between $(\phi \mod 2\pi)/\pi = -0.120$ and 0.120 and between $(\phi \mod 2\pi)/\pi = 0.870$ and 1.120, respectively. We notice that W^{α} (D₂BN) ($\alpha = 13$ and 2) leaves the second diagonal components unchanged and exchange the other two diagonal components up to the overall minus sign.

In the bulk D_4 -BN phase, we consider the domain walls connecting the neighboring degenerate states in the angles $(\phi \mod 2\pi)/\pi = 0$ and 1 and denote them in the following way:

$$
W^{13}(\text{D}_4 \text{BN}) : \frac{f_0}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \longleftrightarrow \frac{f_0}{\sqrt{2}} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad \frac{f_0}{\sqrt{2}} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \longleftrightarrow \frac{f_0}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad (22)
$$

between $(\phi \mod 2\pi)/\pi = 0$ and 1 and between $(\phi \mod 2\pi)/\pi = 1$ and 2, respectively. $W^{13}(D_4BN)$ leaves

the second diagonal components unchanged and exchanges the other two diagonal components.

Several comments are in order. In the above definitions, we remark that W^{α} (UN) ($\alpha = 1, 2, 3$), W^{α} (D₂BN) ($\alpha = 13$, 2), and W^{α} (D₄BN) (α = 13) leave the (absolutely) minimum components unchanged up to the minus sign at the left and right infinities: $\pm f_0/\sqrt{6}$ in the case of W^{α} (UN) ($\alpha = 1, 2,$ 3), $\pm 0.302 f_0$ in the case of W^{α} (D₂BN) ($\alpha = 13, 2$), and 0

¹⁵We notice that different values for ϕ in the degenerate states will be realized for different strengths of the magnetic field in the D_2 -BN phase. In contrast, the values of ϕ in the degenerate states in the UN and D4-BN phases have no dependence on the magnetic field.

in the case of W^{α} (D₄BN) ($\alpha = 13$). We also notice that the domain wall configuration passes through various different phases. To see more details, in Fig. [4,](#page-6-0) we show the angles $\phi/\pi = 1/6 + (3/2)n$ corresponding to the UN phase by the horizontal solid lines, and the angles $\phi/\pi = (3/2)n$ corresponding to the D4-BN phase by the horizontal dashed lines (*n* an integer). The regions between the solid lines and the dashed lines correspond to the D_2 -BN phase. From them, we then find that the domain walls go across several phases as follows: For example, the domain wall W^{α} ($\alpha = 1, 2, 3$) connecting the two vacua in the bulk UN phase pass through the D_2 -BN phase and the D4-BN phase in the following order:

$$
W^{\alpha}(\text{UN}): \text{UN} \cdot \text{D}_2 \text{BN} \cdot \text{D}_4 \text{BN} \cdot \text{D}_2 \text{BN} \cdot \text{UN}, \tag{23}
$$

where the boundary is fixed by the UN phase by definition. In the bulk D_2 -BN phase, $W^2(D_2BN)$ passes through only the D_4 -BN phase, while $W^{13}(D_2BN)$ passes through the UN and D4-BN phases in the following order:

$$
W^{2}(D_{2}BN): D_{2}BN \cdot D_{4}BN \cdot D_{2}BN, \qquad (24)
$$

\n
$$
W^{13}(D_{2}BN): D_{2}BN \cdot UN \cdot D_{2}BN \cdot D_{4}BN \cdot D_{2}BN \cdot UN
$$

\n
$$
\cdot D_{2}BN \cdot D_{4}BN \cdot D_{2}BN \cdot UN \cdot D_{2}BN, \qquad (25)
$$

where the boundary is fixed by the D_2 -BN phase by definition. Finally, in the bulk D_4 -BN phase, $W^{13}(D_4BN)$ passes through the UN and D_2 -BN phases in the following order

$$
W^{13}(D_4BN): D_4BN \cdot D_2BN \cdot UN \cdot D_2BN \cdot D_4BN \cdot D_2BN
$$

$$
\cdot UN \cdot D_2BN \cdot D_4BN \cdot D_2BN \cdot UN \cdot D_2BN \cdot D_4BN
$$

$$
(26)
$$

where the boundary is fixed by the D_4 -BN phase by definition. Accompanied by those internal phases, the number of the Nambu-Goldstone modes induced by the symmetry breaking can change locally at each internal phase inside the domain walls.¹⁶ In particular, the UN phase has less number of the NG modes. Therefore, the domain wall W^{α} (UN) in the UN phase contains one NG mode localized in its vicinity. On the other hand, the continuous U(1) symmetry that the UN phase preserves restores in the cores of the domain walls $W^{13}(D_2BN)$ and $W^{13}(D_4BN)$ in the D₂-BN and D₄-BN phases.

When a magnetic field *b* is continuously changed, there happen phase transitions at some magnetic fields, among the UN phase, the D_2 -BN phase, and the D_4 -BN phase, as shown in Fig. [2.](#page-5-0) Here we discuss how the domain walls in each phase is connected to those of the other phases, see Fig. [4.](#page-6-0) When we gradually increase a magnetic field from zero to some finite value, the phase changes from the UN to D_2 -BN phase. In this process, the two domain walls W^1 (UN) and W^3 (UN) in the UN phase are bound together as a coalescence to become a single domain wall $W^{13}(D_2BN)$ in the D_2-BN phase: $W^1 + W^3 \rightarrow W^{13}$. This is because the potential minimum at $(\phi \mod 2\pi)/\pi = \pm 1/2$ existing between the two walls W^1 (UN) and W^3 (UN) is lifted in the D₂-BN phase and they are confined. Therefore, the domain wall $W^{13}(D_2BN)$ can be

FIG. 5. The metamorphism of the domain walls with the fixed directions, with depending on the strength of the magnetic field. The magnetic fields in the D_2 -BN and D_4 -BN phases ($b = 0.1$ and 0.2) are applied to the x_2 (vertical) direction.

regarded as a composite domain wall. If we further increase the magnetic field so that the phase becomes the D_4 -BN phase, then the domain wall $W^{13}(D_2BN)$ is changed to $W^{13}(D_4BN)$, which can be regarded as a genuine elementary domain wall since the local energy minimum completely disappears finally in the D_4 -BN phase. On the other hand, returning back the zero magnetic field, the domain wall W^2 (UN) in the UN phase is transformed to the domain wall $W^2(D_2BN)$ in the D2-BN phase without causing coalescence or fragmentation of domain walls. Further increasing the magnetic field to the D_4 -BN phase, it disappears completely in the D_4 -BN phase because the two degenerate ground states connected by $W^2(D_2BN)$ merge to one ground state $(\phi \mod 2\pi)/\pi = 0$ or 1 in the D_4 -BN phase. In Fig. 5, we summarize a part of the metamorphism of domain walls under the change of the strength of the magnetic field.

We consider that the direction of the domain walls is defined by the normal vector perpendicular to the surface. In order to show the simple example, we consider that the domain walls are directed in the three special cases: (i) the *x*₁ direction, i.e., $\mathbf{n} = (1, 0, 0), (\theta, \varphi) = (\pi/2, 0)$; (ii) the *x*₂ direction, i.e., $\mathbf{n} = (0, 1, 0), (\theta, \varphi) = (\pi/2, \pi/2)$; and (iii) the *x*₃ direction, i.e., $\mathbf{n} = (0, 0, 1), (\theta, \varphi) = (0, 0)$. At the end of the discussion, we will investigate the stability of the domain walls against small changes of the directions. When we need to specify the directions of the domain wall, we use the notation W_i^{α} for $i = 1, 2$, and 3 for the x_1, x_2 , and x_3 directions: W_i^{α} ($\alpha = 1, 2, 3$) in the UN phase, W_i^{α} ($\alpha = 13, 2$) in the D_2 -BN phase, and W_i^{α} ($\alpha = 13$) in the D_4 -BN phase.

C. Configurations of domain walls

For the domain walls defined in the previous subsection, we consider their configurations in the three-dimensional space and calculate the energy per unit area (surface tension) on the surface of the domain walls. We solve the EL equation [\(8\)](#page-4-0) for the domain walls by introducing the boundary conditions in the bulk space. The boundary conditions are given in Eqs. [\(17\)](#page-7-0), [\(18\)](#page-7-0), and [\(19\)](#page-7-0) in the bulk UN phase, Eqs. [\(20\)](#page-7-0) and [\(21\)](#page-7-0) in the bulk D_2 -BN phase, and Eq. [\(22\)](#page-7-0) in the bulk D_4 -BN

¹⁶See, e.g., Ref. [\[64\]](#page-18-0) for the Nambu-Goldstone modes appearing in the UN, D_2 -BN, and D_4 -BN phases.

TABLE I. The surface energy densities by the domain walls with the directions along x_1 , x_2 , and x_3 directions. ϕ is defined in Eq. [\(15\)](#page-5-0) (cf. Fig. [4\)](#page-6-0). The bulk UN, D_2 -BN, and D_4 -BN phases have $(t, b) = (0.9, 0), (0.9, 0.1),$ and $(0.9, 0.2),$ respectively.

Bulk UN phase	W^2 (UN)			W^1 (UN)			W^3 (UN)			
Angle	$-1/6 \le (\phi \mod \pi)/\pi < 1/6$			$1/6 \leqslant (\phi \mod \pi)/\pi < 1/2$			$1/2 \leqslant (\phi \mod \pi)/\pi < 5/6$			
Direction	W_1^2	W_2^2	W_3^2	W_1^1	W_2^1	W_3^1	W_1^3	W_2^3	W_3^3	
σ (keV/fm ²)	0.0154	0.0199	0.0154	0.0199	0.0154	0.0154	0.0154	0.0154	0.0199	
Bulk D_2 -BN phase		$W^2(D_2BN)$		$W^{13}(D_2BN)$						
Angle	$-0.129 \le (\phi \mod \pi)/\pi < 0.129$				$0.129 \le (\phi \mod \pi)/\pi < 0.870$					
Direction	W_1^2	W_2^2	W_3^2	W_1^{13}		W_2^{13}			W_3^{13}	
σ (keV/fm ²)	0.0082	0.0107	0.0082	0.0722		0.0616		0.0722		
Bulk D_4 -BN phase				$W^{13}(D_4BN)$						
Angle				$0 \leqslant (\phi \mod \pi)/\pi < 1$						
Direction					W_1^{13}		W_2^{13}		W_3^{13}	
σ (keV/fm ²)				0.1533			0.1353		0.1533	

phase. For the analysis, we consider the three-dimensional vector as functions of d for a fixed n ,

$$
f(\tilde{d}) \equiv (f_1(\tilde{d}; \mathbf{n}), f_2(\tilde{d}; \mathbf{n}), f_3(\tilde{d}; \mathbf{n})), \tag{27}
$$

whose components have been introduced in Eq. (11) in the three-dimensional space with the coordinate $(\tilde{x}_1, \tilde{x}_2, \tilde{x}_3)$. The schematic figures are presented in the bottom panels in Fig. [3.](#page-6-0) The numerical results of $f(\tilde{d})$ are shown in Figs. [10,](#page-16-0) [11,](#page-17-0) and [12](#page-17-0) in Appendix [B.](#page-16-0)

With the solutions of $f(\tilde{d})$, we consider the surface energy density per unit area of the domain walls surface directed along *n*, which are expressed as

$$
\sigma(\mathbf{n}) \equiv \int_{-\infty}^{\infty} [f(d; \mathbf{n}) - f_{\text{bulk}}] dd,
$$
 (28)

for with the GL free energy densities $f(d; n)$ in the domain. Here f_{bulk} is the GL free energy density in the bulk space $(|d| \rightarrow \infty)$.¹⁷ We show the numerical results of the surface energy density for W_i^{α} (UN) with $\alpha = 1, 2, 3, W_i^{\alpha}$ (D₂BN) with $\alpha = 13, 2$ and W_i^{13} (D₄BN) (*i* = 1, 2, 3) in Table I. From the table, we observe the following properties of the domain walls, depending on the strengths of the magnetic field:

(i) In the zero magnetic field, i.e., in the bulk UN phase, the domain walls W_i^{α} (UN) with the condition $\alpha \neq i$

 17 For the convenience of the calculation, we can express the surface energy density as

$$
\sigma(\mathbf{n}) = \frac{p_F^2 T_{c0}}{2\pi^2} \tilde{\sigma}(\mathbf{n}),\tag{29}
$$

where we have defined the dimensionless surface energy density by

$$
\tilde{\sigma}(\boldsymbol{n}) \equiv \int_{-\infty}^{\infty} [\tilde{f}(\tilde{d}; \boldsymbol{n}) - \tilde{f}_{\text{bulk}}] d\tilde{d}, \qquad (30)
$$

for the dimensionless GL free energy densities, $\tilde{f}(\tilde{d}; n)$ in the domain wall, and \tilde{f}_{bulk} in the bulk space ($|\tilde{d}| \to \infty$).

satisfied are the most stable ones, while W_i^{α} (UN) with $\alpha = i$ have higher energy. The directions x_1, x_2 , and x_3 of the domain walls yield essentially the same results by cyclic transformations, because the rotational symmetry exists in the absence of a magnetic field.

- (ii) In the weak magnetic fields, i.e., in the bulk D_2-BN phase, the domain walls in the bulk UN phase are transformed as follows: the domain walls W_i^1 and W_i^3 in the bulk UN phase merge to the single domain wall W_i^{13} in the bulk D₂-BN phase: $W_i^1 + W_i^3 \to W_i^{13}$, while the domain wall W_i^2 in the bulk UN phase becomes the one W_i^2 in the bulk D_2 -BN phase. We notice that, in the bulk D_2 -BN phase, W_i^{13} has higher energy than W_i^2 , because of the composite nature of W_i^{13} .
- (iii) In the strong magnetic fields, i.e., in the bulk D_4 -BN phase, the domain wall W_i^2 in the D₂-BN phase disappears while the domain wall W_i^{13} survives to become an elementary domain wall, which is the unique domain wall in the D_4 -BN phase.

So far we have fixed the directions of the domain walls to be along the coordinate axes *x*1, *x*2, and *x*3, by setting the normal vector as $n = (1, 0, 0), (0,1,0),$ and $(0,0,1)$. Now we discuss the stability of the domain walls against a *continuous* rotation of \boldsymbol{n} . For example, we pick up W_2^{13} as the most stable domain wall in the bulk D_4 -BN phase, and investigate the angle dependence in the surface energy density of W_2^{13} . For this purpose, we substitute the profile solution for W_2^{13} , which has been solved for $\mathbf{n} = (0, 1, 0)$ ($\theta = \pi/2$ and $\varphi = \pi/2$), into Eq. (28) , where the direction of *n* in Eq. (28) is set to be arbitrary in the vicinity of $n = (0, 1, 0)$. We then calculate approximately the surface energy density for the domain wall whose normal vector *n* is different from $n = (0, 1, 0)$. The result is shown in Fig. [6.](#page-10-0) It is found that $\theta = \pi/2$ and $\varphi =$ $\pi/2$, i.e., the x_2 direction, still gives the minimum point. It is also found that the values of $\tilde{\sigma}$ for the x_1 direction and for the x_3 direction are reproduced approximately, while the true

FIG. 6. The approximate values of the surface energy density $\sigma = \sigma(n)$ for the domain wall W_2^{13} in the bulk D₄-BN phase. Left: The function of θ for $\varphi = \pi/2$ fixed. Right: The function of φ for $\theta = \pi/2$ fixed. The horizontal thick-dotted lines indicate the value $\sigma = 0.1353 \text{ keV/fm}^2$, i.e., the value at the *x*₂ direction ($\theta = \pi/2$ and $\varphi = \pi/2$). The horizontal thin-dotted lines indicate the value $\sigma = 0.1533 \text{ keV/fm}^2$, i.e., the value at the *x*₁ direction ($\theta = \pi/2$ and $\varphi = 0$) or at the *x*₃ direction ($\theta = 0$). See the text for more details.

solution (points in the figure) of course has less energy (see also Table [I\)](#page-9-0).

D. Piling domain walls

Here we discuss piling multiple domain walls. We display the schematic image for a pile of domain walls which is the most stable for the given direction in Fig. 7. We notice that, when the domain walls are piled up, the phase function $\phi(\tilde{d}; n)$ defined in Eq. [\(12\)](#page-4-0) should change continuously throughout the piled domain walls. From the continuity of $\phi(\tilde{d}; n)$ modulo 2π , the ordering of the domain walls is determined uniquely (see also the upper panels of Fig. [3\)](#page-6-0):

$$
\cdots - (W_i^1 - W_i^3 - W_i^2) - (W_i^1 - W_i^3 - W_i^2) - \cdots, \quad (31)
$$

FIG. 7. The schematic figures for the metamorphism of the domain walls with the fixed directions $(i = 1, 2)$, depending on the strength of the magnetic field. The magnetic fields in the D_2 -BN and D₄-BN phases ($b = 0.1$ and 0.2) are applied to the x_2 (vertical) direction. The configurations W_2^1 , W_2^3 , and W_2^{13} are the most stable states in the x_2 direction along the magnetic field, and the configurations W_1^2 or W_3^2 are the most stable states in the x_1 or x_3 direction perpendicular to the magnetic field. The surface energy densities in the unit cells are shown. See Table [I.](#page-9-0)

in the bulk UN phase,

$$
\cdots - (W_i^{13} - W_i^2) - (W_i^{13} - W_i^2) - \cdots, \qquad (32)
$$

in the bulk D_2 -BN phase, and

$$
\cdots - (W_i^{13}) - (W_i^{13}) - \cdots, \qquad (33)
$$

in the bulk D_4 -BN phase, along the directions of the x_i axis $(i = 1, 2, 3)$.¹⁸ We have introduced the unit cells by brackets as $(W_i^1 - W_i^3 - W_i^2)$ in the bulk UN phase, $(W_i^{13} - W_i^2)$ in the bulk D_2 -BN phase, and (W_i^{13}) in the bulk D_4 -BN phase, and the piled domain walls are regarded as a repetition of the unit cell.

Let us discuss the surface energy density per a unit cell for the pile along the x_1 (or x_3) direction and along the x_2 direction. It is

$$
\sigma (W_i^1 - W_i^3 - W_i^2) = \sigma (W_i^1) + \sigma (W_i^3) + \sigma (W_i^2) + \sigma_{int}
$$

= 0.0507 keV/fm² for $i = 1, 2, 3$ (34)

for the UN phase,

$$
\sigma(W_i^{13} - W_i^2) = \sigma(W_i^{13}) + \sigma(W_i^2) + \sigma_{int}
$$

=
$$
\begin{cases} 0.0727 \text{ keV/fm}^2 & \text{for } i = 2\\ 0.0804 \text{ keV/fm}^2 & \text{for } i = 1, 3 \end{cases}
$$
 (35)

for the D_2 -BN phase, and

$$
\sigma(W_i^{13} - W_i^2) = \sigma(W_i^{13}) + \sigma(W_i^2) + \sigma_{int}
$$

=
$$
\begin{cases} 0.1353 \text{ keV/fm}^2 & \text{for } i = 2\\ 0.1535 \text{ keV/fm}^2 & \text{for } i = 1, 3 \end{cases}
$$
 (36)

for the D4-BN phase, where we have ignored the interaction energy σ_{int} . We summarized the situation in Fig. 7. Thus, at finite magnetic field, we conclude that a pile of the domain walls perpendicular to the magnetic field (the x_2 direction) is realized as the most stable states. As we did for a single domain wall, we can rotate the piled domain wall configurations with an arbitrary angle.

IV. ESTIMATION OF DOMAIN WALL ENERGY RELEASED FROM A NEUTRON STAR

We estimate the energy released from domain walls when they exist inside neutron stars. As an example, we consider W_2^{13} in the bulk D₄BN phase, which is the most stable state along the x_2 direction perpendicular to the applied magnetic field (cf. Table [I\)](#page-9-0). We suppose simply that domain walls are disks at constant x_2 inside a spherical condensation of a ${}^{3}P_2$ superfluid of the radius $R \approx 10$ km of a neutron star. Utilizing the surface energy density $\sigma = 0.1353 \text{ keV}/\text{fm}^2$ for $W_{2,2}^{13}$ in Table [I,](#page-9-0) we obtain the total energy of W_2^{13} , $E_{\text{DW}} = \sigma \times \pi R^2 =$ 0.85×10^{29} erg.¹⁹ Here we suppose that the domain walls

¹⁸We can define the "chirality" for right-winding and left-winding for the traveling direction of the domain walls in the bulk UN phase. We may assign the left-winding for a pile of domain walls W_i^1 – $W_i^3 - W_i^2$. As the opposite chirality, we may also assign the rightwinding for a pile of domain walls $W_i^1 - W_i^2 - W_i^3$

¹⁹We use the unit conversion 1 keV $\approx 2.0 \times 10^{-9}$ erg.

FIG. 8. The schematic figure of the bunch of the domain walls W_2^{13} in the bulk D₄-BN phase in the neutron star.

are densely piled in the neutron star as shown schematically in Fig. 8. In order to estimate the maximum number of the domain walls in the neutron stars, we suppose that the domain walls are packed maximally, where the interdistance between two domain walls will reach the healing distance as expected from defect formations at a phase transition $[7,8]$: $\xi \approx p_F/mT_{c0} = 355$ fm for $p_F = 338$ MeV and $T =$ 0.9 T_{c0} (*t* = 0.9). This is obtained from $d = [p_F/(mT_{c0})]\tilde{d}$ by substituting $\tilde{d} \approx 1$, where the value of \tilde{d} can be read from Fig. [12](#page-17-0) in Appendix [B.](#page-16-0) Then, roughly speaking, the number of the domain walls will reach $N \approx R/\xi = 2.8 \times 10^{16}$. Therefore, the energy stemming from the piled domain walls can be estimated as $E_{\text{DW}}N \approx 2.4 \times 10^{45}$ erg. In reality, the number *N* would be smaller than the present estimation, and hence the energy $E_{\text{DW}}N$ would be reduced also. Nevertheless, we consider that a huge energy can be released from the domain walls, leading to a possibility that the domain walls can be found in the astrophysical phenomena such as glitches as sudden speed-up events of the rotation of neutron stars.

We may consider the following situation that the domain wall trapped around the equator of the neutron star will not be the static objects, but they move to the north or south poles by releasing the energy of the domain wall. This is because the smaller radius should be favored energetically, and therefore the domain walls will try to reduce the radius. In this process, the domain walls would finally disappear when they reach the north or south poles, see Fig. 9. We may consider that the released energy by the domain walls, which will be emitted from the surface of the neutron stars, can be detected in astrophysical observation.

We comment that the healing distance ξ is the temperaturedependent quantity as the order parameter. Because the healing distance should be very large near the critical temperature and it should become divergent just at the critical temperature, the number of domain walls in the neutron stars decreases accordingly. On the other hand, when the temperature becomes lower, the healing distance becomes smaller, and hence the number of domain walls in the neutron stars increases. Therefore, the released energies of the domain walls from the neutron stars are sensitive to the temperature inside the neutron stars.

V. SUMMARY AND DISCUSSION

We have worked out the domain walls in a neutron ${}^{3}P_{2}$ superfluid in neutron stars. As an effective theory, we have adopted the GL equation for describing the domain walls as the nonuniform systems. Considering the bulk UN, D_2 -BN, and D_4 -BN phases in the neutron 3P_2 superfluids, we have constructed the configurations of the domain walls and have calculated the surface energy densities. As examples, we have discussed the domain walls denoted by W_i^{α} ($\alpha = 1, 2, 3$) in the bulk UN phase, W_i^{α} ($\alpha = 13, 2$) in the bulk D₂-BN phase, and W_i^{α} ($\alpha = 13$) in the bulk D₄-BN phase for the fixed direction x_i ($i = 1, 2, 3$) in space. As for symmetry structures, domain wall configurations pass thorough different phases in their vicinities. Consequently, unbroken symmetries around their cores are different from those in the bulk. For instance, the phases of domain walls in the bulk UN phase

FIG. 9. The schematic figure for the domain walls W_2^{13} in the bulk the D₄-BN phase, moving toward the north and south poles. The orientation of the domain walls is along the magnetic field (the *x*₂ direction). After arriving at the poles, the domain walls will disappear in the end.

are either D_2 -BN or D_4 -BN phase. As a result, there appears one extra Nambu-Goldstone mode localized in the vicinity of the domain walls in the UN phase. On the other hand, in the D_2 -BN phase, a U(1) symmetry restores in the vicinity of the domain wall $W^{13}(D_2BN)$ but not of the other case $W^2(D_2BN)$. The same symmetry restoration occurs in the vicinities of all domain walls $W^{13}(D_4BN)$ in the D₄-BN phase. Considering a pile of domain walls, we have found that the domain walls are lined up perpendicular to the magnetic field. We have estimated the energy released from a pile of the domain walls existing inside neutron stars and have shown that the emitted energy can reach a huge amount which may be found in signals from the neutron stars, such as glitches, in the astrophysical observation.

In this paper, we have restricted ourselves to the diagonal components in $A(d; n)$. Taking into the off-diagonal components, the configuration may be unstable or metastable. This is because a set two different ground states that we were considering in this paper can be connected by a global transformation of $U(1) \times SO(3)$, and therefore they are not disconnected in the full space. Physically, the configurations should decay to a ground state by emitting Nambu-Goldstone modes because symmetry transformation exchange diagonal components through off-diagonal components. In spite of the limitation in the present research, we expect that the domain walls can give an impact on the astrophysical observation of the neutron stars as long as the domain walls survive within the timescale of the decay. It will be a next subject to study the lifetime of the domain walls, for which we have to consider the off-diagonal components in the order parameter. It is also important to study the interaction between two domain walls which will be caused by the exchange of massive particles or sometimes Nambu-Goldstone modes. Although the interaction is expected to be repulsive, it is still an open problem to discuss carefully the strength of the interaction, the dependence on the bulk phases, and so on.

Since the phases in the vicinities of domain walls are different from those in the bulk, unbroken symmetries are also different. This may allow topological defects living inside domain walls. For instance, the U(1) symmetry unbroken in the bulk UN phase is further broken to D_2 or D_4 in the vicinity of the domain wall, admitting vortices inside domain walls. 20 What do such composite configuration represent will be one of future directions.²¹

We also will need to study the edge effect of the domain walls, because the domain walls realistically should be affected by the surface of the neutron stars. The surface of

the neutron ${}^{3}P_2$ superfluids has the topological property [\[67\]](#page-18-0). The properties of the domain walls in the rotating system are also interesting subjects, in which the interaction between the domain walls and the quantum vortices may become important.²² Beyond the description by the GL theory, it is an interesting question whether fermion (quasi-)gapless modes are present inside domain walls, by investigating fermionic degrees of freedom in terms of the BdG equation [\[68\]](#page-19-0), in which ${}^{3}P_{2}$ surface was shown to allow gapless Majorana fermions.

There exist superfluid vortices in ${}^{3}P_{2}$ superfluids and they form a lattice under a rotation [\[35,36,61,62,64,65,](#page-18-0)[84\]](#page-19-0). How these vortices interact with domain walls is an important question. Also, vortices may terminate on a domain wall with forming so-called a D-brane soliton, which is known to exist in two-component Bose-Einstein condensates [\[101–104\]](#page-19-0) and supersymmetric field theory $[105, 106]$, where the endpoint of the vortex is called as a boojum. Another possibility is that a domain wall may terminate on a vortex, or in other words, a vortex is attached by a domain wall as axion strings.

Domain walls also exist in color superconductivity in the quark matter considered to exist deeply inside of neutron stars, see, e.g., Ref. [\[99\]](#page-19-0). Then a similar situation occurs in this case. It is also an interesting question how domain walls interact with other topological defects. It has been known that, in a rotating neutron star, Abelian quantum superfluid vortices are created along the rotation axis in the hadron matter as well as non-Abelian quantum vortices (color magnetic flux tubes) in the quark matter [\[107–111\]](#page-19-0). Recently, the presence or absence of boojums have been discussed, which are defects at endpoints (or junction points) of these vortices at the interface [\[112–116\]](#page-19-0). The interactions between the domain walls and the boojum may influence the dynamics of neutron stars. Those problems are left for future works.

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²⁰This situation is similar to the boundary surface of superfluid studied recently [\[67\]](#page-18-0).

²¹See, for instance, Refs. [\[99\]](#page-19-0) and $[100]$, for composite soliton configurations in dense QCD and supersymmetric gauge theories, respectively.

²² See, e.g., Refs. [\[64,65](#page-18-0)[,84\]](#page-19-0) for the recent works on the ${}^{3}P_2$ superfluid vortices in neutron matter.

APPENDIX A: EULER-LAGRANGE EQUATIONS

We show the concrete expressions of the terms in the left-hand sides in the EL equations [\(8\)](#page-4-0) and [\(9\)](#page-4-0):

$$
\begin{split} &-\nabla_{d}\frac{\delta f}{\delta(\nabla_{d}F_{1})}+\frac{\delta f}{\delta F_{1}} \\ &=-\frac{K^{(0)}}{4}\Big[2(2-\sin^{2}\theta\sin^{2}\phi)\nabla_{d}^{2}F_{1}+(1+2\cos^{2}\theta)\nabla_{d}^{2}F_{2}+2\cos\theta\sin\theta\sin\phi\nabla_{d}^{2}G_{1} \\ &-2\sin^{2}\theta\cos\phi\sin\phi\nabla_{d}^{2}G_{3}\Big]+ \alpha^{(0)}2(2F_{1}+F_{2})+\beta^{(0)}4(2F_{1}+F_{2})\big(F_{1}^{2}+F_{1}F_{2}+F_{2}^{2}+G_{1}^{2}+G_{2}^{2}+G_{3}^{2}\big) \\ &+ \gamma^{(0)}24\big(12F_{1}^{5}+30F_{2}F_{1}^{4}+52F_{2}^{2}F_{1}^{3}+24G_{1}^{2}F_{1}^{3}+24G_{2}^{2}F_{1}^{3}+24G_{3}^{2}F_{1}^{3}+48F_{2}^{3}F_{1}^{2}+42F_{2}G_{1}^{2}F_{1}^{2} \\ &+36F_{2}G_{2}^{2}F_{1}^{2}+30F_{2}G_{3}^{2}F_{1}^{2}+26F_{2}^{4}F_{1}+14G_{1}^{4}F_{1}+12G_{2}^{4}F_{1}+44G_{3}^{4}F_{1}+40F_{2}^{2}G_{1}^{2}F_{1}+40F_{2}^{2}G_{1}^{2}F_{1} \\ &+24G_{1}^{2}G_{2}^{2}F_{1}+28F_{2}^{2}G_{3}^{2}F_{1}+20G_{1}^{2}G_{3}^{2}F_{1}+14G_{1}^{4}F_{1}+12G_{2}^{4}F_{1}+44G_{2}^{4}F_{1}+40F_{2}^{2}G_{1}^{2}F_{1}+40F_{2}^{2}G_{1}^{2}F_{1} \\ &-4G_{1}G_{2}G_{3}^{3}+12F_{2}^{3}G_{1}^{2}+14F_{2}^{2}G_{2}^{2}F_{1}+24G_{2}^{
$$

for F_1 ,

$$
-\nabla_d \frac{\delta f}{\delta(\nabla_d F_2)} + \frac{\delta f}{\delta F_2}
$$
\n
$$
= -\frac{K^{(0)}}{4} \left[(1 + 2 \cos^2 \theta) \nabla_d^2 F_1 + 2(2 - \sin^2 \theta \cos^2 \varphi) \nabla_d^2 F_2 - 2 \sin^2 \theta \cos \varphi \sin \varphi \nabla_d^2 G_3 + 2 \cos \theta \sin \theta \cos \varphi \nabla_d^2 G_2 \right]
$$
\n
$$
+ \alpha^{(0)} 2(F_1 + 2F_2) + \beta^{(0)} 4(F_1 + 2F_2)(F_1^2 + F_2F_1 + F_2^2 + G_1^2 + G_2^2 + G_3^2) + \gamma^{(0)} 24 (6F_1^5 + 26F_2F_1^4 + 48F_2^2F_1^3 + 14G_1^2F_1^3 + 12G_2^2F_1^3 + 10G_3^2F_1^3 + 52F_2^3F_1^2 + 40F_2G_1^2F_1^2 + 40F_2G_2^2F_1^2 + 28F_2G_3^2F_1^2
$$
\n
$$
+ 4G_1G_2G_3F_1^2 + 30F_2^4F_1 + 6G_1^4F_1 + 6G_2^4F_1 + 8G_3^4F_1 + 36F_2^2G_1^2F_1 + 42F_2^2G_2^2F_1 + 14G_1^2G_2^2F_1 + 30F_2^2G_3^2F_1
$$
\n
$$
+ 10G_1^2G_3^2F_1 + 10G_2^2G_3^2F_1 + 8F_2G_1G_2G_3F_1 + 12F_2^5 + 12F_2G_1^4 + 14F_2G_2^4 + 14F_2G_3^4 - 4G_1G_2G_3^3
$$
\n
$$
+ 24F_2^3G_1^2 + 24F_2^3G_2^2 + 24F_2^2G_2^2F_1^2 + 24F_2^3G_3^2 + 24F_2^2G_3^2F_1^3 + 20
$$

$$
+108F_{2}G_{1}^{2}G_{3}^{2}F_{1}^{2}+108F_{2}G_{2}^{2}G_{3}^{2}F_{1}^{2}+24G_{1}G_{2}^{3}G_{3}F_{1}^{2}+24G_{1}^{3}G_{2}G_{3}F_{1}^{2}+72F_{2}^{2}G_{1}G_{2}G_{3}F_{1}^{2}+56F_{2}^{6}F_{1}+8G_{2}^{6}F_{1}+8G_{2}^{6}F_{1}+14G_{3}^{6}F_{1}+72F_{2}^{2}G_{1}^{4}F_{1}+99F_{2}^{2}G_{2}^{4}F_{1}+30G_{1}^{2}G_{2}^{4}F_{1}+81F_{2}^{2}G_{3}^{4}F_{1}+24G_{1}^{2}G_{3}^{4}F_{1}+24G_{2}^{2}G_{3}^{4}F_{1}+18G_{1}^{4}G_{3}^{2}F_{1}+16G_{2}^{4}G_{3}^{2}F_{1}+120F_{2}^{4}G_{3}^{2}F_{1}+150F_{2}^{4}G_{2}^{2}F_{1}+30G_{1}^{4}G_{2}^{2}F_{1}+180F_{2}^{2}G_{1}^{2}G_{2}^{2}F_{1}+90F_{2}^{4}G_{3}^{2}F_{1}+18G_{1}^{4}G_{3}^{2}F_{1}+18G_{1}^{4}G_{3}^{2}F_{1}+18G_{2}^{4}G_{3}^{2}F_{1}+108F_{2}^{2}G_{1}^{2}G_{3}^{2}F_{1}+54G_{1}^{2}G_{2}^{2}G_{3}^{2}F_{1}+48F_{2}G_{1}G_{2}^{3}G_{3}F_{1}+48F_{2}G_{1}^{3}G_{2}G_{3}F_{1}+48F_{2}^{3}G_{1}^{3}G_{2}G_{3}F_{1}+16F_{2}^{3}G_{1}G_{2}G_{3}F_{1}+16F_{2}^{3}+16F_{2}^{3}G_{1}^{4}G_{3}^{2}F_{1}+108F_{2}^{2}G_{2}^{2}G_{
$$

for *F*2,

$$
-\nabla_d \frac{\delta f}{\delta (V_dG_1)} + \frac{\delta f}{\delta G_1}
$$
\n
$$
= -\frac{K^{(0)}}{4} [2\cos\theta \sin\theta \sin\phi \nabla_d^2 F_1 + 2(2 - \sin^2\theta \cos^2\phi) \nabla_d^2 G_1 + 2\sin^2\theta \cos\phi \sin\phi \nabla_d^2 G_2 + 2\cos\theta \sin\theta \cos\phi \nabla_d^2 G_3]
$$
\n
$$
+ \alpha^{(0)}4G_1 + \beta^{(0)}8G_1 (F_1^2 + F_2F_1 + F_2^2 + G_1^2 + G_2^2 + G_3^2) + \gamma^{(0)}24(12G_1^5 + 28F_1^2G_1^3 + 24F_2^2G_1^3 + 24G_2^2G_1^3 + 24G_2^2G_1^3)
$$
\n
$$
+ 24F_1F_2G_1^3 + 12F_1G_2G_3G_1^2 + 12F_1^4G_1 + 12F_2^4G_1 + 12G_2^4G_1 + 12G_3^4G_1 + 24F_1F_2^3G_1 + 40F_1^2F_2^2G_1 + 24F_1^2G_2^2G_1 + 24F_2^2G_2^2G_1 + 28F_1^3F_2G_2^2 - 42F_1G_2G_3^2 + 42F_2^2G_3^2G_1 + 24F_2^2G_3^2G_1 + 22F_1F_2G_3^2G_1 + 22F_1F_2G_3^2G_1
$$
\n
$$
+ 28F_1^3F_2G_1 - 4F_1G_2G_3^3 - 4F_2G_2G_3^3 + 4F_2G_2^3G_3 + 4F_1F_2^2G_2G_3 + 4F_1^2F_2G_2G_3)
$$
\n
$$
+ \delta^{(0)}384(8G_1^2 + 33F_1^2G_1^5 + 24F_2^2G_1^5 + 24G_2^2G_1^5 + 24G_2^2G_1^5 + 24G_1^2G_1^
$$

for G_1 ,

$$
-\nabla_d \frac{\delta f}{\delta(\nabla_d G_2)} + \frac{\delta f}{\delta G_2}
$$

= $-\frac{K^{(0)}}{4} [2 \cos \theta \sin \theta \cos \varphi \nabla_d^2 F_2 + 2 \sin^2 \theta \cos \varphi \sin \varphi \nabla_d^2 G_1 + 2(2 - \sin^2 \theta \sin^2 \varphi) \nabla_d^2 G_2 + 2 \cos \theta \sin \theta \sin \varphi \nabla_d^2 G_3]$
+ $\alpha^{(0)} 4G_2 + \beta^{(0)} 8G_2 (F_1^2 + F_2 F_1 + F_2^2 + G_1^2 + G_2^2 + G_3^2) + \gamma^{(0)} 24 (12G_2^5 + 24F_1^2 G_2^3 + 28F_2^2 G_2^3 + 24G_1^2 G_2^3 + 24G_3^2 G_2^3 + 24F_1 F_2 G_2^3 + 12F_2 G_1 G_3 G_2^2 + 12F_1^4 G_2 + 12F_2^4 G_2 + 12G_3^4 G_2 + 28F_1 F_2^3 G_2 + 40F_1^2 F_2^2 G_2 + 24F_1^2 G_1^2 G_2^2$

$$
+24F_2^2G_1^2G_2+28F_1F_2G_1^2G_2+24F_1^2G_3^2G_2+20F_2^2G_3^2G_2+32G_1^2G_3^2G_2+20F_1F_2G_3^2G_2+24F_1^3F_2G_2-4F_1G_1G_3^3-4F_2G_1G_3^3+4F_1G_1^3G_3+4F_1F_2^2G_1G_3+4F_1^2F_2G_1G_3)+8^{(0)}384(8G_2^7+24F_1^2G_2^5+33F_2^2G_2^5+24G_1^2G_2^5+24G_3^2G_2^5+24F_1F_2G_2^5+30F_2G_1G_3G_2^4+24F_1^4G_2^3+30F_2^4G_2^3+24G_1^4G_2^3+24G_3^4G_2^3+66F_1F_2^3G_2^3+90F_1^2F_2^2G_2^3+48F_1^2G_1^2G_2^3+54F_2^2G_1^2G_2^3+60F_1F_2G_1^2G_2^3+48F_1^2G_3^2G_2^2+42F_2^2G_3^2G_2^3+72G_1^2G_3^2G_2^3+36F_1F_2G_3^2G_2^3+48F_1^3F_2G_2^3-18F_1G_1G_3^3G_2^2+18F_1G_1^3G_3G_2^2+18F_2G_1^3G_3G_2^2+18F_2^3G_1G_3G_2^2+36F_1F_2^2G_1G_3G_2^2+36F_1^2F_2G_1G_3G_2^2+8F_1^6G_2+8F_2^6G_2+8G_3^6G_2+30F_1F_2^5G_2+63F_1^2F_2^4G_2+27F_1^2G_1^4G_2+24F_2^2G_1^4G_2+27F_1^2G_3^4G_2+21F_2^2G_3^
$$

for *G*2, and

$$
-V_{d}\frac{\delta f}{\delta (V_{d}G_{3})} + \frac{\delta f}{\delta G_{3}}
$$
\n
$$
= -\frac{K^{(0)}}{4}[-2\sin^{2}\theta\cos\varphi\sin\varphi V_{d}^{2}F_{1} - 2\sin^{2}\theta\cos\varphi\sin\varphi V_{d}^{2}F_{2} + 2\cos\theta\sin\theta\cos\varphi V_{d}^{2}G_{1} + 2\cos\theta\sin\theta\sin\varphi V_{d}^{2}G_{2}
$$
\n
$$
+ 2(1 + \sin^{2}\theta)V_{d}G_{3}] + \alpha^{(0)}4G_{3} + \beta^{(0)}8G_{3}(F_{1}^{2} + F_{2}F_{1} + F_{2}^{2} + G_{1}^{2} + G_{2}^{2} + G_{3}^{2}) + \gamma^{(0)}24(12G_{3}^{5} + 28F_{1}^{2}G_{3}^{3} + 24F_{2}^{2}G_{3}^{3} + 24G_{2}^{2}G_{3}^{3} + 32F_{1}F_{2}G_{3}^{3} - 12F_{1}G_{1}G_{2}G_{3}^{2} - 12F_{2}G_{1}G_{2}G_{3}^{2} + 12F_{1}^{4}G_{3} + 12F_{2}^{4}G_{3} + 12G_{1}^{4}G_{3} + 12G_{2}^{4}G_{3}
$$
\n
$$
+ 20F_{1}F_{2}^{3}G_{3} + 28F_{1}^{2}F_{2}^{2}G_{3} + 20F_{1}^{2}G_{1}^{2}G_{3} + 24F_{2}^{2}G_{1}^{2}G_{3} + 24F_{1}^{2}G_{2}^{2}G_{3} + 20F_{1}^{2}F_{2}^{2}G_{3}
$$
\n
$$
+ 32G_{1}^{2}G_{2}^{2}G_{3} + 28F_{1}^{2}F_{2}^{2}G_{3} + 20F_{1}^{2}F_{2}G_{3}^{2} + 24F_{2}^{2}G_{1}^{2}G_{3} + 24F_{1}^{2}G_{1}^{2}G_{3} + 24F_{1}^{2}F_{2}^{2}G_{1}G_{2}
$$
\n<math display="</math>

for *G*3.

APPENDIX B: PLOTS OF THE THREE-DIMENSIONAL VECTOR *f* **(***d***˜) OF THE DOMAIN WALLS**

We present the plots of the three-dimensional vector $f(\tilde{d}) = (f_1(\tilde{d}; n), f_2(\tilde{d}; n), f_3(\tilde{d}; n))$ in Eq. [\(11\)](#page-4-0), as functions of \tilde{d} for a fixed *n*, in the three-dimensional coordinate $(\tilde{x}_1, \tilde{x}_2, \tilde{x}_3)$ as the solutions of the EL equation [\(8\)](#page-4-0) for the domain walls: W_i^{α} (UN) with $\alpha = 1, 2, 3$ in Fig. 10, W_i^{α} (D₂BN) with $\alpha = 13, 2$ in Fig. [11,](#page-17-0) and W_i^{13} (D₄BN) in Fig. [12.](#page-17-0) The subscripts $i = 1, 2, 3$ denote the direction of the domain walls, \tilde{x}_1 , \tilde{x}_2 , and \tilde{x}_3 directions, respectively.

FIG. 10. The plots of the profile functions as the three-dimensional vectors $f(\tilde{d}) = (f_1(\tilde{d}; \mathbf{n}), f_2(\tilde{d}; \mathbf{n}), f_3(\tilde{d}; \mathbf{n}))$ with $f_1(\tilde{d}; \mathbf{n}) + f_2(\tilde{d}; \mathbf{n}) + f_3(\tilde{d}; \mathbf{n})$ $f_3(\tilde{d}; \mathbf{n}) = 0$ for the domain walls W_i^2 , W_i^1 , and W_i^3 ($i = 1, 2, 3$ the directions along \tilde{x}_1 , \tilde{x}_2 , and \tilde{x}_3 directions) in the bulk UN phase.

FIG. 11. The plots of the profile functions as the three-dimensional vectors $f(\tilde{d}) = (f_1(\tilde{d}; \mathbf{n}), f_2(\tilde{d}; \mathbf{n}), f_3(\tilde{d}; \mathbf{n}))$ with $f_1(\tilde{d}; \mathbf{n}) + f_2(\tilde{d}; \mathbf{n}) + f_3(\tilde{d}; \mathbf{n})$ $f_3(\tilde{d}; \mathbf{n}) = 0$ for the domain walls W_i^2 and W_i^{13} (*i* = 1, 2, 3 the directions along \tilde{x}_1, \tilde{x}_2 , and \tilde{x}_3 directions) in the bulk D₂-BN phase.

FIG. 12. The plots of the profile functions as the three-dimensional vectors $f(\tilde{d}) = (f_1(\tilde{d}; \mathbf{n}), f_2(\tilde{d}; \mathbf{n}), f_3(\tilde{d}; \mathbf{n}))$ with $f_1(\tilde{d}; \mathbf{n}) + f_2(\tilde{d}; \mathbf{n}) + f_3(\tilde{d}; \mathbf{n})$ $f_3(\tilde{d}; \mathbf{n}) = 0$ for the domain walls W_i^{13} (*i* = 1, 2, 3 the directions along \tilde{x}_1, \tilde{x}_2 , and \tilde{x}_3 direction) in the bulk D₄-BN phase.

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