

Spin-motive force due to domain-wall motion in the presence of Dzyaloshinskii-Moriya interaction

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We theoretically demonstrate that the presence of Dzyaloshinskii-Moriya interaction (DMI) can lead to enhancement of the spin-motive force (SMF) arising due to field-induced ferromagnetic domain-wall motion. A SMF refers to an electric voltage induced by dynamical magnetic textures, which reflects the temporal and spatial variations of the magnetization. A DMI can introduce extra spatial rotation of the magnetization in the domain-wall region, which turns out to cause the enhancement of the SMF. We derive an expression for the SMF, and examine the field and DMI dependencies of the SMF. We find that the SMF can be amplified by up to an order of magnitude in the low field regime, where the external field is lower than the so-called Walker breakdown field.

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I. INTRODUCTION

The exchange interaction between the conduction electron spin and the local magnetization in magnetic materials is responsible for a variety of important phenomena. Among the spintronic effects caused by this interaction, spin-transfer torque [1,2] paves a path to promising information technology, providing an efficient way of manipulating the magnetization by charge current [3]. As a reciprocal process, the same interaction can also mediate an electric-voltage generation by dynamical magnetic textures. This electric voltage (or the mechanism that induce the electric voltage) is known as spin-motive force (SMF) [4–9]. A SMF reflects temporal and spatial variations of the magnetization, and thus offers a powerful method to probe and explore various dynamical magnetic textures, such as a moving domain wall (DW) [4,6,10–16], magnetic vortex [17–19], and skyrmion lattice [20,21].

Theoretically, SMF can be attributed to a spin-dependent electric field [22–24], which is often referred to as spin electric field, arising due to the exchange coupling and acting on the conduction electrons. While the basic concept and theoretical framework of SMF had been established through the 1970s–1990s [4,5,23–26], the first experimental confirmations had to wait until the late 2000s [11,16,19,27–29] since it requires a control of dynamical magnetic textures at the precision of submicron meter scales. The development of the SMF theory in the past decade has shed light on the roles of the nonadiabaticity in electron spin dynamics [30–34] and the Rashba spin-orbit coupling [35–39] on the SMF. The possibility of SMF in antiferromagnetic materials has recently been pointed out [40–43].

The experimentally observed SMFs thus far are typically 100 nV–1 μ V in magnitude [11,16,19,28,29]. To achieve larger SMF is deemed indispensable towards realization of spintronic devices actively exploiting SMF. In this article we address this problem demonstrating that, in the presence of Dzyaloshinskii-Moriya interaction (DMI), the SMF due to field-induced DW motion can be enhanced by up to an

order of magnitude in low field regime [44]. A DMI arises in systems with broken inversion symmetry [45,46], favoring spatially rotating magnetic structures with a specific rotational sense. In the present study, we focus on the so-called bulk DMI [47–50], which emerges due to noncentrosymmetric crystal structures such as in B20 compounds [51]. The presence of bulk DMI leads to extra spatial rotation of the magnetization in the DW region [52–55], which turns out to play a crucial role in the enhancement of the SMF. We derive an expression for the SMF, and examine the field and DMI dependencies of the SMF. Our results suggest a new perspective on DMI materials as a suitable stage for pursuit of larger SMF and for certain types of SMF applications.

II. DOMAIN-WALL DYNAMICS

Let us begin by examining the field-induced DW dynamics in the presence of DMI. We consider a one-dimensional ferromagnetic nanowire extending along the z axis (the inset of Fig. 1), whose magnetic energy density u is assumed as

$$u = A \left(\frac{\partial \vec{m}}{\partial z} \right)^2 - K m_z^2 + K_{\perp} m_y^2 - D \left(m_x \frac{\partial m_y}{\partial z} - m_y \frac{\partial m_x}{\partial z} \right) - \mu_0 M_S \vec{m} \cdot \vec{H}, \quad (1)$$

where \vec{m} is the unit vector that defines the magnetization direction, A is the exchange stiffness, $K (> 0)$ and $K_{\perp} (> 0)$ are the easy-axis and hard-axis anisotropy constants, respectively, D is the DMI constant, M_S is the saturation magnetization, and \vec{H} is the external magnetic field. Our form of DMI corresponds to the so-called Dzyaloshinskii vector lying in the z axis, and here we assume $D > 0$.

In the parameter regime of $D^2 > 4AK$ the ground state is unique, which is a magnetic spiral configuration, and it prevents the formation of a DW [52]. For $D^2 < 4AK$, on the other hand, the two solutions $m_z = \pm 1$ minimize the magnetic energy, thus allowing a DW to exist as a transition region from one solution to another. Assuming the hard-axis anisotropy

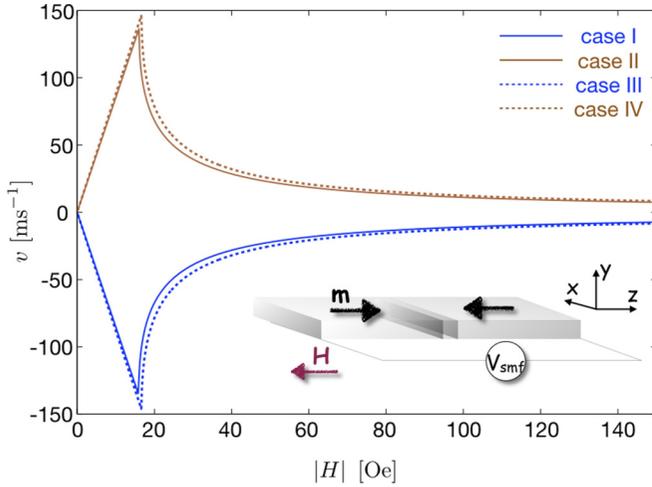


FIG. 1. Magnetic field $|H|$ dependence of DW velocity v for four different sets of (D, Q) , calculated by numerically solving Eqs. (5) and (6). Cases I, II, III, and IV show the results for $(D, Q) = (10^{-3} \text{ J m}^{-2}, +1)$, $(10^{-3} \text{ J m}^{-2}, -1)$, $(0, +1)$, and $(0, -1)$, respectively; the color of the curves indicates the sign of Q (blue for $Q = +1$ and brown for $Q = -1$), while the style of the curves distinguishes $D \neq 0$ (solid curves) and $D = 0$ (dashed curves). In the presence of DMI, the Walker breakdown fields H_W are shifted by several percent, consistent with Eq. (7) that is derived by the collective-coordinate model. In the inset, schematic of the studied system is depicted.

to be small compared to the easy-axis anisotropy and the DMI, an equilibrium DW solution that locally minimizes the magnetic energy is given by [52,53]

$$\theta(z) = 2 \tan^{-1} e^{Q(z-z_0)/\Delta}, \quad (2)$$

$$\phi(z) = \Gamma z + \varphi, \quad (3)$$

where the polar angles (θ, ϕ) are defined by $\vec{m} = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$, z_0 represents the DW center position, Δ is the DW width parameter given by $\Delta = \Delta_0(1 - D^2/4AK)^{-1/2}$ with $\Delta_0 = (A/K)^{1/2}$, Q is the topological charge of the DW defined by $Q = \pi^{-1} \int_{-\infty}^{\infty} dz(\partial\theta/\partial z) = \pm 1$ ($Q = +1$ corresponds to a head-to-head DW, while $Q = -1$ to a tail-to-tail one), $\Gamma = D/2A$, and φ is a constant that takes 0 or π in equilibrium. In the absence of DMI ($D = 0$), Eqs. (2) and (3) reduce to the usual Walker solution with $\Delta = \Delta_0$ and $\Gamma = 0$ [56].

The DW can be driven into motion by an external magnetic field $\vec{H} = H\vec{e}_z$. We here assume H to be sufficiently weak that the dynamical DW sustains the structure of Eqs. (2) and (3), but with $z_0(t)$ and $\varphi(t)$ becoming time dependent. In this case, since the time evolution of \vec{m} occurs only through that of z_0 and φ , these two parameters are regarded as the collective coordinates for the DW dynamics [56]; the variation of $z_0(t)$ corresponds to the translational motion of the DW along the nanowire, while $\varphi(t)$ describes the rotational motion of the DW magnetization around the z axis.

The dynamics of the magnetization \vec{m} in general obeys the Landau-Lifshitz-Gilbert equation

$$\frac{\partial \vec{m}}{\partial t} = -\gamma \vec{m} \times \vec{H}_{\text{eff}} + \alpha \vec{m} \times \frac{\partial \vec{m}}{\partial t}, \quad (4)$$

where γ is the gyromagnetic ratio, α is the Gilbert damping constant, and $\vec{H}_{\text{eff}} = -(\mu_0 M_S)^{-1} \delta u / \delta \vec{m}$ is the effective magnetic field. Equation (4) with the above-introduced ansatz leads to a set of equations of motion for (z_0, φ) [55],

$$\frac{dz_0}{dt} = \frac{Q\gamma\Delta}{1+\alpha^2} \left[\alpha H + \frac{\zeta(1-Q\alpha\Gamma\Delta)}{\Delta} \frac{H_k}{2} \sin 2\varphi \right], \quad (5)$$

$$\frac{d\varphi}{dt} = \frac{\gamma}{1+\alpha^2} \left[(1+Q\alpha\Gamma\Delta)H - \frac{\zeta\Delta}{\Delta_0^2} \frac{\alpha H_k}{2} \sin 2\varphi \right], \quad (6)$$

where $H_k = 2K_{\perp}/\mu_0 M_S$ and $\zeta = \pi\Gamma\Delta^2/\sinh(\pi\Gamma\Delta)$.

Figure 1 plots the DW velocity $v = T^{-1} \int_0^T dt(dz_0/dt)$, obtained by numerically simulating Eqs. (5) and (6) from $t = 0$ to $T = 10 \mu\text{s}$, as a function of $|H|$ for four different sets of (D, Q) . Cases I, II, III, and IV correspond to $(10^{-3} \text{ J m}^{-2}, +1)$, $(10^{-3} \text{ J m}^{-2}, -1)$, $(0, +1)$, and $(0, -1)$, respectively. The other parameters are common for the four cases, which are $A = 10^{-11} \text{ A m}^{-1}$, $K = 4 \times 10^5 \text{ J m}^{-3}$, $K_{\perp} = 10^5 \text{ J m}^{-3}$, $M_S = 6 \times 10^5 \text{ A m}^{-1}$, $\gamma = 2.211 \times 10^5 (\text{A m}^{-1})^{-1} \text{ s}^{-1}$, and $\alpha = 0.01$. Notice that $H = -|H|$, as depicted in the inset of Fig. 1. The DW mobility $|\partial v/\partial H|$ sharply drops at the so-called Walker breakdown field H_W [57], which is in the presence of bulk DMI given by [55]

$$H_W = \frac{\zeta\Delta/\Delta_0^2}{1+Q\alpha\Gamma\Delta} \frac{\alpha H_k}{2}, \quad (7)$$

and estimated as $\simeq 16 \text{ Oe}$ for I, $\simeq 15.9 \text{ Oe}$ for II, and $\simeq 16.7 \text{ Oe}$ for III and IV, respectively. For $|H| < H_W$, the last term in Eq. (6) cancels out the other terms at $\varphi = \frac{1}{2} \sin^{-1} \frac{2(1+Q\alpha\Gamma\Delta)\Delta_0^2}{\alpha} \frac{H}{\zeta\Delta H_k}$, resulting in a purely translational DW motion with $d\varphi/dt = 0$. Once $|H|$ exceeds H_W , the rotational dynamics with $d\varphi/dt \neq 0$ takes place, leading to the decrease in the DW mobility.

Within the collective-coordinate model with our present choice of parameter values, which are in a reasonable range for typical bulk-DMI materials [58], the effect of the DMI on DW velocity is merely to reduce H_W by several percent. We will find shortly, nevertheless, that the DMI can have a major impact on the SMF that is induced by the DW motion. For more systematic study of the field-driven DW dynamics itself in the presence of bulk DMI, see Ref. [55], where the collective-coordinate model is compared with micromagnetic simulations.

III. ELECTRIC VOLTAGE GENERATION

Now let us discuss the SMF induced by the DW dynamics. In an itinerant ferromagnet, the conduction electrons are subject to the spin electric field [22–24,30–33]

$$\mathcal{E} = \frac{P\hbar}{2e} \left[\sin \theta \left(\frac{\partial \theta}{\partial t} \frac{\partial \phi}{\partial z} - \frac{\partial \theta}{\partial z} \frac{\partial \phi}{\partial t} \right) + \beta \left(\frac{\partial \theta}{\partial t} \frac{\partial \theta}{\partial z} + \sin^2 \theta \frac{\partial \phi}{\partial t} \frac{\partial \phi}{\partial z} \right) \right], \quad (8)$$

which arises as a result of the electron-magnetization exchange interaction. Here P represents the spin polarization of the conduction electrons, and β is the dimensionless parameter characterizing the nonadiabaticity in the electron spin

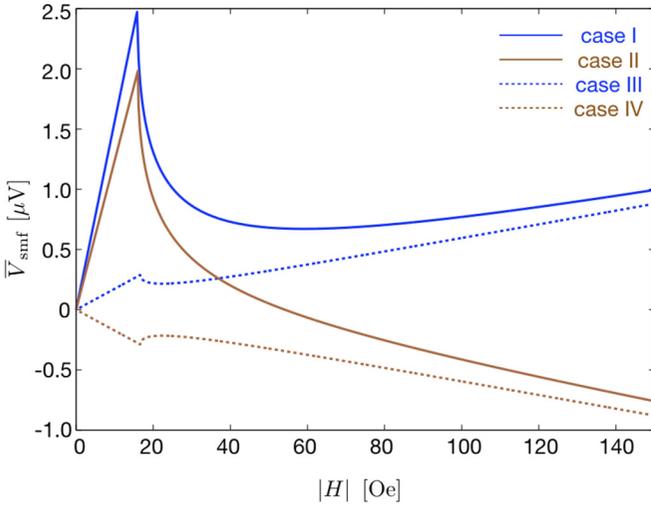


FIG. 2. Magnetic field $|H|$ dependence of the time-averaged SMF \bar{V}_{smf} , obtained based on Eq. (9) with the DW dynamics numerically computed by Eqs. (5) and (6). Cases I, II, III, and IV refer to the same sets of (D, Q) as in Fig. 1. In each case, $|\bar{V}_{\text{smf}}|$ experiences a sharp drop at $|H| = H_W \simeq 16\text{--}17$ Oe, reflecting the Walker breakdown in the DW dynamics. In the presence of DMI (cases I and II), the enhancement of \bar{V}_{smf} is attributed to the extra spatial rotation that the magnetization acquires in the DW region, which invokes the $\partial\phi/\partial z$ terms in Eq. (8). The effect of the DMI is most pronounced for $|H| < H_W$, in which $|\bar{V}_{\text{smf}}|$ for $D \neq 0$ are nearly an order of magnitude greater than those for $D = 0$. As $|H|$ is increased passing H_W , the \bar{V}_{smf} curves with $D \neq 0$ converge to the curves for $D = 0$. These behaviors of \bar{V}_{smf} are understood from the analytical results, Eqs. (10) and (11).

dynamics. From the perspective of looking at the SMF as the reciprocal effect of spin-transfer torque [9], the terms in the first and second lines in Eq. (8) are the counterparts of, respectively, the so-called adiabatic and nonadiabatic spin-transfer torques. Equation (8) requires the temporal and spatial derivatives of \vec{m} to be finite simultaneously, and this condition is indeed satisfied around the dynamical DW.

The spin electric field can accelerate the conduction electrons in the same fashion as the ordinary electric field does, resulting in the electric voltage $V_{\text{smf}} = \int_{-\infty}^{\infty} dz \mathcal{E}$ appearing across the DW. In the absence of DMI, ϕ is spatially uniform [see Eq. (3)] and thus the terms that contain $\partial\phi/\partial z$ in Eq. (8) vanish. When $D \neq 0$, in contrast, these terms can no longer be ignored since $\partial\phi/\partial z = \Gamma$. We will show that the $\frac{\partial\theta}{\partial t} \frac{\partial\phi}{\partial z}$ term in Eq. (8) indeed provides the most dominant contribution to V_{smf} in the field regime of $|H| < H_W$.

Using the DW dynamics obtained by the collective-coordinate approach and doing some elementary algebra, one obtains

$$V_{\text{smf}} = -\frac{P\hbar}{e} \left[(\beta + Q\Gamma\Delta) \frac{1}{\Delta} \frac{dz_0}{dt} + (Q - \beta\Gamma\Delta) \frac{d\phi}{dt} \right]. \quad (9)$$

Equation (9) contains our central results, revealing the way the DMI contributes to the SMF. For $D = 0$, Eq. (9) reproduces the expression for the SMF known from the previous studies [31,34]. In the following, we examine Eq. (9) more closely.

Figure 2 displays the time-averaged SMF $\bar{V}_{\text{smf}} = T^{-1} \int_0^T dt V_{\text{smf}}(t)$ as a function of $|H|$, where $V_{\text{smf}}(t)$ is computed by Eq. (9), with dz_0/dt and $d\phi/dt$ numerically simulated as before. Cases I–IV refer to the same sets of parameters as in Fig. 1. For P and β we employed $P = 0.5$ and $\beta = 0.03$ for all four cases.

The influence of the DMI is most prominent for $|H| < H_W \simeq 16\text{--}17$ Oe, where \bar{V}_{smf} exhibits the linear dependence on $|H|$ for all four cases, while its slope is remarkably enhanced in the presence of DMI. As for the sign of \bar{V}_{smf} , it is positive for both I and II regardless of the sign of Q . This is in contrast to the simple linear Q dependence for $D = 0$, i.e., $\bar{V}_{\text{smf}}(H, D = 0, Q = +1) = -\bar{V}_{\text{smf}}(H, D = 0, Q = -1)$. In this field regime, an analytical expression for the SMF is available from Eqs. (5), (6), and (9) as

$$V_{\text{smf}} = -\frac{P\hbar}{e} \frac{Q\beta + \Gamma\Delta}{\alpha} \frac{\Delta_0^2}{\Delta^2} \gamma H \quad (|H| < H_W). \quad (10)$$

This is time independent, and can be directly compared to \bar{V}_{smf} in Fig. 2. Because $\Gamma\Delta \simeq 0.55 \gg \beta$, the Q -independent $\Gamma\Delta$ term in Eq. (10) dominates the other one, which explains the above-mentioned behavior of \bar{V}_{smf} . Notice that \bar{V}_{smf} reaches as high as $\sim 2.5 \mu\text{V}$ at $|H| \simeq H_W \simeq 16$ Oe for case I. The largest experimentally observed SMF due to DW motion thus far is $\sim 1 \mu\text{V}$ with $|H| \simeq 150$ Oe, exploiting Permalloy nanowires [16].

As $|H|$ is increased passing H_W , the impact of the DMI on the SMF diminishes; after hitting the peaks at $|H| = H_W$, the \bar{V}_{smf} curves for $D \neq 0$ sharply plunge and approach the curves for $D = 0$ (I approaches III, and II to IV, as seen in Fig. 2). This may be understood from the fact that, in Eq. (9), the dz_0/dt term is dominated by the DMI contribution since $\Gamma\Delta \gg \beta$, while the DMI is less important for the $d\phi/dt$ term because $1 \gg \beta\Gamma\Delta$. For $|H| < H_W$, the DW dynamics is a pure translational motion ($d\phi/dt = 0$), and this is because in this field regime the effect of the DMI is most pronounced, as discussed before. For $|H| > H_W$, the decrease in dz_0/dt and the switching on of $d\phi/dt$ spoil the influence of the DMI. When $|H|$ is large enough compared to H_W so that the oscillating terms ($\propto \sin 2\phi$) in Eqs. (5) and (6) can be neglected in the time-averaged DW dynamics, an approximate expression for the SMF may be given by

$$\bar{V}_{\text{smf}} \simeq -\frac{P\hbar}{e} [Q - \Gamma\Delta(\beta - 2\alpha)] \gamma H \quad (|H| \gg H_W), \quad (11)$$

where $\alpha, \beta \ll 1$ has been used. Since $\Gamma\Delta(\beta - 2\alpha) \ll 1$, the DMI only presents a small correction to \bar{V}_{smf} in this field regime, being consistent with the above argument.

We should remark here that a larger DMI does not always lead to a higher SMF because, according to Eq. (7), H_W monotonically decreases as D increases, see the inset of Fig. 3. We plot the D dependence of \bar{V}_{smf} in Fig. 3, where the purple and black curves show the results with H being fixed at -13 and -130 Oe, respectively, and $Q = +1$ for both cases. (The other parameters are again the same as before.) For the latter case, $|H|$ is well above H_W regardless of the value of D , and the SMF is thus relatively insensitive to D as discussed before. For $H = -13$ Oe, on the other hand, $|H| < H_W$ for $D < D_c \simeq 2.1 \times 10^3 \text{ J m}^{-2}$, while $|H| > H_W$ for $D > D_c$. This is why \bar{V}_{smf} increases with D up to D_c , and decreases

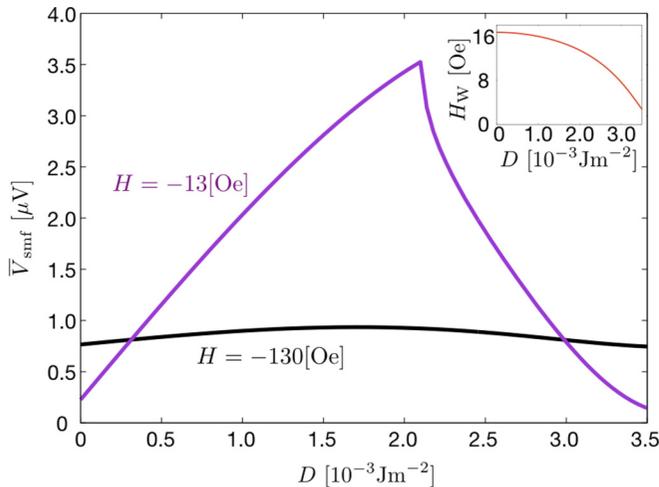


FIG. 3. DMI constant D dependencies of the time-averaged SMF \bar{V}_{smf} , with H fixed at $H = -13$ Oe (purple curve) and $H = -130$ Oe (black curve). In the latter case, \bar{V}_{smf} is relatively insensitive to D because $|H| \gg H_W$ at any value of D . For the case with $H = -13$ Oe, on the other hand, \bar{V}_{smf} increases with D up to $D = D_c \simeq 2.1 \times 10^{-3} \text{ J m}^{-2}$, while decreases with D for $D > D_c$. This reflects the fact that at $D = D_c$, $|H|$ coincides with H_W . The other parameters are taken as the same in the previous calculations, and $Q = +1$ for both cases. This result shows that a larger DMI does not always lead to a higher SMF; the material should be carefully chosen to have sufficiently large Walker breakdown field as well as large DMI. In the inset, D dependence of H_W is plotted based on Eq. (7), where H_W monotonically decreases as D increases, and converges to zero as $D \rightarrow (4AK)^{1/2} = 4 \times 10^{-3} \text{ J m}^{-2}$.

with D for $D > D_c$. Desirable materials, in terms of pursuing larger SMF, would have large DMI as well as large magnetic anisotropies.

IV. DISCUSSION AND CONCLUSIONS

When estimating the SMF with different values for D , as in Figs. 2 and 3, we simply assumed the other parameters to be fixed. The inclusion of DMI may imply, however, the necessity of correction to some material parameters; α , β , and the magnetic anisotropies have their origins in common with the DMI, i.e., the spin-orbit coupling, and the broken inversion symmetry may also affect the exchange coupling. The possible modifications to those parameters accompanying the change in the DMI may require more careful analysis for a more detailed and quantitatively accurate examination of the DMI dependence of SMF.

In conclusion, we have theoretically demonstrated that DMI is capable of dramatically amplifying the SMF arising due to field-induced DW dynamics. Importance of DMIs in the magnetism community has been growing in recent years since they can stabilize magnetic skyrmion lattices as well as individual skyrmions, which exhibit various characteristic properties that are advantageous for technological applications [59–62]. In the context of DW physics, interfacial DMIs have been widely studied since in perpendicularly magnetized materials they stabilize either Bloch or Néel wall with specific chirality [63,64], resulting in high efficiency in current-driven DW motion [65]. A bulk DMI, on the other hand, invokes the spatial variation of ϕ and does not necessarily lead to higher DW velocity. We believe our results have revealed a novel importance of bulk DMI in the SMF-related DW physics, and have made a vital step towards realization of SMF-based spintronic devices.

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