Berry phase of adiabatic electronic configurations in fullerene anions

Naoya Iwahara*

Theory of Nanomaterials Group, University of Leuven, Celestijnenlaan 200F, B-3001 Leuven, Belgium



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The selection rule on vibronic angular momentum of a $t_{1u}^n \otimes h_g$ Jahn-Teller problem (n=1–5) is reinvestigated. It is shown that among three adiabatic orbitals only two have nonzero Berry phase. Thus, the Berry phase of adiabatic electronic configurations depends on the spin multiplicity as well as the number of electrons. On this basis, the general relation between the Berry phase and the angular momentum is described. It allows us, in particular, to clarify the nature of vibronic states arising from high spin configurations. In comparison with the previous solution for the low-lying vibronic states for bimodal systems, the present solutions correctly fulfill all the symmetry requirements.

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I. INTRODUCTION

It is widely accepted that the Berry phase [1] appears in various physical systems and characterizes their properties. In molecular physics, the Berry phase has been recognized as the sign change of an adiabatic orbital by the excursion along the path encircling the degenerate point in the nuclear configuration space [2–6]. Within the dynamic $E \otimes e$ Jahn-Teller (JT) problem, where the double degenerate E electronic state couples to double degenerate e normal mode, the phase change makes the angular momentum characterizing the vibronic states half-integer [2,4], which has been experimentally addressed to evidence the Berry phase [7,8]. The relation between the Berry phase and the vibronic states was clarified by Ham [9]. He found in the $E \otimes e$ JT problem that the sequence of the irreducible representations of the vibronic states is modified by the presence of the Berry phase. Since then the relation between the vibronic (also rovibronic) states and the Berry phase has been intensively studied [10–23].

The majority of the works have addressed the simple cases where one electron or hole occupies degenerate orbitals, whereas Auerbach *et al.* [12] studied the relation between the Berry phase and the population of the orbital shell as in the case of fullerene anions (C_{60}^{n} , n=1–5). In their study of the $t_{1u}^{n} \otimes h_{g}$ JT model, where a triply degenerate t_{1u} orbital couples to the fivefold degenerate h_{g} vibrations, the following selection rule for the vibronic angular momentum L was proposed [12]:

$$(-1)^{n+L} = 1. (1)$$

This relation indeed gives correct L of low-spin ground vibronic states in the strong coupling limit. However, being applied to the description of the high-spin terms, it gives contradictory results. For example, the selection rule always predicts odd L for the t_{1u}^1 system and even L for the t_{1u}^2 system, whereas the spin triplet (high-spin) state of the t_{1u}^2 system must have odd L because the vibronic Hamiltonian is isomorphic to the one for t_{1u}^1 . Although the isomorphism has

been confirmed later [13,24], the relation between the Berry phase and high-spin state has not been elucidated.

In this work, the selection rule for vibronic angular momentum in the $t_{1u}^n \otimes h_g$ JT problem is revisited. The symmetry properties of adiabatic orbitals are inspected, and the Berry phases of t_{1u}^n electron configurations are established. On this basis, the selection rule on angular momentum (1) is generalized for both low- and high-spin adiabatic configurations. The present solution for the vibronic state of the bimodal system is consistent with the symmetry requirement.

II. VIBRONIC HAMILTONIAN

In C_{60}^{n-} anions with icosahedral symmetry, the triply degenerate t_{1u} orbital couples to the fivefold degenerate h_g normal mode [25]. Although there are eight sets of JT active h_g modes in the C_{60} molecule, the effective model including only one set of h_g modes is considered. Moreover, the bielectronic interaction which induces the term splitting is neglected. The model vibronic Hamiltonian consists of the harmonic oscillator part \hat{H}_0 and the linear vibronic part \hat{H}_{JT} [12,13,26]:

$$\hat{H} = \hat{H}_0 + \hat{H}_{\rm JT}.\tag{2}$$

The first contribution is the vibrational Hamiltonian for JT active modes [27],

$$H_0 = \sum_{\gamma = \theta, \epsilon, \xi, \eta, \zeta} \frac{\hbar \omega}{2} (p_{\gamma}^2 + q_{\gamma}^2), \tag{3}$$

where q_{γ} and p_{γ} are dimensionless normal coordinates and the conjugate momenta [12], ω is frequency, and a real basis for the h_g representation is used [28]. The vibronic interaction is given by [12,13,26,29]

$$\begin{split} \hat{H}_{\rm JT} &= \sum_{\sigma} \hbar \omega g(\hat{c}_{x\sigma}^{\dagger}, \hat{c}_{y\sigma}^{\dagger}, \hat{c}_{z\sigma}^{\dagger}) \\ &\times \begin{pmatrix} \frac{1}{2} q_{\theta} - \frac{\sqrt{3}}{2} q_{\epsilon} & -\frac{\sqrt{3}}{2} q_{\zeta} & -\frac{\sqrt{3}}{2} q_{\eta} \\ -\frac{\sqrt{3}}{2} q_{\zeta} & \frac{1}{2} q_{\theta} + \frac{\sqrt{3}}{2} q_{\epsilon} & -\frac{\sqrt{3}}{2} q_{\xi} \\ -\frac{\sqrt{3}}{2} q_{\eta} & -\frac{\sqrt{3}}{2} q_{\xi} & -q_{\theta} \end{pmatrix} \begin{pmatrix} \hat{c}_{x\sigma} \\ \hat{c}_{y\sigma} \\ \hat{c}_{z\sigma} \end{pmatrix}, \end{split}$$

^{*}naoya.iwahara@kuleuven.be

where $\hat{c}^{\dagger}_{\gamma\sigma}$ and $\hat{c}_{\gamma\sigma}$ are the electron creation and annihilation operators in the t_{1u} orbital λ (= x, y,z) with z component of electron spin σ (= \uparrow , \downarrow), respectively, and g is the dimensionless vibronic coupling parameter. Hereafter, for simplicity, the Hamiltonian is measured in units of $\hbar\omega$, and the phase factor of the normal mode is chosen so that g > 0.

The harmonic oscillator and the electronic Hamiltonian (orbital energy is set to zero) possess SO(5) and SO(3) symmetries, respectively, and the symmetry of the system is SO(5) \otimes SO(3), which is reduced by the vibronic interaction to SO(3) symmetry [30]. The vibronic angular momentum \hat{L} is defined by the sum of vibrational part L_{vib} and electronic part \hat{L}_{el} . The Hamiltonian \hat{H} , the squared angular momentum \hat{L}^2 , and one of the components, e.g., \hat{L}_z , mutually commute. Therefore, the vibronic state (eigenstate of \hat{H}) is characterized by angular momentum L and its z component M. In this work, the selection rule on the angular momentum L is derived in the strong limit of the vibronic coupling $g \gg 1$.

III. POLAR COORDINATES

In the strong coupling limit, the adiabatic orbitals [eigenstates of the matrix in $\hat{H}_{JT}(4)$] give fundamental information of the low-energy electronic states. For the diagonalization, it is convenient to introduce the polar coordinates [12,13,26,30]. Because of its importance, the parametrization of the t_{1u} orbitals and the h_g coordinates is described in detail below.

We make use of the analogy between the derivation of adiabatic orbitals and that of the principal values of the inertia tensor of a rigid body,

$$\sum_{\lambda,\lambda'=x,y,z} \omega_{\lambda} I_{\lambda\lambda'} \omega_{\lambda'} \to \sum_{i=1,2,3} I_i \omega_i^2, \tag{5}$$

where $I_{\lambda\lambda'}$ is the inertia moment and ω_{λ} is the λ component of the angular velocity in the laboratory coordinate system (x,y,z), and I_i and ω_i (i=1,2,3) are the principal moment of inertia and the angular velocity in the rotating coordinate system spanned by axes i [Fig. 1(a)] [31]. Suppose both coordinate systems are right handed, they are related by the rotation defined by Euler angle $\Omega=(\phi,\theta,\psi)$ with the range of $0 \le \theta \le \pi$, $0 \le \phi,\psi < 2\pi$. In the JT problem, Eq. (4) and its diagonal form

$$\hat{H}_{\rm JT} = \sum_{\sigma} \sum_{i=1}^{3} \varepsilon_i \hat{n}_{i\sigma} \tag{6}$$

are, respectively, regarded as left- and right-hand sides of Eq. (5). Thus, x, y, z and 1,2,3 axes correspond to the laboratory and rotating coordinates, the adiabatic orbital energy ε_i to I_i , and the adiabatic orbitals

$$\hat{a}_{i\sigma}^{\dagger} = \sum_{\lambda = x, y, z} \hat{c}_{\lambda\sigma}^{\dagger} D_{\lambda i}^{(1)}(\Omega) \tag{7}$$

to ω_i . Here $D^{(1)}$ is a Wigner D function of rank 1 with the Condon-Shortley phase convention [32], and $\hat{n}_{i\sigma} = \hat{a}^{\dagger}_{i\sigma}\hat{a}_{i\sigma}$. With the real basis of representations, Wigner D functions are real.

The parametrization of five dimensional coordinates in Ref. [33] is adapted to the JT problem. The obtained

coordinates and the ranges are equivalent to those in Refs. [12,13,26,30,34]. In general, three ε_i 's differ from each other, whereas the trace of the matrix is invariant under rotation (i.e., $\sum_{i=1}^{3} \varepsilon_i = 0$), and thus, they are expressed by two parameters. The deformation of the spheroid from the sphere ($\varepsilon_1 = \varepsilon_2 = \varepsilon_3$) is described by linear combination of the real parts of spherical harmonics Y_{2m} [32] of rank 2 and component $m = 0, \pm 2$ in the rotating coordinate system:

$$\begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{pmatrix} = a_{\theta}' \mathbf{e}_{\theta}' + a_{\epsilon}' \mathbf{e}_{\epsilon}' = gq \begin{pmatrix} -\cos\left(\alpha - \frac{2\pi}{3}\right) \\ -\cos\left(\alpha + \frac{2\pi}{3}\right) \\ -\cos\alpha \end{pmatrix}. \tag{8}$$

Here $e'_{\theta} = \frac{1}{\sqrt{6}}(-1, -1, 2)^T$ and $e'_{\epsilon} = \frac{1}{\sqrt{2}}(1, -1, 0)^T$ are the θ (Y_{20}) and $\epsilon \left(\frac{1}{\sqrt{2}}[Y_{2,-2}+Y_{22}]\right)$ types of deformations, respectively, the coordinates a'_{κ} ($\kappa = \theta, \epsilon$) are parametrized as $a'_{\theta} =$ $-\frac{\sqrt{6}}{2}gq\cos\alpha$ and $a'_{\epsilon}=-\frac{\sqrt{6}}{2}gq\sin\alpha$. The coefficient $(-\frac{\sqrt{6}}{2})$ and g are introduced by comparing the forms of the Hamiltonians (4) and (6) in the special case where two coordinate systems coincide (x = 1, y = 2, z = 3). In this case, q corresponds to the magnitude of the deformation and α determines the direction in the q_{θ} - q_{ϵ} plane $(0 \leqslant q \text{ and } -\pi \leqslant \alpha < \pi)$. The other coordinates ($\kappa = \xi, \eta, \zeta$) do not contribute because they only modify the angles between the principal axes. Similarly, the shape of the rigid body is written as $\sum_{\gamma} q_{\gamma} {m e}_{\gamma}$ in the laboratory coordinate system, where the polarization vectors e_{ν} 's also express the deformation of rank 2. The polarization vectors e'_{κ} are obtained by rotation of the polarization vectors e_{γ} in the laboratory coordinate system $e'_{\kappa} = \sum_{\gamma} e_{\gamma} D_{\gamma\kappa}^{(2)}(\Omega)$, and hence, the normal coordinates $q'_{\kappa} (= \frac{2}{\sqrt{6}\sigma} a'_{\kappa})$ and q_{γ} are related by the inverse rotation

$$q_{\gamma} = \sum_{\kappa = \theta, \epsilon} D_{\gamma\kappa}^{(2)}(\Omega) q_{\kappa}'. \tag{9}$$

It results that the five dimensional h_g coordinates are described by the shape (q,α) and the orientation (Ω) of the rigid body [Fig. 1(a)]. However, the Cartesian q_{ν} and polar (q,α,Ω) coordinates are not in a one-to-one correspondence because the latter have extra degrees of freedom to label the principal axes (1,2,3) and to fix their directions [Fig. 1(a) is an example]. The degrees of freedom amount to as many as 48 ways ($\cong O_h$) given the numbers of combinations are 3! = 6 for the former and $2^3 = 8$ for the latter. By choosing the labels and the directions, the ranges of the polar coordinates are restricted. Different labeling of the axes for a certain set of orbital energies (8) is achieved by shifting α . Figure 1(b) shows that there are six physically equivalent regions of α with different order of ε_i 's, and one of the equivalent domains has to be chosen. Now, there remain only eight ways of arbitrariness regarding the directions of axes ($\cong D_{2h}$). By taking the right-handed coordinate system, which discards the inversion of the coordinate systems, the degrees of freedom are further decreased to $4 \cong D_2$. Choosing one set of directions is equivalent to the restriction of the domain of Euler angles. The restriction can be done by using the generators of the D_2 group, for example, the C_2 (or π) rotation around principal axis 1 (R_1) and the C_2 rotation around axis 3 (R_3). Under R_1 , the Euler angles change as (see, e.g.,

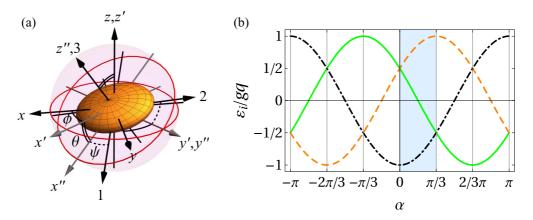


FIG. 1. (a) Laboratory (x, y, z) and rotating (1,2,3) coordinate systems and Euler angles (ϕ, θ, ψ) describing the orientation of the spheroid (orange). The red circles show x-y and 1-2 planes. (b) Evolution of ε_i (8) with respect to angle α . The green solid, orange dashed, and black dot-dashed lines correspond to ε_1 , ε_2 , ε_3 , respectively. The blue shaded region appears six times in the plot.

Ref. [33] and Sec. 4.4 in Ref. [32])

$$(\phi, \theta, \psi) \to (\phi + \pi, \pi - \theta, -\psi).$$
 (10)

Since both angles express physically the same orientations of the rigid body (ε_i 's) with different directions of the principal axes 2 and 3, their domains should not overlap. Consequently, the range of θ is narrowed as $0 \le \theta \le \frac{\pi}{2}$. By the second rotation R_3 , the Euler angles become

$$(\phi, \theta, \psi) \to (\phi, \theta, \psi + \pi),$$
 (11)

and the range of ψ decreases to $0 \leqslant \psi < \pi$. As the result, the Cartesian coordinates q_{γ} and the polar coordinates are in one-to-one correspondence when $0 \leqslant q, 0 \leqslant \alpha \leqslant \frac{\pi}{3}$ or in the other equivalent domain, $0 \leqslant \phi < 2\pi, 0 \leqslant \theta \leqslant \frac{\pi}{2}, 0 \leqslant \psi < \pi$.

Figure 1(a) uniquely defines the adiabatic orbitals and normal coordinates within the obtained domain: the directions of the principal axes of the rigid body correspond to the three adiabatic orbitals, and the shape and the orientation of the rigid body show the radial coordinates (q,α) and Euler angles (ϕ,θ,ψ) of the h_g normal coordinate, respectively. The domain of coordinates allows any shape and orientation of the rigid body such that the ellipsoid retains the order of the principal moment of inertia and the directions of the principal axes do not coincide with the other ones.

With the polar coordinates defined above, the kinetic energy term splits into a radial vibrational part and a pseudorotational part [33], the potential energy term of H_0 becomes $q^2/2$, and the vibronic term (6) contains only radial coordinates. The pseudorotational part is expressed as

$$H_{\text{rot}} = \sum_{i=1}^{3} \frac{L_i^2}{2q^2 I_i},\tag{12}$$

where I_i is the principal moment of inertia:

$$I_i = 4\sin^2\left(\alpha - i\frac{2\pi}{3}\right),\tag{13}$$

and L_i are the angular momentum of the rigid body in the rotating coordinate system [35]. One should note that I_i in Eq. (13) and I_i in Eq. (5) used for the analogy with ε_i have nothing in common. L_i corresponds to the vibrational angular momentum in the rotating coordinate system, and also to the

vibronic angular momentum L within adiabatic approximation [36].

IV. BERRY PHASE

A. Adiabatic orbitals

The phase change of each adiabatic orbital (7) is examined under the adiabatic process around the circuit in the nuclear coordinate space. Pictorially, this can be done by observing the evolution of axes i under the adiabatic transportation such that the initial and final orientations of the spheroid coincide [Fig. 1(a)]. For any loops described inside the domain of Euler angles, the axes simply return to their original positions. On the other hand, for any paths connecting two sets of Euler angles related by C_2 rotation with respect to axis i, two axes except for i are reversed at the end point with respect to those of the starting point. The reversal of the direction of axis i means the sign change of adiabatic orbital i [37]. The second type of path is also closed in nuclear configuration space because C_2 is the symmetry operation of the spheroid.

The phase change can be demonstrated more directly by using the explicit form of adiabatic orbitals,

$$\hat{a}_{1\sigma}^{\dagger} = (\cos\psi\cos\theta\cos\phi - \sin\psi\sin\phi)\hat{c}_{x\sigma}^{\dagger} + (\cos\psi\cos\theta\sin\phi + \sin\psi\cos\phi)\hat{c}_{y\sigma}^{\dagger} - \cos\psi\sin\theta\hat{c}_{z\sigma}^{\dagger},$$

$$\hat{a}_{2\sigma}^{\dagger} = -(\sin\psi\cos\theta\cos\phi + \cos\psi\sin\phi)\hat{c}_{x\sigma}^{\dagger} - (\sin\psi\cos\theta\sin\phi - \cos\psi\cos\phi)\hat{c}_{y\sigma}^{\dagger} + \sin\psi\sin\theta\hat{c}_{z\sigma}^{\dagger},$$

$$\hat{a}_{3\sigma}^{\dagger} = \sin\theta\cos\phi\hat{c}_{x\sigma}^{\dagger} + \sin\theta\sin\phi\hat{c}_{y\sigma}^{\dagger} + \cos\theta\hat{c}_{z\sigma}^{\dagger}. \quad (14)$$

Under the first type of loops the resultant phase changes are null. For the second kind of loops, the sign changes result: with R_1 (10), the adiabatic orbitals transform as

$$(\hat{a}_{1}^{\dagger}, \hat{a}_{2}^{\dagger}, \hat{a}_{3}^{\dagger}) \to (\hat{a}_{1}^{\dagger}, -\hat{a}_{2}^{\dagger}, -\hat{a}_{3}^{\dagger}),$$
 (15)

and with R_3 (11),

$$(\hat{a}_{1}^{\dagger}, \hat{a}_{2}^{\dagger}, \hat{a}_{3}^{\dagger}) \to (-\hat{a}_{1}^{\dagger}, -\hat{a}_{2}^{\dagger}, \hat{a}_{3}^{\dagger}).$$
 (16)

5

Berry phase S R_1 R_3 I_i (q,α) $\hat{a}_{3\sigma}^{\dagger}|0\rangle$ 1 (g,0)1 (3,3,0) $\hat{a}_{3\uparrow}^{\dagger}\hat{a}_{3\downarrow}^{\dagger}|0\rangle$ 2 0 $\varepsilon_3 < \varepsilon_1 = \varepsilon_2$ 1 (2g,0)(3,3,0) $\varepsilon_1 = \varepsilon_2 < \varepsilon_3$ $\hat{a}_{1\sigma}^{\dagger}\hat{a}_{2\sigma}^{\dagger}|0\rangle$ -1 (g,π) (3,3,0) $\hat{a}_{1\uparrow}^{\dagger}\hat{a}_{1\downarrow}^{\dagger}\hat{a}_{3\sigma}^{\dagger}|0\rangle$ 3 $(\sqrt{3}g,\frac{\pi}{2})$ -1(1,1,4) $\hat{a}_{1\sigma}^{\dagger}\hat{a}_{2\sigma}^{\dagger}\hat{a}_{3\sigma}^{\dagger}|0\rangle$ 1 (0, -) $\hat{a}_{1\uparrow}^{\dagger}\hat{a}_{1\downarrow}^{\dagger}\hat{a}_{2\uparrow}^{\dagger}\hat{a}_{2\downarrow}^{\dagger}|0\rangle$ 4 $\varepsilon_1 = \varepsilon_2 < \varepsilon_3$ 1 (3,3,0) $(2g,\pi)$ $\hat{a}_{1\sigma}^{\dagger}\hat{a}_{2\sigma}^{\dagger}\hat{a}_{3\uparrow}^{\dagger}\hat{a}_{3\downarrow}^{\dagger}|0\rangle$ -1(3,3,0)(g,0) $\varepsilon_3 < \varepsilon_1 = \varepsilon_2$

 $\hat{a}_{1\uparrow}^{\dagger}\hat{a}_{1\downarrow}^{\dagger}\hat{a}_{2\uparrow}^{\dagger}\hat{a}_{2\downarrow}^{\dagger}\hat{a}_{3\sigma}^{\dagger}|0\rangle$

TABLE I. The JT distortion, static JT energy, typical adiabatic states, Berry phases under rotation R_1 (10) and R_3 (11), and moments of inertia I_i .

Indeed, for C_2 rotation around axis i, all the adiabatic orbitals except for i change their signs. This result is consistent with the fact that $D^{(1)}$ is an element of SO(3) group, i.e., det $D^{(1)} = 1$ [16] (see also Ref. [21]).

 (g,π)

At a first glance, the difference in Berry phase of adiabatic orbitals seems to be contradictory to the physical equivalence of adiabatic orbitals. The equivalence can be seen in the symmetric situation under all three rotations in D_2 : by the third rotation $R_2 = R_1 R_3$, the adiabatic orbitals change as

$$(\hat{a}_{1}^{\dagger}, \hat{a}_{2}^{\dagger}, \hat{a}_{3}^{\dagger}) \to (-\hat{a}_{1}^{\dagger}, \hat{a}_{2}^{\dagger}, -\hat{a}_{3}^{\dagger}),$$
 (17)

 $\varepsilon_1 = \varepsilon_2 < \varepsilon_3$

and now the sign of orbital 2 remains the same and the rest changes.

B. Adiabatic electron configurations

The Berry phase of the adiabatic electron configuration

$$|\Phi^{(n)}(\Omega)\rangle = \hat{a}_{i_1\sigma_1}^{\dagger} \hat{a}_{i_2\sigma_2}^{\dagger} \cdots \hat{a}_{i_n\sigma_n}^{\dagger} |0\rangle, \tag{18}$$

for the loops including R_i rotation is the product of those of occupied orbitals,

$$|\Phi^{(n)}(\Omega)\rangle \to (-1)^{n-n_i}|\Phi^{(n)}(\Omega)\rangle,\tag{19}$$

where $|0\rangle$ is the vacuum state of the t_{1u} shell, and n_i (= 0,1,2) is the occupation number of electrons in adiabatic orbital i. Thus, the main task here is the calculations of the lowest electron configurations for different n and spin multiplicity. To this end, the potential terms of \hat{H} ,

$$\hat{U} = \frac{q^2}{2} - \sum_{\sigma} gq \left[\cos \left(\alpha - \frac{2\pi}{3} \right) \hat{n}_{1\sigma} + \cos \left(\alpha + \frac{2\pi}{3} \right) \hat{n}_{2\sigma} + \cos \alpha \hat{n}_{3\sigma} \right], \tag{20}$$

are minimized with respect to q, α , and electron occupations under constraint on n and spin S [12], where \hat{U} is obtained using Eqs. (6) and (8). The angle α is chosen so that I_i (13) becomes symmetric with respect to the third principal axis $I_1 = I_2 \neq I_3$. The results are listed in Table I and the electron configurations are shown in Fig. 2.

Under R_3 , the sign of an adiabatic electronic state does not change for any n and S. Under R_1 , orbital 1 does not change sign, whereas the orbital is either empty or doubly filled as long as the low-spin adiabatic states are considered (Fig. 2). Therefore, the sign changes of low-spin states coincide with the electronic part $(-1)^n$ of Eq. (1). On the other hand, orbital 1 is occupied by one electron in high-spin states ${}^3T_{1g}$ of t_{1u}^2 (t_{1u}^4) and 4A_u of t_{1u}^3 , and thus, the phase changes of these states are -1 and 1, respectively. The results differ from the prediction of Eq. (1). The absence of the sign change for 4A_u configuration is consistent with the nondegeneracy of the orbital part (no conical intersection).

-1

(3,3,0)

V. SELECTION RULE ON VIBRONIC ANGULAR MOMENTUM

The selection rule on vibronic angular momentum characterizing the low-energy vibronic states is further generalized so that it is applicable to both low- and high-spin cases. As shown in Table I, there are two types of moments of inertia: the oblate type ($I_1 = I_2 > I_3$) and the prolate type ($I_1 = I_2 < I_3$), which are, respectively, called unimodal and bimodal [12]. These cases are treated separately.

A. Unimodal case

Since one of the moments of inertia is zero ($I_3 = 0$) as in diatomic molecule, the pseudorotational Hamiltonian H_{rot} describes one-dimensional vibration and rotation of the system with two angles [38] (see for detailed derivation Refs. [12,13]). In this case, the vibronic state is given by the product of the adiabatic electronic, vibrational, and pseudorotational parts [39]:

$$|\Psi^{(n)}(q,\alpha,\Omega)\rangle = |\Phi^{(n)}(\Omega)\rangle \chi(q,\alpha,\psi) D_{M0}^{(L)}(\phi,\theta,0).$$
 (21)

The vibronic states have to be single valued under R_1 and R_3 (and thus R_2). The sign changes of the adiabatic electronic configurations are $(-1)^{n-n_i}$, Eq. (19). The pseudorotational part changes by $(-1)^L$ for R_1 and remains the same for R_3 [40]. The radial vibrational part χ should be invariant under

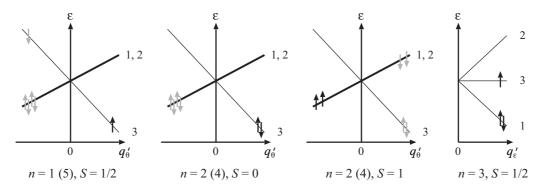


FIG. 2. Electron configuration for different n and S. The thin and thick slopes indicate the nondegenerate and doubly degenerate adiabatic orbitals, respectively, q'_{θ} and q'_{ϵ} are the normal coordinate in the rotating coordinate, the black arrows are electrons for $n \leq 3$, and gray arrows indicate those for $n \geq 4$.

any changes of ψ by R_i . Therefore, the relation between the vibronic angular momentum L and the Berry phase of the adiabatic electronic state is given by

$$(-1)^{n-n_1+L} = 1. (22)$$

In this formula, n_1 is equivalent to n_2 for the present choice of α which fulfills $I_1 = I_2 > I_3$. The latter corresponds to using R_2 rotation. For the other choice of α , n_1 in Eq. (22) should be replaced by n_i where i is not the main symmetry axis of the principal moment of inertia, $I_i = I_j \neq I_k$ (i, j, k = 1, 2, 3).

For the low-spin states with an odd (even) number of electrons, the angular momentum L is odd (even). This is in line with the previous results [12]. Contrary, the Berry phase of ${}^3T_{1g}$ term (n=2,4) is -1 as in the case of ${}^2T_{1u}$ term (n=1,5), thus the angular momentum L (L=1 for the ground state) is also odd. Since the Berry phase of the highspin terms is adequately described, the angular momentum L is consistent with the fact that the JT Hamiltonian for the ${}^3T_{1g}$ term of t_{1u}^2 (t_{1u}^4) has the same form as that for t_{1u}^1 . Although 4A_u state of t_{1u}^3 is neither unimodal nor bimodal, by a similar discussion L must be even, which is nothing but a vibrational angular momentum [33]. The fingerprint of the vibronic angular momentum of the high-spin vibronic states could be observed by spectroscopic techniques and also in thermodynamic quantities. An example of the latter is a spin

gap of C_{60} anions in which the large entropy due to the degeneracy of the low-lying vibronic states plays a crucial role [24].

B. Bimodal case

Since all the moments of inertia are nonzero, the pseudorotational part of H_0 reduces to the Hamiltonian for a symmetric top with $\alpha = \frac{\pi}{2}$ [12,13,38]. Similarly to the unimodal case, the vibronic state would be written as $|\Phi^{(3)}(\Omega)\rangle\chi_K(q,\alpha)D_{MK}^{(L)}(\Omega)$. This gives rise to 2(2L+1)-fold degeneracy (2L+1) is from M and 2 from $\pm K$ for $K \neq 0$), which is two times larger than expected, as pointed out by O'Brien [13]. This issue may be solved by taking into account quantum correction to the pseudorotational Hamiltonian due to the deviation of α from classical value $\frac{\pi}{2}$,

$$H_{\text{rot}} = \frac{1}{2q^2} \left(L^2 - \frac{3L_3^2}{4} \right) + \frac{\sqrt{3}}{q^2} \Delta \alpha \left(L_1^2 - L_2^2 \right), \quad (23)$$

where $L^2 = \sum_{i=1}^3 L_i^2$ and $\Delta \alpha = \alpha - \frac{\pi}{2}$. Because of the second term, the system becomes an asymmetric top being coupled to the radial part, and hence the vibronic states may be described by the superposition of pseudorotational states of a symmetric top (see for an asymmetric top Refs. [33,35,38]). Considering the transformation properties of the vibronic states under C_2 rotations, we obtain the selection rule as well as the form of the vibronic state (see the Appendix):

$$|\Psi^{(3)}(q,\alpha,\Omega)\rangle = |\Phi^{(n)}(\Omega)\rangle\chi_{K}(q,\alpha) \times \begin{cases} \left(D_{MK}^{(L)}(\Omega) + D_{M,-K}^{(L)}(\Omega)\right) & L : \text{odd}, K = 0, 2, 4, \dots, L - 1, \\ \left(D_{MK}^{(L)}(\Omega) - D_{M,-K}^{(L)}(\Omega)\right) & L : \text{even}, K = 2, 4, \dots, L. \end{cases}$$
(24)

The selection rule agrees with Ref. [13], however, the pseudorotational state differs from the previous one. The previous pseudorotational state shows sign change, while it also suffered from unnecessary change of its form under the symmetry operation. This issue is fixed in our solution.

VI. CONCLUSION

The selection rule on vibronic angular momentum of a $t_{1u}^n \otimes h_g$ Jahn-Teller problem is thoroughly investigated. The

Berry phases of adiabatic orbitals are analyzed, and it was confirmed that only two among three orbitals can have nonzero Berry phases. The Berry phase of an adiabatic electronic configuration depends not only on the number of electrons n but also on spin multiplicity. On this basis, the relation between the Berry phase and vibronic angular momentum L is generalized. Particularly, the contradiction between the vibronic state of a high-spin system and the selection rule is solved. In addition, the present vibronic state of a bimodal

system fulfills the symmetry requirement, which is not fully satisfied in the previous one. The present result enables the comprehensive understanding of the relation between the nature of the vibronic states of a $t_{1u}^n \otimes h_g$ Jahn-Teller system. Moreover, the dependence of Berry phase on configuration will play an important role in the other multielectronic Jahn-Teller systems such as d metal ions in a cubic site.

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APPENDIX: CALCULATION OF EQ. (24)

The vibronic state of an asymmetric top may be written as

$$|\Psi^{(n)}\rangle = |\Phi^{(3)}(\Omega)\rangle \sum_{N=-L}^{L} \chi_N(q,\alpha) D_{MN}^{(L)}(\Omega).$$
 (A1)

Since the vibronic state is single valued in the space of nuclear coordinates, under the projection operator onto totally symmetric representation,

$$\hat{P}_A = \frac{1}{|D_2|} \sum_{G \in D_2} \hat{G},$$
 (A2)

it remains the same, where $|D_2|$ is the number of elements in the group. The projected state is

$$\hat{P}_{A}|\Psi^{(n)}\rangle = \frac{1}{4}|\Phi^{(3)}(\Omega)\rangle \sum_{N=-L}^{L} \chi_{N}(q,\alpha)[1+(-1)^{N}] \times \left[D_{MN}^{(L)}(\Omega)-(-1)^{L}D_{M,-N}^{(L)}(\Omega)\right], \quad (A3)$$

implying that N has to be even. Expanding the sum over N partly,

$$\hat{P}_{A}|\Psi^{(n)}\rangle = \frac{1}{2}|\Phi^{(3)}(\Omega)\rangle \sum_{K}' \times \left\{ \chi_{K}^{S}[1 - (-1)^{L}] \left[D_{MK}^{(L)}(\Omega) + D_{M,-K}^{(L)}(\Omega) \right] + \chi_{K}^{A}[1 + (-1)^{L}] \left[D_{MK}^{(L)}(\Omega) - D_{M,-K}^{(L)}(\Omega) \right] \right\},$$
(A4)

where K is even and fulfills $0 \le K \le L$, and χ_K^S and χ_K^A are the symmetric and antisymmetric parts of χ_K under inversion of K. For odd and even L, the first and second terms in the curly bracket become zero, respectively, and for K = 0, the second term is zero. The dominant part for each vibronic state is shown in Eq. (24). In the expression, the superscript of χ_K is omitted.

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