

Universal short-time dynamics: Boundary functional renormalization group for a temperature quench

Alessio Chiocchetta and Andrea Gambassi

SISSA - International School for Advanced Studies and INFN, via Bonomea 265, 34136 Trieste, Italy

Sebastian Diehl and Jamir Marino

*Institut für Theoretische Physik, Universität zu Köln, D-50937 Cologne, Germany**and Institut für Theoretische Physik, TU Dresden, D-01062 Dresden, Germany*

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We present a method to calculate short-time nonequilibrium universal exponents within the functional-renormalization-group scheme. As an example, we consider the classical critical dynamics of the relaxational model A after a quench of the temperature of the system and calculate the initial-slip exponent which characterizes the nonequilibrium universal short-time behavior of both the order parameter and correlation functions. The value of this exponent is found to be consistent with the result of a perturbative dimensional expansion and of Monte Carlo simulations in three spatial dimensions.

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I. INTRODUCTION

The quest for nonequilibrium collective properties in macroscopic classical and quantum systems lies at the forefront of modern statistical physics. In fact, when macroscopic systems are driven out of equilibrium, they exhibit a variety of novel and fascinating phenomena which have no counterpart in equilibrium: when these collective properties are insensitive to the microscopic details of the system, *nonequilibrium universality* emerges. Instances of it are found in both classical and quantum systems. For the former, examples are provided by relaxational models [1–5], driven-diffusive [6] and reaction-diffusion systems (both in stationary and transient regime) [7–10], directed percolation [11–13], self-organized criticality [14], and roughening phenomena [15,16]. In quantum many-body systems, nonequilibrium universality was predicted in open electronic systems [17], noise-driven phase transitions [18], superfluid turbulence and nonthermal fixed points of Bose gases [19–28], driven-dissipative quantum-optical platforms [29–33], aging dynamics of isolated [34–36] and open [37–39] quantum systems, dynamical phase transitions [40–49], and in the statistics of the work done upon quenching [50,51].

The theoretical investigation of nonequilibrium universality is, however, considerably more challenging than its equilibrium counterpart, since one cannot rely in general on the minimization of thermodynamic potentials or exploit fluctuation-dissipation relations [2,52–56], which constrain static and dynamical properties in equilibrium systems. Accordingly, a systematic description of nonequilibrium universality calls for the introduction of novel theoretical tools.

The response-function formalism (also known as MSRJD formalism) [2,53,57–60] provides a practical framework for a systematic classification of equilibrium critical dynamics [5,61] based on a renormalization-group (RG) approach, which was also successfully used to study nonequilibrium classical critical systems [1,3,5]. A similar formalism, based on the Schwinger-Keldysh functional [62–65], is correspondingly used for investigating nonequilibrium criticality in quantum systems. While the typical RG scheme used for studying

nonequilibrium universality is based on the dimensional expansion [5], the functional renormalization group (FRG) has been recently introduced for the investigation of nonequilibrium classical [66–68] and quantum systems [30,32,69–71], where it turned out to be effective in providing quantitative predictions which are out of reach of low-order dimensional expansions. FRG methods have been used, so far, to investigate both the universal critical properties of nonequilibrium *stationary* states of classical and quantum statistical systems, and the nonequilibrium real-time evolution of small quantum systems coupled to an environment [72–79], with a few notable exceptions concerning the nonequilibrium dynamics of many-body systems [80–82].

In this paper, we introduce a FRG scheme to address the nonequilibrium dynamics of classical systems quenched close to a critical point; specifically, we consider the so-called stochastic model A [5,61] after the temperature of the thermal bath (which provides the thermal noise) has been quenched to the critical value. A concrete lattice realization of a system belonging to this universality class is the classical Ising model with nonconserved, i.e., spin-flip, dynamics. In fact, the nonequilibrium dynamics of this model exhibits a universal short-time behavior [1–3], which is revealed, e.g., in the scaling form of correlation functions and of the global magnetization, and is characterized by a new critical exponent, the so-called initial-slip exponent θ . This universal quantity was first calculated at the second order in the dimensional ϵ expansion in Ref. [1], and subsequently determined via numerical simulations (see Ref. [3] for a summary). Here, we show how to calculate the exponent θ by implementing FRG within the response function formalism.

The presentation is organized as follows: In Sec. II we introduce model A and the scaling form of correlation functions and of the order parameter after a critical quench. In Sec. III, the FRG scheme is introduced for a quench, after rephrasing the Langevin dynamics of model A in a functional setting. In Sec. IV we detail the results of our analysis for a simple ansatz of the effective action, benchmarking the method with the available predictions based on the analytical first-order

(dimensional) ϵ expansion reported in the literature [1]. In Sec. V, we introduce an improved ansatz and we discuss and compare its results with those of a second-order (dimensional) ϵ expansion and of numerical Monte Carlo simulations. Finally, in Sec. VI we provide an overview of potential applications of our approach to classical and quantum systems. All the relevant details of the calculations are reported in a number of appendices.

II. CRITICAL QUENCH OF MODEL A

The so-called model A [5,61] captures the universal aspects of the relaxational dynamics of a classical system belonging to the Ising universality class and coupled to a thermal bath. This model prescribes an effective dynamics for the coarse-grained order parameter (i.e., the local magnetization), described by the classical field $\varphi \equiv \varphi(\mathbf{r}, t)$ and evolving according to the Langevin equation

$$\dot{\varphi} = -\Omega \frac{\delta \mathcal{H}}{\delta \varphi} + \zeta, \quad (1)$$

where Ω is the diffusion coefficient, ζ is a zero-mean Markovian and Gaussian noise with correlation $\langle \zeta(\mathbf{r}, t) \zeta(\mathbf{r}', t') \rangle = 2\Omega T \delta^{(d)}(\mathbf{r} - \mathbf{r}') \delta(t - t')$, describing the thermal fluctuations induced by the bath at temperature T (measured in units of Boltzmann constant), and \mathcal{H} is given by

$$\mathcal{H} = \int_{\mathbf{r}} \left[\frac{1}{2} (\nabla \varphi)^2 + \frac{\tau}{2} \varphi^2 + \frac{g}{4!} \varphi^4 \right], \quad (2)$$

where $\int_{\mathbf{r}} \equiv \int d^d r$ with d the spatial dimensionality, τ parametrizes the distance from the critical point, and $g \geq 0$ controls the strength of the interaction. The parameter τ depends on T and it takes a critical value τ_c at the critical temperature $T = T_c$.

We assume that the system is prepared at $t = t_0$ in the high-temperature phase with $T \rightarrow +\infty$ and an external magnetic field h_0 , i.e., that the initial condition $\varphi(\mathbf{r}, t = t_0) = \varphi_0(\mathbf{r})$ is a random field with probability distribution $P_0[\varphi_0]$ given by

$$P_0[\varphi_0] \propto \exp \left[- \int_{\mathbf{r}} \frac{\tau_0}{2} (\varphi_0 - h_0)^2 \right]. \quad (3)$$

Equation (3) implies that the initial field φ_0 , with average $\langle \varphi_0(\mathbf{r}) \rangle = h_0(\mathbf{r})$, is characterized by short-range correlations

$$\langle [\varphi_0(\mathbf{r}) - h_0(\mathbf{r})][\varphi_0(\mathbf{r}') - h_0(\mathbf{r}')] \rangle = \tau_0^{-1} \delta^{(d)}(\mathbf{r} - \mathbf{r}'), \quad (4)$$

where $1/\tau_0$ is the correlation length of the order parameter $\varphi_0(\mathbf{r})$ at $t = t_0$. We recall that the correlation function G_C is defined as [5]

$$G_C(\mathbf{r}, t, t') = \langle \varphi(\mathbf{r}, t) \varphi(\mathbf{0}, t') \rangle, \quad (5)$$

where $\langle \dots \rangle$ denotes the average over the dynamics generated by Eq. (1), which includes averaging over both the initial condition φ_0 and the realizations of the noise ζ . The response function G_R is defined as the linear response to an external field $h(\mathbf{r}, t)$, which couples linearly to φ and which modifies the Hamiltonian \mathcal{H} in Eq. (2) as $\mathcal{H}_h = \mathcal{H} - \int_{\mathbf{r}} h \varphi$; specifically, we have

$$G_R(\mathbf{r}, t, t') \equiv \left. \frac{\delta \langle \varphi(\mathbf{r}, t) \rangle_h}{\delta h(\mathbf{0}, t')} \right|_{h=0}, \quad (6)$$

where $\langle \dots \rangle_h$ denotes the average over the dynamics generated by Eq. (1) with the Hamiltonian \mathcal{H}_h . Note that in Eqs. (5) and (6) we made use of the spatial translational invariance of the dynamical equation (1), as G_C and G_R only depend on the distance between the two spatial points involved in these equations. Accordingly, one can take the Fourier transform with respect to \mathbf{r} and express more conveniently $G_{C,R}$ in wave-vector space.

We assume that the temperature T of the bath takes the critical value T_c for $t > t_0$, so that the system will eventually relax to a critical equilibrium state. As a consequence of being at criticality, this relaxation dynamics exhibits self-similar properties, signaled by the emergence of a scaling behavior referred to as aging; for example, correlation and response functions in momentum space read [1,3,83], after a quench occurring at $t = t_0$,

$$G_R(q, t, t') \simeq q^{-2+\eta+z} \left(\frac{t}{t'} \right)^\theta \mathcal{G}_R(q^z t), \quad (7a)$$

$$G_C(q, t, t') \simeq q^{-2+\eta} \left(\frac{t}{t'} \right)^{\theta-1} \mathcal{G}_C(q^z t), \quad (7b)$$

with η the anomalous dimension [84,85], z the dynamical critical exponent [5,86], and $\mathcal{G}_{R,C}(x)$ scaling functions. The scaling forms (7) are valid for $h_0 = 0$, $t' \ll t$, and $t' \rightarrow t_m$, where t_m is a microscopic time which depends on the specific details of the underlying microscopic model. The dynamics at times shorter than t_m has a nonuniversal character and it depends on the material properties of the system. The scaling forms (7) are characterized by the so-called initial-slip exponent θ , which is generically independent of the static critical exponents η, ν [84,85] and of the dynamical critical exponent z characterizing the equilibrium dynamics of model A. The physical origin of θ can be eventually traced back to the (transient) violation of detailed balance due to the breaking of the time-translational invariance induced by the quench [1].

In the presence of a nonvanishing initial homogeneous external field h_0 , the evolution of the magnetization $M(t) \equiv \langle \varphi(\mathbf{r}, t) \rangle$ displays an interesting nonequilibrium evolution. In fact, for $t \gg t_m$, it follows the scaling form [1]

$$M(t) = M_0 t^{\theta'} \mathcal{F}(M_0 t^{\theta'+\beta/(vz)}), \quad (8)$$

where $\theta' = \theta + (2 - z - \eta)/z$, β is the equilibrium critical exponent of the magnetization [84,85], $M_0 \equiv h_0$ is the initial value of the magnetization, and $\mathcal{F}(x)$ is a function with the following asymptotic properties:

$$\mathcal{F}(x) \approx \begin{cases} x^{-1} & \text{for } x \rightarrow \infty, \\ 1 & \text{for } x \rightarrow 0. \end{cases} \quad (9)$$

Accordingly, $M(t)$ exhibits the nonmonotonic behavior depicted in Fig. 1: for times $t \lesssim t_{M_0} \propto M_0^{1/[\theta'+\beta/(vz)]}$ it grows as an algebraic function with the nonequilibrium exponent θ' , while for $t \gtrsim t_{M_0}$ it relaxes towards its equilibrium value $M_{\text{eq}} = 0$, with an algebraic decay controlled by a combination of universal equilibrium (static and dynamic) critical exponents.

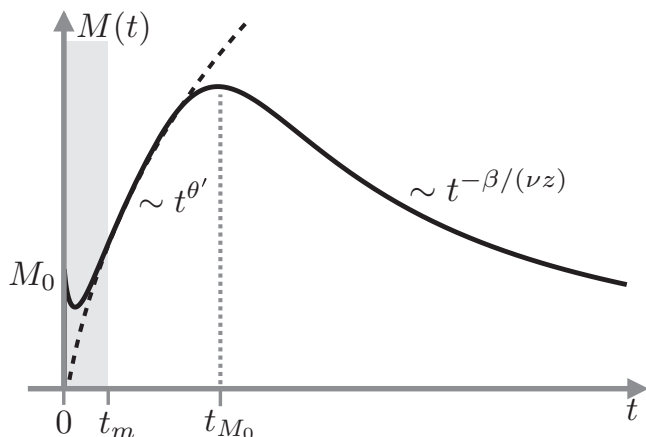


FIG. 1. Sketch of the time evolution of the magnetization $M(t)$ after a quench at $t = t_0$ from a disordered initial state with a small value M_0 of the magnetization to the critical temperature. The gray area indicates the time interval up to t_m within which the dynamics does not display universal features.

Gaussian approximation

In the absence of interaction ($g = 0$), Eq. (1) is linear and therefore it is possible to calculate exactly the correlation and response functions. By solving Eq. (1) with $g = 0$ and $h_0 = 0$, based on the definitions (5) and (6), one finds, after a Fourier transform in space with wave vector q ,

$$G_{OR}(q, t, t') = \vartheta(t - t') e^{-\Omega \omega_q (t - t')}, \quad (10)$$

$$G_{OC}(q, t, t') = \frac{T}{\omega_q} \left[e^{-\Omega \omega_q |t - t'|} + \left(\frac{\omega_q}{T \tau_0} - 1 \right) e^{-\Omega \omega_q (t + t' - 2t_0)} \right], \quad (11)$$

where $\omega_q = q^2 + \tau$ is the dispersion relation, $\vartheta(t)$ is the Heaviside step function, and t_0 is the time at which the quench occurs. The subscript 0 in $G_{OC,OR}$ indicates that these expressions refer to the Gaussian approximation. Notice that while G_{OR} is a time-translational invariant function, as it depends only on the difference of times $t - t'$, G_{OC} breaks time-translational invariance. However, by taking the initial time $t_0 \rightarrow -\infty$ and as long as $\omega_q \neq 0$, G_{OC} recovers its equilibrium time-translational invariant form [5]; this is, in fact, a consequence of the relaxational nature of model A, which erases at long times the information about the initial state. In the presence of a nonvanishing initial homogeneous external field h_0 , it is also possible to calculate exactly the evolution of the magnetization $M(t)$, i.e.,

$$M(t) = M_0 e^{-\Omega \tau (t - t_0)}, \quad (12)$$

which vanishes exponentially fast in time for $\tau > 0$, while it keeps its initial value $M_0 = h_0$ for $\tau = 0$.

Within this Gaussian approximation, the dynamics (1) becomes critical for $\tau = 0$; in this case, by comparing Eqs. (10), (11), and (12) with Eqs. (7a), (7b), and Eq. (8), one finds $\theta = 0$, $\eta = 0$, and $z = 2$.

As a result of a having finite interaction strength $g \neq 0$, the Gaussian value of the initial-slip exponent

acquires sizable corrections [1,3]. In Sec. III we introduce a functional-renormalization-group formalism, which we employ in Secs. IV and V in order to calculate the resulting value of θ .

III. FUNCTIONAL RENORMALIZATION GROUP FOR A QUENCH

In general, breaking translational invariance in space and/or time prevents the use of ordinary computational strategies of FRG [87], which are primarily based on writing the corresponding flow equations in Fourier space, where they acquire a particularly simple form; accordingly one has to resort to more advanced techniques [88–91]. In this section, we show how the case of broken time-translational invariance can be successfully and effectively studied.

A. Response functional and FRG equation

The Langevin formulation of model A in Eq. (1) can be converted into a functional form by using the response functional [2,5,53,57–60]. The corresponding action is given by

$$S[\varphi, \tilde{\varphi}] = S_0[\varphi_0, \tilde{\varphi}_0] + \int_{\mathbf{r}} \int_{t_0}^{+\infty} dt \tilde{\varphi} \left(\dot{\varphi} + \Omega \frac{\delta \mathcal{H}}{\delta \varphi} - \Omega T \tilde{\varphi} \right), \quad (13)$$

where $\tilde{\varphi} = \tilde{\varphi}(\mathbf{r}, t)$ is the so-called response field, while $\tilde{\varphi}_0 = \tilde{\varphi}(\mathbf{r}, t = t_0)$. The averages of quantities $O[\varphi, \tilde{\varphi}]$ can thus be calculated via a functional integration as [5]

$$\langle O[\varphi, \tilde{\varphi}] \rangle = \int \mathcal{D}\varphi \mathcal{D}\tilde{\varphi} O[\varphi, \tilde{\varphi}] e^{-S[\varphi, \tilde{\varphi}]}. \quad (14)$$

The action $S_0[\varphi_0, \tilde{\varphi}_0]$ contains information about the initial state and can be derived by including the initial probability distribution (3) into the functional description [1–3]. We postpone the discussion of its precise form to Sec. III B. The quench occurs at time t_0 ; if one is interested only in the stationary properties of model A, the limit $t_0 \rightarrow -\infty$ can be taken, thus recovering a full time-translational invariant behavior, as discussed in Sec. IV C.

In order to implement the FRG [87,92], it is necessary to supplement the action $S[\varphi, \tilde{\varphi}]$ with a cutoff function $R_k(q)$, and to derive the one-particle irreducible effective action $\Gamma[\phi, \tilde{\phi}]$ as the Legendre transform of the generating function associated with $S_k[\varphi, \tilde{\varphi}]$ [see Appendix A, in particular Eq. (A3)]. $R_k(q)$ is introduced as a quadratic term in the modified action $S_k[\Psi] \equiv S[\Psi] + \Delta S_k[\Psi]$, where $\Delta S_k[\Psi] = \int_{t, \mathbf{r}} \Psi^\dagger \sigma \Psi R_k / 2$ with the Pauli matrix $\sigma = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ acting in the two-dimensional space of the variables φ and $\tilde{\varphi}$, encoded in $\Psi^\dagger = (\varphi, \tilde{\varphi})$. The cutoff function R_k as a function of k is characterized by the following limiting behaviors [87,92,93]:

$$R_k(q) \simeq \begin{cases} \Lambda^2 & \text{for } k \rightarrow \Lambda, \\ 0 & \text{for } k \rightarrow 0, \end{cases} \quad (15)$$

where Λ is the ultraviolet cutoff of the model. Correspondingly, the effective action Γ_k can be interpreted as an action which interpolates between the microscopic one $S[\varphi, \tilde{\varphi}]$ for $k \rightarrow \Lambda$, and the long-distance effective one for $k \rightarrow 0$. When

the fluctuations of the order parameter are integrated out in order to evaluate the effective action, the effect of R_k is to supplement slow modes with an effective k -dependent quadratic term (a mass, in field-theoretical language), allowing a smooth approach to the critical point, when the effective low-energy action is recovered for $k \rightarrow 0$. More specifically, for momenta $q \lesssim k$ the mass of the critical modes becomes proportional to $R_k(q) \simeq k^2$ [as we detail in Eq. (30)], and this regularizes the infrared divergences of RG loop corrections, occurring at criticality when $q \rightarrow 0$ (see, e.g., Refs. [87,92,93]). As a consequence of the introduction of the regulator R_k , the k -dependent effective action Γ_k can then also be regarded as an action which has been coarse-grained on a spatial volume k^{-d} .

As discussed in Appendix A, the flow equation for Γ_k upon varying the coarse-graining scale k is given by [87,94]

$$\frac{d\Gamma}{dk} = \frac{1}{2} \int_x \text{tr} \left[\vartheta(t - t_0) G(x, x) \frac{dR}{dk} \sigma \right], \quad (16)$$

where, in order to simplify the notation, we no longer indicate explicitly the dependence on k of Γ and R , while we defined $x \equiv (\mathbf{r}, t)$, $\int_x \equiv \int d^d r \int_{t_0}^{+\infty} dt$. The matrix $G(x, x')$ is defined as

$$G(x, x') = (\Gamma^{(2)} + R\sigma)^{-1}(x, x'), \quad (17)$$

where the inverse of the matrix on the right-hand side is taken with respect to spatial and temporal variables, as well as to the internal matrix structure. The kernel $\Gamma^{(2)}(x, x')$ is the second variation of the effective action Γ with respect to the fields, i.e.,

$$\Gamma^{(2)}(x, x') = \begin{pmatrix} \frac{\delta^2 \Gamma}{\delta \phi(x) \delta \phi(x')} & \frac{\delta^2 \Gamma}{\delta \phi(x) \delta \tilde{\phi}(x')} \\ \frac{\delta^2 \Gamma}{\delta \tilde{\phi}(x) \delta \phi(x')} & \frac{\delta^2 \Gamma}{\delta \tilde{\phi}(x) \delta \tilde{\phi}(x')} \end{pmatrix}. \quad (18)$$

While Eq. (16) is exact, it is generally not possible to solve it. Accordingly, one has to resort to approximation schemes which render Eq. (16) amenable to analytic and numerical calculations. A first step in this direction is to provide an ansatz for the form of the effective action Γ which, once inserted into Eq. (16), results in a set of coupled nonlinear differential equations for the couplings which parametrize it. In fact, any coupling $g_{n,l} \phi^n \tilde{\phi}^l / (n! l!)$ (with n and l positive integers) appearing in Γ corresponds to a term of its vertex expansion [69,95,96] as

$$g_{n,l} = \left. \frac{\delta^{l+n} \Gamma}{\delta \phi^n \delta \tilde{\phi}^l} \right|_{\substack{\tilde{\phi}=0 \\ \phi=\phi_m}}, \quad (19)$$

where the derivatives of Γ are evaluated at some homogeneous field configurations $\tilde{\phi} = 0$ and $\phi = \phi_m$. The field ϕ_m , referred to as background field, is typically chosen as the minimum of the effective action Γ .

In this work, we consider the following ansatz for model A:

$$\begin{aligned} \Gamma[\phi, \tilde{\phi}] &= \Gamma_0[\phi_0, \tilde{\phi}_0] \\ &+ \int_x \vartheta(t - t_0) \tilde{\phi} \left(Z \dot{\phi} + K \nabla^2 \phi + \frac{\partial \mathcal{U}}{\partial \phi} - D \tilde{\phi} \right). \end{aligned} \quad (20)$$

The boundary action $\Gamma_0[\phi_0, \tilde{\phi}_0]$ accounts for the initial conditions and its form will be discussed in detail in Sec. III B. For the time being, we just assume that it is a quadratic function of the fields. Note that the effective action (20) can generally describe a quench because of the presence of the Heaviside step function in the second term. The field-independent factors Z , K , and D account for possible renormalizations of the derivatives and of the Markovian noise, while the generic potential $\mathcal{U}(\phi)$ is a \mathbb{Z}_2 -symmetric local polynomial of the order parameter ϕ . For constructing the FRG equations, we consider the following cutoff function:

$$R(q) = K(k^2 - q^2) \vartheta(k^2 - q^2), \quad (21)$$

which is known to minimize spurious effects introduced by the specific truncation ansatz of the effective action [93].

The kernel $\Gamma^{(2)} + R\sigma$ appearing in Eq. (17)—which is obtained by deriving Eq. (20)—can be conveniently reexpressed by separating the field-independent part G_0^{-1} (which receives contributions from the quadratic part of Γ and from σR) from the field-dependent part V , i.e.,

$$\Gamma^{(2)}(x, x') + R(x, x') \sigma = G_0^{-1}(x, x') - V(x, x'), \quad (22)$$

such that [see Eq. (17)]

$$G^{-1}(x, x') = G_0^{-1}(x, x') - V(x, x'). \quad (23)$$

Note that, since we assumed $\Gamma_0[\phi_0, \tilde{\phi}_0]$ to be quadratic, its presence is completely encoded in the function G_0^{-1} . For the ansatz (20), the field-dependent part V reads

$$V(x, x') = V(x) \delta(x - x'), \quad (24)$$

where the delta function $\delta(x - x') \equiv \delta(t - t') \delta^{(d)}(\mathbf{r} - \mathbf{r}')$ appears as a consequence of the locality in space and time of the potential \mathcal{U} , and where the function $V(x)$ is defined as

$$V(x) = -\vartheta(t - t_0) \begin{pmatrix} \tilde{\phi}(x) \frac{\partial^3 \mathcal{U}}{\partial \phi^3}(x) & \frac{\partial^2 \mathcal{U}}{\partial \phi^2}(x) \\ \frac{\partial^2 \mathcal{U}}{\partial \phi^2}(x) & 0 \end{pmatrix}. \quad (25)$$

The function ϑ in this expression of $V(x)$ appears as a consequence of the one in Eq. (20): as will become clear below, the presence of ϑ allows one to encompass both the case of the quench and of a stationary state in the calculation of G (see Sec. IV C).

Finally, in order to derive the RG equations for the couplings appearing in the effective action (20), one has to take the derivative with respect to k on both sides of Eq. (19) and, by using Eq. (16), one finds

$$\begin{aligned} \frac{dg_{n,l}}{dk} &= \frac{\delta^{l+n}}{\delta \phi^n \delta \tilde{\phi}^l} \frac{1}{2} \int_x \text{tr} \left[\vartheta(t - t_0) G(x, x) \frac{dR}{dk} \sigma \right] \Big|_{\substack{\tilde{\phi}=0 \\ \phi=\phi_m}} \\ &+ \frac{\delta^{l+n+1} \Gamma}{\delta \phi^{n+1} \delta \tilde{\phi}^l} \Big|_{\substack{\tilde{\phi}=0 \\ \phi=\phi_m}} \frac{d\phi_m}{dk}, \end{aligned} \quad (26)$$

from which one can evaluate the flow equation for the couplings $g_{n,m}$, once the derivative of ϕ_m is calculated, where ϕ_m corresponds to the minimum of the potential \mathcal{U} .

B. Functional renormalization group for a quench

In order to study the critical properties of the temperature quench described in Sec. II, we consider the effective

action (20), in which one has still to specify the form of the boundary action Γ_0 . The Gaussian probability distribution (3) of the initial condition can be effectively accounted for by taking

$$\Gamma_0 = \int_{\mathbf{r}} \left(-\frac{Z_0^2}{2\tau_0} \tilde{\phi}_0^2 + Z_0 \tilde{\phi}_0 \phi_0 + Z_0 h_0 \tilde{\phi}_0 \right). \quad (27)$$

This form is uniquely fixed by requiring that it does not result in a violation of causality in the response functional [97] and that it reproduces the Gaussian Green's functions (10) and (11); see Appendix B. The factor Z_0 accounts for a possible renormalization of the initial response field $\tilde{\phi}_0$: the way in which corrections to Z_0 are generated is discussed further below in this section. Note, in addition, that the term $\propto \tilde{\phi}_0^2$ can be regarded as a Gaussian noise located at the initial time t_0 . The boundary action Γ_0 may in principle contain higher powers of ϕ_0 and $\tilde{\phi}_0$, and spatial and temporal derivatives of these fields; however, taking into account their engineering dimension, one can argue [1] that they are irrelevant in the renormalization-group sense, and therefore they have not been included here. The presence of a nonvanishing initial field h_0 induces a nontrivial evolution of the magnetization $M(t)$, but it does not generate new additional critical exponents (see Sec. II and Ref. [1]), and therefore in the rest of this work we will assume $h_0 = 0$ without loss of generality.

In order to study the flow of the couplings of the effective action Γ in Eq. (20) from the FRG equation (16) it is necessary to evaluate the matrix G defined in Eq. (17). However, the presence of the boundary action given in Eq. (27) as well as the breaking of time-translational invariance in Eq. (20) makes the calculation of $G(x, x')$ nontrivial, since now G depends separately on the two times t and t' . In order to overcome this difficulty, we notice that G satisfies the following integral equation (see Appendix C for a proof of this statement):

$$G(x, x') = G_0(x, x') + \int_y G_0(x, y) V(y) G(y, x'), \quad (28)$$

with G_0 and V defined in Eq. (22). The explicit form of G_0 can be evaluated by using the boundary action Γ_0 in Eq. (27) and it reads (see Appendix B for details)

$$G_0(t, t') = \begin{pmatrix} G_{0C}(t, t') & G_{0R}(t, t') \\ G_{0R}(t', t) & 0 \end{pmatrix}, \quad (29)$$

where G_{0R} and G_{0C} are given by Eqs. (10) and Eqs. (11) (with $\Omega = 1$ and T replaced by D), respectively, with the dispersion relation ω_q replaced by the regularized one $\omega_{k,q}$, defined as

$$\omega_{k,q} \equiv Kq^2 + \tau + K(k^2 - q^2)\vartheta(k^2 - q^2). \quad (30)$$

Equation (28) can then be solved iteratively and, once its solution has been replaced into the FRG equation (16), the latter can be cast in the form [see, e.g., Eqs. (C5) and (C7)]

$$\frac{d\Gamma}{dk} = \sum_{n=1}^{+\infty} \Delta\Gamma_n, \quad (31)$$

where the functions $\Delta\Gamma_n$ are defined as (see Appendix C for details)

$$\Delta\Gamma_n = \frac{1}{2} \int_{x, y_1 \dots y_n} \text{tr} \left[G_0(x, y_1) V(y_1) G_0(y_1, y_2) \times \dots \times V(y_n) G_0(y_n, x) \frac{dR}{dk} \sigma \right]. \quad (32)$$

As discussed in Appendix C, the FRG equation in the form of Eq. (31) is the most convenient one for calculations when, as in the present case, time-translational invariance is broken, and therefore it cannot be further simplified by expressing it in the Fourier frequency space.

For simplicity, let us assume that the potential \mathcal{U} in Eq. (20) is quartic in the field ϕ , i.e.,

$$\mathcal{U}(\phi) = \frac{\tau}{2} \phi^2 + \frac{g}{4!} \phi^4, \quad (33)$$

such that, from Eq. (25), the field-dependent function $V(x)$ reads

$$V(x) = -\vartheta(t - t_0) g \begin{pmatrix} \tilde{\phi}\phi & \phi^2/2 \\ \phi^2/2 & 0 \end{pmatrix}. \quad (34)$$

Accordingly, since this V appears n times in the convolution (32) which defines $\Delta\Gamma_n$ on the right-hand side of Eq. (31), it follows that $\Delta\Gamma_n$ contains products of $2n$ possibly different fields. Because of the ansatz (20) also the left-hand side of Eq. (31) is a polynomial of the fields, and therefore each term on the left-hand side is uniquely matched by a term of the expansion on the right-hand side. Accordingly, in order to derive the RG equation for the coupling of a term involving a product of $2n$ fields, it is sufficient to evaluate the corresponding $\Delta\Gamma_n$. Note that this line of argument applies also to the time-translational invariant case, and, moreover, it can be easily generalized to the case in which the potential contains powers of ϕ of higher order than those in Eq. (33).

IV. TRUNCATION FOR $\phi_m = 0$

In this section we discuss the derivation of the RG equations from the ansatz (20) with the quartic potential \mathcal{U} introduced in Eq. (33). Considering this simple case allows us to detail how the boundary action (27) is renormalized by the postquench interaction. Since this ansatz corresponds to a local potential approximation [67,87,92], the anomalous dimensions of the derivative terms (K, Z) and of the Markovian noise strength D vanish, and therefore in the following we set, for simplicity, $K = Z = 1$. The only nonirrelevant terms which are renormalized within this scheme are those proportional to quadratic and quartic powers of the fields ϕ and $\tilde{\phi}$, i.e., those associated with the postquench parameter τ , the boundary field renormalization Z_0 , and the coupling g . As discussed in Sec. III B, the renormalization of the quadratic terms is determined by the contribution $\Delta\Gamma_1$ appearing on the right-hand side of Eq. (31), while the renormalization of the quartic one by the contribution $\Delta\Gamma_2$.

A. Derivation of the RG equations

Let us now consider Eq. (31) and focus on the term $\Delta\Gamma_1$, as defined in Eq. (32). A simple calculation renders (see

Appendix D for details)

$$\Delta\Gamma_1 = -k^{d+1} \frac{a_d g D}{d \omega_k^2} \int_{\mathbf{r}} \int_{t_0}^{+\infty} dt \tilde{\phi}(t, \mathbf{r}) \phi(t, \mathbf{r}) \times [1 - f_\tau(t - t_0)], \quad (35)$$

where $a_d = 2/[\Gamma(d/2)(4\pi)^{d/2}]$, with d the spatial dimensionality of the system and $\Gamma(x)$ the gamma function. The integration over the intermediate time variable in Eq. (32) for $n = 1$ generates, within the square brackets in the integrand of Eq. (35), one term which is independent of time and one which depends on it via the function $f_\tau(t - t_0)$, defined as

$$f_\tau(t) = e^{-2\omega_k t} \left[1 + 2\omega_k t \left(1 - \frac{\omega_k}{D\tau_0} \right) \right], \quad (36)$$

where $\omega_k \equiv \omega_{q=k}$ or, equivalently, $\omega_k \equiv \omega_{k,q=k}$ [see Eq. (30)]. Since $f_\tau(t)$ vanishes exponentially fast upon increasing the time t , its contribution to the renormalization of the time-independent parameter τ can be neglected [98]. Accordingly, the flow equation for τ can be simply obtained by comparing the left-hand side of Eq. (31) with Eq. (35), where we introduced the potential (33) in the truncated action (20); this yields

$$\frac{d\tau}{dk} = -k^{d+1} \frac{a_d g D}{d (k^2 + \tau)^2}. \quad (37)$$

At short times, instead, the function $f_\tau(t)$ singles out contributions containing fields of the temporal boundary, thus renormalizing the boundary action Γ_0 introduced in Eq. (27). In fact, the formal identity

$$\int_{t_0}^{+\infty} dt g(t) e^{-c(t-t_0)} = \sum_{n=0}^{+\infty} \frac{1}{c^{n+1}} \frac{d^n g}{dt^n} \Big|_{t=t_0}, \quad (38)$$

with $c > 0$ and $g(t)$ an arbitrary smooth function, can be used in order to express the part of the integral involving $f_\tau(t)$ on the right-hand side of Eq. (35) as

$$\int_{t_0}^{+\infty} dt \tilde{\phi}(t) \phi(t) f_\tau(t - t_0) = \sum_{n=0}^{+\infty} \frac{c_{n,k}(\tau_0)}{(2\omega_k)^{n+1}} Z_{0,n} \frac{d^n}{dt^n} [\tilde{\phi}(t) \phi(t)] \Big|_{t=t_0}, \quad (39)$$

with

$$c_{n,k}(\tau_0) \equiv (n+2) - \frac{(n+1)\omega_k}{D\tau_0}. \quad (40)$$

Accordingly, the time-dependent part in the integrand of Eq. (35) generates an infinite series of operators contributing to the boundary action Γ_0 . For future convenience, we introduced in Eq. (39) additional numerical factors $Z_{0,n}$, which account for possible renormalization of the boundary operators and which equal one in the nonrenormalized theory. Most of the terms in the sum (39) renormalize irrelevant operators which were not included in the original ansatz (27) for the boundary action, and therefore one can neglect them. The only nonirrelevant term corresponds to $n = 0$ in Eq. (39): by inserting the boundary action Γ_0 [see Eq. (27)] into the left-hand side of Eq. (31), and by combining it with Eqs. (35) and (39), one finds the flow

equation for $Z_0 \equiv Z_{0,0}$, i.e.,

$$\frac{dZ_0}{dk} = k^{d+1} \frac{a_d g D}{d (k^2 + \tau)^3} \left[1 - \frac{k^2 + \tau}{2D\tau_0} \right] Z_0. \quad (41)$$

We consider now the renormalization of the quartic term, which can be read off from $\Delta\Gamma_2$. A simple calculation renders (see Appendix D for details)

$$\Delta\Gamma_2 = \frac{3}{2} k^{d+1} \frac{a_d g^2 D^2}{d \omega_k^4} \int_{\mathbf{r}} \int_{t_0}^{+\infty} dt \tilde{\phi}^2(t) \phi^2(t) [1 - f_D(t - t_0)] + k^{d+1} \frac{a_d g^2 D}{d \omega_k^3} \int_{\mathbf{r}} \int_{t_0}^{+\infty} dt \tilde{\phi}(t') \phi^3(t) [1 - 0 f_g(t - t_0)], \quad (42)$$

where f_g and f_D , given in, cf., Eqs. (D10) and (D11), respectively, decay exponentially upon increasing the time t , and therefore they do not contribute to the renormalization of the couplings at long times. Note that the integration produces a term proportional to $\tilde{\phi}^2 \phi^2$ in Eq. (42); however, this operator is irrelevant for $d > 2$ and it can be neglected, since our truncation includes only relevant couplings. On the other hand, the term proportional to $\tilde{\phi} \phi^3$ in Eq. (42) renormalizes the relevant coupling g and, comparing Eq. (42) with the left-hand side of Eq. (31) after using the ansatz (20) for Γ with the potential (33), one finds the flow equation for g :

$$\frac{dg}{dk} = 6k^{d+1} \frac{a_d g^2 D}{d (k^2 + \tau)^3}. \quad (43)$$

B. Flow equations

In order to study the flow of τ and g prescribed by Eqs. (37) and (43), it is convenient to introduce the dimensionless quantities $\tilde{\tau} = \tau/k^2$ and $\tilde{g} = g D k^{d-4} a_d / d$. The corresponding flow equations follow from Eqs. (37) and (43):

$$k \frac{d\tilde{\tau}}{dk} = -2\tilde{\tau} - \frac{\tilde{g}}{(1 + \tilde{\tau})^2}, \quad (44)$$

$$k \frac{d\tilde{g}}{dk} = \tilde{g} \left[-\epsilon + 6 \frac{\tilde{g}}{(1 + \tilde{\tau})^3} \right], \quad (45)$$

where $\epsilon = 4 - d$. These equations describe the RG flow of the couplings in the equilibrium state which is asymptotically reached by the system at long times. Accordingly, they are independent of both Z_0 and τ_0 : the relaxational nature of model A erases the information about the initial state in the long time. Since the final state corresponds to an equilibrated system, the equations for $\tilde{\tau}$ and \tilde{g} must result in the same critical exponents as in the equilibrium Ising universality class [5,85,86]. This can be seen, for instance, by comparing Eqs. (44) and (45) (at leading order in ϵ) with the results obtained within the perturbative RG at one loop in the equilibrium theory [5]. Note that Eqs. (44) and (45) do not have the same form as the corresponding equations derived within perturbative RG, as they are obtained within a different renormalization scheme; nevertheless, they provide the same critical exponents, as discussed further below.

Equations (44) and (45) admit two fixed points: the Gaussian one $(\tilde{\tau}_G^*, \tilde{g}_G^*) = (0, 0)$ and the Wilson-Fisher one, which at leading order in ϵ reads $(\tilde{\tau}_{WF}^*, \tilde{g}_{WF}^*) = (-\epsilon/12, \epsilon/6) + O(\epsilon^2)$ (in general we will denote by the superscript * any quantity

which is evaluated at a fixed point). By linearizing Eqs. (44) and (45) around these fixed points, one finds that the Gaussian one is stable only for $\epsilon < 0$, while the Wilson-Fisher fixed point is stable only for $\epsilon > 0$. The latter has an unstable direction, and from the inverse of the negative eigenvalue of the associated stability matrix, one derives the critical exponent ν , which reads $\nu = 1/2 + \epsilon/12 + O(\epsilon^2)$, which is the same as in equilibrium [5,85,86]. As mentioned at the beginning of this section, the ansatz (33) for the potential does not allow for a renormalization of the time and spatial derivatives in the effective action (20). Accordingly, the anomalous dimension η and the dynamical critical exponent z are equal to their Gaussian values $\eta = 0$ and $z = 2$.

Let us now focus on the renormalization of the terms in the boundary action Γ_0 in Eq. (27). From Eq. (41), we define the anomalous dimension η_0 of the response field ϕ_0 at initial time as

$$\eta_0 \equiv -\frac{k}{Z_0} \frac{dZ_0}{dk} = -\frac{\tilde{g}}{(1+\tilde{\tau})^3} \left(1 - \frac{1+\tilde{\tau}}{2\tilde{\tau}_0}\right), \quad (46)$$

where we introduced the rescaled prequench parameter $\tilde{\tau}_0 = \tau_0/k^2$ and we used Eq. (41). Since τ_0 does not receive any correction from the renormalization, its flow equation is simply determined by its canonical dimension and thus

$$k \frac{d\tilde{\tau}_0}{dk} = -2\tilde{\tau}_0. \quad (47)$$

Accordingly, $\tilde{\tau}_0$ has only one stable fixed point $\tilde{\tau}_0^* = +\infty$, in the infrared regime (i.e., for $k \rightarrow 0$). Close to this fixed point, any possible term in the boundary action Γ_0 (except for $\phi_0\phi_0$) is irrelevant for $d > 2$, and therefore the ansatz (27) is consistent. Note that the right-hand side of Eq. (46) diverges at the unstable fixed point $\tilde{\tau}_0^* = 0$; this is expected since $\tau_0 = 0$ is unphysical [1] for the initial probability in Eq. (3) and hence for the ansatz in Eq. (27), as it would correspond to a non-normalizable probability.

The value η_0^* of the anomalous dimension η_0 of the initial response field at the Wilson-Fisher fixed point can be straightforwardly derived by substituting in Eq. (46) the fixed-point values $\tilde{\tau}_{\text{WF}}^*$ and \tilde{g}_{WF}^* of the couplings, obtaining $\eta_0^* = -\epsilon/6$. The initial-slip exponent θ is then defined as [1,3]

$$\theta = -\frac{\eta_0^*}{z}, \quad (48)$$

and therefore, in the present case, it takes the value

$$\theta = -\frac{\eta_0^*}{2} = \frac{\epsilon}{12}, \quad (49)$$

which agrees up to first order in ϵ , with the expression

$$\theta = \frac{\epsilon}{12} \left[1 + \epsilon \left(\frac{8}{27} + \frac{2 \log 2}{3}\right)\right] + O(\epsilon^3), \quad (50)$$

obtained in Ref. [1].

C. Comparison with equilibrium dynamics

In this section, we show how one can recover the flow equations for the equilibrium case in the limit $t_0 \rightarrow -\infty$. First of all, we note that in the expressions for $\Delta\Gamma_1$ and $\Delta\Gamma_2$ given in Eqs. (35) and (42), respectively, the only dependence on t_0 occurs in the lower limit of the integration domain of the

integrals on t and in the functions $f_\tau(t-t_0)$, $f_g(t-t_0)$, and $f_D(t-t_0)$. For $t_0 \rightarrow -\infty$ these functions vanish exponentially fast [see Eqs. (36), (D11), and (D10)] and Eqs. (35) and (42) read

$$\Delta\Gamma_1^{\text{eq}} = -k^{d+1} \frac{a_d g D}{d \omega_k^2} \int_x \tilde{\phi}(x) \phi(x), \quad (51a)$$

$$\Delta\Gamma_2^{\text{eq}} = k^{d+1} \frac{a_d g^2 D}{d \omega_k^3} \int_x \left[\frac{3D}{2\omega_k} \tilde{\phi}^2(x) \phi^2(x) + \tilde{\phi}(x) \phi^3(x) \right], \quad (51b)$$

with $x \equiv (\mathbf{r}, t)$ and $\int_x \equiv \int d^d r \int_{-\infty}^{+\infty} dt$.

Alternatively, one could have taken the limit $t_0 \rightarrow -\infty$ from the outset, i.e., before evaluating $\Delta\Gamma_1$ and $\Delta\Gamma_2$; in this case one simply needs to replace $\vartheta(t-t_0)$ with its limiting value 1 in Eqs. (16) and (25), while G_{0R} is modified inasmuch as G_{0C} becomes time-translational invariant as $t_0 \rightarrow -\infty$ [see Eqs. (11) and (29)]. This gives rise again to Eq. (51), since the operations of taking the limit $t_0 \rightarrow -\infty$ and of calculating the integrals over time (and momenta) on the right-hand side of Eq. (31) do commute (because all the time integrals are convergent due to the decreasing exponentials in G_{0R} and G_{0C}).

Taking the limit $t_0 \rightarrow -\infty$ in the action (20) just corresponds to considering the equilibrium, time-translational invariant theory [5], and therefore one concludes that Eq. (51) give rise to the equilibrium flow equations. Since the flow equations (44) and (45) can also be derived from Eq. (51), they thus represent the equilibrium ones: this is an expected result, since the relaxational nature of model A leads the system to its equilibrium state (yet for asymptotically long times at the critical point), regardless of the quench protocol [1].

V. TRUNCATION FOR $\phi_m \neq 0$

In this section, we discuss the results of a different, improved ansatz for the potential \mathcal{U} in the effective action (20), namely

$$\mathcal{U} = \frac{g}{4!} (\phi^2 - \phi_m^2)^2 + \frac{\lambda}{6!} (\phi^2 - \phi_m^2)^3, \quad (52)$$

the flow of which is derived in Appendix E. This potential differs from the one considered in Eq. (33) in two respects. First, it corresponds to an expansion around a finite homogeneous value ϕ_m ; this choice has the leverage to capture the leading divergences of two-loop corrections in a calculation which is technically carried at one-loop, as typical of background field methods (see, e.g., Refs. [69,87,92,96]), and thus it allows us to calculate, for instance, the renormalization of the factors Z , K , and D . In fact, the presence of a background field, ϕ_m , reduces two-loop diagrams to one-loop ones in which an internal classical line (corresponding to a correlation function, G_C) has been replaced by the insertion of two expectation values ϕ_m (straight lines stand for the field ϕ , curved lines for the response field $\tilde{\phi}$; see, e.g., Ref. [5]). For instance, the

renormalization of Z and K comes from the diagram

$$\Rightarrow \quad (53)$$

while the renormalization of the noise strength D comes from the diagram

$$\Rightarrow \quad (54)$$

Second, we added a sextic interaction, which is marginal for $d = 3$ and therefore it is expected to contribute with sizable corrections to the value of the critical exponents only upon approaching $d = 3$. In fact, the effective action (20) with the potential (52) contains all the nonirrelevant operators in $d = 3$. As anticipated, this ansatz allows the renormalization of the time and spatial derivative terms and of the Markovian noise, i.e., of the coefficients K , Z , and D in Eq. (20), which therefore will be reinstated in the following analysis. The flow equations for these coefficients can be conveniently expressed in terms of the corresponding anomalous dimensions η_D, η_Z , and η_K , defined as

$$\eta_D \equiv -\frac{k}{D} \frac{dD}{dk}, \quad \eta_Z \equiv -\frac{k}{Z} \frac{dZ}{dk}, \quad \eta_K \equiv -\frac{k}{K} \frac{dK}{dk}. \quad (55)$$

The calculation of η_D , η_Z , and η_K is detailed, respectively, in Appendices F 1, F 2, and F 3.

The somewhat lengthy flow equations of the corresponding dimensionless couplings

$$\tilde{m} = \frac{1}{3} \frac{\phi_m^2 g}{K k^2}, \quad \tilde{g} = \frac{a_d}{d} \frac{D}{Z K^2} \frac{g}{k^{4-d}}, \quad \tilde{\lambda} = \frac{a_d}{d} \frac{D^2}{Z^2 K^3} \frac{\lambda}{k^{6-2d}} \quad (56)$$

and of the anomalous dimensions $\eta_{D,Z,K}$ are reported in Eqs. (G1)–(G6) of Appendix G. First of all, we note that $\eta_D = \eta_Z$; this is a consequence of detailed balance [5,69,96], which characterizes the equilibrium dynamics of model A. In fact, while the short-time dynamics after the quench violates detailed balance inasmuch as time-translational invariance is broken, in the long-time limit (in which the flow equations are valid) detailed balance is restored.

The fixed points $(\tilde{m}^*, \tilde{g}^*, \tilde{\lambda}^*)$ of Eqs. (G1)–(G4) can be determined numerically (see Appendix G for details) and they can be used in order to calculate the anomalous dimension η and the dynamical critical exponent z as

$$\eta = \eta_K^*, \quad z = 2 - \eta_K^* + \eta_Z^*. \quad (57)$$

The critical exponent ν can be determined after linearizing the flow equations around the fixed point, as the inverse of the negative eigenvalue of the stability matrix (see Appendix G).

As a consistency check, we compare our values $\nu = 0.64$, $\eta = 0.11$, and $z = 2.05$ in $d = 3$ with the ones determined in Ref. [96] for the equilibrium dynamics of model A within the same truncation ansatz for the effective action Γ as the one employed here, i.e., $\nu = 0.65$, $\eta = 0.11$, and $z = 2.05$, finding

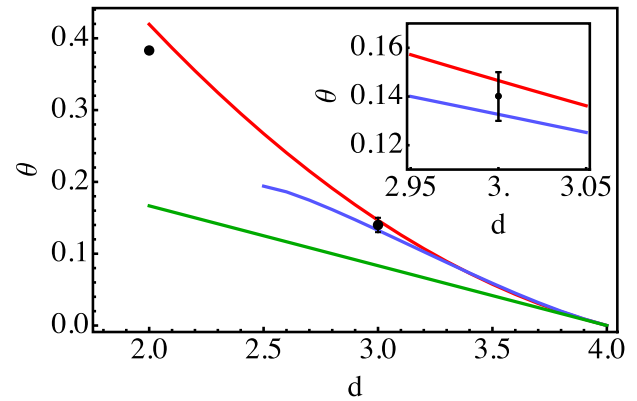


FIG. 2. Main plot: Initial-slip exponent θ as a function of the spatial dimensionality d , evaluated from the FRG discussed here (blue, central line) and from the ϵ expansion to first (green, lower line) and second (red upper line) order in $\epsilon = 4 - d$ provided in Eq. (50). The value of θ obtained from numerical Monte Carlo simulations are indicated for $d = 2$ and 3 (symbols with error bars). For $d = 2$, the error bars are within the symbol size. Inset: Magnification of the main plot for $d \simeq 3$.

very good agreement. For completeness, we also report the Monte Carlo estimates (see Ref. [96] for a summary), given by $\nu_{MC} = 0.6297(5)$, $\eta_{MC} = 0.0362(8)$, and $z_{MC} = 2.055(10)$.

In Fig. 2, we compare the values of θ obtained from Eq. (48) on the basis of the present analysis (blue line), and of the first- (green line) and second-order (red line) ϵ expansion of Ref. [1] reported in Eq. (50), as a function of the spatial dimensionality d . The first-order term in the ϵ expansion is accurate only for spatial dimensionality d close to $d = 4$, while the second-order contribution provides sizable corrections at smaller values of d . Our results are in remarkable agreement with the latter expansion for $d \gtrsim 3.2$, while increasing discrepancies emerge at smaller values of d . In particular, for $d \leq 3$ additional stable fixed points appear in the solution of Eqs. (G1)–(G4) beyond the Wilson-Fisher one, while for $d \leq 2.5$ the latter disappears. This is not surprising, since for $d \leq 3$ new nonirrelevant terms are allowed, and therefore the potential in Eq. (52) is no longer an appropriate ansatz and additional terms have to be introduced. In particular, the number of nonirrelevant operators diverges as d approaches 2: one should indeed recall that in $d = 2$ any term of the form $\tilde{\phi}\phi^{2n+1}$, with positive integer n , is relevant in the RG sense and therefore the correct truncation for the effective action requires considering a full functional ansatz for the potential, beyond the polynomial expansion used in this work. In Refs. [92,96] it is shown how to deal with this issue within the standard approach to FRG.

For comparison, we report in Fig. 2 also the two values of θ obtained from Monte Carlo simulations (see, e.g., the summary in Ref. [3]) in $d = 2$ and $d = 3$ (symbols). Remarkably, the predictions of both FRG and ϵ expansion are compatible (within error bars) with the numerical estimate in $d = 3$, where the ansatz for the potential (52) is reliable, while the FRG predicts a smaller value compared to the one predicted by the ϵ expansion. For $d = 2$, instead, our ansatz (52) is unable to provide reliable predictions for the reasons reported above, while the ϵ expansion still provides an unexpectedly

accurate estimate, yet outside the error bars of the best available numerical estimate $\theta = 0.383(3)$.

VI. CONCLUSIONS AND PERSPECTIVES

In this work we generalized the functional-renormalization-group (FRG) scheme in order to describe the universal dynamical behavior emerging at short times in a classical statistical system after a temperature quench to its critical point. Specifically, we focused on the relaxational dynamics described by the model A [5] for a scalar order parameter and a Landau-Ginzburg effective Hamiltonian, and we evaluated the initial-slip exponent θ , which controls the universal scaling of correlation functions and magnetization after the quench within the Ising universality class with spin-flip (Glauber) dynamics. The value of θ is found to be in good agreement with the one obtained via an ϵ expansion and numerical simulations in $d = 3$. Our prediction for θ can be systematically improved by using a more refined ansatz for the effective action, taking advantage of the existing FRG schemes for equilibrium systems [87,92].

The approach developed in this work can be extended to different static universality classes, such as $O(N)$ and Potts models, or to different dynamics, e.g., with conserved quantities [99,100]. In addition, it can also be used in order to study equilibrium phase transitions in systems with a spatial boundary, whose description is formally similar to the case of a quench [101], and possibly also their nonequilibrium dynamics [102,103]. Moreover, this FRG approach can provide quantitative predictions for additional relevant nonequilibrium universal quantities such as the fluctuation-dissipation ratio and the effective temperatures in the aging regime [3,104–107].

Finally, the approach discussed here constitutes a first step towards the exploration of universality in the dynamics of isolated quantum many-body systems after a parameter quench, a current topic of considerable theoretical and experimental interest [28,108–113].

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APPENDIX A: DERIVATION OF THE FRG EQUATION

In this appendix we briefly review the derivation of Eq. (16) for the response functional [87]. Let us consider the action $S[\Psi]$, where $\Psi^\dagger = (\varphi, \tilde{\varphi})$, with φ the order parameter and $\tilde{\varphi}$ the response field. We define a modified action $S_k[\Psi] = S[\Psi] +$

$\Delta S_k[\Psi]$ where $\Delta S_k[\Psi] = \frac{1}{2} \int_{t,r} \Psi^\dagger \sigma \Psi R_k$, where $\sigma = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ and R_k is a function which implements the infrared cutoff. Then we define the generating function $W_k[J]$ as

$$W_k[J] = \log \left[\int D\Psi e^{-S_k[\Psi] + \int_{t,r} \Psi^\dagger J} \right], \quad (\text{A1})$$

where $D\Psi$ denotes functional integration over both the fields φ and $\tilde{\varphi}$, while $J^\dagger = (j, \tilde{j})$ is an external field. Defining the expectation value $\langle \Psi \rangle$, where the average is taken with respect to the action $-S_k[\Psi] + \int_{t,r} \Psi^\dagger J$, it is straightforward to check that the following properties follow from Eq. (A1) [87]:

$$\langle \Psi \rangle = \frac{\delta W_k}{\delta J^\dagger}, \quad \langle \Psi \Psi^\dagger \rangle - \langle \Psi \rangle \langle \Psi^\dagger \rangle = \frac{\delta^2 W_k}{\delta J^\dagger \delta J} = \frac{\delta \langle \Psi^\dagger \rangle}{\delta J^\dagger}. \quad (\text{A2})$$

The effective action $\Gamma_k[\Phi]$ is defined as

$$\Gamma_k[\Phi] = -W_k[J] + \int_{t,r} J^\dagger \Phi - \Delta S_k[\Phi], \quad (\text{A3})$$

where J is fixed by the condition

$$\Phi = \frac{\delta W_k}{\delta J^\dagger}. \quad (\text{A4})$$

By comparing the previous equation with the first one in Eq. (A2), it follows that $\Phi = \langle \Psi \rangle$; accordingly, by using Eq. (A2), the following relationships can be derived [87]:

$$\begin{aligned} \frac{\delta \Gamma_k}{\delta \Phi^\dagger} &= J - \sigma R_k \Phi, \\ \frac{\delta^2 \Gamma_k}{\delta \Phi^\dagger \delta \Phi} + \sigma R_k &= \frac{\delta J^\dagger}{\delta \Phi^\dagger} = \left[\frac{\delta^2 W_k}{\delta J^\dagger \delta J} \right]^{-1}. \end{aligned} \quad (\text{A5})$$

The definition of $\Gamma_k[\Phi]$ in Eq. (A3) is such that [87] $\Gamma_{k=\Lambda}[\Phi] \approx S[\Phi]$; i.e., when k is equal to the ultraviolet cutoff Λ of the theory, the effective action Γ_k reduces to the ‘‘microscopic’’ action $S[\Phi]$ evaluated on the expectation value Φ . This can also be easily seen by taking a Gaussian microscopic action $S[\Psi]$; in this case a simple calculation shows that $\Gamma_k[\Phi] = S[\Phi]$. We can now derive the FRG equation by taking the total derivative of the effective action with respect to k :

$$\begin{aligned} \frac{d\Gamma_k}{dk} &= -\frac{\partial W_k}{\partial k} - \int_{t,r} \left(\frac{\delta W}{\delta J} - \Phi^\dagger \right) \frac{dJ}{dk} - \frac{1}{2} \int_{t,r} \Phi^\dagger \sigma \frac{dR_k}{dk} \Phi \\ &= \frac{1}{2} \int_{t,r} \left\langle \Psi^\dagger \sigma \frac{dR_k}{dk} \Psi \right\rangle - \frac{1}{2} \int_{t,r} \Phi^\dagger \sigma \frac{dR_k}{dk} \Phi \\ &= \frac{1}{2} \int_{t,r} \text{tr} \left[\langle \Psi \Psi^\dagger \rangle \sigma \frac{dR_k}{dk} \right] - \frac{1}{2} \int_{t,r} \text{tr} \left[\Phi \Phi^\dagger \sigma \frac{dR_k}{dk} \right] \\ &= \frac{1}{2} \int_{t,r} \text{tr} \left[\left(\frac{\delta^2 \Gamma_k}{\delta \Phi^\dagger \delta \Phi} + \sigma R_k \right)^{-1} \sigma \frac{dR_k}{dk} \right], \end{aligned} \quad (\text{A6})$$

where we repeatedly used Eqs. (A2) and (A5) and we expressed the scalar products $\Psi^\dagger \sigma \Psi$ and $\Phi^\dagger \sigma \Phi$ as traces over the internal degrees of freedom. Equation (A6) is the FRG equation which describes the flow of the effective action Γ_k upon varying the infrared cutoff k .

APPENDIX B: DERIVATION OF GAUSSIAN GREEN'S FUNCTIONS FROM Γ_0

In this appendix we show how the boundary action Γ_0 in Eq. (27) contributes to the matrix G_0 defined in Eq. (29). Let us consider the quadratic part of the effective action (we consider $Z_0 = 1$ and $h_0 = 0$ for the sake of simplicity) expressed in momentum space:

$$\Gamma = \int_{\mathbf{q}} \left(-\frac{1}{2\tau_0} \tilde{\phi}_0^2 + \tilde{\phi}_0 \phi_0 \right) + \int_{t,\mathbf{q}} \vartheta(t-t_0) \tilde{\phi}(\dot{\phi} + \omega_q \phi - D\tilde{\phi}), \quad (\text{B1})$$

where $\omega_q = q^2 + \tau$ is the dispersion law, $\int_{\mathbf{q}} \equiv \int d^d q / (2\pi)^d$, and $\phi \equiv \phi(t, \mathbf{q})$, $\tilde{\phi} \equiv \tilde{\phi}(t, \mathbf{q})$. By taking its second variation $\Gamma^{(2)}(q, t, t')$ as defined in Eq. (18), one finds

$$\Gamma^{(2)}(q, t, t') = [-V_0 \delta(t-t_0) + \hat{B}_q(t)] \delta(t-t'), \quad (\text{B2})$$

where the matrices V_0 and $\hat{B}_q(t)$ are defined as

$$V_0 = \begin{pmatrix} 0 & -1 \\ -1 & \tau_0^{-1} \end{pmatrix}, \quad \hat{B}_q(t) = \begin{pmatrix} 0 & -\partial_t + \omega_q \\ \partial_t + \omega_q & -2D \end{pmatrix}. \quad (\text{B3})$$

The matrix V_0 is obtained from the boundary action, and consequently it appears in Eq. (B2) multiplied by a delta function localized at $t = t_0$, while the term proportional to $\hat{B}_q(t)$ is, instead, related to the bulk action. The matrix $G_0(t, t')$ of the correlation functions, defined in Eq. (29), is given by $G_0(q, t, t') = [\Gamma^{(2)}]^{-1}(q, t, t')$, where the inverse is taken with respect to the internal matrix structure, the times t, t' , and the momentum q . However, since the matrix is diagonal in q , the inversion with respect to the dependence on momenta is trivial. Making use of the definition of $G(q, t, t')$ in Eq. (17), multiplying both sides by $G_{\text{eq}}(q, t, t') \equiv [\hat{B}_q(t, t')]^{-1}$, and integrating over the intermediate times, one finds

$$G_0(t, t') = G_{\text{eq}}(t, t') + G_{\text{eq}}(t, t_0) V_0 G_0(t_0, t'). \quad (\text{B4})$$

The explicit form of $G_{\text{eq}}(q, t, t')$ can be calculated by inverting the Fourier transform of $\hat{B}_q(t, t')$ and antitransforming in real time:

$$G_{\text{eq}}(q, t, t') = \int \frac{d\omega}{2\pi} e^{-i\omega(t-t')} [B_q(\omega)]^{-1} = \begin{pmatrix} D\omega_q^{-1} e^{-\omega_q|t-t'|} & \vartheta(t-t') e^{-\omega_q(t-t')} \\ \vartheta(t'-t) e^{-\omega_q(t'-t)} & 0 \end{pmatrix}. \quad (\text{B5})$$

Notice that $B_q(\omega)$ is diagonal in the frequency ω , since $\hat{B}_q(t, t')$ depends only on the difference of times $t - t'$. In fact, $G_{\text{eq}}(t, t')$ is a time-translational invariant function which corresponds to the correlation matrix of the model at thermal equilibrium. Equation (B4) can be solved by iteration, and it yields the formal solution

$$G_0(q, t, t') = G_{\text{eq}}(q, t, t') + G_{\text{eq}}(q, t, t_0) V_0 \times \sum_{n=0}^{+\infty} [G_{\text{eq}}(q, t_0, t_0) V_0]^n G_{\text{eq}}(q, t_0, t'). \quad (\text{B6})$$

Recalling that within the response functional formalism adopted here we set $\vartheta(0) = 0$ in order to ensure causality [5], we get

$$V_0 \sum_{n=0}^{+\infty} [G_{\text{eq}}(q, t_0, t_0) V_0]^n = V_0 [1 - G_{\text{eq}}(q, t_0, t_0) V_0]^{-1} = \begin{pmatrix} 0 & -1 \\ -1 & D\omega_q^{-1} + \tau_0^{-1} \end{pmatrix}. \quad (\text{B7})$$

Combining Eqs. (B6), (B5), and (B7), one finds the same Gaussian Green's functions as those in Eqs. (11) and (10), with $\Omega = 1$ and T replaced by D .

APPENDIX C: INTEGRAL EQUATION FOR G

In this appendix we derive and discuss Eq. (28) for the matrix G defined in Eq. (17). The former can be obtained by multiplying both sides of the latter by $G_0^{-1} - V$ defined in Eq. (22) and by integrating over intermediate coordinates, which yields

$$\int_y [G_0^{-1}(x, y) - V(x, y)] G(y, x') = \delta(x - x'), \quad (\text{C1})$$

where the delta function on the right-hand side of Eq. (C1) appears as a consequence of Eq. (23). Accordingly, by multiplying both sides of Eq. (C1) by G_0 and integrating over the intermediate coordinates, and by using Eq. (24), one finds the integral equation for G

$$G(x, x') = G_0(x, x') + \int_y G_0(x, y) V(y) G(y, x'). \quad (\text{C2})$$

This equation can be formally solved by iteration, and the solution can be expressed as the infinite series

$$G(x, x') = G_0(x, x') + \sum_{n=1}^{+\infty} G_n(x, x'), \quad (\text{C3})$$

where G_n are convolutions given by

$$G_n(x, x') \equiv \int_{y_1 \dots y_n} G_0(x, y_1) V(y_1) G_0(y_1, y_2) \times \dots \times V(y_n) G_0(y_n, x'). \quad (\text{C4})$$

The formal solution Eq. (C3) can be inserted into Eq. (16), providing a convenient expression for the FRG equation, which now reads (as in the main text, the dependence of Γ and R on k is understood)

$$\frac{d\Gamma}{dk} = \sum_{n=0}^{+\infty} \Delta\Gamma_n, \quad (\text{C5})$$

where

$$\Delta\Gamma_0 \equiv \frac{1}{2} \int_x \text{tr} \left[G_0(x, x) \frac{dR}{dk} \sigma \right] \quad (\text{C6})$$

and

$$\Delta\Gamma_n = \frac{1}{2} \int_x \text{tr} \left[G_n(x, x) \frac{dR}{dk} \sigma \right] \text{ for } n \geq 1. \quad (\text{C7})$$

A straightforward calculation shows that $\Delta\Gamma_0 \propto \vartheta(0)$ and therefore this term vanishes, since we assumed from the outset $\vartheta(0) = 0$ in order to ensure causality [5]. As a result, the sum over n in Eq. (C5) actually starts from $n = 1$, as in Eq. (31).

The FRG equation in the form of Eq. (C5) can be used to study the case of systems with broken time-translational symmetry, since each $\Delta\Gamma_n$ can now be calculated independently of the presence of such a symmetry. However, we emphasize that in general it is not possible to sum the series on the right-hand side of Eq. (C5) in a closed form, because the convolutions in $\Delta\Gamma_n$ are generically rather complicated nonlocal functions of the fields ϕ and $\tilde{\phi}$.

If, instead, time-translational invariance is not broken, e.g., when one takes the limit $t_0 \rightarrow -\infty$ in the action (20), the matrix G determined from Eq. (C3) is identical to the one obtained by the direct inversion of Eq. (17). In order to show this, let us assume that one is interested only in the renormalization of the potential \mathcal{U} , disregarding those of K , D , and Z . Then one makes use of the so-called local-potential approximation [67,87,92], in which the field-dependent function

$V(\mathbf{r}, t)$ introduced in Eq. (25) is evaluated on configurations of the fields ϕ and $\tilde{\phi}$ which are constant in space and time, such that $V(\mathbf{r}, t)$ is actually independent of \mathbf{r} and t . As a consequence of time-translational invariance, G depends only on the difference of its arguments, i.e., $G_0(x, x') = G_0(x - x')$ and $G(x, x') = G(x - x')$. Then, after taking the Fourier transform with respect to the relative coordinates $\mathbf{r} - \mathbf{r}'$ and $t - t'$, the convolutions in Eq. (C3) become products of the $G_0(\mathbf{k}, \omega)$, which are functions of the momentum \mathbf{k} and of the frequency ω . Accordingly, this equation becomes

$$\begin{aligned} G(\mathbf{k}, \omega) &= \sum_{n=0}^{+\infty} G_0(\mathbf{k}, \omega) [V G_0(\mathbf{k}, \omega)]^n \\ &= [G_0^{-1}(\mathbf{k}, \omega) - V]^{-1}. \end{aligned} \quad (\text{C8})$$

This expression can thus be used in Eq. (16), which then acquires a closed form. Notice that Eq. (C8) could have been obtained directly by simply taking the Fourier transform of Eq. (17) with the definition (22).

APPENDIX D: CALCULATION OF $\Delta\Gamma_1$ AND $\Delta\Gamma_2$

In this appendix, we detail the calculations which lead to Eqs. (35) and (42). Starting from Eq. (C7), we find

$$\begin{aligned} \Delta\Gamma_1 &= \frac{1}{2} \int_{t, t', \mathbf{r}, \mathbf{r}'} \text{tr} \left[G_0(\mathbf{r} - \mathbf{r}', t, t') V(t', \mathbf{r}') G_0(\mathbf{r}' - \mathbf{r}, t', t) \sigma \frac{dR}{dk} \right] = \frac{1}{2} \int_{t, t', \mathbf{q}, \mathbf{r}'} \text{tr} \left[G_0(q, t, t') V(t', \mathbf{r}') G_0(q, t', t) \sigma \frac{dR}{dk}(q) \right] \\ &= k^{d+1} \frac{a_d}{d} \int_{t, t', \mathbf{r}'} \text{tr} [G_0(k, t, t') V(t', \mathbf{r}') G_0(k, t', t) \sigma], \end{aligned} \quad (\text{D1})$$

where $a_d = 2/[\Gamma(d/2)(4\pi)^{d/2}]$, with d the spatial dimensionality and $\Gamma(x)$ the gamma function. In the second equality of Eq. (D1) one expresses $G_0(\mathbf{r}, t, t')$ in terms of its Fourier transforms $G_0(q, t, t')$ and then calculates the integral over the spatial coordinates \mathbf{r} . In the third equality, instead, after performing the integration over angular variables (which generates the factor a_d), the integral over momenta q becomes trivial since the function [see Eq. (21)]

$$\frac{dR(q)}{dk} = 2k \vartheta(k^2 - q^2) \quad (\text{D2})$$

restricts the integration domain to $0 \leq q \leq k$, within which $G_0(q, t, t')$ is constant and equal to $G_0(k, t, t')$ as a consequence of the modified dispersion relation in Eq. (30). Similarly, $\omega_{k,q}$ is replaced by $\omega_{k,q \leq k} = \omega_{k,k} = \omega_{q=k}$ [see Eq. (30) and after Eq. (11)]. Note that, since K is not renormalized within this approximation, it does not contribute to Eq. (D2) and, for simplicity, we set $K = 1$. Finally, by using the definitions (29) and (34), one evaluates the trace in Eq. (D1), finding

$$\begin{aligned} \Delta\Gamma_1 &= -2k^{d+1} \frac{a_d}{d} g \int_{\mathbf{r}'} \int_{t_0}^{+\infty} dt' \tilde{\phi}(\mathbf{r}', t') \phi(\mathbf{r}', t') \int_{t_0}^{+\infty} dt G_R(k, t', t) G_C(k, t', t) \\ &= -k^{d+1} \frac{a_d}{d} \frac{gD}{\omega_k^2} \int_{\mathbf{r}} \int_{t_0}^{+\infty} dt' \tilde{\phi}(t', \mathbf{r}) \phi(t', \mathbf{r}) [1 - f_\tau(t' - t_0)], \end{aligned} \quad (\text{D3})$$

where in the last equality the integral over time t was calculated. The function $f_\tau(t)$ is defined in Eq. (36) and corresponds to the time-dependent part of the result of the integration over t . Note that the terms proportional to ϕ^2 contained in V do not appear in the final result (as required by causality [5,63]) since they would be multiplied by a factor $\vartheta(t - t')\vartheta(t' - t) = 0$. The last equality of Eq. (D3) is nothing but Eq. (35) of the main text.

The calculation of $\Delta\Gamma_2$ is lengthier, but it proceeds as discussed above for $\Delta\Gamma_1$. From the definition in Eq. (C7) one has

$$\begin{aligned} \Delta\Gamma_2 &= \frac{1}{2} \int_{t, t', t'', \mathbf{r}, \mathbf{r}', \mathbf{r}''} \text{tr} \left[G_0(\mathbf{r} - \mathbf{r}', t, t') V(t', \mathbf{r}') G_0(\mathbf{r}' - \mathbf{r}'', t', t'') V(t'', \mathbf{r}'') G_0(\mathbf{r}'' - \mathbf{r}, t'', t) \frac{dR}{dk} \right] \\ &= \frac{1}{2} \int_{t, t', t'', \mathbf{r}', \mathbf{r}'', \mathbf{q}, \mathbf{q}'} e^{i\mathbf{r}' \cdot (\mathbf{q}' - \mathbf{q})} \text{tr} \left[G_0(q, t, t') V(t', \mathbf{r}' + \mathbf{r}'') G_0(q', t', t'') V(t'', \mathbf{r}'') G_0(q, t'', t) \frac{dR(q)}{dk} \right] \end{aligned}$$

$$\begin{aligned}
 &\approx \frac{1}{2} \int_{t,t',t'',\mathbf{r},\mathbf{r}',\mathbf{q},\mathbf{q}'} e^{i\mathbf{r}'\cdot(\mathbf{q}'-\mathbf{q})} \text{tr} \left[G_0(q,t,t') V(t',\mathbf{r}'') G_0(q',t',t'') V(t'',\mathbf{r}'') G_0(q,t'',t) \frac{dR(q)}{dk} \right] \\
 &= k^{d+1} \frac{a_d}{d} \int_{t,t',t'',\mathbf{r}''} \text{tr} [G_0(k,t,t') V(t',\mathbf{r}'') G_0(k,t',t'') V(t'',\mathbf{r}'') G_0(k,t'',t) \sigma], \tag{D4}
 \end{aligned}$$

where in the second equality we expressed the various $G_0(\mathbf{r},t,t')$ [see Eq. (29)] in terms of their Fourier transforms, we made the change of variables $\mathbf{r}' \rightarrow \mathbf{r}' + \mathbf{r}''$, and we integrated over the spatial coordinate \mathbf{r} . In the third step we expanded $V(t',\mathbf{r}' + \mathbf{r}'') \approx V(t',\mathbf{r}'')$ in order to retain only local combinations of fields, while in the last step we integrated over \mathbf{r}' and calculated the trivial integrals over \mathbf{q} and \mathbf{q}' . After determining the trace on the basis of the definitions (29) and (34), and by noticing that the prefactor of the term $\propto \phi^4$ vanishes (as required by causality [5,63]) as it contains the factor $\vartheta(t-t')\vartheta(t'-t'')\vartheta(t''-t) = 0$, Eq. (D4) becomes

$$\begin{aligned}
 \Delta\Gamma_2 &= k^{d+1} \frac{a_d}{d} g^2 \int_{\mathbf{r}''} \int_{t_0}^{+\infty} dt dt' dt'' \{ 2\tilde{\phi}(t')\phi(t')\tilde{\phi}(t'')\phi(t'') G_{0C}(k,t',t'') G_{0C}(k,t'',t) G_{0R}(k,t',t) \\
 &\quad + \tilde{\phi}(t')\phi(t')\phi^2(t'') [G_{0C}(k,t',t'') G_{0R}(k,t,t'') G_{0R}(k,t',t) \\
 &\quad + G_{0C}(k,t',t'') G_{0R}(k,t,t'') G_{0R}(k,t',t) + G_{0C}(k,t',t) G_{0R}(k,t',t'') G_{0R}(k,t'',t) \} \\
 &\simeq k^{d+1} \frac{a_d}{d} g^2 \int_{\mathbf{r}''} \int_{t_0}^{+\infty} dt' [2\tilde{\phi}^2(t')\phi^2(t') F_D(t') + \tilde{\phi}(t')\phi^3(t') F_g(t')], \tag{D5}
 \end{aligned}$$

where we omitted the dependence on \mathbf{r}'' of the fields for the sake of clarity. In the last step of Eq. (D5), we expanded the fields for $t' \simeq t''$ as $\phi(t'') \simeq \phi(t')$ and $\tilde{\phi}(t'') \simeq \tilde{\phi}(t')$ in order to retain only combinations of the fields local in time, and we introduced the functions

$$F_D(t') = \int_{t_0}^{+\infty} dt dt'' G_{0C}(k,t,t') G_{0C}(k,t',t'') G_{0R}(k,t'',t) \tag{D6}$$

and

$$\begin{aligned}
 F_g(t') &= \int_{t_0}^{+\infty} dt dt'' [G_{0C}(k,t',t'') G_{0R}(k,t,t'') G_{0R}(k,t',t) + G_{0C}(k,t,t'') G_{0R}(k,t',t'') G_{0R}(k,t',t) \\
 &\quad + G_{0C}(k,t,t') G_{0R}(k,t',t'') G_{0R}(k,t'',t)]. \tag{D7}
 \end{aligned}$$

The functions F_D and F_g can be easily evaluated using Eqs. (11) and (10), and they render

$$F_D(t) = \frac{1}{4} \frac{D^2}{\omega_k^4} [3 - f_D(t - t_0)], \tag{D8}$$

$$F_g(t) = \frac{D}{\omega_k^3} [1 - f_g(t - t_0)], \tag{D9}$$

with

$$f_D(t) = \left\{ 2 + 2\omega_k t - 2(1 + \omega_k t)^2 \left(\frac{\omega_k}{D\tau_0} - 1 \right) - \left(\frac{\omega_k}{D\tau_0} - 1 \right)^2 \right\} e^{-2\omega_k t}, \tag{D10}$$

$$f_g(t) = \left[1 + 2\omega_k t - 2(\omega_k t)^2 \left(\frac{\omega_k}{D\tau_0} - 1 \right) \right] e^{-2\omega_k t}. \tag{D11}$$

Finally, substituting Eqs. (D8) and (D9) into Eq. (D5), we find Eq. (42) of the main text.

APPENDIX E: FLOW EQUATIONS IN THE ORDERED PHASE

In this appendix, we will detail the derivation of the flow equations for the potential expanded around a finite homogeneous value $\phi = \phi_m$ and $\tilde{\phi} = 0$. For the sake of clarity, we consider the potential \mathcal{U} in Eq. (52) with $\lambda = 0$. The generalization to the case $\lambda \neq 0$ is straightforward and proceeds as in the equilibrium case (see, for instance, Refs. [87] and [69]).

First of all, since the factor K is renormalized within the ansatz discussed here, the derivative with respect to k of the regulator $R(q)$ defined in Eq. (21) has also to account for

the renormalization factor K on k , as

$$\frac{dR(q)}{dk} = \frac{K}{k} \vartheta(k^2 - q^2) [2k^2 - \eta_K(k^2 - q^2)], \tag{E1}$$

where we made use of the definition of η_K in Eq. (55); see also Ref. [69]. In fact, since the factor K depends on k within this approximation, the derivative with respect to k of Eq. (21) produces a contribution proportional to η_K .

Then, by taking the second variation of the effective action Γ in Eq. (20) [see Eq. (18)], we cast the equation for the function G defined in Eq. (17) into the same form as Eq. (C2), with the field-dependent function V defined as (we assume

$t_0 = 0$ for simplicity)

$$V(x) = -g \vartheta(t) \begin{pmatrix} \tilde{\rho}(x) & \rho(x) - \rho_m \\ \rho(x) - \rho_m & 0 \end{pmatrix}, \quad (\text{E2})$$

where we define

$$\rho \equiv \frac{\phi^2}{2}, \quad \tilde{\rho} = \tilde{\phi}\phi, \quad \rho_m \equiv \frac{\phi_m^2}{2}, \quad (\text{E3})$$

while G_0 is defined according to Eq. (29), but with the postquench parameter r replaced by

$$m = \frac{2}{3} \rho_m g. \quad (\text{E4})$$

The use of the \mathbb{Z}_2 invariants ρ and $\tilde{\rho}$ is customary in the context of FRG [69] and it helps in simplifying the notation in what follows. The form of $V(x)$ in Eq. (E2) allows us to express the right-hand side of the FRG equation (31) as a power series of $\rho - \rho_m$, in the spirit of Eq. (C5); this provides, together with the vertex expansion (19), a way to unambiguously identify the renormalization of the terms appearing in the potential \mathcal{U} in Eq. (52). In fact, ρ_m and the couplings g and λ are identified as [92]

$$\left. \frac{d\mathcal{U}}{d\rho} \right|_{\rho=\rho_m} = 0, \quad \frac{g}{3} = \left. \frac{d^2\mathcal{U}}{d\rho^2} \right|_{\rho=\rho_m}, \quad \frac{\lambda}{15} = \left. \frac{d^3\mathcal{U}}{d\rho^3} \right|_{\rho=\rho_m}, \quad (\text{E5})$$

where the first condition actually defines ρ_m as the minimum of the potential. In terms of the effective action Γ , Eq. (E5) become [69,96]

$$\left. \frac{\delta\Gamma}{\delta\tilde{\rho}} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} = 0, \quad \frac{g}{3} = \left. \frac{\delta^2\Gamma}{\delta\tilde{\rho}\delta\rho} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}}, \quad \frac{\lambda}{15} = \left. \frac{\delta^3\Gamma}{\delta\tilde{\rho}\delta\rho^2} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}}. \quad (\text{E6})$$

By taking a total derivative with respect to k of each equality in Eqs. (E6), one finds

$$\left. \frac{\delta}{\delta\tilde{\rho}} \frac{\partial\Gamma}{\partial k} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} + \left. \frac{\delta^2\Gamma}{\delta\tilde{\rho}\delta\rho} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} \frac{d\rho_m}{dk} = 0, \quad (\text{E7})$$

$$\frac{1}{3} \frac{dg}{dk} = \left. \frac{\delta^2}{\delta\tilde{\rho}\delta\rho} \frac{\partial\Gamma}{\partial k} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} + \left. \frac{\delta^3\Gamma}{\delta\tilde{\rho}\delta^2\rho} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} \frac{d\rho_m}{dk}, \quad (\text{E8})$$

$$\frac{1}{15} \frac{d\lambda}{dk} = \left. \frac{\delta^3}{\delta\tilde{\rho}\delta\rho^2} \frac{\partial\Gamma}{\partial k} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} + \left. \frac{\delta^4\Gamma}{\delta\tilde{\rho}\delta^3\rho} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} \frac{d\rho_m}{dk}, \quad (\text{E9})$$

which, after replacing $\partial\Gamma/\partial k$ with the FRG equation (16), render the flow equations for ρ_m , g , and λ . For the case of the potential \mathcal{U} in Eq. (52) with $\lambda = 0$, by using Eq. (E6), the set of flow equations (E7) and (E8) simplifies as

$$\frac{d\rho_m}{dk} = -\frac{3}{g} \left. \frac{\delta}{\delta\tilde{\rho}} \frac{\partial\Gamma}{\partial k} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} = -\frac{3}{g} \left. \frac{\delta\Delta\Gamma_1}{\delta\tilde{\rho}} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}}, \quad (\text{E10})$$

$$\frac{1}{3} \frac{dg}{dk} = \left. \frac{\delta^2}{\delta\tilde{\rho}\delta\rho} \frac{\partial\Gamma}{\partial k} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} = \left. \frac{\delta^2\Delta\Gamma_2}{\delta\tilde{\rho}\delta\rho} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}}, \quad (\text{E11})$$

where we used Eq. (C5) with $\Delta\Gamma_1$ and $\Delta\Gamma_2$ defined as in Eqs. (C7) and (C4) in terms of the $V(x)$ in Eq. (E2). The explicit form of the flow equations comes from a calculation analogous to the one discussed in Sec. IV and in Appendix D

[see Eqs. (35) and (42)]. In particular, the flow of m , defined in Eq. (E4), takes contributions from both the flow equations for ρ_m and g . Similarly, the renormalization of Z_0 is determined by the contribution localized at $t = 0$ of the coefficient of the quadratic term $\tilde{\phi}\phi$ in the effective action (20) equipped with the potential (52).

APPENDIX F: ANOMALOUS DIMENSIONS

In this appendix we discuss the derivation of the renormalization of K , Z , and D resulting from the potential \mathcal{U} in Eq. (52) and from the effective action Γ in Eq. (20).

1. Renormalization of D

The strength D of the Markovian noise can be unambiguously defined from the effective action Γ in Eq. (20) as [69]

$$D = -\rho_m \left. \frac{\delta^2\Gamma}{\delta^2\tilde{\rho}} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}}, \quad (\text{F1})$$

where ρ and $\tilde{\rho}$ are defined in Eq. (E3). By differentiating the previous equation with respect to k , we find

$$\frac{dD}{dk} = -\left(\frac{\delta^2\Gamma}{\delta^2\tilde{\rho}} + \frac{\delta^3\Gamma}{\delta^2\tilde{\rho}\delta\rho} \right) \left. \frac{d\rho_m}{dk} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} - \rho_m \left. \frac{\delta^2}{\delta^2\tilde{\rho}} \frac{\partial\Gamma}{\partial k} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}}. \quad (\text{F2})$$

For the effective action Γ in Eq. (20) with the potential \mathcal{U} in Eq. (52), the terms in parentheses in Eq. (F2) vanish and the flow equation for D simplifies as

$$\frac{dD}{dk} = -\rho_m \left. \frac{\delta^2}{\delta^2\tilde{\rho}} \frac{\partial\Gamma}{\partial k} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}} = -\rho_m \left. \frac{\delta^2\Delta\Gamma_2}{\delta^2\tilde{\rho}} \right|_{\substack{\tilde{\rho}=0 \\ \rho=\rho_m}}, \quad (\text{F3})$$

where we used Eqs. (C5) and (C7) with $V(x)$ as in Eq. (E2). In fact, a direct inspection of Eq. (42) shows that $\Delta\Gamma_2$ contains a term proportional to $\tilde{\rho}^2$, while any other term $\Delta\Gamma_n$ with $n > 2$ generated by the field-dependent function (E2) vanishes when evaluated for $\rho = \rho_m$. Accordingly, by calculating $\Delta\Gamma_2$ as in Eq. (42) (see also Appendix D), in the long-time limit within which the function $f_D(t)$ [see Eqs. (42) and (D10)] vanishes, and by applying Eq. (F3), we find the equation

$$\frac{dD}{dk} = -3k^{d+1} \frac{a_d}{d} \frac{KD^2}{Z} \left(1 - \frac{\eta_K}{d+2} \right) \frac{\rho_m g^2}{(Kk^2 + m)^4}, \quad (\text{F4})$$

with m given in Eq. (E4). Note that the factor $1 - \eta_K/(d+2)$ comes from the integration over momenta with dR/dk given by Eq. (E1). According to definition (55), η_D is eventually given by

$$\eta_D = 3k^{d+2} \frac{a_d}{d} \frac{KD}{Z} \left(1 - \frac{\eta_K}{d+2} \right) \frac{\rho_m g^2}{(Kk^2 + m)^4}. \quad (\text{F5})$$

2. Renormalization of Z

Following the general procedure described, e.g., in Refs. [69,96], in order to evaluate the correction to the coefficient Z , we express the fields ϕ and $\tilde{\phi}$ as fluctuations

around the homogeneous field ϕ_m :

$$\phi(\mathbf{r}, t) = \phi_m + \delta\phi(\mathbf{r}, t), \quad \tilde{\phi}(\mathbf{r}, t) = \delta\tilde{\phi}(\mathbf{r}, t). \quad (\text{F6})$$

By replacing Eq. (F6) into the field-dependent function $V(x)$ defined in Eq. (E2), we find

$$V(x) = V_1(x) + V_2(x), \quad (\text{F7})$$

with V_1 being linear in the fluctuations $\delta\phi$ and $\delta\tilde{\phi}$, i.e.,

$$V_1(x) = -g\phi_m\vartheta(t) \begin{pmatrix} \delta\tilde{\phi}(x) & \delta\phi(x) \\ \delta\phi(x) & 0 \end{pmatrix}, \quad (\text{F8})$$

while V_2 contains only terms quadratic in the fluctuations, i.e.,

$$V_2(x) = -g\vartheta(t) \begin{pmatrix} \delta\phi(x)\delta\tilde{\phi}(x) & [\delta\phi(x)]^2/2 \\ [\delta\phi(x)]^2/2 & 0 \end{pmatrix}. \quad (\text{F9})$$

When V in Eq. (F7) is substituted in the expression of $\Delta\Gamma_2$ in Eq. (D4), it produces a term which contains a product of two V_1 calculated at different spatial and temporal coordinates, generating a quadratic term $\propto \delta\phi\delta\tilde{\phi}$, nonlocal in both spatial and temporal coordinates. Since we are interested in the renormalization of Z , we can restrict ourselves to terms which are local in space and therefore we can use Eq. (D4) and replace V by V_1 in it; this gives [cf. Eq. (D5)]

$$\begin{aligned} \Delta\Gamma_2|_{V \rightarrow V_1} &= 4k^{d+1} \frac{a_d}{d} K \left(1 - \frac{\eta_K}{d+2}\right) g^2 \rho_m \int_{\mathbf{r}} \int_{t_0}^{+\infty} dt dt' dt'' \{2\delta\tilde{\phi}(t')\delta\tilde{\phi}(t'') G_{0C}(k, t', t'') G_{0C}(k, t'', t) G_{0R}(k, t', t) \\ &+ \delta\tilde{\phi}(t')\delta\phi(t'') [G_{0C}(k, t', t'') G_{0R}(k, t, t'') G_{0R}(k, t', t) + G_{0C}(k, t', t'') G_{0R}(k, t, t'') G_{0R}(k, t', t) \\ &+ G_{0C}(k, t, t') G_{0R}(k, t', t'') G_{0R}(k, t'', t)]\}, \end{aligned} \quad (\text{F10})$$

where the dependence of the fluctuations on the spatial coordinates \mathbf{r} has been omitted for simplicity. Then, by neglecting the term $\propto \delta\tilde{\phi}^2$, which generates only additional irrelevant terms, and by expanding $\delta\phi(t'')$ for $t'' \simeq t'$ as $\delta\phi(t'') \simeq \delta\phi(t') + (t'' - t')\delta\dot{\phi}(t')$, keeping only the derivative, from Eq. (F10) we find

$$\Delta\Gamma_2|_{V \rightarrow V_1} \simeq 4k^{d+1} \frac{a_d}{d} K \left(1 - \frac{\eta_K}{d+2}\right) g^2 \rho_m \int_{\mathbf{r}} \int_{t_0}^{+\infty} dt' \delta\tilde{\phi}(t') \delta\dot{\phi}(t') F_Z(t'), \quad (\text{F11})$$

where

$$\begin{aligned} F_Z(t') &= \int_{t_0}^{+\infty} dt dt'' (t'' - t') [G_{0C}(k, t', t'') G_{0R}(k, t, t'') G_{0R}(k, t', t) \\ &+ G_{0C}(k, t, t'') G_{0R}(k, t', t'') G_{0R}(k, t', t) + G_{0C}(k, t, t') G_{0R}(k, t', t'') G_{0R}(k, t'', t)]. \end{aligned} \quad (\text{F12})$$

The function $F_Z(t)$ can be easily evaluated using Eqs. (11) and (10), and reads

$$F_Z(t) = \frac{D}{4\omega_k^4} [3 - f_Z(t - t_0)], \quad (\text{F13})$$

where $f_Z(t)$ is a function which vanishes exponentially fast upon increasing t and therefore does not contribute to the renormalization of Z at long times. Finally, by replacing Eq. (F13) into Eq. (F11), and by comparing the right-hand side of Eq. (C5) with its left-hand side in which the effective action (20) has been inserted, one finds the flow equation for Z :

$$\frac{dZ}{dk} = -3k^{d+1} \frac{a_d}{d} \frac{KD}{Z} \left(1 - \frac{\eta_K}{d+2}\right) \frac{g^2 \rho_m}{(Kk^2 + m)^4} Z, \quad (\text{F14})$$

where m is given in Eq. (E4). By using the definitions in Eq. (55), one thus finds the expression of the anomalous dimension η_Z :

$$\eta_Z = 3k^{d+2} \frac{a_d}{d} \frac{KD}{Z} \left(1 - \frac{\eta_K}{d+2}\right) \frac{g^2 \rho_m}{(Kk^2 + m)^4}. \quad (\text{F15})$$

3. Renormalization of K

The calculation of the flow equation for K proceeds as in the case of Z discussed in the previous section; i.e., we

expand the field ϕ around the homogeneous configuration as in Eq. (F6). This renders the same field-dependent function $V(x)$ as in Eq. (F7), containing a term V_1 linear in the fluctuations which—when inserted in the expression (D4) for $\Delta\Gamma_2$ —generates quadratic terms which are nonlocal in spatial and temporal coordinates. It is convenient to define K as follows [96]:

$$K = \mathcal{N} \frac{\partial}{\partial p^2} \frac{\delta^2 \Gamma}{\delta\tilde{\phi}(t, -\mathbf{p})\delta\phi(t, \mathbf{p})} \Big|_{\substack{\mathbf{p}=0 \\ \delta\tilde{\phi}=\delta\phi=0}}, \quad (\text{F16})$$

where \mathcal{N} is a normalization factor formally given by $\mathcal{N} = (2\pi)^d / [\delta^{(d)}(q=0)\delta(t=0)]$, and \mathbf{p} is a given momentum, eventually vanishing. By taking the total derivative with respect to k of the previous expressions, we find

$$\begin{aligned} \frac{dK}{dk} &= \mathcal{N} \frac{\partial}{\partial p^2} \frac{\delta^2}{\delta\tilde{\phi}(t, -\mathbf{p})\delta\phi(t, \mathbf{p})} \frac{\partial \Gamma}{\partial k} \Big|_{\substack{\mathbf{p}=0 \\ \delta\tilde{\phi}=\delta\phi=0}} \\ &= \mathcal{N} \frac{\partial}{\partial p^2} \frac{\delta^2 \Delta\Gamma_2|_{V \rightarrow V_1}}{\delta\tilde{\phi}(t, -\mathbf{p})\delta\phi(t, \mathbf{p})} \Big|_{\substack{\mathbf{p}=0 \\ \delta\tilde{\phi}=\delta\phi=0}}, \end{aligned} \quad (\text{F17})$$

where in the last equality we used Eq. (C5) and the fact that the sole nontrivial contribution comes from the part of $\Delta\Gamma_2$ (indicated as $\Delta\Gamma_2|_{V \rightarrow V_1}$ in the previous equation) involving the product of two V_1 (see Appendix F2). From Eq. (D4), we

find with some simple calculations

$$\begin{aligned}
 \Delta\Gamma_2|_{V \rightarrow V_1} &= \frac{1}{2} \int_{t,t',t'',\mathbf{q},\mathbf{q}'} \text{tr} \left[G_0(q,t,t') V(t',\mathbf{q}-\mathbf{q}') G_0(q',t',t'') \right. \\
 &\quad \left. \times V(t'',\mathbf{q}'-\mathbf{q}) G_0(q,t'',t) \frac{dR}{dk}(q) \right] \\
 &\simeq 2g^2 \rho_m \int_{t',\mathbf{q},\mathbf{q}'} \delta\tilde{\phi}(\mathbf{q}-\mathbf{q}',t') \delta\phi(\mathbf{q}'-\mathbf{q},t') \\
 &\quad \times F_K(q,q',t') \frac{dR(q)}{dk}, \tag{F18}
 \end{aligned}$$

where $V(t,\mathbf{q}) = \int_{\mathbf{r}} e^{-i\mathbf{q}\cdot\mathbf{r}} V(t,\mathbf{r})$ and in the last step we retained only the part of the fields which is local in time by expanding them as $\delta\phi(t'') \simeq \delta\phi(t')$ for $t'' \simeq t'$. In the last equality of Eq. (F18), we also discarded the term proportional to $\delta\tilde{\phi}^2$, which does not contribute to the renormalization of K . The function $F_K(q,q',t')$ in Eq. (F18) is defined as

$$\begin{aligned}
 F_K(q,q',t') &= \int_{t_0}^{+\infty} dt dt'' [G_{0C}(q',t',t'') G_{0R}(q,t,t'') G_{0R}(q,t',t) \\
 &\quad + G_{0C}(q,t,t'') G_{0R}(q',t',t'') G_{0R}(q,t',t) \\
 &\quad + G_{0C}(q,t,t') G_{0R}(q',t',t'') G_{0R}(q,t'',t)]. \tag{F19}
 \end{aligned}$$

Then, combining Eqs. (F17) and (F18), one finds

$$\frac{\delta^2 \Delta\Gamma_2|_{V \rightarrow V_1}}{\delta\tilde{\phi}(t,-\mathbf{p})\delta\phi(t,\mathbf{p})} = \frac{2g^2 \rho_m}{\mathcal{N}} \int_{\mathbf{q}} F_K(q,|\mathbf{q}-\mathbf{p}|,t) \frac{dR(q)}{dk}. \tag{F20}$$

In order to evaluate Eq. (F17), we need to retain the contribution proportional to p^2 from $F_K(q,|\mathbf{q}-\mathbf{p}|,t)$ defined in Eq. (F19). To this end, we define the function $P(q) \equiv K[q^2 + (k^2 - q^2)\vartheta(k^2 - q^2)]$ and note that $G_{0R,0C}(q,t,t')$ depend on q via $P(q)$, as their explicit expression is given by Eqs. (5) and (6) with ω_q replaced by $\omega_{k,q} = P(q) + \tau$ given in Eq. (30). For a generic function of $P(q)$ one can write

$$\frac{\partial^2}{\partial q_i \partial q_j} = \frac{\partial P(q)}{\partial q_i} \frac{\partial P(q)}{\partial q_j} \frac{\partial^2}{\partial P^2} + \frac{\partial^2 P}{\partial q_i \partial q_j} \frac{\partial}{\partial P}, \tag{F21}$$

where $i, j = 1, \dots, d$ label the components of the momenta q_i . A simple calculation shows that

$$\frac{\partial P(q)}{\partial q_i} = 2K q_i [1 - \vartheta(k^2 - q^2)], \tag{F22}$$

$$\frac{\partial^2 P(q)}{\partial q_i \partial q_j} = 2K \delta_{ij} [1 - \vartheta(k^2 - q^2)] + 4K q_i q_j \delta(k^2 - q^2),$$

and therefore, all contributions proportional to $1 - \vartheta(k^2 - q^2)$ vanish when inserted into the integral on the right-hand side of Eq. (F20), because they multiply the term $\propto \vartheta(k^2 - q^2)$ contained in dR/dk [see Eq. (E1)]. Accordingly, by discarding these contributions, the derivatives $\partial^2 G_{0R,0C}(q,t,t')/\partial q_i \partial q_j$ which are involved in the expansion of the function F_K in the

integrand of Eq. (F20) can be effectively replaced by

$$\frac{\partial^2 G_{0R/0C}(q,t,t')}{\partial q_i \partial q_j} \mapsto \frac{\partial G_{0R/0C}(q,t,t')}{\partial P(q)} 4K q_i q_j \delta(k^2 - q^2), \tag{F23}$$

where, from Eqs. (10) and (11) with $\omega_q \rightarrow \omega_{k,q}$ given in Eq. (30), we have

$$\frac{\partial G_{0R}(q,t,t')}{\partial P(q)} = -(t-t') G_{0R}(q,t,t'), \tag{F24}$$

$$\begin{aligned}
 \frac{\partial G_{0C}(q,t,t')}{\partial P(q)} &= -\frac{D}{\omega_{k,q}} \left[\left(\frac{1}{\omega_{k,q}} + |t-t'| \right) e^{-\omega_{k,q}|t-t'|} \right. \\
 &\quad \left. + \left(\frac{1}{\omega_{k,q}} + t+t' \right) \left(\frac{\omega_{k,q}}{D\tau_0} - 1 \right) e^{-\omega_{k,q}(t+t')} \right]. \tag{F25}
 \end{aligned}$$

Accordingly, terms proportional to p^2 in the Taylor expansion of $F_K(q,|\mathbf{q}-\mathbf{p}|,t)$ can be obtained by using Eqs. (F19), (F23), (F24), and (F25), and they eventually read

$$\frac{1}{2} \sum_{i,j=1}^d p_i p_j \frac{\partial^2 F_K(q,q,t)}{\partial q_i \partial q_j} = 2K(\mathbf{q} \cdot \mathbf{p})^2 \delta(k^2 - q^2) \tilde{F}_K(q,t), \tag{F26}$$

with

$$\begin{aligned}
 \tilde{F}_K(q,t') &= \int_{t_0}^{+\infty} dt dt'' \left[\frac{\partial G_{0C}(q,t',t'')}{\partial P(q)} G_{0R}(q,t,t'') G_{0R}(q,t',t) \right. \\
 &\quad + G_{0C}(q,t,t'') \frac{G_{0R}(q,t',t'')}{\partial P(q)} G_{0R}(q,t',t) \\
 &\quad \left. + G_{0C}(q,t,t') \frac{\partial G_{0R}(q,t',t'')}{\partial P(q)} G_{0R}(q,t'',t) \right]. \tag{F27}
 \end{aligned}$$

Then, by inserting Eq. (F26) into Eq. (F20), and by using the fact that, from Eq. (E1),

$$\frac{dR_k}{dk} \delta(k^2 - q^2) = \frac{1}{2} K \delta(k - q), \tag{F28}$$

as well as the identity for the d -dimensional integral of a rotational-invariant function $f(q)$

$$\int d^d q (\mathbf{q} \cdot \mathbf{p})^2 f(q) = \frac{p^2}{d} \int d^d q q^2 f(q), \tag{F29}$$

we find

$$\frac{\partial^2}{\partial p^2} \frac{\delta^2 \Delta\Gamma_2|_{V_1^2}}{\delta\tilde{\phi}(t,-\mathbf{p})\delta\phi(t,\mathbf{p})} \Big|_{\mathbf{p}=0} = 2 \frac{a_d}{d} k^{d+1} \frac{g^2 \rho_m}{\mathcal{N}} K^2 \tilde{F}_K(k,t). \tag{F30}$$

Finally, a lengthy but straightforward evaluation of $\tilde{F}_K(k,t)$, using Eqs. (F19), (10), and (11) with $\omega_q \rightarrow \omega_{k,q}$ [see Eq. (30)], yields

$$\tilde{F}_K(k,t) = -\frac{D}{Z\omega_k^4} [1 - f_K(t)], \tag{F31}$$

where $\omega_k = \omega_{q=k}$ and $f_K(t)$ is a function which vanishes exponentially fast upon increasing t and therefore does not

contribute to the renormalization of K at long times. By inserting Eqs. (F31) and (F30) into Eq. (F17), we finally find the flow equation for K , which reads

$$\frac{dK}{dk} = -2k^{d+1} \frac{a_d}{d} \frac{DK^2}{Z} \frac{g^2 \rho_m}{(Kk^2 + m)^4}, \quad (\text{F32})$$

and, according to Eq. (55), the anomalous dimension η_K reads

$$\eta_K = 2k^{d+2} \frac{a_d}{d} \frac{DK}{Z} \frac{g^2 \rho_m}{(Kk^2 + m)^4}. \quad (\text{F33})$$

APPENDIX G: FLOW EQUATIONS

In this appendix we report the explicit form of the flow equations derived from the effective action Γ in Eq. (20) with the potential \mathcal{U} in Eq. (52) and $\lambda \neq 0$. These equations can be derived by repeating the calculations presented in Appendices E and F but by keeping λ finite; here we report only the final result of this somewhat lengthy calculation. The flow equations for the couplings \tilde{m} , \tilde{g} , and $\tilde{\lambda}$, defined in Eq. (56), turn out to be

$$k \frac{d\tilde{m}}{dk} = (-2 + \eta_K) \tilde{m} + \left(1 - \frac{\eta_K}{d+2}\right) \frac{2\tilde{g}}{(1+\tilde{m})^2} \left[1 + \frac{3}{2} \left(\frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right)^2 + \frac{3\tilde{m}}{1+\tilde{m}} \left(1 + \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right)^2\right], \quad (\text{G1})$$

$$k \frac{d\tilde{g}}{dk} = g \left[d - 4 + 2\eta_K + \left(1 - \frac{\eta_K}{d+2}\right) \frac{6g}{(1+\tilde{m})^3} \left(1 + \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right)^2 \right] + \left(1 - \frac{\eta_K}{d+2}\right) \frac{\tilde{\lambda}}{(1+\tilde{m})^2} \left(-2 + 3 \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right), \quad (\text{G2})$$

$$k \frac{d\tilde{\lambda}}{dk} = \tilde{\lambda} \left[2d - 6 + 3\eta_K + 30 \left(1 - \frac{\eta_K}{d+2}\right) \frac{\tilde{g}}{(1+\tilde{m})^3} \left(1 + \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right) \right] - 18 \left(1 - \frac{\eta_K}{d+2}\right) \frac{\tilde{g}^2}{(1+\tilde{m})^4} \left(1 + \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right), \quad (\text{G3})$$

while the anomalous dimensions η_K, η_D, η_Z and η_0 , defined, respectively, in Eqs. (55) and (46), read

$$\eta_K = \frac{3\tilde{m}\tilde{g}}{(1+\tilde{m})^4} \left(1 + \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right)^2, \quad (\text{G4})$$

$$\eta_Z = \eta_D = \left(1 - \frac{\eta_K}{d+2}\right) \frac{9\tilde{m}\tilde{g}}{2(1+\tilde{m})^4} \left(1 + \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right)^2, \quad (\text{G5})$$

$$\eta_0 = -\left(1 - \frac{\eta_K}{d+2}\right) \frac{\tilde{g}}{(1+\tilde{m})^3} \left[1 + \frac{3}{2} \left(\frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right)^2 + \frac{9\tilde{m}}{2(1+\tilde{m})} \left(1 + \frac{\tilde{m}\tilde{\lambda}}{\tilde{g}^2}\right)^2\right]. \quad (\text{G6})$$

Setting to zero Eqs. (G1), (G2), (G3), we find numerically (using Wolfram Mathematica) the following fixed point values of the rescaled couplings (up to the second significative digit):

$$\tilde{m}^* \simeq 0.30, \quad \tilde{g}^* \simeq 0.26, \quad \tilde{\lambda}^* \simeq 0.04. \quad (\text{G7})$$

The linearization of the flow equations (G1), (G2), and (G3) around the fixed point values given in Eq. (G7) determines the associated stability matrix, and from the inverse of its negative eigenvalue (see for instance Ref. [95]), we find the critical exponent ν reported in Sec. V C. The values $\eta_{K,Z,0}^*$ of the anomalous dimensions at the fixed point are found by replacing directly Eq. (G7) into the expressions (G4), (G5), and (G6).

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