

Current-induced fingering instability in magnetic domain walls

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The shape instability of magnetic domain walls under current is investigated in a ferromagnetic (Ga,Mn)(As,P) film with perpendicular anisotropy. Domain wall motion is driven by the spin transfer torque mechanism. A current density gradient is found either to stabilize domains with walls perpendicular to current lines or to produce fingerlike patterns, depending on the domain wall motion direction. The instability mechanism is shown to result from the nonadiabatic contribution of the spin transfer torque mechanism.

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Interface instabilities are encountered in a great variety of physical systems such as liquids [1], liquid-gas interfaces, ferro- and ferrimagnetic films [2–4], electrically polarizable and magnetic liquids [5–7], the intermediate state in type I superconductors [8,9], etc. These instabilities originate from a competition between the surface tension, which tends to favor flat interfaces, and a destabilizing interaction as a gradient of external driving force (temperature, gravitational field, magnetic field, etc.), or as long-range dipolar interactions [10,11] for quasi-two-dimensional systems [12]. A crucial point for understanding the interface dynamics as well as the formation of domain pattern is to determine the parameters controlling the instabilities and their formation mechanism.

In ferromagnetic systems, it was shown recently that domain walls (DWs) can be moved by a spin polarized current [13–16] through the so-called spin transfer torque (STT) [17–20]. This has motivated an intense research effort for elucidating the physics of STT and for potential applications in spin electronics [21,22]. The STT acts as a driving force proportional to the current density. As expected by analogy with the well-studied field-driven dynamics, essentially two dynamical regimes are observed. At low drive, DWs move in the pinning-dependent creep regime. Above a depinning threshold, the dynamics corresponds to flow regimes limited by dissipation [16]. Current-driven DW dynamics is most generally studied in narrow tracks, where DWs remain stable over the track width. However, field- and current-driven dynamics exhibit, in extended geometry, quite different behavior. A magnetic field acts essentially as a magnetic pressure pushing DWs with an average uniform velocity. In contrast, the current-driven creep regime was found to result in the formation of triangular domain shapes [23]. In the flow regime [24], the DW velocity was shown to depend on the respective orientations of the DW and the current flow. Those observations suggest a complex interplay between the DW shape and dynamics, and the STT magnitude.

In this frame, it is particularly interesting to characterize the shape stability of DWs driven by current. To address this issue, we investigated DW motion under current in wide geometries where instabilities induced by current and/or dipolar interactions can develop and be visualized. We used a (Ga,Mn)(As,P) thin film with perpendicular magnetization due to the extraordinary weak current density that is required for DW motion, which gives us access to a wide range of dynamical regimes [16,25]. To get a better understanding of the role of current-induced motion on DW stability, we introduce, on purpose, a progressive current density gradient by patterning our device in a semicircular geometry [26].

In this Rapid Communication, we show how the STT mechanism affects the domain pattern and the DW shape stability. We found, in particular, that a current density gradient, depending on the DW motion direction, stabilizes or destabilizes the DW shape. A model, also taking into account the surface tension and dipolar interactions, grasps the main features of DW stability.

A 50 nm thick (Ga_{0.95}Mn_{0.05})(As_{0.9}P_{0.1}) film was grown by low-temperature ($T = 250^\circ\text{C}$) molecular beam epitaxy on a GaAs (001) substrate [25]. It was then annealed at $T = 250^\circ\text{C}$ for 1 h. Its magnetic anisotropy is perpendicular (saturation magnetization $M = 23 \pm 1$ kA/m) and its Curie temperature T_c is 119 ± 1 K. The semicircular geometry (100 μm radius) was patterned by electron beam lithography and etching and then connected to a narrow (width $w = 2$ μm) electrode at the straight edge center and to a semicircular electrode made of Ti (20 nm)/Au (200 nm) layers [see Fig. 1(a)]. The shape of the magnetic domains and of DWs is controlled by differential polar magneto-optical Kerr microscopy with a 1 μm resolution in a cryostat with a base temperature of 95 K for all the experiments presented here [see Figs. 1(b)–1(d)]. The two gray levels correspond to opposite magnetization directions perpendicular to the film. Due to the semicircular geometry, the electrical current lines are radial. The current density j decays with the distance r from the narrow electrode as $j(r) \approx I/\pi r h$ (I is the injected current and $h = 50$ nm the film thickness) so that the absolute value of the gradient

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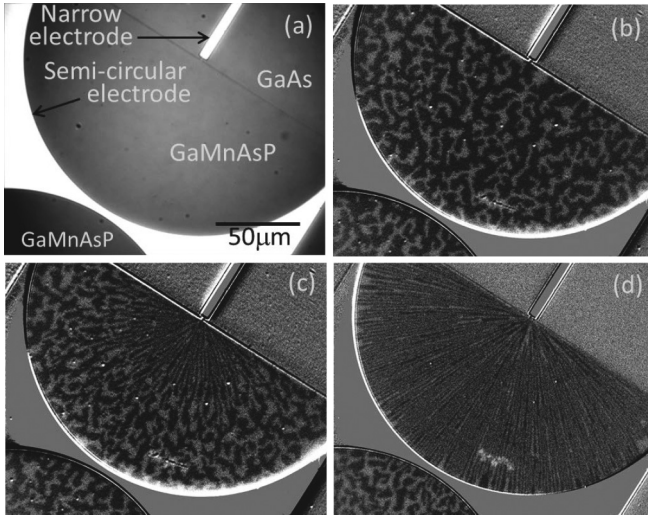


FIG. 1. Current-induced modification of the magnetic domain pattern. (a) Sample description. (b) Magnetic-field-driven domain pattern corresponding to the initial magnetic state. (c), (d) Modification of the domain pattern due to a dc current. The current flows from the narrow to the semicircular electrode ($j > 0$) for 60 s. Its amplitude was (c) $I = 2.16$ mA and (d) $I = 2.98$ mA. The domain pattern is observed by magneto-optical Kerr microscopy. The two gray levels reflect the two opposite magnetization directions perpendicular to the (Ga,Mn)(As,P) film. $T = 95$ K.

decreases progressively with r as $|dj/dr| = |I|/(\pi hr^2)$. In the following, by convention, $I > 0$ (i.e., $j > 0$) corresponds to a current flow from the narrow to the semicircular electrode.

First evidences of domain wall shape instability are shown in Fig. 2. A set of semiconcentric magnetic domains centered on the narrow electrode [see Figs. 2(a) and 2(e)] was prepared using current-induced stochastic domain nucleation and DW propagation (see Ref. [26] for details) starting from a uniform magnetization state. Next, a dc current was injected between the two electrodes for a fixed duration, after which an image was acquired. The sequence is repeated for Figs. 2(b)–2(d) with increasing current (for 60 s at $I = 0.7, 1.1, \text{ and } 1.2$ mA) and for Figs. 2(e)–2(g) with increasing duration (1 μs , 10 μs , and 100 μs at $I = -1.547$ mA). The DW motion observed in Figs. 2(b)–2(d) and 2(e)–2(g) originates from the spin transfer torque. In ferromagnets, the electrical current is spin polarized and carriers crossing a DW exert a torque on the local magnetic moment, which results in DW propagation. In (Ga,Mn)(As,P) films with perpendicular anisotropy, DW motion is in the opposite direction to the current [16], as it can be observed. In this experiment, different DW dynamical regimes are expected to occur due to the decay of j with r . Close to the narrow electrode, the current density ($j \approx I/hw = 10\text{--}20$ GA/m², where $w = 2$ μm is the width of the narrow electrode) is sufficiently large for the flow regime to be reached [16] while pinning-dependent regimes are expected to occur in the other parts of the device.

The most original of the results shown in Fig. 2 is the dependence of the shape of the domains on the current polarity. For $j > 0$, the semicircular symmetry of the domains breaks. In Fig. 2(b), the black domain next to the narrow electrode expands toward the electrode by forming fingerlike shapes.

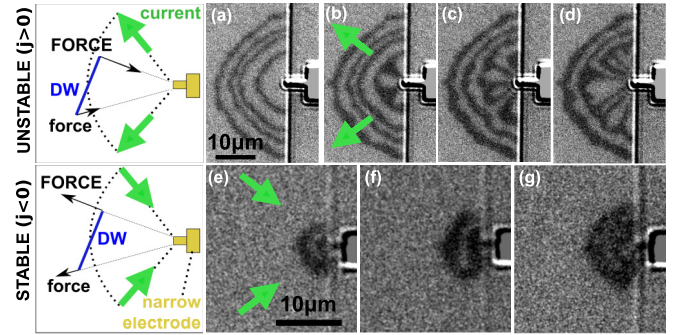


FIG. 2. (Color online) Instability of magnetic DW produced by a gradient of current density. Left frames: Stability of a domain wall (dotted arcs) placed perpendicularly to a current density gradient. A small tilt of an elementary wall length (blue segments) produces an asymmetry of the forces due to spin transfer (thin black arrows). A current flow (thick green arrows) in the direction of the narrow electrode ($j > 0$, top frame) tends to destabilize the initial orientation while it tends to be stabilized for $j < 0$ (bottom frame). (a)–(d) DW shape instability for $j > 0$. (a) Initial state. (b)–(d) A 60 s dc current flow produces a finger growth towards the narrow electrode. Increasing the current magnitude [$I = 0.70, 1.10, \text{ and } 1.20$ mA for (b)–(d), respectively] enhances the distance at which the semicircular DWs become unstable. (e)–(g) Stable radial DW growth for $j < 0$. The sample that is initially in an homogeneous magnetic state is submitted to a current pulse of amplitude -1.547 mA of increasing duration [1 μs , 10 μs , and 100 μs for (e)–(g), respectively]. The propagation front remains almost semicircular. The weak anisotropy of magnetic domain growth is most probably associated with the in-plane anisotropy of the (Ga,Mn)(As,P) single crystal. $T = 95$ K.

As the current amplitude increases [Figs. 2(c) and 2(d)], the instability process also takes place in domains located farther away from the electrode. In contrast, for $j < 0$, the semicircular geometry is conserved. The shape of the domain walls is stable during the motion. We explain now, first qualitatively, the contribution of the current density gradient to the domain wall stability. The left frames of Fig. 2 give a schematic description of this mechanism. Let us consider a slightly tilted elementary DW segment. Due to the current density gradient, the two segment ends experience a different STT amplitude. It is larger for the one closer to the narrow electrode. This asymmetry is the driving mechanism for the DW stabilization or destabilization. When the j is negative, the STT force points away from the narrow electrode and the DW segment moves away from the electrode. However, the lagging segment extremity experiences a stronger STT force than the opposite end, therefore acting as a restoring force. The DW remains stable during its motion. In turn, this mechanism is responsible for the DW destabilization when $j > 0$ (opposite DW motion direction) since the STT force is stronger for the forward end. It eventually leads to domain growth along the current lines. This behavior shares similarities with the Rayleigh-Taylor instability [1], when a heavier liquid is above a lighter one.

This instability mechanism has dramatic consequences on domain pattern formation up to very large radii and hence very low DW velocities [see Figs. 1(b)–1(d)]. Figure 1(b) shows an initial demagnetized state (obtained before applying any

magnetic field or current). The magnetic domains with opposite magnetization direction present a self-organized pattern, as usually observed in ferromagnetic films with perpendicular anisotropy. The typical domain width and spacing (≈ 10 and $\approx 20 \mu\text{m}$, respectively) results from a balance between the positive DW energy and long-range magnetic interactions between domains [27]. The domain shape corresponds to randomly oriented corrugated lamellae.

After applying a positive dc current ($j > 0$) for 60 s [see Figs. 1(c) and 1(d)], the domains tend to be aligned radially. For the largest current value ($I = 2.98 \text{ mA}$), the domain pattern is modified over the full sample surface area, as observed in Fig. 1(d). The DWs are aligned along the current lines, a consequence of the gradient-induced destabilization mechanism described earlier. We can get insight into the DW organization dynamics when injecting lower current values. In that case, the domain pattern modification remains spatially limited by a semicircular boundary centered on the narrow electrode, as seen in Fig. 1(c) ($I = 2.16 \text{ mA}$). Indeed, sufficiently far from the narrow electrode, DWs follow dynamical regimes controlled by DW pinning and thermal activation. In those regimes, the DW velocity varies exponentially with the driving force. As the STT amplitude decreases as $|I|/r$, the DW velocity considerably reduces as it is located at a greater distance from the high current density regions close to the narrow electrode. Therefore, for a limited current pulse duration (60 s), each given current value I defines a clear-cut semicircular boundary separating regions with unmodified patterns (at a scale of the experimental spatial resolution $\approx 1 \mu\text{m}$) from regions presenting significant DW displacements, as observed in Fig. 1(c).

At this point, we have shown how a current density gradient can stabilize or destabilize a DW. However, we have not considered yet how this mechanism competes or cooperates with the other mechanisms involved in DW stability, such as dipolar interactions and the DW surface tension. To that end, we extended the experiment described in Figs. 2(e)–2(h) ($I = -1.55 \text{ mA}$) to longer current pulses. As previously, the sample was first prepared in a fully homogeneous magnetized state. Negative current pulses were injected for 10 ms, 690 ms, and 29.7 s durations. In this situation, the gradient acts as a stabilization contribution. For the shortest duration, the domains present a semicircular shape [see Fig. 3(a)] that reflects the current line symmetry, as already observed in Figs. 2(e)–2(h). However, for the longest durations [see Figs. 3(b) and 3(c)], the semicircular shape of the domains with the largest radius becomes unstable and fingerlike domain growth is observed. The finger width is close to the typical size of the domain patterns observed in the demagnetized configuration [see Fig. 1(b)]. This behavior strongly points toward dipolar interactions as the destabilization mechanism. For a different injected current I , the values of the critical instability radius r_c at which the finger-shaped domains start to grow were systematically deduced from images [such as those presented in Figs. 3(a)–3(c)] obtained for a large set of increasing pulse durations. As reported in Fig. 3(d), r_c^2 is found to vary linearly with I , i.e., the critical radius is associated to a well-defined critical current density gradient $|dj/dr|_c = |I|/(\pi h r_c^2)$. Therefore, the DW shape instability observed in Figs. 3(a)–3(c) occurs when the current density

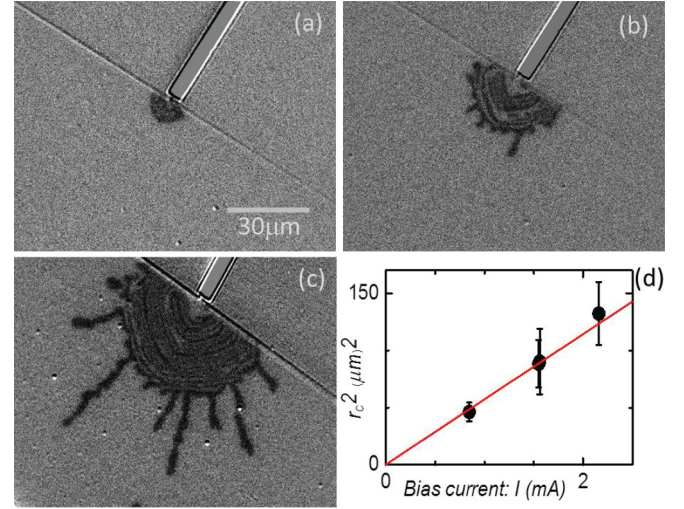


FIG. 3. (Color online) Fingerlike magnetic domain growth resulting from domain wall instability. The images were obtained for a constant current ($I = -1.55 \text{ mA}$) directed towards the narrow electrode ($j < 0$) and for different durations [(a) 100 μs , (b) 690 ms, and (c) 29.7 s]. $T = 95 \text{ K}$. (d) Square of the critical instability radius as a function of the bias current. The line corresponds to the best fit of the theoretical prediction.

gradient becomes too weak to stabilize the DWs perpendicular to current lines against the dipolar interactions.

To get more quantitative insight on the DW shape instabilities, we have elaborated a model that describes the stability limit of a flat DW subjected to an electrical current gradient. The model considers a ferromagnetic layer of thickness h , aligned along the z direction. A flat DW separating two domains with opposite magnetization directions is parallel to the x - z plane. The DW is submitted to a current flow exhibiting a gradient in the y direction. The magnetization vector is given as $\vec{M} = M(\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$. In the perturbed state, the DW position is given by the equation $y = q(x, t)$. The DW shape stability analysis is based on the Landau-Lifshitz-Gilbert equation and follows the calculation of Refs. [28,29]. The full calculation is detailed in the Supplemental Material [30]. For a weakly perturbed DW, the equations of motion are

$$\gamma \left(\mu_0 M + \frac{2\psi_{2M}(q, h)}{h} \right) - \frac{2A\gamma}{M\Delta} \frac{\partial^2 q}{\partial x^2} = \dot{\varphi} - \frac{\alpha \dot{q}}{\Delta} + \frac{\beta u}{\Delta} \quad (1)$$

and

$$\frac{\mu_0}{2} \gamma M \sin 2\varphi - \frac{2A\gamma}{M} \frac{\partial^2 \varphi}{\partial x^2} = -\alpha \dot{\varphi} + \frac{u}{\Delta} - \frac{\dot{q}}{\Delta}, \quad (2)$$

where γ , α , and β are the gyromagnetic factor, the Gilbert damping parameter, and the so-called nonadiabatic term, respectively. $\Delta = \sqrt{A/K}$ is the domain wall thickness parameter, where A and K are the spin stiffness and the anisotropy constant, respectively. The parameter u is the spin drift velocity defined by $u = \frac{jP_c g \mu_B}{2eM}$, where j , P_c , g , μ_B , and e (< 0), are the current density, the current spin polarization, the Landé factor, the Bohr magneton, and the electron charge, respectively. In Eq. (1), $\psi_{2M}(q, h)$ is a potential describing

the dipolar interaction between the DW magnetization and the field created by the two magnetic domains with opposite magnetization.

For a small perturbation $\delta\varphi, \delta q$ of the DW, the perturbation of the spin drift velocity can be written as $\delta u \approx (du/dq)\delta q$. Assuming a steady DW motion ($\dot{\varphi} = 0$) and looking for solutions of the type $\delta q \sim \delta q_0 \exp(ikh)$, Eq. (1) leads to a growth rate of the instability given by

$$\frac{d(\delta q_0)}{dt} = \frac{\mu_0 M \gamma \Lambda^2}{\alpha h^2} \left[F + \frac{du}{dq} \frac{\beta}{\mu_0 M} \frac{h^2}{\gamma \Lambda^2} \right] \delta q_0, \quad (3)$$

where we have introduced the exchange length Λ defined by $A = \mu_0 M^2 \Lambda^2 / 2$, and the magnetic Bond number [31] $B_m = \mu_0 (2M)^2 h / (4\pi\sigma)$ with the DW surface energy given by $\sigma = 4\sqrt{AK}$. In Eq. (3), the function F is given by $F = 4B_m(\gamma_E + \log(kh/2) + K_0(kh)) - (kh)^2$, where $K_0(kh)$ is the McDonald function and $\gamma_E (= 0.5772)$ is the Euler constant.

The differential equation (3) shows that a flat DW is unstable [i.e., $d(\delta q_0)/dt > 0$] if the term in brackets on the right-hand side is positive. The instability thus results from a competition between the dipolar energy (the first terms of function F), the DW surface tension [the term $(kh)^2$ in F], and the STT gradient [$\propto du/dq$ in Eq. (3)]. One should note that only the nonadiabatic contribution ($\propto \beta$) of the STT plays a role in DW stability [30]. The fastest instability growth rate corresponds to the function F maximum which is equal to $F_{\max} = 2B_m \exp(1 - 2\gamma_E - 2/B_m)$ and to a wavelength $\lambda = \pi h \exp(\gamma_E + 1/B_m - 1/2)$, in the limit of small kh .

For the semicircular geometry considered in this work, the conservation of the current $I = j\pi r h$ leads to $\frac{du}{dq} = \frac{I P_c g \mu_B}{\pi h r^2 2|e|M}$. For a current flow from the narrow electrode ($j > 0$, i.e., $du/dq > 0$), the term in brackets in Eq. (3) remains positive and the flat DW is always unstable. This corresponds to the case presented in the top frames of Fig. 2 for which both the current density gradient and the dipolar interactions have a destabilizing contribution. For the opposite current direction ($j < 0$, i.e., $du/dq < 0$), the DW is only stable below a critical radius given by $r_c^2 = I \frac{C}{F_{\max}}$, where $C = \frac{h\beta P_c g \mu_B}{4\pi A \gamma |e|}$ [see Figs. 2(e)–2(g) and 3(a)]. Above this critical radius, as the stabilization contribution of the gradient becomes too weak to counteract the effect of dipolar interactions, the domain wall becomes unstable. This instability leads to the growth of fingerlike domains, as observed in Figs. 3(b) and 3(c).

Comparing those predictions to the experimental results requires the evaluation of the magnetic Bond number B_m . First, B_m can be estimated from the critical radius r_c , measured in Fig. 3(d). The data best fit gives a ratio $r_c^2/I = C/F_{\max} = 58 \pm 3 \mu\text{m}^2/\text{mA}$. Assuming $\beta = 0.3$ [16], $P_c = 0.5$, $g = 2$, $\mu_B = 9.3 \times 10^{-24} \text{ J T}^{-1}$, $\gamma = 1.76 \times 10^{11} \text{ Hz T}^{-1}$, and $A = 0.07 \pm 0.03 \text{ pJ/m}$ [32], we have $1/F_{\max} \approx 10\,000$ and $B_m \approx 0.25$ [33]. B_m can also be deduced from the number n of fingers observed in Figs. 3(b) and 3(c). Indeed, assuming n to remain constant after the onset of DW instability (occurring for $r = r_c$), the critical perturbation wavelength reads $\lambda = \pi r_c/n$, whose value was extracted from a statistical analysis, $\lambda = 3 \pm 1 \mu\text{m}$. The prediction for λ leads to $B_m = 0.36 \pm 0.06$, a value close to the previous estimation. Finally, B_m can also be estimated independently from micromagnetic parameters (see Ref. [32]) since $B_m = \mu_0 (2M)^2 h / (4\pi\sigma)$ with $\sigma = 4\sqrt{AK}$. The obtained Bond number equals 0.3 ± 0.1 and presents a good quantitative agreement with the two previous estimations. This unambiguously demonstrates that the domain wall fingering instability, observed for $j < 0$, originates from a competition between the dipolar interactions and the effect of the current gradient whose magnitude is shown to be proportional to the nonadiabatic contribution of the STT.

In conclusion, these results show that the domain wall orientation with respect to a current flow is very sensitive to current density gradients in current-induced DW motion experiments. They unveil some potential weaknesses for future devices relying on complex circuits where these gradients are ubiquitous, yet they also give us some interesting directions to propagate and manipulate DW over large surfaces, by taking advantage of the gradient-controlled stability.

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