



Levitated spinning graphene flakes in an electric quadrupole ion trap

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(Received 29 July 2010; revised manuscript received 26 August 2010; published 22 September 2010)

A method is described for levitating micron-sized few-layer graphene flakes in an electric quadrupole ion trap. Starting from a liquid suspension containing graphene, charged flakes are injected into the trap using the electrospray ionization technique and are probed optically. At micro-torr pressures, torques from circularly polarized light cause the levitated particles to rotate at frequencies >1 MHz, which can be inferred from modulation of light scattering off the rotating flake when an electric field resonant with the rotation rate is applied. Possible applications of these techniques will be presented, both to fundamental measurements of the mechanical and electronic properties of graphene and to new approaches to graphene crystal growth, modification, and manipulation.

DOI: [10.1103/PhysRevB.82.115441](https://doi.org/10.1103/PhysRevB.82.115441)

PACS number(s): 78.67.Wj, 42.50.Tx, 37.10.Ty, 81.05.ue

I. INTRODUCTION

Since its discovery in 2004,¹ graphene has received a tremendous amount of attention directed both toward understanding its fundamental properties and seeking applications for this new material.^{2–4} From the physics perspective, graphene is the first truly two-dimensional (2D) system, with electronic, mechanical, and thermodynamic properties all determined by the structure of a single sheet of carbon atoms. It seems likely that the revolutionary applications for graphene in the future will make use in some way of the unique properties of an intrinsically 2D system.

While graphene is an ideal 2D material, it nonetheless must be coupled to the outside world in real experiments and, in practice, attached to a three-dimensional (3D) substrate in some way. By now it is known that the substrate can limit mobility of graphene electrons,^{5–7} and consequently the recent experiments demonstrating the fractional quantum Hall effect in graphene^{8,9} were conducted on samples that were suspended (i.e., the substrate was etched away) in the region of measurement. Locally suspended samples were also used for the first measurements of the mechanical properties of graphene^{10,11} but it is probable that loss mechanisms and residual stresses in these experiments are determined by the substrate.¹² The thermodynamic measurements of graphene are perhaps most likely to be hindered by the presence of a substrate since the expected melting temperature of graphene is in excess of 3000 K, higher than that of any other material.

It is possible to avoid coupling to a substrate altogether if graphene is levitated using the particle trapping technologies that have been perfected in recent decades. Indeed, optical trapping of graphene suspended in solution has recently been demonstrated.¹³ Diamagnetic trapping is possible for graphite.¹⁴ For measurements of graphene, however, electric quadrupole (ion) trapping has several advantages: it is compatible with ultrahigh vacuum (UHV), low-, and high-temperature measurements; it can provide tight confinement of very small graphene particles; finally, ion trapping has the advantage that charged graphene flakes will tend to remain flat when levitated due to electrostatic repulsion. Interestingly, ion trap techniques have been applied previously to

graphite particles for studies of interstellar dust.^{15–18} Ion trapping of micron-sized particles has also been developed as a test bed for quantum information processing techniques^{19,20} and for materials studies of small particles.^{21,22}

Below, I describe a quadrupole trap optimized for graphene measurements and present preliminary data. Graphene flakes originally suspended in liquid are injected into the trap vacuum chamber using the electrospray ionization technique.²³ Trapped flakes are detected optically. The optical absorption and low mass of the flakes mean that the particles absorb angular momentum from circularly polarized light^{24,25} and begin to spin rapidly at low pressure ($p \cong 1$ μ torr). This spinning is directly demonstrated by the observation of rotational resonance—the modulation of optical scattering from the particle at a well-defined frequency of an applied electric field—at frequencies above 1 MHz. This high rotation frequency, facilitated by the ability of graphene to withstand centrifugal tension during rotation, is, to the author's knowledge, the largest ever measured for a macroscopic trapped object.^{17,24,26,27}

The experiment remains to be optimized, and all the data presented below are likely taken on multilayer flakes, rather than on single-layer graphene. Nonetheless, it is hoped that further refinements will enable levitation of single-layer graphene and that rotation resonance measurements will effectively capitalize on the powerful techniques of analysis developed for magnetic resonance and ultimately provide a wealth of information on the levitated sample and its internal properties.

I provide below a detailed description of the experimental design, including the development of many formulas necessary to understand the requirements for trapping graphene, the expected optical signal from the trapped sample, and the torques that will affect graphene motion in the trap. After a presentation of the data, I conclude with a consideration of possible improvements to the current design and a discussion of applications for graphene trapping, both for fundamental measurements and as a possible new environment for graphene crystal modification and growth.

II. DESCRIPTION OF THE QUADRUPOLE TRAP

At its simplest, a quadrupole trap is comprised of two or more electrodes in a configuration where the electric field

$E=0$ at some point $r=0$ in space away from the electrodes.^{28,29} If only dc potentials are applied to the electrodes then confinement of a charged particle at the point $r=0$ is always unstable but stable trapping is possible with ac applied fields under appropriate conditions. The equation of motion is

$$\ddot{\mathbf{r}} + \gamma_v \dot{\mathbf{r}} = \frac{q}{m} \cos(\Omega_t t) \mathbf{E}(\mathbf{r}), \quad (1)$$

where q is the particle charge, m is its mass, $\Omega_t/2\pi$ is the frequency of the trapping field, and dots above variables are used here and below to signify time derivatives. γ_v is the velocity damping rate, which will be extremely important for graphene flakes, due to their small mass (typically $\sim 10^{-18}$ kg for a micron-sized monolayer) and large surface area to mass ratio.

While it is possible to get exact results valid in the limit $r \rightarrow 0$ by linearizing Eq. (1),³⁰ a more intuitive picture of ion trap dynamics comes from the pseudopotential approximation.²⁹ In this approximation, the particle is assumed to be rapidly oscillating and experiences a spatially nearly uniform electric field during each oscillation period. The position of the particle is separated into an oscillatory “micromotion” δ and a position \mathbf{R} of the particle averaged over an oscillation period: $\mathbf{r} = \mathbf{R} + \delta$. Trapping occurs because in an oscillating nearly uniform electric field in the absence of damping, δ and $\ddot{\delta}$ (\propto force) are 180° out of phase: a particle in the neighborhood of $r=0$ will experience a force toward $r=0$ when it is furthest away from $r=0$ and away from $r=0$ when it is closest to it. If $E \rightarrow 0$ at $r=0$, then the force on the particle averaged over its micromotion will be directed toward $r=0$, leading to stable trapping. The effect of finite damping is to reduce the phase difference between δ and $\ddot{\delta}$, which will tend to reduce the average trapping force directed toward $r=0$.

The above arguments can be used to derive an equation of motion for the particle position averaged over the micromotion,^{16,29}

$$\ddot{\mathbf{R}} + \gamma_v \dot{\mathbf{R}} + \frac{q}{m} \nabla \Psi(\mathbf{R}) = 0, \quad (2)$$

where the pseudopotential, $\Psi(\mathbf{R})$, is

$$\Psi(\mathbf{R}) = \frac{1}{4} \frac{q}{m} \frac{1}{\Omega_t^2 + \gamma_v^2} E^2(\mathbf{R}). \quad (3)$$

From the formula for the pseudopotential, it is seen that a smaller Ω_t leads to greater confinement (provided the pseudopotential approximation remains valid), and that the confinement rapidly weakens when $\gamma_v > \Omega_t$.

The trap used in the experiments described below is similar the stylus trap developed for ions.³¹ It is a coaxial arrangement of two conically shaped pieces of stainless steel, the apex of which is shown in Fig. 1. The ac trap voltage is applied to the outer electrode while the inner electrode is kept near ground. Additionally, the chamber surrounding the trap (~ 2 cm away from the apex) is also grounded.

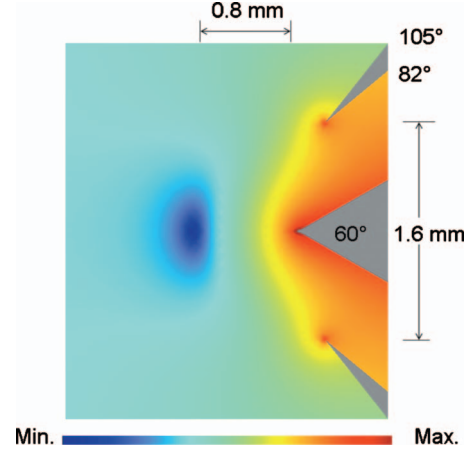


FIG. 1. (Color) Cross section of the apex of the trap electrodes (gray regions) and the surrounding pseudopotential. The trap is made from two coaxial pieces of conically tapered stainless steel. The oscillating trap voltage is applied to the outer electrode while the inner electrode is held near ground. The surrounding vacuum enclosure (not shown) is also grounded. The tip of the inner electrode extends beyond the face of the outer electrode by about 200 μm .

Calculated³² values of $E^2(\mathbf{R})$ are plotted, showing the pseudopotential minimum point about 0.8 mm away from the trap apex.

Along the axis of symmetry of the trap in the neighborhood of $r=0$, $E(\mathbf{r})$ may be approximated as

$$E_z = -\frac{z}{z_0^2} V_{\text{out}} \quad \text{and} \quad E_x = E_y = 0. \quad (4)$$

Here, V_{out} is the amplitude of the voltage applied to the outer electrode, and z_0 is a parameter determined from modeling the electrode configuration, and is 1.84 mm for the trap design depicted in Fig. 1. When $\gamma_v=0$, Eqs. (2)–(4) are readily solved to get oscillating solutions with

$$\omega_z = \frac{1}{\sqrt{2}} \frac{q}{m} \frac{V_{\text{out}}}{\Omega_t z_0^2}. \quad (5)$$

Similarly, for radial motion away from the axis of symmetry, oscillatory solutions can be obtained with $\omega_x = \omega_y = \omega_z/2$. These solutions are obviously only valid in the regime $\omega_z \ll \Omega_t$. However, the trap will remain stable when $\omega_z/\Omega_t < 0.32$.¹⁹

Nonzero biases applied to the *inner* electrode on the trap will produce an electric field at $r=0$ of $E_z = -V_{\text{in}}/z_1$, where $z_1 = 6.4$ mm is another parameter that can be determined by trap modeling.³² Nonzero V_{in} at dc shifts the trap minimum position along the z axis while V_{in} applied at finite frequencies can be used to determine ω_z (and thus q/m) by observing resonance behavior.

Quadrupole traps are usually designed to maximize confinement while maintaining stability. For atomic systems, this requires that $\Omega_t > 10^7$ s $^{-1}$, and excitation at this frequency is typically provided with a tuned resonator. For graphene particles charged using electrospray ionization, $q/m = 10\text{--}100$ C kg $^{-1}$ ($10^{-7}\text{--}10^{-6}$ $|e|$ amu $^{-1}$), much smaller

than the values for atomic ions. Consequently, the trap excitation is conveniently provided by a circuit³³ using a high-voltage op-amp.³⁴ This allows for a maximum voltage amplitude of 400 V at a maximum frequency of about 100 kHz. Using $V_{\text{out}}=300$ V, $\Omega_t/2\pi=30$ kHz (values typically used in these experiments), and $q/m=10$ C kg⁻¹ in Eq. (5) for the trap in Fig. 1, I obtain: $\omega_z=3300$ s⁻¹. Thus, the assumptions of the pseudopotential approximation are well satisfied during the experiments discussed below.

When a particle is confined by a quadrupole trap, fluctuations about the pseudopotential minimum will ultimately be determined by Brownian motion.¹³ Using the equipartition theorem,

$$\frac{1}{2}k_B T = \frac{1}{2}m\omega_z^2 \langle z^2 \rangle. \quad (6)$$

For temperature $T=300$ K and $m=10^{-18}$ kg, $\langle z^2 \rangle^{1/2}=20$ μm for the hypothetical particle discussed above. This dimension is small compared to the size of the trap, but it is readily measurable, and can be used to provide information about the trapped particle. Finally, the acceleration of gravity, g , will displace the particle from the trap center by a distance g/ω_x^2 , which is a few micron in this experiment and is generally not observable.

III. PARTICLE DAMPING

From very crude kinetic theory in the free molecular (Knudsen) regime, the velocity relaxation time of a particle, $1/\gamma_v$, is the time it takes to collide with its own mass of the gas molecules in its surroundings. For single-layer graphene, this time is just the time it would take for a monolayer of gas molecules to attach to the surface (if they all stuck and had a mass comparable to C atoms). The pressure-time product necessary to deposit a monolayer is known to surface scientists as the Langmuir unit= 10^{-6} torr s. Consequently, for a graphene monolayer $p/\gamma_v \cong 10^{-6}$ torr s. More refined kinetic theory³⁵ gives a very similar result for graphene in a N₂ ambient at 300 K. An important point is that for a 2D object such as graphene, the mass and collision cross section are proportional to one another so γ_v is independent of the lateral size of the graphene layer. However, The number of layers, n , will affect the mass but not cross section. Thus, measurement of p/γ_v can be used to determine n .

Using these ideas γ_v versus pressure is plotted in Fig. 2 for graphene for $n=1$ and $n=10$. As mentioned above, finite γ_v weakens the trapping pseudopotential in Eq. (3) unless $\gamma_v < \Omega_t$. For the trap parameter $\Omega_t=200\,000$ s⁻¹, this requirement means that the trap can only operate at pressure below 1 torr. On the other hand, finite γ_v is necessary, since—without a drag force—particles could never become bound in the trap. Consequently, the experiments discussed below are conducted by trapping the particles at around 0.5 torr and subsequently pumping the system down to 10^{-3} – 10^{-6} torr for most measurements.

While the picture above is adequate to motivate the design of this experiment, it is worth noting that many of the assumptions underlying simple kinetic theory may be unwarranted for a 2D object in the Knudsen regime. For spherical

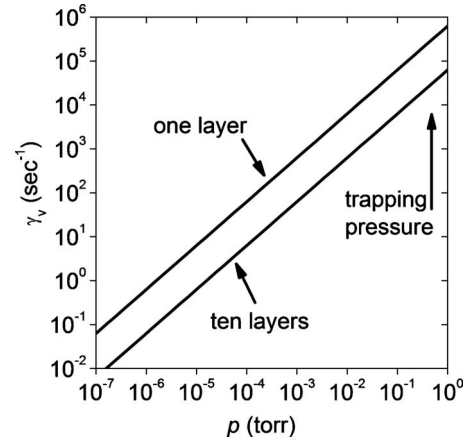


FIG. 2. Predicted velocity relaxation rate, γ_v , of graphene as a function of pressure.

objects the values of γ_v determined assuming purely specular and purely diffuse scattering of molecules off the surface differ by only about 15%.³⁵ However, for a 2D plate moving in a direction parallel to its surface, molecules specularly reflected off the surface do not transfer momentum to the plate in the direction of its motion, and thus would not contribute to γ_v . (Purely specular scattering would also not contribute to γ_ω the angular velocity relaxation rate for a plate rotating on an axis perpendicular to the plate.) The relative contributions of diffuse and specular scattering off graphene is unknown but it is notable that crystalline surfaces with a high degree of perfection are being developed as “atom mirrors” in which the ratio of specular to diffuse scattering is significant.³⁶

IV. GENERATION OF CHARGED FLAKES BY ELECTROSPRAY IONIZATION

Graphene flakes are introduced into the trap using the electrospray ionization technique. Originally developed for mass spectrometry,²³ electrospray has also been applied to inject micron-scale charged particles into quadrupole ion traps.^{19–21} In the electrospray technique, a liquid suspension containing the particles is ejected from a capillary tube held at high voltage. Ejected droplets shrink in size due to a combination of liquid evaporation and droplet fission, until only dry charged particles remain suspended in the chamber gas. The large voltages required for electrospray mean that it is most easily performed at or near atmospheric pressure, with charged particles subsequently introduced into a higher vacuum environment through a pinhole orifice located near the electrospray emitter tip.

The suspensions used in these experiments are similar to those developed by Hernandez *et al.*^{37,38} These workers prepared suspensions by ultrasonication of graphite flakes in a variety of liquids. The resulting mixture was then centrifuged to deposit coarse material while finer particles remained suspended. The particles that remain in suspension were shown to be micron-scale flakes of few-layer graphene, with n typically in the range 1–10.

In order to use these suspensions for electrospray, it is extremely important to minimize nonvolatile impurities in the liquid since these impurities will accumulate on the graphene flake during liquid evaporation, and can ultimately outweigh the residual graphene if care is not taken. While many liquids are effective for graphene suspensions,³⁷ I have chosen to use an isopropyl alcohol (IPA)-water mixture (3:1 volume ratio) since IPA and water are commonly used in mass spectrometry and are available in “MS grade” (low in ionic contaminants and <1 ppm residue after evaporation).³⁹ Care must also be taken to ensure that only clean and inert materials are brought into contact with the suspension and that it is not contaminated with foreign particulates. For these reasons I give a rather detailed description below of the materials and techniques used to prepare and deliver the suspension to the emitter tip.

The suspensions are prepared in 8 mL glass vials with polytetrafluoroethylene (PTFE)-faced phenolic caps (VWR #14230-824). After the vials are rinsed in IPA, 5 mg of graphite flake (Aldrich #332461) are weighed and introduced into the vial. 5 mL of liquid is then added and the cap is closed. The vial is then placed in an ultrasonic bath (Branson #1510) in a position so that the fluid level in the bath matches that inside the vial, and the sample is ultrasonicated for 30 min. All operations where the suspension is exposed to air are performed in a clean room.

After ultrasonication, the vial is centrifuged (Drucker #642E, approximate acceleration=1000 g) for 30 min. After centrifugation the supernatant has a typical optical attenuation coefficient (measured at 532 nm) of 80 m^{-1} . Using the attenuation dependence on concentration determined by Hernandez³⁷ of $2500 \text{ L m}^{-1} \text{ g}^{-1}$, the typical concentration of graphene flakes in the suspension is about 30 mg L^{-1} .

The supernatant is drawn through a syringe needle (Hamilton #90122) into a glass syringe (Hamilton #1750, 0.5 mL volume, with PTFE luer lock connection), which is placed into a syringe pump (Harvard Apparatus, Nanomite) located at the top of the quadrupole trap vertical column (Fig. 3). Upon exiting the syringe the suspension travels through PEEK 1.6 mm diameter tubing and fittings to the stainless steel electrospray emitter (New Objective Corporation, $100 \mu\text{m}$ tip inner diameter). The metal tip is connected to a wire that allows it to be biased at high voltages.

During operation the emitter tip is surrounded by N_2 at atmospheric pressure and is about 6 mm above a $25 \mu\text{m}$ diameter grounded stainless steel pinhole aperture (Edmund Optics). Because contamination may arise from particles in the gas surrounding the emitter tip that come into contact with exiting charged droplets, the N_2 is filtered (Swagelok, SCF Series, $0.003 \mu\text{m}$) prior to entering the chamber surrounding the tip. The chamber walls are made of glass so electrospray emission is visible when the tip is illuminated with a laser pointer. Onset of electrospray emission typically occurs at $V_{\text{tip}} \cong \pm 2 \text{ kV}$, with optimal performance around 3 kV. Optimal flow rates during electrospray are typically $1\text{--}3 \mu\text{L min}^{-1}$. During particle trapping, a roughing pump evacuates the chamber downstream from the pinhole to about 0.5 torr. After a particle is trapped, a gate valve between the electrospray source and the main chamber is closed (Fig. 3), allowing the chamber to be pumped with a

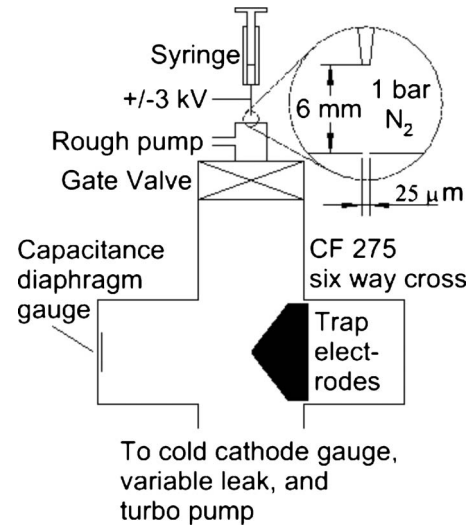


FIG. 3. Diagram showing the particle injection system and the gas handling of the experimental apparatus. The minimum obtainable pressure in the chamber is $\leq 1 \mu\text{torr}$.

turbo pump to below 10^{-6} torr. For measurement of pressures $>10^{-4}$ torr, a capacitance diaphragm gauge and a convection gauge located close to the trap center are used. A cold cathode ionization gauge is located downstream from the trap to measure lower pressures. Close proximity between the trap center and the ionization gauge was avoided to prevent possible discharging of trapped particles, and consequently there is considerable uncertainty in the pressure measurements below $p < 10^{-4}$ torr. Finally, a N_2 variable leak is located downstream from the ionization gauge to enable control of the chamber pressure.

V. OPTICAL APPARATUS

During and subsequent to trapping, particles are imaged from light scattered at small angles from the direction of an illuminating laser (Fig. 4). The light source is a $\lambda = 532 \text{ nm}$ wavelength laser (Lasermate Corp.) with adjustable output power. Laser power is leveled during measurements by using a photodiode and a proportional-integral-derivative controller. Power flux at the center of the beam is determined by scanning the laser across a (nongraphitic) trapped particle and fitting the scattered intensity to a Gaussian. The power flux calculated in this way is $3300 \text{ W m}^{-2} \text{ mW}^{-1}$.

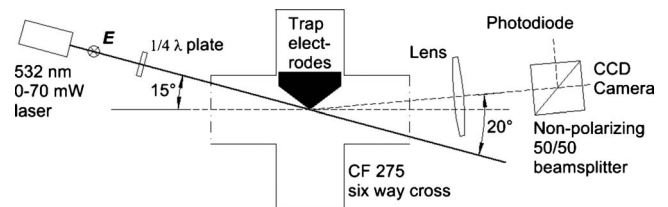


FIG. 4. Diagram of optical instrumentation for the experiments. The electric field of the light originating from the laser points out of the diagram. Light received at the detectors on average has scattered 20° from the incident beam direction.

Care must be taken to avoid light scattering into the collection optics that could wash out the signal. For this reason, coated windows (Lesker VPZL-450AR) are used for the optical entrance and exit to the trap chamber. Additionally, the trap outer electrode is conically tapered to minimize scatter from corners and edges. Also, laser line filter is placed in the collection optics to minimize interference from ambient light.

The collection optics consists of two 40 mm diameter lenses located outside the trap vacuum chamber, 120 mm away from the trap center, with magnification factor of 4.2. A beam splitter is used so that trapped particles may be simultaneously viewed by both a low light level charge coupled device video camera (WATEC 120N) and a low noise photodiode (FEMTO FWPR-20-SI) with a 20 Hz bandwidth. A 500 μm diameter pinhole aperture is positioned in the focal plane in front of the photodiode to minimize the contribution of background light to the detected signal coming from trapped objects. Finally, a 1/4 wave plate on a rotation stage allows for control of the light polarization illuminating the trapped particle.

VI. INTERACTION OF GRAPHENE WITH ELECTRIC FIELDS

The graphene samples studied in this experiment are irregularly shaped flakes whose size will in general not be small in comparison to the 532 nm laser wavelength. However, to get a rough idea of the expected signal from scattered light, I will estimate the interactions of a graphene flake with an applied electric field in the quasistatic dipole approximation. In this approximation, the dipole moment, $\mathbf{p} = \epsilon_0 \alpha \mathbf{E}$, is estimated from the polarization induced by a uniform electric field. α is the polarizability tensor, and ϵ_0 is the permittivity of vacuum. Analytically tractable results for a circular disk may be derived by determining the polarizability of an oblate spheroid⁴⁰ with semimajor axis, a , and allowing the semiminor axis, b , to go to zero. Inside the spheroid, the complex permittivity is

$$\epsilon = \epsilon_0 + \frac{\sigma_{3D} i}{\omega}, \quad (7)$$

where σ_{3D} is the volume conductivity of the material and ω is the angular frequency of the applied field. For an oblate spheroid, α_{\parallel} , the response to an electric field oriented in the plane of rotational symmetry, E_{\parallel} , is

$$\alpha_{\parallel} = \frac{4}{3} \pi a^2 b \frac{\frac{\sigma_{3D} i}{\epsilon_0 \omega}}{1 + \beta \frac{\sigma_{3D} i}{\epsilon_0 \omega}}, \quad (8)$$

where β is a geometrical factor $\cong \pi b / (4a)$ for $b \ll a$.⁴⁰ To obtain an expression for a disk, I equate σ_{2D} with the product of σ_{3D} and $4b/3$, the mean thickness of the spheroid in the direction of its axis of symmetry averaged over its cross section. The result is

$$\alpha_{\parallel} = \pi a^3 \frac{\left[\frac{\sigma_{2D}}{\epsilon_0 \omega a} \right] i}{1 + \frac{3\pi}{16} \left[\frac{\sigma_{2D}}{\epsilon_0 \omega a} \right] i}. \quad (9)$$

A. Optical scattering and absorption

At optical frequencies it is now well established experimentally^{41,42} that $\sigma_{2D} \cong e^2 / 4\hbar$ for monolayer graphene. Using this value and $\omega = \omega_L = 3.54 \times 10^{15} \text{ s}^{-1}$ (for $\lambda = 532 \text{ nm}$) yields a value of 4×10^{-3} for the term in brackets in Eq. (9) with $a = 0.5 \mu\text{m}$. Thus, at optical frequencies for micron-scale flakes with one or a few layers,

$$\alpha_{\parallel} \cong i \pi a^2 \frac{\sigma_{2D}}{\epsilon_0 \omega_L}. \quad (10)$$

This value will scale linearly with n , the number of layers in a flake, provided n is small. Using this approximation, the optical absorption cross section, σ_{abs} , of a flake oriented perpendicular to the incident radiation is⁴⁰

$$\sigma_{abs} = \frac{2\pi}{\lambda} \text{Im}[\alpha_{\parallel}] = n \pi a^2 \times \frac{e^2}{4\epsilon_0 \hbar c} \cong 0.023 \times n \pi a^2. \quad (11)$$

This picture predicts that a graphene monolayer absorbs 2.3% of the light impinging on its area, in agreement with experiments.⁴¹ This absorption has significant implications for optical measurements since sample heating can be large in a high-vacuum environment at laser powers above a milliwatt (Fig. 5).

To determine the visibility of a flake, I next calculate the forward scattering differential (per solid angle Ω) cross section of a flake oriented perpendicular to the incoming radiation using the same assumptions,⁴⁰

$$\left(\frac{d\sigma}{d\Omega} \right) [\theta = 0] = \left(\frac{1}{4\pi} \right)^2 \left(\frac{2\pi}{\lambda} \right)^4 |\alpha_{\parallel}|^2 \cong \left(\frac{0.023 \times n \pi a^2}{2\lambda} \right)^2. \quad (12)$$

The quantity $n \pi a^2$ is proportional to the mass of the flake. The result of Eq. (12) is plotted in Fig. 6 as a function of particle mass using typical experimental parameters. These calculations show that a single layer of graphene with a $1 \mu\text{m} \times 1 \mu\text{m}$ area should be visible in the experiments. It is important to note, however, that visible objects will not conform to the condition that $a \ll \lambda$. This, combined with the fact that flakes will be irregular in shape (and possibly contain regions with different layer thickness), means that these results are at best rough estimates of the expected optical scattering from trapped flakes.

B. Optical anisotropy

The results above were all derived for a flake in a plane oriented perpendicular to the direction of the incoming radiation, when \mathbf{E} always lies in the plane of the flake. Because of the thinness of graphene (and the anisotropy of graphite in

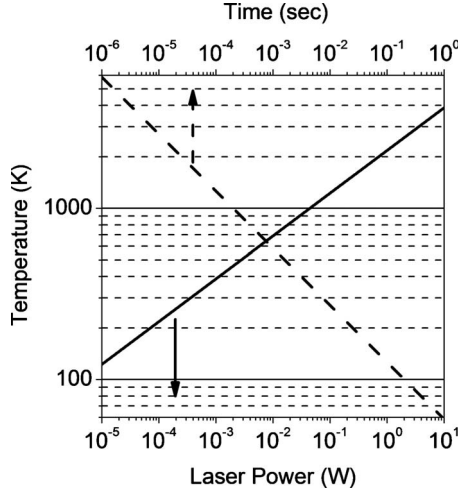


FIG. 5. Predicted temperature of a graphene single layer in vacuum. Solid line is versus laser power while dashed line is versus time after the heating source is turned off and the sample is cooling from a very high initial temperature. Heat is assumed to be removed from the flake by black body radiation into a surrounding environment at $T=0$, and the heat capacity is assumed to be $3k_B$ per C atom. The laser beam diameter is 0.5 mm, and 2.3% absorptivity and emissivity are assumed. Size effects and temperature dependence of the heat capacity have been neglected and will become increasingly important at low temperature.

general), $\alpha_{\parallel} \gg \alpha_{\perp} \approx 0$. Consequently the optical response of trapped graphene should vary with time if the flake orientation changes with respect to the incident radiation. If the flake is randomly oriented in linear polarized light (LPL),

$$\left(\frac{d\sigma}{d\Omega}\right)_{\text{LPL}}^{\text{mean}} = \frac{2}{3} \left(\frac{d\sigma}{d\Omega}\right)_{\text{LPL}}^{\text{max}} \quad \text{and} \quad \left(\frac{d\sigma}{d\Omega}\right)_{\text{LPL}}^{\text{min}} = 0. \quad (13)$$

The maximum value is that determined from Eq. (12), and will be the same for linear or circular polarized incident light. Because circular polarized light (CPL) effectively averages over orientation around the direction of incident radiation,

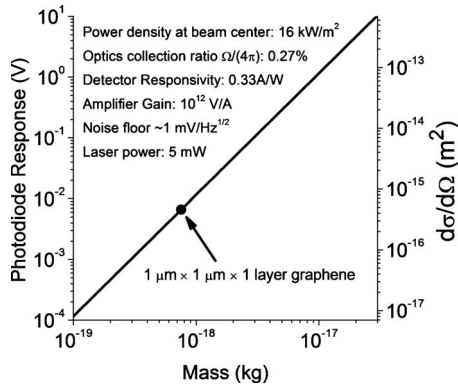


FIG. 6. Predicted optical signal and forward scattering cross section for graphene as a function of its size. Finite-size corrections to dipole scattering are neglected.

$$\left(\frac{d\sigma}{d\Omega}\right)_{\text{CPL}}^{\text{mean}} = \frac{2}{3} \left(\frac{d\sigma}{d\Omega}\right)_{\text{CPL}}^{\text{max}} \quad \text{and} \quad \left(\frac{d\sigma}{d\Omega}\right)_{\text{CPL}}^{\text{min}} = \frac{1}{2} \left(\frac{d\sigma}{d\Omega}\right)_{\text{CPL}}^{\text{max}}. \quad (14)$$

These equations predict that temporal fluctuations should approach 100% in LPL and 50% in CPL. The slow (20 Hz) response of the photodiode in the experiments means that these fluctuations will be averaged out at high pressures, however.

C. Optical torque

Because electromagnetic waves carry angular momentum as well as energy, absorption of light [Eq. (11)] must also convey torque, $N = \mathbf{p} \times \mathbf{E}$, to the particle if the incoming radiation is circularly polarized,

$$N_{\perp} = I_{\perp} \dot{\omega}_{\perp} = \pm \frac{S}{\omega_L} \times 0.023 \times n \pi a^2, \quad (15)$$

where S is the incoming radiation power flux. N_{\perp} , ω_{\perp} , and I_{\perp} are, respectively, the torque, angular velocity, and moment of inertia associated with motion around an axis perpendicular to the plane of the flake, which is assumed to be oriented perpendicular to the direction of incident radiation. For a circular flake with uniform density: $I_{\perp} = ma^2/2 = \pi a^4 \rho_{2D}/2$, where ρ_{2D} is the 2D mass density of single-layer graphene $= 7.6 \times 10^{-7} \text{ kg m}^{-2}$. Thus

$$\dot{\omega}_{\perp} \cong \pm \frac{S}{\omega_L} \times 0.023 \times \frac{2}{a^2 \rho_{2D}}. \quad (16)$$

Note that since both torque and mass are linearly dependent on n , n does not appear in this formula. For 5 mW laser power and $a \cong 0.5 \text{ } \mu\text{m}$, $\dot{\omega}_{\perp} = 1.1 \times 10^6 \text{ s}^{-2}$. In circularly polarized light, the angular rotation velocity of a graphene flake will increase until the optical torque is matched by frictional drag at $\omega_{\text{max}} = \dot{\omega}_{\perp} / \gamma_{\omega}$. This result implies that at low pressures, when $\gamma_{\omega} \leq 1 \text{ s}^{-1}$, rotational frequencies above 1 MHz are possible. The *thermal* rotational angular velocity is given by

$$\frac{1}{2} k_B T = \frac{1}{2} I \omega^2, \quad (17)$$

which, for a $1 \text{ } \mu\text{m}$ diameter single-layer graphene flake at 300 K, leads to $\omega = 2 \times 10^5 \text{ s}^{-1}$. Thus, at low pressures, light-induced rotation will exceed thermal rotation of the graphene flakes.

D. Low-frequency torques

At frequencies $\leq 1 \text{ GHz}$, the bracketed term in Eq. (9) $\gg 1$ and

$$\alpha_{\parallel} \cong \frac{16}{3} a^3 \left(1 + \frac{16}{3\pi} \left[\frac{\epsilon_0 \omega a}{\sigma_{2D}} \right] i \right). \quad (18)$$

The real part of this expression is simply the static electric polarizability of a thin disk of radius a .⁴³ This term produces a torque along an axis in the plane of the flake when \mathbf{E} is at an angle θ from the flake plane,

$$N_{\parallel} = E_{\perp} \epsilon_0 \alpha_{\parallel} E_{\parallel} = \frac{16}{3} \epsilon_0 a^3 E^2 \sin \theta \cos \theta = I_{\parallel} \dot{\omega}_{\parallel}. \quad (19)$$

For 2D objects the moments of inertia have the property: $I_{\parallel 1} + I_{\parallel 2} = I_{\perp}$, and for a circular uniform disk: $I_{\parallel} = ma^2/4$. Thus, for a disk,

$$\dot{\omega}_{\parallel} = \frac{64}{3} \frac{a}{m} \epsilon_0 E^2 \sin \theta \cos \theta. \quad (20)$$

Typical low-frequency electric fields that can be conveniently applied in the trap (by applying a voltage to the *inner* electrode) are $\sim 1000 \text{ V m}^{-1}$. This value is comparable to the electric field that the particle experiences due to thermal motion away from the trap minimum. For $a = 0.5 \text{ }\mu\text{m}$ and $m = 10^{-18} \text{ kg}$, $\dot{\omega}_{\parallel}$ is at most $5 \times 10^7 \text{ s}^{-2}$, a value that can be considerably larger than the value for the angular acceleration from optical fields calculated above.

Finally, the imaginary term in Eq. (18) leads to a braking effect since dissipation occurs when charge moves on the spinning flake to shield external electric fields oriented in the flake plane. For a circular disk,

$$\gamma_{\omega}(E_{\parallel}) = \dot{\omega}_{\perp} / \omega_{\perp} = \frac{512}{9\pi} \frac{a^2}{m \sigma_{2D}} \epsilon_0^2 E_{\parallel}^2. \quad (21)$$

At low frequencies, it is inappropriate to use the optical value for σ_{2D} since the conductivity will depend on the number of carriers in the flake (and possibly on quantum size effects in a mesoscopic system). However, to obtain an order of magnitude estimate of the braking rate, I use $\sigma_{2D} = e^2/4\hbar$, $a = 0.5 \text{ }\mu\text{m}$, $m = 10^{-18} \text{ kg}$, and $E = 1000 \text{ V m}^{-1}$ to get $\gamma_{\omega}(E_{\parallel}) \cong 10^{-5} \text{ s}^{-1}$. From a perusal of Fig. 2 it is seen that $\gamma_{\omega}(E_{\parallel})$ is negligible compared to damping from background gas (assuming $\gamma_b \cong \gamma_{\omega}$) for the conditions of this experiment. However, damping either from applied electric fields or those experienced during thermal motion could become dominant at pressures $< 10^{-10} \text{ torr}$.

VII. MEASUREMENTS

While the graphene suspensions described above are stable for weeks, for these experiments they are typically prepared within 24 h of their use. After the syringe containing the suspension is placed on the trap column, high voltage is applied to the tip, and the gas surrounding it is purged with filtered N_2 for several minutes. The gate valve is then opened to the trap chamber and liquid flow is initiated out of the electrospray tip by activating the syringe pump. Once electrospray emission is initiated, particles are observable with the video camera (typically $0.1\text{--}1 \text{ s}^{-1}$), and pressure in the trap chamber increases. The 500 mtorr pressure in the chamber used during trapping will decrease, along with collection efficiency, as the pinhole becomes contaminated during operation.

Trapping of particles passing near the trap is facilitated by applying a dc bias (typically $\pm 2 \text{ V}$) to the inner electrode that draws the trap minimum toward the electrodes (Fig. 7). Once a particle is caught, the gate valve is closed; the dc bias can be removed; and the chamber can be pumped to lower



FIG. 7. Photo of the trap with a confined visible graphene flake. The particle is on the left while scattering from the faces of the electrodes is visible on the right.

pressures with the turbo pump. Trapped graphene flakes are highly sensitive to light: at high pressures (when they are trapped) this can be seen in “fluttering” (irregular motion) that increases with laser power; at lower pressures ($\leq 10 \text{ mtorr}$) particles can rapidly discharge (and leave the trap) when the laser power significantly exceeds 10 mW. These effects are consistent with heating of the flakes by absorbed light. Discharging at high light levels occurs at a similar rate for both negatively and positively charged trapped flakes, suggesting that thermionic emission is not the operative mechanism. Most likely ionic species are present on the flake surface of both polarities and volatilize at high temperatures to discharge the flake.

At the lowest obtainable pressures ($p < 0.1\text{--}1 \text{ }\mu\text{torr}$), damping is extremely inefficient, and particles are frequently expelled from the trap, most likely from electrical or acoustic noise coupling to the resonant frequency of motion of the trapped flake. At higher pressures and at low light levels, particles can remain in the trap for weeks.

During pumping to low pressures, the optical signal coming from scattering from the flake is monitored with the photodiode. Strong fluctuations in time appear typically at $p < 10 \text{ mtorr}$ for graphene flake samples [Fig. 8(a)]. These fluctuations are largest in magnitude when the sample is viewed with LPL. Such fluctuations do not appear when non-graphitic dust particles are trapped. Of the particles that do display fluctuations, greater than half of them display virtually 100% signal modulation in LPL at $p < 0.1 \text{ mTorr}$. Only these ($\sim 100\%$ modulating) are chosen for more detailed study. It should be emphasized at the outset that this criterion does not mean that the graphene flakes are single layer since even multilayer flakes are still optically very thin, and should display a large anisotropy. It is unlikely, however, that crumpled balls or wads of graphene would display large anisotropy, and consequently the measurements discussed below are taken on thin, flat flakes.

Data for such a flake at $p < 10^{-5} \text{ torr}$ is shown in Fig. 8(b). When pumped down while viewing in LPL, the fluctuations evident at higher pressures increase to 100% of the photodiode signal. If the sample is then illuminated with CPL, the fluctuations almost completely disappear, and the signal approaches a nearly constant, equilibrated value. If the illumination subsequently is switched back to LPL, quasiperiodic behavior is observed: the characteristic frequency of the fluctuations increases with time until they exceed the

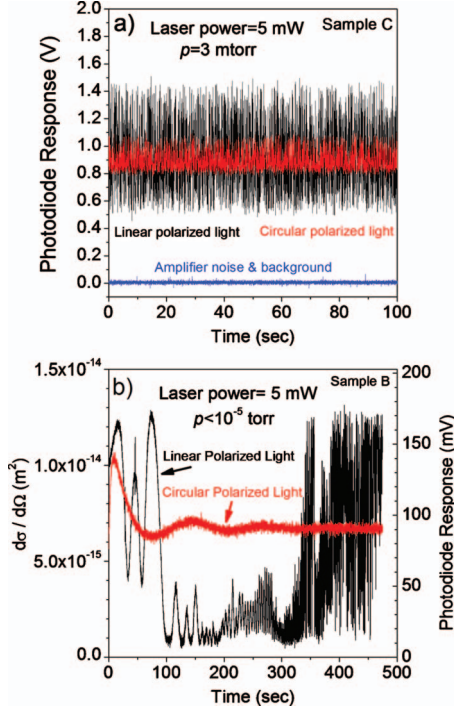


FIG. 8. (Color) (a) Light scattering from a graphene flake at a pressure near the onset of the appearance of fluctuations. At higher pressure, the scattered light signal becomes uniform. (b) Behavior of a flake at low pressure. For the circular polarized light measurement, the laser is turned on at $t=0$ after being off for an extended period. Data is taken for linear polarized light after switching away from a long exposure to circular polarized light at $t=0$. The minimum signal observed using linear polarized light is limited by instrumental noise.

measurement bandwidth of the photodiode, at which time large-amplitude random fluctuations are again observed.

The likely interpretation of this behavior is that rotation of the flake is induced by CPL, which stabilizes its orientation relative to the direction of incident radiation. The quasiperiodic behavior observed when the illumination is switched to LPL is a consequence of the gradual slowing of this rotation

due to friction with the residual gas in the trap chamber. Periodic behavior can occur if there are torques on the flake along an axis in the flake plane, which can come from electric fields, as was discussed above. These torques would cause the axis of rotation of the flake to precess with angular velocity $\sim \dot{\omega}_{\parallel} / \omega_g(t)$. The precession frequency increases as the angular velocity of the graphene flake, ω_g , slows down, just as the wobbling frequency of a top increases as it spins down.

It has been shown under general circumstances²⁵ that the axis of symmetry of small, absorbing, oblate spheroid will tend to align with the direction of incident radiation when illuminated with CPL. The plane of the flake is thus presumably oriented perpendicular to the incident radiation when the particle has reached its steady-state value when illuminated with CPL. The theory above predicts that the scattered light intensity should be maximal in this orientation since the electric field is always in the plane of the flake. The data in Fig. 8(b) clearly show, however, that peak scattering occurs under LPL illumination and substantially exceeds the scattering from the flake after it has been illuminated by CPL for a long period. This discrepancy is likely an indication that the flake is not in fact significantly smaller than a wavelength. A flake in the mirror configuration, where the angle of incidence is equal to the angle of scattering and where the electric field lies in the flake plane, should presumably scatter with peak intensity for a large flake. It is likely that this is the orientation of the flake when the signal is maximal under LPL illumination.

The characteristics of five samples that showed rotating behavior at low pressures are listed in Table I. q/m is determined by observing motional resonance (typically at 1–10 mtorr) and using Eq. (5) with the known trap parameters. $(\frac{d\sigma}{d\Omega})_{\text{LPL}}^{\text{max}}$ is the peak signal scattered from the sample in LPL, and $(\frac{d\sigma}{d\Omega})_{\text{CPL}}^{\text{equil}}$ is the signal from the sample after it has been illuminated with CPL for an extended period. Both of these optical measurements are made at $p < 10^{-5}$ μtorr . Because it is likely to be least sensitive to size effects, $(\frac{d\sigma}{d\Omega})_{\text{LPL}}^{\text{max}}$ is used to determine the “optical” mass using Eq. (12), and q is then determined from the optical mass.

It is also possible to estimate the mass by observing Brownian motion (also typically at 1–10 mtorr) and using

TABLE I. Characteristics of five flake samples. V_{tip} is the voltage applied during electrospray ionization and determines the sign of the charge of the trapped particle. Optical mass is that inferred from Eq. (12) and Fig. 6. The rotation resonance measurements were performed on sample E.

Parameter	Units	A	B	C	D	E
V_{tip}	kV	-2	-2.2	2.8	2.8	3.1
$\Omega_t / 2\pi$	kHz	35	30	20	30	20
q/m	C kg ⁻¹	-121	-48	16	30	14
$(\frac{d\sigma}{d\Omega})_{\text{LPL}}^{\text{max}}$	10 ⁻¹⁵ m ²	5.5	12	160	100	460
$(\frac{d\sigma}{d\Omega})_{\text{CPL}}^{\text{equil}}$	10 ⁻¹⁵ m ²	3.3	6.5	75	50	210
Optical m	10 ⁻¹⁸ kg	2.6	3.9	14	11	24
Inferred q	$ e $	-1970	-1170	1400	2060	2100
γ_ω	s ⁻¹	0.02	0.012	0.003	0.01	0.09
p	μtorr	0.6	1.0	0.3	0.6	1.5
p / γ_ω	$\mu\text{torr s}$	30	80	100	60	17

Eq. (6). This technique gives results 3–10 times smaller than the optical mass. Systematic errors can easily enter this measurement, however: T for the flake under illumination is not known accurately. Also, electronic and acoustic noise can contribute to the observed fluctuations and cause the mass to be underestimated.

Perhaps the most surprising aspect of the data is the extremely long times it takes for the sample to equilibrate at low pressures. The rotational damping rates γ_ω listed in Table I are estimated from the changing frequency of the quasiperiodic oscillations observed during spin down in LPL, assuming that the torque that is causing precession is constant. The pressure reading on the ionization gauge downstream from the trap was between 0.3 and 1.5 μtorr during these measurements. The resultant values for p/γ_ω are large and suggest that the samples all contain many layers if the simple kinetic picture of damping presented above is correct and if $\gamma_\omega \sim \gamma_v$. The pressure measurement in the experiment is certainly inadequate but to bring the data into line with theory for a monolayer flake, the pressure in the chamber would need to be *lower* than the gauge value, which would be surprising. (The cold cathode gauge reading is closely matched to the capacitance diaphragm gauge, very near to the trap center, when they are both in range.)

VIII. OBSERVATION OF ROTATIONAL RESONANCE AT MHz FREQUENCIES

The data presented above provides strong indirect evidence that flake spinning is induced by exposure to CPL. The long measured values of γ_ω —combined with the estimates of optical torque for grapheme—suggest that the rotation frequency is in the megahertz (MHz) range in the experiments. Direct optical observation of this spinning using fast optical detectors is a challenge due to the small (femtowatt) signals scattering off the flakes. An alternative is to excite the flakes at high frequencies and seek to observe changes in the optical signal measured at low frequencies. In particular, a sample can be exposed to high-frequency electric fields by applying a voltage to the *inner* electrode of the trap. At MHz frequencies, these fields have a negligible effect on the position of the trapped flake but do produce torques on the sample as was discussed above.

To perform this experiment a sample was illuminated with CPL at $p < 10 \mu\text{torr}$. An 8 V amplitude ac signal was applied to the inner electrode, corresponding to a peak E at the trap center of 1250 V m^{-1} . The frequency was ramped logarithmically while the optical scattering signal was monitored (Fig. 9). The data clearly show sharp jumps in the photodiode signal, occurring both when the frequency is scanned upward and downward. The jumps are not uniform in size, however. Note also that the direction of the jump (toward brightening or dimming) is not always the same for a given direction of the frequency sweep.

The rotation resonance jumps show clear dependence on the pressure in the trap: the magnitude of the jumps decreases markedly at low pressure, and the frequency at which the jumps occur is roughly inversely proportional to the pressure (Fig. 10). The scatter in the frequency associated with

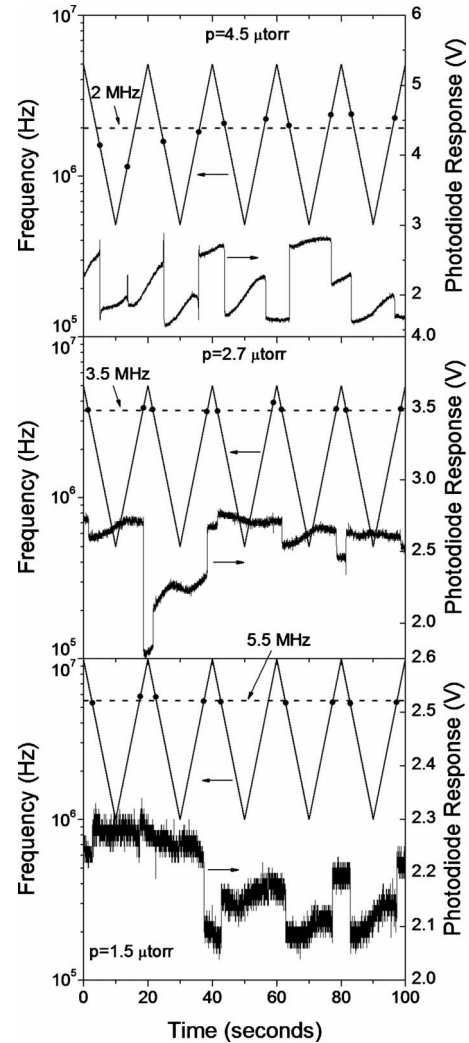


FIG. 9. Observation of rotational resonance of a graphene flake. The light scattering off of the spinning flake measured by the photodiode is plotted as a function of time while the triangle wave modulation of the frequency of the applied electric field is superposed. Jumps in the photodiode response occur near particular frequencies of the applied field (dots), and the average value of the frequency where these jumps occur (horizontal dashed lines) is sensitive to chamber pressure. For all of the data, the sample is exposed to 4 mW circular polarized light during the measurements.

the jumps is increasing at high pressures, probably an indication that random or thermal fluctuations in the rotation and orientation of the flake are becoming significant. Subsequent to these resonance measurements, the bias applied to the inner electrode was switched off, and γ_ω was determined using observation of the spin-down behavior in linear polarized light (Fig. 11).

The fact that signal intensity changes abruptly strongly suggests that the axis of orientation of the flake (or its average orientation) is shifted by a resonant interaction with the applied torque. While it is tempting to treat this as a problem of rigid body dynamics, a better approximation for graphene is to examine the dynamics of a thin membrane with no rigidity whatsoever under tension purely from centrifugal forces. This problem was treated by Lamb and Southwell⁴⁴

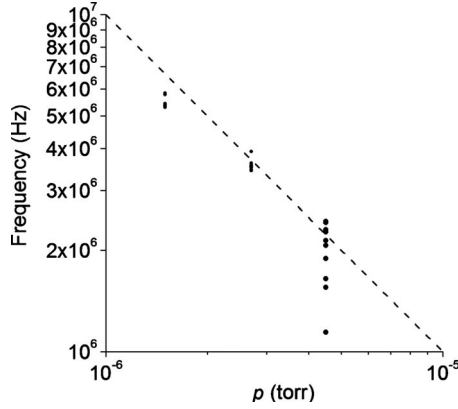


FIG. 10. Effect of chamber pressure on the frequency at which rotation resonance jumps occur.

for the case of a circular membrane. For the lowest frequency transverse vibrations of a circular membrane rotating with angular velocity ω , the membrane remains planar but

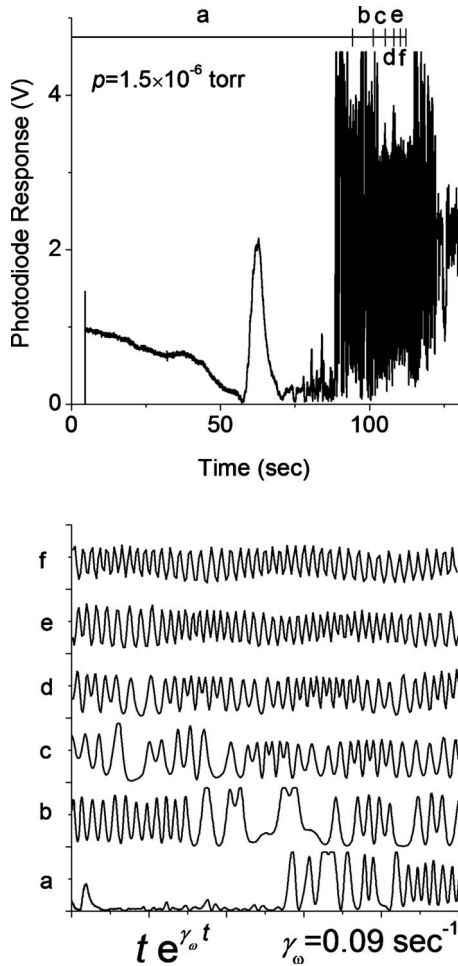


FIG. 11. Spin-down behavior measured subsequent to observation of rotational resonance of the flake observed with 4 mW of linear polarized light. Previous to $t=0$, the flake had been exposed to 4 mW of circular polarized light for a long period. To facilitate the observation of the quasiperiodic oscillations, the time axis is exponentially expanded in the bottom plot.

the axis perpendicular to the membrane plane precesses at angular velocity $\pm\omega$ when observed in a corotating frame. In a nonrotating frame, these excitations correspond to a dc tilt of the axis of the membrane plane and fast precession at 2ω of the membrane orientation. This latter motion can presumably be excited by an external torque applied at angular frequency 2ω .

For *rigid* 2D plates of arbitrary shape (where $I_{\parallel 1} + I_{\parallel 2} = I_{\perp}$), small deviations of the instantaneous axis of rotation from the principal axis perpendicular to the plate precess at angular velocity,⁴⁵

$$\omega \sqrt{\frac{(I_{\perp} - I_{\parallel 1})(I_{\perp} - I_{\parallel 2})}{I_{\parallel 1} I_{\parallel 2}}} = \pm \omega \quad (22)$$

in the corotating frame of reference, just as was the case for the spinning circular membrane. It is likely then that under very general conditions, rotating 2D objects are susceptible to transverse excitation at angular frequency 2ω .

Equating the observed resonance frequency in the data with twice the rotation frequency of the flake, ω_g/π , allows for the estimation of the flake dimensions: γ_ω may be estimated from the data in Fig. 11. Combining these values (both measured at $1.5 \mu\text{torr}$) allows for the determination of $\dot{\omega}_{\perp} = \omega_g \gamma_\omega = 1.7 \times 10^6 \text{ s}^{-2}$. Equation (16) can then be used to evaluate the size of the flake: $a \approx 0.4 \mu\text{m}$. Furthermore, p/γ_ω can be used to estimate $n=17$, if the simple kinetic theory of damping is valid. A flake with these dimensions would have $m = \pi a^2 n \rho_{2D} = 6 \times 10^{-18} \text{ kg}$, a factor of 4 lower than the optical mass listed in Table I.

Finally, using these estimates for the particle size and the result of Eq. (20), the precession rate of the axis of the flake induced by torques from the resonant electric field can be estimated: $\dot{\omega}_{\parallel}/\omega_g \sim 0.3 \text{ s}^{-1}$ (at $p=1.5 \mu\text{torr}$). Resonant reorientation (on the slow experimental time scales) is thus a reasonable explanation for the observed modulation of light scattering from the rotating graphene flake at specific excitation frequencies. A detailed understanding of the reorientation dynamics observed in Fig. 9, however, will require additional experimentation.

IX. OPTIMIZING THE MEASUREMENTS

The measurements presented above are obviously preliminary, and many aspects of the experimental design need to be improved. More uniform samples and better techniques to estimate their dimensions are desirable. A more accurate model of light scattering from micron-scale graphene flakes will also be required. Below is a list of several improvements to the experiment.

A. Trap design

The trap design presented in Fig. 1 suffers from the disadvantage that there is a large cubic term in the confining pseudopotential near the trap minimum. When excited to large amplitudes the system exhibits hysteresis, making it difficult to measure the frequency of resonance accurately. Traps with a symmetric design can make much more precise determinations of q/m (Ref. 21) and (by observing single

electron discharging or charging events) of q and m separately.²² An advantage of the current design, however, is that a trapped particle can, in principle, be transferred between two traps whose apexes are brought close together. Sample transfer may be useful, for example, in a load lock to a UHV or cryogenic environment.

B. Particle injection and preparation

While the techniques presented above for creating graphene suspensions and injecting them into the trap have yielded encouraging preliminary results, the data suggest that flakes trapped so far have been multilayer (or even many) layer. It is possible that the suspension contains mostly multilayer flakes. However, it is also likely that there is substantial selection bias in the experiment toward trapping large particles: given a $\sim 30 \text{ mg L}^{-1}$ suspension of graphene injected into the trap chamber at $1 \mu\text{L min}^{-1}$, there are 10^5 – 10^6 particles injected every second while typically ~ 0.1 – 1 s^{-1} are observed to enter the trap vicinity. If the trap design favors trapping heavy particles (for example, if the chamber pressure is so high that the large damping of light particles prevents effective trapping), then measurements of trapped particles will not reflect the distribution of sizes of particles in the original suspension. Further measurements on both the distribution of particle sizes in the suspension and of biases present in the trapping design are necessary.

In the current experiment, q/m is not a readily adjustable parameter (aside from its sign). Further charging of trapped particles would be desirable, for example, to offset the discharging of the particles that was observed at high light intensities or to increase flake charge beyond what is possible using the electrospray ionization method. Additional charging could be provided, either by using ultraviolet light¹⁸ or by an electron beam.²²

Finally, while suspensions of graphene created using ultrasonication yield irregularly shaped flakes with a distribution of sizes, substantial improvement are possible: with a starting material of long cylinders etched using deep reactive ion etching⁴⁶ from highly oriented pyrolytic graphite, for example, the lateral dimensions of the flake could be made uniform. Ultracentrifugation techniques⁴⁷ may lead to the production of suspensions containing flakes of only a specified number of layers.

C. Optics

The optical setup presented above will clearly benefit from a more rapid and versatile method for controlling light polarization. The measurements of rotational resonance were performed under continuous CPL illumination for simplicity. A better experiment would illuminate with CPL to confer angular momentum on the flake and measure with LPL in order to maximize sensitivity to flake orientation. Another improvement would be to view scattering at an angle perpendicular to the incoming radiation (and thus in the plane of the spinning disk) to maximize sensitivity of scattering to small changes in the orientation of the flake.

X. APPLICATIONS FOR LEVITATED GRAPHENE

A. Mechanical and materials properties measurements

Graphene has been deemed the world's strongest material because of its large Young's modulus and proven ability to withstand tensile strain in excess of 10%.¹¹ Spinning graphene up to high rotational velocities should provide an important measurement tool for graphene in an environment where uniform and controllable tensile stresses can be applied. The tensile stress from centrifugal force, f_c , at the center of a circular graphene single layer rotating about an axis perpendicular to its plane is⁴⁴

$$f_c = \frac{1}{8}(3 + \nu)a^2\omega^2\rho_{2D}, \quad (23)$$

where ν is the Poisson ratio [around ~ 0.17 (Ref. 11) for graphene]. If the yield strength is roughly at 10% strain and the Young's modulus is $E_{2D} = 340 \text{ N m}^{-1}$,¹¹ then the maximum possible value of $a\omega \sim 10^4 \text{ m s}^{-1}$, and the maximum rotation frequency of a graphene flake with $a = 1 \mu\text{m}$ is $\sim 1.7 \text{ GHz}$. While this rotation rate is much greater than was achieved in the experiments presented above, higher rotational velocities should be attainable, either by performing experiments at lower pressures or at higher laser powers.

In addition to centrifugal force, charged graphene also experiences electrostatic tension, f_e , which may be estimated from the capacitance (C) of a circular disk,⁴³

$$f_e = \frac{d}{d(\pi a^2)} \left(\frac{q^2}{2C} \right) = \frac{1}{2\pi a} \frac{d}{da} \left(\frac{q^2}{16\epsilon_0 a} \right) = \frac{q^2}{32\pi\epsilon_0 a^3}. \quad (24)$$

For the experiments discussed above, $q \sim \pm 2000 e$ and $a \sim 0.5 \mu\text{m}$ so $f_e \sim 10^{-3} \text{ N m}^{-1}$. While this number suggests that flake charge can be substantially increased, it is likely that electronic or ionic field emission at the edges of the flake will determine the maximum charge it can hold, rather than the intrinsic strength of the graphene.

The measurement of rotational resonance, in addition to providing direct information about the flake's rotation frequency, may provide a means to measure dissipation of vibrational excitations of the spinning disk when coupling to the external environment is extremely small and controllable. Rotational resonance may have sensitivity exceeding mechanical resonance of graphene attached to substrates for determination of the mechanical properties of the material, especially in the regime of large tensile deformations.

The thermal isolation of trapped graphene, combined with its strong optical absorption, means that it should be relatively easy to measure graphene's material and chemical properties at extremely high temperatures without any interaction from a substrate. Very little is known about the melting of graphene² or how defects will behave at high temperatures. Temperature-dependent adsorption and desorption of various atomic species⁴⁸ introduced into the trap chamber can presumably be measured with high accuracy, either by measurement of the flake mass²² or by rotational resonance.

B. Crystal growth and modification of trapped graphene

A significant limitation of the approach to graphene trapping presented above is that flake size is limited: it is improbable that flakes larger than $\sim 10 \mu\text{m}$ can be injected into the trap using liquid suspensions and the electrospray technique. Trapped flakes may possibly be modified *in situ*, however. For example, high-temperature anneals of rotating flakes might alter the shape of the trapped flake by promoting migration and smoothing rough edges. It is possible that the trapped environment may also have applications for graphene crystal growth: the general arguments against 2D crystallization⁴⁹ are unlikely to be valid in the presence of electrostatic or centrifugal tensions that would tend to keep the structure planar. The low mass of graphene monolayers means that even “wafer-scale” graphene can be held in traps without difficulty. The challenge is to find appropriate conditions where a small trapped graphene crystal will expand and maintain crystallinity when exposed to carbon sources, such as those used for C doping in molecular-beam epitaxy.^{50,51} One possibility is that vacancies are first injected into the bulk from the edge by a brief exposure to a high temperature. Subsequently, at a lower temperature, C from an impinging molecular beam is incorporated into the crystal at the positions of the vacancies. Because of the short time constants associated with cooling graphene at high temperatures (Fig. 5), such multitemperature growth cycles could proceed very rapidly.

The fact that electrostatic or centrifugal tensioning of graphene flakes can be used to increase the lattice constant by up to 10% may also facilitate novel heteroepitaxial materials based on a graphene substrate with an adjustable lattice. Boron nitride, with a lattice constant about 2% greater than graphene, may grow conformally on an appropriately tensioned substrate. Possible C-BN multilayers grown in this way may modify the band structure of the carriers in the graphene⁵² or improve their mobility.⁷

Is it likely that for many applications a sample prepared or modified in a trap will ultimately need to be positioned on a substrate. It is possible that electromagnetic focusing techniques (such as those used in mass spectroscopy and electron microscopy) could be used with trapped flakes to place them accurately on substrates, although maintaining proper orientation of the flake during its deposition onto a surface could be challenging.

C. New physics

The strong optical absorption that makes observing and spinning graphene easy will unfortunately make it very chal-

lenging to cool samples and observe new physics, either of the mechanical system or of the confined charge carriers. The optical measurement scheme presented above would need to be dramatically improved to enable low-temperature measurements. Nonetheless it is worth mentioning some experimental possibilities worthy of investigation: buffer gas cooling of the trapped flake using ^3He may enable cooling to $\sim 0.3 \text{ K}$. Measurement of the 2D charge carriers could be accomplished either by their effect on the rotational resonance behavior or by the braking effect noted above [Eq. (21)]. Graphene samples annealed at high temperature to remove adsorbates and measured in high vacuum may have extremely high carrier mobilities. Traps could be placed in magnetic fields to facilitate measurements in the quantized Hall regime but the charge density on the flakes will not be uniform⁴³ and will be sensitive to the orientation and the rotational velocity of the flake. Torques associated with orbital diamagnetism⁵³ of the 2D charge carriers should be detectable by their effect on flake orientation.⁵⁴ It is also possible that under appropriate conditions resonant coupling between electron or nuclear spins situated in the flake and the rotation or orientation of the flake could be observable.

Finally, it may be possible to cool levitated graphene using unorthodox techniques: for example, the out of plane (flexural) vibrations of levitated graphene are predicted to dominate its low-energy thermal properties since the dispersion of these modes is quadratic at zero tension³ while other phonon modes have linear dispersion. In the presence of tension, however, the flexural phonon dispersion becomes linear. Adiabatic detensioning of the flexural modes of a spinning membrane may thus lead to cooling as the rotational frequency is slowed, in close analogy to adiabatic demagnetization of spins. Low temperatures could also conceivably be reached either by coupling to a laser-cooled atomic system^{55,56} or by direct optical cooling using cavity optomechanics techniques.⁵⁷⁻⁵⁹ Perhaps the ultimate goal is to reach $kT/\hbar < \omega_g$, a regime where thermal excitations of transverse motion of the rotating membrane are suppressed, analogous to cooling to the ground state of a mechanical system.⁶⁰ For a graphene flake rotation frequency of order 1 GHz, this goal can be reached at $T \sim 50 \text{ mK}$. Trapped graphene would then be a “spinning qubit” for studies in quantum information science.

ACKNOWLEDGMENTS

This work was supported by the Laboratory for Physical Sciences. The author has benefited from discussions with M. Fuhrer and C. Monroe. Special thanks to B. Palmer for the use of a table in his laboratory.

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