Noncollinear spin valve effect in ferromagnetic semiconductor trilayers

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(Received 15 May 2007; published 19 July 2007)

We report the observation of the spin valve effect in (Ga,Mn)As/*p*-GaAs/(Ga,Mn)As trilayer devices. Magnetoresistance measurements carried out in the current-in-plane geometry reveal positive magnetoresistance peaks when the two ferromagnetic layers are magnetized orthogonal to each other. Measurements carried out for different postgrowth annealing conditions and spacer layer thicknesses suggest that the positive magnetoresistance peaks originate in a noncollinear spin valve effect due to spin-dependent scattering that is believed to occur primarily at interfaces.

DOI: 10.1103/PhysRevB.76.035324

PACS number(s): 72.25.Dc, 75.47.Pq, 75.70.Cn, 85.75.-d

I. INTRODUCTION

Heterostructures derived from ferromagnetic semiconductors (FMSs) are of current interest for both fundamental and applied problems in semiconductor-based spintronics.¹ In analogy with tunnel-based metallic spintronic devices, prior work has studied spin-dependent transport in various tunneling geometries²⁻⁶ that incorporate the "canonical" FMS Ga_{1-r}Mn_rAs.⁷ Some experiments suggest contributions of spin-dependent scattering (SDS) to spin transport in tunneling FMS devices.² However, there are no reports of SDS in the conventional spin valve geometry wherein the FMS layers are separated by a *conducting* nonmagnetic spacer (for instance, two Ga_{1-v}Mn_xAs layers separated by nonmagnetic p-doped GaAs). In such a device, the observation of a magnetoresistance (MR) that depends on the relative orientation of the magnetizations of the FMS layers would provide an all-semiconductor analog of a phenomenon central to metal-based spintronics. In this paper, we report the observation of such a spin valve effect in $Ga_{1-x}Mn_xAs/GaAs:Be/Ga_{1-x}Mn_xAs$ trilayers. In strong contrast with metallic spin valves, the associated MR in these FMS spin values is large on an absolute scale (ΔR ~15 Ω), but small on a relative scale $\left(\frac{\Delta R}{R} \sim 0.2\%\right)$. In addition, the unusual in-plane anisotropy of $Ga_{1-r}Mn_rAs$ results in spin valve devices that show MR when the relative magnetization of the two FMS layers switches from collinear to noncollinear (orthogonal) configurations.

In metallic systems, the conventional spin valve effect yields a giant magnetoresistance (GMR) when the magnetizations of the ferromagnetic layers switch from parallel to antiparallel states.^{8,9} The physical origins of GMR are attributed to differences in the contributions of SDS to the electrical conductivity for majority and minority spin carriers. A detailed knowledge of the band structure, interfaces, and impurity scattering is needed to quantitatively understand the GMR effect in a spin valve in the current-in-plane (CIP) geometry. However, a qualitative understanding can be obtained using a simple two resistor model wherein majority and minority spins are assigned different resistivities (ρ_{\uparrow} and ρ_{\downarrow} , respectively), and where the spin diffusion length is larger than the spacer layer thickness (*d*). Such an analysis leads to a MR given by⁹

$$\frac{\Delta R}{R} = \frac{(\alpha - 1)^2}{4(\alpha + pd_{NM}/d_{FM})(1 + pd_{NM}/d_{FM})}.$$
 (1)

Here, $\alpha = \rho_{\perp} / \rho_{\uparrow}$, $p = \rho_{NM} / \rho_{\uparrow}$, and ρ_{NM} is the spacer layer resistivity. Therefore, in order to obtain GMR, for a given value of α , it is important to have a low resistivity of the nonmagnetic spacer layer, at least comparable to the majority-spin resistivity ρ_{\uparrow} in the magnetic layers. For the CIP geometry, contributions to the spin valve effect from SDS at interfaces are enhanced by increasing both the mean free path (l_e) and the spin diffusion length (l_{sf}) of carriers in the spacer layer. Both these quantities are short in the low temperature grown p-GaAs spacer incorporated within Ga_{1-r}Mn_rAs-based trilayers. We estimate typical Drude values of $l_e \sim 3-5$ nm (due to point defects created during the low temperature growth) and $l_{sf} \sim 5$ nm (due to the short spin scattering time for holes). The spin valve effect can also have some contributions from SDS in the bulk of the ferromagnetic layers. However, both majority and minority holes presumably have a short spin diffusion length in Ga_{1-x}Mn_xAs, making scattering in the bulk largely spin independent and reducing this source of GMR. All these factors suggest a very narrow window of device parameters that would allow the definitive observation of the spin valve effect in $Ga_{1-r}Mn_rAs$ -based trilayer devices. Finally, we note that other sources of pronounced MR in Ga1-xMnxAs-such as the anisotropic magnetoresistance (AMR), the planar Hall effect (PHE), and the anomalous Hall effect¹⁰⁻¹²—may also complicate the identification of the spin valve effect. However, as will be shown later in this paper, the contributions of each of these effects can be distinguished from GMR. Additional MR effects have also been observed in tunneling geometries⁶ but are unimportant in the conventional spin valve geometry studied here.

II. EXPERIMENTAL DETAILS

We fabricated $Ga_{1-x}Mn_xAs/GaAs:Be/Ga_{1-x}Mn_xAs$ trilayers by low temperature molecular beam epitaxy on semi-insulating (001) GaAs substrates after the growth of a 100-nm-thick standard (high temperature) GaAs buffer layer. The thickness of the $Ga_{1-x}Mn_xAs$ layers is ~10 nm (calibrated using reflection high energy electron diffraction techniques) and the Mn concentration is nominally $x \sim 0.03$ (based on earlier calibrations). The GaAs:Be spacer layer is p doped using a Be source, with a nominal hole density of $p \sim 10^{20}$ cm⁻³ and a resistivity of ~ 10 m Ω cm; this is based on electrical measurements of thick Be-doped GaAs epilayers grown under identical conditions. Electrical transport measurements were carried out using dc techniques on lithographically defined, wet-etched 500 × 200 μ m² Hall bar mesas oriented along [110] and [100], with In contacts. We also measured the magnetization (*M*) of each sample using a Quantum Design superconducting quantum interference device (SQUID) magnetometer.

In order to observe spin valve behavior in such trilayers, the Ga_{1-r}Mn_rAs layers need to have distinct coercive fields (H_C) . We accomplish this by postgrowth annealing which drives hole-compensating Mn interstitials from the topmost $Ga_{1-x}Mn_xAs$ layer to benign regions at the free surface of the sample;¹³ in contrast, the diffusion of interstitials in the buried Ga_{1-r}Mn_rAs layer is believed to be self-limited by the establishment of Coulomb barriers at the GaAs/Ga1-rMnrAs interfaces. This results in clear changes to the magnetic properties of the top Ga_{1-x}Mn_xAs layer, while leaving the magnetic properties of the buried Ga1-rMnrAs layer unaffected.^{14,15} We investigated samples with a GaAs spacer layer thickness of 2, 5, and 10 nm: devices fabricated from these samples are identified as A, B, and C, respectively. We also studied pieces of sample B as a function of annealing time at 190 °C: devices fabricated from pieces of sample B are labeled as B1, B2, B3, B4, and B5, corresponding to as-grown devices, and annealed for 30, 60, 90, and 120 min, respectively. All devices fabricated from samples A and C are annealed for 60 min. Finally, as a control sample, we measured an as-grown 10-nm-thick epilayer of Ga_{1-x}Mn_xAs with nominally identical Mn concentration as in the trilayers (device D).

Figure 1(a) shows the temperature dependence of the remanent magnetization for devices B1 and B4 (as grown and 90 min anneal, respectively). The data indicate that annealing is necessary to create distinct Curie temperature (T_C) for each of the Ga_{1-x}Mn_xAs layers (T_C =65 K for the bottom $Ga_{1-x}Mn_xAs$ layer and $T_C=90$ K for the top layer). Figure 1(b) shows that the annealing also yields a two-step M(H)hysteresis loop (measured with $H \parallel [110]$), with a distinct value of H_C for each of the Ga_{1-x}Mn_xAs layers. Note that the switching of the magnetization of the Ga_{1-x}Mn_xAs layers occurs with a 90° rotation between in-plane easy axes $([\overline{1}00] \rightarrow [010] \rightarrow [100] \rightarrow [0\overline{1}0]).^{10,11}$ Since the two Ga_{1-r}Mn_rAs layers do not switch simultaneously, this results in a plateau in M(H). Temperature- and field-dependent SQUID measurements of devices B1-B5 show that the magnetic behavior of the top and bottom Ga_{1-x}Mn_xAs layers gradually becomes more different as a function of annealing time (data not shown).

In order to track the magnetization configurations in the trilayer, we exploit the GPHE in $Ga_{1-x}Mn_xAs$ by carrying out transport measurements in the CIP geometry with the magnetic field \vec{H} deliberately misaligned with respect to the current density $\vec{j}=j\hat{x}$ at an angle ϑ . Figures 1(c)–1(f) show $R_{xx}(H)$ and $R_{xy}(H)$ for devices B1, B2, B3, and B5, respec-



FIG. 1. (Color online) Magnetization of sample B as grown and after annealing at 190 °C for 90 min as a function of (a) temperature and (b) magnetic field. Remanent magnetization in (a) was measured in a field of 30 Oe after cooling in a 10 kOe field. Inset in (b) shows magnetic field and magnetization configuration at the flat step in M(H) hysteresis loop. Magnetic field dependence of R_{xx} and R_{xy} at T=4.2 K in devices fabricated from the same wafer but subject to different annealing periods is shown in (c) device B1: as grown; (d) device B2: annealed for 30 min; (e) device B3: annealed for 60 min; and (f) device B5: annealed for 120 min. The data are all taken in the CIP geometry with $\vec{j} \parallel [110]$ and \vec{H} aligned 20° off [110].

tively, at T=4.2 K with $i \parallel \hat{x} \parallel [110]$ and $\vartheta \sim 20^{\circ}$. The data for the as-grown device (B1) are similar to those for a single $Ga_{1-x}Mn_xAs$ epilayer because the two $Ga_{1-x}Mn_xAs$ layers have the same T_C and H_C . However, we observe a clear qualitative change in the MR as the device is annealed: with increasing annealing time, R_{xx} shows a tendency to stand out of the MR background, eventually resulting in two pairs of double MR peaks, which must have a different origin from the AMR associated with a single $Ga_{1-x}Mn_xAs$ epilayer. The annealing-induced changes to $R_{xx}(H)$ are accompanied by corresponding changes in $R_{xy}(H)$, which evolves from a onestep hysteresis loop to a two-step hysteresis loop with increasing annealing time. We will argue below that the double peak MR structure is an unambiguous indication of a spin valve effect that occurs when the magnetizations of the two Ga_{1-r}Mn_rAs layers are orthogonal to each other. Additional evidence for the spin valve origin of these MR peaks arises from the temperature dependence of R_{xx} and R_{xy} : in Fig. 2, we show the magnetic field dependence of R_{xx} and R_{xy} at different temperatures in device B4 with $j \|\hat{x}\| [110]$ and ϑ $\sim +15^{\circ}$. As the temperature increases, the saturated magne-



FIG. 2. (Color online) Temperature dependence of (a) R_{xx} and (b) R_{xy} in device B4. The data are taken in the CIP geometry with $\vec{j} \parallel [110]$ and \vec{H} aligned 15° off [110]. The data are offset vertically for clarity.

tization and the coercive fields of the two $Ga_{1-x}Mn_xAs$ layers decrease: as a consequence, there is a decrease in the magnitudes of the jumps in both $R_{xy}(H)$ and $R_{xx}(H)$. Once the bottom layer becomes paramagnetic (T > 60 K), the spin valve effect vanishes, but the GPHE due to the top $Ga_{1-x}Mn_xAs$ layer still persists.

III. THEORETICAL ANALYSIS

We now develop an analytical model of the observed behavior of $R_{xx}(H)$ and $R_{xy}(H)$ in the annealed devices. The discussion will refer to the data shown in Fig. 3 for device B4. We start with standard equations that describe the electrical field \vec{E} within a single domain ferromagnet with inplane magnetization,¹¹



FIG. 3. (Color online) Magnetic field dependence of (a) R_{xx} and (b) R_{xy} at T=1.5 K in device B4. The data are taken in the CIP geometry with $\vec{j} \parallel [110]$ and \vec{H} aligned 15° off [110]. Arrows in (b) represent relative magnetizations of the top and bottom $Ga_{1-x}Mn_xAs$ layers. Panels (c) and (d) depict the configurations of magnetization and magnetic field when $\varphi=45^\circ$ and $\varphi=135^\circ$, respectively. The sample was annealed for 90 min at 190 °C.

$$E_x = j\rho_{\perp} + j(\rho_{\parallel} - \rho_{\perp})\cos^2\varphi, \qquad (2)$$

$$E_{y} = j(\rho_{\parallel} - \rho_{\perp}) \sin \varphi \cos \varphi.$$
(3)

Here, φ is the angle between the direction of the current density \vec{j} ([110]) and the magnetization \vec{M} ; ρ_{\perp} and ρ_{\parallel} are the resistivities for current flow perpendicular and parallel to the magnetization, respectively. We note that ρ_{\parallel} is usually smaller than ρ_{\perp} in Ga_{1-x}Mn_xAs.¹¹ We now use these equations to develop an analytical understanding of $R_{xy}(H)$ in a trilayer device by treating it as three parallel resistors with resistivity ρ_1 (top FM layer), ρ_{NM} (nonmagnetic spacer layer), and ρ_2 (bottom FM layer).

For an in-plane magnetic field, there is no transverse electric field (E_y) due to the ordinary Hall effect. However, there is a contribution to E_y from the PHE in the two FM layers, driving a transverse current in each FM layer. According to Eq. (2), if the two layers were independent, such a transverse current would experience a resistivity $\rho_{\perp} + (\rho_{\parallel} - \rho_{\perp})\cos^2(90^0 - \varphi) = \rho_{\perp} + (\rho_{\parallel} - \rho_{\perp})\sin^2 \varphi$ in each layer. Hence, using Eq. (3), the PHE in the two FM layers would lead to a net transverse current given by

$$j_{M} = -\left[\sum_{i=1,2} \frac{j_{i}(\rho_{i\parallel} - \rho_{i\perp})\sin\varphi_{i}\cos\varphi_{i}}{\rho_{i\perp} + (\rho_{i\parallel} - \rho_{i\perp})\sin^{2}\varphi_{i}}\right].$$
 (4)

Here, j_1 and j_2 are the current densities (along the *x* direction by definition) in the top and bottom $\text{Ga}_{1-x}\text{Mn}_x\text{As}$ layers, respectively. However, the three parallel resistors in the trilayer must experience the same effective transverse field $(E_y)_{\text{eff}}$ that drives a transverse electrical current j_E . Taking each layer's thickness into account,

$$j_E = (E_y)_{\text{eff}} \left[\frac{1}{2\rho_{NM}} + \sum_{i=1,2} \frac{1}{(\rho_{i\perp} + (\rho_{i\parallel} - \rho_{i\perp})\sin^2 \varphi_i)} \right].$$
(5)

A meaningful physical measurement of the Hall effect requires carrier accumulation on the sidewalls at equilibrium (i.e., the total transverse electrical current should be zero for the entire device). Under this condition, $j_E=j_M$ and hence the effective transverse field $(E_y)_{eff}$ is given by

$$(E_{y})_{\text{eff}} = \left[\sum_{i=1,2} \frac{j_{i}(\rho_{i\parallel} - \rho_{i\perp})\sin\varphi_{i}\cos\varphi_{i}}{\rho_{i\perp} + (\rho_{i\parallel} - \rho_{i\perp})\sin^{2}\varphi_{i}} \right] \\ \times \left[\frac{1}{2\rho_{NM}} + \sum_{i=1,2} \frac{1}{(\rho_{i\perp} + (\rho_{i\parallel} - \rho_{i\perp})\sin^{2}\varphi_{i})} \right]^{-1}.$$
(6)

From Eq. (6), it follows that $(E_y)_{eff}$ has a minimum when the two Ga_{1-x}Mn_xAs layers have their magnetization parallel $(\varphi_1 = \varphi_2 = 45^\circ)$. In the down-field sweep in Fig. 3(b), this corresponds to the field range between "A" and $H \sim -0.05$ kOe. In contrast, $(E_y)_{eff} \sim 0$ when the magnetization of the top layer is switched by the external magnetic field $(\varphi_1 = 135^\circ)$ and $(\varphi_2 = 45^\circ)$, corresponding to "B" in the down sweep in Fig. 3(b). Finally, $(E_y)_{eff}$ reaches a maximum when the bottom layer magnetization switches $(\varphi_1 = \varphi_2 = 135^\circ)$, corresponding to "C" in the down sweep in Fig. 3(b). At "D," we again have $(E_y)_{eff} \sim 0$ with the magnetizations or-

thogonal to each other as in "B." The abrupt switching of the magnetization of each layer in the trilayer system results in a characteristic change of R_{xy} that allows us to track the relative configuration of magnetization orientations. As shown in Fig. 3, the distinctive features in $R_{xx}(H)$ are then directly correlated with the magnetization configuration of the Ga_{1-x}Mn_xAs layers, with a minimum R_{xx} when the magnetizations are aligned parallel, and an enhanced R_{xx} for noncollinear configurations.^{16,17}

However, Fig. 3 also shows that the detailed shape of the MR in these FMS spin valves is more complex than that found in most metallic spin valves, showing a double peak structure. This feature arises from an interesting interplay between the spin valve effect and the intrinsic AMR of an individual Ga_{1-r}Mn_rAs layer, leading to a MR valley exactly where a pure spin valve effect would lead to a MR peak. This behavior may be qualitatively explained using the magneto impurity scattering model, ^{10,18} which shows that $R_{xx}(H)$ for a single Ga_{1-r}Mn_rAs layer decreases abruptly when the magnetization first switches upon field reversal [as in Fig. 1(c)]. This occurs because of a discontinuous change in $\rho_{\perp} = a$ -b|B|=a-b|H+M|, where both a and b are positive parameters. Hence, when the magnetization of the top Ga_{1-r}Mn_rAs layer in a spin valve device switches, |B| = |H+M| increases, ρ_{\perp} decreases, and R_{xx} decreases [Eq. (1)]. As a consequence, the enhanced MR due to the spin valve effect is opposed by the intrinsic single layer AMR precisely when the layers switch from parallel to orthogonal configurations, resulting in a MR valley.

Yet more evidence for the spin valve effect arises from studies of MR along a different crystalline direction ([010]). In this configuration, for each individual layer of $Ga_{1-r}Mn_rAs$, the angle between the current density and magnetization [φ in Eq. (3)] is restricted to 0°, 90°, 180°, and 270° because the magnetic easy axis has to lie along one of the $\langle 100 \rangle$ directions. Thus, Eq. (3) predicts that the abrupt switching of the magnetization in a single layer will be accompanied by an equally abrupt change of longitudinal resistance $\delta R_x \propto (\rho_{\perp} - \rho_{\parallel})$. In a trilayer device, such switching produces four distinct jumps in longitudinal resistance as the magnetic field is swept from one field orientation to the opposite one. This behavior is seen in Fig. 4 which shows $R_{\rm rr}(H)$ at T=1.5 K in device B4 with $\tilde{j} \parallel [010]$ and H misaligned at $\sim +15^{\circ}$ with the [110] direction. We focus on the jumps labeled as "I" and "II" in Fig. 4. These correspond, respectively, to the switching of the magnetization of the top layer from a direction antiparallel to the field to orthogonal to the field and from orthogonal to parallel to the field. We model the longitudinal resistance of the trilayer device as three parallel resistors: $R^{-1} = \Sigma(R_i)^{-1}$. Since the observed $\delta R/R$ in Fig. 4 is relatively small (less than 1.7%), the total resistance of the trilayer system and the single layer resistances can be approximately treated as constants. Hence, if the only contribution to MR at jumps I and II is due to the switching of the top FMS layer, then $\Delta R = \frac{R^2}{R_{top}^2} \Delta R_{top}$. If there are no contributions from SDS and one only considers the change in ρ_{\perp} due to magnetization switching, then the two jumps in resistance due to the switching of the top layer's



FIG. 4. (Color online) Magnetic field dependence of R_{xx} in sample B3 at 1.5 K. The data are taken in CIP geometry with $\vec{j} \parallel [010]$ and *H* aligned 15° off [110]. The sample was annealed for 90 min at 190 °C.

magnetization (marked as I and II in Fig. 4) should have a distinct relationship: specifically, jump I should be a little smaller than jump II. This is because at jump I, ρ_{\perp} opposes the AMR contribution, but at jump II, it enhances the AMR contribution. However, Fig. 4 shows exactly the opposite behavior: the resistance change is bigger at jump I than at jump II. Further, the difference in magnitude of the resistance jumps (~12 Ω) cannot be explained by AMR alone. On the other hand, if the spin valve effect is taken into account, it will enhance the positive resistance jump but oppose the negative resistance jumps. Hence, the presence of a spin valve effect is consistent with our observation that jump I is bigger than jump II.

IV. DISCUSSION

The spin valve effect in these semiconductor-based trilayers could have two possible microscopic origins: SDS occurring at the interfaces between layers and SDS in the bulk of the FMS layer and possibly due to diffused magnetic ions in the nonmagnetic spacer layer. From the data presented here, we cannot definitively identify the source of SDS, although it is reasonable to expect that SDS in the bulk of the FMS layers does not play a dominant role given that the short diffusion length for holes is in $Ga_{1-x}Mn_xAs$. The observed enhancement of the spin valve effect by annealing is consistent with SDS at the interfaces: we speculate that the annealing leads to compositional disorder at the interfaces (possibly due to migration of both Mn and Be atoms), resulting in enhanced interfacial SDS. Such a mechanism has been suggested as an explanation for annealing-induced increases to GMR in metallic multilayers, although we caution that compositional disorder may also decrease GMR under certain conditions.¹⁹ Within such a picture, the spin valve effect



FIG. 5. (Color online) Magnetic field dependence of R_{xx} and R_{xy} at T=4.2 K in trilayer devices with (a) 2 nm spacer (device A), (b) 5 nm spacer (device B3), and (c) 10 nm spacer (device C). All three trilayers are subject to 60 min annealing at 190 °C. Panel (d) shows data for the as-grown epilayer (device D). The data are all taken in the CIP geometry with $\vec{j} \parallel [110]$ and \vec{H} aligned 20° off [110].

should show a nonmonotonic dependence on annealing time due to the trade-off between the enhancement of SDS due to Mn diffusion into the spacer layer and reduction of spin scattering due to Be migration into the $Ga_{1-x}Mn_xAs$ layers. This is supported by our data, showing that 90 min annealing has a bigger spin valve effect than shorter and longer annealing times.

The role of SDS at interfaces is also consistent with the dependence of the observed spin valve effect on the thickness of the spacer layer. This is shown in Figs. 5(a)-5(d) where we compare the field dependence of R_{xx} for devices A, B3, C (all annealed for 60 min at 190 °C), and the (as-

grown) control sample D. The data show that the spin valve effect is absent in devices with the thinnest (2 nm) spacer layer [Fig. 5(a)], where the behavior is similar to that of the control epilayer [Fig. 5(d)]. We attribute this to a coupling between the Ga_{1-x}Mn_xAs layers which makes the trilayer act like a single layer. The spin valve effect is strongest in devices with the 5 nm spacer [Fig. 5(b)] and absent in devices with the thickest (10 nm) spacer [Fig. 5(c)]. The latter is consistent with an anticipated hole spin diffusion length of several nanometers. We note that qualitative features of this spacer thickness dependence has been reproduced in devices fabricated from different wafer runs of nominally identical samples.

V. CONCLUSION

In conclusion, we have shown that annealing is critical to the observation of GMR in all-semiconductor Ga_{1-r}Mn_rAs/Be:GaAs/Ga_{1-r}Mn_rAs trilayer devices. The dependence of the spin valve effect on annealing time and spacer thickness suggests that the spin valve effect principally arises from interfacial spin-dependent scattering. These semiconductor spin valves give access to a different regime of parameter space for studying GMR compared to metallic systems and may provide fundamental insights into the underlying physics. Further insights into the spin valve effect in these all-semiconductor trilayer devices can be obtained in the current-perpendicular-to-the-plane geometry and such measurements will be reported in future reports.

ACKNOWLEDGMENTS

This research has been supported by Grant No. ONR N0014-05-1-0107, University of California-Santa Barbara Subcontract No. KK4131, and NSF Grants Nos. DMR-0305238 and DMR-0401486. We also acknowledge the use of the NSF funded NNIN facility at Penn State University.

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