Effect of internal friction on transformation twin dynamics in perovskite $Sr_rBa_{1-r}SnO_3$ $(x=0.6, 0.8)$

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The dynamics of transformation twins in $Sr_xBa_{1-x}SnO_3$ ($x=0.6,0.8$) perovskite has been studied by dynamical mechanical analysis in three-point bend geometry. This material undergoes phase transitions from orthorhombic to tetragonal and cubic structures on heating. The mechanical loss signatures of the transformation twins include relaxation and frequency-independent peaks in the orthorhombic, and tetragonal phases, with no observed energy dissipation in the cubic phase. The macroscopic shape, orientation, and relative displacements of twin walls have been calculated from bending and anisotropy energies. The mechanical loss angle and distribution of relaxation time are discussed in terms of bending modes of domain walls.

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The attenuation of seismic waves at frequencies from 1 mHz to 1 Hz is expected to affect the geophysical signatures of mantle-forming minerals in the deep earth, such as $(Mg, Fe)(Si, Al)O₃$ $(Mg, Fe)(Si, Al)O₃$ $(Mg, Fe)(Si, Al)O₃$ perovskites.^{1–3} $(Mg, Fe)(Si, Al)O₃$ perovskite is orthorhombic at lower mantle pressures and temperatures,⁴ but is metastable at ambient \overline{T} and \overline{P} . Thus, structural analogs with a stable orthorhombic crystalline structure are needed for studying and modeling the lowfrequency mechanical properties of perovskite. Ferroelastic perovskites, in particular, those isostructural with (Mg, Fe)(Si, Al)O₃, develop mobile domain structures in their low-symmetry (ferroelastic) phases.⁵ Mechanical loss or internal friction of these domain structures results in a dissipation peak related to the microstructure and its mobility. In the high-symmetry (paraelastic) phase, the ferroelastic transformation twins are absent and the dissipation of me-chanical energy is (comparatively) negligible.^{1,[5](#page-5-4)}

Earlier observations have stimulated much interest in the displacement of the domain walls on the mesoscopic scale, where the needle growth from crystal interfaces is a timedependent self-adjustment toward a new equilibrium, dependent on temperature and applied external stress σ . The dynamics of relaxation depends on a viscosity function *B* \lceil Pa s/m \rceil that originates from the internal structure of the domain wall and the domain-wall–point-defect interactions. As the viscous displacements of domain walls from their equilibrium positions are, by their very nature, dissipative in energy, they can be investigated by mechanical spectroscopy.⁶

Previous studies of domain-wall trajectories have only considered the static case.⁷ Here, we extend that approach to include time dependence. The motion of a single transformation twin through an inhomogeneous concentration of point defects at given T and σ is described by the following timedependent equation:

$$
B\frac{dy(x,t)}{dt} = -S\frac{d^4y(x,t)}{dx^4} + U\frac{d^2y(x,t)}{dx^2} - \Pi y(x,t) + \sigma, \quad (1)
$$

where $y(x, t)$ gives the trajectory of wall position in the elastically soft direction of the crystal, *B* is the dragging force per unit length depending on the intrinsic viscosity of wall width, Π is the Peierls force responsible for the lateral motion, and *S* and *U* are the bending and the anisotropy energies of wall segments, respectively.

Equation ([1](#page-0-0)) determines the wall profile from the minimum condition that the total energy density⁷

$$
E[y(x,t)] = \int (E_{\text{anisotropy}} + E_{\text{bending}} + E_{\text{Peierls}})dx
$$
 (2)

is given by the Euler-Lagrange equation

$$
\frac{\partial E[y(x,t)]}{\partial y(x,t)} = F_{\text{diss}} + F_{\text{ext}},\tag{3}
$$

with dissipative $F_{\text{diss}} = Bdy(x, t)/dt$ and driving F_{ext} forces per unit area of wall surface. $E_{\text{bending}} = S(d^2y(x, t)/dx^2)^2$ and $E_{\text{anisotropy}} = U(dy(x, t)/dx)^2$ measure the excess energies for bending and rotation of wall segments with respect to the elastically soft direction of the crystal. If dissipative forces act on a domain wall, then the wall dynamics is damped. In the approximation of defect-free bulk or weak domain-wall– defect interactions, this damping is associated with the asymmetric growth of needles from the crystal interfaces due to the local structure of those interfaces and microscopic shearing of the sample. Here, we examine the effect of internal conformational arrangements of wall segments due to the movement of asymmetrical domain walls during an external stress perturbation.

In the steady-state limit $(Bdy/dt \rightarrow 0)$, the dynamics of domain walls is suppressed in time by twin-wall–defect interactions which, in general, determine needle trajectories and the symmetrical shapes of needle tips.⁷ The tip remains rigidly pinned in the vicinity of defects for the time of any observation, but the trajectory may relax slowly causing a microscopic deformation of the sample at large distances from the pinning center within a characteristic time greater than the lattice relaxation time. Such twin walls form, in particular, needles with shapes which do not depend on *T*, *P*, or the crystal structure in which they occur. Furthermore, low-frequency spectroscopy measurements and *in situ* optical microscopy demonstrate that the needle motions toward equilibrium $(dy/dt \neq 0)$ are subject to a Debye relaxation with a distribution of relaxation times.¹ The needles remain

pinned on the crystal interfaces over a wide range of temperatures and stresses, while a comb of the symmetric and asymmetric needle tips is found to sweep between the sample boundaries, yielding two mechanical responses in the Cole-Cole diagram: one with an anelastic signature described by a suppressed semicircle and other with a creep signature at low frequency, which has yet to understand from a viewpoint of domain-wall morphology and relaxation times.

 $Sr_xBa_{1-x}SnO_3$ ($x=0.6,0.8$) perovskite is a model system adopting the orthorhombic phase at room temperature. It undergoes a number of phase transitions to cubic symmetry with temperature [see Fig. $1(a)$ $1(a)$]. The low-symmetry orthorhombic (Pnma, Imma) and tetragonal (I4/mcm) structures are related to the ideal cubic $(Pm\overline{3}m)$ structure of $Sr_xBa_{1-r}SnO₃$, via tilting of the SnO₆ octahedra about the cubic symmetry axes.⁸ Experimentally, we have studied its mechanical response by dynamical mechanical analysis (DMA-7), which permits measuring the mechanical loss and elastic constants of $Sr_xBa_{1−x}SnO₃$ in parallel-plate stress (PPS) and/or three-point bending (TPB) geometries.³ As the elastic constants of perovskite are closely related to spontaneous strain induced during the $SnO₆$ tilting, the mechanical loss spectrum in Fig. [1](#page-1-0) follows closely the phase transitions with temperature.^{1,[9,](#page-5-8)[10](#page-5-9)} The peaks at 170 °C $(Sr_{0.6}Ba_{0.4}SnO_3)$ and 580 °C $(Sr_{0.8}Ba_{0.2}SnO_3)$ are spectroscopic features of the tetragonal-orthorhombic phase transitions [compared with the phase diagram on Fig. $1(a)$ $1(a)$]. The peak at 411 °C for the 1 Hz mechanical loss spectrum of $Sr_{0.8}Ba_{0.2}SnO₃$ depends on frequency and is accompanied by a modulus anomaly. By using the peaks as markers of the frequencytemperature shifts, we estimated values of 1.85 eV and 10^{+14} s⁻¹ for the activation enthalpy ΔH_{act} and the attempt frequency ω_0 , respectively. These values are characteristics of a pinning-depinning transition, which is mainly attributed to the interaction of domain walls with oxygen vacancies $11,12$ $11,12$ and cation interstitials 13 in perovskites. The apparent activation energy for those pinning sites decreases with *T* in the ferroelastic phase, as the energy landscape experienced by the domain walls becomes insensitive to the defect distribution with increasing temperature (wall width increases dramatically at T_c). Here, we explore whether needle growth is the origin for these apparent values of activation energy, since needle displacements may contribute to the effective energy through spatial redistributions of bending modes due to the local structure of crystal surfaces.

Above 550 °C $(Sr_{0.6}Ba_{0.4}SnO_3)$ and $800 °C$ $(Sr_{0.8}Ba_{0.2}SnO_3)$, the measured loss angle is minimal, while the stiffness of material is maximal. Such a behavior is a manifestation of a transition to the cubic symmetry in which the transformation twins no longer exist and domain-wall dynamics has no bearing on dissipation.

On the macroscopic scale, the internal structure of domain walls is determined by the spatial variations of the order parameter below the phase transition.⁵ The pulling and pushing of neighboring structural units at the boundary separating mesoscopic domains of different orientations (macroscopic spontaneous strains) induce displacement fields, which propagate in the elastically soft direction of the ferroelastic phase via a knock-on effect. In the approximation when no

FIG. 1. (a) Temperature-composition phase diagram for the solid-solution Sr_xBa_{1−*x*}SnO₃ stannate. Isochronal mechanical loss spectra of (b) $Sr_{0.6}Ba_{0.4}SnO₃$ and (c) $Sr_{0.8}Ba_{0.2}SnO₃$ at frequency between 1 and 6 Hz. For the cubic phase above (b) 800 \degree C and (c) 550 \degree C, the modulus saturates and the loss drops to a negligible value, so the data are not reported.

FIG. 2. Needle profiles calculated for *t* from 0 to 100 s in 2 s steps. Each trajectory corresponds to a different time. The stress is abruptly applied at ξ_0 ($t=0$) and held to a constant value σ_0 at *t* >0 . (a) PPS mode, anisotropy dominates over bending energy. (b) PPS mode, bending dominates over anisotropy energy. [(c) and (d)] Similar concepts of energies but in TPB mode.

additional short-range interactions are considered, the coordinate of wall displacement $y(x, t)$ measured along the normal to domain wall is given by

$$
y(x,t) = \int_0^t \int_0^l G(x,\xi,t-s)f(\xi)\delta(s)d\xi ds
$$

+
$$
\int_0^t \int_0^l G(x,\xi,t-s)\vartheta(\xi,s)d\xi ds.
$$
 (4)

In Eq. ([4](#page-2-0)), $f(x)=y(x,0)$ accounts for the Cauchy initial conditions, $\delta(x)$ is the Dirac delta function, $G(x, \xi, t)$ is the Green's function, and $\vartheta(\xi, s)$ is the nonhomogeneous term in Eq. ([1](#page-0-0)). The explicit solution of $G(x, \xi, t)$ is¹⁴

$$
G(x, \xi, t) = \frac{2}{l} \sum_{n} \sin\left(n\pi \frac{x}{l}\right) \sin\left(n\pi \frac{\xi}{l}\right)
$$

$$
\times \exp\left(-\frac{\Pi}{B}t - \frac{U}{B}\left(\frac{n\pi}{l}\right)^{2}t - \frac{S}{B}\left(\frac{n\pi}{l}\right)^{4}t\right). \quad (5)
$$

The Green's function is calculated at $t \ge 0$ for $0 \le x \le l$, which accounts for the mesoscopic situations observed in perovskites $1,3$ $1,3$ when the twin boundaries propagate through the bulk under effect of applied stress while the surface of the crystal is allowed to relax so that $y=0$ at $x=0$ and $x=l$. It is relevant to define the relaxation time by $\tau = (B/U)$ $\times (l/n\pi)^2 = (1/n)^2 \tau_U$ or $\tau = (B/S)(l/n\pi)^4 = (1/n)^4 \tau_S$, where τ_U and τ_s are the single Debye relaxation times, in the limiting cases that either the anisotropy or bending energy dominates the total energy. The Peierls contribution is not considered further in Eq. (5) (5) (5) as the domain walls mainly interact with

defects at temperature at which $E_{\text{Peierls}} = \Pi y(x, t)$ is much smaller than E_{bending} and $E_{\text{anisotropy}}$. Thus, we neglect the influence of sample geometry at high temperatures (E_{Peierls} \rightarrow 0) and calculate domain walls with universal shapes of needle tips. By contrast, at very low temperature, the Peierls energy scales with the barrier height of the Landau doublewell potential and, thus, dominates over all energies in the energy landscape. The wall trapping is determined by the lattice potential (E_{Peierls}) and/or point defects, and the energy for thermal activation is calculated from the energy barrier in the Landau potential.¹⁵

The domain profiles at high temperatures are calculated for a stress field which is abruptly applied at *t*=0 and held to a constant value σ_0 at $t > 0$. From Eqs. ([4](#page-2-0)) and ([5](#page-2-1)), one obtains

$$
y(x,t) = IT + \sigma^* \int_0^t \int_0^l G(x,\xi,s) d\xi \, ds. \tag{6}
$$

The initial trajectory (IT) determines the wall trajectory at *t*=0 for a stress level exceeding the threshold for nucleation. The profiles of domain walls from Eq. (6) (6) (6) are plotted in Fig. [2.](#page-2-3) Simulations were carried out with $l \sim 10$ nm, $S/U/l^2$ \sim 0.1, $\sigma^* = \sigma_0 / B \sim 10^6$ nm s⁻¹, and $\sigma_0 \sim 1000$ mN/mm², which are values typical for the needle profiles in ferroelastics.^{5[,7](#page-5-6)} The parabolic tips of domain walls follow a Debye relaxation pattern toward an equilibrium position both whether the trajectories are dominated by the anisotropy [Fig. $2(a)$ $2(a)$] or bending [Fig. $2(b)$] energies. The geometry of the needle tip is strongly dependent on the stress profile $\vartheta(\xi, s)$ applied on the perovskite surface. Figures $2(a)$ $2(a)$ and $2(b)$ $2(b)$ are examples of time-dependent wall evolution calcu-

lated from Eq. ([6](#page-2-2)) for a homogeneous stress profile along the surface (the PPS mode). In the TPB mode, we induced an inhomogeneous stress profile through the sample by applying a dynamic force in the middle of $Sr_xBa_{1−*x*}SnO₃ surface, e.g.,$ at $\xi_0 = 1/2$ precisely. Thus, by substituting $\vartheta(\xi, s) d\xi ds$ with $\sigma^* \delta(\xi - \xi_0) d\xi ds$ in Eq. ([4](#page-2-0)), we calculated the wall trajectory in the TPB geometry as follows:

$$
y(x,t) = IT + \sigma^* \int_0^t G(x,\xi_0,s)ds.
$$
 (7)

The results are plotted in Figs. $2(c)$ $2(c)$ and $2(d)$ for $E \approx E_{\text{anisotropy}}$ and $E \approx E_{\text{bending}}$, respectively. Time ranges from 2 to 100 s were used for wall simulations in both geometries.

The wall trajectory in Figs. $2(c)$ $2(c)$ and $2(d)$ ends in a tip, which diverges from the parabolic one observed in Figs. $2(a)$ $2(a)$ and $2(b)$ $2(b)$. $E_{\text{anisotropy}}$ yields a straight trajectory around the needle tip for large *t*, which is identical to the steady-state profile calculated in previous works.^{τ} For small t , however, exponential needles develop in time with tip angles which vary with the needle half-width due to the inhomogeneous stress profile along ξ . They are not characteristic-length dependent as $E_{\text{Peierls}} \rightarrow 0$. They are due to the macroscopic sample deformation caused by the strain along the soft direction as a result of accommodation of wall relaxation at $\xi=0$ and $\xi=1$, as well as the absence of bending energy. Indeed, the excess of E_{bending} does maximize the curvature of the wall trajectory at each point along ξ , as in Fig. [2](#page-2-3)(d), by superimposing a modified parabolic shape upon a straighter shape at the vicinity of the pinning centers on the surface. Strictly speaking, the maximum curvature of the parabolic profile at $\xi = 1/2$ $\xi = 1/2$ in Fig. 2(d) is a result of the smooth connection of the rotated parts of the wall around the center.

In the PPS mode, neither exponential nor linear trajectories are calculated from Eq. (6) (6) (6) . The profiles in Fig. $2(a)$ $2(a)$ are insensitive to the anisotropy energy since it is suppressed by the homogeneous sample deformation, which introduces parallel shift and constant curvature of domain walls at each point along the soft direction in the PPS mode. Furthermore, the wall displacements for E_{bending} are also strengthened by this deformation, making their trajectories in Fig. $2(b)$ $2(b)$ to look similar to the ones calculated for $E_{\text{anisotropy}}$ in Fig. [2](#page-2-3)(a).

Building on the results in Fig. [2,](#page-2-3) we observe that the wall displacement in the TPB mode depends on the magnitude of anisotropy and/or bending energy and the stress profile on the crystal surfaces. The boundary conditions applied in Eqs. (4) (4) (4) and (5) (5) (5) define a planar interface for needle growth at $t \geq 0$. In contrast, the surfaces of real experimental samples are highly rough and nonplanar. For the purposes of modeling, we may consider a saw-toothed boundary along ξ with an average slope, which depends on the redistribution of normal stresses across the boundary plane.¹⁶ The shear component of the stress is relaxed along ξ (strong pinning sites on the surface), causing a displacement along the soft direction which is driven by the stress balance between the internal stresses acting on the boundary plane and σ . This results in a shift of the resulting stress from $\xi_0=1/2$ toward another

FIG. 3. Needle profile for a stress at $\xi_0 = l/3$ in TPB mode. (a) Anisotropy energy dominates bending energy. (b) Bending energy is larger than anisotropy energy.

point $\xi_0 \neq 1/2$, which accounts for needles with tips at $\xi_0 \neq 1/2$ and an asymmetric shape.

In Fig. [3,](#page-3-0) the trajectories are calculated with a stress applied at $\xi_0=1/3$, which describes a model example of wall behaviors expected due to an inhomogeneous stress profile with σ acting away from the center in the TPB geometry. The offset of the tip from the center is critical to the needle symmetry in crystals with a large $E_{\text{anisotropy}}$ and less critical in crystals with large E_{bending} . Indeed, for E_{bending} , the shift of the tip toward the center is balanced by the angular momentum for each length element that rotates the wall toward the center and the time-dependent sliding of each length element toward the equilibrium state, Fig. $3(b)$ $3(b)$. Note that no tip shift with time is predicted for $E_{\text{anisotropy}}$ in Fig. [3](#page-3-0)(a) because the wall dynamics is constrained along the elastically soft direction of the crystal, in particular, which is the axis of energy minimum of the conformational arrangements of wall segments.

The above results show that for nonplanar interfaces, the normal stresses cause a narrow distribution of the needle shapes for $E \approx E_{\text{bending}}$ [Fig. [3](#page-3-0)(b)] around the wall trajectory of the most probable shape (e.g., one which is a parabolic tip

in the center at equilibrium) and a much broader one for $E \approx E_{\text{anisotropy}}$ [Fig. [3](#page-3-0)(a)]. Thus, a distribution of relaxation times around τ_m (the most probable value), together with broadening of the relaxation spectra around $\omega = 1/\tau_m$ in frequency space, is expected from the intrinsic effects of needle movements. Building on previous work on distribution of relaxation times in perovskites, we also know that the dynamics associated with the needle motions throughout a nonuniform distribution of defects may generate a stretched exponential relaxation.¹ For the sake of completeness, an asymmetric profile in perovskites may be obtained by needle growth not only from surface defects but also from bulk defects when needles split into pairs with smaller tip angles due to minimization of $E_{\text{anisotropy}}$ contribution.⁵ The trapping of one of those tips into the stability field of point defects or lattice singularities (a probabilistic process) suppresses the tip displacement along the soft direction and promotes an asymmetric shape via lateral displacements of other tip into the bulk. It would be, however, difficult to distinguish needle dynamics due to surface and bulk defects quantitatively from mechanical spectroscopy alone, and additional observations, such as transmission electron microscopy, would have to be made to confirm such a description.

For this reason, we chose here a qualitative description of the underlying mechanism by deriving the probability density function of intrinsic movements of domain walls. The *E*anisotropy effects on the loss dynamics will be considered firstly. The complex compliance in ω space, $J^*(x, w)$, can be calculated in a straightforward manner⁶ from

$$
J^*(x,\omega) = J_U + i\omega \int_0^\infty [J(x,t) - J_U] \exp(-i\omega t) dt,
$$
 (8)

where $J(x,t) = J_U + y(x,t) / L / \sigma$. Thus, from Eq. ([8](#page-4-0)), one gets

$$
J^*(x, \omega) \equiv J_1 - iJ_2
$$

$$
= J_U + \frac{l^2}{LU} \sum_n \frac{\sin\left(n\pi \frac{x}{l}\right)}{n\pi} \frac{\sin\left(n\pi \frac{\xi_0}{l}\right)}{n\pi} \frac{1}{1 + i\omega \tau_n},
$$

(9)

where $J_U = 1/E$ is the unrelaxed compliance and *L* is the width of the sample in the elastically soft direction. Further, the discrete τ_n spectrum can be approximated by a continuous spectrum for time intervals closely spaced and relative to $1/\omega$. Examples of statistical developments with a continuous rather than a discrete distribution of relaxation times are the motion of dislocations in the multiwell energy diagram dependent on the segregation of point defects on the dislocation $\lim_{h \to 0}$ and the grain boundary sliding lubricated by an amorphous intergranular layer causing stretched exponential relaxation due to the interaction between the relaxing species into the film.¹⁹ Following Nowick and Berry,²⁰ we define the distribution in terms of $\ln \tau$, rather than in τ itself. The expressions for J_1 and J_2 in the continuous limit are

$$
\frac{J_1 - J_U}{\delta J} = \int_{-\infty}^{\infty} \frac{X[\ln(\pi/\tau_D)/\mu]}{1 + \omega^2 \tau^2} d \ln(\pi/\tau_D)
$$
(10a)

and

$$
\frac{J_2}{\delta J} = \int_{-\infty}^{\infty} X \left[\frac{\ln(\pi/\tau_D)}{\mu} \right] \frac{\omega \tau}{1 + \omega^2 \tau^2} d \ln(\pi/\tau_D). \tag{10b}
$$

In Eq. (10), $\delta J = J_R - J_U = l^2 / (LU)/2$ is the magnitude of the domain-wall relaxation, and μ is the distribution parameter proportional to the half-width of $X(\eta)$. Following Nowick and Berry²⁰ and Tobolsky,²¹ we substitute $\ln(\omega \tau_D)$ with *z* and $\ln(\tau/\tau_D)/\mu$ with η :

$$
\frac{J_1 - J_U}{\delta J} = \int_{-\infty}^{\infty} \frac{X(\eta)}{1 + \exp(2z + 2\mu \eta)} d\eta \equiv f_1(z, \mu) \quad (11a)
$$

and

$$
\frac{J_2}{\delta J} = \int_{-\infty}^{\infty} \frac{X(\eta)}{\cosh(z + \mu \eta)} d\eta \equiv f_2(z, \mu).
$$
 (11b)

Equations $(11a)$ $(11a)$ $(11a)$ and $(11b)$ $(11b)$ $(11b)$ are similar to those used by Nowick and Berry²⁰ and Tobolsky²¹ for the box and lognormal distributions of relaxation times. The normalized probability density function of domain walls,

$$
X\left[\frac{\ln(\pi/\tau_D)}{\mu}\right] = \frac{\left[\sin\left(\pi \frac{\ln(\pi/\tau_D)}{\mu}\right) / \pi \ln(\pi/\tau_D)\right]^2}{\int_{-\infty}^{\infty} \left[\sin\left(\pi \frac{v}{\mu}\right) / \pi v\right]^2 dv}
$$

$$
= \frac{1}{\mu} \left[\frac{\sin\left(\pi \frac{\ln(\pi/\tau_D)}{\mu}\right)}{\pi \frac{\ln(\pi/\tau_D)}{\mu}}\right]^2, \qquad (12)
$$

is a corollary of the Fourier transforms of the integral kernel $[Eq. (5)]$ $[Eq. (5)]$ $[Eq. (5)]$. It assigns the distribution density of relaxation time around some mean value τ_U in the interval $[\tau, \tau + d\tau]$ as a result of the probability density of finding a needle trajectory defined by τ around the most probable needle bending mode defined by τ_U in the range between τ and $\tau + d\tau$. The distribution parameter was introduced in the $sinc²$ function [Eq. (12) (12) (12)] through the offset of needle tips from the center (Fig. [3](#page-3-0)), which follows from the redistribution of the normal stress along ξ as a consequence of surface inhomogeneity.

In Fig. [4,](#page-5-11) the relaxation peaks in $Sr_{0.8}Ba_{0.2}SnO₃$ are well modeled by a distribution of Debye peaks tan $\phi(z,\mu)$ calculated from Eq. (11) in terms of variable $1/T$, rather than in $\ln(\omega \tau_D)$ itself, for thermally activated atomic motions. We calculated μ =10.3 and $\delta J / J_U$ =0.35 from the relative peak width, $r_2(\mu) \equiv \Delta T^{-1}(\mu) / \Delta T^{-1}(0) = 3.7$, and the relative peak height $2f_2(0, \mu) \equiv J_2(0) / \delta J = 0.28$, where $\Delta T^{-1}(0)$ and $J_2(0)$ are the half-width and the relaxation strength of the single Debye peak, respectively. For the fit, we used a Debye peak with relative peak width given by $\Delta H_{\text{act}}/r_2(\mu)$, as well as the values of $(\tan \phi)_P$ and T_P at the maximum of the peak. The internal friction peak in Fig. $4(a)$ $4(a)$ and therefore the relaxation

FIG. 4. (a) Mechanical loss peaks in $Sr_{0.8}Ba_{0.2}SnO₃$ in the domain freezing T are fitted with distributed Debye peaks. (b) Normalized distributed Debye peaks tan $\phi(z,\mu)$ /tan $\phi(0,\mu)$ calculated for μ =0–6. A single Debye relaxation process corresponds to μ =0.

process are completely characterized by ω_0 , ΔH_{act} , μ , and $\delta J/J_{U}$.

The values of $\delta J / J_U$, $f_2(0, \mu)$, and $r_2(\mu)$ calculated from Eq. (11) differ from the ones calculated and tabulated by Nowick and Berry for the lognormal distribution.²⁰ This difference is a corollary of the maxima existing at $x = \pm 3/2\pi$ around the main maximum at $x=0$ in sinc²(x), which results in an additional statistical broadening of relaxation times for large μ . For small μ , however, the broadening of the domain walls is described by the Gaussian-like distribution²⁰ as the central maximum in $\text{sinc}^2(x)$ smears out the effect of other maxima. The transition from small values of μ to larger ones gives a transition in J_2 − J_1 space, which does not result from the onset of low-frequency creep in the material but does result from the different quantitative description of the wall dynamics in terms of distributions of relaxation times. Experimental studies on superelasticity show that μ changes with temperature,¹ e.g., it decreases with increasing T (the distribution of the relaxation time is more likely to be in the activation energy rather than in the limit relaxation time.^{1[,20](#page-6-8)}), through a number of factors (wall width, wall density, and surface roughness) which are intrinsic function of temperature.^{3,[10](#page-5-9)} Thus, the systematic dependence of μ with *T* may lead to a transition in the $J_2 - J_1$ diagram,¹ as well as positive shift in the effective value of the activation energy.

In conclusion, for $E \approx E_{\text{anisotropy}}$, the needle trajectory of ferroelastic domain walls gives rise to a distribution of relaxation times for wall dynamics around τ_U . This, however, is not found when $E \approx E_{\text{bending}}$. It follows from Eqs. ([4](#page-2-0)) and ([5](#page-2-1)) that the E_{bending} effects can be introduced in J_2 and J_1 spectra by replacing $\tilde{X}(\eta)$ with $X(\eta)/\eta^2$ into Eq. (11). For integral operations, it is more convenient to normalize the latter and write in terms of $\delta(\eta) = \lim [X(\eta)\varepsilon/(\eta^2 + \varepsilon)]$. Both integrals $\varepsilon \rightarrow 0$

reduce to the Debye equations for $E \approx E_{\text{bending}}$. Hence, needle dynamics is governed by a single Debye relaxation time τ_s , which determines a needle trajectory of a modified parabolic shape. No broadening of relaxation peaks in terms of relaxation times exists in a crystal with $E \approx E_{\text{bending}}$. Additionally, it follows from $S/U \sim l^2$ for $l \sim 100$ nm and $\tau_s = 2\pi/\omega_s$ $=(B/S)(l^4/\pi^4)$ that the maximum in the energy dissipation is described by a relaxation peak in the kilohertz frequency range, which is much higher than the frequency range in Figs. [1](#page-1-0) and [4,](#page-5-11) and the frequency of seismic waves, although the influence of pressure in the deep earth on this relation has yet to be determined.

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