

Two-point correlations near the phase transition in a compressible magnet

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Leading order in $\epsilon (= 4 - d)$ solutions of renormalization-group recursion relations are used to calculate the two-point correlation function in an n -component compressible magnet. The effect of finite compressibility on two-point correlations is studied and comparisons with the rigid system are made.

I. INTRODUCTION

One of the most useful tools in studying the critical-point behavior of magnetic systems is elastic neutron scattering. The coupling between the neutron and electron magnetic moments leads to a dependence of the differential scattering cross section on the Fourier transform of the spin-spin correlation function

$$G(\vec{q}, t) = \sum_{\vec{R}} e^{-i\vec{q} \cdot \vec{R}} \langle \vec{S}(\vec{R}) \cdot \vec{S}(\vec{0}) \rangle \quad (1.1)$$

Here \vec{q} is the momentum transfer which is related to the scattering angle and $t = (T - T_c)/T_c$ is the reduced temperature. In rigid magnetic systems for wave vectors satisfying $qa \ll 1$ where a is the lattice constant G is expected to take on the asymptotic form (as $t \rightarrow 0$)

$$G(q, t) = Ct^{-\nu} D(q^2 \xi^2) \quad (1.2)$$

In the above, C is the amplitude of the susceptibility and ξ is the correlation length given by (as $t \rightarrow 0$)

$$\xi = fat^{-\nu} \quad (1.3)$$

where f is the amplitude of the second spatial moment of $G(\vec{R}, t) = \langle \vec{S}(\vec{R}) \cdot \vec{S}(\vec{0}) \rangle$. The function $D(x^2)$ has been determined for both large and small values of its argument by Fisher and Aharony¹ correct to $O(\epsilon^2)$. For $x \ll 1$ (i.e., in the uncorrelated region) they obtain the Ornstein-Zernike form

$$D(x^2) = \frac{1}{1+x^2} + O(\epsilon^2) \quad (1.4)$$

while for $x \gg 1$ (i.e., in the strongly correlated region) $D(x^2)$ can be written

$$D(x^2) \approx \frac{D_0^\infty}{x^{2-\eta}} + \frac{D_1^\infty}{x^{2-\eta+(1-\alpha)/\nu}} + \frac{D_2^\infty}{x^{2-\eta+1/\nu}} \quad (1.5)$$

where $D_0^\infty = 1 + O(\epsilon^2)$,

$$D_1^\infty = \left(\frac{n+2}{4-n} \right) + \left(\frac{n+2}{n+8} \right) \frac{(7n+20)}{(4-n)^2} \epsilon + O(\epsilon^2)$$

and

$$D_2^\infty = -\frac{6}{(4-n)} - \left(\frac{n+2}{n+8} \right) \frac{(7n+20)}{(4-n)^2} \epsilon + O(\epsilon^2)$$

Their calculations were done for $T > T_c$ and in the absence of an external field. Combescot *et al.*² then extended these calculations to the case of nonzero external field. Although these and other³ calculations gave detailed information about the small- and large- x behavior of $D(x^2)$, the properties of $D(x^2)$ for intermediate values of x remained unknown until Nelson⁴ obtained results for $D(x^2)$ valid for all x which properly reproduced the large- and small- x behavior. Although these results only exponentiated singular behavior to $O(\epsilon)$, comparisons with high-temperature series expansions were encouraging.

The purpose of this paper is to present calculations of the two-point correlation function for an n -component magnetic system coupled to an isotropic elastic medium. The methods used are similar to those employed by Nelson⁴ for the rigid system. A calculation including the effects of finite compressibility is worthwhile since a coupling between elastic and magnetic degrees of freedom can produce corrections to scaling behavior affecting two-point correlations and hence the analysis of scattering data. The paper is organized as follows. In Sec. II we review the model Hamiltonian and give solutions to renormalization-group⁵ (RG) recursion relations obtained from it. Section III contains a calculation of the correlation function with a discussion of the RG matching conditions. The large and small $q\xi$ behavior of the function is obtained explicitly and compared to the rigid system results. We also present results of numerical calculations which

display the dependence of G on both l and the strength of the magnetoelastic coupling. Section V contains a summary of results.

II. MODEL AND RECURSION RELATION SOLUTIONS

A model Hamiltonian useful for describing an n -component magnetic system coupled to an isotropic elastic medium is given in wave-vector space by^{6,7}

$$H_{\text{eff}}\left(\frac{H}{T}\right) = \frac{L^{-d}}{2} \sum_{i, \vec{k}} (r + k^2) S_{i, \vec{k}} S_{i, -\vec{k}} \\ + uL^{-3d} \sum_{i, j; \vec{k}_1, \vec{k}_2, \vec{k}_3} S_{i, \vec{k}_1} S_{i, \vec{k}_2} S_{j, \vec{k}_3} \\ \times S_{j, -(\vec{k}_1 + \vec{k}_2 + \vec{k}_3)} \\ + vL^{-3d} \left(\sum_{i, \vec{k}} S_{i, \vec{k}} S_{i, -\vec{k}} \right)^2, \quad (2.1)$$

where the $S_{i, \vec{k}}$ constitute a set of nN collective coordinates, N being the number of spins in volume L^d and the wave-vector sums are restricted to the interior of a spherical Brillouin zone of unit radius. The first two terms in Eq. (2.1) are the usual terms found in the Ginzburg-Landau-Wilson (GLW) Hamiltonian⁵ for a rigid magnetic system while the last term is a new mean-field-like interaction between the spins mediated by $\vec{k} = 0$ phonons. The properties of Eq. (2.1) under RG transformation in $d = 4 - \epsilon$ have been studied previously, and the results of these works along with solutions to the differential RG recursion relations are summarized in our earlier paper⁸ (hereafter referred to as I). The thermodynamic state of the system described by Eq. (2.1) is given by the fields r , u , and v and the set of differential RG recursion relations satisfied by these fields are given in I. The solutions⁸ are

$$r(l) = t(l) - \frac{1}{2}\lambda(l) + \frac{1}{2}t(l)\lambda(l)\ln[1+t(l)] + O(\epsilon^2), \quad (2.2a)$$

$$u(l) = ue^{\epsilon l}/Q(l) + O(\epsilon^2), \quad (2.2b)$$

$$v(l) = \frac{ve^{\epsilon l}}{Q(l)^{A/C}f(l)} + O(\epsilon^2), \quad (2.2c)$$

where $t(l) \equiv te^{2l}/f(l)$, $\lambda(l) \equiv Au(l) + Bv(l)$, $t \equiv r + \frac{1}{2}\lambda$, and the constants, A , B , and C are given by $A = (n+2)/2\pi^2$, $B = n/2\pi^2$, and $C = (n+8)/2\pi^2$. The functions $Q(l)$ and $f(l)$ are

$$f(l) = Q(l)^{A/C} [1 + G(Q(l)^{1-2A/C} - 1)],$$

$$Q(l) = 1 + (Cu/\epsilon)(e^{\epsilon l} - 1),$$

where $G = Bv/Cu(1 - 2A/C)$; λ , r , u , and v are the $l=0$ values of these quantities and l is the logarithm

of the spatial rescaling factor associated with the RG transformation. With these solutions at hand we now proceed to a calculation of the two-point correlation function.

III. CORRELATION FUNCTION AND RG MATCHING

The recursion relation method for calculating thermodynamic properties always involves making use of a scaling relation satisfied by the quantity of interest. In this case we use the relation⁹

$$G(q, \mu) = \exp\left[2l - \int_0^l \eta(l') dl'\right] G(e^l q, \mu(l)), \quad (3.1)$$

where the set of fields $\mu = \{r, u, v\}$ defines the thermodynamic state of the near-critical system and $\mu(l) = \{r(l), u(l), v(l)\}$ corresponds to the thermodynamic state of a system onto which we map the near-critical system. With a suitable choice for l , one may be able to map onto a system whose two-point correlation function is easily calculated which means, in practice, that perturbation theory is applicable. One possible choice for l is a value, say l^* , which makes $r(l^*) = 1$. This would make a calculation of $G(l^*)$ possible. The problem however with this choice is that, as pointed out by Nelson,⁴ it leads to technical difficulties because as $T \rightarrow T_c$ (i.e., as $t \rightarrow 0$) l^* grows very large (it is approximately given by $e^{l^*} \approx t^{-\nu}$) and since $e^l q$ must be bounded from above by unity this particular choice for l would only be useful for values of $q < e^{-l^*} \approx t^\nu$. This corresponds to values of $x = q\xi < 1$. Another possible choice for l^* is given by $q^2 e^{2l^*} = 1$. The difficulty with this choice is that for wave vectors too small l^* will grow so large ($e^{l^*} \approx q^{-1}$) that for a given bare t , $t(l^*)$ will become larger than unity invalidating the solutions given in Eqs. (2.2). Thus this l^* is only useful for values of $x = q\xi > 1$. In order to have results valid for any x we choose l^* by Nelson's compromise condition⁴

$$t(l^*) + e^{2l^*} q^2 = 1. \quad (3.2)$$

With this l^* and ignoring η since it is of $O(\epsilon^2)$ Eq. (3.1) becomes

$$G(q, \mu) = e^{2l^*} G(e^{l^*} q, \mu(l^*)). \quad (3.3)$$

We now need to calculate $G(e^{l^*} q, \mu(l^*))$ which may in fact be near critical depending on the values of μ and q . We write the Dyson equation¹⁰ for $G(e^{l^*} q, \mu(l^*))$ which is shown graphically in Fig. 1.

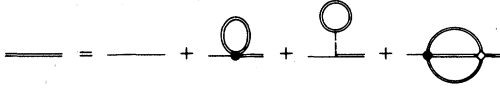


FIG. 1. Dyson equation for the two-point correlation function in terms of fully renormalized propagators and vertices. The broken line which carries no momentum is the bare v vertex while the solid dot and square are, respectively, the bare and fully renormalized four-point vertices u and u_R ($\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4; l$).

Analytically this reads

$$G^{-1}(e^l q, \mu(l^*)) = r(l^*) + e^{2l^*} q^2 + \frac{\lambda(l^*)}{K_4} \int \frac{d^d k}{(2\pi)^d} G(k, \mu(l^*)) , \quad (3.4)$$

where we have omitted the $O(\epsilon^2)$ terms in Eq. (3.4) since the condition (3.2) ensures that their contribu-

$$G(q, t, u^*, v) = e^{2l^*} \left[1 + \frac{\lambda(l^*) t(l^*)}{4K_4(4-n)u^*} [t(l^*)^{-(\epsilon/2)(4-n)/(n+8)} - 1] \right] , \quad (3.8)$$

where we have set $u = u^*$ for convenience (the fixed point we are referring to here is $F4$ of I — the rigid Heisenberg fixed point).

In order to remove the explicit l^* dependence from Eq. (3.8) we note that condition (3.2) with $u = u^*$ becomes

$$\frac{te^{\lambda_l l^*}}{(1-G)[1+Ge^{\lambda_v l^*}/(1-G)]} + e^{2l^*} q^2 = 1 . \quad (3.9)$$

This expression is more conveniently given in terms of the nonlinear scaling fields appropriate to this problem. With the definitions $g_t(l) = g_t e^{\lambda_l l}$ and $g_v(l) = g_v e^{\lambda_v l}$ we find that [cf. Eqs. (5.17) of I]

$$g_t = t/(1-G), \quad g_v = \frac{v/\epsilon}{1-G} . \quad (3.10)$$

$$G(q, t, u^*, v) = g_t^{-2\nu} \Phi^2 \left[1 + \left(\frac{n+2}{4-n} \right) \frac{\{1 + [6y/(n+2)]\Phi^{\lambda_v}\}}{(1+y\Phi^{\lambda_v})^2} \Phi^{\lambda_t} \left[\left(\frac{\Phi^{\lambda_t}}{1+y\Phi^{\lambda_v}} \right)^{-(\epsilon/2)(4-n)/(n+8)} - 1 \right] \right] . \quad (3.13)$$

Writing G in the form

$$G(q, t, u^*, v) \equiv g_t^{-\gamma} D(x, y) \quad (3.14)$$

and realizing that $\gamma = 2\nu + O(\epsilon^2)$ we obtain for $D(x, y)$

tions are less singular than those terms retained order by order in perturbation theory. The integral in Eq. (3.4) can be expressed in terms of the energy of a system in the thermodynamic state $\mu(l^*)$

$$E(\mu(l^*)) = -\frac{1}{2} n \int \frac{d^d k}{(2\pi)^d} G(k, \mu(l^*)) . \quad (3.5)$$

Since the energy of a compressible system was calculated in I we can carry over those results. We found that

$$E(r, u, v) = \frac{1}{8} n \frac{t}{u} \frac{1}{(4-n)} \left[\frac{F(t, u)^{1-2A/C} - 1}{1 + G(F(t, u)^{1-2A/C} - 1)} \right] , \quad (3.6)$$

where

$$F(t, u) \equiv 1 + (Cu/\epsilon)(t^{-\epsilon/2} - 1) . \quad (3.7)$$

Combining Eqs. (3.3)–(3.6) we find to leading order in ϵ

Making use of these results in Eq. (3.9) along with the substitution

$$e^{l^*} = g_t^{-\nu} \Phi(x, y) , \quad (3.11)$$

where $x \equiv qg_t^{-\nu}$ and

$$y \equiv n[(n+8)/2\pi^2(4-n)]g_v g_t^{-\phi_\nu} \quad (\phi_\nu = \nu\lambda_\nu = \alpha)$$

we obtain an equation satisfied by the function $\Phi(x, y)$

$$\frac{\Phi(x, y)^{\lambda_t}}{1+y\Phi(x, y)^{\lambda_v}} + x^2 \Phi(x, y)^2 = 1 . \quad (3.12)$$

Assuming that this equation can be solved for the function Φ we can now use Eq. (3.11) in the expression for G to obtain correct to $O(\epsilon)$

$$D(x,y) = \Phi^2 \left[1 + \left(\frac{n+2}{4-n} \right) \frac{\{1 + [6/(n+2)]y\Phi^{\lambda\nu}\}}{(1+y\Phi^{\lambda\nu})} \Phi^{\lambda_t} \left[\left(\frac{\Phi^{\lambda_t}}{1+y\Phi^{\lambda\nu}} \right)^{-(\epsilon/2)(4-n)/(n+8)} - 1 \right] \right] \quad (3.15)$$

We can now examine the small- and large- x behavior of $D(x,y)$. In doing this we will initially assume that $n > 4$ to avoid complications associated with a first-order transition (see I). In this case y is positive since g_ν is negative (the only physically admissible values of ν are negative ones). Furthermore, since $\alpha < 0$ for $n > 4$, y will go to zero with g_t . Using Eq. (3.12) we obtain an expansion of the function Φ in x for $x \ll 1$ of the form

$$\Phi(x,y) = \Phi_0(x,y) \left[1 + \frac{1}{2} \left(\frac{n+2}{n+8} \right) \epsilon \frac{\{1 + [6/(n+2)]y\}}{(1+y)^2} \Phi_0(x,y)^2 \ln \Phi_0(x,y) + O(\epsilon^2) \right], \quad (3.16)$$

where

$$\Phi_0(x,y) = [x^2 + 1/(1+y)]^{-1/2} \quad (3.17)$$

Substituting into Eq. (3.15) we obtain for $x \ll 1$

$$D(x,y) = \frac{1}{x^2 + 1/(1+y)} \left[1 + \frac{1}{2} \left(\frac{n+2}{n+8} \right) \epsilon \frac{\{1 + [6/(n+2)]y\}}{(1+y)^2} \frac{\ln(1+y)}{[x^2 + 1/(1+y)]} + O(\epsilon^2) \right] \quad (3.18)$$

In the case when $\nu \rightarrow 0$ ($y \rightarrow 0$) this reduces to the rigid system result. Similarly when x is set to zero in this expression one obtains the scaling function for the susceptibility.⁸ In the other extreme limit when $x \gg 1$ (deep within the critical region) the expansion of the function Φ is implemented by first writing

$$\Phi(x,y) = (1/x)\psi(w,z), \quad (3.19)$$

where $w \equiv x^{-1/\nu}$ and $z \equiv yx^{-\alpha/\nu}$. The equation for ψ is

$$\psi(w,z)^2 + \frac{\psi(w,z)^{\lambda_t}}{[1 + z\psi(w,z)^{\lambda\nu}]} = 1, \quad (3.20)$$

which can be expanded for small w (large x) to obtain

$$\psi(w,z) = \psi_0(w,z) \left[1 + \frac{\epsilon}{2} \left(\frac{n+2}{n+8} \right) \frac{w\{1 + [6/(n+2)]z\}}{(1+z)^2} \psi_0(w,z)^2 \ln \psi_0(w,z) + O(\epsilon^2) \right], \quad (3.21)$$

where

$$\psi_0(w,z) \equiv [1 + w/(1+z)]^{-1/2} \quad (3.22)$$

Substituting these results into Eq. (3.15) we obtain for $x \gg 1$

$$D(x,y) = \frac{1}{x^2} - \frac{1}{1+yx^{-\alpha/\nu}} \left[\frac{[6/(4-n)]y}{x^{2+(1+\alpha)/\nu}} + \frac{[6/(4-n)](1-y)}{x^{2+1/\nu}} - \frac{(n+2)/(4-n)}{x^{2+(1-\alpha)/\nu}} \right] \quad (3.23)$$

This expression can be studied in two different regimes. The variable y can be written $y = [(v/v_3^*)/(1-v/v_3^*)]g_t^{-\alpha}$ where v_3^* is the value of v at fixed point $F3$ of I. In the limit of stiff lattice and/or weak spin-lattice coupling we have $v/v_3^* \ll 1$ and $y \ll 1$. In this case the system's critical behavior is controlled for all g_t by the rigid Heisenberg fixed point ($F4$ of I) and Eq. (3.23) becomes

$$D(x,y) = \frac{1}{x^2} - \frac{[6/(4-n)]y}{x^{2+(1+\alpha)/\nu}} - \frac{[6/(4-n)](1-y)}{x^{2+1/\nu}} + \frac{(n+2)/(4-n)}{x^{2+(1-\alpha)/\nu}}, \quad (3.24)$$

where we have ignored $yx^{-\alpha/\nu}$ compared to unity. The second term above is due entirely to the lattice coupling and since $\alpha < 0$ it constitutes the leading correction to scaling. Note that when y is set to zero in Eq. (3.24) we recover the rigid system results of Fisher and Aharony¹ [neglecting the absence of η which is $O(\epsilon^2)$] with amplitudes correct to leading order in ϵ . The other regime is characterized by the inequality $[(v/v_3^*)/(1-v/v_3^*)]g_t^{-\alpha} \gg 1$. In this case the systems behavior is governed by fixed point $F3$ of I and Eq. (3.23) becomes

$$D(x,y) = \frac{1}{x^2} - \frac{6/(4-n)}{x^{2+1/\nu}} + \frac{6/(4-n)}{x^{2+(1-\alpha)/\nu}}, \quad (3.25)$$

where we have retained only terms which survive the $y \rightarrow \infty$ limit. This form for D will dominate for all $g_t > [(v/v_3^*)/(1-v/v_3^*)]^{1/\alpha}$. Since in the $y \rightarrow \infty$ limit the critical behavior is governed by fixed point $F3$ of I it is more appropriate to write the exponents in Eq. (3.25) (which are the exponents associated with the rigid Heisenberg fixed point) in terms of the exponents at fixed point $F3$. Making use of the relations⁷ $\alpha = \alpha' / (\alpha' - 1)$ and $\nu = \nu' / (1 - \alpha')$ where the primed exponents are associated with fixed point $F3$ we obtain

$$D(x,y) = \frac{1}{x^2} + \frac{6/(4-n)}{x^{2+1/\nu'}} - \frac{6/(4-n)}{x^{2+(1-\alpha')/\nu'}}. \quad (3.26)$$

This has the same form as that given by Eq. (3.24) with y set to zero. This is to be expected since the short-distance expansion makes no reference to a specific fixed point.

Although Eqs. (3.18) and (3.24) correctly describe, respectively, the small and large x behavior of $D(x,y)$ for $y \ll 1$ it is more interesting to solve Eq. (3.12) numerically for intermediate values of x interpolating between the analytical results. In these calculations we have taken $\epsilon = 1$ and $n = 5$. Setting $n = 5$ we ensure that $\alpha < 0$: an assumption we have made throughout. The results are given in Fig. 2 where we plot $G(q, t(0), u^*, v)$ for different values of v/v_3^* as a function of $t(0)$. Here $t(0) = [T - T_c(0)]/T_c(0)$ is the temperature scale reduced with respect to T_c of the rigid system. Each curve is labeled by its respective value of v/v_3^* and since the lattice coupling raises T_c from $T_c(0)$ the curves corresponding to successively larger values of v/v_3^* begin at higher values of $t(0)$. It is interesting to compare the compressible system with the rigid system at fixed $t(0) > 0$. Two point correlations are enhanced in the compressible system relative to those in the rigid system. Furthermore the relative enhancement appears to increase as $q \rightarrow 0$. These results are plausible since the presence of the lattice coupling tends to favor long-range order. The insets of Figs. 2(a) and 2(b) give an expanded view of the maxima appearing at finite $t(0)$ in the function G . These maxima which occur due to a competition between the second and third terms in the short-distance expansion [which in the rigid system are proportional to $t(0)$ and $t(0)^{1-\alpha}$] are qualitatively similar to the maxima appearing in the high-temperature series expansion results of Ritchie and Fisher¹¹ for the Heisenberg model. Although the positions of the maxima at fixed angle will depend on v we have only given an expanded view of the rigid system maximum since all the maxima are qualitatively similar in appearance.

IV. SUMMARY

We have calculated the two-point correlation function with singularities exponentiated to $O(\epsilon)$ in an

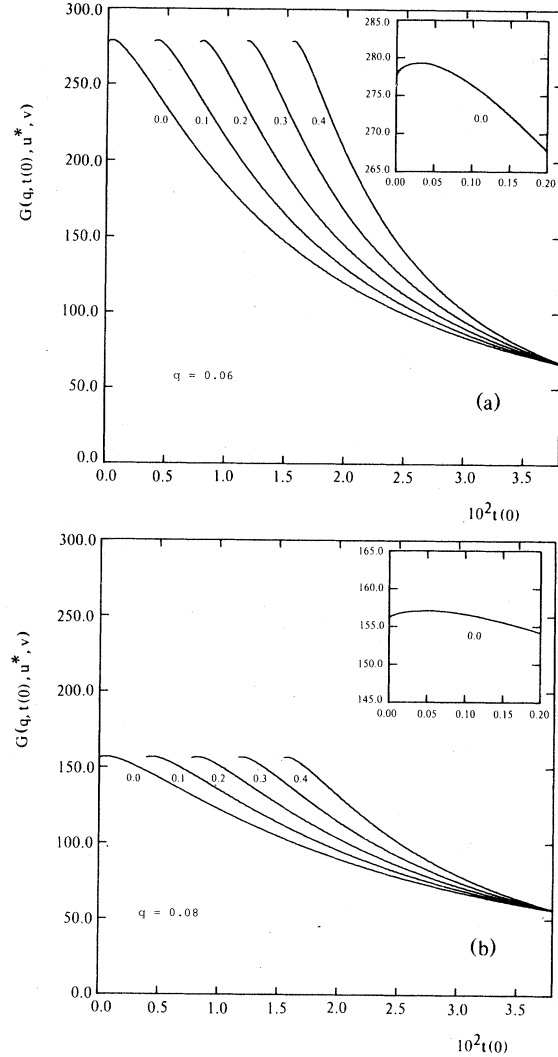


FIG. 2. Plot of $G(q, t(0), u^*, v)$ as a function of $t(0)$ for various values of v/v_3^* with (a) $q = 0.06$ and (b) $q = 0.08$. Here $t(0)$ is the temperature reduced with respect to T_c of the rigid system. Insets display expanded view of the maxima occurring in the rigid system curves for (a) $q = 0.06$ and (b) $q = 0.08$.

isotropic n -component compressible magnet for $T > T_c(v)$ and in the absence of an external field. We find that for $n > 4$ the lattice coupling produces a new correction to scaling in $G(q, t)$ which is more singular [it goes like $1/q^{(1+\alpha)/\nu}$] than the leading correction to scaling in the rigid system (which is proportional to $1/q^{1/\nu}$). The amplitude of this new correction to scaling is linear in $[T - T_c(v)]$ and the lattice coupling v . Although we have not explicitly given attention to the behavior of D when $n < 4$ and $\alpha > 0$, we believe that the analytical results given above can nevertheless be carried over. The only restriction on their use would be to exclude from con-

sideration values of $t \leq t_c$ where t_c is the temperature at which a first-order transition occurs. In the Ising model, for example, we find $t_c = \frac{3}{2} K_4 u^* e^{-1} \times (4|v|/3u^*)^{1/\alpha}$ (see I). A simplification in our analysis involved setting $u = u^*$ which was not necessary. Letting u be arbitrarily small, for instance, would allow for a calculation of the Gaussian to Heisenberg crossover scaling function for two-point correlations.¹² We have also omitted a detailed study

of the crossover behavior associated with the systems bare v being close to v_3^* (but still within the domain of attraction of the rigid Heisenberg fixed point).

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