

From observations to complexity of quantum states via unsupervised learning

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The vast complexity is a daunting property of generic quantum states that poses a significant challenge for theoretical treatment, especially in nonequilibrium setups. Therefore, it is vital to recognize states which are locally less complex and thus describable with (classical) effective theories. We use unsupervised learning with autoencoder neural networks to detect the local complexity of time-evolved states by determining the minimal number of parameters needed to reproduce local observations. The latter can be used as a probe of thermalization, to assign the local complexity of density matrices in open setups, and for the reconstruction of underlying Hamiltonian operators. Our approach is an ideal diagnostics tool for data obtained from (noisy) quantum simulators because it requires only practically accessible local observations.

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Finding a suited notion of the complexity of quantum many-body states is a key aspect of various lines of research on correlated quantum systems. Entanglement entropy has emerged as a highly relevant information-theoretic quantity in the case of pure states, that reveals universal features in exotic states of matter [1–6], in quantum many-body dynamics far from equilibrium [7,8], and it indicates the feasibility of classical computer simulations [9–11]. Recently, it has also been measured experimentally using cold atoms and trapped ions [12,13]. Generalizations of entanglement entropy applicable to mixed states have been proposed [14] and entanglement witnesses can detect entanglement [15], e.g., in experiments where entanglement entropy is inaccessible. An alternative perspective is that of quantum circuit complexity, which corresponds to the minimal size of a circuit to prepare the state of interest from a fiducial state [16–18].

Entanglement and circuit complexity, however, do not universally align with the physically relevant degree of complexity of many-body states. For example, although ergodic many-body systems quickly become highly entangled under unitary nonequilibrium dynamics, the late-time dynamics of physically relevant local observables is described by the hydrodynamic equations of motion of a few quantities [19–21]. Moreover, their eventual thermalization implies that a few thermodynamic quantities fully characterize local properties, and entanglement entropy turns into thermodynamic entropy of subsystems. Since typical initial states are weakly entangled, it is expected that in terms of “local complexity” associated with local observables, the nonequilibrium dynamics typically passes an “information barrier” at intermediate times. Such a “barrier” has been identified by considering the operator entanglement entropy evolution in closed and

open quantum systems [22–26] and the envisioned time dependence of the local quantum state complexity is depicted schematically in Fig. 1.

This Letter introduces an approach to analyze the local complexity of quantum many-body states based on recently developed machine learning techniques. At the core, we employ deep autoencoder networks [27], which we train in an unsupervised fashion with observable expectation values, in order to obtain a dimensional reduction enabling us to assess the effective complexity of the quantum state of interest. We address different regimes of the nonequilibrium dynamics of open and closed quantum systems, which are indicated in Fig. 1 by the different background shadings. This Letter is structured such that we progress from (i) the infinite-time limit over (ii) practically attainable steady states at late finite times to (iii) the “information barrier” itself at intermediate and short times. Following this order, we can first test our approach in a controlled setting by assigning the local complexity of thermodynamic ensembles; these are idealized

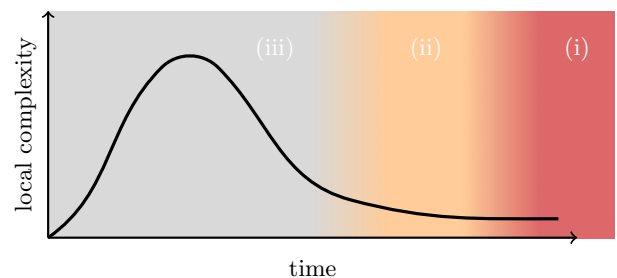


FIG. 1. Schematic picture of the “information barrier” of quantum many-body dynamics. The different shaded areas illustrate the logical structure of this Letter. We address (i) infinite-time steady states, (ii) practically attainable states at late but finite times, and (iii) short to intermediate times, where the “information barrier” is crossed.

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local descriptions of steady states of chaotic or integrable models [28–30]. Then, we investigate the dynamical approach of a weakly dissipative system to such states in terms of our complexity measure. For nearly integrable systems, the absence of thermalization despite weak integrability breaking sources is a nontrivial effect [31–35], which can be detected with the unsupervised learning approach. Finally, we reveal an “information barrier” at intermediate times by analyzing the time-dependent local complexity in random unitary dynamics, which has in many recent works been proven to be a useful model to analyze typical features of nonequilibrium dynamics [26,36–46]. Besides the assertion of complexity, we demonstrate how further information about effective descriptions can be extracted, e.g., to reconstruct Hamiltonians for thermal states.

Being based on local observations, this approach is suited to exploit highly resolved observations of many-body quantum systems that are possible in modern quantum simulators [12,47–53].

Autoencoder. The autoencoder [27] is an artificial neural network consisting of multiple layers. The input and output layers have the same dimension, and at least one of the additional layers between the two constitutes a “bottleneck” with a considerably smaller number of N_L neurons, spanning the N_L dimensional latent space. The part prior to the bottleneck is called *encoder*, and the subsequent part is the *decoder*; see Fig. 2(a). Deep learning with autoencoder neural networks has previously been explored as a tool to investigate a variety of physical problems. Examples are unsupervised discovery of physical concepts [54,55], the identification of entangled states [56], encoding of quantum many-body states [57], or the exploration of relations to nonequilibrium statistical mechanics [58].

Here, the objective of an autoencoder is to reconstruct the input data \mathbf{x} given by local observations, despite the intermediate compression in the bottleneck. For this purpose, the reconstruction loss,

$$\mathcal{L}_{\mathcal{D}_T}(\boldsymbol{\theta}) = \frac{1}{|\mathcal{D}_T|} \sum_{\mathbf{x} \in \mathcal{D}_T} [f_{\boldsymbol{\theta}}(\mathbf{x}) - \mathbf{x}]^2, \quad (1)$$

over a training data set \mathcal{D}_T is minimized by optimizing the variational parameters $\boldsymbol{\theta}$ of the neural network $f_{\boldsymbol{\theta}}$. Thereby, the encoder learns to map the input data to a suited low-dimensional *latent representation*, which holds the necessary information for the decoder to recover the original input \mathbf{x} . Achieving a small reconstruction loss depends on the existence of such a low-dimensional representation, and too narrow bottlenecks lead to a larger loss $\mathcal{L}_{\mathcal{D}_T}$. Therefore, the effective dimensionality of a data set can be analyzed by varying the bottleneck width and comparing the corresponding reconstruction errors. This analysis should be conducted with validation data that were not used for training to exclude overfitting; we will call the reconstruction error (1) evaluated on the test data, the *test error*. Details about the network architecture and optimization are included in the Supplemental Material (SM) [59].

Training data. In the exemplary applications below we consider quantum spin- $\frac{1}{2}$ chains, with composite Hilbert spaces $\mathcal{H} = \bigotimes_l h_l$, where $\dim(h_l) = 2$ and l is the lattice site in-

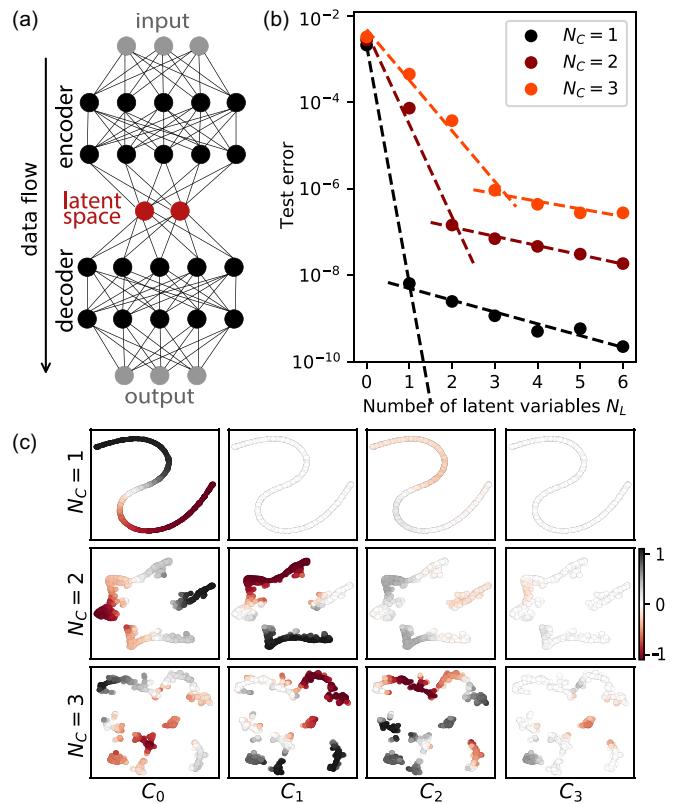


FIG. 2. (a) Schematic depiction of the neural autoencoder network. (b) Test error as a function of the number of latent variables obtained by training on the transverse-field Ising model data from (generalized) Gibbs ensembles with a varying number of charges N_C . Dashed lines are linear fits included as a guide for the eye. (c) t -SNE of the latent representation of (G)GEs with different numbers of charges N_C and $N_L = 4$. Color coding in each column is according to expectation values $\langle \hat{C}_i \rangle / N$ of charges, denoted in the bottom. Parameters: $N = 12$, $h_x = 0.6J$, $h_z = 0$.

dex. As input for the encoder, we use data sets, where each element consists of the expectation values of all possible operator strings up to a fixed compact support \mathcal{S} , i.e., $O_\rho(\boldsymbol{\alpha}) = \text{Tr}[\hat{\rho} \hat{\sigma}_1^{\alpha_1} \cdots \hat{\sigma}_{|\mathcal{S}|}^{\alpha_{|\mathcal{S}|}}]$ with density matrix $\hat{\rho}$, and $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_{|\mathcal{S}|}) \in \{0, x, y, z\}^{|\mathcal{S}|}$ and $\hat{\sigma}_i^{0,x,y,z}$ denoting the identity and the Pauli matrices, respectively. Measuring these observables amounts to a full tomography of the reduced density matrix of the subsystem \mathcal{S} . While the corresponding cost grows exponentially with subsystem size $|\mathcal{S}|$, we show in our examples that already moderate supports $|\mathcal{S}| = 3, 4$ are informative of the local complexity; for larger supports it might be useful to employ the recently proposed classical shadow techniques [13,60,61].

In our analysis, we consider families of quantum states $\hat{\rho}_\lambda$ parametrized by a potentially high-dimensional parameter λ . Individual training data elements are given by observations $\{O_{\rho_\lambda}(\boldsymbol{\alpha}) | \boldsymbol{\alpha} \in \{0, x, y, z\}^{|\mathcal{S}|}\}$ for sampled parameters λ . By optimizing the reconstruction objective (1) with autoencoder networks, we gain insights about the effective local complexity of $\hat{\rho}_\lambda$ that is relevant for local observations. The complexity is quantified through the number of latent variables required for faithful reconstruction according to Eq. (1). For this

procedure it is crucial to exhaustively sample the space of states $\hat{\rho}_\lambda$ in order to avoid detecting spurious low-dimensional representations.

Idealized steady states of closed systems and Hamiltonian reconstruction. As a first test bed, we consider (generalized) Gibbs ensembles [(G)GEs] of the spin- $\frac{1}{2}$ quantum Ising model (QIM)

$$\hat{H} = \sum_j (J\hat{\sigma}_j^z\hat{\sigma}_{j+1}^z + h_x\hat{\sigma}_j^x + h_z\hat{\sigma}_j^z), \quad (2)$$

relevant for quantum simulators [51,52,62–65]. For $h_z = 0$, the QIM (2) is integrable, featuring an extensive set of mutually commuting local charges \hat{C}_i (see SM [59]), one of which is the Hamiltonian [66]. Conservation laws play a crucial role in the long-time description of excited integrable/chaotic systems [Fig. 1(i)], when reduced density matrices become indistinguishable from GGEs/GEs of the form [28–30]

$$\hat{\rho}_\lambda = \frac{e^{\sum_i \lambda_i \hat{C}_i}}{\text{Tr}[e^{\sum_i \lambda_i \hat{C}_i}]}. \quad (3)$$

Although long-time states show volume law entanglement entropy [7,67], local observables are (for most practical purposes) determined by a few Lagrange parameters λ_i . Our goal is to detect these simple parametrizations.

To benchmark the utility of our approach to analyze such characteristics of long-time states [Fig. 1(i)], we do not perform an actual time evolution but instead generate training data from GGEs with randomly drawn Lagrange multipliers $\lambda_i \in [-2, 2]$ using exact diagonalization techniques for the QIM (2) at $h_x = 0.6J$, $h_z = 0$ with system size $N = 12$. Each sampled λ yields a training data element with expectation values of all Pauli strings up to support $|\mathcal{S}| = 3$, and we separate these samples into training and test sets (see SM [59]). Figure 2(b) displays the test errors [Eq. (1)] achieved after training for different numbers of charges N_C included in the GGEs. We see that the error drops rapidly with an increasing number of latent variables N_L as long as $N_L < N_C$; for $N_L \geq N_C$ the curves level off in all cases. This behavior of the test error is expected because N_C is the minimal number of independent variables needed for encoding the GGE data. The change of slope becomes more distinct with larger training data sets [59].

In Fig. 2(c) we employ t -distributed stochastic neighbor embedding (t -SNE) [68] to visualize what the autoencoder learned to encode in its latent space. The t -SNE is a dimensional reduction technique, where the proximity of data points in the resulting low-dimensional representation is determined based on their Euclidian distance in the original space. The position of each point corresponds to the latent representation of one set of observations. The color code indicates the corresponding expectation value of the different charges. For $N_C = 1$, we find that also for a higher-dimensional latent space, $N_L > N_C$, the latent representation of observations lies on a one-dimensional manifold with energy density monotonously changing along it. When including more charges, we see that the dimensionality of the latent representation grows. For $N_C > 1$, the locations of extremal regions of the color code reveal that each charge can be associated with a different direction in the latent space. This indicates that the unsupervised

learning procedure yielded an encoding directly related to the physical charges. In the SM [59], we show that the learned representation is connected to the charges through an invertible map, which is sufficient for an unambiguous encoding of the data.

Having demonstrated the possibility to identify and analyze ideal (G)GE states, we next turn to genuine late-time states [Fig. 1(ii)]. To add some additional structure to these states, we perform time evolution with respect to open quantum systems. As we show in the following, the local complexity of late-time states in closed and weakly open systems share many properties.

Steady states of open systems. Here, we characterize steady states of open systems described by the Liouville equation

$$\dot{\hat{\rho}} = i[\hat{\rho}, \hat{H}] + \epsilon \sum_{j,\gamma} \left(\hat{L}_j^{(\gamma)} \hat{\rho} \hat{L}_j^{(\gamma)\dagger} - \frac{1}{2} \{ \hat{L}_j^{(\gamma)\dagger} \hat{L}_j^{(\gamma)}, \hat{\rho} \} \right), \quad (4)$$

with couplings to nonequilibrium baths represented by Lindblad operators $\hat{L}_j^{(\gamma)}$. The strength of the Markovian part is parametrized by ϵ . In direct relation with the previous section, at a weak coupling to dissipators, $\epsilon \ll 1$, steady states for a chaotic (integrable) \hat{H} can be approximated with (G)GEs [Eq. (3)] which are corrected by a small $\delta\hat{\rho}(\epsilon)$, $\hat{\rho} \propto \hat{\rho}_\lambda + \delta\hat{\rho}(\epsilon)$. For an integrable \hat{H} , the absence of thermalization despite weak integrability breaking sources is a nontrivial effect observed in weakly open systems [31–35].

In this context, the unsupervised learning approach enables us to address several natural questions. For the integrable \hat{H} , we will utilize our approach to detect how many conservation laws must be considered to reproduce local observables—a question often raised in quench protocols in closed setups. For the chaotic \hat{H} , we will examine the effect of noise as of relevance for quantum simulators that are never completely isolated.

The Hamiltonian \hat{H} is again the QIM [Eq. (2)] while the Lindblad dissipators for different data elements are randomly rotated single- and two-site operators (see SM [59]). The exact form of $\hat{L}_j^{(\gamma)}$ is not important, but sufficient randomness in either the form or the relative dissipation rates is needed to have a diverse enough training set. Figure 3 shows results for steady states obtained using the time-evolving block decimation technique [69,70] for vectorized density matrices on systems of size $N = 40$, using bond dimension $\chi = 100$. For $|\mathcal{S}| = 4$, we plot the test error as a function of the number of latent variables for different strengths of coupling to Markovian baths ϵ and for Hamiltonians that are either integrable or nonintegrable.

At a weak coupling to baths $\epsilon = 0.001$ and chaotic \hat{H} the test error levels off at $N_L \approx 2$ [Fig. 3(a)]. In the SM [59], we show that the single latent variable, which already reaches high accuracy, again corresponds to the energy, confirming that Gibbs ensembles approximate density matrices. Further latent variables capture information about $\delta\hat{\rho}(\epsilon)$ corrections. We find that observables strongly and monotonously varying along the perpendicular direction of the t -SNE representation are related to the features of the baths, i.e., the correlations that baths promote (see SM [59]). This could be used for the detection of noise type, as relevant for quantum error correction.

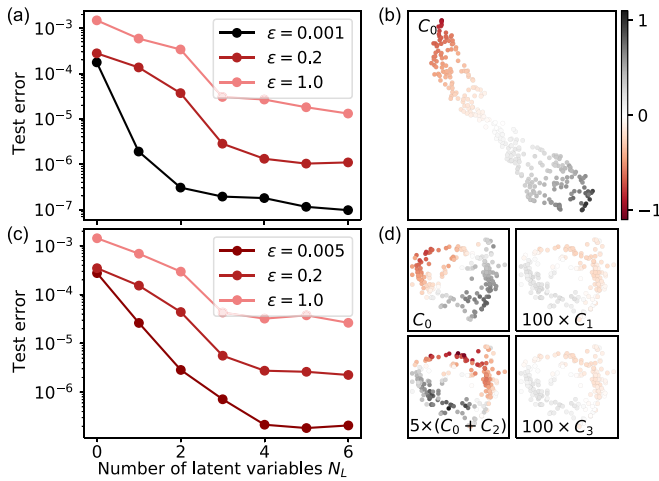


FIG. 3. Results obtained by training on data from steady states for setups with different strengths of openness ϵ [Eq. (4)] for chaotic (top) and integrable (bottom) \hat{H} . (a), (c) Test error as a function of the number of latent variables. (b) t -SNE of the latent representation for chaotic \hat{H} and $\epsilon = 0.001$, $N_L = 5$. Color coding is with respect to the energy density. (d) t -SNE of the latent representation for integrable \hat{H} and $\epsilon = 0.005$, $N_L = 5$. Color coding is with respect to the (rescaled) densities of charges written in the inset. The gradient in the coloring with respect to $(5/N)(\hat{C}_0 + \hat{C}_2)$ is roughly perpendicular to the gradient of $\langle \hat{C}_0 \rangle / N$. For our choice of Lindblads, inversion nonsymmetric $\hat{C}_{1,3}$ show much smaller expectation values, i.e., not comparable to $\langle \hat{C}_0 \rangle / N$ even upon rescaling with 100 and are thus not so crucial for an approximate description. Parameters: $N = 40$, $h_x = 1.152J$, $h_z = 0.974J$ (top), and $h_x = 1.352J$ (bottom).

For integrable \hat{H} [Fig. 3(c)] more than one latent variable is needed even for an approximate description. The t -SNE in Fig. 3(d) reveals that the first two latent variables are related to linear combinations of the two most local inversion symmetric charges $\hat{C}_0 = \hat{H}$ and \hat{C}_2 , confirming that GGEs approximately describe steady states [31–33]. Furthermore, our approach exposes that of macroscopically many conservation laws, only two of which are particularly relevant for an approximate description of all local observables with support up to $|\mathcal{S}| = 4$. Further latent variables are for corrections $\delta\hat{\rho}(\epsilon)$. At stronger $\epsilon = 0.2, 1.0$, a larger number of latent variables is necessary. Hence, for our choice of Lindblad operators, there is no simple emergent description.

Random unitary evolution and information bottleneck. Finally, we study the local complexity at intermediate times [Fig. 1(iii)] by analyzing states evolved by random unitary dynamics. Random unitary circuits have recently received substantial interest because they allow the analysis of typical features of nonequilibrium dynamics [26,36–46]. We will now show that in combination with our unsupervised learning of local complexity, they provide suited grounds to explore the information barrier, appearing at intermediate times in the time evolution from simple (product) states. To detect the information barrier, a detour away from Hamiltonian dynamics is necessary, in order to add a random component to the time evolution. From the perspective of the autoencoder, states that are obtained through deterministic dynamics starting from the few-parameter family of product states have a constant

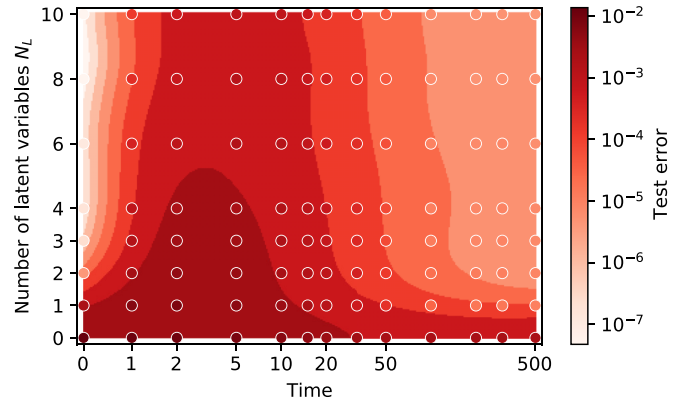


FIG. 4. Complexity during random unitary evolution of $N = 20$ spins captured by the autoencoder network. Starting from a simple product state, an intermediate regime of high complexity is traversed before an effective one-dimensional description emerges at late times due to the presence of a conserved charge. For times $t > 1$ the scale is logarithmic. Data points (colored dots) are augmented by discretized heat map based on a bivariate B -spline interpolation.

complexity: The fixed unitary map can be absorbed in the encoder/decoder of the network such that a few-parameter representation is possible at all times. On the other hand, the effective reduction of complexity at late times could also be studied under Hamiltonian dynamics when considering a higher-dimensional manifold of initial states.

Our model of random unitary evolution is based on an alternating application of two-site gates on even and odd links of the spin chain. The unitary gates vary randomly from step to step, but they are homogeneous across the chain to preserve translational symmetry. Moreover, we choose the unitaries to be $U(1)$ symmetric to impose magnetization as a single conserved quantity. Building on the results of the previous sections, we anticipate that a single Lagrange multiplier associated with the magnetization conservation will locally characterize states at late times. The initial states are random translationally invariant product states. At each time step, we measure all operators with support $|\mathcal{S}| = 3$ and train the autoencoder with different N_L -dimensional bottlenecks. See SM [59] for details.

Figure 4 displays the test errors that we find as a function of time and number of latent variables. The full description of the initial product state by two Bloch angles is reflected in very small test errors when using two or more latent variables. At late times a single latent variable is sufficient for faithful reconstruction, consistent with convergence to a reduced density matrix corresponding to an ensemble fully characterized by a single Lagrange multiplier. At intermediate times, however, the reconstruction error becomes large even for rather wide bottlenecks because the generic dynamics modeled by random unitary circuits generates complex quantum states, for which no effective low-dimensional parametrization exists. In that sense, our unsupervised learning approach probes the information barrier of quantum many-body dynamics. This concept of local complexity should, on the other hand, not be mistaken for the circuit complexity, which generically grows as a function of the random circuit depth [18].

Hamiltonian reconstruction. When our approach reveals that the data have a (near) one-dimensional latent representation [such as seen in the top of Figs. 2(c) or 3(b)], presumably corresponding to thermal states ρ , this connection can be exploited to reconstruct \hat{H} , as we outline now for the translationally invariant case. We first single out operators $\hat{O}(\alpha) \equiv \hat{O}_{j=1}(\alpha) = \hat{\sigma}_1^{\alpha_1} \cdots \hat{\sigma}_{|S|}^{\alpha_{|S|}}$ for which we measure a large average gradient of $O_\rho(\alpha) = \text{Tr}[\hat{\rho} \hat{O}(\alpha)]$ along the effective one-dimensional latent manifold, spanned by different temperatures. These are candidate Hamiltonian terms $\hat{H} = \sum_{j,\alpha} a_\alpha \hat{O}_j(\alpha)$. Using Newton's method or similar, we find coefficients a_α up to a scaling factor from the conditions $\text{Tr}[\hat{O}(\alpha) e^{\sum_{j,\alpha} a_\alpha \hat{O}_j(\alpha)}] / \text{Tr}[e^{\sum_{j,\alpha} a_\alpha \hat{O}_j(\alpha)}] - O_\rho(\alpha) = 0$. Testing this approach with the data presented in Fig. 2, h_x/J is reconstructed within the accuracy of the Newton's method. Using the data in Fig. 3(b) for $\epsilon = 0.001$, the relative strength of the fields is obtained within 5% and 1% for h_x/J and h_z/J , respectively. See the SM [59] for more information on the algorithm. In contrast to other methods [71–74], our approach is unsupervised and relies only on expectation values.

Discussion. We have introduced an unsupervised learning approach that reveals information about the existence of effective low-dimensional descriptions of many-body quantum states. Although no domain knowledge is provided during optimization, we showed for some examples how physical information can be extracted from the trained autoencoders. In that sense, our results constitute a step towards interpretable machine learning of physics.

An alternative to our approach is the analysis of the intrinsic dimension of the data sets [68,75–85]. In the SM [59] we include a corresponding analysis of our data as a reference. While the results are consistent, the autoencoder method

seems more robust, and it has the advantage to reveal further information beyond the minimal number of independent variables.

Autoencoders could be used, for example, to detect GGEs in weakly open trapped-ion setups [33]. Natural extensions of the present work could be the investigations of Floquet prethermal plateaus and of thermalization in strongly disordered many-body systems. Our method could complement the recent proposal to use supervised or confusion learning based on observations from cold atom experiments [86]. In the SM [59], we give evidence that autoencoders can be used for noise-type recognition, relevant for quantum error correction, which opens another exciting direction. Finally, interesting questions to explore are the possibilities of learning with incomplete or imperfect observations. In that regard, refinements of the deep learning model might be required, e.g., the utilization of variational autoencoders for resilience against noise [87].

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