





Fermion sign bounds theory in quantum Monte Carlo simulation

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Sign problems in fermion quantum Monte Carlo (QMC) simulation appears to be an extremely hard problem. Traditional lore passing around for years tells people that when there is a sign problem, the average sign in QMC simulation approaches zero exponentially fast with the space-time volume of the configurational space. We, however, analytically show this is not always the case and manage to find physical bounds for the average sign. Our understanding is based on a direct connection between the sign bounds and a well-defined partition function of the reference system and could distinguish when the bounds have the usual exponential scaling and when they are bestowed on an algebraic scaling at the low-temperature limit. We analytically explain such algebraic sign problems found in flat-band moiré lattice models at the low-temperature limit. At finite temperature, a domain-size argument based on sign bounds also explains the connection between sign behavior and finite-temperature phase transition. Sign bounds, as a well-defined observable, may have the ability to ease or even make use of the sign problem.

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I. INTRODUCTION

Quantum Monte Carlo (QMC) is a standard and unbiased method for studying strongly correlated systems, widely used in condensed-matter, high-energy, and quantum-material research [1–4]. However, in reality, very often due to inadequate choices of basis, QMC simulations suffer from the so-called sign problem [5–7], in which configurational weights become negative or even complex and can no longer be interpreted as classical probabilities. It has been proven that if the nondeterministic polynomial hard problem can be solved efficiently, then the obtained scheme can be used to solve the sign problem [8], so many interesting and fundamental questions in quantum many-body systems will be understood thereafter. Unfortunately, this has not happened yet.

Even though lacking a general guiding principle, many successful efforts have been done in finding systems without sign problems [9–21], methods to alleviate sign problems [22–37], origins of sign problems [8,38–45], and connection of sign problems with phase transitions [46–48]. While there have been some attempts for bosonic models in linking the average sign with the ratio of two partition functions [5,25,49], at the zero temperature limit, the requirement that two ground states are the same is too strict and the sign problem is also either none or exponential. For fermionic systems, it is even

harder to find a system with the same decoupled space and ground states because of the involved determinant. Past experience and arguments from those case-by-case efforts tells us if there is a sign problem in QMC simulation, then the average sign will scale exponentially fast to zero with the space-time volume. But in our recent attempts of model design and QMC solutions for flat band moiré lattice models at integer filling both for real [50], and momentum space [51], interesting outliers, where the average sign scales algebraically with system size and is independent with temperature at low temperature limit, were discovered. These results challenge conventional thought and urge a new understanding on universal properties of sign problems.

To understand the behavior of the average sign, we suggest an observable called sign bounds which is basically the ratio of two related well-defined partition functions. With this tool, we may unveil bound behavior of the average sign analytically by studying ground state degeneracy (GSD) and ground state energy (GSE) and roughly estimate finite temperature phase transition point.

We organize this paper as below: First, we review determinant QMC and sign problem taking momentum space version as example. Then, we introduce sign bounds as an observable in sign bounds theory by suggesting two reference systems, and identify the situation where they can be used, respectively, by delivering two corollaries. We also give three cases related with flat band moiré materials [50,52–55], where average signs are all algebraic scaling with size at low temperature and the decay behavior of sign bounds is achieved exactly

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for any given size. Raising operator construction and tensor Young tableau method are used to derive the GSD analytically (see Appendixes B and C for details), which of course can be extended to count GSD for other $SU(n)$ symmetry systems. Numerical QMC results for computing small-size GSD as shown in Fig. 3(a) affirmed our derivation. Next, we point out sign bounds is also useful at finite temperature. Even though we cannot derive this part analytically due to lacking detailed knowledge of partition function at finite temperature, an argument based on domain size can be used to roughly distinguish the finite temperature phase transition point. Finally, we conclude our results and discuss the inspiration behind sign bounds theory.

II. DETERMINANT QMC ALGORITHM AND SIGN PROBLEM

First, we introduce the background of how determinant QMC works by following the momentum space version in Ref. [52]. The interaction Hamiltonian can be written as

$$H = \sum_{q \neq 0} V(q) \rho_q \rho_{-q},$$

$$\rho_q = \sum_{k_1, k_2, m, n} \left(\lambda_{k_1, k_2, m, n}(q) c_{k_1, m}^\dagger c_{k_2, n} - \frac{1}{2} \mu_q \right). \quad (1)$$

Here, $V(q)$ is the Fourier transformation of any real space potential, λ is the unitary transformation form factor of projecting interaction from the plane-wave basis to kinetic term diagonalized band basis. μ_q can be any constant number from projecting chemical potential terms. k_1, k_2 are used to label momentum and m, n are used to label bands or any other freedom, e.g., spins or valleys. According to the discrete Hubbard-Stratonovich (HS) transformation, $e^{\alpha \hat{O}^2} = \frac{1}{4} \sum_{l=\pm 1, \pm 2} \gamma(l) e^{\sqrt{\alpha} \eta(l) \hat{O}} + O(\alpha^4)$, where α is a small constant number, \hat{O} can be any operator, $\gamma(\pm 1) = 1 + \frac{\sqrt{6}}{3}$, $\gamma(\pm 2) = 1 - \frac{\sqrt{6}}{3}$, $\eta(\pm 1) = \pm \sqrt{2(3 - \sqrt{6})}$, and $\eta(\pm 2) = \pm \sqrt{2(3 + \sqrt{6})}$. We can rewrite the partition function as

$$Z = \text{Tr} \left\{ \prod_{\tau} e^{-\Delta \tau H(\tau)} \right\}$$

$$= \text{Tr} \left\{ \prod_{\tau} e^{-\Delta \tau \sum_{q \neq 0} \frac{V(q)}{2} [(\rho_{-q} + \rho_q)^2 - (\rho_{-q} - \rho_q)^2]} \right\}$$

$$\approx \sum_{\{l_{|q|, \tau}\}} \prod_{\tau} \left[\prod_{|q| \neq 0} \frac{1}{16} \gamma(l_{|q|, \tau}) \gamma(l_{|q|, 2, \tau}) \right]$$

$$\times \text{Tr} \left\{ \prod_{\tau} \left[\prod_{|q| \neq 0} e^{i \eta(l_{|q|, \tau}) A_q (\rho_{-q} + \rho_q)} e^{\eta(l_{|q|, 2, \tau}) A_q (\rho_{-q} - \rho_q)} \right] \right\}. \quad (2)$$

Here τ is the imaginary time index with step $\Delta \tau$, $A_q = \sqrt{\frac{\Delta \tau V(q)}{2}}$ and $\{l_{|q|, 1, \tau}, l_{|q|, 2, \tau}\}$ are the four-component auxiliary fields. By defining $P(\{l_{|q|, \tau}\}) \equiv \prod_{\tau} \left[\prod_{|q| \neq 0} \frac{1}{16} \gamma(l_{|q|, 1, \tau}) \gamma(l_{|q|, 2, \tau}) \right]$ and $D(\{l_{|q|, \tau}\}) \equiv \text{Tr} \left\{ \prod_{\tau} \left[\prod_{|q| \neq 0} e^{i \eta(l_{|q|, \tau}) A_q (\rho_{-q} + \rho_q)} e^{\eta(l_{|q|, 2, \tau}) A_q (\rho_{-q} - \rho_q)} \right] \right\}$, one can

see partition function Z as a sample average for $D(\{l_{|q|, \tau}\})$ with configuration weight $P(\{l_{|q|, \tau}\})$:

$$Z = \sum_{\{l_{|q|, \tau}\}} P(\{l_{|q|, \tau}\}) D(\{l_{|q|, \tau}\}). \quad (3)$$

Since $P(\{l_{|q|, \tau}\})$ here comes from a continuous HS transformation coefficient (i.e., $\frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2}$ in $e^{\alpha \hat{O}^2} = \frac{1}{\sqrt{2\pi}} \int e^{-\frac{1}{2}x^2} e^{\sqrt{2\alpha} x \hat{O}} dx$), it has already been normalized and only depends on configuration. Even though there is no sign problem for sampling this partition function as all configuration weights $P(\{l_{|q|, \tau}\})$ are non-negative, this sampling is extremely time consuming since one can see the weight here is just a Gaussian distribution and contains no information for the physical system. But it is still useful, e.g., to determine small-size GSD to benchmark the analytical method as shown in Fig. 3(a).

Now, we focus ourselves on how to compute an observable by QMC. Ensemble average of any observable \hat{O} can be written as

$$\langle \hat{O} \rangle = \frac{\text{Tr}(\hat{O} e^{-\beta H})}{\text{Tr}(e^{-\beta H})}$$

$$= \sum_{\{l_{|q|, \tau}\}} \frac{P(\{l_{|q|, \tau}\}) \text{Tr}[\prod_{\tau} \hat{B}_{\tau}(\{l_{|q|, \tau}\})] \frac{\text{Tr}[\hat{O} \prod_{\tau} \hat{B}_{\tau}(\{l_{|q|, \tau}\})]}{\text{Tr}[\prod_{\tau} \hat{B}_{\tau}(\{l_{|q|, \tau}\})]}}{\sum_{\{l_{|q|, \tau}\}} P(\{l_{|q|, \tau}\}) \text{Tr}[\prod_{\tau} \hat{B}_{\tau}(\{l_{|q|, \tau}\})]}. \quad (4)$$

Here $\hat{B}_{\tau}(\{l_{|q|, \tau}\}) = \prod_{|q| \neq 0} e^{i \eta(l_{|q|, 1, \tau}) A_q (\rho_{-q} + \rho_q)} e^{\eta(l_{|q|, 2, \tau}) A_q (\rho_{-q} - \rho_q)}$. Now, we see $W_l = P(\{l_{|q|, \tau}\}) \text{Tr}[\prod_{\tau} \hat{B}_{\tau}(\{l_{|q|, \tau}\})]$ as possibility weight and $\langle \hat{O} \rangle_l = \frac{\text{Tr}[\hat{O} \prod_{\tau} \hat{B}_{\tau}(\{l_{|q|, \tau}\})]}{\text{Tr}[\prod_{\tau} \hat{B}_{\tau}(\{l_{|q|, \tau}\})]}$ as sample value for configuration $\{l_{|q|, \tau}\}$. Then the Markov chain Monte Carlo can compute this $\langle \hat{O} \rangle$. That is how determinant QMC works in a sign problem free case (i.e., W_l is real and $W_l \geq 0$ for all configurations). But this is not the case most of the time. With the sign problem, one can still simulate according to QMC by reweighting [5]:

$$\langle \hat{O} \rangle = \frac{\sum_l W_l \langle \hat{O} \rangle_l}{\sum_l W_l} = \frac{\sum_l |\text{Re}(W_l)| \frac{W_l \langle \hat{O} \rangle_l}{|\text{Re}(W_l)|}}{\sum_l |\text{Re}(W_l)|} \equiv \frac{\langle \hat{O} \rangle_{|\text{Re}(W_l)|}}{\langle \text{sign} \rangle}. \quad (5)$$

Here Re is taking the real part operator. One can see $|\text{Re}(W_l)|$ as a well-defined possibility weight and $\langle \hat{O} \rangle_{|\text{Re}(W_l)|}$ is the measurement result according to this weight. The ratio $\frac{\sum_l W_l}{\sum_l |\text{Re}(W_l)|}$ is the average sign $\langle \text{sign} \rangle$ we keep talking about. One can see if $\langle \text{sign} \rangle$ is exponentially small, fluctuation of computing $\langle \hat{O} \rangle$ from $\langle \hat{O} \rangle_{|\text{Re}(W_l)|}$ will be exponentially large, which causes the so-called sign problem. To understand the sign behavior, one may interpret $\sum_l |\text{Re}(W_l)|$ as an effective partition function [5]. But most of time, this partition function is not well-defined, which means we cannot write it back to a physical system before decomposition, as shown in Fig. 1. This is basically because we can hardly write the absolute value for the real part of a determinant with another determinant. Then the idea comes out that if we can find a bad

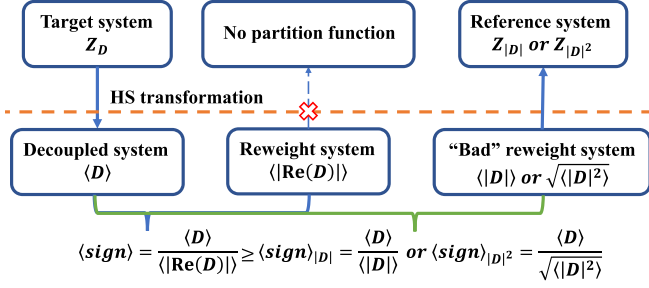


FIG. 1. Schematic relationship between target system, reweight system, and reference system. Average sign is ill-defined observable because reweight system cannot recover to a physical system, while bad reweight system corresponds to a physical system so sign bounds is a well-defined observable.

reweight system which can be written back to the partition function of a physical system (which we call a reference system) and there is a certain relationship between this well-defined partition function and the ill-defined partition function $\sum_l |\text{Re}(W_l)|$, we find the bounds of $\langle \text{sign} \rangle$ as a new physical observable which is defined as the ratio of two well-defined partition functions for related interactive systems. At low temperature, the exponential part with temperature can tell the GSE difference for those two systems, while the polynomial part with system size can tell GSD. Since we can measure both sign bounds and reference system, we can extract information for the target system where there is a sign problem. At finite temperature, if those two systems have different phase transition behaviors, e.g., 2D Ising and no finite temperature phase transition, the sign bounds can roughly tell the phase transition point according to a domain size argument. All of these will be discussed in detail below.

III. SIGN BOUNDS THEORY

For a generic quantum many-body system with Hamiltonian H , we have partition function $Z = \text{Tr}(e^{-\beta H})$. Then, as shown in Eq. (3), the partition function can be written as the weighted average of fermion determinants after the Trotter decomposition and HS transformation, $Z_D = \sum_{\{l\}} P(\{l\})D(\{l\}) \equiv \langle D \rangle$, where l represents different configurations, $P(\{l\})$ is the configurational weight for determinant $D(\{l\})$. Since we only consider Hermitian system by default, $Z_D = \text{Re}(Z_D) = \langle \text{Re}(D) \rangle$. Now, imagine we can find a bad reweight system with the same configuration space. As a reweight system, it requires non-negative determinant $V(\{l\}) \geq 0$ for any configuration l . Besides, we also require $\langle V \rangle \equiv \sum_{\{l\}} P(\{l\})V(\{l\})$, corresponding to a partition function Z_V of a physical Hamiltonian before HS decomposition. We call this physical Hamiltonian the reference system V and define the average sign bounds based on V as $\langle \text{sign} \rangle_V$. This sign bounds can give bounds behavior of $\langle \text{sign} \rangle$ based on the inequality between $\langle |\text{Re}(D)| \rangle$ and $f(\langle V \rangle)$. Here f can be any function of $\langle V \rangle$. For a concrete understanding, we give two reference systems $V = |D|^2$, $V = |D|$, which satisfies $\langle D \rangle = \langle \text{Re}(D) \rangle \leq \langle |\text{Re}(D)| \rangle \leq \sqrt{\langle |D|^2 \rangle}$ and $\langle D \rangle = \langle \text{Re}(D) \rangle \leq \langle |\text{Re}(D)| \rangle \leq \langle |D| \rangle$. One can see those reference

systems do give bounds as

$$\frac{Z_D}{\sqrt{Z_{|D|^2}}} \equiv \frac{\langle D \rangle}{\sqrt{\langle |D|^2 \rangle}} \leq \langle \text{sign} \rangle \equiv \frac{\langle D \rangle}{\langle |\text{Re}(D)| \rangle} \leq 1,$$

$$\frac{Z_D}{Z_{|D|}} \equiv \frac{\langle D \rangle}{\langle |D| \rangle} \leq \langle \text{sign} \rangle \equiv \frac{\langle D \rangle}{\langle |\text{Re}(D)| \rangle} \leq 1. \quad (6)$$

The logic is drawn schematically in Fig. 1. For now, the non-negative requirement and inequality between $\langle |\text{Re}(D)| \rangle$ and $f(\langle V \rangle)$ are both trivial, which means it is true for any system. Then the only nontrivial requirement for a reference system is it must have a physical partition function so we can say sign bounds is a well-defined observable. Below we give two corollaries where two possible reference systems $Z_{|D|^2}$, $Z_{|D|}$ can apply separately on a large group of systems.

A. Corollary I

For a fermion Hamiltonian whose sign of QMC for every configuration is real, we can introduce another $U(2)$ freedom $s \in \{+, -\}$ such as spin or valley, to prepare a reference system.

This is what we usually do to avoid sign problems when designing a sign-problem-free model to study general effects of certain interaction. But here we do not simulate this sign-problem-free system as our target system. We extract physical information of our target system with a sign problem from sign bounds behavior $\frac{Z_D}{\sqrt{Z_{|D|^2}}}$. For example, if this ratio does not change with temperature when temperature goes to zero, the GSE E between reference system and target system must have the certain relation $E_D = E_{|D|^2}/2$. And the GSD g can be derived from $\frac{Z_D}{\sqrt{Z_{|D|^2}}} = \frac{g_D}{\sqrt{g_{|D|^2}}}$. Here $g_{|D|^2}$ is the GSD with this $U(2)$ freedom. For a global discrete symmetry of the Hamiltonian, the ground states belong to finite-dimension irreducible representation which contributes degeneracy independently with system size. For global continuous symmetry such as $SU(n)$, degeneracy is determined by normal Young diagram ground states belong to, which is polynomial with system size. Then the polynomial average sign behavior with system size will be seen. We will discuss this zero GSE and global continuous symmetry case below.

B. Examples

We introduce two cases here, which are set in momentum space, with a generic positive semidefinite (PSD) Hamiltonian (e.g., describing the long-range Coulomb interaction in a flat-band system),

$$H = \sum_{q \neq 0} V(q) \rho_{-q} \rho_q = \sum_{q \neq 0} V(q) \rho_q^\dagger \rho_q, \quad (7)$$

where $\rho_q = \sum_{i,j} (\lambda_{i,j}(q) c_i^\dagger c_j - \frac{1}{2} \mu_q)$, i, j are matrix indexes with dimension N (e.g., the momentum grid in moiré Brillouin zone (mBZ), $N = 6 \times 6, 9 \times 9, \dots$), and the averagely half-filled physical system requires $V(q) = V(-q) > 0$, $\text{Tr}(\lambda_{i,j}(q)) = \mu_q$. In our previous momentum space QMC work [52], we proved that $\text{Tr}(\lambda_{i,j}(q)) = \mu_q$ guarantees the sign for every configuration is real. Then one can require zero-energy ground state for observing $\langle \text{sign} \rangle \geq g_D / \sqrt{g_{|D|^2}}$ behavior.

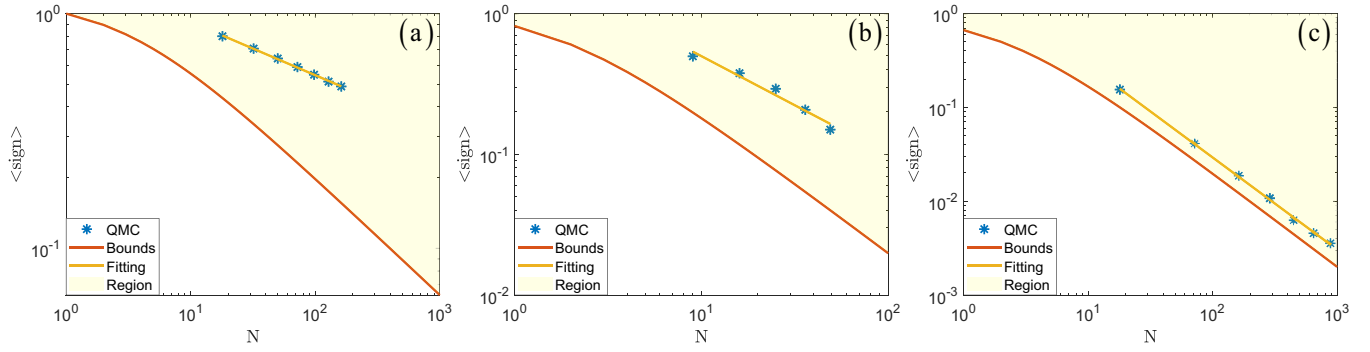


FIG. 2. For three example cases, the average sign bounds, allowed region, QMC measurement (sign), and its polynomial fitting with fitting lines are shown. The error bars in QMC data are smaller than the symbol size. (a) For momentum space case 1 model, bounds are determined by $\langle \text{sign} \rangle \geq 2/\sqrt{N+3}$. QMC measurements for $N = 18, 32, 50, 72, 98, 128, 162$ are carried out at a $\langle \text{sign} \rangle$ converged temperature. Fitting line $\propto N^{-0.23}$. (b) For momentum space case 2 model, bounds are determined by $\langle \text{sign} \rangle \geq 2/\sqrt{(N+1)^2+2}$. QMC measurements for $N = 9, 16, 25, 36, 49$ are carried out at $T = 0.91$ meV. Fitting line $\propto N^{-0.70}$. (c) For real space model, bounds are determined by $\langle \text{sign} \rangle \geq 2/(N+2)$ and $N = 18, 72, 162, 288, 450, 648, 882$ are measured from QMC [50]. Fitting line $\propto N^{-0.98}$.

In our case 1, $\mu_q = 0$ and $\lambda_{i,j}(q)$ is set randomly. For $\mu_q = 0$, one can easily check empty and full states are two ground states with zero energy. Random $\lambda_{i,j}(q)$ means there should be no other symmetry, so no other degeneracy. Then we have $g_D = 2$. After, we introduce another freedom $s \in \{+, -\}$, which means now $\rho_{s,q} = \sum_{i,j} (\lambda_{i,j}(q)(c_{i,+}^\dagger c_{j,+} + c_{i,-}^\dagger c_{j,-}) - \mu_q)$. For computing degeneracy $g_{|D|^2}$, one can define a raising operator,

$$\Delta^\dagger = \sum_{i'} c_{i',+}^\dagger c_{i',-}, \quad (8)$$

by noticing $[\Delta^\dagger, \rho_{s,q}] = 0$, and $|\psi_{+, \text{empty}}\rangle \otimes |\psi_{-, \text{full}}\rangle$ is a ground state. We can apply Δ^\dagger at most N times on this state, and this gives us $N+1$ ground states with N particles. Besides, we also have ground states with 0 and $2N$ particles (i.e., $|\psi_{+, \text{empty}}\rangle \otimes |\psi_{-, \text{empty}}\rangle$ and $|\psi_{+, \text{full}}\rangle \otimes |\psi_{-, \text{full}}\rangle$). Together, $g_{|D|^2} = N+3$ for random $\lambda_{i,j}(q)$ so $\langle \text{sign} \rangle \geq g_D/\sqrt{g_{|D|^2}} = 2/\sqrt{N+3}$ as shown in Fig. 2(a). This means at low temperature and large size limit, $\langle \text{sign} \rangle$ will decay no faster than $N^{-\frac{1}{2}}$. It is worth mentioning this derivation and the tensor Young tableau method below should be *exact* and can

be checked for small size numerically as shown in Fig. 3(a) unless there is accidental degeneracy.

In our case 2, $\mu_q \neq 0$ and there are two band labels $m, n \in \{1, -1\}$ for $\lambda_{i,j,m,n}(q) = m \cdot n \cdot \lambda_{i,j,m,n}(q)$ (e.g., chiral flat-band limit for spin-polarized and valley-polarized TBG at half filling, following gauges chosen in Refs. [56,57]). Now $\rho_q = \sum_{i,j,m,n} (\lambda_{i,j,m,n}(q) c_{i,m}^\dagger c_{j,n} - \frac{1}{2}\mu_q)$ and there are two degenerate ground states with Chern number ± 1 , i.e., $g_D = 2$. Again, after introducing freedom $s \in \{+, -\}$, $\rho_{s,q} = \sum_{i,j,m,n} (\lambda_{i,j,m,n}(q) \cdot (c_{i,m,+}^\dagger c_{j,n,+} + c_{i,m,-}^\dagger c_{j,n,-}) - \mu_q)$. One can define two raising operators (see Appendix B):

$$\begin{aligned} \Delta_1^\dagger &= \sum_{j'} (c_{j',1,+}^\dagger + ic_{j',-1,+}^\dagger)(c_{j',1,-} - ic_{j',-1,-}), \\ \Delta_2^\dagger &= \sum_{j'} (c_{j',1,+}^\dagger - ic_{j',-1,+}^\dagger)(c_{j',1,-} + ic_{j',-1,-}). \end{aligned} \quad (9)$$

Here i is the imaginary unit. It is straightforward to verify $[\Delta_1^\dagger, \rho_{s,q}] = [\Delta_2^\dagger, \rho_{s,q}] = 0$ and $[\Delta_1^\dagger, \Delta_2^\dagger] = [\Delta_1^\dagger, \Delta_2] = 0$. This means Δ_1^\dagger and Δ_2^\dagger generate two groups of orthogonal

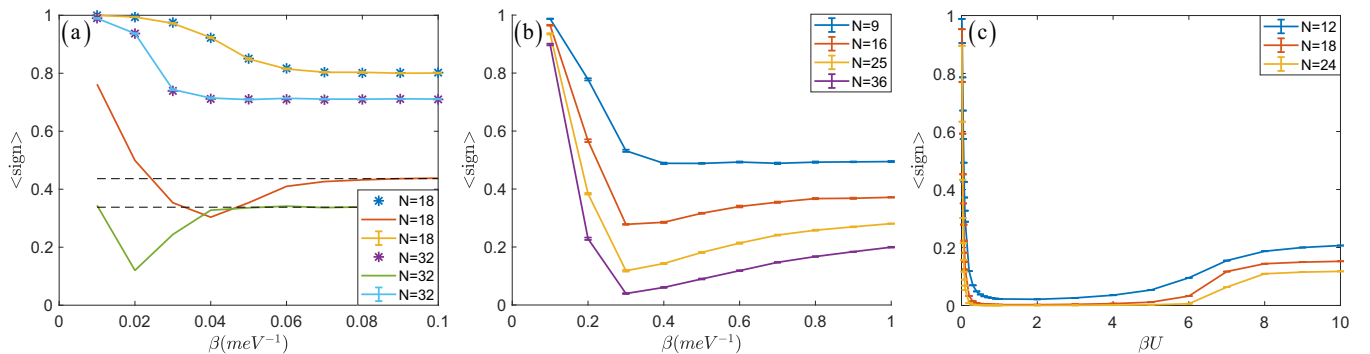


FIG. 3. Finite-temperature results for three example cases. (a) For momentum space case 1 model, size $N = 18, 32$ are plotted. We measure $\langle \text{Re}(D) \rangle$, $|\langle \text{Re}(D) \rangle|$, and $\sqrt{|\langle D \rangle|^2}$ according to $Z = \sum_{\{l\}} P(\{l\}) D(\{l\})$. Stars are $\langle \text{sign} \rangle$ determined by $\frac{\langle \text{Re}(D) \rangle}{|\langle \text{Re}(D) \rangle|}$ and lines without error bars are sign bounds determined by $\frac{\langle \text{Re}(D) \rangle}{\sqrt{|\langle D \rangle|^2}}$, dashed lines are low temperature limit bounds $\frac{2}{\sqrt{N+3}}$. Error bar lines are $\langle \text{sign} \rangle$ computed independently with importance sampling QMC. (b) For momentum space case 2 model, we plot $\langle \text{sign} \rangle$ computed with importance sampling QMC for size $N = 9, 16, 25, 36$. (c) For real space case 3 model, we plot $\langle \text{sign} \rangle$ computed with importance sampling QMC for size $N = 12, 18, 24$.

eigenstates with the same energy. By noticing $|\psi_{+, \text{empty}}\rangle \otimes |\psi_{-, \text{full}}\rangle$ is a ground state, applying Δ_1^\dagger or Δ_2^\dagger independently will give $(N+1)^2$ orthogonal zero-energy states with zero Chern number. Here N is dimension of label i, j in $\lambda_{i,j,m,n}(q)$. Besides, there are also two states with nonzero Chern number, on which raising operators apply are equal to 0 so no other states will be given, $g_{|D|^2} = (N+1)^2 + 2$. This means for this model, $\langle \text{sign} \rangle \geq 2/\sqrt{(N+1)^2 + 2}$ as shown in Fig. 2(b).

C. Corollary II

For a Hamiltonian with a PSD interaction part $\sum_A (A - \mu_A)^2$ and a kinetic part K , where A and K are the fermion bilinears and μ_A is real constant number. If for a certain group of μ_A , there is no sign problem, then $Z_{|D|}$ can be used as partition function of reference system (This can be seen by noticing μ_A only contributes a phase in $D(\{I\})$, so that the reference system now is just the Hamiltonian with the sign-problem-free μ_A). At low temperature, $\langle \text{sign} \rangle \geq g_D e^{-\beta(E_D - E_{|D|})} / g_{|D|}$. If $E_D = E_{|D|}$, $\langle \text{sign} \rangle \geq g_D / g_{|D|}$.

D. Example

It is easy to notice this corollary can give a sign bounds behavior for all kinds of repulsive Hubbard models (by seeing μ_A as chemical potential or other on-site ionic potential), where the usual exponential decay of average sign is commonly seen. Though QMC may say little about E_D and g_D , one could expect with the improvement of constrained path QMC, density matrix renormalization group, and tensor-network type methods, GSE and GSD for a finite-size doped Hubbard system can be obtained [58–62], so theoretical sign bounds behavior $g_D e^{-\beta(E_D - E_{|D|})} / g_{|D|}$ can be achieved and check with the numerical one. Since there have been many discussions on the sign problem therein [5,31,46,63–66], here we still focus the application of this reference system on a PSD Hamiltonian without kinetic part K . We study the Kang-Vafeek's real space model [67], for twisted bilayer graphene at the flat-band limit with $1/4$ or $3/4$ filling ($\nu = \pm 2$), whose GSE $E = 0$ is equal to that at half filling ($\nu = 0$). In this example, we give an explanation for algebraic average sign observed in Ref. [50], and determine the sign bounds analytically. The model is written below:

$$H = U \sum_{\square} (Q_{\square} + \alpha T_{\square} - \nu)^2, \quad (10)$$

where $Q_{\square} = \frac{1}{3} \sum_{\sigma, \tau} \sum_{l=1}^6 c_{R+\delta_l, \sigma, \tau}^\dagger c_{R+\delta_l, \sigma, \tau} - 4$, $T_{\square} = \sum_{\sigma, \tau} \sum_{l=1}^6 [(-1)^l c_{R+\delta_{l+1}, \sigma, \tau}^\dagger c_{R+\delta_l, \sigma, \tau} + \text{H.c.}]$, ν is used to control filling, σ, τ are spin and valley indexes, $R + \delta_l$ represents site l in a single R hexagon, and U, α are real constants. Attention to the subtraction of a constant 4 in the definition of operator Q_{\square} which moves the charge neutrality point to $\nu = 0$. We consider the infinite- U case as studied in Ref. [50]. Fixing α , then the only parameter is βU , and any finite β in the infinite- U limit corresponds to the low-temperature limit. We consider the system with linear system size L up to $L = 21$ and the total number of sites is $N = 2L^2$. This model is sign problem free at charge neutrality [68,69], with partition function identical

to $Z_{|D|}$, as when ν is away from charge neutrality, it only introduces a phase to the weight [50]. As the real space model is PSD, and one can construct a zero-energy ground state both at charge neutrality and at $\nu = \pm 2$ with GSD $g_D = (N+3)(N+2)(N+1)/6$ for $\nu = \pm 2$ [57,67] and GSD $g_{|D|} = (N+3)(N+2)^2(N+1)/12$ for $\nu = 0$ [57], (see Appendix C for the tensor Young tableau method in which the GSD are obtained), therefore $\langle \text{sign} \rangle \geq g_D / g_{|D|} = 2/(N+2)$. Figure 2(c) shows the average sign presented in Ref. [50], compared with the sign bounds we proposed.

IV. SIGN BOUNDS AT FINITE TEMPERATURE

We will show how sign bounds can roughly imply a finite-temperature phase transition point with a domain size argument in this section.

It is worthwhile to notice when we are talking about the low-temperature limit at finite temperature and finite-size system simulation, we are actually considering the simulated system size is covered by a single domain within which the partition function can be well described by GSE and GSD, that is, the low-temperature limit discussed above. For the finite-temperature case, we generally cannot achieve partition function explicitly. But we expect partition functions for the target system and reference system should have different behaviors with temperature according to the different symmetry or irreducible representation their ground states belong to.

Taking our first two cases as an example, one can see the target system has Z_2 symmetry for double degenerated ground states while the reference system has continuous $SU(2)$ symmetry with continuous excitations. For the 2D system, we know a Z_2 symmetry ground state has a finite temperature phase transition, while there is no finite temperature phase transition for $SU(2)$ symmetry. This difference causes a result that, when increasing temperature from zero, the partition function for target system Z_D is almost unchanged because the system is still in a single ground state domain as long as below phase transition temperature, while continuous excitations from $SU(2)$ symmetry will contribute to Z_V so long as the temperature fluctuation suppresses this domain size below the system size. This is the first step shown in Fig. 3(b)—more states contributing to Z_V will make $\langle \text{sign} \rangle$ decrease. Things change when the energy scale of the temperature touches excitation breaking Z_2 symmetry. The correlation length of the ground state begins to decrease linearly with the inverse of temperature τ^{-1} , which is faster than $SU(2)$ symmetry. It means domain size decreases faster for the target system. At this time, excitations contribute more to Z_D than Z_V . This is the second step in Fig. 3(b), $\langle \text{sign} \rangle$ begins to increase after the phase transition of the target system. Finally, fluctuation from temperature almost makes all freedom of Hamiltonians contribute equally to partition function. That is the high-temperature limit where $\langle \text{sign} \rangle \approx 1$ is well understood.

According to this argument, one can forecast the excitation gap should enlarge with size for our case 1, since the lowest point of sign bounds shift to high temperature with increasing size as shown in Fig. 3(a). This behavior is unphysical just because we use random matrix to construct our Hamiltonian. In our physical case 2, different sizes dip at similar temperature, which indicates the phase transition temperature

roughly. Besides, one can also forecast the domain size of target systems decrease slower than reference systems at low temperature in our case 3 so there is a reduction of $\langle \text{sign} \rangle$ when increasing temperature as shown in Fig. 3(c), even though the target system and reference system here almost have the same symmetry. Stars and error bar lines match well in Fig. 3(a), also indicating the way we compute $Z = \sum_{\{I\}} P(\{I\})D(\{I\})$ is valid for finite size at finite temperature. And the converging to dash line at the low-temperature limit shows our GSD analysis is correct.

V. CONCLUSION AND DISCUSSION

We bridge a connection between the sign problem and well-defined partition function properties of the target system and reference system in interactive quantum many-body problems. At low temperature, the sign bounds depend on GSE and GSD of the target system and the reference system. At finite temperature, a domain size argument based on symmetry is delivered. Our two corollaries give two groups of systems where reference systems $|D|^2$, $|D|$ can apply separately, so sign bounds theory can work. As applications of our two corollaries at the low-temperature limit, we demonstrate the algebraic scaling of average sign in a class of PSD models which have a physical background with flat band quantum morié materials. The sign bounds theory we proposed is a generic criteria that could help find new quantum many-body models that acquire the algebraic sign or mild exponential sign.

Inspiration ideas can also be extended to projection versions of QMC [70–74]. Suppose we have a trial wave function with $|\Psi_T\rangle = \sum_n c_n |\Psi_n\rangle$, where $|\Psi_n\rangle$ is the eigenstate of H with eigenvalue E_n . In the projection version of QMC, the true wave function is achieved by projection, i.e., $|\Psi_0\rangle \sim \lim_{\Theta \rightarrow \infty} e^{-\Theta H} |\Psi_T\rangle$. To keep a similar notation with the finite-temperature case, we denote $Z_D = \langle \Psi_T | e^{-2\Theta H} | \Psi_T \rangle = c_D e^{-2\Theta E_D}$, where $c_D = \sum_{n \in D} |c_n|^2$ is the ground-state component in $|\Psi_T\rangle$ and E_D is the GSE. For the reference system, we have $Z_V = c_V e^{-2\Theta E_V}$, where c_V is the reference-system ground-state component in $|\Psi_T\rangle$ and E_V is the reference-system GSE. Then the sign bounds are

$$\langle \text{sign} \rangle_V = \frac{c_D e^{-2\Theta E_D}}{c_V e^{-2\Theta E_V}}. \quad (11)$$

This implies that to alleviate the sign problem, it is important to make the trial wave function have larger components of the ground state and make the reference system have closer GSE with the origin system, though this generally still cannot remove the exponential part from the energy difference. This may explain the recent proposed adiabatic method, where the trial wave function is adiabatically improved and the closeness of the reference GSE is well expected [37].

In a similar spirit, with further improvement of DMRG and tensor-network-type approaches, where the low temperature, GSE, and GSD on finite-size systems are expected to be

obtained with better accuracy, it will be natural to make use of this information and perform the analysis with our theory to provide (hopefully improved) bounds of QMC on systems with conventional exponential sign problems, such as doped Hubbard model or quantum spin systems with frustration. Moreover, as our theorem directly relates the sign problem to the physical properties of the system, it implies there may be important information hidden inside configurations even when the simulation has a sign problem. Therefore, machine learning and related data mining of Monte Carlo data with sign problems are encouraging [75].

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APPENDIX A: PARAMETERS FOR THREE CASES

For the first two cases, we take $V(q)$ in the equation of main text as single gate screened Coloumb potential used in Ref. [52]:

$$V(\bar{q}) \approx 7.925 \frac{1}{\sqrt{N_k \bar{q}}} \left(1 - e^{-22.36 \frac{1}{\sqrt{N_k} \bar{q}}} \right) \text{meV}. \quad (A1)$$

Here, \bar{q} is the distance between momenta in mBZ by setting two nearest k points with unit length and N_k is the number of momentum points in mBZ. We take a cutoff for \bar{q} that the longest \bar{q} is the length of reciprocal lattice vectors of the mBZ. m, n in $\lambda_{i,j,m,n}$ are two flat band indexes for TBG. Form factor λ is the overlap between two flat band wave functions at momentum k_1, k_2 (i.e., $\lambda_{k_1,k_2,m,n} = \sum_{G',X} u_{k_1,m;G',X}^* u_{k_2,n;G',X}$). For case 1, we just take this $2N_k \times 2N_k$ matrix $\lambda_{k_1,k_2,m,n}$ randomly with requiring $\text{Tr}(\lambda) = 0$ and maximum mode 1 for every complex element. For case 2, we compute flat-band wave functions at the chiral limit with Bistritzer-MacDonald (BM) continuous model [76–81], parameters $(\theta, \hbar v_F/a_0, u_0, u_1) = (1.08^\circ, 2.37745 \text{ eV}, 0 \text{ eV}, 0.11 \text{ eV})$. For convenience, we put BM continuous model Hamiltonian below:

$$H_{k,k'}^\tau = \begin{pmatrix} -\hbar v_F(k - K_1) \cdot \sigma \delta_{k,k'} & U_0 \delta_{k,k'} + U_1 \delta_{k,k'+G_1} + U_2 \delta_{k,k'+G_1+G_2} \\ U_0^\dagger \delta_{k,k'} + U_1^\dagger \delta_{k,k'-G_1} + U_2^\dagger \delta_{k,k'-G_1-G_2} & -\hbar v_F(k - K_2) \cdot \sigma \delta_{k,k'} \end{pmatrix}. \quad (A2)$$

Here, the explicit 2×2 matrix is labeled by the layer index, and in each layer there is also an implied 2×2 matrix labeled by sublattice index. σ is just a Pauli matrix for describing Dirac cone of monolayer graphene. Twist angle θ is set as a magic angle where two flat bands emerge. The θ will be included in Hamiltonian by noticing moiré lattice constant is determined by $a_M = a_0/\theta$ when θ is small. Interlayer tunneling between two Dirac cones located at K_1 and K_2 in the same valley τ is described by matrices $U_0 = \begin{pmatrix} u_0 & u_1 \\ u_1 & u_0 \end{pmatrix}$, $U_1 = \begin{pmatrix} u_0 & u_1 e^{-i\frac{2\pi}{3}} \\ u_1 e^{i\frac{2\pi}{3}} & u_0 \end{pmatrix}$ and $U_2 = \begin{pmatrix} u_0 & u_1 e^{i\frac{2\pi}{3}} \\ u_1 e^{-i\frac{2\pi}{3}} & u_0 \end{pmatrix}$, where u_0 and u_1 are the intra-sublattice and intersublattice interlayer tunneling amplitudes. a_0 is the lattice constant of monolayer graphene, G_1 and G_2 are reciprocal vectors of mBZ, and τ in $H_{k,k'}^\tau$ means one only considers one valley τ Hamiltonian and ignores intervalley tunneling.

For case 3, the model parameters used in Fig. 2 are the same as the parameters used in Ref. [50]. We set $\alpha = 0.5$, and only have βU as an independent parameter. We divide βU into L_τ slices $\beta U = L_\tau \Delta_\tau U$, where L_τ scales with L , $L_\tau = 10L$. We then use the infinite- U projection scheme, which corresponds to the zero-temperature limit. Therefore, we have perfect scaling of average sign in Fig. 2(c). In Fig. 3, we calculate system size 3×2 , 3×3 , and 3×4 , as each unit cell has two sites, we have a total number of sites $N = 12, 18$, and 24 . We do not allow L_τ to scale with L in this case, but determine it through $L_\tau = \beta U / \Delta_\tau U$, where βU ranges from 0.01 to 10 (for βU from 0.01 to 0.09, $\Delta_\tau U = 0.001$ is used; for βU from 0.1 to 1, $\Delta_\tau U = 0.01$ is used; for βU from 2 to 10, $\Delta_\tau U = 0.1$ is used), and the infinite- U projection scheme is not used, therefore it corresponds to a finite temperature study.

APPENDIX B: RAISING OPERATOR CONSTRUCTION

Here we introduce the way we look for raising operators. First, for random $\lambda_{i,j}$, $\rho_q = \sum_{i,j} (\lambda_{i,j}(q) c_i^\dagger c_j - \frac{1}{2} \mu_q)$ and $\rho_{s,q} = \sum_{i,j} (\lambda_{i,j}(q) \cdot (c_{i,+}^\dagger c_{j,+} + c_{i,-}^\dagger c_{j,-}) - \mu_q)$. If we want to find a two-fermion operator Δ^\dagger commuting with $\rho_{s,q}$, we only need to find a matrix commuting with $\rho_{s,q}$ in single-particle basis. The total dimension of $\rho_{s,q}$ can be written into i, j space direct products $s \in \{+, -\}$ space noted by $K \otimes S$. Since generally $\lambda_{i,j}$ in K space does not have any symmetry, one needs a unit operator in this space to commute with $\rho_{s,q}$. While in S space, one can see $\rho_{s,q,i,j}$ looks like

$$\rho_{s,q,i,j} = \begin{pmatrix} \lambda_{i,j}(q) & 0 \\ 0 & \lambda_{i,j}(q) \end{pmatrix}, \quad (\text{B1})$$

which means actually any 2×2 matrix will commute with $\rho_{s,q,i,j}$. We choose a raising operator which makes charge flip from $-$ to $+$ space:

$$\Delta_{i,j}^\dagger = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}. \quad (\text{B2})$$

As a direct product those two parts of Δ^\dagger , we achieve the raising operator we want:

$$\Delta^\dagger = \sum_i c_{i,+}^\dagger c_{i,-}. \quad (\text{B3})$$

Then, with similar spirit, we can derive $\Delta_1^\dagger, \Delta_2^\dagger$ in case 2. The only difference is now we have another band space 1, -1 . At chiral limit, $\rho_{s,q,i,j,+,-}$ in band space looks like

$$\begin{aligned} \rho_{s,q,i,j,+,-} &= \begin{pmatrix} \lambda_{i,j,1,1}(q) & \lambda_{i,j,1,-1}(q) \\ -\lambda_{i,j,1,-1}(q) & \lambda_{i,j,1,1}(q) \end{pmatrix} \\ &= \lambda_{i,j,1,1}(q) \sigma_0 + i \lambda_{i,j,1,-1}(q) \sigma_y. \end{aligned} \quad (\text{B4})$$

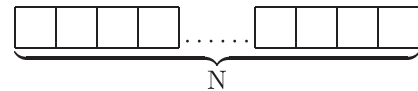
Here σ_0 is a unit matrix and σ_y is the Pauli matrix. For commuting with this matrix, the 2×2 matrix can only be in the form of $\alpha \sigma_0 + \beta \sigma_y$. For now, any choosing of α, β can generate one reasonable raising operator. If one also would like two different raising operators with different choices of α, β satisfying $[\Delta_1^\dagger, \Delta_2^\dagger] = 0$ means they are two groups of independent operators commuting with each other, and $(\alpha_1 \sigma_0 + \beta_1 \sigma_y)(\alpha_2 \sigma_0 + \beta_2 \sigma_y) = 0$ must be satisfied. One simple choice is $(\sigma_0 + \sigma_y)(\sigma_0 - \sigma_y) = 0$. Then we achieve $\Delta_1^\dagger, \Delta_2^\dagger$ we used in case 2 in the main text:

$$\begin{aligned} \Delta_1^\dagger &= \sum_j (c_{j,1,+}^\dagger + i c_{j,-1,+}^\dagger)(c_{j,1,-} - i c_{j,-1,-}), \\ \Delta_2^\dagger &= \sum_j (c_{j,1,+}^\dagger - i c_{j,-1,+}^\dagger)(c_{j,1,-} + i c_{j,-1,-}). \end{aligned} \quad (\text{B5})$$

APPENDIX C: TENSOR YOUNG TABLEAU METHOD

For self-consistency, we introduce another useful way, which is also used in Refs. [53,57,82], to compute the GSD besides raising operator construction. This method works for models whose degeneracy is introduced by $SU(n)$ symmetry. $g_D = (N+3)(N+2)(N+1)/6$ for $\nu = \pm 2$ and $GSD_{|D|} = (N+3)(N+2)^2(N+1)/12$ for $\nu = 0$ in Kang-Vafek's real space model are calculated in this way.

In Kang-Vafek's real space model case, degeneracy is introduced by $SU(4)$ symmetry, where spin and valley contribute two $SU(2)$. One can easily see any m -particle wave function can always be described by a four-dimension rank- m tensor like T_{a_1, a_2, \dots, a_m} , where different $a_i \in \{1, 2, 3, 4\}$, with four spin-valley dimensions label particles. $SU(4)$ transformation for spin-valley space and S_m permutation for particle index are independent and will only change tensor T to another tensor T' in tensor space, which means T is well-defined for decomposition according to irreducible representation. By noticing the number of the same a_i must be less than lattice size N , the Young diagram must have rows less than 4 and columns less than N . The Young diagram to which fulfilling one spin-valley flavor ground state for $\nu = \pm 2$ belongs is

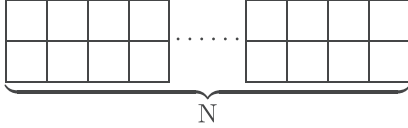


Assume only this irreducible representation contributes to ground states. Then, counting the degeneracy is equal to counting a normal Young tableau of this Young diagram,

which can be calculated by hook length formula:

$$d_{[N]}(\text{SU}(4)) = \prod_j \frac{4+j-1}{j} = \frac{(N+3)!}{3!N!} \\ = \frac{(N+3)(N+2)(N+1)}{6}, \quad (\text{C1})$$

while the Young diagram to which fulfilling the two spin-valley flavors ground state for $\nu = 0$ belongs is just



The number of the normal Young tableau calculated by hook length formula is

$$d_{[N,N]}(\text{SU}(4)) = \prod_{i,j} \frac{4+j-i}{h_{i,j}} = \frac{(N+3)!(N+2)!}{3!2!(N+1)!N!} \\ = \frac{(N+3)(N+2)^2(N+1)}{12}. \quad (\text{C2})$$

The numerical way to compute the GSD by QMC according to $Z = \sum_{\{I\}} P(\{I\})D(\{I\})$ also confirms the assumption that only one irreducible representation contributes to ground states in this case.

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