# Excitation of a bound state in the continuum via spontaneous symmetry breaking

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*Bound states in the continuum* (BICs) are nonradiating solutions of the wave equation with a spectrum embedded in the continuum of propagating waves of the surrounding space. The complete decoupling of BICs from the radiation continuum makes their excitation impossible from the far-field. Here, we develop a general theory of parametric excitation of BICs in nonlinear systems with Kerr-type nonlinearity via spontaneous symmetry breaking, which results in a coupling of a BIC and a bright mode of the system. Using the temporal coupled-mode theory and perturbation analysis, we find the threshold intensity for excitation of a BIC and study the possible stable and unstable solutions depending on the pump intensity and frequency detuning between the pump and BIC. We reveal that at some parameters of the pump beam, there are no stable solutions and the BIC can be used for frequency comb generation. Our findings can be very promising for use in nonlinear photonic devices and all-optical networks.

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## I. INTRODUCTION

The *bound state in the continuum* (BIC) is a nonradiating solution with an energy embedded in the continuum spectrum of propagating modes of the surrounding space. It was first revealed in quantum mechanics in 1929 by von Neumann and Wigner [1]. Despite that the proposed idea has been never implemented in practice for quantum-mechanical systems, it affects the development of atomic physics [2,3], acoustics [4–6], and hydrodynamics [7–9]. In recent years, BICs have attracted more and more attention in nanophotonics [10–13] providing great enhancement of the electromagnetic field and its localization at the nanoscale. The advantages of BICs were demonstrated for lasing [14–17], sensing [18,19], filtering [20,21], enhancement of light-matter interaction [22,23], non-linear photonics [24–33], and vortex generation [34,35].

BICs are formed due to the complete decoupling of leaky modes (resonant states) from the radiating waves. The decoupling can happen, for example, in the system with separable potentials or due to parameter tuning (Friedrich-Wintgen scenario) [36]. More specific mechanisms are discussed in Ref. [10]. Periodic structures with a rotational symmetry can naturally host so-called *symmetry-protected* BICs when the coupling between the radiation continuum and BICs is forbidden in virtue of the symmetry reasons [37–40]. Such states are robust to the presence of a substrate and fabrication inaccuracies preserving the symmetry of the sample.

The high-Q states are very beneficial, for example, for sensing as they manifest themselves in transmission/reflection spectra as narrow Fano-type resonances whose spectral shift due the presence of an analyte

can be precisely measured [41–43]. However, the efficient excitation of high-Q states and strong field enhancement inside the resonator require the fulfillment of the critical coupling condition when the intrinsic losses  $\Gamma_{int}$  of the resonator are equal to the radiative ones  $\Gamma_{rad}$  [44,45]. Therefore, the efficient excitation of a genuine BIC with  $\Gamma_{rad} = 0$  from the far-field is a challenging problem that can substantially extend its applicability in nanophotonics and metadevices.

BICs can be excited by near-fields of quantum light sources such as quantum wells, quantum dots, nitrogen vacancy centers, and dye molecules [15,17,46–48]. Another way is to provide a finite but tiny coupling between the radiation continuum and BIC. In this case, the BIC turns into a quasi-BIC. The precise control of radiation losses of the quasi-BIC in periodic structures or single resonators can be achieved via the symmetry breaking of the unit cell or the shape of the resonator [49,50]. This method is a powerful tool for on-demand engineering of high-Q states. The structures supporting quasi-BICs have proven themselves well for nonlinear photonics and sensing [51-56]. Nonlinear polarization induced by the external field can be also used for the excitation of a genuine BIC. Thus, it was shown theoretically that a BIC can be excited because of Kerr nonlinearity or second-harmonic generation [57–61].

In this work, we develop a general theory of parametric excitation of BICs in systems with Kerr-type nonlinearity via spontaneous symmetry breaking resulting in a coupling between the BIC and the bright mode. Figure 1(a) illustrates the main idea of the paper. The BIC at frequency  $\omega_D$  has vanishing radiative loss ( $\Gamma_D = 0$ ). The bright mode at frequency  $\omega_B$  has a finite radiative loss ( $\Gamma_B \neq 0$ ). The bright mode and BIC usually appear in pairs as symmetric and antisymmetric solutions of the wave equation (see, e.g., Ref. [62]). The pump at frequency  $\omega$  excites only the bright mode in the linear regime. However, in the nonlinear regime, when the pump intensity is high enough, the division of the solutions into the

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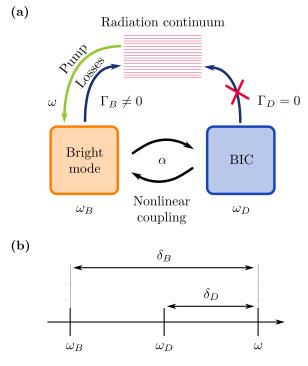


FIG. 1. (a) Schematic picture of the considered system consisting of two modes with a nonlinear coupling. One of them is a leaky or bright mode, directly coupled to the radiation continuum, and another one is a genuine BIC with no radiative loss. (b) Schematic picture of the relations between eigenfrequencies of the modes  $\omega_{B,D}$  and the pump frequency  $\omega$ .

symmetric (bright) and antisymmetric (BIC) solutions is not applicable as these solutions are no longer robust: the *spontaneous symmetry breaking* occurs [63–65]. It can be interpreted as the nonlinear coupling between the BIC and bright mode resulting in a parametric excitation of the BIC. Therefore, at some pump intensity, the stationary solution corresponding to the BIC in the linear case becomes a hybrid (without certain parity) and it can be represented as a combination of the bright mode and BIC.

The rest of the paper is organized as follows. In Sec. II we describe the physical models and introduce the master equations. Then, in Sec. III we discuss excitation of the BIC in terms of stability of the stationary solutions. After that in Sec. IV we describe stationary hybrid states, which occur due to nonlinearity, and finally, in Sec. V we consider dynamics of a nonlinear system and possible operating regimes. Section VI summarizes the obtained results and concludes the paper. The main text is supported by Appendices. In Appendix A, we provide a detailed description of the stability analysis. Appendix **B** contains the example of trajectories in phase space and a graphical representation of the frequency comb generation. Additionally, Supplemental Material [75] contains the derivation of coupled-mode equations for RLC circuits, which may be used as an experimental model for the verification of the obtained results.

### **II. MODEL**

The following analysis is done in the framework of the coupled-mode theory, which is applicable for a wide range

of systems, including atomic systems and resonance photonic and acoustic structures [66-70]. One of the simplest mechanisms of BIC formation is based on the coupling between two identical resonances with frequency  $\omega_0$  and a finite radiation rate  $\gamma_r$ . The coupling mixes the resonances, leading to the appearance of two normal modes of different parity (symmetric and asymmetric). When the coupled leaky resonances interfere constructively, they form a symmetric superradiant state with radiation rate  $2\gamma_r$ —an analog of the Dicke superradiant state for two emitters [71,72]. The destructive interference cancels out the far-field and, thus, the radiative losses vanish and a symmetry-protected BIC appears. It is worth mentioning that a symmetry-protected BIC appears exclusively due to the symmetry of the system and the interaction potential allowing the division of the normal modes into symmetric and antisymmetric modes.

We consider the system with a conservative cubic nonlinearity and denote the frequencies of the BIC and bright mode as  $\omega_D$  and  $\omega_B$ , respectively, and their complex amplitudes as D and B. The amplitude and the frequency of the pump we denote as p and  $\omega$ , respectively (see Supplemental Material [75] for details). The evolution of B and D can be described by the coupled-mode equations written for the slowly varying complex amplitudes of the modes, as in Refs. [73,74] or the Supplemental Material [75], for instance:

$$\dot{D} = -i\delta_D D - \Gamma_D D + i\alpha D(|D|^2 + 2|B|^2) + i\alpha B^2 D^*, \dot{B} = -i\delta_B B - \Gamma_B B + i\alpha B(|B|^2 + 2|D|^2) + i\alpha D^2 B^* + p.$$
(1)

All the parameters and variables in this system are dimensionless and their normalization is discussed in the Supplemental Material [75]. Here  $\delta_D$ ,  $\delta_B$  are the detunings of the BIC and the bright mode from the pump frequency  $\omega$  [see Fig. 1(b)]. Note that in these equations we assume that the time dependence is  $e^{i\omega t}$ . The coefficient of nonlinear coupling  $\alpha$  is responsible for the possible symmetry breaking and coupling between the BIC and bright mode. In the general case both equations for *D* and *B* have the decay coefficients  $\Gamma_B$  and  $\Gamma_D$ , respectively. The coefficient  $\Gamma_D$  accounts for the nonradiative loss of BIC, which is almost unavoidable in practice, and  $\Gamma_B$ contains both the radiative and nonradiative loss of the bright mode (see Supplemental Material [75] for details), and for quasi-BICs  $\Gamma_B \gg \Gamma_D$ .

As we mentioned above, such a system of equations is quite generic and, thus, the further results are applicable for a broad range of systems. However, to have an illustrative practical example, we suggest in the Supplemental Material [75] a particular system of coupled RLC circuits exactly described by Eqs. (1). The choice of the system is based on the fact that electrical circuits proved themselves to be a good platform for observation of BICs [76]. The absence of a pump term in the equation for the BIC clearly indicates that it is decoupled from the far-field. However, the nonlinear term  $i\alpha B^2 D^*$  can be considered as an effective parametric amplification (driving force) for the BIC. The excitation is possible only at specific values of the pump amplitude p and frequency detuning  $\delta_D$ , for which the solution D = 0 becomes unstable and, thus, any fluctuation in D results in the development of instability—the parametric excitation of the BIC.

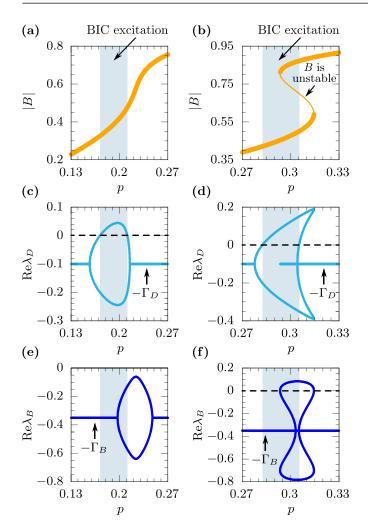


FIG. 2. (a) and (b): Stationary solutions of Eq. (2), when D = 0. Thick dots correspond to stable solutions for which  $\text{Re }\lambda_B < 0$  and thin dots correspond to unstable solutions for which  $\text{Re }\lambda_B \ge 0$ . Plot of  $\text{Re }\lambda_D$  vs p is shown in panels (c) and (d). Plot of  $\text{Re }\lambda_D$  vs p is shown in panels (e) and (f). Shadowed areas indicate the pump ranges at which the BIC is excited, i.e., where  $\text{Re }\lambda_D > 0$ . The dependencies are plotted for the following parameters:  $\Gamma_D = 0.1$ ,  $\Gamma_B = 0.35$ ,  $\delta_B =$  $\delta_D + 0.25$ , and  $\alpha = 1$ . Detuning  $\delta_D$  is equal to 0.25 for (a), (c), and (e) and 0.5 for (b), (d), and (f).

# **III. CONDITIONS OF BIC EXCITATION**

To find the parameters at which the excitation of the BIC is possible we need to analyze the stability of the solution  $D(\tau) = 0$  of Eqs. (1). This system for the coupled modes reduces to the single equation if we put D = 0:

$$\dot{B} = -i\delta_B B - \Gamma_B B + i\alpha B|B|^2 + p.$$
(2)

The stationary solutions of this equations can be easily found setting  $\dot{B} = 0$ . The amplitude |B| as a function of the pump pfor various detuning parameters  $\delta_D$  is shown in Figs. 2(a) and 2(b). All the parameters are listed in the caption. One can see that the increase of the detuning  $\delta_B$  results in the appearance of S-shaped dependence characteristic for nonlinear systems.

To analyze the stability of the found stationary solutions corresponding to the BIC and bright mode we will follow the standard procedure adding fluctuations to them (see Appendix A for details):

$$\delta B(\tau) = (m_1 e^{\lambda_B \tau} + n_1 e^{\lambda_B^* \tau}) e^{i\delta_D \tau},$$
  

$$\delta D(\tau) = (m_2 e^{\lambda_D \tau} + n_2 e^{\lambda_D^* \tau}) e^{i\delta_D \tau}.$$
(3)

Here  $m_{1,2}$  and  $n_{1,2}$  are small arbitrary functions. The system of Eqs. (1) can be linearized with respect to these small functions and reduced to the homogeneous form. The complex parameters  $\lambda_D$  and  $\lambda_B$  are found from the condition of solvability of the linearized homogeneous system. The exact expressions for  $\lambda_B$  and  $\lambda_D$  can be written as (see Appendix A)

$$\lambda_i = -\Gamma_i \pm \sqrt{-\delta_i^2 + 4\alpha \delta_i |B|^2 - 3\alpha^2 |B|^4}.$$
 (4)

Here i = B, D. The stability of the solutions  $B(\tau)$  and  $D(\tau)$  is defined by the sign of the real part of  $\lambda_B$  and  $\lambda_D$ , respectively. If it is positive then the corresponding solution is unstable and vice versa. Therefore, there are four possible scenarios depending on the detuning  $\delta_B$ , loss  $\Gamma_B$ , and pump p. All of the them are illustrated in Fig. 2. The left columns [panels (a), (c), and (e)] correspond to the case when  $\text{Re }\lambda_B < 0$  for all considered values of the pump. Nevertheless, there is a range of p (shaded region), where BIC is excited.

The right column of Fig. 2 [panels (b), (d), and (f)] corresponds to the case when the bright mode demonstrates a bistable behavior. The middle part of the S-shaped curve in Fig. 2(b) plotted with a thin solid line is unstable. One can see that the BIC can be excited for both cases, when  $\text{Re }\lambda_B > 0$  or  $\text{Re }\lambda_B < 0$ . It worth mentioning that  $\Gamma_i$  directly affects the stability of the corresponding mode and there are no unstable solutions in a system with high losses.

Equation (4) allows us to find the range of amplitudes |B| and frequency detunings  $\delta_{B,D}$  for which the BIC is excited and the bright mode is unstable. These ranges are defined by the following inequalities:

$$\frac{2\delta_i - \sqrt{\delta_i^2 - 3\Gamma_i^2}}{3\alpha} < |B|^2 < \frac{2\delta_i + \sqrt{\delta_i^2 - 3\Gamma_i^2}}{3\alpha}.$$
 (5)

Here i = B, D. The graphical representation of these inequalities is shown in Fig. 3(a). In the shaded areas, also known as *Arnold tongues*, the solutions are unstable. These graphs explicitly demonstrate that excitation of the BIC at high amplitudes of the bright mode requires high detunings  $\delta_D$ , since the frequency of the BIC shifts with the increase of |B|. In the case of the negative Kerr shift, such a detuning would be negative. The inequality (5) allows us to find the maximal loss  $\Gamma_{B,D}$  as a function  $\delta_{B,D}$  at which the parametric excitation of the BIC and the instability of the bright mode are possible:

$$\Gamma_{B,D} \leqslant \delta_{B,D}/\sqrt{3}.$$
 (6)

Importantly, if  $\Gamma_D = 0$ , the tip of the Arnold tongue touches the point |B| = 0 and  $\delta_D = 0$  [see Eq. (5)]. Therefore, the parametric excitation of the BIC is thresholdless; i.e., it is possible at any arbitrary small values of the pump amplitude p. On the other hand,  $\delta_B > \delta_D$  according to the chosen definition [see Fig. 1(b)], so it is always nonzero, since  $\delta_D \ge 0$ according to the structure of Eqs. (1). Therefore, the bright mode becomes unstable only if the pump amplitude exceeds some threshold value.

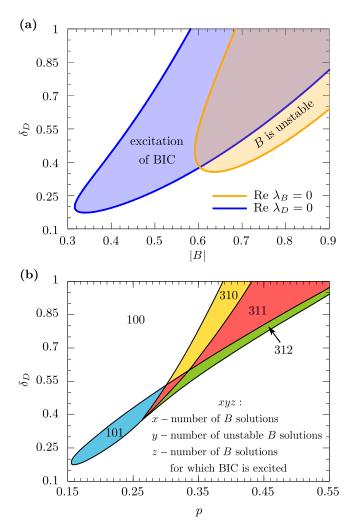


FIG. 3. (a) Arnold tongues (shaded areas) indicate the regions where the bright mode is unstable and the parametric excitation of the BIC is possible. These regions are defined by the inequalities (5). Inside the blue shaded area the solution D = 0 is unstable, i.e., Re  $\lambda_D > 0$ , and the BIC can be excited. Similarly, the shaded orange area indicates the instability of the bright mode. Panel (b) shows possible regimes of the bright mode stability and BIC excitation. Numerical *xyz* code has the following meaning: *x* stands for the total number of the bright mode solutions, *y* shows how many of them are unstable (i.e., Re  $\lambda_B > 0$ ), and *z* indicates the number of bright solutions for which excitation of the BIC is possible (i.e., Re  $\lambda_D > 0$ ). For example, 312 means that there are 3 bright solutions, 1 of them is unstable, and 2 of them lead to excitation of the BIC. Each graph in this figure was plotted for  $\Gamma_D = 0.1$ ,  $\Gamma_B = 0.35$ ,  $\delta_B = \delta_D + 0.25$ , and  $\alpha = 1$ .

The diagram in Fig. 3(b) summarizes possible stability regimes of the bright mode and the BIC solutions assuming variation of the pump amplitude p and the detuning  $\delta_D$ . These regimes are labeled by a numerical xyz code, where x is the total number of solutions, y shows how many of these solutions are unstable, and z stands for the number of solutions for which excitation of the BIC is possible, i.e., when Re  $\lambda_D > 0$ . For example, the region labeled as 100 in Fig. 3(b) indicates that Eqs. (1) have only one solution for B which is stable and the BIC is not excited. Similarly, the region labeled as 312 in

the same diagram corresponds to the case when Eqs. (1) have three solutions for *B*: one of them is unstable (bistability), and the parametric excitation of the BIC takes place for two of the solutions.

Thus, we have analyzed the conditions necessary for the excitation of the BIC. The next question that we are going to answer is, Are there any stable states after BIC excitation?

# **IV. HYBRID STATES**

In Sec. III we analyzed the solutions of Eqs. (1) for which  $D(\tau) = 0$ . However, these are not all stationary solutions. When the symmetry breaks, the division of the solutions into the symmetric and antisymmetric solutions is no longer applicable and stationary hybrid states can appear. For the hybrid states, both *B* and *D* are not zero. To find all possible stationary hybrid solution we need to set all time derivatives in Eqs. (1) without the assumption that  $D(\tau) = 0$ .

Figures 4(a)-4(d) show the dependence of the amplitudes |B| and |D| on the pump p for the stationary solutions of Eqs. (1) accounting for the hybrid states. The dependencies in panels (a), (c) and (b), (d) are plotted for the same parameters as in Figs. 2(a) and 2(b), respectively. One can see that for some solutions both amplitudes B and D are not zero and, thus, the states are hybrid. The stable solutions are plotted with thick lines and the unstable solutions are plotted with thin lines.

One can see that Eqs. (1) have a simple form but their solutions are very manifold. The diagram in Fig. 4(e) summarizes possible stability regimes of the considered system depending on the pump amplitude p and the detuning  $\delta_D$ . Each region is labeled by a numerical xy code, where x is the total number of solutions and y shows how many of them are stable. For example, in the region labeled as 32 there are three solutions and two of them are stable. Note that hybrid states are doubly degenerate; thus, they are counted twice in the number of solutions. This degeneracy arises from the symmetry of a structure as the coupled oscillators are identical in the considered case. When the oscillators are not identical (for example, in photonics this corresponds to the case of an asymmetric unit cell [49]), these states may have different energies and the degeneracy lifts off. In particular, for the RLC circuits considered in the Supplemental Material [75] this means that elements of the coupled circuits have different parameters.

The stability analysis of the hybrid solutions does not reveal the process of their formation. To gain deeper insight into this problem we consider the time dynamics of the BIC excitation and multistability of the bright mode.

# V. TIME DYNAMICS

#### A. Excitation of BIC

As we mentioned above, the parametric excitation of the BIC is possible due to the spontaneous symmetry breaking when the amplitude *B* of the bright mode reaches a threshold value at which the division of the solutions into symmetric and antisymmetric is not energetically favorable. To demonstrate this effect numerically we should add a weak perturbation to the initial condition  $D(\tau) = 0$ . Equations (1) are solved

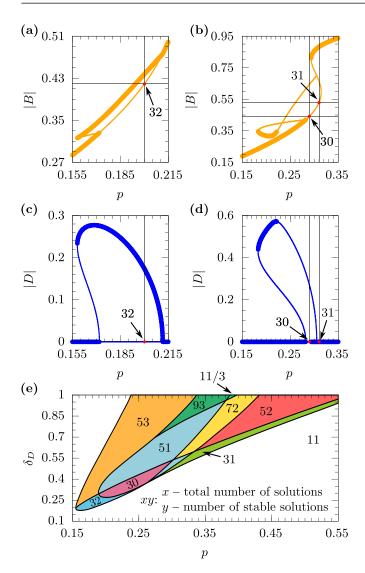
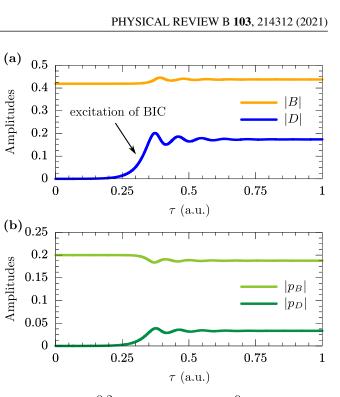


FIG. 4. Stationary solutions represented as the dependence of |B|and |D| amplitudes on the amplitude of pump p. Thick dots represents the stable solutions and thin dots are for unstable solutions. Detuning is  $\delta_D = 0.25$  for (a) and (c), and  $\delta_D = 0.5$  for (b) and (d). The diagram (e) shows possible stability regimes of the stationary solutions. Numerical xy code has the following meaning: x stands for the total number of solutions and y shows how many of these solutions are stable. Solutions  $D \neq 0$  are doubly degenerate, which is accounted for by the number of solutions. The dependencies are plotted for the following parameters:  $\Gamma_D = 0.1$ ,  $\Gamma_B = 0.35$ ,  $\alpha = 1$ , and  $\delta_B = \delta_D + 0.25$ .

numerically by a standard method implemented in Python using the SciPy library. For the cross-check, the same solutions were obtained with the help of the standard ODE solver implemented in MATLAB.

As an example, we took the following parameters: p = 0.2,  $\delta_D = 0.25, \delta_B = 0.5, \Gamma_D = 0.1, \Gamma_B = 0.35, \alpha = 1$ . According to the analysis from Sec. IV, these parameters correspond to the region labeled as 32 in Fig. 4(e), i.e., when three solutions exist: one unstable pure bright solution and one stable doubly degenerate hybrid solution [see the red points in Figs. 4(a) and 4(c) labeled as 32].



Amplitudes

Amplitudes

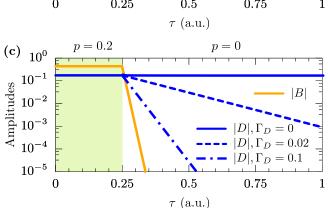


FIG. 5. (a) Stable hybrid solution, which exists in the system constantly pumped with amplitude p = 0.2. Here  $\Gamma_D = 0.1$ . (b) Corresponding values of  $|p_{B,D}|$  show that the effective driving force acting on the modes actually may change with time due to the nonlinear coupling even if the pump amplitude is constant. (c) Demonstration of the energy locking. The system initially is in a stable hybrid state, constantly pumped with amplitude p = 0.2(shaded area). Then at time  $\tau = 0.25$  the pump is switched off, so the bright mode amplitude quickly decreases to zero. The BIC can remain in the system for a longer period of time, defined by the decay rate  $\Gamma_D$ , which accounts for nonradiative losses. All graphs in this figure were obtained for  $\Gamma_B = 0.35$ ,  $\alpha = 1$ ,  $\delta_D = 0.25$ , and  $\delta_B = 0.5.$ 

The time dynamics of B and D are shown in Fig. 5(a). Initially, the system is in a state when |D| = 0 and |B| is a constant but this state is unstable and the introduced fluctuation in D develops: the BIC is excited. We can see that the system tends to another stationary stable solution, which is a hybrid. Thus, we can conclude that the hybrid solution is an attractor. Indeed, the phase portrait demonstrated in Appendix B [see Fig. 7(a)] reveals the presence of a focus point, associated with the stable hybrid solution.

The energy exchange between the BIC and bright mode can be interpreted in terms of the nonlinear driving forces, which can be written as

$$p_D = i\alpha B^2 D^*, \tag{7}$$

$$p_B = i\alpha D^2 B^* + p. \tag{8}$$

Figure 5(b) demonstrates that the change in amplitudes *B* and *D* is induced by these corresponding driving forces  $p_B$  and  $p_D$ . The amplitude *D* of the BIC starts to grow with the increase of  $p_D$  caused by the coupling with the bright mode.

#### B. Trapping of energy by BIC

In open linear systems, the coupling matrix is symmetric [77]. This means that the coupling and decoupling rates are equal to each other. In particular, an infinite radiative lifetime of a photon in a resonator implies a complete decoupling of the resonator's mode from the radiative continuum that makes it impossible to excite the mode from the far-field. However, in nonlinear systems, this issue can be overcome as the coupling of the mode with the radiative continuum depends on the pump intensity. In our case, the coupling of the BIC to the continuum is governed by the amplitude of

the bright mode *B* [see Eqs. (1)]. This allows not only the excitation of the BIC but also the trapping of energy inside the system for a long time [58]. Indeed, let us imagine that the BIC is excited and the system is in a hybrid stationary state supported by an external pump. After the pump is switched off, the amplitude *B* decreases fast due to the radiation of the bright mode. It results in vanishing coupling of BIC to the radiation continuum as it is proportional to the coupling term in Eqs. (1) proportional to  $B^2$ . Therefore, the energy initially pumped to the BIC is trapped.

Figure 5(c) clearly demonstrates the behavior of the BIC and the bright mode in this scenario. The system is set into a stationary hybrid state supported by a permanent external pump with amplitude p = 0.2. One can see that after switchoff of the pump at  $\tau = 0.25$ , the amplitude of the bright mode *B* decays rapidly but the amplitude of the BIC becomes constant in the absence of nonradiative loss ( $\Gamma_D = 0$ ); thus, the energy is locked in the BIC. In the lossy case, the storage time is completely defined by  $\Gamma_D$  [see dashed and dot-dashed lines in Fig. 5(c)]. This effect may be used for the realization of optical memory [58,78].

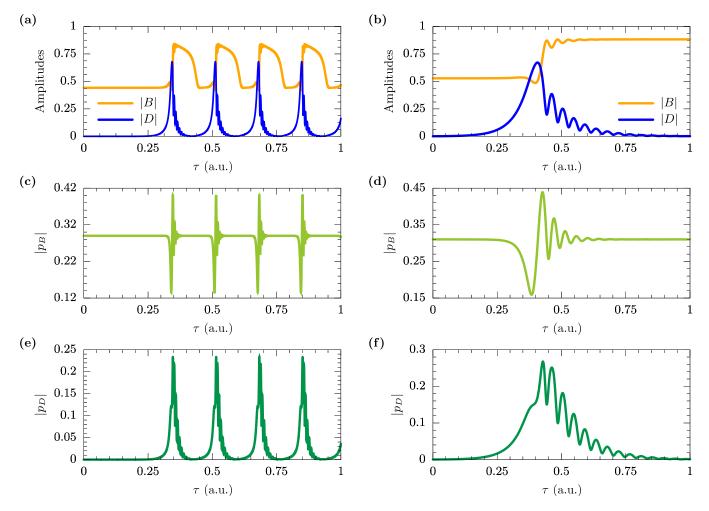


FIG. 6. (a) Time dynamics of the self-oscillatory regime occurring in a system pumped with constant amplitude p = 0.29, and (c), (e) corresponding graphs for the driving forces. (b) Single-pulse excitation of the BIC. Amplitude of the pump remains constant, p = 0.31. Panels (d) and (f) show corresponding dynamics of the driving forces  $p_{B,D}$ . Each graph in this figure was obtained for  $\Gamma_D = 0.1$ ,  $\Gamma_B = 0.35$ ,  $\alpha = 1$ ,  $\delta_D = 0.5$ , and  $\delta_B = \delta_D + 0.25$ .

### C. Regime of self-oscillations

It is interesting to note that the instability of the bright state can lead to the dynamical regime of self-sustained oscillations. This happens when the system has no stable states at all. An example of such a region is labeled as 30 in Fig. 4(e). Indeed, one can also see from Fig. 4(b) that the black vertical line p = 0.29 does not cross the thick orange curve; thus, there are no unstable solutions for such a pump amplitude. Similar behavior was also discussed in Ref. [74].

The time dynamics of |B| and |D| for this case are shown in Fig. 6(a). The parameters of the system are listed in the caption. The system is initially in an unstable bright state. Then the instability is developed and the amplitude of the BIC grows reaching some maximal value. However, after that the system returns back to the state close to the initial bright solution, since the effective driving force  $p_D$  decreases to zero. Then the process repeats, so the system oscillates as Fig. 6(a)shows. This behavior of the system also can be traced with the phase portrait presented in Fig. 7(b) in Appendix B. The initial point corresponding to  $D \approx 0$  is actually a saddle point. In this case the system is stable with respect to fluctuations in B, but unstable with respect to fluctuations in D. Therefore, the trajectory near this point is hyperbolic. Moreover, the system follows the closed path since the effective driven forces  $p_B$ and  $p_D$  also demonstrate a periodic behavior [see Figs. 6(c) and 6(e)]. Each period of such self-oscillations is associated with the presence of a large number of equidistant harmonics [see Fig. 7(d) in Appendix B], which is a manifestation of a frequency comb generation. The idea to use the BIC in systems with Kerr nonlinearity for frequency comb generation is also discussed in Ref. [79].

Let us also remark that the transition from the unstable pure bright state to the stable pure bright state can be accompanied by the excitation of the BIC. The time dynamics of |B| and |D| for this case are shown in Fig. 6(b). The instability results in growth of D but the rise of the bright mode amplitude Bdecreases the effective gain for the BIC [see Figs. 6(d) and 6(f)]. As a result, the system switches from the unstable to the stable bright state and during this transition the BIC is excited. This is the case labeled as 31 in Fig. 4. The phase portrait in this case represents the movement of the system from an unstable node to a stable node, as Fig. 7(c) in Appendix B demonstrates.

### **VI. CONCLUSION**

To conclude, we have developed a theory describing the parametric excitation of symmetry-protected BICs in nonlinear systems with Kerr-type nonlinearity due to spontaneous symmetry breaking resulting in a coupling of the BIC to the bright mode of the system. The proposed theory is very general. It is based on the two coupled oscillators model that can be applied to a variety of physical systems in optics, acoustics, hydrodynamics, quantum mechanics, etc. The obtained results are especially important for photonics as they provide useful guidelines for the excitation of BICs from the far-field. We also provided a detailed analysis of possible stable and unstable solutions accounting for hybrid states that appear as a result of coupling between the BIC and bright mode. We revealed several interesting regimes of the nonlinear system supporting the BIC. In particular, we have shown that the energy from the far-field can be trapped by the BIC for a long time, which is limited only by nonradiative losses of the BIC. We also have found regimes when there are no stable solutions at all. The numerical analysis of the time dynamics shows that such regimes can be potentially used for the frequency combs or supercontinuum generation. We believe that our findings can help to extend the practical applicability of the BIC in different systems. Especially, the obtained results can be very promising for nonlinear photonics and all-optical networks.

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## APPENDIX A: STABILITY ANALYSIS OF STATIONARY SOLUTIONS OF COUPLED-MODE EQUATIONS

In this section, we provide details on the procedure of stability analysis of stationary solutions of Eqs. (1) and (2). We actually use a conventional method based on the determination of eigenvalues [80]. For that, coupled-mode equations for the bright mode and BIC can be linearized with

$$B = (B + m_1 e^{\lambda \tau} + n_1 e^{\lambda^* \tau}) e^{i\delta_D \tau},$$
  
$$D = (D + m_2 e^{\lambda \tau} + n_2 e^{\lambda^* \tau}) e^{i\delta_D \tau},$$
 (A1)

where  $m_{1,2}$  and  $n_{1,2}$  are some small arbitrary functions. Therefore, the coupled-mode equations transform to

$$\lambda m_2 = K_D m_2 + Q n_2^* + R m_1 + S n_1^*,$$
  

$$\lambda^* n_2 = K_D n_2 + Q m_2^* + R n_1 + S m_1^*,$$
  

$$\lambda m_1 = K_B m_1 + Q n_1^* + R m_2 + S n_2^*,$$
  

$$\lambda^* n_1 = K_B n_1 + Q m_1^* + R n_2 + S m_2^*.$$
 (A2)

In combination with the conjugated versions of these equations, the matrix form can be written as

$$\begin{pmatrix} K_B - \lambda & R & Q & S \\ R & K_D - \lambda & S & Q \\ Q^* & S^* & K_B^* - \lambda & R^* \\ S^* & Q^* & R^* & K_D^* - \lambda \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \\ n_1^* \\ n_2^* \end{pmatrix} = 0,$$
(A3)

where the following notation is used:

$$S = 2i\alpha BD, \quad Q = i\alpha (B^2 + D^2),$$
  

$$R = 2i\alpha (BD^* + DB^*),$$
  

$$K_B = -i\delta_B - \Gamma_B + 2i\alpha (|B|^2 + |D|^2),$$
  

$$K_D = -i\delta_D - \Gamma_D + 2i\alpha (|B|^2 + |D|^2).$$
 (A4)

Calculation of the determinant gives the fourth-order equation for eigenvalues  $\lambda$ . A solution is considered to be unstable if at least one Re  $\lambda$  has a positive real part.

$$B(\tau) = (B + me^{\lambda_B \tau} + ne^{\lambda_B^* \tau})e^{i\delta_D \tau}, \qquad (A5)$$

leading to the following system of equations:

solution introducing similar linearization,

$$\begin{pmatrix} K - \lambda_B & Q \\ Q^* & K^* - \lambda_B \end{pmatrix} \begin{pmatrix} m \\ n^* \end{pmatrix} = 0,$$
 (A6)

where the following notation is used:

$$Q = i\alpha B^2$$
,  $K = -i\delta_B - \Gamma_B + 2i\alpha |B|^2$ . (A7)

The above system has solutions when the matrix determinant is equal to zero. This condition allows us to obtain the equation for  $\lambda_B$ , which is simply the quadratic equation with a solution

$$\lambda_B = -\Gamma_B \pm \sqrt{-\delta_B^2 + 4\alpha \delta_B |B|^2 - 3\alpha^2 |B|^4}.$$
 (A8)

The same analysis can be done for the trivial dark mode solution. In this case we use

$$D(\tau) = (me^{\lambda_D \tau} + ne^{\lambda_D^* \tau})e^{i\delta_D \tau}.$$
 (A9)

The obtained system of equations for  $\lambda_D$  will be fully equivalent to the system for  $\lambda_B$ ; hence the result differs only in parameters:

$$\lambda_D = -\Gamma_D \pm \sqrt{-\delta_D^2 + 4\alpha \delta_D |B|^2 - 3\alpha^2 |B|^4}.$$
 (A10)

## APPENDIX B: PHASE PORTRAITS AND FREQUENCY COMB GENERATION

Here, we consider phase portraits of dynamical regimes considered in Sec. V. Excitation of the stable hybrid solution is associated with a stable focus point and a corresponding spiral trajectory. An example of the phase portrait for this case is demonstrated in Fig. 7(a). On the other hand, the self-oscillatory regime is associated with a closed-loop trajectory, as Fig. 7(b) shows. The solution corresponding to D = 0 is

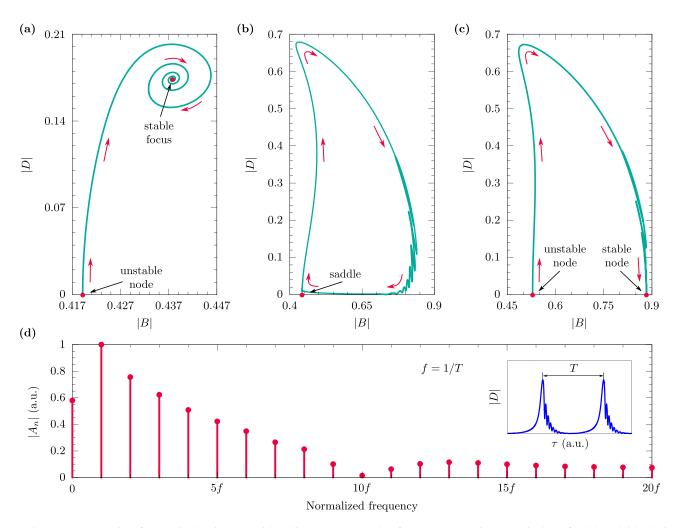


FIG. 7. Phase portraits of dynamical regimes considered in Sec. V. (a) Stable focus corresponding to excitation of stable hybrid solution [Fig. 5(a)], (b) closed-loop trajectory corresponding to self-oscillations [Fig. 6(a)], and (c) stable node corresponding to a pulse excitation of the BIC [Fig. 6(b)]. System trajectories are depicted by red arrows and red dots indicate fixed points of different types. (d) Frequency comb generation: coefficients of a Fourier series for a single period of self-oscillations [Fig. 6(a)]. The coefficients are normalized on a maximal value.

stable and therefore this point should be stable for the pure bright state. However, the presence of fluctuations in D results in excitation of the BIC and the system moves away from this point. Hence, trajectories in horizontal directions point to a stable point corresponding to the case when D = 0, but at the same time trajectories in vertical direction point out this point because of the instability of the D amplitude. Therefore, this point is a saddle and trajectories near it are hyperbolic. When the amplitude D reaches its maximal value the effective driven force  $p_D$  decreases and the system tends to return to the initial point. But in the vicinity of the saddle, fluctuations in D start to grow again, so the system repeats the path in phase space. The single period of such self-oscillations is associated with generation of a large number of harmonics, as Fig. 7(d) demonstrates, where

$$|A_n| = \sqrt{a_n^2 + b_n^2}, \quad n = 0, 1, \dots,$$
 (B1)

such that  $a_n$  and  $b_n$  are coefficients of the corresponding Fourier series:

$$a_m = \frac{2}{T} \int_0^T F(t) \sin\left(\frac{2\pi mt}{T}\right) dt, \quad a_0 = \frac{1}{T} \int_0^T F(t) dt,$$

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$$b_m = \frac{2}{T} \int_0^T F(t) \cos\left(\frac{2\pi mt}{T}\right) dt, \quad b_0 = 0,$$
 (B2)

where m = 1, 2, ... Therefore, the function in the time domain can be represented as

$$F(t) = a_0 + \sum_{m=1}^{\infty} \left[ a_m \sin\left(\frac{2\pi mt}{T}\right) + b_m \cos\left(\frac{2\pi mt}{T}\right) \right].$$
(B3)

Each coefficient  $A_n$  is associated with the corresponding frequency nf, such that f = 1/T, where T is the period of self-oscillations [see the inset of Fig. 7(d)]. Importantly, the harmonics are equidistant and hence it can be stated that self-oscillations of the system result in the formation of a frequency comb. Finally, single-pulse excitation of the BIC corresponds to switching from one pure bright state to another pure bright state, and hence the phase portrait in this case represents a movement from an unstable node to a stable one, as Fig. 7(c) shows.

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