Localized charges in thin films by Kelvin probe force microscopy: From single to multiple charges

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The study of thin-film materials is a subject of growing interest. Some of these materials are insulating due to the presence of disorder, which also produces localization of charges. Kelvin probe force microscopy (KPFM) is a unique tool to characterize these materials, but a full quantitative interpretation of the results is still lacking. To address this problem, we propose a simple and fast procedure based on the image charge method that represents an advance in this direction since it is not limited to any film thickness or the nature of the underlying substrate. Even more, it can be combined with fast Fourier transform algorithms to generate theoretical images from known charge distributions or to obtain charge distributions from the Kelvin voltage images. Within this framework, we analyze the problem of the lateral resolution of the technique, providing a criterion to estimate it. Finally, we address the problem of systems with hopping conductivity where multiple localized charges coexist. We demonstrate that even in these complex systems, the KPFM gives valuable information, allowing us to distinguish between noninteracting and interacting electronic systems. Furthermore, it is possible to calculate the charge density in the noninteracting case.

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I. INTRODUCTION

The characterization of localized charges on insulating surfaces is a key point in many fields ranging from triboelectric charging studies $[1,2]$, defects in solids $[3-5]$, and nanoclusters [\[6–8\]](#page-6-0) to biological systems such as adsorbed molecules on dielectric substrates [\[9,10\]](#page-6-0). Moreover, the development of smaller, faster, and ecofriendly optoelectronic devices lies in the use of thin films of novel materials such as conducting polymers, low- and high- κ materials, and two-dimensional (2D) flakelike materials such as graphene oxide (GO), reduced GO, transition-metal dichalcogenides, etc. These materials usually present low or moderate conductivity and are treated as low-crystallinity or glassy systems in which the high degree of disorder induces the localization of the electron wave function, with their conductivity being via hopping mechanisms [\[11–15\]](#page-6-0). In these systems, a direct observation of the charge distribution would be of great importance. It could permit us to map the energy landscape and could give quantitative validity to the theoretical models. Similarly, the possibility of monitoring the charge dynamics, both in equilibrium and when the system is perturbed, is fundamental to link the conductivity with the microscopic parameters, and it would help to elucidate the role of the different underlying processes.

Kelvin probe force microscopy (KPFM) has been revealed as a unique tool to monitor localized charges [\[16,17\]](#page-6-0). It can give invaluable information inaccessible with other techniques since it can be used in highly insulating samples $[12]$. Independent of the experimental KPFM mode, amplitude modulation (AM), frequency modulation (FM), or a heterodyne mode in a static, open-loop, or closed-loop configuration, the KPFM signal V_{KPFM} is

$$
V_{\text{KPFM}} = V_{\text{Charge}} + V_{CPD},\tag{1}
$$

where $V_{CPD} = \Delta \phi / e$ is the classical surface contact potential difference of the electrode work functions $\Delta \phi$ (tip and sample in this case) and V_{charge} is the term that includes the localized charge contribution [\[18\]](#page-6-0). The quantitative analysis of the *V*_{Charge} signal is not straightforward and demands further theoretical modeling. On the one hand, it depends on the tip geometry, the tip-sample distance *z*, and the relative permittivity $(\varepsilon_r = \varepsilon/\varepsilon_0)$ of the different materials of the system. Thus, all these parameters should be characterized during the data acquisition. On the other hand, the absence of analytical expressions, even for the simplest systems, forces us to address the problem numerically. This may require a large computational effort, especially when many charges are involved.

Recently, it was shown that this computation can be drastically reduced by using fast Fourier transform (FFT) algorithms both to generate the theoretical $V_{\text{Charse}}(x, y, z)$ image of a preestablished charge distribution and to directly obtain the charge distribution $q(x, y)$ from an experimental $V_{\text{Charge}}(x, y, z)$ image [\[19\]](#page-6-0). However, in both cases, the Kelvin voltage image that would generate a point charge placed at the center of the image $V_{point}(x, y, z)$ for a specific system and specific working conditions is needed. Simple charge distributions in thick dielectrics for different tip geometries have already been modeled using different approximations [\[7,20–](#page-6-0)[23\]](#page-7-0). Nevertheless, a model to calculate V_{point} for localized charges in thin films supported on metallic or dielectric substrates is still lacking.

In this work we propose a simple and fast procedure based on the image charge method to obtain the *V*_{point} signal when the charges are localized on thin films. This versatile method

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is not limited to any film thickness or nature of the underlying substrate, and it shows that V_{point} is a key quantity that plays an important role in any quantitative interpretation of V_{Charge} images. We then combine the obtained V_{point} with FFT algorithms to generate the expected *V*_{Charge} images for known charge distributions and discuss the final lateral resolution of the technique. Finally, we address the problem of systems with hopping conductivity where multiple localized charges coexist. We demonstrate that even in these complex systems, the KPFM gives valuable information, allowing us to distinguish between noninteracting and interacting electronic systems. Furthermore, it is possible to calculate the charge density in the noninteracting case as well as to validate different models for the electron-electron interaction in the interacting systems.

II. MODEL DESCRIPTION

In order to simplify the following discussion, from now on, we will focus on the *V*_{Charge} contribution of the *V*_{KPFM} signal considering $V_{CP} = 0$. Following the notation of Refs. [\[18](#page-6-0)[,23\]](#page-7-0), the electrostatic energy of the tip-sample system in the presence of charges is

$$
W_{\text{elec}}(V, z) = u_0(z) + u_1(z)V + u_2(z)V^2, \tag{2}
$$

where *V* is the bias voltage between the tip and the sample. The term proportional to V , $u_1(z)$, is due to the interaction of the localized charges with the potential generated by the tip-sample capacitor, while the term $u_2(z)$ is the energy of the capacitor, which is independent of the localized charges. Depending on whether the force or the frequency is used for the KPFM measurements, the *V*_{Charge} signal is

$$
V_{\text{charge}}^{\text{AM}} = -\frac{u_1'(z)}{2u_2'(z)},
$$
 (3)

$$
V_{\text{charge}}^{\text{FM}} = -\frac{u_1''(z)}{2u_2''(z)}.
$$
 (4)

Therefore, in order to obtain V_{charge} , the derivatives of $u_1(z)$ and $u_2(z)$ (with respect to *z*) should be calculated. The image charge method was previously used to calculate both u'_1 and u'_2 for systems with localized charges in thick dielectrics, modeling a metallic spherical tip in front of a semi-infinite dielectric [\[17,](#page-6-0)[23,24\]](#page-7-0). The case of thin films was already considered in Refs. $[25-27]$, but only the u_2 term was obtained. However, to fully solve the problem of localized charges on thin films, the u_1 term is of vital importance and should also be obtained.

According to the superposition principle a general $V_{\text{Change}}(x, y, z)$ can be expressed as

$$
V_{\text{charge}}(x, y, z) = \int dx' dy' dz' \ q(x', y', z') V_{\text{point}}(x, y, z; x', y', z'),
$$
\n(5)

where $q(x', y', z')$ is the charge density of the problem and $V_{\text{point}}(x, y, z; x', y', z')$ is the V_{charge} image corresponding to a single point charge located at (x', y', z') . This expression can be further simplified if we assume that all localized charges

are located at the same height $z' = d$. Then, as explained in Ref. [\[19\]](#page-6-0), we can use FFT algorithms:

$$
V_{\text{Charge}}(x, y) = \text{IFT}[q(\mathbf{k})V_{\text{point}}(\mathbf{k})],\tag{6}
$$

$$
q(x, y) = IFT[V_{\text{charge}}(\mathbf{k})/V_{\text{point}}(\mathbf{k})],\tag{7}
$$

where IFT corresponds to inverse Fourier transform. We see that we can use $V_{\text{point}}(\mathbf{k})$ either to construct the expected *V*_{Charge} image from a known charge density $q(x, y, d)$ or to determine it from an experimental *V*_{Charge} image. The assumption of charges at the same height is reasonable in many experiments where the V_{point} signal is similar for not very different charge heights, such as deposition of charged particles on the surface or in very thin 2D materials. There is no a generic formula to know *a priori* the validity of this approximation, and the dependence of V_{point} on the tip height should be computed for each specific system see Sec. II and Figs. $2(c)$ and $2(d)$ below. However a generic rule can be given: the lower ε_1 and ε_2 are, the better the approximation is. In the opposite limit, when the *V*_{point} signal strongly decreases with the charge depth (large ε_1 and/or ε_2), the KPFM technique is sensitive to only the upper charges, and the "same-height" approximation is still useful to determine the density of these upper charges. For simplicity, in this work we will consider only the case where Eqs. (6) and (7) are valid, although a generalization to the case of charges located at different planes is straightforward and is described in the Supplemental Material [\[28\]](#page-7-0).

Calculation of V_{point} in thin-film materials

Form the previous section it is realized that $V_{\text{point}}(x, y, z, x', y', z')$ plays a key role in the interpretation of *V*charge images. This quantity was calculated for thick dielectrics, but it has not been estimated for the important case of thin-film geometry. Thus, in this section we solve the electrostatic problem, Eqs. (2) – (4) , for a single point charge inside a thin film. A scheme of our system is shown in Fig. [1.](#page-2-0) A metallic spherical tip (of radius *R* at constant potential *V*) is placed (at a tip-surface distance *z*) on top of a thin layer of thickness *h* and relative permittivity ε_1 supported by a semi-infinite substrate with relative permittivity ε_2 . Then, a point charge q_0 is placed inside the layer (at $z = d \le 0$).

Since we are interested in calculating the force acting on the sphere due to electrostatic interactions, we need to properly describe the electrostatic potential in the region of ε_0 . This is done using the image charge method by locating image charges inside the sphere and in the subsurface $(z < 0)$ region. To do so, we first calculate the capacitance-related u_2 term in a way similar to Refs. [\[25,27\]](#page-7-0), but we generalize the result to any ε_2 and not only to metal substrates (we recover their results when $\varepsilon_2 \to \infty$).

In order to calculate the image charges, the general problem is divided into two parts. First, due to the layer geometry and the two boundary conditions that need to be fulfilled (at $z = 0$ and $z = -h$) any charge q located at $z_0 > 0$ will produce an infinite set of image charges in the region $z < 0$ according to Table [I,](#page-2-0) where $s_1 = (\varepsilon_1 - 1)/(\varepsilon_1 + 1)$ and $s_2 =$ $(\varepsilon_2 - \varepsilon_1)/(\varepsilon_2 + \varepsilon_1)$. Second, to guarantee a constant potential at the surface of the sphere, any charge q located at **r** outside

FIG. 1. Scheme of the model used.

the sphere will produce an image charge q' located at \mathbf{r}' inside the sphere according to the equations

$$
q' = q \frac{R}{|\mathbf{r}_s - \mathbf{r}|},\tag{8}
$$

$$
\mathbf{r}' = \mathbf{r}_s + \frac{R^2}{|\mathbf{r}_s - \mathbf{r}|^2} (\mathbf{r} - \mathbf{r}_s),
$$
 (9)

where \mathbf{r}_s is a vector pointing to the center of the sphere.

According to these equations, we calculate all the image charges proportional to *V* , starting the procedure with a point charge $Q_0 = 4\pi \varepsilon_0 RV$, located at the center of the sphere, that produces the desired potential at the sphere surface. Then, the equations in Table I must be applied to this charge, producing an infinite set of image charges located at *z* < 0. Each of these charges will generate a new image inside the sphere, which again will produce another infinite set inside the dielectrics and so on. This results in infinite series of infinite charges, both in the sphere and at $z < 0$, that must be truncated to afford the numerical calculation. Afterward, the image charges inside the sphere are used to calculate the u_2 term [\[27,29\]](#page-7-0). As $Q_V = CV$, u_2 is directly obtained:

$$
u_2(z) = -\frac{1}{2}C(z),\tag{10}
$$

TABLE I. Image charges associated with a charge *q* located at $z_0 > 0$.

	Чi	Z.i
$i=0$	$-s_1q$	$-z_0$
$i \geqslant 1$	$(-s_1)^{i-1} s_2^i (s_1^2 - 1) q$	$-z_0-2ih$

TABLE II. Image charges associated with a charge q_0 located at $-h < d < 0.$

i	q_i	Zi
$i \geqslant 0$	$(-s_1s_2)^i(1-s_1)q_0$	$d-2ih$
j	q_i	Z_i
$j\geqslant 0$	$-(-s_1s_2)^{j}(1-s_1)s_2q_0$	$-(d+2(j+1)h)$

where Q_V is the sum of all the charges proportional to V inside the sphere and V is the potential of the battery connected to the sphere.

Now, to obtain u_1 , we need to extend the image charge method to describe a localized charge inside the thin layer. As shown in the Supplemental Material [\[28\]](#page-7-0) (see also Refs. [\[25–27\]](#page-7-0) therein), one charge q_0 located at $-h \leq d \leq 0$ will generate two infinite sets of image charges in the *z* < 0 region, as indicated in Table II. Each of these charges will generate new image charges inside the sphere and in $z < 0$ that, as in the previous case, are calculated with Table I and Eq. (9), all of them proportional to the initial charge q_0 .

The computation of the force between all charges inside the sphere with all charges outside directly leads to the force acting on the sphere $(-u'_1$ and $-u'_2)$. Unfortunately, as stated above, for thin layers we are dealing with an extremely large number of charges that results in a large computational effort (for large ε_1 and ε_2 , if high precision is required, the number of image charges can be larger than $10⁸$). To solve this problem, a practical solution (similar to the one used for u_2) is used to calculate u_1 directly and then calculate the derivative numerically. As shown in Ref. [\[30\]](#page-7-0), the electrostatic energy of the problem (including the battery) can be written as

$$
U_{\rm eff} = \frac{1}{2}q_0 V(\mathbf{r}) - \frac{1}{2}Q^{\rm tot}V,\tag{11}
$$

where $V(\mathbf{r})$ is the electrostatic potential at the location of the charge q_0 and Q^{tot} is the total charge in the sphere. The charge Q^{tot} has two contributions: (i) the sum of all the charges proportional to *V* inside the sphere Q_V and (ii) the sum of all the charges proportional to q_0 inside the sphere Q_{q_0} . As shown above, the first contribution produces a V^2 dependence and is used to calculate u_2 . The potential $V(\mathbf{r})$ also has two contributions: (i) $V_V(\mathbf{r})$, the potential generated by all charges proportional to *V*, and (ii) $V_{q_0}(\mathbf{r})$, the potential generated by all charges proportional to q_0 (except q_0 itself). Collecting the contributions proportional to *V* , we get

$$
u_1 V = (1/2)q_0 V_V(\mathbf{r}) - (1/2)Q_{q_0} V, \qquad (12)
$$

but it turns out that both terms produce identical contributions [\[30\]](#page-7-0), so

$$
u_1 = -Q_{q_0}.\tag{13}
$$

In summary, not only u_2 but also u_1 can be obtained by adding the different image charges inside the sphere. This result is of great importance for the numerical calculation. We not only save computing time, avoiding the double sum that a direct calculation of forces would require, but also, during the numerical calculation, we can save computer memory, deleting all charges for which the corresponding images have been taken into account. Equation (13) also justifies a simple

truncation procedure of the infinite series neglecting any image charge smaller and err $\times q_0$, where we typically used err < 10^{-13} .

Finally, once u_1 and u_2 for different tip distances are computed, we calculate the derivatives numerically in order to obtain the corresponding $V_{\text{point}}^{\text{AM}}$ and $V_{\text{point}}^{\text{FM}}$ from Eq. [\(4\)](#page-1-0). In this way, typical $V_{\text{point}}^{\text{FM}}$ curves (horizontal or lateral profiles), with absolute error lower than 10−6, can be computed with a common modern laptop in a few seconds. We will be pleased to share our code upon request.

From now on, we will focus on the $V_{\text{charge}}^{\text{FM}} = V_{\text{charge}}$ signal since in our model the spherical tip assumption neglects the cone and cantilever contributions and it is well known that $V_{\text{charge}}^{\text{FM}}$ is less sensitive to them than the $V_{\text{charge}}^{\text{AM}}$ one [\[31\]](#page-7-0). A similar analysis could be done for the $V_{\text{Charge}}^{\text{AM}}$ signal. Finally, we would like to note that in this work the contribution of u_0 is not used, but according to Eq. (11) , it can also be easily calculated if needed, adding the potential generated at **r** by all charges proportional to *q*0.

III. RESULTS

A. Model applications

It is not the aim of this work to exhaustively explore and analyze all the possible systems but to show the potential of the proposed method, especially for complex multiplepoint-charge distributions. However, to show its versatility, some relevant examples are calculated in Fig. 2, where V_{point} of a point charge as a function of the tip-sample distance together with the corresponding lateral profiles at $z = 0.5R$ for different configurations are plotted.

Figures $2(a)$ and $2(b)$ show the dependence of V_{point} on the film thickness *h*. Another important case is when the localize charge is not at the surface but buried within the thin layer, as shown in Figs. $2(c)$ and $2(d)$. In this situation, depending on the depth of the charge d , V_{point} may increase or decrease with the tip-sample distance. However, for a fixed distance, the deeper the charge is, the smaller the $V_{\text{point}}^{\text{FM}}$ signal is [Fig. 2(d)]. This means that, in systems with localized charges at different depths, the main contribution to V_{Charge} will come from the upper charges. Finally, changing ε_1 with respect to ε_2 [see Fig. $2(e)$], V_{point} decreases for short distances and increases for large distances with a minimum at $z \approx R$. Besides that, other behaviors can be found for different parameter combinations; the previous results highlight that not only *h*, *d*, and ε_1 but also z and ε_2 of the underlying substrate greatly affect the contrast of the *V*_{Charge} images. While the former are usually related to the studied thin-film material, the latter can be tuned (selecting the appropriate substrate) to optimize the KPFM measurements.

B. *V***Charge image generation and lateral resolution**

From the lateral profiles shown above and taking advantage of the uniaxial symmetry, we directly obtain the V_{point} image for a specific system $(\varepsilon_1, \varepsilon_2, h, \text{ and } d)$ and measurement parameters $(R, z, \text{ image size } L \times L, \text{ and image number of})$ points $n \times n$). Then, by using Eq. [\(6\)](#page-1-0) we generate a theoretical $V_{\text{Charge}}(x, y, z)$ image produced by an *ad hoc* charge distribu-

FIG. 2. Left: $V_{\text{charge}}^{\text{FM}}$ as a function of the tip-sample distance *z*. Right: Lateral profiles at $z = 0.5R$. (a) and (b) $\varepsilon_1 = 3.9$, $\varepsilon_2 =$ 12, *d* = 0, and *h* = 0.05, 0.1, 0.3, 0.5, 0.7, 1, 3, 5, 10, 20 and 50 (*R* units). The two limits $h = 0$ and $h = \infty$ have been included (dashed lines). (c) and (d) $\varepsilon_1 = 3.9$, $\varepsilon_2 = 12$, $h = 1$, and $d = 0, 0.2, 0.3, 0.4$, 0.5, 0.6, 0.7, 0.8, 0.9, 1 in *R* units. (e) and (f) $\varepsilon_2 = 3.9$, $h = R$, $d =$ 0, and $\varepsilon_1 = 3.9, 4, 6, 8, 10, 12, 15, 17, 20, 30, 40, 50, 70.$

tion $q(x, y)$ [\[19\]](#page-6-0). In order to show this procedure, two V_{point} calculated for the same system ($h = R = 15$ nm, $d = 0$, $\varepsilon_1 =$ 3.9, $\varepsilon_2 = 12$, $L = 600$ nm) but at different tip-sample distances $(z = 7$ and 28 nm) are used to obtain the corresponding *V*Charge images of a charge distribution consisting of three pairs of charges separated 7, 14, and 28 nm, respectively [Figs. $3(a)$] and $3(b)$]. This simple example is useful to address the lateral resolution question that in any KPFM experiment is typically discussed directly from *V*_{KPFM} profiles. In the presence of localized charges, this lateral resolution is directly related to the broadness of the corresponding V_{point} and mainly depends on the measurement parameters (*R* and *z*) [\[17\]](#page-6-0). However, it is important to note that a better lateral resolution can be achieved by analyzing the $q(x, y)$ image that is obtained from Eq. [\(7\)](#page-1-0). A noisy experimental *V*_{Charge} image can be expressed as

$$
V_{\text{charge}}(x, y, z) = V_{\text{charge}}^{\text{ideal}}(x, y, z) + \sigma^{\text{noise}}(x, y), \quad (14)
$$

where $V_{\text{charge}}^{\text{ideal}}(x, y)$ is the ideal noise-free image generated by an underlying charge distribution and $\sigma^{noise}(x, y)$ is the noise matrix. Then,

$$
q(x, y) = IFT\left(\frac{V_{\text{charge}}^{\text{ideal}}(\mathbf{k}) + \sigma^{\text{noise}}(\mathbf{k})}{V_{\text{point}}(\mathbf{k})}\right).
$$
 (15)

FIG. 3. (a) Generated $V_{\text{Charge}}^{\text{FM}}$ image of $q(x, y)$ of three pairs of charges separated 7, 14, and 28 nm in a system with parameters $h = R$ 15 nm, $d = 0$, $\varepsilon_1 = 3.9$, $\varepsilon_2 = 12$, $L = 600$ nm, and $z = 7$ nm. (b) Simulated experimental images with a random Gaussian noise ($\sigma = 15$ mV). (c) $q(x, y)$ image obtained after IFT deconvolution with k_c given by Eq. (17). (d)–(f) Same images as (a)–(c), but obtained at $z = 28$ nm. (g) $q(\mathbf{k}) = \frac{V_{\text{Change}}(\mathbf{k})}{V_{\text{point}}(\mathbf{k})}$. The dashed vertical lines indicate the k_c used in each of the cases.

In an ideal noise-free image ($\sigma^{\text{noise}} = 0$), Eq. [\(15\)](#page-3-0) would lead to the exact charge distribution. In practice, the final lateral resolution of the $q(x, y)$ image is limited by the cutoff k_c of the filter applied to $[V_{\text{charge}}^{\text{ideal}}(\mathbf{k}) + \sigma^{\text{noise}}(\mathbf{k})]/V_{\text{point}}(\mathbf{k})$ needed to avoid nonphysical artifacts produced by different sources of noise [\[19\]](#page-6-0). This cutoff determines the real lateral resolution δ*x* that can be achieved, as it is roughly half of the wavelength related to k_c :

$$
\delta x \approx \frac{\pi}{k_c}.\tag{16}
$$

This k_c can be easily estimated from Eq. (15) [see also Fig. 3(g)]. If the main source of noise is white noise, $\sigma^{\text{noise}}(\mathbf{k})$ is approximately constant in amplitude, while $V_{\text{point}}(\mathbf{k})$ decays exponentially with *k* [as does $V_{\text{charge}}^{\text{ideal}}(\mathbf{k})$]. So a good estimation of k_c is obtained from the ratio

$$
\frac{\sigma^{\text{noise}}(k_c)}{V_{\text{point}}(k_c)} \approx 1. \tag{17}
$$

Actually, under an appropriate data filtering this resolution can be slightly improved $[19]$. These ideas are shown in Figs. $3(b)$ and $3(e)$, where experimental images are simulated by adding a random Gaussian noise to each image point of Figs. $3(a)$ and $3(d)$. In order to obtain the corresponding $q(x, y)$ images [Figs. $3(c)$ and $3(f)$], the cutoff radius has been used in each case following the previous criterion. In Fig. $3(g)$ it can be observed how the apparent $q(\mathbf{k})$ grows exponentially after the dashed line due to the effect of $\sigma^{\text{noise}}(\mathbf{k})$ (the flat behavior for large *k* is due to numerical errors).

C. Multiple-charge distributions: Effect of charge correlations

The previous methodology allows us to address the study of systems where multiple charges coexist [\[1,2,](#page-6-0)[32–34\]](#page-7-0). In this section we will focus on thin-film systems with hopping conductivity where charge localization plays a crucial role

[\[11–15\]](#page-6-0). These systems are characterized by a large amount of disorder that produces the localization of charges, and the electronic transport takes place via activated tunneling: electrons hop from a localized occupied state to an empty one assisted by phonons. Coulomb interaction between charges is especially important in the strongly localized regime because the low mobility of charges results in a drastic reduction of the screening. One significant effect of the interaction is that, at low temperatures, the density of states is greatly reduced, and a soft gap is opened at the Fermi level, as predicted by Pollak [\[35\]](#page-7-0) and characterized by Efros and Shklovskii [\[36\]](#page-7-0). In this case conductivity follows an Efros-Shklovskii variablerange hopping (VRH) law. At high temperatures, interactions become less important, and as a result the soft gap is filled, and conduction changes to a Mott VRH law. In general, we can expect that correlations between charges become negligible when $kT > U$, where U is the typical interaction energy between nearest-neighbor localized charges. In order to analyze how the interactions and correlation between charges modify the *V*Charge images, we have generated correlated and noncorrelated $q(x, y)$ distributions using a standard electron glass model [\[37,38\]](#page-7-0) considering a squared system of size $L \times L$ with *N* sites randomly distributed:

$$
\mathcal{H} = \sum_{i=1}^{N} \epsilon_i n_i + U_0 R \sum_{i < j} \frac{(n_i - K)(n_j - K)}{r_{ij}},\qquad(18)
$$

where N is the number of sites. The first term on the righthand side includes the effect of disorder, n_i is the occupation of one site (which is either 0 or 1), and ϵ_i is a random energy in the interval [−*W*/2,*W*/2], where *W* measures the strength of disorder. The second term corresponds to the Coulomb interaction between sites, where K is the mean occupation of one site (we consider $K = 1/2$). The strength of interaction is determined by U_0R , where *R* is the tip radius. Then, U_0

FIG. 4. *V*_{Charge} images from $q(x, y)$ with an increasing number of charges generated with the same V_{point} ($\varepsilon_1 = 3.9$, $\varepsilon_2 = 12$, $h = 15$ nm, $R = 15$ nm, $z = 7$ nm); image lateral size $L = 500$ nm for (a)–(d) noninteracting and (e)–(h) interacting systems. To highlight the differences between the two types of systems, the *z* scale has been fixed to ± 120 mV in all the images.

corresponds to the interaction energy of two unit charges separated by a tip radius, and we will fix $U_0 = 1$ as the unit of energy. Although, so far, this analysis must be considered qualitative, we have fixed some quantities to realistic values: $L = 500$ nm, $W = 2U_0$, and the localization length is assumed to be smaller than 2 nm to consider a point charges distribution in a *V*_{Charge} image. Finally, to get typical equilibrium configurations of $q(x, y)$, we performed Monte Carlo simulations using a metropolis algorithm for electron glasses [\[39\]](#page-7-0). With this model, we can generate multicharge distributions for systems both with interacting, correlated charges (we fixed temperature $kT = 0.03U_0$) and with uncorrelated charges (we fixed $U_0 = 0$, although similar results would have been obtained for interacting systems at high temperatures) and therefore compare their expected *V*_{Charge} images.

An example of how the V_{Change} images evolve as the number of charges *N* is increased is shown in Figs. $4(a) - 4(d)$ for noninteracting systems and Figs. $4(e) - 4(h)$ for interacting systems for $\varepsilon_1 = 3.9$, $\varepsilon_2 = 12$, $h = 15$ nm (e.g., a 15-nm polymer or $SiO₂$ on silicon) imaged with a tip of $R = 15$ nm at a tip-sample distance $z = 7$ nm, with the image lateral size $L = 500$ nm. For these parameters, the typical distance between nearest charges corresponds to $l = 50, 22, 15, 11$ nm. At low charge densities, the localized charges can be resolved individually, and the effect of interaction is almost negligible as the mean distance between particles is large. As *N* increases (decreasing the mean distance between charges), *V*_{Charge} of the noninteracting system develops large bright and dark domains, increasing the overall image contrast. On the contrary, in the interacting system, the domain size and domain contrast are basically constant and insensitive to the number of charges, with the *V*_{Charge} image being very similar independent of *N*. This is understood by noticing that, in a

noninteracting system ($U_0 = 0$ or $kT \ll U_0$), the probability of charge aggregation of the same sign increases with *N* and therefore the domain size and contrast of the generated *V*_{Charge} domains increase. Conversely, in the interacting system $(kT =$ $0.03U₀$), this possibility is not allowed as charges of the same sign strongly repel each other and tend to be surrounded by charges of the opposite sign. In this situation, the average local charge should always be about $\pm e$ independent of N. Then, an alternate domain contrast is expected in the V_{Charge} image, with the domain size being about the width of the corresponding $V_{\text{point}}(x, y, z)$. The above results show that it is possible to distinguish between interacting and noninteracting systems from the overall appearance and contrast of the V_{Charge} image, as the two kinds of systems generate very different images.

According to this discussion we have found that the variance of a $V_{\text{charge}}^{\text{FM}}$ image is a sensitive quantity to determine the effect of interactions (see Fig. [5\)](#page-6-0). This is a simple but interesting quantity also because it is easy to demonstrate that, for the noninteracting case,

$$
\text{Var}\left[V_{\text{charge}}^{\text{FM}}\right] = N\text{Var}\left[V_{\text{point}}\right] + \sigma_{\text{noise}}^2,\tag{19}
$$

where σ_{noise}^2 is the variance of the experimental noise (assumed to be uncorrelated white noise). This relation provides a useful tool to estimate the charge density in noninteracting systems if the parameters of the system are properly characterized. Verification of the results can be obtained by measuring at different tip-sample distances.

The dependence of $Var[V_{\text{charge}}]$ on *N* in the interacting system is more complicated, and it is out of the scope of the present work. However, we note that it is related to charge correlations due to interactions. It strongly depends on the model and the parameters used, as well as on the

FIG. 5. Var^{[$V_{\text{Charge}}^{\text{FM}}$] vs *N* for noninteracting and interacting sys-} tems ($\varepsilon_1 = 3.9$, $\varepsilon_2 = 12$, $h = 15$ nm, $R = 15$ nm, $z = 7$ nm). The solid black line corresponds to Eq. [\(19\)](#page-5-0).

temperature. Nevertheless, Var[V_{Charge}] could be a simple and useful quantity to validate different theoretical interacting models. Also, if V_{point} is well characterized for a system, the charge correlation function can be obtained from the *V*_{Charge} image using FFT methods.

IV. CONCLUSIONS

There is no doubt that the KPFM is a very promising technique to study systems with localized charges, but at the same time, it becomes necessary to improve the quantitative interpretation of the results. In this sense, the image generated by a point charge V_{point} is a key quantity. On the one hand, it allows us to generate theoretical V_{Charge} images to test different physical models. It is also needed in order to calculate the underlying charge distribution from experimental images. In this context, we have proposed a charge image method to calculate it for geometries consistent with most experiments (a layer of thickness *h* and relative permittivity ε_1 on top of another material with relative permittivity ε_2). Even more, we have analyzed the influence of V_{point} in the lateral resolution as well as the role of the image noise, which is the limiting factor of the final lateral resolution of the technique.

In systems with multiple-charge distribution, the *V*_{Charge} image is always composed of bright and dark potential domains. At large charge densities, each domain cannot be assigned either to an individual charge or to an effective charge density. Due to the long-range nature of the electrostatic interaction not only is the *V*_{Charge} contrast due to the charge below the tip, but the nearby charges also have important contributions. However, even in this situation, the quantification of $Var[V_{\text{charge}}]$ makes it possible to determine the density of localized charges for noninteracting systems or at least to measure the importance of interactions. In addition, working with the $q(x, y)$ images obtained from the V_{Change} images by using the V_{point} image calculated with the proposed method would lead to a more accurate analysis. This is particularly important in the study of heterogeneous charge distributions or charge dynamics.

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