Lipkin-Meshkov-Glick model with Markovian dissipation: A description of a collective spin on a metallic surface

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Motivated by recent prototypes of engineered atomic spin devices, we study a fully connected system of N spins 1/2, modeled by the Lipkin-Meshkov-Glick (LMG) model of a collective spin s = N/2 in the presence of Markovian dissipation processes. We determine and classify the different phases of the dissipative LMG model with Markovian dissipation, including the properties of the steady state and the dynamic behavior in the asymptotic long-time regime. Employing variational methods and a systematic approach based on the Holstein-Primakoff mapping, we determine the phase diagram and the spectral and steady-state properties of the Liouvillian by studying both the infinite-s limit and 1/s corrections. Our approach reveals the existence of different kinds of dynamical phases and phase transitions, multistability, and regions where the dynamics is recurrent. We provide a classification of critical and noncritical Liouvillians according to their spectral and steady-state properties.

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I. INTRODUCTION

Quantum systems submitted to nonequilibrium conditions support a rich set of physical phenomena yet to be classified. This endeavor encompasses emergent features found in nonlinear classical dynamics and equilibrium quantum matter but has also the potential to reveal effects unique to nonequilibrium quantum degrees of freedom. Various of these aspects have been explored recently, motivated by advances in the manipulation and control of cold atomic and solid-state setups.

Artificial magnetic structures deposited on metallic surfaces are particular examples of novel setups, where the ability to manipulate and monitor individual atomic spins offers the possibility to study a nonequilibrium quantum open system in a controlled fashion [1-4]. A number of prototypes have already demonstrated the potential of these engineered atomic spin devices for information processing [5-10] and spintronics applications [1,11-13]. The basic setup consists of a set of magnetic atoms deposited on a thin insulating layer coating a metallic surface. Atoms are individually addressable by a spin-polarized metallic tip. Applying a finite bias voltage between the tip and the surfaces induces an inelastic current that can be used to infer properties of the magnetic state [14–19]. For artificial magnetic structures, the most relevant system-environment interaction is the magnetic exchange with the itinerant electrons of the metallic substrate [16,20]. The environment induces an effective memory on the dynamics of the system's density matrix. Although memory effects are generically non-negligible, they can, in some cases, be assumed instantaneous as compared with timescales within

the system. For metallic environments, this Markovian regime is obtained for large temperatures or chemical potentials [21]. In this work, we consider regimes where the bias voltage applied between the tip and the metallic substrate is large. In this case, the master equation for the evolution of the density matrix of the magnetic system, obtained in Ref. [19], is Markovian and reduces to the Lindblad equation [22,23].

We examine the case of a fully connected magnetic structure made of *N* spins-1/2 and study the dynamics in the highest spin sector, which can be modeled by a collective spin s = N/2. In the absence of dissipation, collective spin models have been extensively investigated. Perhaps, one of the best studied is the Lipkin-Meshkov-Glick (LMG) model [24–26]—a ubiquitous system featuring a fully connected set of spins-1/2. Its ground-state properties [27–31], spectrum, correlation functions [32–36], and dynamics [31,37–40] can be systematically obtained in the thermodynamic limit, i.e., large *s* limit, by a semiclassical expansion with 1/*s* playing a role similar to \hbar . Nonperturbative effects can also be captured by semiclassical methods [36].

Markovian dissipation in collective spin models was first considered to describe spontaneous emission of an ensemble of two-level atoms in a superradiant phase [41–44]. Various variants and generalizations of these models have been studied since then [45–49]. These systems belong to a family that we refer to as dissipative Lipkin-Meshkov-Glick models, in analogy with its dissipationless counterpart. In cases where an exact construction of the steady state exists [43,50], correlation functions can be computed exactly. Otherwise, semiclassical methods [45,46] and perturbative 1/s expansions [47] were employed, as well as exact diagonalization, to access the steady state and the spectrum of the Lindblad operator. Such studies revealed the existence of several phases characterized by qualitatively different steady-state properties. These include systems with a single or bistable steady states [46]

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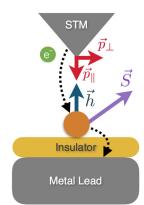


FIG. 1. (a) Schematic representation of the setup. A collective moment is obtained as an effective description of an aggregate of N = 2s magnetic atoms, with a large charge gap, deposited on an insulating layer coating a metallic substrate. Upon applying a voltage difference between the metallic spin-polarized tip and the substrate, a charge current ensues. Two polarization directions are considered: $p = pe_z$ (i.e., $p \parallel h$) and $p = pe_y$ (i.e., $p \perp h$).

or cases where, in the thermodynamic limit, no steady state could be found and the system attains a recurrent periodic orbit, dependent on its initial condition [41-44]. Recently, models featuring independent, i.e., noncollective, spin decay have also been considered [51-53].

Contrarily to their equilibrium counterparts, a classification of quantum critical phenomena in the presence of dissipation has not yet been accomplished despite the significant body of works devoted to the topic [48,54–63]. In particular, dissipative phase transitions have been shown to escape Landau's symmetry breaking paradigm [48,55,57] in some cases but not others [61].

In this paper, we propose a classification of the phases of collective spin models with Markovian dissipation according to their steady-state and spectral properties. To do so, we study the different phases of the dissipative LMG model with Markovian dissipation. The specific form of the jump operators is motivated by a solid-state setup, which features magnetic atoms deposited on a metallic surface, and where spin transport arises by the proximity with a spin-polarized metallic tip held at a finite bias voltage (Fig. 1). To access these properties of the model, we employ variational methods, a systematic Holstein-Primakoff mapping and exact diagonalization studies of the Liouvillian.

Besides helping to understand nonequilibrium states of engineered solid-state devices, our results are also of interest to quantum optics and cold atomic setups, where dissipative phase transitions in optical cavities [64–67] have been observed which can be modeled by variants of the dissipative LMG model.

The paper is organized as follows. The model is introduced in Sec. II. A description of the phase diagrams obtained for two tip polarization directions, as well as the main characteristics of each phase and phase transitions, are given in Sec. III. Section IV A gives a summary account of the 1/s expansion using the Holstein-Primakoff mapping that can be used to systematically compute 1/s corrections of observables. A detailed analysis of the Liouvillian spectrum, dynamics, and properties of the steady state in each of the phases, as well as the phase transition lines are given in Sec. IV. In Sec. V, we give a classification of the different phases and summarize our main findings. We conclude in Sec. VI with the implications of our work. Appendices present some of the details of calculations used to derive the results in the main text. Appendix A provides a derivation of the semiclassical and variational equations of motion. Appendix B contains helpful simulations of the magnetization dynamics for finite-*s* systems and Appendix C details the derivation of the linearized Liouvillian.

II. MODEL

We consider the system depicted in Fig. 1, consisting of a magnetic moment deposited on a metallic surface and in contact with a metallic tip having a spin polarization vector p. The collective magnetic moment that can be of an atom, an artificial atomic structure or a molecule, is modeled by the LMG Hamiltonian

$$H = -\boldsymbol{h} \cdot \boldsymbol{S} - \frac{1}{2s} \left(\gamma_x S_x^2 + \gamma_y S_y^2 \right) \tag{1}$$

with $S_{\alpha=x,y,z}$ obeying the su(2) commutation relations with $S \cdot S = s(s + 1)$. This spin representation is obtained as the symmetric sector of N = 2s two-level systems. The coefficients γ_x , γ_y are determined by the surface anisotropy and h is a local magnetic field. In what follows, we consider that the applied field always points in the direction perpendicular to the surface, i.e., $h = he_z$, and two possible orientations for the polarization vector: a case where the field and the polarization are parallel, with $p = pe_z$; and a case where they are perpendicular, with $p = pe_y$ with $-1 \leq p \leq 1$.

The collective magnetic moment is a good effective description of an atomic aggregate with a large charge gap. The exchange interaction between the magnetic moment and electrons in the metallic leads is induced by virtual processes where the atomic aggregate acquires (donates) and donates (acquires) an electron from the leads. Such processes induce relaxation and decoherence effects to the magnetic state and allow a charge current to ensue in the presence of a finite applied voltage. If the effective exchange coupling is not too strong, a perturbative treatment allows for the description of the dynamics in terms of a (non-Markovian) master equation for the density matrix of the magnetic moment; the details of the derivation can be found in Ref. [19].

A simple limit is recovered for a large bias voltage, where the environment becomes memoryless. In this limit, the effect of the leads is simply to perform spin flips at a constant rate. In case the leads are spin polarized, this yields a net spin transfer. In this Markovian limit, the Liouvillian superoperator \mathcal{L} , determining the evolution of the system's reduced density matrix, $\partial_t \rho = \mathcal{L}(\rho)$, acquires the Lindblad form [22,23]

$$\mathcal{L}(\rho) = -i[H, \rho] + \sum_{i} W_{i}\rho W_{i}^{\dagger} - \frac{1}{2} \{\rho, W_{i}^{\dagger}W_{i}\}, \quad (2)$$

where W_i , with i = +, -, z, are the so called jump operators

$$W_{z} = \sqrt{\frac{\Gamma}{2s}}\tilde{S}_{z}; W_{+} = \sqrt{\frac{\Gamma}{2s}\frac{1-p}{2}}\tilde{S}_{+}; W_{-} = \sqrt{\frac{\Gamma}{2s}\frac{1+p}{2}}\tilde{S}_{-}.$$
(3)

The tilde "~" denotes that the quantization axis of the operator is taken along the polarization of the tip. In the two situations treated here, we have $\tilde{S}_{\alpha} = S_{\alpha}$ for the parallel case and $\tilde{S}_{\alpha} = e^{i\frac{\pi}{2}S_x}S_{\alpha}e^{-i\frac{\pi}{2}S_x}$ for the perpendicular setup. Γ is the rate of the quantum jumps, proportional to the absolute value of the applied voltage (see Appendix G of Ref. [19]).

Under Liouvillian dynamics, the evolution of the density matrix is given by

$$\rho(t) = e^{t\mathcal{L}}\rho(t_0) = \sum_i \exp\left(t\Lambda_i\right) X_i \operatorname{tr}[\tilde{X}_i\rho(t_0)], \qquad (4)$$

where X_i and \tilde{X}_i are respectively left and right eigenvectors of the superoperator corresponding to the eigenvalue Λ_i and normalized such that $tr[X_i \tilde{X}_j] = \delta_{ij}$. The real part of Λ_i is nonpositive and there is at least one zero eigenvalue $\Lambda_0 = 0$ corresponding to left eigenvector $\tilde{X}_0 = 1$.

III. STEADY-STATE PHASE DIAGRAM

In this section, we determine the phase diagram of the model and characterize the different phases according to the qualitative properties of the steady states. As in equilibrium, nonanalyticities in the steady-state observables are only expected once the thermodynamic limit is taken, i.e., $N = 2s \rightarrow \infty$. Since, within the symmetric sector, the total angular momentum is determined by s = N/2, the thermodynamic limit corresponds to that of a large classic spin, $s \rightarrow \infty$.

To approximate the dynamics of $\rho(t)$ in the large *s* limit, we assume an ansatz density matrix of the form $\rho \propto e^{m \cdot S}$, and derive the equation of motion for the vector *m*. Away from phase transition points, this ansatz becomes exact in the $s \rightarrow \infty$ limit and allows for higher-order corrections in powers of 1/s. In Appendices A 2 and A 1, we provide the details of the method and show how this approach compares with the standard mean-field approximation [41–44].

From the ansatz parameter m, we compute the rescaled magnetization vector $\mathbf{n} = \langle S \rangle / s$ and solve the fixed-point condition $\partial_t \mathbf{n} = 0$ in order to obtain the steady-state magnetization. The fixed points of the dynamics are classified as attracting (stable), repulsive (unstable), mixed (saddle points, having at least one attractive and one repulsive direction) or marginal (no attractive or repulsive direction), according to the dynamics in their vicinity. Regarding steady-state properties, different phases are characterized by the number and nature of the fixed points. A change in the number or nature of the fixed points typically corresponds to nonanalyticities of certain observables as well as in the slowest decaying rate towards these points.

We recall that, while all fully-polarized vectors, i.e., |n| = 1, correspond to pure states, vectors with |n| < 1 may correspond both to pure or mixed states.

In the following two sections, we study the two cases shown in Figs. 2 and 3, corresponding to an applied field parallel $(p \parallel h)$ or perpendicular $(p \perp h)$ to the polarization.

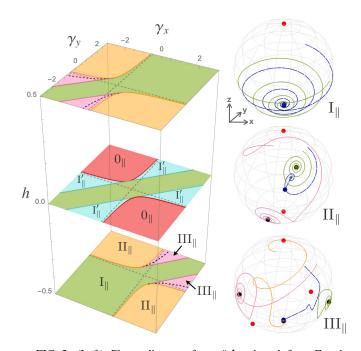


FIG. 2. (Left) Phase diagram for $p \parallel h$, plotted for $p\Gamma = 1$. (Right) Average magnetization $\mathbf{n} = \langle S \rangle / s$ shown for representative states of each phase. Stable (unstable) infinite-*s* steady states are depicted as black (red) points. Representative trajectories in the $s = \infty$ limit are represented in full colored (pink, green and orange) lines. The steady state and the evolution of the magnetization for s = 20 are depicted by a blue point and blue dashed lines, respectively. Parameters: $I_{\parallel} - h = 1$, $\gamma_x = -0.2$, $\gamma_y = -0.3$, $p\Gamma = 0.2$; $II_{\parallel} - h = 1$, $\gamma_x = 0.5$, $\gamma_y = -2.5$, $p\Gamma = 1$; $III_{\parallel} - h = 1$, $\gamma_x = -3$, $\gamma_y = -1.5$, $p\Gamma = 1$.

We qualitatively describe the different phases, as well as the nature of the phase transitions between them based on the steady-state properties and dynamics. The spectral analysis within each phase is relegated to Sec. IV.

The main findings of this section are summarized in Sec. V (see Table I).

A. Parallel polarization

For parallel polarization $(p \parallel h)$ [see Fig. 2 (left panel)], there are three stable phases, I_{\parallel} , Π_{\parallel} , and Π_{\parallel} , in the $\gamma_x - \gamma_y - h$ parameter space, separated by critical surfaces where phase transitions occur. Regions 0_{\parallel} and I'_{\parallel} , arising only at h = 0, are also critical and correspond either to $I_{\parallel} \leftrightarrow \Pi_{\parallel}$ transitions or to transitions between phases Π_{\parallel} with different steady-state symmetries. The critical phases 0_{\parallel} and I'_{\parallel} are similar to some of the phases found in the perpendicular case ($p \perp h$) and we relegate their study for the next section. While phases I_{\parallel} , Π_{\parallel} , and Π_{\parallel} can be distinguished by their number of fixed points (1,2 and 3), the further division within region Π_{\parallel} , depicted as a dashed black line, is obtained by considering steady-state properties at finite *s* (see below).

Figure 2 (right panels) illustrates the dynamics of the average magnetization $\langle S \rangle$ within each phase. Pink, green, and yellow curves correspond to qualitatively different trajectories obtained by our variational method. Attractive fixed points are depicted by black dots and the red dots represent unstable

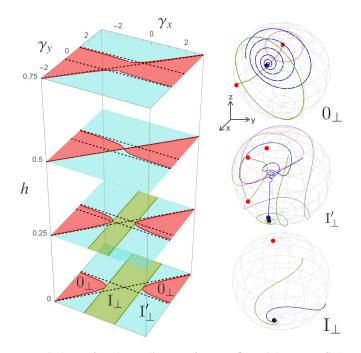


FIG. 3. (Left) Phase diagram for $p \perp h$. (Right) $n = \langle S \rangle / s$ shown for states for the different phases. The color codes are the same as in Fig. 2. In the middle panel (I'_{\perp}), the separatrix separating the two qualitative long-time states of regions 0_{\perp} and I_{\perp} is depicted in gray. The plots are done for the following set of parameters: 0_{\perp} h = 1, $\gamma_x = 0.1$, $\gamma_y = 0.2$, $p\Gamma = 1$; I_{\perp} - h = 1, $\gamma_x = -2$, $\gamma_y =$ 2.1, $p\Gamma = 1$; Γ_{\perp} - h = 0.2, $\gamma_x = 0.1$, $\gamma_y = 1$, $p\Gamma = 1$.

or saddle points. An example of the dynamics for a finite *s*, obtained by exact diagonalization of the Liouvillian, is depicted as blue dashed lines and the steady state attained in the limit $t \rightarrow \infty$ is depicted as blue dots.

1. Phases

Region I_{\parallel} is characterized by a unique stable steady state located along the *z* axis. The average magnetization of the steady state for finite *s* approaches the variational ansatz value up to 1/*s* corrections (almost coinciding blue and black points in Fig. 2, I_{\parallel}). The variational and finite-*s* dynamics (green and blue dashed lines, respectively) yield qualitatively similar results. In addition to the attractive fixed point at the south pole (black dot), an unstable fixed point is located at the north pole (red dot). Saddle points, not present for the choice of parameters of Fig. 2, I_{\parallel} , may appear but do not change the dynamics qualitatively.

In region II_{\parallel} (Fig. 2, II_{\parallel}), we find two variational steady states related by symmetry. For finite-*s*, the degeneracy of the eigenvalues of the Liouvillian is lifted and a unique steady state emerges (blue dot) whose magnetization approaches the average of the two variational ones. In the variational dynamics, one of the two attractors is attained at large times depending on the initial condition (green and pink lines in Fig. 2, II_{\parallel}); for finite-*s* (blue dashed line) there are two separated timescales, the initial dynamics approaches one of the variational fixed points and is followed by a decay to the finite-*s* steady state. We analyze the two timescale dynamics in Sec. IV C 1.

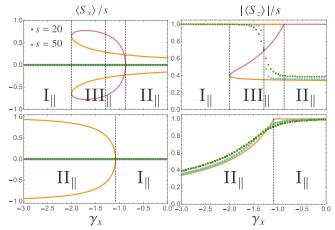


FIG. 4. (Top) Magnetization for the phase transition $I_{\parallel} \leftrightarrow III_{\parallel} \leftrightarrow II_{\parallel} H$ for h = 1, $\gamma_y = -3$, $p\Gamma = 1$. (Bottom) Magnetization for phase transition $I_{\parallel} \leftrightarrow II_{\parallel}$ for h = 1, $\gamma_y = 2$, $p\Gamma = 1$. The stable and unstable fixed points are depicted as orange and pink lines, respectively.

Region III_{||} has three variational stable fixed points (two related by symmetry and one with $\langle S \rangle = -se_z$). Which fixed point is realized in the $t \to \infty$ limit depends on the basin of attraction of the initial state. The finite-*s* dynamics also shows a separation of timescales, similar to region II_{||}, before the finite-*s* steady state is attained.

2. Phase transitions

We now turn to the description of the phase transitions. Figures 4 and 5 show the magnetization in the *x* (left panels) and *z* (right panels) directions as a function of γ_x and *h*, for finite values of *s* (blue and green dots) and for the stable (orange) and unstable (pink) fixed point of the variational dynamics. Figure 4 depicts the passage from phase I_{\parallel} to

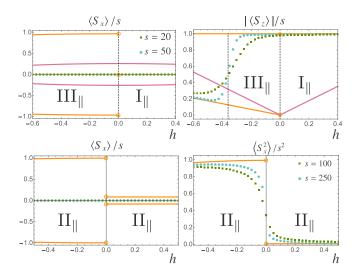


FIG. 5. (Top) Magnetization at the phase transition $I_{\parallel} \leftrightarrow III_{\parallel}$ with $\gamma_y = 3$, $\gamma_y = 1$, $p\Gamma = 1$. (Bottom) Magnetization at the phase transition for $II_{\parallel} \leftrightarrow II_{\parallel}$ with $\gamma_y = 3$, $\gamma_y = -3$, $p\Gamma = 1$. The stable and unstable infinite-*s* results are depicted as orange and pink lines, respectively.

phase II_{\parallel} , with (upper panels) and without (lower panels) the presence of the intermediate phase III_{\parallel} . Figure 5 shows a cross section of the phase diagram of Fig. 2 (left panels) obtained by varying *h* along two vertical lines that cross the $I_{\parallel} \leftrightarrow III_{\parallel}$ transition (upper panels) and the $II_{\parallel} \leftrightarrow II_{\parallel}$ one (lower panels) that crosses the 0_{\parallel} critical plane.

Analyzing Figs. 4 and 5, we list the properties of each transition. The transition $I_{\parallel} \leftrightarrow II_{\parallel}$ is of second order, with the unique steady state of I_{\parallel} giving place to two symmetry broken ones for II_{\parallel} [see Fig. 4 (lower panels)]. A good order parameter for this transition is $\langle S_z \rangle / s - 1$, which vanishes in phase I_{\parallel} and is nonzero in phase II_{\parallel} .

At the $II_{\parallel} \leftrightarrow III_{\parallel}$ and $III_{\parallel} \leftrightarrow I_{\parallel}$ transitions, the quantity $\lim_{s\to\infty} \langle S_z \rangle / s$ computed in the steady state is analytic as seen in Fig. 4 (upper panels). Analyticity was also observed for all other steady-state observables. Therefore these transitions only concern dynamic properties.

A discontinuous steady-state phase transition arises within III_{||}. For finite *s*, quantum fluctuations select a steady state with an average magnetization that is either that of the stable fixed point of I_{||} or the average of the fixed points of II_{||}, since these three fixed points coexist in III_{||}. This scenario of a first-order phase transition is similar to that reported in Ref. [63], the only difference being that the phase equivalent to II_{||} has in Ref. [63] a unique stable fixed point.

The transition $I_{\parallel} \leftrightarrow III_{\parallel}$ across the plane h = 0 is of first order. However, since the symmetry is not broken for finite-*s*, the steady-state magnetization is continuous, see Fig. 5.

The transition $II_{\parallel} \leftrightarrow II_{\parallel}$ across the h = 0 plane is also of first order. The discontinuity of $\langle S_x^2 \rangle / s^2$ is shown in Fig. 5.

B. Perpendicular polarization

The case $p \perp h$ shown in Fig. 3 (left panel), has three different phases: 0_{\perp} , I'_{\perp} , and I_{\perp} . The corresponding dynamics is plotted in Fig. 3 (right panels) with the same color code of Fig. 2. In addition, the gray line in Fig. 3, I'_{\perp} , depicts a separatrix curve dividing orbits where variational ansatz has qualitatively different dynamics. Note that both 0_{\perp} and I'_{\perp} support states that do not relax in the infinite-*s* limit.

1. Phases

Region 0_{\perp} has no variational stable fixed points. However, the variational method finds a line of marginal fixed-point solutions (brown line) where the eigenvalues of the stability matrix, obtained by linearizing the equations of motion, have a zero real part. This line connects two marginal steady states that satisfy $|\mathbf{n}| = 1$, depicted as red dots on the z = 0plane in Fig. 3, 0_{\perp} . The dynamics of any initial condition (green and pink lines) follows closed orbits that surround the marginal line. Thus the asymptotic long-time state of the variational dynamics is recurrent and keeps memory of the initial condition for all times. The existence of recurrent classical solutions was previously identified in Refs. [41–44] and recently studied in Refs. [48,49]. For the case $\gamma_x = \gamma_y = 0$ and p = -1, an explicit solution of the steady state for finite *s* is known [41–43].

For finite *s*, a single unique steady state (blue dot), with $|\langle S \rangle|/s \neq 1$, is attained. This fixed point corresponds to the unique place along the line of marginal fixed points where

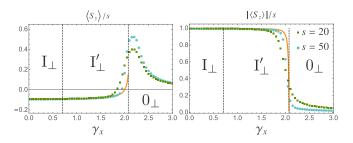


FIG. 6. Magnetization across the $0_{\perp} \leftrightarrow I'_{\perp} \leftrightarrow I_{\perp}$ transitions for h = 0.2, $\gamma_y = -2$, $p\Gamma = 1$. The stable infinite-*s* steady state is depicted as orange line.

 $\langle S_x \rangle = 0$, which is consistent with the fact that the finite-*s* steady state cannot break the microscopic symmetries.

The finite-*s* picture emerging from our variational dynamics is the following: finite-size corrections destabilize the recurrent variational evolution (valid for $s \rightarrow \infty$) and, after a timescale that increases with s^{-1} (see Sec. B), the unique steady state is attained. Note that, if the initial state is arbitrarily close to one of the marginal fixed points, the evolution to the finite-*s* steady state is along the lines of marginal fixed points found by the variational method. Therefore including 1/s corrections to the variational procedure is expected to lift the degeneracy of the states along the line and yield a unique steady state that coincided with the finite-*s* one.

Region I'_{\perp} is characterized by a stable fixed-point solution coexisting with recurrent states. A separatrix line(gray line in Fig. 3, I'_{\perp}) separates the region where an initial state attains asymptotically the stable fixed point (e.g., green trajectory) from the region where an initial state yields a recurrent evolution (e.g., pink trajectory). The finite-*s* evolution (blue dashed line) starting from an initial state in the recurrent region, first follows the variational recurrent evolution and, subsequently, decays towards the unique stable fixed point.

Region I_{\perp} has a single stable steady state and the same qualitative properties as I_{\parallel} . This region exists only for $h < h_c = p\Gamma/2$.

2. Phase transitions

The phase transitions in the perpendicular case can be of two kinds $0_{\perp} \leftrightarrow I'_{\perp}$ and $I'_{\perp} \leftrightarrow I_{\perp}$. Figure 6 shows the magnetization in the y (left panel) and z (right panel) directions as a function of γ_x for two values of s (blue and green dots) and for the stable fixed point obtained by the variational ansatz (orange curve). When h < 1/2, there are two points within a fixed h plane for which the passage from 0_{\perp} to I_{\perp} can be done directly, without passing by I'_{\perp} . As the steady-state properties of phases I'_{\perp} and I_{\perp} are similar, crossing the transition along these special points will not affect qualitatively the scenario presented in Fig. 6.

The $0_{\perp} \leftrightarrow I'_{\perp}$ transition is of first order, with a discontinuous magnetization shown in Fig. 6. However, as there is no stable fixed point within phase 0_{\perp} , this transition seems to escape the Landau paradigm [48].

The $I'_{\perp} \leftrightarrow I_{\perp}$ transition regards only the spectral properties of the Liouvillian and is discussed below. The steady-state magnetization, depicted in Fig. 6 for finite *s*, is continuous across the transition for $s \rightarrow \infty$.

IV. STEADY-STATE AND SPECTRAL AND DYNAMIC SIGNATURES OF NONEQUILIBRIUM PHASES

In this section, we analyze the spectral and steady-state properties of the phases described in Sec. III. For these quantities, large-*s* predictions require to go beyond the variational analysis. We achieve this using a Holstein-Primakoff transformation, mapping the spin into a bosonic degree of freedom, which allow a subsequent 1/*s* expansion of the Liouvillian. At leading order, the bosonic Liouvillian is quadratic and thus exactly solvable. Details of the exact solution are given in Appendix C. Analytic predictions obtain in this way are then compared with exact diagonalization results.

The main findings of this section are summarized in columns 4 and 5 of Table I and discussed in Sec. V.

A. Holstein-Primakoff transformed Liouvillian

The Holstein-Primakoff (H-P) transformation maps a spin *s* into a bosonic degree of freedom. A generalized version of this transformation, which conserves the spin commutation relations, can be obtained by the usual mapping

$$S_z = -s + a^{\dagger}a, \tag{5}$$

$$S_+ = a\sqrt{2s - a^{\dagger}a},\tag{6}$$

$$S_{-} = \sqrt{2s - a^{\dagger}a} a^{\dagger}, \qquad (7)$$

followed by a shift in the bosonic operators $a \to a + \sqrt{2s} \frac{\alpha}{\sqrt{1+\alpha\alpha}}$, with $\alpha \in \mathbb{C}$. This generalized H-P mapping allows a systematic 1/s development around a spin-coherent state, $|\alpha\rangle_c = e^{\alpha S_+} |s, -s\rangle$, parametrized by α , with average magnetization

$$\langle \mathbf{S} \rangle = s \left\{ \frac{\alpha + \bar{\alpha}}{1 + \bar{\alpha}\alpha}, i \frac{\alpha - \bar{\alpha}}{1 + \bar{\alpha}\alpha}, 1 - \frac{2}{1 + \bar{\alpha}\alpha} \right\} + O(\sqrt{s}).$$
(8)

Inserting the expansion of the spin operators in the Liouvillian and developing in powers of s, up to order s^0 , we obtain a quadratic Liouvillian in the bosonic operators, where H can generically be casted in the form

$$H = A^{\dagger} \cdot \boldsymbol{H} \cdot A + A^{\dagger} \cdot \boldsymbol{\zeta} + \boldsymbol{\zeta}^{\dagger} \cdot A + O(s^{-1/2})$$
(9)

with $A = \{a, a^{\dagger}\}^{T}$, the single-particle Hamiltonian H is a 2 × 2 matrix and ζ a two-component complex vector. In the same way the jump operator W_i can be written as

$$W_i = w_i^{\dagger} \cdot A + c_i \tag{10}$$

with w_i a two-component complex vector and c_i a complex constant. The quantities H and w_i are of order s^0 and ζ and c_i are of order $s^{1/2}$. A suitable choice of the shift, α , can be used to set to zero the terms proportional to ζ or c_0 in the linearized Liouvillian, obtaining an operator with only quadratic terms. The values of α that have this property are those that fulfill fixed-point conditions of the variational and semiclassical dynamics given in Appendix A 1. This step, is thus, equivalent to choose as linearization points the fixed points of the infinite-*s* equation of motion with $|\mathbf{n}| = 1$.

Properties of quadratic bosonic Liouvillians were studied in Ref. [68]. We derive some of these results in the

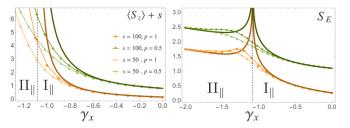


FIG. 7. 1/s corrections to $\langle S_z \rangle - s$ (left) and S_E (right) with h = 1, $\gamma_v = 2$, $\Gamma = 1/p$.

Appendix C using an approached similar to that developed in Ref. [21] for quadratic fermionic Liouvillians. Using this method, we compute the single particle correlation matrix, $\chi = \langle A.A^{\dagger} \rangle$, which encodes the properties of the steady state, the spectral gap, and derive the simple structure of the low-energy spectrum.

B. Steady state

In this section, we study steady-state properties starting with the parallel polarization case $(p \parallel h)$.

For phase I_{\parallel} , there is only one stable solution, α_1 , of the variational equations, thus to leading order in s, $\rho_0 \simeq |\alpha_1\rangle_c \langle \alpha_1|_c$. Analytic predictions for the steady-state observables to next-to-leading order can be obtained using density matrix $\rho_0 = \chi_1$, where χ_1 is the density matrix obtained by linearizing the Liouvillian around α_1 .

For phase II_{\parallel}, at leading order in s, \mathcal{L} has two eigenstates with eigenvalues exponentially close to zero that are well approximated by $\rho_0 = \frac{1}{Z_0} (|\alpha_1\rangle_c \langle \alpha_1|_c + |\alpha_2\rangle_c \langle \alpha_2|_c),$ with $Z_0 = \operatorname{tr}(|\alpha_1\rangle_c \langle \alpha_1|_c + |\alpha_2\rangle_c \langle \alpha_2|_c)$, and $\rho_1 = |\alpha_1\rangle_c \langle \alpha_1|_c - |\alpha_1\rangle_c \langle \alpha_1|_c$ $|\alpha_2\rangle_c \langle \alpha_2|_c$, from which only ρ_0 is a physical density matrix. At next to leading order in s, the density matrix is given by $\rho_0 = \frac{1}{2}(\chi_1 + \chi_2)$, where $\chi_{1,2}$ are the finite entropy density matrices obtained by linearizing the Liouvillian around $\alpha_{1,2}$, respectively. Since the overlap $\langle \alpha_1 | \alpha_2 \rangle_c$ is exponentially small in s, χ_1 and χ_2 are exponentially nonoverlapping, i.e., $\ln tr(\chi_1 \chi_2) \propto -s$. As a consequence, mean values of operators can be approximated by $tr(\rho_0 O) \simeq$ $\frac{1}{2}$ [tr($\chi_1 O$) + tr($\chi_2 O$)]. The entropy of ρ_0 is also well approximated by $S_{\rm E} \simeq \ln 2 - \frac{1}{2} \operatorname{tr}(\chi_1 \ln \chi_1) - \frac{1}{2} \operatorname{tr}(\chi_2 \ln \chi_2) = \ln 2 - \frac{1}{2} \operatorname{tr}(\chi_2 \ln \chi_2) = \frac{1}{2} \operatorname{tr}(\chi_2 \ln \chi_2$ tr($\chi_1 \ln \chi_1$), since by symmetry the entropy of χ_1 and χ_2 are equal.

Figure 7 shows the 1/s corrections to the magnetization $\langle S_z \rangle - s$ and the von Neumann entropy, $S_E = -\text{tr}(\rho \ln \rho)$, of the steady state as a function of γ_x , in phases I_{\parallel} and II_{\parallel} and across the $I_{\parallel} \leftrightarrow II_{\parallel}$ transition. Since in phase I_{\parallel} , the magnetization satisfies $\langle S_z \rangle = -s + \delta S_z + O(s^{-1})$, the values of $\delta S_z = s + \langle S_z \rangle$ for finite *s* converge to the analytic predictions obtained using the linearized Liouvillian around the stable steady state. For the entropy, Fig. 7 shows that the numerical results tend to the analytic predictions as $s \to \infty$. The convergence is much slower around the phase transition point.

At the phase transition, the perturbative expansion is no longer valid and the above estimate breaks down. When the linearized steady state is a good approximation of the finite-*s* one, the von Neumann entropy in the $s = \infty$ limit

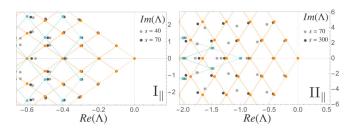


FIG. 8. Numerical eigenspectrum of \mathcal{L} for regions I_{\parallel} (left) and II_{\parallel} (right) and analytical predictions obtained from the linearized Liouvillian around the stable fixed point (light orange) and around the unstable one (light blue). Parameters from Fig. 2.

approaches a constant value. The proximity with the critical point where the linearized procedure breaks down, explains the slow convergence with *s*.

For the perpendicular polarization case $(p \perp h)$ and in the regions where a stable steady state is present $(I_{\perp} \text{ and } I'_{\perp})$, the properties of the steady state are similar to those of region I_{\parallel} . On the other hand, the recurrent region 0_{\perp} has no stable fixed point to approximate the finite-*s* steady state. In this case, as presented below, the entanglement entropy of the finite-*s* steady state grows as $\ln(s)$. It is tempting to interpret this logarithmic growth as an extension of the argument above for phase Π_{\parallel} , where O(s) degenerate steady states contribute equally to $S_{\rm E}$.

C. Spectrum and characteristic timescales

We now focus on spectrum of the Liouvillian linearized around each steady state. For the case of a single bosonic mode obtained by 1/s expansion of the H-P transformation, the eigenvalues $\Lambda_{n,m}$ of the Liouvillian are given by $\Lambda_{n,m} = i(n\lambda - m\bar{\lambda})$, with $m, n \in \mathbb{N}_0^+$, where λ is a complex number that can be obtained from H and w_i (see Appendix C). Each eigenvalue corresponds to a decaying mode of the dynamics towards the steady state with a characteristic timescale $\tau = -(\text{Re}\Lambda)^{-1}$.

1. Parallel case

Figure 8 depicts the spectrum of the Liouvillian \mathcal{L} in I_{\parallel} and II_{\parallel} . The gray level coded dots correspond to spectrum of the full Liouvillian for increasing values of *s*. The orange (blue) dots correspond to the spectrum of the linearized Liouvillian around the stable (unstable) fixed points, the orange (blue) lines were drawn to highlight the simple periodic structure of the spectrum.

For the case of Fig. 8, I_{\parallel} , the spectrum is generated by $\lambda = \lambda_s = \sqrt{(h + \gamma_x)(h + \gamma_y)} - \frac{1}{2}i\Gamma p$ (see derivation in Sec. C 3). Note that the agreement between the finite-*s* spectrum and the linearized one is faster for small values of $|\text{Re}(\Lambda_{n,m})|$. For larger values, we can still observe a convergence to the linearized prediction with increasing *s*. The decay towards the unique steady state, after the fast decaying modes vanish, is ruled by the two slowest decaying modes depicted in Fig. 8, I_{\parallel} , with a characteristic timescale $\tau_0 = |\text{Im}(\lambda_s)|^{-1}$.

In case of Fig. 8, II_{\parallel} , there are two stable fixed points related by symmetry. Linearizing the Liouvillian around each of these fixed points yields a spectrum that is doubly degenerate. A quasidegeneracy is also observed in the finite-*s* spectrum obtained by exact diagonalization with a convergence to the linearized prediction with increasing *s*.

In region II_{\parallel} , the dynamics for finite-*s* is thus characterized by two different timescales. The first timescale, of order s^0 , is given by $\tau_0 = |Im(\lambda_s)|^{-1}$, with λ_s obtained by linearizing the Liouvillian around one of the two symmetry-related stable steady states. The choice of the particular steady state depends on which basin of attraction the initial conditions belong to. Within this timescale, the evolution of a finite-*s* system tends to the infinite-*s* evolution as the value of *s* increases. For times $t > \tau_0$, the dynamics resolves the degeneracy between the steady state ρ_0 and the first excited state ρ_1 of \mathcal{L} defined in Sec. IV B and the decay is dominated by the inverse of the first nonzero eigenvalue Λ_1 of \mathcal{L} , $\tau_1 = -(Re\Lambda_1)^{-1}$. As $Re(\Lambda_1)$ is exponentially small in *s*, these two timescales become increasingly separated for large *s* and can be well identified in the dynamics (see Appendix B for more details).

The spectrum of region III_{\parallel} is thrice degenerate in the infinite-*s* limit and we also observe convergence as *s* increases (plot not shown). The dynamics in the region is similar to phase II_{\parallel} with the exception that now there are three relevant timescales. The first, $\tau_0 = |Im(\lambda_s)|^{-1}$, determines the convergence to the basin dependent steady state. One of the two other timescales (τ_1 or τ_2) corresponds, as in phase II_{\parallel} , to the decay from one of the symmetry related states to the symmetric mixed state. The other, to the decay between the mixed-symmetric state and a state with $\langle S \rangle \simeq -se_z$ (as the steady state of I_{\parallel}). Which eigenvalue, Λ_1 or Λ_2 , corresponds to each of these processes depends on what side of the first-order transition the system is in.

Interestingly, there is a set of low-lying eigenvalues (blue dots) obtained by exact diagonalization that do not converge to the spectrum of the bosonic Liouvillian linearized around the stable fixed points. Instead, these second set of eigenvalues can be obtained by linearizing the Liouvillian around the unstable fixed points. This spectrum has a similar structure (blue lines) to that of the stable fixed point but the element with the smallest real part within this set of eigenvalues. For the case I_{||}, we obtain $\lambda = \lambda_{uns} = \sqrt{(h - \gamma_x)(h - \gamma_y)} + \frac{i\Gamma p}{2}$ (see derivation in Sec. C 3) and the conelike structure is displaced from the real axis by $-\Gamma p$. A convergence to this second set of analytical predictions is also observed in cases I_{||} and II_{||}.

Therefore the lower part of the spectrum of the full Liouvillian, that rules the long-time dynamics, is an overlap of the spectra of linearized Liouvillians around both stable and unstable fixed points. Thus, in addition to the characteristic timescales determined by the stable fixed points, the long-time dynamics also carries information about the unstable fixed points.

We now focus on the spectrum at the phases transitions of the parallel case. As noticed before, there are three kinds of steady-state phase transitions in the system: two first-order, one with coexisting stable fixed points $(I_{\parallel} \leftrightarrow II_{\parallel} \leftrightarrow II_{\parallel})$ and one with no coexistence $(II_{\parallel} \leftrightarrow II_{\parallel})$, and a second-order phase transition $(I_{\parallel} \leftrightarrow II_{\parallel})$. The $I_{\parallel} \leftrightarrow III_{\parallel} \leftrightarrow II_{\parallel}$ transition is hard to locate numerically and an analytical treatment of the spectral properties beyond the heuristic picture given above requires a nonperturbative treatment that is out of the scope of this work.

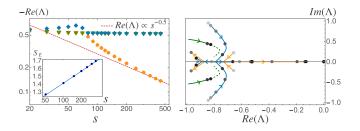


FIG. 9. (Left) Real part of the smallest eigenvalues at the transition $I_{\parallel} \leftrightarrow II_{\parallel}$ as a function of *s*, parameters of Fig. 2. (Inset) von Neumann entropy of the steady state as a function of *s*. (Right) Spectrum of \mathcal{L} at the $I_{\parallel} \leftrightarrow II_{\parallel}$ transition, gray dots represent numeric values from s = 60 up to s = 500 and the lines are trajectories as function of *s*.

The transition $II_{\parallel} \leftrightarrow II_{\parallel}$ is realized passing by the 0_{\parallel} critical plane in Fig. 2 (left panel); the spectral and the steady-state properties of this phase are similar to those of phase 0_{\perp} and will be analyzed in the next section.

The spectrum at the $I_{\parallel} \leftrightarrow II_{\parallel}$ critical point is depicted in Fig. 9. As *s* increases, a larger number of eigenvalues approaches zero following a process sketched in Fig. 9 (right panel): for increasing *s* (see arrows), two complex conjugate eigenvalues meet and become real; after that one eigenvalue approaches zero. The behavior of the firsteigenvalue of the Liouvillian that converges to 0 with *s* is given in Fig. 9 (right panel), showing $\Lambda_1 \propto s^{-\nu}$ with $\nu \simeq 0.5$. The entropy of the finite-*s* steady state is given in the inset of Fig. 9 (left panel). The scaling seems to be logarithmic in *s*, i.e., $S_E \propto \ln(s)$. Away from the phase transition points, all steady states have a finite entropy in the infinite *s* limit.

2. Perpendicular case

The spectrum and dynamics of the magnetization and the entropy in phase I_{\perp} , is similar to that of phase I_{\parallel} in the previous section. Therefore, we refer the reader to the discussion of phase I_{\parallel} (above) for the physical understanding of that phase.

Phases 0_{\perp} and I'_{\perp} allow for recurrent states in the infinite-*s* limit with a time-independent amplitude and frequency which depend on the initial condition. In the $s \to \infty$ limit, this corresponds to a spectrum of \mathcal{L} with an accumulation of points on the imaginary axis. This property, recently studied in Ref. [49], is shown in Fig. 10 for the case of a point in region 0_{\perp} . For finite *s* [see Fig. 10 (right panel)], we observe that some eigenvalues indeed approach the imaginary axis, fall along lines predicted for the marginal fixed points of the linearized Liouvillian. In this phase, the Liouvillian gap Λ_1 and the real part of the first few Liouvillian eigenvalues ($\Lambda_2, \Lambda_3,...$) vanish as s^{-1} [see Fig. 10 (left panel)].

This implies that in phase 0_{\perp} , the approach to the unique finite-*s* steady state is done with a rate of the order of s^{-1} . The entropy of the finite-*s* steady state increases logarithmically with *s* (inset of Fig. 10, blue dots). In the same inset, we compare the entropy of state chosen by our variational procedure (blue line) in Sec. III B 1 and find a remarkable agreement (no fitting performed).

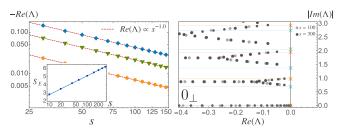


FIG. 10. (Left) Real part of the smallest eigenvalues as a function of s in region 0_{\perp} , parameters of Fig. 2. (Inset) von Neumann entropy as function of s. (Right) Spectrum of \mathcal{L} for region 0_{\perp} , light (dark) gray dots represent numeric values for s = 100 (s = 300), the orange and blue dots are obtained by linearizing the dynamics around the two marginal infinite-s fixed points located on the sphere.

The spectrum in phase I'_{\perp} (not shown) is a direct overlap of the spectra of 0_{\perp} and I_{\perp} . Properties of the finite-*s* steady state are always well approximated by a quadratic Liouvillian, linearized around the stable fixed point of I'_{\perp} .

V. CLASSIFICATION OF STEADY-STATE PHASES

We can now establish a complete classification of the different phases of the model. A summary of the following discussion and acronyms table is presented in Table I and should be understood as the main result in our paper.

We start by classifying the different systems in two major classes: noncritical system (NCS), where the number of zero eigenvalues of the Liouvillian operator is finite for $s \rightarrow \infty$; and critical systems (CS) that have a spectrum where an infinite number of eigenvalues approaches the imaginary axis as $s \rightarrow \infty$.

NCS correspond to the phases I_{\parallel} , II_{\parallel} , III_{\parallel} , and I_{\perp} . For these systems, the spectrum is well approximated by a linearized bosonic Liouvillian obtained after a Holstein-Primakoff transformation around the (stable and unstable) fixed points of the infinite-s dynamics. Each stable point in the dynamics, $\alpha_{i=1,2,3}$, corresponds to a zero eigenvalue on the Liouvillian in the $s \to \infty$ limit with an eigenvector that is well approximated by the density matrix $\rho \simeq |\alpha_i\rangle_c \langle \alpha_i|_c$, with $|\alpha_i\rangle_c$ a spin coherent state. In NCS phases with more than one infinite-s steady state, the dynamics follows the two timescale paradigm observed in phases II_{\parallel} and III_{\parallel} . This corresponds to a first decay towards the infinite-s state in the basin of attraction of the initial point, with a timescale of order s^0 , and a second decay to the finite-s steady state, with a timescale that diverges exponentially as s increases. Observables, such as the steadystate magnetization and entropy, can be obtained, at every order in s, by systematically computing 1/s corrections to the leading-order linearized Liouvillian. In particular, the von Neumann entropy is finite in the infinite-*s* limit.

NCS systems can be divided into three subclasses: nondegenerate (nCnD), with unique single steady state (I_{||}, I_⊥); degenerate-symmetric (nCDS) and degenerate-nonsymmetric (nCDnS) where more than one steady state exist (II_{||} and III_⊥, respectively).

For nCDS phases, a pair of symmetry broken steady states becomes exponentially degenerate, $\Delta \sim \exp(-s)$, in the infinite-*s* limit. Because the states break the symmetry of the

Description		Abbreviation	Region	Spectral Gap	S.S. Entropy
Noncritical	nondegenerate	nCnD	I_{\parallel}, I_{\perp}	$\Delta \sim s^0$	$S_E \sim s^0$
	degenerate-symmetric	nCDS	\mathbf{II}_{\parallel}	$\ln\Delta\sim -s$	$S_E \sim s^0$
	degenerate-nonsymmetric	nCDnS	III_{\parallel}	$\ln \Delta \sim -s$	$S_E \sim s^0$
Critical					
	nonrecurrent	CnR	$I_{\parallel} \leftrightarrow II_{\parallel}$	$\Delta \sim s^{-rac{1}{2}}$	$S_E \sim \ln s$
	coexistence	CC	$I'_{\perp}, I'_{\parallel}$	$\Delta \sim s^{-1}$	$S_E \sim s^0$
	recurrent	CR	$0_{\perp}, 0_{\parallel}^{"}$	$\Delta \sim s^{-1}$	$S_E \sim \ln s$

TABLE I. Classification of steady-state phases.

underlying Liouvillian in the infinite-*s* limit, the finite-*s* steady state is well approximated by a symmetric combination of the two infinite-*s* states and we say that the transition $I_{\parallel} \leftrightarrow II_{\parallel}$ is of second order.

nCDnS phases can encompass multiple pairs of symmetry broken steady states and symmetric states. All steady states are exponentially degenerate in the infinite-*s* limit, however in order to compute which of the steady states is realized for finite *s*, a nonperturbative calculation in *s* is needed that goes beyond the scope of the current work.

CS are represented in this work by regions 0_{\perp} , I'_{\perp} and by the phase transition planes, including: 0_{\parallel} , I'_{\parallel} and the transitions lines $I_{\parallel} \leftrightarrow II_{\parallel}$. These can be divided into three sub-classes: recurrent (CR) with all the initial states displaying recurrent behavior $(0_{\perp}, 0_{\parallel})$, coexistence (CC) whose properties depend on the initial state $(I'_{\perp}, I'_{\parallel})$ and nonrecurrent (CnR) where a (likely infinite) number of eigenvalues vanish $(I_{\parallel} \leftrightarrow II_{\parallel})$.

CR have a massive degenerate spectrum with nonzero imaginary parts, therefore allowing for recurrent dynamics in the infinite-*s* limit. While the infinite-*s* limit does not include a stable-steady state, our variational approach, together with symmetry considerations, can be used to predict both the magnetization and the entropy to leading order in *s*. In this phase, we have that $\lim_{s\to\infty} ||\langle S \rangle||/s < 1$ and the von Neumann entropy diverges logarithmically with *s*.

In CC phases, a stable steady state may still exist. In this case, the degenerate spectrum coexists with a regular one that is well approximated, as for NCS, by linearizing the Liouvillian around the stable fixed point. Moreover, the finite-*s* steady state are well approximated by those obtained perturbatively from the linearized Liouvillian. This implies that steady-state observables have a convergent 1/*s* expansion and that the entropy of the steady state is finite in the infinite-*s* limit.

For CnR systems, eigenvalues approach zero with a spectral gap that vanishes as a power law. Here, the fitted numerical value is compatible with a mean-field exponent $s^{-1/2}$. This, together with the perturbative results obtained in region I_{\parallel} , suggests that the approach to the steady state for a generic observable, $\langle O(t) \rangle - \langle O(\infty) \rangle$, follows a scaling function of the from $s^{-\frac{1}{2}} \Phi(|\lambda|t, |\lambda|^2 s^{\frac{1}{2}})$, where λ is the eigenvalue of the linearized problem that vanishes at the transition. Assuming a scaling hypothesis, this implies a t^{-2} power-law relaxation at the infinite-*s* limit. However, with the system sizes available to us, we were not able to numerically confirm this prediction. For a CnR, the steady-state entropy is observed to grow logarithmically with increasing *s*.

Although our classification focuses only on the properties of stable and marginal steady states, we have also shown that the low-lying spectrum of the Liouvillian operator in the large *s* limit *cannot* be reproduced only by analyzing the stable fixed points. Instead, the spectrum is obtained as a superposition of two sets of eigenvalues, coming from the stable and unstable fixed points. Since these eigenvalues with a small real part rule the decay to the steady state at large times, the decay rates also carry information about the unstable fixed points. Such understanding is relevant for experimental setups aimed at studying the characteristic timescales described in Sec. IV C.

VI. CONCLUSION

In summary, we present a detailed analysis of the LMG model, featuring a collective spin system, in the presence of a Markovian dissipative environment. Motivated by recent prototypes of engineered atomic spin devices we focus on two polarization cases. Our analysis is also of interest to other variants of the dissipative LMG model that have previously been studied in the contexts of quantum optics and cold atomic setups. By employing a variational approach, as well as a 1/s perturbative method, we are able to systematically study the model. Despite its apparent simplicity, this model exhibits a rich phase diagram where different phases are shown to possess qualitatively different steady-state and dynamical properties. We identify a number of different phases and provide a tentative classification with terms of their spectral and steady-state properties (see Table I).

One of the open issues, not addressed in the present work, is to understand the nature of the coexisting region near firstorder phase transitions. Detailed studies [69,70] have already reveled some of the properties of distribution functions near the transition. However, in the coexisting region, a criterion to predict which fixed point is realized at finite s, similar to Maxwell's construction for equilibrium first-order phase transitions [71], is still lacking.

ACKNOWLEDGMENTS

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APPENDIX A: EQUATIONS OF MOTION IN THE LARGE *s* LIMIT

In this section, we present the details of a derivation of the semiclassical equations of motion of the model. We do this in the next two sections in two slightly different ways. The first is the usual semiclassical analysis. The second method consists of approximating the dynamics by constraining the possible states within a family of variational density matrices. To treat both parallel and perpendicular cases at the same time, in this section, we assume that the Hamiltonian and the jump operators are generically given by

$$H = -\sum_{\alpha} \left(h^{\alpha} S_{\alpha} + \frac{1}{2s} \gamma^{\alpha} S_{\alpha}^2 \right), \tag{A1}$$

$$W_i = \frac{1}{\sqrt{2s}} \sum_{\alpha} \eta_i^{\alpha} S_{\alpha}, \qquad (A2)$$

where $h^{\alpha=x,y,z}$ and γ^{α} are real and η_i^{α} are complex parameters.

1. Semiclassical dynamics

A close set of equations of motion in the semiclassical limit is obtained assuming that, for a typical state, $\langle S_{\alpha}S_{\beta}\rangle = \langle S_{\alpha}\rangle\langle S_{\beta}\rangle + O(s^{1})$. Assuming this factorization in the equations of motion for the magnetization

$$\partial_t \langle S_\beta \rangle = \operatorname{tr}[S_\beta \mathcal{L}(\rho)], \tag{A3}$$

one obtains the semiclassical equations of motion for the quantity $n_{\alpha} = \frac{1}{s} \langle S_{\alpha} \rangle$:

$$\partial_t n_\beta = \sum_{\alpha\gamma} \varepsilon_{\alpha\beta\gamma} h_\alpha n_\gamma + \sum_{\alpha\gamma} \varepsilon_{\alpha\beta\gamma} \gamma_\alpha n_\alpha n_\gamma - \sum_{i,\alpha\alpha\prime\gamma} \frac{1}{2} \varepsilon_{\alpha\beta\gamma} \operatorname{Im} [\bar{\eta}_i^{\alpha'} \eta_i^{\gamma}] n_\alpha n_\alpha, \qquad (A4)$$

where $\varepsilon_{\alpha\beta\gamma}$ is the antisymmetric tensor.

The stability of the fixed points of the semiclassical dynamics, i.e., points obeying $\partial_t n_\beta = 0$, is obtained by linearizing the equations of motion in their vicinity

$$\partial_t \delta n_\beta = M(n_\beta^*) \delta n_\beta,$$

where n_{β}^* is the value of the fixed point and $\delta n_{\beta} = n_{\beta} - n_{\beta}^*$.

Besides the trivial fixed point with $|\mathbf{n}| = 0$, which is found to be generically unstable, all the other fixed points found have $|\mathbf{n}| = 1$.

2. Variational density matrix

Here we detail the variational approach employed in the main text. The results of this approach only differ from those in the previous section for phase 0_{\perp} and I'_{\perp} , where it allows to find a line of variational steady states to which the magnetization vector of the finite-*s* steady state belongs.

The variational states are parameterized by

$$\rho(\boldsymbol{m}) = \frac{e^{\boldsymbol{m}.\boldsymbol{S}/\boldsymbol{s}}}{Z_{\boldsymbol{m}}} \tag{A5}$$

with $Z_m = \text{tr}[e^{m.S/s}]$. This family of states includes thermal states of Hamiltonian that are linear in *S*. Within this family, expectation values $\langle S_{\alpha} \rangle$ and $\langle S_{\alpha} S_{\beta} \rangle$ are given by

$$\langle \boldsymbol{S} \rangle = \boldsymbol{R} \cdot \langle \boldsymbol{S} \rangle_{z}, \tag{A6}$$

$$\langle \boldsymbol{S} \cdot \boldsymbol{S}^T \rangle = \boldsymbol{R} \cdot \langle \boldsymbol{S} \cdot \boldsymbol{S}^T \rangle_z \cdot \boldsymbol{R}^T, \qquad (A7)$$

where $\langle \dots \rangle_z = \text{tr}[\dots e^{|\boldsymbol{m}|S^z/s}]/\text{tr}[e^{|\boldsymbol{m}|S^z/s}]$ and \boldsymbol{R} is a rotation matrix chosen such that $\boldsymbol{m} = |\boldsymbol{m}|\boldsymbol{R} \cdot \boldsymbol{e}_z$. In the large *s* limit these expressions simplify to

$$\langle \mathbf{S} \rangle / s = L(m) \frac{m}{m},$$
 (A8)

$$\langle \mathbf{S} \cdot \mathbf{S}^T \rangle / s^2 = G(m)\mathbf{m} \cdot \mathbf{m}^T + \frac{L(m)}{m}\mathbf{1},$$
 (A9)

where

$$L(x) = \coth(x) - \frac{1}{x},$$
 (A10)

$$G(x) = \frac{x^2 - 3x \coth(x) + 3}{x^4}.$$
 (A11)

Replacing this expressions in the equations of motion one obtains

$$\partial_t \left[m_\beta \frac{L(m)}{m} \right] = Y_\beta$$
 (A12)

$$Y_{\beta} = \sum_{\alpha\gamma} \epsilon_{\alpha\beta\alpha'} h_{\alpha} \frac{L(m)}{m} m_{\alpha'} + \sum_{\alpha\alpha'\gamma} \left[\frac{1}{2} \epsilon_{\alpha\beta\alpha'} (\gamma_{\alpha} - \gamma_{\alpha'}) + \frac{i}{4} \sum_{i} \left(\bar{\eta}_{i}^{\alpha'} \eta_{i}^{\gamma} \epsilon_{\alpha\beta\gamma} - \bar{\eta}_{i}^{\gamma} \eta_{i}^{\alpha} \epsilon_{\alpha'\beta\gamma} \right) \right] \times \left[G(m) m_{\alpha} m_{\alpha'} + \frac{L(m)}{m} \delta_{\alpha\alpha'} \right]$$
(A13)

Steady states must satisfy the condition $\sum_{\beta} Y_{\beta} m_{\beta} = 0$. For $Y_{\beta} \neq 0$ this implies: $|\mathbf{m}| \to \infty$ (fully polarized state) or $\sum_{i,\alpha\gamma} \varepsilon_{\alpha\beta\gamma}(\bar{\eta}_i^{\alpha} \eta_i^{\gamma} - \bar{\eta}_i^{\gamma} \eta_i^{\alpha}) = 0$ for all β . Since the second condition is not verified in either models, steady states must be fully polarized and the equations for steady states for $\hat{\mathbf{m}} = \mathbf{m}/|\mathbf{m}|$ reduce to those of \mathbf{n} in the last section, for $|\mathbf{n}| = 1$. Therefore, for fully polarized steady states, both approaches coincide. We may also have solutions satisfying $Y_{\beta} = 0$. Although a general analytical treatment of the phase diagram of these solutions is beyond this paper's scope, we propose that the existence of these solutions of $Y_{\beta} = 0$ will be a continuous line of marginal points connecting the marginal (or saddle) steady states obtained semiclassically. In this paper, such marginal line only occurs for $\mathbf{p} \perp \mathbf{h}$ and in the plane z = 0.

APPENDIX B: DYNAMICS FOR FINITE-S

In this section, we present some helpful simulations of the magnetization dynamics for finite-*s* and all regions of the phase diagram. Figures 11 and 12 show the long-time dynamics of a state initially polarized along the *y* and *x* directions, respectively, for different spins (s = 20, 40, 100).

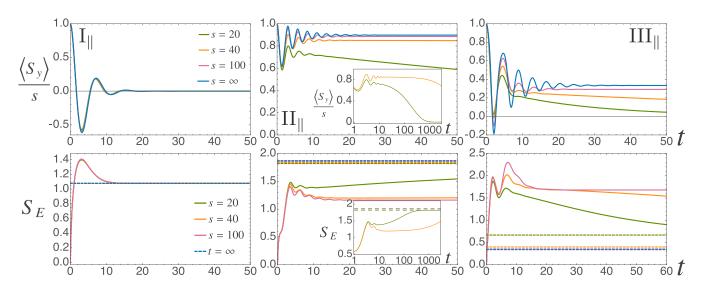


FIG. 11. Dynamics for $p \parallel h$: time evolution of $\langle S_y \rangle / s$ (top) and von Neumann entropy S_E (bottom) of an initial state polarized along the y direction, for different values of s. The parameters are those of Fig. 2.

In parallel case, Fig. 11, we highlight the visible separation of timescales in region II_{\parallel} (center panels), first a decay towards the mixed-symmetric state, followed by an exponential decay towards the true steady state. Unfortunately, the same separation between the three timescales of region III_{\parallel} is not so clear. The *s* scaling convergence towards the infinite-*s* magnetization dynamics (depicted as blue full line) and its entropy (blue dashed lines) shows that the variational approach correctly captures the dynamics in the large *s* limit.

Similarly to the parallel case, the variational approach also captures the dynamics in the large *s* limit perpendicular case Fig. 12, even when no stable steady state exists. As discussed in Sec. IV C the finite-*s* steady state in phase I'_{\perp} is well approximated by the unique stable steady state at infinite-*s* even though the short-time dynamics suggests a recurrent regime. In Fig. 12 (center), we plot the recurrent magnetization dynamics (upper plot) as blue full line and the entropy of the stable steady state as dashed blue line (lower plot).

A similar situation occurs in region 0_{\perp} [Fig. 12 (left)] with the finite-*s* steady state being in the variational line with $\langle S_x \rangle = 0$.

APPENDIX C: THE LINEARIZED LINDBLAD OPERATOR

1. Steady state

In this section, we derive explicit expressions for the steady state of a linearized Lindblad operator. The presentation is done in a generic way such that the approach can be used for more than one species of bosons, in which case $A = \{a_1, a_2, ..., a_n, a_1^{\dagger}, a_2^{\dagger}, ..., a_n^{\dagger}\}^T$.

As for the case of fermions [21,72], it is useful to consider the single-body density matrix $\chi = \langle A.A^{\dagger} \rangle$. The particular choice of the value of ζ and \bar{w}_0 in the Sec. IV leads to the the vanish of the linear terms in *a* and a^{\dagger} , therefore we consider that $H = A^{\dagger}.H.A$, where single-particle Hamiltonian is a $2n \times 2n$ matrix respecting: $H^{\dagger} = H$ and $\hat{H} = SH^TS$, with $S = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, and $W_i = w^{\dagger} A$, where w is a \mathbb{C} -valued vector with 2n components.

Under these assumptions the steady state is Gaussian with a vanishing first moment $\langle A \rangle = 0$. Thus the second moment matrix χ completely characterizes the steady state density matrix. This can be seen explicitly for a density matrix of the form $\rho_0 = e^{-\Omega_0}/Z_0$, with $Z_0 = \text{tr}(e^{-\Omega_0})$ and $\Omega_0 = \frac{1}{2}A^{\dagger} \cdot \Omega_0 \cdot A$ where Ω_0 is Hermitian, $\Omega_0^{\dagger} = \Omega_0$, and particle-hole symmetric, $\hat{\Omega}_0 = S\Omega_0^T S$. In which case, the single-body density matrix is explicitly given by

$$\boldsymbol{\chi}_0 = -n_b (-\boldsymbol{J} \cdot \boldsymbol{\Omega}_0) \boldsymbol{J} \tag{C1}$$

with $n_b(z) = \frac{1}{e^{z-1}}$ the Bose function and $J = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$.

Considering the adjoint of \mathcal{L} , $\mathcal{L}^{ad} = \mathcal{L}^{\dagger}$, defined as $tr[O\mathcal{L}(\rho)] = tr[\mathcal{L}^{ad}(O)\rho]$, for the linearized Lindblad operator the equation of motion $\partial_t A \cdot A^{\dagger} = \mathcal{L}^{ad}_{lin}(A \cdot A^{\dagger})$ can be written as

$$\partial_t A \cdot A^{\dagger} = -i[\boldsymbol{K} \cdot A \cdot A^{\dagger} - A \cdot A^{\dagger} \cdot \boldsymbol{K}^{\dagger}] + \boldsymbol{J} \cdot \boldsymbol{N} \cdot \boldsymbol{J}, \quad (C2)$$

where we defined

$$\boldsymbol{K} = \boldsymbol{J} \cdot (\boldsymbol{H} - i\boldsymbol{\Gamma}), \tag{C3}$$

$$N = \sum_{\mu} w_{\mu} \cdot w_{\mu}^{\dagger}, \qquad (C4)$$

and

$$\Gamma = \frac{1}{2}(N - \hat{N}), \tag{C5}$$

$$M = \frac{1}{2}(N + \hat{N}).$$
 (C6)

Taking the mean value with respect to some density matrix $\langle ... \rangle = tr[... \rho]$, we obtain the equation of motion for the single-body density matrix given by

$$\partial_t \boldsymbol{\chi} = -i[\boldsymbol{K} \cdot \boldsymbol{\chi} - \boldsymbol{\chi} \cdot \boldsymbol{K}^{\dagger}] + \boldsymbol{J} \cdot \boldsymbol{N} \cdot \boldsymbol{J}$$
(C7)

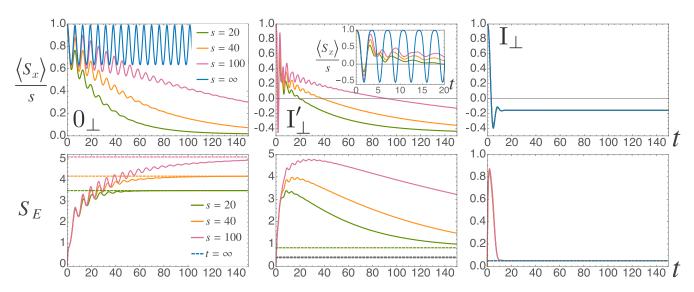


FIG. 12. Dynamics for $p \perp h$: time evolution of $\langle S_x \rangle / s$ (top) and von Neumann entropy S_E (bottom) of an initial state fully polarized along the *x* direction for different values of *s*. Parameters of Fig. 2.

A solution for the steady state $\partial_t \chi = 0$ can be given explicitly as

$$\boldsymbol{\chi}_{\infty} = -i \sum_{\alpha\beta} |\alpha\rangle \frac{\langle \tilde{\alpha} | \boldsymbol{J} \cdot \boldsymbol{N} \cdot \boldsymbol{J} | \beta \rangle}{\lambda_{\alpha} - \bar{\lambda}_{\beta}} \langle \beta |, \qquad (C8)$$

where $|\alpha\rangle$ and $\langle \tilde{\alpha}|$, with $\langle \tilde{\alpha}|\beta\rangle = \delta_{\alpha\beta}$, are right and left eigenvectors of the operator K which can be decomposed as $K = \sum_{\alpha} |\alpha\rangle\lambda_{\alpha}\langle \tilde{\alpha}|$. It is worth noting that the particle-hole antisymmetry K, i.e., $\hat{K} \equiv SK^TS = -K^{\dagger}$, implies that the eigenvectors of K appear in pairs: $|\alpha\rangle$ with eigenvalue λ_{α} and $S|\bar{\alpha}\rangle$ with eigenvalue $-\bar{\lambda}_{\alpha}$.

Higher moments of ρ_0 can be completely determined by χ_0 . For example, the entanglement entropy is given by

$$S = \operatorname{tr}[\boldsymbol{\chi}_{\infty} \boldsymbol{J} \ln(\boldsymbol{\chi}_{\infty})]$$

for such quadratic bosonic model. This expression can be computed from the eigenvalues of $\chi_0 J$ (or of $J\Omega_0$) that can be diagonalized by a symplectic transformation $(JU)\chi_0 J(JU^{\dagger}) = DJ$, where D = SDS is a diagonal matrix and $U^{\dagger}JU = J$.

2. Spectrum and eigenstates of the linearized Lindblad operator

In this section, we obtain the spectrum and eigenstates of the linearized Lindblad operator by acting on the steady state with a set of eigenoperators of $[\mathcal{L}_{\text{lin}}, \ldots]$. We assume at first that ζ and \bar{w}_0 are nonzero to see what are the implications and set them to zero later. As for the last section, the formalism is generic and can be used in the case there are several species of bosons.

For the following treatment, it is helpful to write the Lindblad operator in the form

$$\mathcal{L}_{\text{lin}} = -\frac{i}{2} \mathfrak{a}^{\dagger} \begin{bmatrix} \boldsymbol{H} - i\boldsymbol{M} & i\hat{\boldsymbol{N}} \\ i\boldsymbol{N} & -\boldsymbol{H} - i\boldsymbol{M} \end{bmatrix} \mathfrak{a} + i\frac{1}{2} \text{tr}(\boldsymbol{K}) \quad (C9)$$

with

$$\mathbf{a} = \left\{ a_1 \otimes 1, a_2 \otimes 1, \dots, a_1^{\dagger} \otimes 1, \dots, \\ 1 \otimes a_1^T, \dots, 1 \otimes a_1^{\dagger T}, \dots \right\}^T.$$
(C10)

Since $\mathbf{a} \cdot \mathbf{a}^{\dagger} - (\mathbf{a}^{\dagger T} \cdot \mathbf{a}^{T})^{T} = \mathfrak{J}$, with $\mathfrak{J} = \text{diag}(\boldsymbol{J}, -\boldsymbol{J})$, a transformation $\mathbf{a} \to \mathfrak{R}\mathbf{a}$ that leaved the matrix \mathfrak{J} invariant, i.e., $\mathfrak{R}^{\dagger} \cdot \mathfrak{J} \cdot \mathfrak{R} = \mathfrak{J}$, respects the bosonic commutation relations.

In order to reveal the upper tridiagonal structure of \mathcal{L}_{lin} , we perform the transformation $\tilde{\mathfrak{a}} = \mathfrak{U}\mathfrak{a}$ with $\mathfrak{U} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$, yielding

$$\mathcal{L}_{\text{lin}} = -\frac{i}{2} \tilde{\mathbf{a}}^{\dagger} \tilde{\mathbf{J}} \begin{bmatrix} \mathbf{K} & -2i \mathbf{J} \mathbf{M} \\ 0 & \mathbf{J} \mathbf{K}^{\dagger} \mathbf{J} \end{bmatrix} \tilde{\mathbf{a}} + i \frac{1}{2} \text{tr}(\mathbf{K}), \qquad (C11)$$

where $\tilde{\mathfrak{J}} = \mathfrak{U}^{-1\dagger}\mathfrak{J}\mathfrak{U}^{-1} = \begin{bmatrix} 0 & J \\ J & 0 \end{bmatrix}$. Note that, in this basis, to preserve the bosonic commutation relations, canonical transformations, $\tilde{\mathfrak{a}} \to \mathfrak{R}\tilde{\mathfrak{a}}$, have to leave the form $\tilde{\mathfrak{J}}$ invariant, i.e., $\mathfrak{R}^{\dagger} \cdot \mathfrak{J} \cdot \mathfrak{R} = \mathfrak{J}$. We can now use the upper tridiagonal from of Eq. (C11) find the transformation $\tilde{\mathfrak{a}} = \mathfrak{R}\tilde{\mathfrak{b}}$ with

$$\tilde{\mathfrak{R}} = \begin{bmatrix} \boldsymbol{R} & \boldsymbol{X}\boldsymbol{R}^{-1\dagger}\boldsymbol{J} \\ \boldsymbol{0} & \boldsymbol{J}\boldsymbol{R}^{-1\dagger}\boldsymbol{J} \end{bmatrix}$$

that diagonalizes \mathcal{L}_{lin} . Here, the matrix **R** is taken to diagonalize **K**, i.e., $\mathbf{R}^{-1}\mathbf{K}\mathbf{R} = \mathbf{D}$, with $\mathbf{D} =$ diag $(\lambda_1, \lambda_2, \ldots, -\bar{\lambda}_1, -\bar{\lambda}_2, \ldots)$ and **X**, is defined by $\mathbf{K}\mathbf{X} - \mathbf{X}\mathbf{K}^{\dagger} = 2i\mathbf{J}\mathbf{M}\mathbf{J}$, and can be given explicitly as

$$X = \sum_{\alpha \alpha'} 2i |\alpha\rangle \frac{\langle \tilde{\alpha} | \boldsymbol{J} \boldsymbol{M} \boldsymbol{J} | \tilde{\alpha}' \rangle}{(\lambda_{\alpha} - \bar{\lambda}_{\alpha'})} \langle \alpha' |.$$

In this basis, we thus have

$$\mathcal{L}_{\text{lin}} = -\frac{i}{2} \tilde{\mathbf{b}}^{\dagger} \tilde{\mathbf{\mathfrak{J}}} \begin{bmatrix} \boldsymbol{D} & \boldsymbol{0} \\ \boldsymbol{0} & \boldsymbol{J} \boldsymbol{D}^{\dagger} \boldsymbol{J} \end{bmatrix} \tilde{\mathbf{b}} + i \frac{1}{2} \text{tr}(\boldsymbol{D}).$$

Finally transforming back $\mathbf{b} = \mathfrak{U}^{-1}\tilde{\mathbf{b}}$, defining the single mode variables $\mathbf{b}_{\alpha} = (\mathfrak{U}^{-1}\tilde{\mathfrak{R}}^{-1}\mathfrak{U}\mathfrak{a})_{\alpha}$ and the real and imaginary parts of the eigenvalues of \mathbf{K} , $\lambda_{\alpha} = \varepsilon_{\alpha} - i\gamma_{\alpha}$, we can write

$$\mathcal{L}_{\text{lin}} = \sum_{\alpha} \left(-\frac{i}{2} \mathfrak{b}_{\alpha}^{\dagger} \begin{bmatrix} \varepsilon_{\alpha} \mathbf{1} & -i\gamma_{\alpha} \mathbf{J} \\ i\gamma_{\alpha} \mathbf{J} & -\varepsilon_{\alpha} \mathbf{1} \end{bmatrix} \mathfrak{b}_{\alpha} + \gamma_{\alpha} \right)$$

with $\mathbf{b}_{\alpha} = \{b_{\alpha} \otimes 1, b_{\alpha}^{\dagger} \otimes 1, 1 \otimes b_{\alpha}^{T}, 1 \otimes b_{\alpha}^{\dagger T}\}$, where b_{α} are bosonic operators. In this form, it is easy to see that the eigenoperators of \mathcal{L}_{lin} respecting the property

$$[\mathcal{L}_{\rm lin},\xi]=\mu\xi$$

with μ the respective eigenvector, are given by

$$\begin{split} \xi_{\alpha\pm} &= \frac{1}{\sqrt{2}} \big(b_{\alpha} \otimes 1 \mp 1 \otimes b_{\alpha}^T \big), \\ \xi_{\alpha\pm}^{\dagger} &= \frac{1}{\sqrt{2}} \big(b_{\alpha}^{\dagger} \otimes 1 \mp 1 \otimes b_{\alpha}^{\dagger T} \big), \end{split}$$

with eigenvalues given respectively by

$$\mu_{\alpha\pm} = \mp \gamma_{\alpha} + i\varepsilon_{\alpha},$$

$$\bar{\mu}_{\alpha\pm} = \mp \gamma_{\alpha} - i\varepsilon_{\alpha}.$$

There have the property $[\xi_{\alpha'\sigma}, \xi^{\dagger}_{\alpha\sigma'}] = \delta_{\alpha\alpha'}\delta_{\sigma,-\sigma'}$ and $[\xi_{\alpha'\sigma}, \xi_{\alpha\sigma'-}] = 0.$

The eigenoperators, ξ , are useful because they allow to explicitly construct the eigenstates of \mathcal{L}_{lin} starting from a reference state ρ_0 , for which $\mathcal{L}_{\text{lin}}(\rho_0) = \Lambda_0 \rho_0$, for example,

$$\mathcal{L}_{\text{lin}}.\xi_{\alpha+}(\rho_0) = (\mu_{\alpha+} + \Lambda_0)\xi_{\alpha+}(\rho_0),$$

i.e., $\xi_{\alpha+}(\rho_0)$ is an eigenstate of \mathcal{L}_{lin} with eigenvalue $\Lambda = (\mu_{\alpha+} + \Lambda_0)$. In general, we have

$$\mathcal{L}_{\mathrm{lin}} \prod_{i} \xi_{\alpha_{i},\sigma_{i}} \prod_{j} \xi_{\alpha_{i}',\sigma_{i}'}^{\dagger}(\rho_{0})$$
$$= \left(\sum_{i} \mu_{\alpha_{i},\sigma_{i}} + \sum_{j} \bar{\mu}_{\alpha_{i}',\sigma_{i}'} + \Lambda_{0}\right) \prod_{i} \xi_{\alpha_{i},\sigma_{i}} \prod_{j} \xi_{\alpha_{i}',\sigma_{i}'}(\rho_{0}).$$

In the case where ρ_0 is the steady state, i.e., $\Lambda_0 = 0$, we have that, for a single mode α , all the eigenstates of \mathcal{L}_{lin} can be written as $\rho_{n,m} = (\xi_{\alpha+}^{\dagger})^n (\xi_{\alpha+})^m (\rho_0)$ with eigenvalues $\Lambda_{n,m} = -(n+m)\gamma_{\alpha} - i(n-m)\varepsilon_{\alpha}$. Moreover one can show that for the steady state

$$\xi_{\alpha-}^{\dagger}(\rho_0) = \xi_{\alpha-}(\rho_0) = 0$$

3. Explicit example: region I_I

In most of the examples given in the main text, although linearization can be simply performed, explicit expressions of physical quantities are too cumbersome and bring no further significant understanding. However, it is instructive to present explicit results for a particular case. In this section, we illustrate the treatment of the preceding sections for the particularly simple case of region I_{\parallel} characterized by a stable and an unstable fixed points.

a. Stable fixed point

Assuming p > 0, region I_{\parallel} is characterized by a stable fixed point at $\alpha = 0$, the linearized Lindblad operators around this point is defined by the matrices

$$\boldsymbol{H}_{s} = \begin{pmatrix} -h - \frac{1}{2}(\gamma_{x} + \gamma_{y}) & \frac{1}{2}(\gamma_{y} - \gamma_{x}) \\ \frac{1}{2}(\gamma_{y} - \gamma_{x}) & -h - \frac{1}{2}(\gamma_{x} + \gamma_{y}) \end{pmatrix}$$

and

$$N_{\rm s} = \begin{pmatrix} \frac{1}{2}(p+1)\Gamma & 0\\ 0 & \frac{1}{2}(1-p)\Gamma \end{pmatrix}$$

which yield eigenvalues of K_s given by $\lambda_{s,\pm} = \pm \sqrt{(h + \gamma_x)(h + \gamma_y)} - \frac{1}{2}i\Gamma p$ and to a single-particle density matrix given by

$$\boldsymbol{\chi}_0 = \begin{pmatrix} \kappa + 1 & \bar{\delta} \\ \delta & \kappa \end{pmatrix}$$

with

$$\begin{aligned} \kappa &= \eta [(2h+\gamma_x+\gamma_y)^2 - 4p(h+\gamma_x)(h+\gamma_y) + (1-p)p^2\Gamma^2],\\ \delta &= \eta (\gamma_y-\gamma_x)(2h+\gamma_x+\gamma_y+ip\Gamma),\\ \eta^{-1} &= 2p [4(h+\gamma_x)(h+\gamma_y) + \Gamma^2p^2]. \end{aligned}$$

This expression yields a steady-state expectation value for the magnetization that is given by

$$\langle \mathbf{S} \rangle = (-s + \kappa) \mathbf{e}_z$$

and to the steady-state entanglement entropy

$$S_{\rm E} = p_+ \ln(p_+) + p_- \ln(-p_-)$$

where $p_{\pm} = \frac{1}{2}(1 \pm \sqrt{(1 + 2\kappa)^2 - 4\delta\bar{\delta}})$ are the eigenvalues of $\chi_0 J$. In the main text, the expressions $\lambda_{s,\pm}$, $\langle S \rangle$ and S_E are compared to the numerical results.

b. Unstable fixed point

Although the unstable fixed point does not contribute to the steady-state properties, its signatures can be traced in the spectrum. The linearized Lindblad operator for $\alpha = \infty$, can most easily be obtained considering the alternative Holstein-Primakoff (H-P) transformation

$$S_z = s - a^{\dagger} a, \tag{C12}$$

$$S_{-} = a^{\dagger} \sqrt{2s - a^{\dagger}a}, \qquad (C13)$$

$$S_+ = \sqrt{2s - a^{\dagger}a} a. \tag{C14}$$

After linearization, we obtain

$$\boldsymbol{H}_{\text{uns}} = \begin{pmatrix} h - \frac{1}{2}(\gamma_x + \gamma_y) & \frac{1}{2}(\gamma_y - \gamma_x) \\ \frac{1}{2}(\gamma_y - \gamma_x) & h - \frac{1}{2}(\gamma_x + \gamma_y) \end{pmatrix}$$

and

$$N_{\rm uns} = \begin{pmatrix} \frac{1}{2}(1-p)\Gamma & 0\\ 0 & \frac{1}{2}(1+p)\Gamma \end{pmatrix}$$

which gives $\lambda_{\text{uns},\pm} = \pm \sqrt{(h - \gamma_x)(h - \gamma_y)} + \frac{i\Gamma p}{2}$, confirming that the point is indeed unstable for p > 0. This fixed point is responsible for a second "cone" of eigenvalues of \mathcal{L} , determined by $\Lambda = in_+\lambda_{\text{uns},+} + in_-\lambda_{\text{uns},-}$ with $n_{\pm} = \mathbb{N}^+$ and shifted by $-p\Gamma$.

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