Hysteresis and chaos in anomalous Josephson junctions without capacitance

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Overdamped Josephson junctions usually do not exhibit chaotic behavior in their phase dynamics, either because the phase-space dimension is less than 3 (as in the case of a single overdamped ac-driven junction) or due to the general tendency of systems to become less chaotic with increasing dissipation (as in the case of coupled overdamped junctions). Here we consider the so-called φ_0 superconductor/ferromagnet/superconductor Josephson junction in which the current flowing through the junction may induce magnetization dynamics in the ferromagnetic interlayer. We find that due to the induced magnetization dynamics, even in the overdamped limit (i.e., for a junction without capacitance), the junction may exhibit chaos and hysteresis that in some cases leads to multiple branches in its current-voltage characteristics. We also show that pulsed current signals can be used to switch between the different voltage states, even in the presence of added thermal noise. Such switching could be used in cryogenic memory components.

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I. INTRODUCTION

As is well known, the current-biased single Josephson junction (JJ) without sufficient electrical capacitance (in other words, overdamped), does not show any chaotic behavior [1]. To understand this fact, consider the resistively and capacitively shunted junction model of the JJ [2]:

$$\frac{C\hbar}{2e}\ddot{\varphi} + \frac{\hbar}{2eR_N}\dot{\varphi} + I_c\sin\varphi = I = I_{\rm dc} + I_{\rm ac}\sin(\Omega t), \quad (1)$$

where φ is the phase difference of the macroscopic wave functions for the superconductors on either side of the insulating layer, *C* is the electrical capacitance, R_N is the normal-state resistance, I_c is the critical current, I_{dc} is the direct current (dc) bias, and I_{ac} is the amplitude of the alternating current (ac) bias, with the angular frequency Ω .

High damping (i.e., low R_N) moderates the inertial effects produced by the first term in Eq. (1). One can show that there is the threshold for the Stewart-McCumber parameter,

$$\beta_c = 2eI_c R_N^2 C/\hbar < \frac{1}{4},\tag{2}$$

below which one can disregard the inertial effects on the phase dynamics [3,4]. Formally, if (2) is satisfied, then one can neglect the term $C\hbar\ddot{\varphi}/(2e)$ in Eq. (1), and expect no chaotic behavior in the resulting, overdamped system, a result of the Poincaré-Bendixson theorem [5–7].

However, if additional degrees of freedom (e.g., magnetic degrees of freedom) are coupled to the overdamped JJ, then chaotic behavior may occur. The φ_0 junction, containing a ferromagnetic interlayer, is a good example of such coupling (see [8-10] and the references therein). In this type of junction, the Rashba spin-orbit coupling (SOC) within the ferromagnetic interlayer can be modeled by the Rashba Hamiltonian, $\hat{H}_R = \alpha_R \left[\hat{\boldsymbol{\sigma}} \times \hat{\mathbf{p}} \right] \cdot \hat{\mathbf{n}}$, where α_R is the Rashba SOC coupling strength, $\hat{\sigma}$ is the vector of Pauli matrices, **p** is the electron momentum, and $\hat{\mathbf{n}}$ is the unit vector describing the direction of the structural anisotropy in the system. Here, we choose $\hat{\mathbf{n}} = \hat{\mathbf{e}}_z$. The electrical current through the φ_0 junction induces triplet superconducting correlations via the SOC by means of the direct magnetoelectric effect. These correlations host the electron-spin polarization which interacts with the internal magnetization of the interlayer via the exchange mechanism [11,12]. This mechanism induces motion of the magnetization via the applied current and produces new dynamical regimes which may

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influence the current-voltage characteristics (CVCs) of the junction [13–19].

The current-induced magnetization dynamics in φ_0 JJs has been studied theoretically in many previous works [11-37]. The variety of structures discussed in these works may be classified according to the way in which the SOC and the ferromagnetic element are combined, and through which part(s) of the structures the supercurrent flow(s). Such a classification leads to three essential types of φ_0 JJs: (i) superconductor/ferromagnetic metal with Rashba SOC/superconductor (S/FM with Rashba/S) [11,13–19,21–35]; (ii) superconductor/ferromagnetic insulator/superconductor on top of the three-dimensional (3D) topological insulator (S/FI/S on TI) [12,34,36]; and (iii) superconductor/ferromagnetic metal/superconductor on top of the 3D topological insulator (S/FM/S on TI) [37]. For clarity, in Table I, we provide a summary of each system type.

To the best of the authors' knowledge, there are no experimental studies that specifically probe the currentinduced magnetization dynamics in φ_0 JJs. However, every ingredient of this problem has already been touched upon in experiments. For example, the existence of the φ_0 phase shift has been experimentally confirmed in [38–43], where the anomalous phase φ_0 was achieved due to either the external magnetic in-plane field or uncontrolled magnetic impurities. Also, superconductivity on its own is well known for its direct influence on the magnetization dynamics in S/F/S structures. In particular, the ferromagnetic resonance frequency of the magnetic interlayer appears to be greatly enhanced in S/F/S structures [44,45]. This experimentally observed effect was explained by Silaev [46] in terms of the interaction between the eddy currents induced in the superconducting leads by the interlayer dynamics and the interlayer itself. Here we do not take this effect into account, as it is thought to be significant only when the widths of the leads and interlayers become wide in comparison to the London penetration depth, which we assume is sufficiently large for the structures under our consideration.

In some previous works [13–18], the effect of the magnetization dynamics of monodomain interlayers on the CVCs of φ_0 JJs has been investigated. In these papers, only the underdamped regime was considered for the rather high value ($\beta_c = 25$) of the Stewart-McCumber parameter. A variety of unusual features were found in the CVCs, including multiple branch structure, negative differential resistance, and chaos. The main purpose of our present work is to demonstrate that some of these features, which were previously only studied in a restricted class of underdamped dc+ac biased JJs, do indeed survive in certain overdamped dc+ac biased φ_0 JJs. Mathematically, the observation of unusual features such as chaos and multistability in overdamped dc+ac biased φ_0 JJs is only possible because the state space for the φ_0 JJs is constituted by the Josephson phase difference, φ , as well as the magnetization direction, **m**, compared to only φ for the usual overdamped dc+ac biased JJs. In the previous works [13–18], one had both the capacitance of JJs (since $\beta_c > 0$) and the magnetization dynamics, making it more



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difficult to show the origin of the unusual features that were found. Here, by contrast, we clearly demonstrate that it is really the current-induced magnetization dynamics that is responsible for the additional hysteretic branches and the chaotic regions in CVCs.

The current-induced magnetization dynamics of φ_0 JJs is interesting from a fundamental perspective and for its potential applications [12,25,26]. The magnetization reversal procedure may be employed in such junctions to create classical bits that store information using the direction of the interlayer magnetization: one of the stable directions means 1, while another one stands for 0. Our present work broadens our current theoretical understanding about the magnetization dynamics in φ_0 JJs and provides an alternative way in which classical bits may be constructed. We show that switching between different branches of the current-voltage characteristics may be induced by using current pulses. In this case, the information is encoded by the voltage state of the JJ. These different voltage states exist because of the multistability in the magnetization dynamics and lead to the possibility of switching that is robust to the levels of thermal noise, estimated for real systems.

This paper is organized as follows. In Sec. II, we describe the different types of φ_0 JJ under consideration, including details of the numerical methods used in simulations and estimations of the relevant parameter ranges. In Sec. III, we present and discuss the main results of our simulations for the different models of overdamped dc+ac biased φ_0 JJs that were formulated in Sec. II. These results include observations of multiple branches in the CVCs due to multistability. In Sec. IV, we discuss one possible application (related to switching) of the features described in Sec. III. In Sec. V, we demonstrate that the main branch structure observed in the CVCs is robust under the influence of thermal fluctuations. Finally, we present our conclusions in Sec. VI. The Appendix provides an analysis to explain the observed breaking of the oneto-one correspondence between magnetization and voltage states.

II. MODELS

The magnetization dynamics of the interlayer of φ_0 JJs is described by the Landau-Lifshitz-Gilbert (LLG) equation [47]:

$$\frac{d\mathbf{M}}{dt} = -\gamma \mathbf{M} \times \mathbf{H}_{\text{eff}} + \frac{\alpha}{M_0} \mathbf{M} \times \frac{d\mathbf{M}}{dt}.$$
 (3)

Here, γ is the gyromagnetic ratio, **M** is the interlayer magnetization, $M_0 = |\mathbf{M}|$, and α is the Gilbert damping constant. We do not distinguish between the magnetic anisotropy field of the interlayer and the torque exerted on the magnetization. Both these quantities are included in the term \mathbf{H}_{eff} . For simplicity, we will consider only

the easy-axis anisotropy along $\hat{\mathbf{e}}_z$. For such an interlayer, the magnetic energy is $E_M = -K \mathcal{V} M_z^2 / (2M_0^2)$, where K is the magnetic anisotropy constant and \mathcal{V} is the volume of the ferromagnetic interlayer.

As mentioned in the Introduction, there are essentially three types of φ_0 JJs, differing only by the applied effective magnetic fields in the interlayer, and the current-phase relationships. Physically, the differences between effective magnetic fields are related to how the total current flowing through the system gets divided into the superconducting current I_s and the quasiparticle current I_{qp} . According to the modified resistively shunted junction (RSJ) model without capacitance [19,36], we may write

$$I = I_{dc} + I_{ac} \sin \left(\Omega t\right) = I_s + I_{qp},$$

$$I_s = I_c(m_x) \sin \left(\varphi - \varphi_0\right), I_{qp} = \frac{\hbar}{2eR_N} \left(\dot{\varphi} - \dot{\varphi}_0\right).$$
(4)

Here φ_0 is the anomalous phase shift in the junctions, and $\mathbf{m} = \mathbf{M}/M_0$. In all these types of JJs we have $\varphi_0 = rm_y$, where the dimensionless constant $r \sim \alpha_R$ characterizes the intensity of the SOC. The effective magnetic fields $\mathbf{H}_{\text{eff1,2,3}}$, which are used for the calculation of the magnetization motion, contain torques $\mathbf{T}_{1,2,3}$, which describe the effect of the current on the magnetization.

The type (i) model takes into account only the superconducting part of the current, I_s , in the torque acting on the magnetization, $\mathbf{T}_1 \propto I_s \hat{\mathbf{e}}_v$. The quasiparticle current, in principle, may induce electron-spin polarization and, therefore, participate in the formation of the torque T_1 [19,34,35], but we neglect it for the sake of consistency with previous works [11,13–18,20–33]. If we included the quasiparticle contribution in the torque T_1 , then we would have an additional term proportional to rI_{qp} in T_1 . This term only influences the magnetization dynamics and does not affect the JJ phase evolution, expressed through $\Phi =$ $\varphi - rm_{\nu}$. As we shall see in Sec. III, the CVCs of the type (i) junctions are independent of the magnetization, since their critical currents are independent of the magnetization direction. Therefore, the inclusion of the quasiparticle contribution in T_1 would not change any of the results for the type (i) model.

The type (ii) model uses the total current flowing through the Josephson weak link which is organized through the surface states of the TI, so $\mathbf{T}_2 \propto I = (I_{dc} + I_{ac} \sin(\Omega t)) \hat{\mathbf{e}}_y$ [12,34,36] due to the spin-momentum locking in the TI.

The type (iii) model assumes that the quasiparticle current flows through the FM layer while the superconducting current flows through the Josephson weak link formed by the surface states of the TI, that is, only the superconducting part of the total current is used in the torque: $\mathbf{T}_3 \sim I_{c0}f(m_x) (1 - \cos(\varphi - rm_y)) \hat{\mathbf{e}}_x + I_s \hat{\mathbf{e}}_y$, due to the spin-momentum locking in the TI [37]. The formulas for $i_c(m_x)$ and $f(m_x)$ are written in Table I. The difference between type (ii) and type (iii) φ_0 JJs occurs because the resistance of the FM layer is typically much smaller (around 0.1–1 Ω [48]) than the resistance of surface states of the TI (around 50 Ω [49,50]), and so the quasiparticles "prefer" to flow through the ferromagnetic metal. Models (ii) and (iii) are thus distinguished by the different currents flowing through that part of each structure hosting the SOC and electron-spin polarization.

Model (i) differs crucially from (ii) and (iii) due to the different dependence of the critical current on the magnetization direction $I_c(m_x)$. As stated in Table I, in model (i) the critical current is independent of **m** $(I_c(m_x) = I_{c0} =$ const), while in models (ii) and (iii) it depends on m_x as shown in Fig. 1. The function $I_c(m_x)$ depends on the SOC parameter r and the length of the junction d_F in the current direction $\hat{\mathbf{e}}_x$, given in dimensionless form by $d_F = 2\pi k_B T_c d_F / (\hbar v_F)$, where k_B is the Boltzmann constant, T_c is the critical temperature of the superconductors, and v_F is the Fermi velocity of the TI surface states. In principle, model (i) may also have a nonconstant $I_c(m_r)$ dependence [51], however, this dependence would be very slight due to the small Rashba SOC in ferromagnetic metals [52,53]: $r \sim 0.1$ for $\alpha_R \sim 10^{-3}$ to $10^{-1} \leq 1$ eV Å. Rashba SOC intensities $\alpha_R \sim 1$ eV Å have been achieved in Co/Pt thin films with Co layers of about 0.6 nm [53]. For such films, *r* is also small ($r \sim 0.01$), making $I_c(m_x) \approx$ const a good approximation. In comparison, for TIs [38], $r \sim 1$ to 10 and $\alpha_R \sim 1$ to 3 eV Å.

To calculate the CVCs numerically, the magnetization dynamics and the Lyapunov exponents (LEs) from the system of Eqs. (3) and (4), we first rewrite the equations in terms of the dimensionless variables:

$$t \to \omega_F t, \quad \omega_F = \gamma K/M_0, \quad \Omega \to \Omega/\omega_F;$$

 $\omega_c = 2eI_{c0}R_N/\hbar \to \omega_c/\omega_F;$
 $I_c(m_x) = I_{c0}i_c(m_x) \quad \text{with } I_{c0} = I_c(m_x = 0);$



FIG. 1. The dependence of the critical current on the magnetization direction $i_c(m_x) = I_c(m_x)/I_{c0}$ from Table I for different r. Here we use $I_{c0} = I_c(m_x = 0)$. The dimensionless length is $\tilde{d}_F = 2\pi k_B T_c d_F/(\hbar v_F) = 1$.

$$i = \frac{I}{I_{c0}}, \quad i_{dc} = \frac{I_{dc}}{I_{c0}}, \quad i_{ac} = \frac{I_{ac}}{I_{c0}};$$

$$G = \frac{E_J}{KV} = \frac{\hbar I_{c0}}{2eKd_F d_z d}, \quad w = \frac{\omega_F}{\omega_c}.$$
(5)

As before, d_F is the length of the junction along the current direction $\hat{\mathbf{e}}_x$ and d is its width in the $\hat{\mathbf{e}}_y$ direction. Here we assume that the junction length along the $\hat{\mathbf{e}}_z$ direction is d_z , so that the volume of the ferromagnetic interlayer can be written as $\mathcal{V} = d_F d_z d$. With the help of Eq. (5), we can then write Eqs. (3) and (4) in dimensionless form as

$$\dot{\mathbf{m}} = -\frac{1}{1+\alpha^2} \left\{ \mathbf{m} \times \left(\mathbf{T}_i + m_z \hat{\mathbf{e}}_z \right) + \alpha \mathbf{m} \times \left[\mathbf{m} \times \left(\mathbf{T}_i + m_z \hat{\mathbf{e}}_z \right) \right] \right\},$$
(6a)

$$w\dot{\Phi} = i_{\rm dc} + i_{\rm ac}\sin\left(\Omega t\right) - i_c\left(m_x\right)\sin\Phi.$$
 (6b)

The torques \mathbf{T}_i (i = 1, 2, 3), appearing in Eq. (6a), are given in dimensionless form in Table I. For convenience, we have introduced the new variable, $\Phi = \varphi - rm_y$, in Eq. (6b), which has the same form as that of an ordinary, overdamped, ac-driven JJ. The average dimensionless voltage for any given dc current i_{dc} and any fixed ac current i_{ac} is calculated as

$$V/(I_{c0}R_N) = w\overline{\dot{\varphi}} = w\frac{\varphi(T) - \varphi(0)}{T}.$$

We denote the time average of any time-dependent quantity such as $\dot{\varphi}(t)$, over the time domain $t \in [0, T]$, by $\overline{\dot{\varphi}}$. Typically, in the numerical results that follow we allow a transient time of 500 drive cycles (of period $\tau = 2\pi/\Omega$), before averaging over $T = 500\tau$ for the CVCs, and T =128 000, for the LEs. The LEs are calculated via the full spectrum method [54–56], using the explicit pseudosymplectic method [57] (for further details, see also the Appendix of [18]).

Experimentally, the system parameters fall into the following ranges. The Gilbert damping α is typically much smaller than 1 [12,25]: $\alpha \sim 10^{-4}$ to 10^{-2} . The coefficient G [see Eq. (5)] has been estimated in the range $G \sim 10^{-2}$ to 10^2 [12,23,37]. The following numerical parameters were used for this estimate: $d \sim 100$ nm, $d_F \sim 10$ nm, $d_z \sim 5$ nm, $I_{c0} \sim 6 \mu$ A, $K \sim 1$ to 10^4 J m⁻³. The critical current density of 60 A/m, used here, is consistent with Refs. [49,50], where Nb/Bi₂Te₃/Nb and Nb/HgTe/Nb junctions were investigated. The range of the magnetic anisotropy coefficient, $K \sim 10^1$ to 10^4 J m⁻³ can be achieved in different magnetic bilayers [58-60]. The SOC coefficient r has been estimated in Refs [12,23,36]to be in the range $r \sim 0.1$ to 10. The small value of the SOC intensity $r \ll 1$ is typical for JJs with FM with the SOC interlayer such as permalloy doped with Pt atoms [22,52]. The smallness of the SOC intensity $r \ll 1$ justifies the approximation of the critical current independence on the magnetization direction; see Fig. 1. The high value of the SOC intensity $r \sim 10$ may exist in JJs based on the TI surface states [12,34,36]. Thus, we expect that both *G* and *r* may vary over wide ranges, depending on the quality of the experimentally made structures. With the help of these values, $\omega_F = \gamma K/M_0 \approx 10^{10}$ Hz [23,44,45]. Typically, for the type (ii) system we have $R_N \sim 50 \Omega$ [49,50], stemming from the resistance of the surface states of TI, and the parameter *w* may be estimated as $w \sim 10^{-2}$, which is consistent with the value used in [25]. However, *w* can be different for the model (iii) because in that case R_N is determined by the resistance of the ferromagnetic metal which may be rather small ($R_N \sim 1 \Omega$ [48]), so in that case $w \sim 1$.

It is difficult to estimate the typical capacitance of systems under consideration, but there are experimental works which show that it is possible to achieve nonhysteretic CVCs in JJs based on ferromagnetic interlayers or TI [48,49]. For example, in the experimental work [49], the Stewart-McCumber parameter was estimated to be $\beta_c \sim$ 0.001 for the JJ based on the TI, HgTe. Generally, the overdamped approximation, as in Eqs. (2) and (4), applies to systems in which there is not too much self-heating [61].

III. FEATURES IN THE CURRENT-VOLTAGE CHARACTERISTICS

We now proceed to the main results. It is well known that a magnetic nanoparticle, which experiences a constant longitudinal and a time-dependent transverse component of the external magnetic field or a time-dependent voltagecontrolled magnetic anisotropy, can exhibit chaotic motion and multistability [62–67]. Here, for type (i)–(iii) systems, we have a similar situation in which the magnetic interlayers of the junctions are influenced by the time-dependent ac drive. What are the consequences of this interaction for the CVCs of such JJs? We will show that, due to the magnetization dynamics, chaotic and hysteretic behavior may also occur.

A. Type (i) systems

To begin with, we have established that type (i) systems do not show any new dynamics in their CVCs, compared to superconductor/insulator/superconductor (S/I/S) junctions.

To understand why the CVCs are the same, we notice that the solutions, $\Phi = \varphi - rm_y$, of the RSJ Eq. (6b), with $I_c(m_x) = I_{c0} = \text{const}$, do not depend on the magnetization dynamics, but only on i_{dc} and i_{ac} . This means that, for any $\mathbf{m}(t)$ at fixed i_{dc} and i_{ac} , we obtain the same solutions, Φ , as for the corresponding S/I/S junctions. This leads to the voltage

$$V/(I_{c0}R_N) = w\overline{\dot{\varphi}} = w\overline{(\dot{\Phi} + r\dot{m}_y)} = w\overline{\dot{\Phi}},$$

because

$$\overline{\dot{m}}_y = \frac{1}{T} \int_0^T \mathrm{d}t \, \dot{m}_y = \frac{m_y(T) - m_y(0)}{T} \xrightarrow{T} 0.$$

Thus, the CVCs, for φ_0 JJs with $I_c(m_x) = I_{c0} = \text{const}$, coincide with the CVCs of the corresponding S/I/S junctions. Furthermore, the effect of the magnetization dynamics on such φ_0 S/F/S junctions has recently been discussed [13–18]. We stress here that the dynamical aspects discussed in these previous works relied on having capacitance in the system, while in our present work there is no capacitance.

B. Type (ii) systems

In type (ii) systems the magnetic dynamics is decoupled from phase dynamics, but not vice versa [12,34,36]. In this case the magnetization "feels" only the total current $i = i_{dc} + i_{ac} \sin(\Omega t)$ and is unaffected by the value of φ or $\dot{\varphi}$. If we measure the CVCs of such junctions for $i_{ac} = 0$, we do not see any interesting effects, because the magnetization lines up along one of the stable directions: $\mathbf{m} = (0, \text{ Gr}i_{dc}, \pm \sqrt{1 - (\text{Gr}i_{dc})^2})$ for $\text{Gr}i_{dc} < 1$, or $\mathbf{m} = (0, \pm 1, 0)$ for $\text{Gr}i_{dc} \ge 1$. These stable directions preserve $m_x = 0$, which leads to the preservation of $i_c(m_x)$ along the CVCs. Hence, since the CVCs are determined by φ and $i_c(m_x(t))$, they are unaffected by the magnetization motion in this case.

When we consider $i_{ac} > 0$, for type (ii) systems, we do find interesting features in the CVCs. In Fig. 2, for example, we show the CVCs and the LE spectrum for downward and upward sweeps of the dc bias, respectively. With the ac drive on, the effective dimension of the autonomous state space is now 4: two dimensions for the magnetic subsystem, one for the time-dependent drive and one for the overdamped JJ. The LE spectrum thus consists of four exponents, one being trivially zero, since it corresponds to the perturbation tangent to the trajectory, which fluctuates with no net growth or decay [68]. We see the appearance of a chaotic region for $0.065 < i_{dc} < 0.83$, as indicated by the positive maximal LE, $\lambda_1 > 0$. In addition, we see that the $V(i_{dc})/(I_{c0}R_N)$ functions take different values depending on whether the dc current is increasing or decreasing.

The appearance of the chaotic regions in the CVCs, shown in Fig. 2, is directly related to the chaotic magnetization dynamics. To demonstrate this relationship we have also calculated the LEs for the 3D magnetic subsystem on its own (i.e., the driven LLG equation [69]). We do not show the result of this calculation here, because the three exponents of the magnetic subsystem alone turn out to be exactly the same as the three largest exponents shown in Fig. 2 (i.e., the same as for the unidirectionally coupled system). From this coincidence of the LEs, we conclude that the chaos in the magnetic subsystem is a result of the ac drive, while the chaos in the voltage states of the



FIG. 2. The typical CVCs for model (ii), together with the LE spectrum (λ_i , i = 1, 2, 3, 4), time-averaged voltage $V/(I_{c0}R_N)$, and time-averaged \overline{m}_y , shown as functions of the dc bias i_{dc} , for (a) decreasing and (b) increasing current. The parameters of the system are G = 0.2, r = 5, $\alpha = 0.02$, $\Omega = 1$, $i_{ac} = 0.5$, w = 0.05, and $\tilde{d}_F = 1$. The arrows indicate the direction of the current sweep, while the vertical grid lines correspond to $i_{dc} = 1.44$, a value that will be discussed in connection with Figs. 3 and 8–11.

junction merely reflects the chaotic motion inherent in the magnetic subsystem.

The two branches in the CVCs shown in Fig. 2 are not due to inertial effects, as there are no inertial terms in our models. Rather, as we have mentioned, they are due to different modes that occur in the magnetic subsystem. One can see the effect of the magnetization dynamics by making a comparison between the basins of attraction to different periodicities in $\mathbf{m}(t)$, relative to the drive cycle, and those for the average voltage, as shown in Fig. 3. To obtain Fig. 3, we set $\varphi = 0$ at t = 0, and solve Eq. (6) for 19802 initial conditions (ICs) for m_x , m_y , and m_z . The ICs for the magnetization are expressed in terms of the spherical polar angles (θ, ϕ) , and are uniformly spread over the unit sphere. Each point on the sphere is spaced at an angle of $\pi/100$, giving 99 × 200 + 2 = 19802 points in total. The two extra points are added for the north (0, 0, 1) and south (0, 0, -1) poles. From these initial angles, we then generate the corresponding initial Cartesian components via the usual transformations: $m_x = \sin \theta \cos \phi$, $m_y = \sin \theta \sin \phi$, and $m_z = \cos \theta$. In practice, because of the inherent symmetry in the equations [18]—that is, $m_x \rightarrow -m_x$, $m_y \rightarrow$



FIG. 3. (a) Comparison between the basin of attraction to different periodicities in the magnetization dynamics. The basin of attraction consists of either period 1 or fixed point (FP) behavior, with no chaos (C) in this case. See the color scale on the right. (b) The basin of attraction to the time-averaged voltage. Comparison of (a),(b) shows that there is one-to-one correspondence between the two basins, as discussed in the main text. In both figures $\varphi = 0$ at t = 0 and $i_{dc} = 1.440$. All other parameters are the same as in Fig. 2.

 $m_y, m_z \rightarrow -m_z$ (or in polar coordinates $\theta \rightarrow \pi - \theta, \phi \rightarrow \pi - \phi$)—we need only use the 10 001 ICs which lie in the $z \ge 0$ hemisphere. We see in Fig. 3 that the dependence of the average voltage on the ICs corresponds exactly to the different periodicities $\mathbf{m}(t)$ in relation to the drive, that is, many drive cycles correspond to one cycle of $\mathbf{m}(t)$. The values of the average voltages in Fig. 3(b) are equal to the voltages seen along the CVC shown in Fig. 2, for $i_{dc} = 1.44$ (1.20 and 0.95, respectively).

We have also found that the magnetization dynamics may possess multiple stable attractors at certain values of the dc bias, leading to additional branches in the CVCs. Such a multistability for the magnetic dynamics has been reported in many works (see, for example, [63-67]). As we mentioned previously, for type (ii) systems we have the unidirectional coupling between the magnetization and phase dynamics which allows us to investigate its magnetization modes separately from the phase dynamics. Using this property, we calculate the basins of attraction for the magnetization dynamics and identify three possible regimes at $i_{dc} = 1.25$, with periods 1, 2, and 4. Then we chose initial magnetization directions corresponding to different periods of the magnetization dynamics at $i_{\rm dc} = 1.25$. With the help of these directions and $\varphi = 0$ as ICs, we calculate CVCs sweeping the dc bias in up and down directions. We find that period-4 motion of the magnetization dynamics gives a rise to an additional branch shown in Fig. 4(a). In Figs. 4(a)–4(c), we show the additional branches in CVCs, together with the corresponding basins of attraction. Figures 4(b) and 4(c) are similar to Figs. 3(a) and 3(b), except that there are now three possible voltage states corresponding to three different magnetic modes, respectively. In Fig. 3, there were only two. Unfortunately, as we have shown in Sec. V, not all of the detected branches are robust to the effects of thermal fluctuations. In particular, the dashed red and blue branches, shown in Fig. 4(a), which are associated with the period-4 magnetization dynamics, are completely degraded by relatively small levels of noise. On the other hand, the two main branches are found to be fairly robust.

The one-to-one correspondence between the regions of particular $\mathbf{m}(t)$ periodicities and average voltage does not hold for lower dc biases. This phenomenon is shown in Fig. 5, for $i_{dc} = 1.175$. We see that the period-6 behavior of $\mathbf{m}(t)$, shown in brown in (a), does not map onto a unique value for $V(i_{dc})/(I_{c0}R_N)$, as shown in (b). Moreover, at certain parameters, the boundaries between basins of attraction to different magnetization modes may become fragmented. Such fractal boundaries can in fact be seen between the period-2 (green) and period-6 (brown) basins in Fig. 5(a). These appear to form a so-called riddled basin [70,71], for which every point in one basin is arbitrarily close to some point in another. Consequently, it becomes extremely difficult to discover all possible branches in the CVCs of our system, and we do not claim to have done so here.

A detailed analysis of the system is provided in the Appendix. It shows that the breaking of the one-to-one correspondence depends on the relative amplitudes of the Fourier harmonics in the frequency spectrum of $i_c(m_x)$.

C. Type (iii) systems

In the third system type, the magnetization of the interlayer depends explicitly on the phase difference $\Phi = \varphi - rm_y$ (see Table I). As a result of this dependence, the dc bias alone produces a time-varying torque on the magnetization and one may therefore expect to see interesting dynamical features, including chaos, in CVCs of the type (iii) system without ac driving.

As an example, we show in Fig. 6 the results for the type (iii) system with w = 1 and $i_{ac} = 0$. Without the ac drive, there are no Shapiro steps in the CVC, as shown in Fig. 6(a). Since the effective dimension of the state space is only 3 (i.e., two dimensions for the magnetic subsystem and only one for that of the overdamped JJ), the LE spectrum consists of only three exponents, one being trivially zero, as usual. As the dc bias is varied, we encounter three distinct regions: *periodic*, for $i_{dc} \gtrsim 1.284$; *chaotic*, for $1 < i_{dc} \lesssim 1.284$; and a *fixed point* (FP), for $i_{dc} \le 1$. Because there is no external ac drive here, we measure



FIG. 4. (a) Additional branches in the CVCs due to different magnetization modes in the type (ii) system. The parameters are the same as in Figs. 2 and 3, with the arrows indicating the sweep directions of the dc bias i_{dc} . The black branches are the same as in Figs. 2(a) and 2(b). The additional branches, shown by the dashed lines, were obtained by choosing a particular IC, at $i_{dc} = 1.25$, and then sweeping i_{dc} up (blue dashed line) and down (red dashed line). In both directions we find period-4 behavior in $\mathbf{m}(t)$. The vertical dashed grid line just shows the position of $i_{dc} = 1.25$ are shown for the periodicity of $\mathbf{m}(t)$ and the time-averaged voltage, respectively.

the periodicity of the system relative to the oscillations of $\sin(\varphi - rm_y)$. Specifically, in our numerical simulations we detect how many oscillations of $\sin(\varphi - rm_y)$ correspond to one cycle of $\mathbf{m}(t)$, as explained in [18]. Comparing Figs. 6(b) and 6(c) we see the periodicities of m_x and m_y differ in the $i_{dc} \gtrsim 1.284$ region. We find that the periodicities of m_x and m_z (or m_y , φ , and $\dot{\varphi}$) are always the same in this system, which is why orbit diagrams for m_z , φ , and $\dot{\varphi}$ have been omitted in Fig. 6. The period-2 and



FIG. 5. Broken one-to-one correspondence between the $\mathbf{m}(t)$ periodicities and $V/(I_{c0}R_N)$ at $i_{dc} = 1.175$, for the type (ii) system. In (a) we see that the region of period-2 behavior (green) is interspersed by period-6 behavior (brown), both corresponding to the Shapiro step, $V/(I_{c0}R_N) = 0.7$, represented by the white region(s) in (b). Other parameters are the same as in Figs. 2–4.

period-1 behavior of m_x and m_y , respectively, is related to the inherent symmetry of the equations, which can be seen clearly in the projection of the trajectory, as shown by the inset of Fig. 6(c). The onset to fully developed chaos occurs abruptly at $i_{dc} \approx 1.284$, without any transitioning through intermediatory quasiperiodic or period-doubling regions, as would usually be the case for an ordinary JJ. Finally, for $i_{dc} \leq 1$, the dynamics ceases as the system is attracted to one of the FPs: $m_x = 0$, $m_y = \text{Gr}i_{dc} =$ $\text{Gr} \sin(\varphi - rm_y)$, and $m_z = \pm \sqrt{1 - m_y^2}$. In the orbit diagrams, (b) and (c), when $\sin(\varphi - rm_y)$ does not oscillate, we plot these equilibrium values of m_x and m_y .

We have also generated additional branches in the CVCs and basins of attraction for the type (iii) system. In Fig. 7(a) we have used different ICs to generate the two main branches in the CVCs, corresponding to period-1 and period-2 behaviors in the magnetization. The corresponding periodicities of the magnetization can be seen in Figs. 7(b)–7(d), which show the basins of attraction at three selected dc biases. In Fig. 7(b) the bias current falls within the periodic region and we see that the magnetization vector **m** may exhibit either period-1 or period-2 behavior, depending on the ICs for θ and ϕ . The period-2 behavior here corresponds to orbit diagrams seen previously in Figs. 6(b) and 6(c), where we saw that m_x and m_y had periodicities 2 and 1, respectively. Obviously, the magnetization vector has periodicity corresponding to



FIG. 6. Dynamical response of the type (iii) system to sweeps in the dc-bias current, without the ac drive. In this case, the up and down sweep directions produce the same response. (a) Lyapunov exponents (λ_i , i = 1, 2, 3), time-averaged voltage $V/(I_{c0}R_N)$, and time-averaged \overline{m}_y . In (b),(c) the orbit diagrams are shown for m_x and m_y , respectively. The values shown along the vertical axes are plotted as points at the instant when $\sin(\varphi - rm_y)$ crosses from negative to positive. The inset in (c) shows the inherent symmetry in the typical periodic motion that occurs for $i_{dc} \gtrsim 1.284$, that is, to the right of the chaotic region. See the main text for details. Parameters: $i_{ac} = 0$, G = 0.2, r = 5, $\alpha = 0.02$, w = 1.0, and $\tilde{d}_F = 1$.

the lowest common multiple of the periodicities for its components. On the other hand, the period-1 behavior in **m** is a different regime, which gives rise to a different average voltage than that shown in Fig. 6(a). Thus, even for $i_{ac} = 0$, there occur different magnetization states which in turn can produce multiple branch structure in the CVCs. Here, since there is always a one-to-one correspondence between the magnetization modes and the average voltages within the periodic region, we have not show the corresponding basins for the average voltage. At other parameters,



FIG. 7. Time-averaged voltage (a) and the basins of attraction at three different dc biases (b)–(d), for the type (iii) system. (a) The two different branches in CVC which are in one-to-one correspondence with period 1 (red curve) and period 2 (blue curve) behavior in the magnetic subsystem. The CVC seen previously in Fig. 6(a) coincides with the blue curve for period 2. (b) Coexistence of period 1 and period 2 behavior in the basin of attraction at $i_{dc} = 1.450$. (c) Chaotic regime at $i_{dc} = 1.250$. (d) Coexistence of chaos and periods 5, 6, and 7 behavior within the periodic window surrounding $i_{dc} = 1.225$. Other parameters are as in Fig. 6. In the color scales on the right, FP and C stand for fixed point and chaos, respectively.

however, the one-to-one correspondence could be broken, as we saw previously for the type (ii) system. In Fig. 7(c) we see that, at $i_{dc} = 1.250$, the chaos is global, that is, it does not depend on the ICs. On the other hand, within the chaotic region there are windows of periodic behavior which arise only for certain ICs, such as the one that can be seen in Fig. 6(a) at $i_{dc} = 1.225$. As shown in Fig. 7(d), at $i_{dc} = 1.225$, the basin of attraction within the periodic window contains mostly period-4 behavior, but it is also shared to lesser degrees by period-5, period-6, period-7, and chaotic behavior (corresponding to gray in the color bar). Moreover, as we have mentioned before, the basins are not separated by clear boundaries, but rather are highly fragmented.

IV. DYNAMICAL SWITCHING OF THE JOSEPHSON JUNCTION VOLTAGE STATES VIA A CURRENT PULSE

In this section we demonstrate that it is possible, without capacitance, to switch between different dynamical voltage states, which are seen in the previous sections. We express the switching current pulse in terms of two Heaviside step functions, $\theta(t)$, as

$$i_p(t) = A_s \left[\theta(t - t_0) - \theta(t - \delta t - t_0) \right] \sin \left[\Omega(t - t_0) \right],$$
(7)

where A_s is the height of the pulse, δt is its width, and t_0 is its start time. To apply the switch in our models we simply

add $i_p(t)$ to the total current, $i_{dc} + i_{ac} \sin(\Omega t)$ in Eq. (6), after the usual transient time.

For simplicity, we discuss only the type (ii) model at the dc bias, $i_{dc} = 1.44$. At this current there exist only two magnetization regimes (see Fig. 3): the FPs $\mathbf{m} =$ $(0, \pm 1, 0)$, and the period-1 motion. These regimes correspond to the average voltages $V/(I_{c0}R_N) = 0.95$ and $V/(I_{c0}R_N) = 1.20$, respectively (see Fig. 2). As shown in Fig. 8, the application of the pulse switches the system from the upper branch $(V/(I_{c0}R_N) = 1.20)$ to the lower branch $(V/(I_{c0}R_N) = 0.95)$.

In our present simulations, it was not possible to switch back from the state with $V/(I_{c0}R_N) = 0.95$ at $i_{dc} = 1.44$ to the state $V/(I_{c0}R_N) = 1.20$ at $i_{dc} = 1.44$, due to the fact that, when the magnetization is located at one of the FPs $\mathbf{m} = (0, \pm 1, 0)$, the torque produced by the current pulse cannot move the magnetization away from the FP, even if the FP becomes unstable (because T_2 always acts parallel to m). Thus, in order to achieve switching in both directions, we need to add thermal noise in the form of the thermal field [26], rather than in the form of a thermal current [27]. The thermal noise directly affects the magnetization dynamics, thereby allowing the system to switch back out of the FPs, provided that they are unstable, of course. However, a full discussion of the switching properties of the three types of system present, such as recently done by Guarcello et al. [28] for the case of an underdamped junction, is beyond the scope of the present work.



FIG. 8. Magnetization dynamics in the type (ii) system under the current pulse. (a) The applied current pulse is given by Eq. (7) and is shown by the black arrow. The parameters for the pulse are $A_s = 0.75$, $\delta t = \tau/2$, and $t_0 = 10\tau$. The initial condition used here for the period-1 behavior is $\theta = \phi = 2$ and $\varphi = 0$; cf. Fig. 3(a). Other parameters are the same as in Figs. 2 and 3 (i.e., $i_{dc} = 1.44$, $i_{ac} = 0.5$). (b) The switching from period-1 motion (P1, shaded regions) with $V/(I_{c0}R_N) = 1.20$ to the fixed point (FP) $\mathbf{m} = (0, 1, 0)$ with $V/(I_{c0}R_N) = 0.95$. (c) Time series of the change in voltage that occurs as a result of the switching. The running average (dashed red line) has been computed over 50 time units, using 5000 samples.

In the next section, we will briefly show how the obtained features of the CVCs behave under the influence of thermal fluctuations.

V. STABILITY OF THE JOSEPHSON JUNCTION VOLTAGE STATES TO THERMAL FLUCTUATIONS

Until now relatively few studies have included the effects of noise in systems of JJs coupled to the LLG

equation [26–28]. However, the effects of noise on the two separate subsystems (JJ and LLG), have been studied intensively. For example, the magnetization dynamics with thermal noise has been studied in Refs. [72–75]. In addition, the JJ dynamics in the presence of thermal noise has been investigated in Refs. [76–82]. In the present section we investigate the coupled dynamics of the JJ and its interlayer magnetization in the presence of thermal noise.

In the previous sections we have seen that the CVCs of overdamped φ_0 JJs exhibit some unusual features that are related to the induced magnetization dynamics in the interlayer. These features included chaotic states and, in particular, hysteresis that led to multiple branches in the CVCs. Since the latter feature could facilitate certain cryogenic switching applications, it is important to test how it may be affected by thermal noise, which is inevitably present in real systems. Therefore, in this section, we will calculate the noise-averaged CVCs corresponding to the branches found earlier. As we shall see, for typical noise levels, we may still expect to achieve switching, such as we have seen in connection with Fig. 8, without noise. Furthermore, while in Fig. 8 we were unable to switch the system back from the FP to period-1 behavior, we find that the thermal noise sufficiently destabilizes the FP to allow switching in both directions.

As a general study of the influence of thermal noise on φ_0 JJs is beyond the scope of our present work, we focus here again on type (ii) systems with the same parameters as before: G = 0.2, r = 5, $\alpha = 0.02$, $\Omega = 1$, $i_{ac} = 0.5$, w = 0.05, and $\tilde{d}_F = 1$. Following the latest methods employed in other studies involving noise in magnetic systems [26–28], we add the thermal noise to Eq. (6), as follows:

$$\dot{\mathbf{m}} = -\frac{1}{1+\alpha^2} \left\{ \mathbf{m} \times \left(\mathbf{T}_2 + m_z \hat{\mathbf{e}}_{s_z} + \mathbf{h}_{\text{th}} \right) + \alpha \mathbf{m} \times \left[\mathbf{m} \times \left(\mathbf{T}_2 + m_z \hat{\mathbf{e}}_z + \mathbf{h}_{\text{th}} \right) \right] \right\},$$
(8a)

$$\mathbf{T}_2 = \operatorname{Gr}\left(i_{\rm dc} + i_{\rm ac}\sin\left(\Omega t\right) + i_{\rm th}\right)\hat{\mathbf{e}}_y,\tag{8b}$$

$$w\dot{\Phi} = i_{\rm dc} + i_{\rm ac}\sin\left(\Omega t\right) + i_{\rm th} - i_c\left(m_x\right)\sin\Phi. \tag{8c}$$

Here, \mathbf{h}_{th} and i_{th} represent the fluctuating thermal field and the noise in current, respectively. The noise sources obey the following white noise correlation properties:

$$\langle i_{\rm th}(t) \rangle = 0, \quad \langle i_{\rm th}(t)i_{\rm th}(t') \rangle = 2D_I \delta(t-t'), \langle h_{i,\rm th}(t) \rangle = 0, \quad \langle h_{i,\rm th}(t)h_{j,\rm th}(t') \rangle = 2D_H \delta_{ij} \delta(t-t').$$

$$(9)$$

In Eq. (9), the notation $\langle ... \rangle$ denotes the average over noise realizations and $i,j \equiv x, y, z$. The dimensionless coefficients are given by $D_I = wk_B T/E_J$ and $D_H = \alpha k_B T/(KV) = \alpha G D_I/w$, where T is the temperature. D_I and D_H determine the respective noise intensities in the system. For $T_c \approx 10 \ K$, $I_{c0} \approx 0.45 \ \mu A$, $T \approx T_c/10$, and $E_J = ((\hbar I_{c0})/2e)$ we estimate $D_I \sim 5 \times 10^{-3}$. Using the further variation of *T*, one may gain additional control over D_I that may take values from $D_I \sim 5 \times 10^{-4}$ to 5×10^{-2} . For low temperatures $T \ll T_c$, we estimate the relation between D_H and D_I to be $D_H \approx 0.08 D_I \ll D_I$.

The noise induced by i_{th} and $h_{i,th}$ enters (8) multiplicatively, which is why we use the Stratonovich prescription for the stochastic integration (see, for example, [75]). This numerical scheme treats the magnetization in spherical polar coordinates and is given by

$$\begin{split} \Phi^{n} - \Phi^{n-1} &= \frac{1}{w} \left[i_{dc} + i_{ac} \sin \Omega t^{n-1} - i_{c} \left(\frac{m_{x}^{n} + m_{x}^{n-1}}{2} \right) \sin \left(\frac{\Phi^{n} + \Phi^{n-1}}{2} \right) \right] \Delta t + \frac{\Delta i_{th}}{w}; \\ h_{\theta}^{n-1} &= Gr(i_{dc} + i_{ac} \sin \Omega t^{n-1}) \cos \left(\frac{\theta^{n} + \theta^{n-1}}{2} \right) \sin \left(\frac{\Phi^{n} + \Phi^{n-1}}{2} \right) - \frac{1}{2} \sin \left(\theta^{n} + \theta^{n-1} \right); \\ h_{\phi}^{n-1} &= Gr(i_{dc} + i_{ac} \sin \Omega t^{n-1}) \cos \left(\frac{\Phi^{n} + \Phi^{n-1}}{2} \right); \\ \Delta h_{\theta}^{n-1} &= \Delta h_{x,th} \cos \left(\frac{\theta^{n} + \theta^{n-1}}{2} \right) \cos \left(\frac{\Phi^{n} + \Phi^{n-1}}{2} \right) - \Delta h_{z,th} \sin \left(\frac{\theta^{n} + \theta^{n-1}}{2} \right) \\ &+ \left[\Delta h_{y,th} + \operatorname{Gr} \Delta i_{th} \right] \cos \left(\frac{\theta^{n} + \theta^{n-1}}{2} \right) \sin \left(\frac{\Phi^{n} + \Phi^{n-1}}{2} \right); \\ \Delta h_{\phi}^{n-1} &= \left[\Delta h_{y,th} + \operatorname{Gr} \Delta i_{th} \right] \cos \left(\frac{\Phi^{n} + \Phi^{n-1}}{2} \right) - \Delta h_{x,th} \sin \left(\frac{\Phi^{n} + \Phi^{n-1}}{2} \right); \\ \theta^{n} - \theta^{n-1} &= \frac{\Delta t}{1 + \alpha^{2}} \left[h_{\phi}^{n-1} + \alpha h_{\theta}^{n-1} \right] + \frac{1}{1 + \alpha^{2}} \left[\Delta h_{\phi}^{n-1} + \alpha \Delta h_{\theta}^{n-1} \right]; \\ \phi^{n} - \phi^{n-1} &= \left\{ (1 + \alpha^{2}) \sin \left(\frac{\theta^{n} + \theta^{n-1}}{2} \right) \right\}^{-1} \left\{ \Delta t \left[-h_{\theta}^{n-1} + \alpha h_{\phi}^{n-1} \right] - \Delta h_{\theta}^{n-1} + \alpha \Delta h_{\phi}^{n-1} \right\}. \end{split}$$

Here Δt is a constant timestep and *n* is the discrete time index $(t_n = n\Delta t)$ for the state variables $\{\Phi^n\}$, $\{\theta^n\}$, and $\{\phi^n\}$. The noise terms $\Delta i_{\text{th}} \sim \mathcal{N}(0, 2D_I\Delta t)$, $\Delta h_{i\text{th}} \sim \mathcal{N}(0, 2D_I\Delta t)$ are normally distributed with zero mean and variances $2D_I\Delta t$, $2D_H\Delta t$, respectively.

A. Current-voltage characteristics in the presence of thermal fluctuations

We have recalculated the CVCs that were seen previously in Fig. 2, with the help of the stochastic Eq. (10). We used a timestep $\Delta t = 0.001$, which was found to be sufficiently small to ensure proper convergence. To obtain good statistics we swept the dc bias up and down, 100 times in each direction, and for two low-temperature noise intensities: $(D_I, D_H) = (1, 0.08) \times 10^{-3}$ and $(D_I, D_H) =$ $(5, 0.4) \times 10^{-4}$. The results are presented in Fig. 9. As one may expect, the thermal noise tends to "wash out" the Shapiro steps (cf. Fig. 2) in both of the branches. It also induces jumps from one branch to another, with the result that both branches may occur along either a downward or upward sweep of the dc bias. By comparing the red CVCs (those with the higher noise intensity) to the blue CVCs (those with the lower noise intensity), we see that the jump frequency and position (the value of i_{dc} at which the jump occurs) also depend on the noise intensity. At the higher noise intensity the two branches are somewhat less developed, as one might expect. However, the important point to notice is that both branches are robust to the added noise at $i_{dc} \approx 1.44$, indicated by the vertical dashed lines in Figs. 9(b) and 9(c). For the case of the higher noise level shown in (b), both branches are present along the downward sweep in current, while for the case of the lower noise level shown in (c), both branches occur along the upward sweep.

B. Switching in the presence of thermal fluctuations

In Sec. IV we demonstrated that it is possible, without taking into account thermal fluctuations, to use the current pulse $i_p(t)$ to switch from the period-1 motion to an FP. We also saw that it was not possible to switch back from the FP to the period-1 motion. In this subsection, we will



FIG. 9. CVCs of type (ii) systems at two levels of noise intensity: (a),(b) $(D_I, D_H) = (10^{-3}, 8 \times 10^{-5})$; (c),(d) $(D_I, D_H) = (5 \times 10^{-4}, 4 \times 10^{-5})$. Horizontal arrows indicate the direction of the current sweep. The dashed vertical lines indicate $i_{dc} = 1.44$, the current corresponding to where the switching was investigated in Fig. 8. Other parameters are the same as in Figs. 2–5 and 8.

repeat our simulations of switching with the added thermal fluctuations.

In Fig. 10, we show the same experiment as in Fig. 8, performed here with the added thermal fluctuations. We choose the lower noise intensity level corresponding to the two voltage branches shown in Fig. 9(c), at $i_{dc} = 1.44$. In the presence of these thermal fluctuations, we see that switching from period-1 motion to the FP is still possible.

As mentioned in connection with Fig. 8, in our simulations without the added thermal fluctuations, it appeared to be impossible to switch back from the FP, with $V/(I_{c0}R_N) = 0.95$, to the period-1 motion, with $V/(I_{c0}R_N) = 1.20$. It was not possible because the torque T_2 always acts parallel to **m** at the FPs $(0, \pm 1, 0)$. In the absence of thermal fluctuations, if one switches off the total current i_{dc} , the FPs become unstable, but there is nothing in the simulation to perturb **m** away from one of the FPs. The magnetization therefore remains on one of these points. In the presence of thermal fluctuations, however, this situation changes. We find that, after switching off the total current for a short time interval, the thermal fluctuations drive the system away from the unstable FP and, when the total current is switched back on, the magnetization may return to the period-1 motion. This transition can be induced reliably, provided that the time interval over which the total current is switched off is chosen so



FIG. 10. Magnetization dynamics in the type (ii) system under the current pulse in the presence of thermal fluctuations. (a) The applied current pulse is given by Eq. (7) and is shown by the black arrow. The parameters of the system and the current pulse are the same as in Figs. 2, 3, and 8. (b) The switching from period-1 motion (P1, shaded regions) with $V/(I_{c0}R_N) = 1.20$ to the fixed point (FP) $\mathbf{m} = (0, 1, 0)$ with $V/(I_{c0}R_N) = 0.95$. (c) Time dependence of the voltage along the JJ is blurred by the thermal fluctuations. The running average (dashed red line) has been computed over 50 time units, using 5000 samples. The noise intensities $D_I = 5 \times 10^{-4}$, $D_H = 4 \times 10^{-5}$ are used for (b),(c).

that the magnetization is perturbed from the FP into the basin of attraction for the period-1 motion. An example of this switching back, from the FP to period-1 motion, is provided in Fig. 11. In this case, we achieved the switching by simply turning off the total current for half a drive cycle. Our simulations thus demonstrate that switching in presence of the added thermal fluctuations is indeed feasible. In fact, the instability caused by the added thermal fluctuations makes it possible to switch the system in both directions, as we have seen.



FIG. 11. Magnetization dynamics in the type (ii) system in the short-time absence of the applied current in presence of the thermal fluctuations. (a) The applied current i(t) is switched off for $\tau/2$ at $t_0 = 110\tau$. The parameters of the system are the same as in Figs. 2, 3, 8, and 10. (b) The switching from the fixed point (FP) $\mathbf{m} = (0, 1, 0)$ with $V/(I_{c0}R_N) = 0.95$ to the period-1 motion (P1, shaded regions) with $V/(I_{c0}R_N) = 1.20$. (c) Time dependence of the voltage along the JJ is blurred by the thermal fluctuations. The running average (dashed red line) has been computed over 50 time units, using 5000 samples. The noise intensities $D_I = 5 \times 10^{-4}$, $D_H = 4 \times 10^{-5}$ are used for (b),(c).

VI. CONCLUSION

We have studied the effect of the current-induced magnetization dynamics on the CVCs of three types of overdamped φ_0 JJs with dc and ac biases. We have shown that there exist three different scenarios for this effect depending on the system under consideration. In type (i), for S/FM + Rashba/S structures, the magnetization dynamics has no effect on CVCs. In type (ii), for S/FI/S on TI structures, the magnetization dynamics may lead to the presence of chaos and hysteresis with multiple branches in CVCs. In type (iii), for S/FM/S on TI structures, the appearance of chaotic regimes and hysteresis is possible, even in the absence of the capacitance and without ac driving. Due to the additional magnetization degrees of freedom, even the overdamped φ_0 Josephson junction may exhibit complex dynamical regimes that are reflected in its CVCs as hysteresis and chaos. Moreover, these dynamical regimes may exist even in absence of the ac driving. As the presence of the chaos and the hysteresis can affect potential uses of such systems in, for example, superconducting memory, we believe our results may add value to the emerging field of spintronics. We have also discussed the possibility of applying the hysteresis found in our simulations for the current pulse induced switching between the voltage states of the junctions under consideration, at a fixed dc bias. Our simulations support the idea that switching is also possible in the overdamped limit, and even in the presence of thermal fluctuations. In fact, the instability provided by the added thermal fluctuations makes it possible to switch the type (ii) system back and forth between its two different voltage states, one being related to period-1 behavior of the magnetization dynamics, the other to a FP. Such switching properties are very promising for potential applications. They may serve as the source of voltage signals in rapid single-flux quantum logic schemes, or as energy-dependent memory, where the written information is encoded in the voltage of the junction.

Finally, from a dynamical systems point of view, the transition we found in the type (iii) system at $i_{dc} = 1$, from the stable FP immediately to chaos, is extremely interesting. Since there are few instances of such behavior in the literature (a notable exception being [83]), it would be well worth further investigation. In future work we may try to establish rigorously whether or not the type (iii) system may indeed present a fundamentally different, or at least rare, route to chaos.

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APPENDIX: BROKEN ONE-TO-ONE CORRESPONDENCE BETWEEN m(t) PERIODICITIES AND CURRENT-VOLTAGE CHARACTERISTICS FOR THE TYPE (II) SYSTEM

To understand why the one-to-one correspondence is broken, we notice that the function $\Phi = \varphi - rm_v$ in Eq. (6b) depends indirectly (and hence nonlinearly) on m_x via the critical current $i_c(m_x)$. Thus, the frequency spectra of the time series $i_c(m_x(t))$ and $m_x(t)$ can contain very different components and we need to consider how time-dependent deviations of the critical current from its mean (rather than the oscillations of m_x), perturb the JJ. To this end, we expanded the perturbation, $\delta i_c(t) =$ $i_c(m_x) - \overline{i_c(m_x)}$, in a Fourier series with the frequencies $\Omega_i = \lambda_i \Omega$, where the λ_i are positive numbers describing the harmonics ($\lambda_i = 1, 2, 3, ...$) and subharmonics ($\lambda_i =$ $1/2, 1/3, \ldots$) of the ac-drive frequency, Ω . For a fixed value of i_{dc} , the Josephson oscillations have the frequency $\omega_J = \dot{\Phi}$. For frequency locking to occur, we must have $\omega_J = k\Omega + \sum_i m_i \lambda_j \Omega$, where the term $k\Omega$ comes from the ac drive, and the terms $m_i \lambda_i \Omega$ come from the perturbation, $\delta i_c(t)$. As we have seen in Fig. 2, typically, for integer Shapiro steps, such frequency locking will occur when kand $m_i \lambda_i$ are integers.

Now, let us focus on two specific ICs, $\mathbf{m}_1(0)$ and $\mathbf{m}_2(0)$, each of which leads to a different magnetization mode at the same value of i_{dc} . We assume that each of the magnetization modes, $\mathbf{m}_1(t)$ and $\mathbf{m}_2(t)$, corresponds to two different Shapiro steps, with the average voltages being V_1 for $\mathbf{m}_1(t)$ and V_2 for $\mathbf{m}_2(t)$. If the spectra of $\delta i_c(m_{x1})$ and $\delta i_c(m_{x2})$ contain the same subset of frequencies, $\lambda_i \Omega$, j = 1, 2, ... (which are responsible for the synchronization between the Josephson oscillations and the magnetic oscillations), then we find that $V_1 = V_2$. Note that this equality of the voltages does not rely on the amplitudes of the various harmonics of $\delta i_c(m_{x1})$ and $\delta i_c(m_{x2})$ being the same. It depends only whether the two harmonic series have the same set of the frequencies $\lambda_i \Omega$, j = 1, 2, ...Moreover, the spectra of $\delta i_c(m_{x1})$ and $\delta i_c(m_{x2})$ may contain small amplitude harmonics with mismatched frequencies, without affecting $V_1 = V_2$.

If the spectrum of $\delta i_c(m_{x1})$ contains at least the one term $A_{1k} \sin (\lambda_k \Omega t + \chi_{1k})$ in which A_{1k} significantly differs from the corresponding amplitude A_{2k} of the spectrum for $\delta i_c(m_{x2})$, then one may expect to see $V_1 \neq V_2$. Typically, the bifurcations which are responsible for the birth of subharmonics of Ω in $\mathbf{m}(t)$ do not greatly rearrange the amplitudes of $\delta i_c(t)$. That is why we do not see the high periodicities (6 or greater) of $\mathbf{m}(t)$ in the CVCs.

In order to clarify these ideas via a concrete example, we replace the full dependence $i_c(m_x)$ with the simplified, approximate function $\overline{i_c(m_x)} + A_\lambda \sin(\lambda \Omega t) + A_1 \sin(\Omega t)$. Specifically, we insert this approximate function into the RSJ model [Eq. (6b)], and then recompute the Shapiro



FIG. 12. Stability of the first Shapiro step $\omega_J = \Omega$ against weak harmonic perturbations for changing the amplitudes of (a) $A_{1/2}$ and (b) λ . The parameters used are w = 0.05, $\overline{i_c(m_x)} = 0.9$, $A_1 = 0.1$, $i_{ac} = 0.5$, and $\Omega = 1$.

steps for different values of A_{λ} and λ . The results of these calculations are presented in Fig. 12. We see in Fig. 12(a) that there exists an interval, $0.554 \le i_{dc} \le 0.570$, for the first Shapiro step, $\omega_J = \Omega$, for which $A_{1/2} = 0.05$ produces the same voltage as $A_{1/2} = 0$. In addition, $A_{1/2} = 0.2$ is so large that it shifts the current interval for the first Shapiro step to the left-hand side of the picture. Similarly, in Fig. 12(b) we find that none of the subharmonics, $A_{1/2} \sin (\Omega t/2)$, $A_{3/4} \sin (\Omega \Omega t/4)$, or $A_{3/2} \sin (\Omega \Omega t/2)$, shift the voltage of the first Shapiro step in the current interval $0.561 \le i_{dc} \le 0.567$. Therefore, for small enough harmonic perturbations the voltages of the two Shapiro steps remain the same, besides the voltages of the additional steps due to the spectral form of the perturbation.

Close inspection of the CVC shown in Fig. 2(b), in the region $i_{dc} \approx 1$, also reveals half-integer Shapiro steps. On these half-integer steps we found that the spectrum of $\delta i_c(m_x)$ contains subharmonics of Ω which are approximately of the same order of magnitude as the harmonics of Ω . Thus, the same locking mechanism appears to apply to both types of steps.

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