

## Optical Trapping in a Dark Focus

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The superposition of a Gaussian mode and a Laguerre-Gauss mode with  $\ell = 0, p \neq 0$  generates the so-called bottle beam: a dark focus surrounded by a bright region. In this paper, we theoretically explore the use of bottle beams as an optical trap for dielectric spheres with a refractive index smaller than that of their surrounding medium. The forces acting on a small particle are derived within the dipole approximation and used to simulate the Brownian motion of the particle in the trap. The intermediate regime of particle size is studied numerically and it is found that stable trapping of larger dielectric particles is also possible. Based on the results of the intermediate-regime analysis, an experiment aimed at trapping living organisms in the dark focus of a bottle beam is proposed.

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### I. INTRODUCTION

Tightly focused laser beams can be used to exert forces upon dielectric particles. If the refractive index of the particle is *larger* than that of its surroundings, the laser pulls it to regions of higher intensity of light. This technique, introduced by Ashkin in 1986 [1] and known today as optical tweezing, allows one to hold and manipulate very tiny objects and finds applications in a large number of fields ranging from biology [2–5] to fundamental physics [6–10]. In standard optical tweezers, Gaussian beams are used to create the trapping focus. To a good approximation, the trap can be described as a three-dimensional quadratic potential.

Notably, it has also been pointed out by Ashkin that air droplets immersed in water are pushed away from the Gaussian focus [11]. This is a consequence of the fact that when the refractive index of the particle is *smaller* than that of its surroundings, the particle is repelled from the region of high intensity. One can then envision an *inverted* optical trap, in which an engineered beam of light has a high-intensity boundary and a dark focus. A particle with the appropriate refractive index will be trapped within the dark focus by the absence of light [12]. We refer to this type of beam, which has first been proposed as a tool to

trap atoms [13–16], as a *bottle beam*. A bottle beam such as the one proposed in [17] is one example in a myriad of engineered optical traps aimed at different purposes such as Bessel beams [18], frozen waves [19], circular Airy beams [20–22], radially polarized beams [23,24], and many others [25–30].

Several techniques can be employed to create bottle beams, such as the generation of Bessel beams using axicons [31–33], the interference of Gaussian beams of different waists [34], and the superposition of different modes [35–37] created using spatial light modulators (SLMs). Here, we focus on the bottle beam created by the superposition of a Gaussian beam and a Laguerre-Gauss beam with  $\ell = 0, p \neq 0$  and a relative phase of  $\pi$  presented in [17] and study the optical forces it exerts upon low-refractive-index particles.

The superposition of a Gaussian mode and a Laguerre-Gaussian beam with  $\ell = 0, p \neq 0$  is an interesting choice for a number of reasons. First, as we show, it yields a simple mathematical description from which the trapping potential can be readily obtained. Moreover, description of the trap in terms of its width, height, and shape is simple and clearly defined. Furthermore, such superposition is promptly obtained by the use of a SLM, a well-established technique for engineering structured light beams available in the laboratory [38–41].

Because optical trapping can be applied to particles in a wide size range [42,43], we analyze both the cases of small Rayleigh particles and of larger micron-sized particles. In the former, the optical forces and potential are derived from the dipole approximation and thoroughly analyzed under different assumptions, which are verified

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by simulating the motion of the trapped particle in a viscous medium. In the latter, generalized Lorenz-Mie theory is employed to calculate the forces caused by the beam, with the aid of the tools introduced in Ref. [44]. Constraints on the numerical aperture, particle size, and relative refractive index are found.

An understanding of particle dynamics under the influence of a bottle beam can lead to striking applications. Notably, the bottle is an interesting tool for trapping experiments requiring little or no light scattering upon the trapped object. This is of particular interest in biology, where trapping a living cell or organelles within the cell without the constant influence of laser light might be crucial in revealing the mechanical properties of the organism without excessive heating and laser interference [45–47]. We thus propose a set of experimental parameters that could be used to trap living organisms in the dark focus of a bottle beam.

## II. THE DIPOLE APPROXIMATION

We begin by investigating the optical forces acting on a Rayleigh particle with a refractive index lower than its surrounding medium under the dipole approximation. This is valid when the radius of the trapped particle is much smaller than the wavelength of the trapping laser ( $R \lesssim \lambda/10$ ) [48].

### A. The optical bottle beam

To generate a dark focus surrounded by a bright region, we superpose a Laguerre-Gauss beam with  $\ell = p = 0$ —a Gaussian beam—and a Laguerre-Gauss beam with  $\ell = 0, p \neq 0$  and a relative phase of  $\pi$ . The electric field magnitude of a Laguerre-Gauss (LG) beam is

$$E_{\ell,p}^{\text{LG}}(\rho, \phi, z) = \sqrt{\frac{4P_0}{c\epsilon\pi\omega(z)^2}} \sqrt{\frac{p!}{(|\ell| + p)!}} \times \left(\frac{\sqrt{2}\rho}{\omega(z)}\right)^{|\ell|} L_p^{|\ell|}\left(\frac{2\rho^2}{\omega(z)^2}\right) \exp\left[-\frac{\rho^2}{\omega(z)^2}\right] \times \exp\left[ik_m z + ik_m \frac{\rho^2}{2R(z)} - i\zeta(z) + i\ell\phi\right], \quad (1)$$

where  $c$  is the speed of light,  $\epsilon$  is the permittivity of the medium,  $P_0$  is the laser power,  $k_m$  is the wave number in the medium and  $\omega(z)$ ,  $R(z)$ ,  $\zeta(z)$  and  $L_p^{|\ell|}$  are the beam width, the wave-front radius, the Gouy phase, and the associated Laguerre polynomial. These quantities are,

respectively, given by

$$\omega(z) = \omega_0 \sqrt{1 + \frac{z^2}{z_R^2}}, \quad (2)$$

$$R(z) = z \left(1 + \frac{z_R^2}{z^2}\right), \quad (3)$$

$$\zeta(z) = (2p + |\ell| + 1) \arctan \frac{z}{z_R}, \quad (4)$$

$$L_p^{|\ell|}(x) = \sum_{i=0}^p \frac{1}{i!} \binom{p+|\ell|}{p-i} (-x)^i, \quad (5)$$

where the Rayleigh range ( $z_R$ ) and the beam waist ( $\omega_0$ ) are defined as

$$\omega_0 = \frac{\lambda_0}{\pi \text{NA}}, \quad z_R = \frac{n_m \lambda_0}{\pi \text{NA}^2}, \quad (6)$$

in which  $\lambda_0$  is the wavelength in vacuum,  $n_m$  is the refractive index of the medium, and NA is the numerical aperture. Throughout this paper, we consider linearly polarized electric fields only.

The intensity of the bottle beam reads

$$I_p(\rho, z) = I_0 \frac{\omega_0^2}{\omega(z)^2} \exp\left[-\frac{2\rho^2}{\omega(z)^2}\right] \times \left[1 - 2 \cos\left(2p \arctan \frac{z}{z_R}\right) L_p^0\left(\frac{2\rho^2}{\omega(z)^2}\right) + L_p^0\left(\frac{2\rho^2}{\omega(z)^2}\right)^2\right], \quad (7)$$

where  $I_0 = 2P_0/\pi\omega_0^2$  is the intensity at the origin of the Gaussian beam. Figures 1(a) and 1(b) show the intensity as a function of the transverse coordinate  $x$  and the longitudinal coordinate  $z$ . The potential landscape in the  $x$ - $z$  plane is shown in Fig. 1(c) for the case  $p = 1$  and in Fig. 1(d) for the case  $p = 2$ . A dielectric particle with the appropriate refractive index placed at the origin would be trapped in the dark focus, since it would be repelled in all directions by the surrounding regions of higher electromagnetic intensity.

### B. Dimensions of the bottle

We can define the width  $W$  (height  $H$ ) of the bottle as the distance between the two intensity maxima surrounding the dark region along the  $x$  axis ( $z$  axis). These values can be found by solving

$$dI_p(x, 0, 0)/dx|_{x=W/2} = 0, \quad (8)$$

$$dI_p(z, 0, 0)/dz|_{z=H/2} = 0. \quad (9)$$

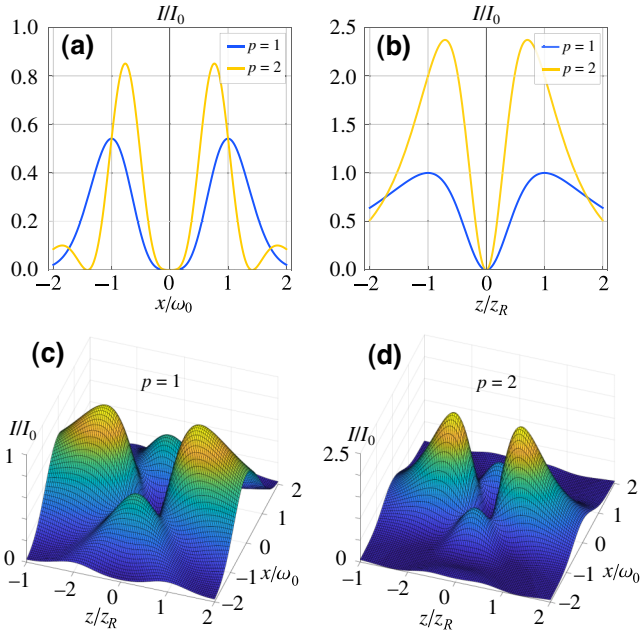


FIG. 1. The intensity in the (a) radial and (b) axial directions for bottle beams with  $p = 1$  and  $p = 2$ . The intensity landscape in the  $x$ - $z$  plane for bottle beams with (c)  $p = 1$  and (d)  $p = 2$ . Due to the normalization of  $x$ ,  $z$ , and  $I$ , these plots depend only on  $p$  and are independent of the remaining beam parameters.

The above equations admit analytical solutions for small  $p$ , yielding  $W = 2\omega_0, H = 2z_R$  for  $p = 1$  and  $W = 2\sqrt{2} - \sqrt{2}\omega_0, H = \sqrt{2}z_R$  for  $p = 2$ .

To gain insight into  $H$  and  $W$ , it is useful to make the change of variables  $\rho/\omega_0 \rightarrow \rho', z/z_R \rightarrow z'$  in the intensity given in Eq. (7). The function  $I_p(\rho', z')$  has no explicit dependence on any of the beam's parameters other than  $p$  and  $I_0$ , with its associated rescaled width  $W'$  and height  $H'$ . The prefactor  $I_0$  does not alter the distance between maxima along the  $x'$  and  $z'$  axes, meaning that  $W' = W'(p)$  and  $H' = H'(p)$  depend only on  $p$ . Going back to the original variables, we find that  $W = \omega_0 W'(p)$  and  $H = z_R H'(p)$ . From Eq. (6), we observe that the width of the bottle scales with  $\text{NA}^{-1}$  and the height scales with  $\text{NA}^{-2}$ . Hence an increase in NA causes the bottle to become smaller overall and compressed along the  $z$  direction.

### C. Radiation forces

When a Rayleigh particle is placed in an electromagnetic field, there are three forces that act on it [49]. The first, called the spin-curl force, is a result of polarization gradients [50] and can be disregarded in the case of uniform linear polarization in which we are interested. The second is called the scattering force and is proportional to the Poynting vector. Near the origin, the scattering force points in the direction of propagation of the beam. Finally, the gradient force is proportional to the gradient of the

potential energy of the particle under the influence of the electromagnetic field. From the intensity given by Eq. (7), the scattering force  $\vec{F}_p^{(\text{scat})}(\vec{r})$ , the gradient force  $\vec{F}_p^{(\text{grad})}(\vec{r})$ , and the optical potential  $V_p(\vec{r})$  acting on a trapped particle with radius  $R$  and refractive index  $n_p$  can be readily calculated using [48]

$$\vec{F}_p^{(\text{scat})}(\vec{r}) = \hat{z} \frac{128\pi^5 R^6}{3c\lambda_0^4} \left( \frac{m^2 - 1}{m^2 + 2} \right)^2 n_m^5 I_p(\vec{r}), \quad (10)$$

$$\vec{F}_p^{(\text{grad})}(\vec{r}) = \frac{2\pi n_m R^3}{c} \left( \frac{m^2 - 1}{m^2 + 2} \right) \nabla I_p(\vec{r}), \quad (11)$$

$$V_p(\vec{r}) = -\frac{2\pi n_m R^3}{c} \left( \frac{m^2 - 1}{m^2 + 2} \right) I_p(\vec{r}), \quad (12)$$

where  $m = n_p/n_m$  is the particle-medium refractive-index ratio. We are interested in situations in which the parameter  $m$  is smaller than 1, in such a way that the particle is repelled by light.

The forces acting on a spherical water droplet ( $n_p = 1.33$ ) with 70-nm radius trapped in oil ( $n_m = 1.46$ ) by a bottle beam ( $\lambda = 780$  nm,  $P_0 = 200$  mW for each beam in the superposition) focused by an objective lens (NA = 0.5) are displayed in Fig. 2. As expected, the gradient forces point to the origin. Note that the scattering force, which points along the propagation direction, is null at the equilibrium position. This is in strong contrast to standard Gaussian traps and presents an advantage, since the imbalance between scattering and gradient forces often poses challenges to optical trapping [51].

Another interesting feature of the bottle-beam trap is the flat bottom of the intensity well in the  $z = 0$  plane, seen in Fig. 1(a), and the approximate null derivative of the force along the radial direction at the origin. This can be understood by looking at the potential near the origin ( $\rho \ll \omega_0, z \ll z_R$ ). It can be approximated to fourth order as

$$\frac{V_p(\rho, z)}{V_0} \approx \underbrace{\frac{4p^2}{\omega_0^4} \rho^4}_{T_{\rho^4}} - \underbrace{\frac{8p^2(p+1)}{\omega_0^2 z_R^2} \rho^2 z^2}_{T_{\rho^2 z^2}} + \underbrace{\frac{4p^2}{z_R^2} z^2}_{T_{z^2}}, \quad (13)$$

where  $V_0 = [2\pi n_m R^3 (m^2 - 1)/c(m^2 + 2)]I_0$  and the term of order  $\mathcal{O}[(z/z_R)^4]$  has been neglected, since  $(z/z_R)^4 \ll (z/z_R)^2$  for  $z \ll z_R$ . At the plane  $z = 0$ , the potential scales with  $\rho^4$ . Therefore, the force scales with  $\rho^3$  and has vanishing first and second derivatives. For  $z \neq 0$ , Eq. (13) has a crossed term  $\rho^2 z^2$  that couples motion along the axial and radial directions. Because the scattering force is proportional to the intensity, it also has null derivatives at the equilibrium position and hence it vanishes for a particle placed at and near the origin.

Finally, the potential in the  $x$ - $z$  plane is displayed in Figs. 2(c) and 2(d) for the cases of  $p = 1$  and  $p = 2$ . As can

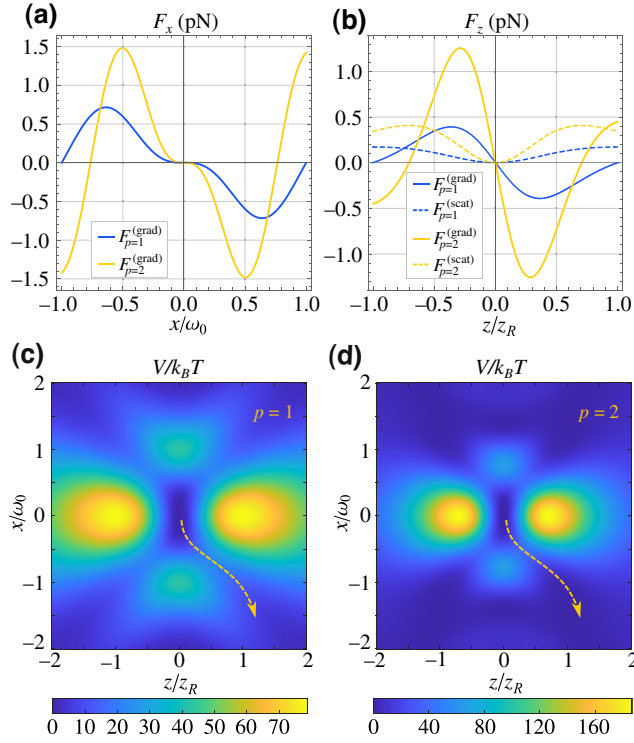


FIG. 2. The forces acting on a trapped sphere in the (a)  $x$  direction and (b)  $z$  direction for  $p = 1$  and  $p = 2$ . The solid lines are gradient forces, while the dashed lines are scattering forces. The potential landscape in the  $x$ - $z$  plane for a sphere trapped by a bottle beam with (c)  $p = 1$  and (d)  $p = 2$ . The parameters used for these plots are  $\text{NA} = 0.5$ ,  $R = 70$  nm,  $\lambda_0 = 780$  nm,  $n_m = 1.46$ ,  $n_p = 1.33$ ,  $P_0 = 200$  mW, and  $T = 300$  K.

be seen, a trapped particle does not need to go through the high-intensity peaks along the  $x$  or  $z$  axis in order to escape the trap. Smaller potential barriers have to be climbed if the particle undergoes paths such as the yellow dashed ones. We call the lowest potential energy needed for the particle to leave the trap  $V_{\min}$ . Because the potential scales with  $V_0$ , we have  $V_{\min} \propto V_0$ .

#### D. Decoupling approximation

The axial and radial movements can be decoupled if the coupling term in Eq. (13) is much smaller than the remaining terms. The conditions under which this assumption holds true can be found by estimating the magnitude of the displacements of the particle under the influence of the trap. Neglecting the cross term and considering thermal equilibrium, we may write

$$\langle \rho^4 \rangle = \frac{1}{Z_0} \int d^3\vec{r} \rho^4 \exp \left[ -\frac{4V_0 p^2}{k_B T} \left( \frac{\rho^4}{\omega_0^4} + \frac{z^2}{z_R^2} \right) \right], \quad (14)$$

$$\langle z^2 \rangle = \frac{1}{Z_0} \int d^3\vec{r} z^2 \exp \left[ -\frac{4V_0 p^2}{k_B T} \left( \frac{\rho^4}{\omega_0^4} + \frac{z^2}{z_R^2} \right) \right], \quad (15)$$

where  $k_B$  is the Boltzmann constant,  $T$  is the temperature, and  $Z_0$  is given by

$$Z_0 = \int d^3\vec{r} \exp \left[ -\frac{4V_0 p^2}{k_B T} \left( \frac{\rho^4}{\omega_0^4} + \frac{z^2}{z_R^2} \right) \right]. \quad (16)$$

From Eqs. (14)–(16), we find that

$$\sqrt[4]{\langle \rho^4 \rangle} = \sqrt[4]{\frac{\omega_0^4 k_B T}{8p^2 V_0}}, \quad (17)$$

$$\sqrt{\langle z^2 \rangle} = \sqrt{\frac{z_R^2 k_B T}{8p^2 V_0}}. \quad (18)$$

Although Eqs. (17) and (18) are derived by neglecting the cross term, they can be used to estimate the magnitude of the three different terms in Eq. (13). Through simple scaling, we are led to

$$\frac{T_{\rho^2 z^2}}{T_{\rho^4}} \sim \frac{T_{\rho^2 z^2}}{T_z} \sim \frac{1+p}{\sqrt{2}p} \left( \frac{V_0}{k_B T} \right)^{-1/2}. \quad (19)$$

Because  $V_{\min}/k_B T \gg 1$  is required for the particle to be confined in the presence of a thermal bath [48] and  $V_{\min} \propto V_0$ , fulfillment of the decoupling condition is associated with increased trap stability.

In the decoupling regime, the optical potential becomes

$$V_p(\rho, z) \approx \frac{k_\rho^{(3)}}{4} \rho^4 + \frac{k_z}{2} z^2, \quad (20)$$

with the constants  $k_\rho^{(3)}$  and  $k_z$  given by

$$k_\rho^{(3)} = \frac{64n_m P_0 R^3}{c} \left( \frac{\pi \text{NA}}{\lambda_0} \right)^6 \left( \frac{1-m^2}{2+m^2} \right) p^2, \quad (21)$$

$$k_z = \frac{32P_0 R^3 \lambda_0^2}{\pi^2 n_m c} \left( \frac{\pi \text{NA}}{\lambda_0} \right)^6 \left( \frac{1-m^2}{2+m^2} \right) p^2. \quad (22)$$

#### E. Trapped particle dynamics

To further evaluate the validity of the above estimates and approximations, it is useful to simulate the dynamics of a particle trapped by the potential of a bottle beam in its exact form, calculated from Eqs. (7) and (12). The equation of motion for a spherical particle under this condition is

$$M\ddot{\vec{r}}(t) = -\gamma\dot{\vec{r}}(t) - \nabla V(\vec{r}(t)) + \sqrt{2\gamma k_B T} \vec{W}(t), \quad (23)$$

where  $\eta$  is the viscosity of the medium,  $\gamma = 6\pi\eta R$  is the drag coefficient, and  $M$  is the mass of the particle. The environmental fluctuations are modeled using a

Gaussian, white, and isotropic stochastic process  $\vec{W}(t) = (W_x(t), W_y(t), W_z(t))$ , with zero mean and no correlations among different directions. We have that

$$\langle W_i(t)W_j(t') \rangle = \delta(t-t')\delta_{ij}, \quad (24)$$

where  $\delta(t-t')$  is the Dirac delta in the time domain.

For a sufficiently small particle, the inertial term  $M\ddot{\vec{r}}$  is negligible in comparison to the viscous term  $\gamma\dot{\vec{r}}$ . In this so-called *overdamped* regime, we can numerically integrate Eq. (23) using

$$\vec{r}(t + \Delta t) = \vec{r}(t) - \frac{\nabla V[\vec{r}(t)]}{\gamma} \Delta t + \sqrt{\frac{2k_B T \Delta t}{\gamma}} \vec{W}(t), \quad (25)$$

where  $\Delta t = \tau/n$  is the time interval between iterations,  $\tau$  is the total time of simulation, and  $n$  is the total number of iterations.

Numerical integration of the motion of a water droplet ( $n_p = 1.33$ ,  $R = 70\text{nm}$ ) trapped in oil ( $n_m = 1.46$ ) by a bottle beam ( $p = 1$ ,  $\lambda = 780\text{ nm}$ ) focused using an objective lens ( $\text{NA} = 0.5$ ) is performed for different trapping powers. Note that the total trapping power is twice as large as the power  $P_0$  of each beam (for details, see Appendix A).

The motion is simulated for a period of 10 s, using time steps of  $0.5\ \mu\text{s}$ . This results in  $20 \times 10^6$  position values for each trapping power. The values of  $\sqrt[4]{\langle x^4 \rangle}$  and  $\sqrt{\langle z^2 \rangle}$  obtained from this simulation of the exact potential and the curves predicted using the approximated potential in Eq. (20) together with Eqs. (14) and (15) are displayed in Fig. 3. The largest values of  $\sqrt[4]{\langle x^4 \rangle}/\omega_0$  and  $\sqrt{\langle z^2 \rangle}/z_R$  obtained are approximately 0.27 and 0.067, respectively. This justifies the fourth-order approximation leading to Eq. (13) for the entire simulated range of trapping powers.

Moreover, we can see from Fig. 3 that agreement between the simulated dynamics of the exact potential and the approximate potential of Eq. (20) increases with  $P_0$ . For  $P_0 > 1\text{ W}$ , the exact and approximate values differ by less than 3% and hence Eq. (20) can be considered a good approximation of the potential. This behavior is consistent with the previous estimate that the ratios  $T_{\rho^{2z^2}}/T_{\rho^4}$  and  $T_{\rho^{2z^2}}/T_{z^2}$  scale with  $V_0^{-1/2}$  and, hence, the larger the trapping power, the smaller the cross term in comparison to the remaining relevant terms.

This can be further verified in Fig. 4, where we plot the ratios

$$r_1 = \frac{\langle T_{\rho^{2z^2}} \rangle}{\langle T_{\rho^4} \rangle}, \quad r_2 = \frac{\langle T_{\rho^{2z^2}} \rangle}{\langle T_{z^2} \rangle} \quad (26)$$

obtained from the simulations. The decreasing behavior of  $r_1$  and  $r_2$  with respect to  $P_0$  confirms that increasing the

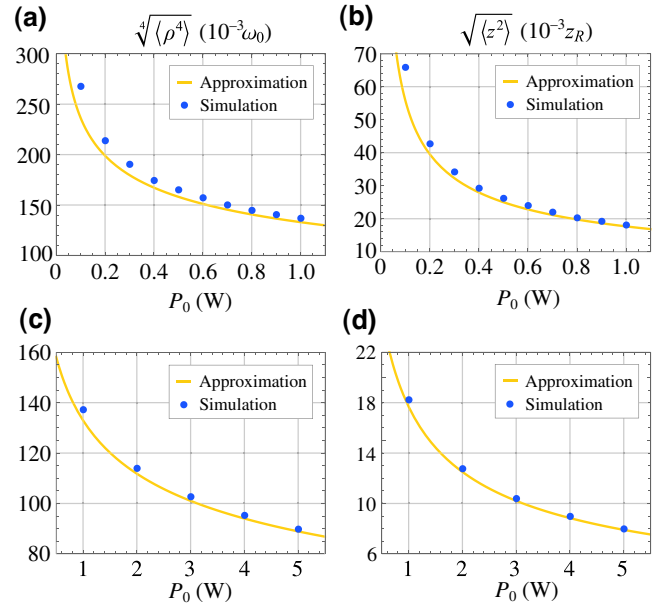


FIG. 3. A comparison between the values of (a),(c)  $\sqrt[4]{\langle \rho^4 \rangle}$  and of (b),(d)  $\sqrt{\langle z^2 \rangle}$  obtained from the approximated potential in Eq. (20) and from simulation of the motion of the particle subject to the exact potential in Eq. (12) for different laser powers. The motion is simulated during a period of 10 s, with time steps of  $0.5\ \mu\text{s}$ , using  $\text{NA} = 0.5$ ,  $R = 70\text{ nm}$ ,  $\lambda_0 = 780\text{ nm}$ ,  $n_m = 1.46$ ,  $n_p = 1.33$ ,  $T = 295\text{ K}$ , and  $p = 1$ .

trapping power is an effective way of decoupling the radial and axial directions.

Another consequence of the interplay between a radial quartic and a longitudinal quadratic potential is that the elongation of the trap can be adjusted by tuning the laser power. This is illustrated in Fig. 5, in which the positions of the trapped particle obtained from the numerical simulation are displayed in a scatter plot, for  $P_0 = 100\text{ mW}$  and  $P_0 = 5\text{ W}$ . As can be seen, the trap is appreciably

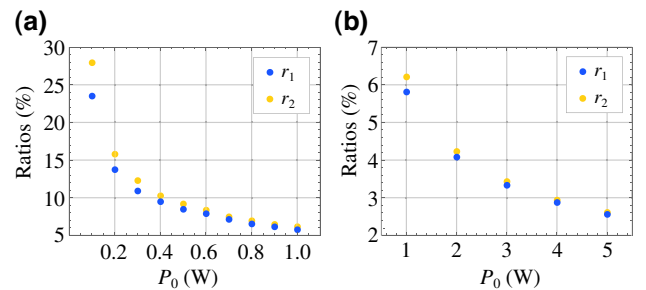


FIG. 4. The ratios  $r_1 = \langle T_{\rho^{2z^2}} \rangle / \langle T_{\rho^4} \rangle$  and  $r_2 = \langle T_{\rho^{2z^2}} \rangle / \langle T_{z^2} \rangle$  obtained by simulating the motion of a particle subject to the exact potential in Eq. (12) for different laser powers. The motion is simulated during a period of 10 s, with time steps of  $0.5\ \mu\text{s}$ , using  $\text{NA} = 0.5$ ,  $R = 70\text{ nm}$ ,  $\lambda_0 = 780\text{ nm}$ ,  $n_m = 1.46$ ,  $n_p = 1.33$ , and  $T = 295\text{ K}$ .

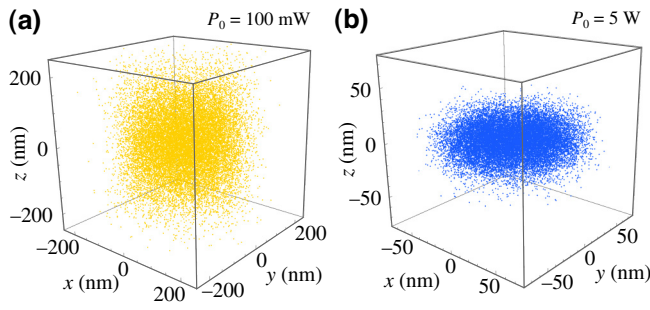


FIG. 5. The positions of the particle obtained by simulating the motion of a particle trapped by the exact potential in Eq. (12) for (a)  $P_0 = 100$  mW and (b)  $P_0 = 5$  W. The motion is simulated during a period of 10 s, with time steps of  $0.5 \mu\text{s}$ , using  $\text{NA} = 0.5$ ,  $R = 70$  nm,  $\lambda_0 = 780$  nm,  $n_m = 1.46$ ,  $n_p = 1.33$ ,  $T = 295$  K, and  $p = 1$ . To allow better visualization, the  $20 \times 10^6$  positions generated by the simulation are divided in 1000 sets and only the first value of each set is displayed in the figure.

compressed along the  $z$  axis in the latter case but not in the former. This feature is not present in regular Gaussian tweezers: since the potential is quadratic along the three axes, the expected values of the displacement along all axes scale equally with  $\sqrt{P}$ .

We note that this compression is different from that caused by an increase in numerical aperture, mentioned previously. In that case, we have a compression of the overall shape of the intensity landscape along the  $z$  axis, which happens in the case of a Gaussian beam due to the scaling of  $\omega_0$  with  $\text{NA}^{-1}$  and of  $z_R$  with  $\text{NA}^{-2}$ . In contrast, an increase in the trapping power of a bottle beam compresses the region visited by the particle over time.

In summary, we conclude that in the dipole regime given in Eq. (13) is a good approximation for the optical potential generated by a bottle beam for a wide range of trapping powers, as it only relies on  $\rho^4/\omega_0^4 \ll 1$  and  $z^4/z_R^4 \ll 1$ . On the other hand, decoupling of the radial and axial motions only occurs for high trapping powers that make the cross term in Eq. (13) negligible. This allows approximation of the potential by Eq. (20). Furthermore, increasing the trapping power causes squashing along the axial direction of the accessible region for a trapped particle.

### F. Decoupling by addition of an extra mode

High trapping powers are only necessary if one wishes to decouple the radial and axial dependencies of the trapping potential but when considering power-sensitive samples, such as biological ones, this is not viable. An alternative, which is valid independent of the trapping power, is to add an extra Laguerre-Gauss mode with  $\ell_2 = 0$  and  $p_2 \neq 0$  to the superposition. Consider the intensity  $I(\rho, z)$  of the following superposition:

$$E(\rho, z) = E_{0,0}^{\text{LG}}(\rho, z) + \alpha_1 E_{0,1}^{\text{LG}}(\rho, z) + \alpha_2 E_{0,p_2}^{\text{LG}}(\rho, z), \quad (27)$$

where  $\alpha_{j=1,2}$  are complex amplitudes. The condition to have a bottle beam is that  $I(\rho, z)$  vanishes at the focus. The light intensity at the beam focus is proportional to

$$I(\mathbf{0}) = \mathcal{N}^2 |1 + \alpha_1 + \alpha_2|^2, \quad (28)$$

where  $\mathcal{N} = \sqrt{4P_0/c\epsilon\pi\omega_0^2}$ .

With the appropriate approximations (for details, see Appendix B) and the bottle-beam condition in Eq. (28), we obtain the approximate intensity  $I(\rho, z)$ :

$$\mathcal{N}^2 \left[ 4|B|^2 \left( \frac{z^2}{z_R^2} + \frac{\rho^4}{w_0^4} \right) - 8[|B|^2 + \text{Re}(AB^*)] \frac{z^2 \rho^2}{z_R^2 w_0^2} \right], \quad (29)$$

where  $A = \alpha_1 + \alpha_2 p_2^2$  and  $B = \alpha_1 + \alpha_2 p_2$ . Decoupling of the radial and longitudinal motions can then be achieved by choosing  $\alpha_1$  and  $\alpha_2$  such that

$$|B|^2 + \text{Re}(AB^*) = 0 \quad (B \neq 0). \quad (30)$$

As an example, let us choose  $p_2 = 2$ . A decoupled bottle beam can be obtained by the superposition coefficients

$$\alpha_1 = -3/2, \quad (31)$$

$$\alpha_2 = 1/2. \quad (32)$$

Using Eq. (12), we can find the decoupled potential near the origin ( $\rho \ll \omega_0$ ,  $z \ll z_R$ ). This is given to fourth order by

$$V(\rho, z) \approx V_0 \left( \frac{z^2}{z_R^2} + \frac{\rho^4}{w_0^4} \right), \quad (33)$$

which has the same form as Eq. (20). Moreover, this solution yields the maximum trap stiffness of the three-mode configuration, as demonstrated in Appendix B.

### G. Calibration of the optical trap

In laboratory conditions, quantitative measurements using optical tweezers rely on knowledge of the trap's parameters. In the case of a bottle trap defined by the potential in Eq. (20), the relevant parameters are  $k_z$  and  $k_\rho^{(3)}$ . To operate the tweezer properly, these must be found by measuring the position of the particle during a finite interval of time. This yields a time series  $\vec{r}_m(t) = \vec{\beta} \cdot \vec{r}(t)$ , where  $\vec{\beta} = (\beta_x, \beta_y, \beta_z)$  are conversion factors between position displacements and the measured quantity, such as the voltage in a position-sensitive detector. For simplicity, we assume  $\beta_x = \beta_y = \beta_\rho$ .

For a bottle-beam trap, the position of the particle can be measured using a high-speed camera [52] or, alternatively, by applying a purely Gaussian beam at a different wavelength with respect to the bottle beam. The second beam can be focused onto the trapped particle by the same objective lens used for the bottle and collected by a second objective lens after separation from the trapping beam by a dichroic mirror. The collected Gaussian light can then be directed onto a quadrant photodetector, where the usual forward-scattering measurement is performed [53]. The Gaussian power should be kept significantly weaker than the bottle power to avoid disturbances due to the presence of this auxiliary Gaussian trap.

In the decoupled regime, movement along the  $z$  axis is independent of movement along the  $x$  and  $y$  axes and the equations of motion can be separated from Eq. (23), yielding

$$-\gamma\dot{z}(t) - k_z z(t) + \sqrt{2\gamma k_B T} W_z(t) = 0, \quad (34)$$

where, once again, we assume that the inertial term is negligible. The constants  $k_z$  and  $\beta_z$  can be found using the standard procedure of analyzing the autocorrelation function [54] or the power spectral density [55,56] of the measured axial displacements  $z_m(t) = \beta_z z(t)$ .

To find the remaining relevant constants, we need two independent equations. Using Eqs. (14) and (21), we may write

$$\frac{k_\rho^{(3)} \langle \rho^4 \rangle}{4} = \frac{k_B T}{2} \rightarrow \langle \rho^4 \rangle = \frac{2k_B T}{k_\rho^{(3)}}, \quad (35)$$

leading to the relation

$$\langle \rho_m^4 \rangle = \beta_\rho^4 \frac{2k_B T}{k_\rho^{(3)}}. \quad (36)$$

A second equation can be obtained from an active method of calibration consisting of moving the sample in which the particle is immersed with a known velocity  $\vec{v}_{\text{drag}}$  [57,58]. This will cause a constant drag force  $\gamma \vec{v}_{\text{drag}}$  on the particle and, taking  $\vec{v}_{\text{drag}} = v_{\text{drag}} \hat{x}$  as the equation of motion along the  $x$  axis, becomes

$$\gamma v_{\text{drag}} - \gamma \dot{x}(t) - k_\rho^{(3)} x(t) \rho(t)^2 + W_x(t) = 0. \quad (37)$$

After a transient time, the particle reaches an equilibrium position displaced with respect to the trap's center, with  $\langle \dot{x}(t) \rangle = 0$ . Taking the time average of Eq. (37) leads to

$$\gamma v_{\text{drag}} - k_\rho^{(3)} \langle x(t) \rho(t)^2 \rangle = 0, \quad (38)$$

which can then be used to obtain the relation

$$\langle x_m(t) \rho_m(t)^2 \rangle = \beta_\rho^3 \frac{\gamma v_{\text{drag}}}{k_\rho^{(3)}}. \quad (39)$$

Equations (36) and (39) together with the standard auto-correlation procedure for the axial motion enables the measurement of the four parameters  $\beta_\rho$ ,  $\beta_z$ ,  $k_\rho^{(3)}$ , and  $k_z$  in the decoupled approximation.

### III. INTERMEDIATE REGIME

In many applications, it is desirable to trap “large” micron-sized particles such as living cells [59,60]. This presents an intermediate regime, in which the size of the particle is comparable to the wavelength of the trapping beam ( $R \approx \lambda$ ) and neither the dipole ( $R \ll \lambda$ ) nor geometric optics ( $R \gg \lambda$ ) approximations can be used to calculate the optical forces. Instead, the forces must be calculated using the so-called generalized Lorenz-Mie theory (GLMT), for which we provide a brief introduction following the treatment presented in Ref. [44].

#### A. Generalized Lorenz-Mie theory

Regardless of the size of the trapped particle, optical forces arise from the exchange of momentum with the photons from the trapping beam. Therefore, the total momentum transferred to the particle is equal to the change in momentum of the scattered electromagnetic field. It is then useful to separate the field into incoming  $\vec{E}_{\text{in}}$  and outgoing  $\vec{E}_{\text{out}}$  parts, which in turn can be expanded in terms of vector spherical wave functions (VSWFs) defined in a coordinate system centered at the center of the particle:

$$\vec{E}_{\text{in}} = \sum_{i=1}^{\infty} \sum_{j=-i}^i a_{ij} \vec{M}_{ij}^{(2)}(k\vec{r}) + b_{ij} \vec{N}_{ij}^{(2)}(k\vec{r}), \quad (40)$$

$$\vec{E}_{\text{out}} = \sum_{i=1}^{\infty} \sum_{j=-i}^i p_{ij} \vec{M}_{ij}^{(1)}(k\vec{r}) + q_{ij} \vec{N}_{ij}^{(1)}(k\vec{r}), \quad (41)$$

where  $\vec{M}_{ij}^{(1)}$ ,  $\vec{N}_{ij}^{(1)}$ ,  $\vec{M}_{ij}^{(2)}$ , and  $\vec{N}_{ij}^{(2)}$  are the VSWFs, with superscript index “(1)” denoting outward-propagating transverse-electric and transverse-magnetic multipole fields and “(2)” denoting the corresponding inward-propagating multipole fields.

The coefficients  $a_{ij}$  and  $b_{ij}$  can be calculated for the incident beam and used to obtain the  $p_{ij}$  and  $q_{ij}$  coefficients for the scattered field by a simple matrix-vector multiplication between the so-called  $T$  matrix and a vector containing the coefficients of the incoming field. The  $T$  matrix depends only on the characteristics of the trapped particle, which we assume to be spherical. Once the coefficients are calculated, the force along the axial direction  $z$

is given by

$$F_z = \frac{2n_{md}P}{cS} \sum_{i=1}^{\infty} \sum_{j=-1}^i \frac{j}{i(i+1)} \text{Re}(a_{ij}^* b_{ij} - p_{ij}^* q_{ij}) - \frac{1}{i+1} \sqrt{\frac{i(i+2)(i-j+1)(i+j+1)}{(2i+1)(2i+3)}} \times \text{Re}(a_{ij} a_{i+1,j}^* + b_{ij} b_{i+1,j}^* - p_{ij} p_{i+1,j}^* - q_{ij} q_{i+1,j}^*), \quad (42)$$

with

$$S = \sum_{i=1}^{\infty} \sum_{j=-i}^i (|a_{ij}|^2 + |b_{ij}|^2). \quad (43)$$

The forces acting along the  $x$  and  $y$  axes have more complicated formulas and can be more easily calculated by rotating the coordinate system. The effect of displacing the particle can be taken into account by appropriate translations of the trapping beam.

Due to the linearity of Eqs. (40) and (41), the expansion coefficients for a superposition of different beams can be found by adding the expansion coefficients for each beam and subsequently substituting in Eq. (42) to calculate the resultant force. To perform these computations for the case

of a particle trapped by a bottle beam, we use the latest version of the toolbox developed in Ref. [44].

## B. Optical forces from a bottle beam

The optical forces generated by the superposition of a Gaussian beam and a Laguerre-Gauss beam with  $\ell = 0, p \neq 0$  are obtained with the aid of Refs. [44,61]. For simplicity, we focus on the  $p = 1$  case and a particle of refractive index  $n_p = 1.33$  trapped by a 500-mW beam at  $\lambda_0 = 780$  nm immersed in oil of refractive index  $n_m = 1.46$ .

Figure 6 shows the plots of  $F_z(z)$  and  $F_x(x)$  divided by the mass of the particle for four different NAs and four different particle radii. The force in the  $z$  direction is evaluated for  $x = y = 0$ , while  $F_x(x)$  is evaluated at  $y = 0, z = z_{\text{eq}}$ , where  $z_{\text{eq}}$  is the equilibrium coordinate along the  $z$  direction, i.e.,

$$\begin{cases} F_z(z_{\text{eq}}) = 0, \\ dF_z(z)/dz|_{z=z_{\text{eq}}} < 0. \end{cases} \quad (44)$$

When no equilibrium position exists,  $F_x(x)$  is evaluated at  $z = 0$ .

Some general trends can be extracted from Fig. 6. First, we note that if the sphere is small ( $R = \lambda_0/4$ ) and the numerical aperture is low ( $\text{NA} = 0.3, 0.5$ ), the force in

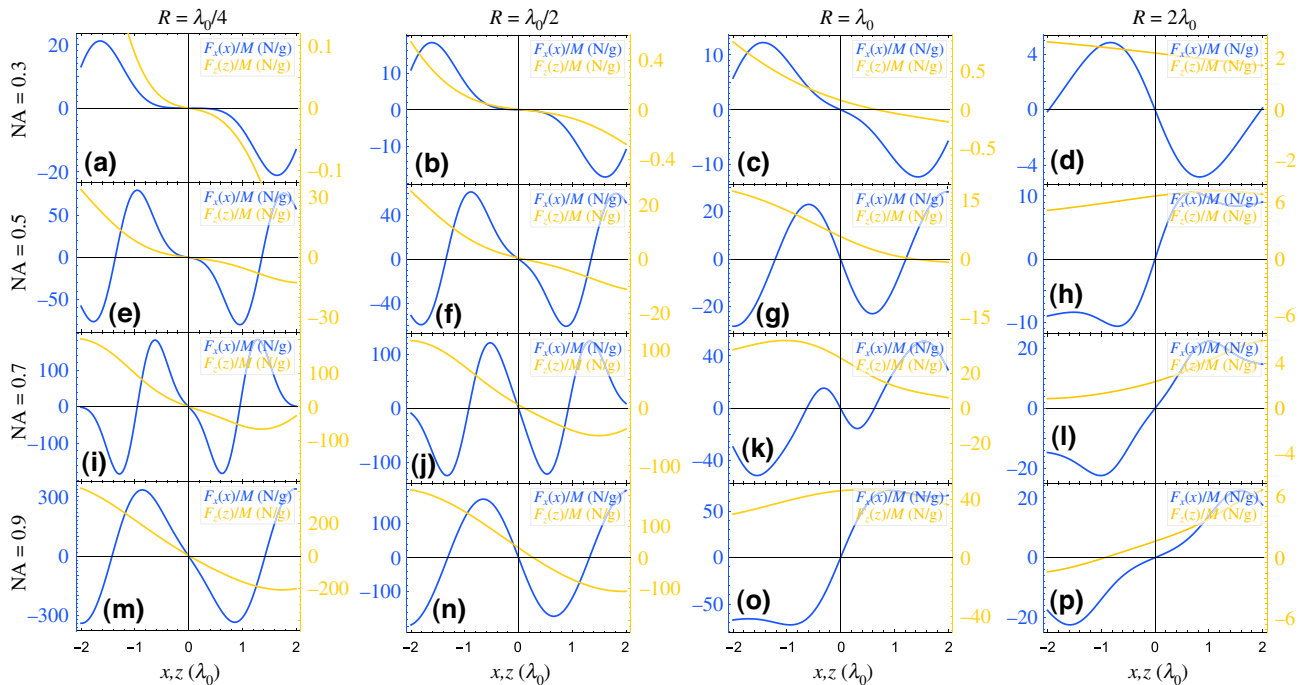


FIG. 6. The optical forces acting on a particle trapped by a bottle beam in the intermediate regime ( $R \approx \lambda$ ). The force in the axial direction [ $F_z(z)$ ] is calculated for  $x = y = 0$ , while the force in the radial direction [ $F_x(x)$ ] is calculated for  $y = 0$  and  $z = z_{\text{eq}}$ . If no axial-equilibrium position is found,  $F_x(x)$  is evaluated at  $z = 0$ . The radius of the particle is constant within each column, while the numerical aperture is constant within each line. The forces are normalized by the mass of the particle. The other parameters used in simulation are  $n_p = 1.33$ ,  $n_m = 1.46$ ,  $\lambda_0 = 780$  nm,  $P = 500$  mW, density of the particle =  $10^3$  kg/m<sup>3</sup>, and  $p = 1$ .



the  $x$  direction resembles that calculated using the dipole approximation, i.e., it appears to scale with  $x^3$  around the origin. As  $R$  or NA increases, this cubic dependence starts to vanish, giving way to a linear dependence.

We can also note that the size of the particle and the numerical aperture play important roles in the existence of an equilibrium position in the axial direction, with a large radius  $R$  and a large NA being detrimental to trap stability along the  $z$  axis. For NA = 0.7, for instance, there is an equilibrium position if  $R = \lambda_0/4$  or  $R = \lambda_0/2$  but not if  $R$  is larger. For a fixed  $R = \lambda_0$ ,  $z_{\text{eq}}$  does not exist for NA > 0.5. This is rather different from what happens in the regular Gaussian trap, in which an increase in NA is associated with an increase in trap stability [48].

### C. Limitations of trapping in a dark focus

The trends observed in Fig. 6 can be understood qualitatively by recalling that a bottle beam is a dark region surrounded by a finite bright-light boundary. If the particle is small enough, it will fit inside the dark region and will be repelled by the boundary. In contrast, if the particle is too big, it does not fit inside the bottle and the dark focus becomes irrelevant, with the beam effectively pushing the particle away.

This can be seen for in Figs. 6(e)–6(h): the dimensions of the bottle when NA = 0.5 are  $W = 0.99 \mu\text{m}$  and  $H = 2.9 \mu\text{m}$ . Therefore, a particle of diameter  $0.5\lambda$  fits entirely inside the bottle and is free within the dark region, causing the force in the  $x$  direction to have a vanishing derivative near the origin. When  $R = \lambda_0$ , the particle no longer fits in the dark focus and the influence of light gives a linear scaling to  $F_x(x)$  around the equilibrium position. When  $R = 2\lambda_0$ , the particle has an increased overlap with the light intensity and no longer encounters an equilibrium position.

Similarly, an increase in the numerical aperture causes the dark focus to shrink. When the bottle becomes too small to contain the particle, the situation in the third column of Fig. 6 is reached and the forces eventually turn into nonrestorative ones.

This qualitative reasoning is confirmed in Fig. 7, in which the equilibrium position  $z_{\text{eq}}$  and the derivative along the  $x$  direction near the equilibrium position are displayed as a function of the radius of the particle and the numerical aperture. Two main regions can be identified in each of the plots. The first of them is the region for which  $z_{\text{eq}}$  is not found in the range of inspected axial coordinates  $-6\lambda_0 < z < 6\lambda_0$ . In this region, the derivative along the  $x$  axis is not evaluated. The remaining areas are those in which an axial-equilibrium position exists.

Because we wish to trap the particle in the dark focus, we need to avoid equilibrium situations such as the ones described in Ref. [62] in the context of vortex beams, in

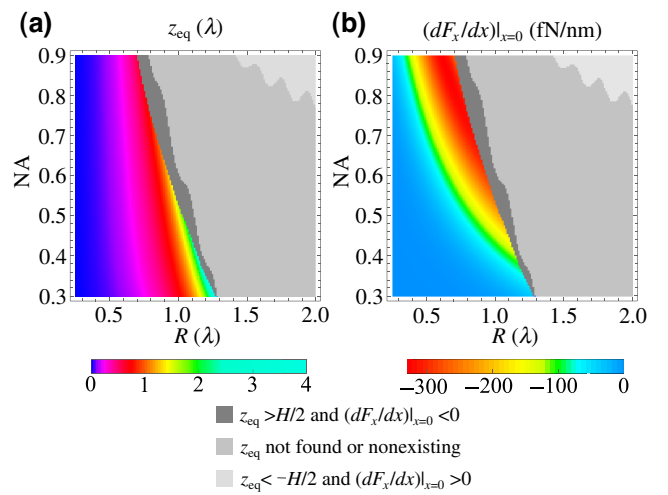


FIG. 7. Intermediate-regime simulations for different values of NA and  $R$ . (a) The axial-equilibrium coordinate and (b) the first derivative of the force in the radial direction: medium gray, no equilibrium position is found in the inspected range ( $-6\lambda_0 < z < 6\lambda_0$ ); light (dark) gray, an equilibrium position is found outside the bottle, at  $z_{\text{eq}} < -H/2$  ( $z_{\text{eq}} > H/2$ ), and the force is nonrestorative (restorative) along the radial direction. The regions in different colors are the ones in which trapping inside the bottle is possible. The parameters used in the simulation are  $\lambda_0 = 780 \text{ nm}$ ,  $P = 500 \text{ mW}$ ,  $n_m = 1.46$ ,  $n_p = 1.33$ , and  $p = 1$ .

which the scattering force is balanced by the repelling gradient force before the focus. To exclude trapping positions outside the bottle, the regions in which  $z_{\text{eq}} > H/2$  are displayed in dark gray and the regions in which  $z_{\text{eq}} < -H/2$  are displayed in light gray. In the latter case, the derivative of the radial force is found to be positive and hence nonrestorative, while in the former this derivative is found to be negative. The colored region, then, is the region for which stable trapping inside the bottle is possible.

We can then conclude that for a given  $R$ , there is a maximum numerical aperture that can be used to form a stable trap. Conversely, for a given NA, there is a limit on the size of the particles that can be trapped. Figure 8(a) shows how this limit varies for different refractive indices of the medium and a fixed N = 0.5. The curves are chopped when  $z_{\text{eq}}$  becomes larger than  $H/2$  and we can clearly see that the closer the refractive index gets to that of the particle, the larger is the radius of the particle that can be trapped. Figure 8 confirms that the radial force is restorative for the entire range of  $R$  and  $n_m$  that we consider. It also shows that while decreasing  $n_m$  can help to trap larger particles, it also diminishes the force experienced by the particle and hence plays an important role in the trap's stability.

### D. Trapping living organisms in the dark

The bottle-beam trap finds promising applications in biology. For instance, it has been reported that organelles

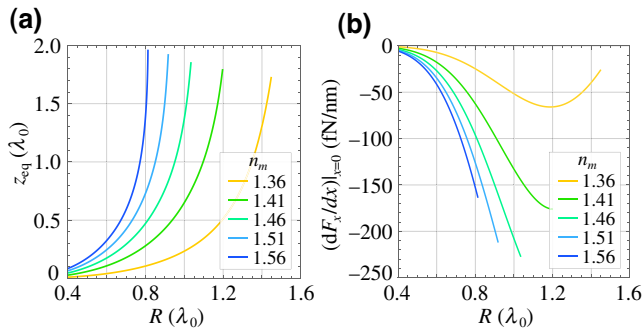


FIG. 8. Intermediate-regime simulations for different values of  $n_m$ . (a) The axial-equilibrium coordinate and (b) the first derivative of the force in the radial direction as a function of the radius of the particle. Points for which  $z_{\text{eq}} > H/2$  are not displayed. The parameters used in the simulation are  $\lambda_0 = 780$  nm,  $P = 500$  mW,  $n_m = 1.46$ ,  $n_p = 1.33$ , and  $p = 1$ .

with a refractive index lower than their surroundings are repelled from standard Gaussian optical tweezers [63]. The bottle beam could then be used to manipulate such organelles within a cell.

Similarly, a dark optical trap could also be employed to trap living organisms without excessive laser damage in the cell by an appropriate choice of a surrounding medium. Iodixanol, with its high water solubility, has been reported as a nontoxic medium for different organisms, in which the refractive index can be linearly tuned in the visible to near-IR range from approximately 1.33 to approximately 1.40 by changing the concentration [64]. Assuming a mean refractive index for a living cell to be within the range from approximately 1.36 to approximately 1.39 [65,66], it is expected that stable trapping in a dark focus can be attained.

*Mycoplasma* are known to be among the smallest living organisms and perhaps the simplest cells [67]. With radii of around  $0.3 \mu\text{m}$ , these organisms lack a cell wall [68], being protected from the surrounding environment solely by their cellular membrane. This may present interesting mechanical and elastic properties that could be probed with the bottle beam. We propose investigating the trapping of *Mycoplasma* cells immersed in a nontoxic mixture of refractive index 1.40. Iodixanol presents a possible such medium but further empirical tests must be carried out to fully determine how it affects living *Mycoplasma* cells. Figure 9 shows the simulated forces acting on a trapped *Mycoplasma* when the parameters shown in Table I are used. As can be seen, forces along radial and axial directions are restorative and should provide stable trapping inside the bottle.

It is known that direct incidence of focused laser light onto living cells can affect their division and growth [63]. As an interesting application of the bottle beam, one could

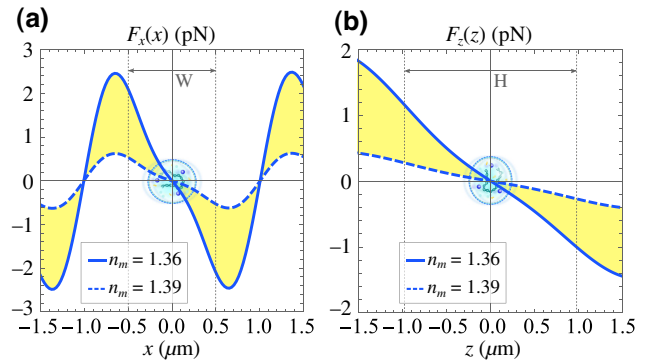


FIG. 9. The forces acting on a trapped *Mycoplasma* cell, shown here centered at the origin for size comparison, (a) along the  $x$  direction as a function of the radial displacement and (b) along the  $z$  direction as a function of the axial displacement. The solid and the dashed curves correspond to a medium's refractive index of 1.36 and 1.39, respectively, while the yellow area corresponds to  $1.36 \leq n_m \leq 1.39$ . The other parameters used in the simulation are displayed in Table I.

observe the process of cell division without directly sending a focused beam onto the trapped particle. The following experiment could be performed: at each round of measurement, a cell undergoing division is trapped in the dark focus by a given laser power and the complete cycle of the division process is observed. A trapped dividing cell will occupy an increasing volume and unavoidably encounter the boundary of the dark region, where the trapping beam will impose a pressure against the volume expansion. By increasing the laser power used in each round, one can look for the threshold power for which cell division is precluded. With the proper tweezer calibration presented in the previous section, the threshold power provides information on the forces acting during the process of cell division.

As for the trapping beam, we note that the desired superposition can be created using a SLM, a versatile tool for shaping arbitrary amplitude and phase distributions without the need for combining aligned multiple beams. For the purpose of the present work, controlled preparation of a desired superposition of Laguerre-Gaussian modes can be

TABLE I. Proposed values for trapping a *Mycoplasma* cell using a bottle beam.

Parameter	Units	Value
Particle refractive index, $n_p$	...	1.36–1.39
Medium refractive index, $n_m$	...	1.40
Particle radius, $R$	$\mu\text{m}$	0.3
Laser wavelength, $\lambda_0$	nm	1064
Numerical aperture, NA	...	0.7
Laser power	mW	500
Index, $p$	...	1

efficiently implemented, as recently demonstrated in Ref. [35]. For the moderate NA of 0.7—much smaller than the usual value of 1.3 used when trapping particles in liquid media—we do not expect aberrations to pose a serious challenge for optical trapping with the bottle beam.

#### IV. CONCLUSIONS

We theoretically analyze the optical forces acting on a particle of lower refractive index than its surrounding medium trapped in the dark focus of a bottle beam generated by the superposition of a Gaussian beam and a Laguerre-Gauss beam with  $\ell = 0$  and  $p \neq 0$ . Because the size of trapped particles commonly ranges from tens of nanometers [42] to several microns [43], we analyze such forces both for particles much smaller than and with dimensions comparable to the wavelength of the trapping beam.

In the case of small particles, the dipole approximation is applied, resulting in a number of distinguishing features of the investigated trap. Scattering is found to be null at the focus of the beam, eliminating imbalance between gradient and scattering forces [51]. The optical potential, on the other hand, couples the motion along the radial and axial directions. It is shown that these can be decoupled by using a sufficiently high trapping power. The approximated decoupled potential turns out to be quartic and quadratic in the radial and axial directions, respectively. To test the validity of the approximated potential, the motion of a particle trapped by the exact potential in a viscous medium is simulated and the results are compared with those expected from the approximation as a function of the laser power. We also show that by superposing a third mode, motion along the axial and radial directions can be decoupled independently of the trap power. To guide future experimental realizations, a calibration method is proposed.

In the case of larger objects, for which the dipole approximation is not valid, the tools developed in Refs. [44,61] are used to calculate the optical forces. Equilibrium positions after the focus are found, indicating a trapping regime different from that described in Ref. [62]. The interplay between the numerical aperture and the radius of the sphere is explored and leads to the conclusion that there is an upper bound for both of these quantities when using bottle beams for optical trapping. These limitations are interpreted in terms of the size of the optical bottle in comparison to the size of the particle and are found to be eased by choosing a medium with a refractive index close to that of the particle.

Finally, the findings obtained through exploration of the intermediate regime lead to an experimental proposal to trap a living organism using the bottle beam. Considering refractive-index values reported in the literature, it is expected that trapping of small cells such as *Mycoplasma* immersed in a nontoxic high-refractive-index medium in

a dark focus is within reach. This could be applied to situations in which focusing a high laser power onto the scrutinized cell is detrimental [47], as in the case of cellular division [63].

As a final remark, we note that the present analysis could be applied to other types of bottle beams and structured beams in general. This would be specially interesting for applications dealing with micron-sized objects, since many works deal only with the case of Rayleigh particles [21–23,25,26]. Additionally, it would be interesting to explore how the dark focus affects the transfer of angular momentum between the trapping beam and the trapped particle when a superposition of circularly polarized beams or beams possessing angular momentum is used.

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#### APPENDIX A: TOTAL POWER OF A BOTTLE BEAM

Throughout Sec. II, we use the power  $P_0$  of each beam in the superposition as a measure of the trapping power. To find the exact relation between  $P_0$  and the total power of the beam, we need to integrate Eq. (7) along some plane orthogonal to the propagation of the beam. Choosing the plane  $z = 0$ ,

$$\begin{aligned}
 P &= \int_0^\infty d\rho \int_0^{2\pi} (d\theta\rho) I_0 e^{-2\rho^2/\omega_0^2} \\
 &\quad \times \left[ 1 - 2L_p^0 \left( \frac{2\rho^2}{\omega_0^2} \right) + L_p^0 \left( \frac{2\rho^2}{\omega_0^2} \right)^2 \right] \\
 &= 2\pi I_0 \int_0^\infty \frac{\omega_0^2 du}{4} e^{-u} [1 - 2L_p^0(u) + L_p^0(u)^2] \\
 &= P_0 \int_0^\infty du e^{-u} [1 - 2L_p^0(u) + L_p^0(u)^2]. \quad (\text{A1})
 \end{aligned}$$

The Laguerre-Polynomials satisfy

$$\int_0^\infty x^\ell e^{-x} L_p^{|\ell|}(x) L_q^{|\ell|}(x) = \frac{(p+\ell)!}{p!} \delta_{p,q}, \quad (\text{A2})$$

which implies that

$$\int_0^\infty du e^{-u} = \int_0^\infty du e^{-u} L_0^0(u) L_0^0(u) = 1, \quad (\text{A3})$$

$$\int_0^\infty du e^{-u} L_p^0(u) = \int_0^\infty du e^{-u} L_0^0(u) L_p^0(u) = 0, \quad (\text{A4})$$

$$\int_0^\infty du e^{-u} L_p^0(u)^2 = \int_0^\infty du e^{-u} L_p^0(u) L_p^0(u) = 1. \quad (\text{A5})$$

Finally, substituting Eqs. (A3)–(A5) into Eq. (A1), we find that

$$P = 2P_0. \quad (\text{A6})$$

## APPENDIX B: THE DECOUPLING MODE

In this appendix, we derive the conditions that must be fulfilled by a three-mode superposition in order to provide a decoupled potential for the trapped particles, while keeping the bottle-beam structure. Let us consider the superposition

$$E(\rho, z) = E_{0,0}^{\text{LG}}(\rho, z) + \alpha_1 E_{0,p_1}^{\text{LG}}(\rho, z) + \alpha_2 E_{0,p_2}^{\text{LG}}(\rho, z). \quad (\text{B1})$$

We want to obtain a relationship between the complex coefficients  $\alpha_1$  and  $\alpha_2$  and the radial orders  $p_1$  and  $p_2$  that achieves the desired decoupling and bottle-beam profile. The LG modes with zero orbital angular momentum are given by

$$E_{0,p}^{\text{LG}}(\bar{\rho}, \bar{z}) = \frac{\mathcal{N}}{\sqrt{1+\bar{z}^2}} e^{-\frac{\bar{\rho}^2}{2}} L_p^0(\bar{\rho}^2) \left( \frac{1-i\bar{z}}{\sqrt{1+\bar{z}^2}} \right)^{2p+1} \times \exp \left[ ikz + ik \frac{\rho^2}{2R(z)} \right], \quad (\text{B2})$$

where we define  $\mathcal{N} = \sqrt{4P_0/c\epsilon\pi\omega_0^2}$ ,  $\bar{\rho} = \sqrt{2}\rho/w(z)$ , and  $\bar{z} = z/z_R$  and the last term is the Gouy phase.

The trapping potential is proportional to the light-intensity distribution and, therefore, to the square modulus of the electric field:

$$I(\bar{\rho}, \bar{z}) = \frac{I_0}{1+\bar{z}^2} e^{-\bar{\rho}^2} \left| 1 + \alpha_1 L_{p_1}^0(\bar{\rho}^2) \left( \frac{1-i\bar{z}}{\sqrt{1+\bar{z}^2}} \right)^{2p_1} + \alpha_2 L_{p_2}^0(\bar{\rho}^2) \left( \frac{1-i\bar{z}}{\sqrt{1+\bar{z}^2}} \right)^{2p_2} \right|^2. \quad (\text{B3})$$

We seek an approximate expression for the trapping potential around the beam focus, which can be obtained from a

power-series expansion around this point. The bottle-beam condition requires that the light intensity vanishes at the focus. Note that  $L_p^0(0) = 1$ , so the light intensity at the beam focus is proportional to

$$I(\mathbf{0}) = I_0 |1 + \alpha_1 + \alpha_2|^2, \quad (\text{B4})$$

which implies that

$$|1 + \alpha_1 + \alpha_2|^2 = 0. \quad (\text{B5})$$

This condition cancels out the zero-order contribution to the power-series expansion. We keep terms up to  $\bar{\rho}^4$  and  $\bar{z}^2$ , which are the first nonvanishing contributions to the power series. Since the zero-order term vanishes, it will be easier to first expand the expression inside the square modulus in Eq. (B3) and keep terms up to  $\bar{\rho}^2$  and  $\bar{z}^2$ . The following approximations are assumed:

$$e^{-\bar{\rho}^2} \approx 1 - \bar{\rho}^2, \quad (\text{B6})$$

$$L_p^0(\bar{\rho}^2) \approx 1 - p\bar{\rho}^2, \quad (\text{B7})$$

$$\left( \frac{1-i\bar{z}}{\sqrt{1+\bar{z}^2}} \right)^{2p} \approx 1 - 2ip\bar{z} - 2p^2\bar{z}^2, \quad (\text{B8})$$

$$\frac{1}{1+\bar{z}^2} \approx 1 - \bar{z}^2. \quad (\text{B9})$$

Applying the approximations above together with the bottle-beam condition (B5), we find the following approximate expression for the trapping intensity:

$$I(\bar{\rho}, \bar{z}) \approx I_0 (1 - \bar{\rho}^2) |2A\bar{z}(\bar{z} - i\bar{\rho}^2) + B(\bar{\rho}^2 + 2i\bar{z})|^2 \approx I_0 [ |B|^2 (4\bar{z}^2 + \bar{\rho}^4) - 4(|B|^2 + \text{Re}(AB^*)) \bar{\rho}^2 \bar{z}^2 ] \approx I_0 \left[ 4|B|^2 \left( \frac{z^2}{z_R^2} + \frac{\rho^4}{w_0^4} \right) - 8[|B|^2 + \text{Re}(AB^*)] \frac{z^2 \rho^2}{z_R^2 w_0^2} \right],$$

where we define

$$A = \alpha_1 p_1^2 + \alpha_2 p_2^2, \quad (\text{B10})$$

$$B = \alpha_1 p_1 + \alpha_2 p_2. \quad (\text{B11})$$

The two-mode bottle-beam potential is recovered by making  $\alpha_1 = -1$  and  $\alpha_2 = 0$ .

Decoupling between the radial ( $\rho$ ) and longitudinal ( $z$ ) dependencies is achieved by choosing  $\alpha_1$  and  $\alpha_2$  such that

$$|B|^2 + \text{Re}(AB^*) = 0 \quad (B \neq 0). \quad (\text{B12})$$

We can write this condition in terms of the real and imaginary parts of the coefficients  $\alpha_j = a_j + ib_j$ . Including the

bottle-beam condition, the following equations must hold:

$$1 + a_1 + a_2 = 0, \quad (\text{B13})$$

$$b_1 + b_2 = 0, \quad (\text{B14})$$

$$(a_1^2 + b_1^2)(p_1^2 + p_1^3) + (a_2^2 + b_2^2)(p_2^2 + p_2^3) + p_1 p_2 (p_1 + p_2 + 2)(a_1 a_2 + b_1 b_2) = 0. \quad (\text{B15})$$

By using (B13) and (B14) in (B15), we derive the following condition:

$$(a_1^2 + b_1^2) [p_1^2(p_1 + 1) + p_2^2(p_2 + 1) - p_1 p_2 (p_1 + p_2 + 2)] + a_1 [2p_2^2(p_2 + 1) - p_1 p_2 (p_1 + p_2 + 2)] + p_2^2(p_2 + 1) = 0. \quad (\text{B16})$$

For example, let us set  $p_1 = 1$  and  $p_2 = 2$ , giving

$$a_1^2 + b_1^2 + \frac{7}{2}a_1 + 3 = 0 \Rightarrow b_1^2 = -\left(a_1^2 + \frac{7}{2}a_1 + 3\right) \geq 0. \quad (\text{B17})$$

This condition has infinite solutions in the interval  $-2 \leq a_1 \leq -3/2$ . Its limits provide real solutions for the superposition coefficients:

- (a)  $\alpha_1 = -2, \alpha_2 = 1$ .
- (b)  $\alpha_1 = -3/2, \alpha_2 = 1/2$ .

Note that the first real solution is useless, since it gives  $B = 0$  and cancels out all terms up to  $\rho^4$  and  $z^2$  in the trapping potential. The other real solution gives  $A = 1/2$  and  $B = -1/2$ , resulting in the following expression for intensity of the electric field:

$$I(\rho, z) \approx I_0 \left( \frac{z^2}{z_R^2} + \frac{\rho^4}{w_0^4} \right), \quad (\text{B18})$$

which provides the desired bottle-beam configuration with decoupled dynamics along the transverse and longitudinal directions. Moreover, we can easily show that this solution is optimal. Under the bottle-beam and decoupling condition, the trapping strength is

$$4|B|^2 = 2a_1 + 4, \quad (\text{B19})$$

which is a linear function of  $a_1$  with positive slope. Therefore, its maximum value is obtained at the upper limit  $a_1 = -3/2$ .

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