Proving genuine multiparticle entanglement from separable nearest-neighbor marginals

Marius Paraschiv, Nikolai Miklin, Tobias Moroder, and Otfried Gühne Naturwissenschaftlich-Technische Fakultät, Universität Siegen, Walter-Flex-Straße 3, D-57068 Siegen, Germany



(Received 26 May 2017; revised manuscript received 4 October 2018; published 3 December 2018)

We address the question of whether or not global entanglement of a quantum state can be inferred from local properties. Specifically, we are interested in genuinely multiparticle entangled states whose two-body marginals are all separable, but where the entanglement can be proven using knowledge of a subset of the marginals only. Using an iteration of semidefinite programs we prove that for any possible marginal configuration up to six particles multiqubit states with the desired properties can be found. We then present a method to construct states with the same properties for more particles in higher dimensions.

DOI: 10.1103/PhysRevA.98.062102

I. INTRODUCTION

An essential property of quantum systems is that they can be entangled, meaning that the state of the system cannot be factorized [1,2]. A related question concerns the relationship between global properties of the system and the local properties of its subsystems. In the simplest version, one may just ask whether the global state can be determined from its marginals, and which sets of marginals are compatible. This is a rather old problem, sometimes called the marginal problem, or the representability problem [3], but recently it attracted again much attention [4–11]. More precisely, one can also ask whether certain global properties, such as entanglement, can be concluded from the marginals. In fact, several examples have been identified, where this is the case: Using spinsqueezing inequalities one may prove entanglement from twobody marginals, although these marginals itself are separable [12,13]. Similar phenomena exist for Bell inequalities, where the marginals are compatible with a local hidden-variable model, but the global state is not, and this can be proven from the marginals [14–16].

The notion of entanglement used in the above mentioned works relies on the question whether or not the global state can be factorized completely, that is, whether it is fully separable or not. In other words, if the state does not factorize, it is entangled. This does not mean, however, that it is genuine multiparticle entangled, as genuine multiparticle entanglement requires the entanglement between all particles and not only some of them. So the more demanding task of proving that a state is genuinely multiparticle entangled just from separable two-body marginals still remained. In Ref. [17], however, a first example of this phenomenon has been presented and in Ref. [18] the authors provided a systematic method of finding genuinely multiparticle entangled states with separable two-body marginals, where the genuine multiparticle entanglement can be proven from the marginals only. They have also provided a scheme for constructing states with the desired properties for any number of particles, and gave examples of numerically found states for up to five

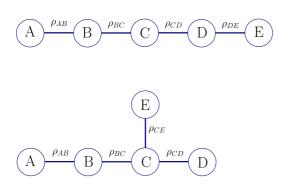
In this paper we go one step further and see what happens if only a subset of the marginals is known, but still all marginals are required to be separable. Using a suitable ordering and topology of the particles, one can always view the subset of known marginals as the set of nearest-neighbor marginals. It is clear that only from subsets of two-body marginals where all particles are included and where all marginals form a connected graph the global entanglement can be proven. The possible marginal configurations are known as unlabeled trees [19]. The number of these configurations is known to scale exponentially [20], but for a small number of particles an exhaustive classification is known [19,21]. We will see that it is always possible to find examples of states where genuine multiparticle entanglement can be proven from separable two-body nearest-neighbor marginals.

In order to study different marginal configurations for higher particle numbers the numerical tools used in Ref. [18] are not sufficient and improved optimization methods are required. The extension to more particles, however, gives new insights: For the minimal configurations of five (see Fig. 1) and six qubits, examples of states can always be found already for qubits and, remarkably, most of these states are pure. This purity allows one to present a method to find examples for general marginal configurations of an arbitrary number of particles using copies of the numerically found five- and sixqubit states. This method allows one to construct the desired states for any marginal configuration of an arbitrary number of particles, but higher-dimensional systems are required.

This paper is organized as follows. In Sec. II we introduce the required facts about multiparticle entanglement and state the problem. In Sec. III we describe the iteration of semidefinite programs that we use to solve this problem. Section IV presents the results for four, five, and six qubits. In Sec. V we discuss the generalization to an arbitrary number of particles. Finally, we conclude and discuss further research directions.

II. DEFINITIONS AND STATEMENT OF THE PROBLEM

We begin by recalling the notion of genuinely multiparticle entangled states, detailed discussions can be found in Refs. [1,2,22]. For simplicity, we will restrict ourselves to three-particle systems, but the definitions are valid for an arbitrary number of particles. First, a state ρ_{ABC} is said to



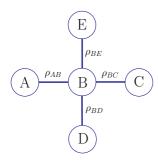


FIG. 1. If global entanglement should be concluded from a set of two-body marginals $\{\rho_{ij}\}$ then the set of marginals has to obey two conditions: First, any particle k must be covered by the set and secondly, the graph arising from the interpretation of the ρ_{ij} as edges must be connected. Among the marginal sets with these conditions, the minimal sets are of special interest, and these are necessarily treelike configurations. The figure shows all minimal tree configurations of marginals for five particles, up to permutations of the particles [19].

be separable with respect to a bipartition A|BC if it can be written as a mixture of product states, with respect to the bipartition A|BC,

$$\rho_{A|BC}^{\text{sep}} = \sum_{k} q_{k} |\phi_{A}^{k}\rangle\langle\phi_{A}^{k}| \otimes |\psi_{BC}^{k}\rangle\langle\psi_{BC}^{k}|, \qquad (1)$$

where the q_k form a probability distribution. If the global state of the system can be written as

$$\rho^{\text{bs}} = p_1 \rho_{A|BC}^{\text{sep}} + p_2 \rho_{B|AC}^{\text{sep}} + p_3 \rho_{C|AB}^{\text{sep}}, \tag{2}$$

it is called biseparable. This gives the definition of genuine multiparticle entanglement: If a state is not biseparable, i.e., it cannot be written in the form of Eq. (2), then it is genuinely multiparticle entangled.

Due to the definition of biseparability, it is very difficult to verify this property directly. For our approach it is very useful to consider a relaxed definition by considering a larger set of states, the set of so-called PPT mixtures (see Fig. 2). Let us first recall the entanglement criterion of the positivity of the partial transpose (PPT). Any two-particle state on an $N \times M$ system can be written as

$$\rho = \sum_{i,j}^{N} \sum_{k,l}^{M} \rho_{ij,kl} |i\rangle\langle j| \otimes |k\rangle\langle l|.$$
 (3)

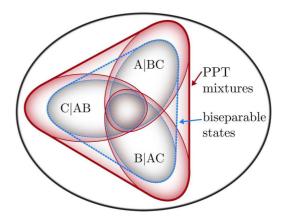


FIG. 2. Illustration of biseparable states and PPT mixtures for a three-particle system; see text for further details. The figure is taken from Ref. [22].

The partial transposition of ρ with respect to the first subsystem (we use the standard convention of naming the two subsystems Alice and Bob), is then given by

$$\rho^{T_A} = \sum_{i,j}^{N} \sum_{k,l}^{M} \rho_{ji,kl} |i\rangle\langle j| \otimes |k\rangle\langle l|. \tag{4}$$

A state ρ is said to have a positive partial transpose (PPT) if

$$\rho^{T_A} \geqslant 0, \tag{5}$$

that is, ρ^{T_A} has no negative eigenvalues. Separable states are PPT [23] and according to the Horodecki theorem [24], for 2×2 and 2×3 systems, any PPT state is also separable. This criterion for separability is very easy to test numerically, thus we shall use it to test the separability of our two-body marginals.

For multiparticle states, the partial transposition can be defined for any bipartition of the system. Now, similarly to biseparable states, a state that can be written as

$$\rho^{\text{pmix}} = p_1 \rho_{A|BC}^{\text{ppt}} + p_2 \rho_{B|AC}^{\text{ppt}} + p_3 \rho_{C|AB}^{\text{ppt}}$$
 (6)

is called a PPT mixture, as it is a mixture of PPT states for the different bipartitions [22].

Looking at Fig. 2, the convex hull of all states separable with respect to a fixed bipartition is the set of biseparable states. In a similar way, the convex hull of states which are PPT with respect to a bipartition is the set of PPT mixtures. It is clear that every biseparable state is also a PPT mixture. Thus, if we can prove that a state is not a PPT mixture, then it is genuinely multiparticle entangled. Note that the partial transposition is only one example of a map that can be used; other positive but not completely positive maps work as well [25].

Now, having a suitable criterion for entanglement, we can write down an entanglement witness that can detect a state which is not a PPT mixture. An entanglement witness is an observable \mathcal{W} that is non-negative on all biseparable states and has a negative expectation value on at least one entangled state. For the two-particle case a witness \mathcal{W} is called decomposable if it can be written in terms of two positive

semidefinite observables P and Q ($P \ge 0$ and $Q \ge 0$) as

$$W = P + Q^{T_A}. (7)$$

One can generalize this definition to the multiparticle case. A witness that can be written as

$$W = P_M + Q_M^{T_M}, \tag{8}$$

for any bipartition $M|\bar{M}$ of the system is called fully decomposable. The connection to the notion of PPT mixtures is the following.

Observation 1. If ρ is not a PPT mixture, then there exists a fully decomposable witness W that detects it. The proof can be found in Ref. [22].

Now we can define the problem in a rigorous way. For N particles there are N(N-1)/2 possible two-body marginals (reduced density matrices) ρ_{ij} . We fix a subset S of them and call them also the nearest-neighbor marginals. Then, we want to find an N-particle state ρ such that the following.

- (1) All N(N-1)/2 two-body marginals of ρ are separable. Since we are first looking for multiqubit states, the marginals are systems of two qubits and for them separability is equivalent to being PPT.
- (2) The state ρ is genuinely multiparticle entangled and this entanglement can be proven from knowledge of the marginals in the subset S only. This condition can be assured by using fully decomposable witnesses, which detect states that are not PPT mixtures and which contain only two-body interactions corresponding to the marginals in the subset S. Clearly, the subset S has to obey some conditions, in order to find the requested states. First, any particle k must be covered by the set and second, the graph arising from the interpretation of the ρ_{ij} as edges must be connected; otherwise there is one bipartition, for which entanglement cannot be checked (see also Fig. 1). Among the marginal sets with these conditions, the minimal sets are of special interest as in these the least amount of knowledge is given. These configurations are necessarily treelike configurations.

III. DESCRIPTION OF THE ALGORITHM

In this section, we describe the algorithm used for finding the desired states. The algorithm relies on an iteration of semidefinite programs (SDPs) [27], some basic facts about SDPs are explained in the Appendix A.

To obtain a state with the desired properties, we implement a program as a sequence of steps, over which an iteration is performed until the desired precision is reached. The main idea of this program was already used in Ref. [18].

Step 0: Generate a random pure state ρ . For practical purposes, it is preferable that the initial state does not have any symmetries. Otherwise, the following iteration may in practice end up in a fixed point which does not have the desired properties.

Step 1: Insert the state into the first SDP. This SDP aims at finding an optimal fully decomposable witness, meaning that the witness has the smallest expectation value (among all other considered witnesses) for the given state. The witness is constructed such that it can be evaluated from knowledge of the marginals ρ_{ij} in the subset S only. Formally, this program

is given by

$$\begin{aligned} & \min \operatorname{Tr}(\mathcal{W}\rho), \\ & \text{s.t.} \operatorname{Tr}(\mathcal{W}) = 1, \\ & \mathcal{W} = \sum_{i,j} \omega_{i,j}^{\alpha,\beta} \sigma_i^{\alpha} \otimes \sigma_j^{\beta} \otimes \mathbb{1}^{\otimes (N-2)} + \text{perm. in } S, \\ & \mathcal{W} = P_M + Q_M^{T_M} \text{ with } P_M, Q_M \geqslant 0 \text{ for all } M | \bar{M}. \end{aligned} \tag{9}$$

The first condition, Tr(W) = 1 is just a normalization condition on the witness. This normalization is not the only possible one; it does, however, assure the best robustness against white noise [22].

The second condition ensures the constraint that the witness contains only contains two-body terms from the marginals in S. Here, σ_i^{α} denotes a Pauli matrix acting on the qubit α . The permutation is performed over two-body marginals within this set, with a different $\omega_{i,j}^{\alpha,\beta}$ coefficient for each term. It is also important to stress here that, while the witness is restricted to only two-body terms, the operators P_M and Q_M are not.

Finally, the last condition ensures that the witness is fully decomposable, hence it detects non-PPT mixtures.

Step 2: Insert the optimal witness from the previous step, into the second SDP. The purpose of this SDP is to obtain an optimal state that minimizes the expectation value of \mathcal{W} as much as possible under the condition that all two-body marginals are PPT. This program is

min
$$\operatorname{Tr}(\mathcal{W}\rho)$$
,
s.t. $\operatorname{Tr}(\rho) = 1$.
 $\rho \geqslant 0$, (10)
 $\rho_{\alpha,\beta}^{T_{\alpha}} \geqslant 0$ for all α, β .

While the first two conditions are present just to assure the fact that ρ is a density matrix, the third one represents the constraint that all two-body marginals of ρ must be separable (for qubits the PPT condition is equivalent to separability). Separability must hold for all two-body marginals, not just the marginals in S.

One can then iterate steps 1 and 2, obtaining a better approximation of the optimal state with each additional step. This see-saw algorithm is, of course, not guaranteed to converge to the global optimum. However, in practice different solutions turned out to be equivalent under local unitary transformations.

In practice, the two SDPs have been implemented in PYTHON, using the Picos convex optimization interface [26]. After a remarkably small number of iterations (usually two or three) one already finds a state that satisfies the desired requirements. On a regular desktop configuration, the four-qubit state is obtained in less than a minute, the five-qubit state in around 45 min and the six-qubit state in around 6 h. We thus managed to obtain such states for four, five, and six qubits, for various configurations (see Table I below). We started with a pure initial random state and it is important to mention that

TABLE I. Obtained states and witness values for the various configurations. All states are uniquely determined by their known two-body marginals from the set *S*.

Index	Configuration	${ m Tr}[ho {\cal W}]$	Pure
	4-qubit conf	igurations	
4a	•••	-3.15×10^{-3}	No
4b	• • •	-3.56×10^{-3}	Yes
	5-qubit conf		
5a	• • • •	-1.13×10^{-3}	Yes
5b	• • •	-1.31×10^{-3}	Yes
5c	•	-1.38×10^{-3}	Yes
	6-qubit conf		
6a	••••	-2.01×10^{-4}	Yes
6b		-2.56×10^{-4}	Yes
6c	><	-2.84×10^{-4}	Yes
6d	••••	-2.92×10^{-4}	Yes
6e	•••	-3.80×10^{-4}	Yes
6f		-4.54×10^{-4}	No

all obtained optimal states are also pure, except for two of them; see Table I. The obtained pure states are also uniquely determined by the marginals $\rho_{i,j}$ in S, which can be concluded from the fact that they are eigenstates corresponding to the smallest eigenvalue of the witness, and this eigenvalue is nondegenerate. This will turn out to be essential later on, when we discuss generalizations of these results.

The negative expectation values found numerically (and presented in Table I) may seem small (10^{-4} for six-qubit states) but it is important to note that the SDP solver works with a precision of at least 10^{-10} .

One can observe that, as the number N of particles increases, the absolute value of the witness value for the numerically found state decreases. This may be expected, since the total number of two-body marginals is $\binom{N}{2} = N(N-1)/2$ and the total number of parameters of the density matrix is 4^N-1 . On the other hand, the number of nearest-neighbor two-body marginals is N-1 and in total 3(N-1) parameters of the density matrix are known. Thus, as N grows, the witness has information about a very small fraction of all marginals and parameters and the phenomenon becomes fragile.

IV. RESULTS FOR THE VARIOUS CONFIGURATIONS

In this section, we present the results obtained by using the previously described method. After finding the numerical form of the desired states, one also needs to find an analytical approximation. This is a tedious task and has only been done here for the four- and five-qubit states. By noting that local unitary transformations do not affect the entanglement in our system, we can apply local unitary transformations to the state,

$$\rho_{\text{num.}}(\alpha, \theta, \phi) = U^{\dagger} \rho_{\text{num.}} U, \tag{11}$$

and perform an optimization over any function of the parameters α , θ , and ϕ . This generally leads to a state ρ with some zero elements, simplifying the task of finding an analytical form. The above local unitaries are constructed from tensor products of qubit unitaries, which can be parametrized as

$$U(\alpha, \theta, \phi) = \begin{pmatrix} e^{i\alpha} \cos(\phi) & e^{i\theta} \sin(\phi) \\ -e^{-i\theta} \sin(\phi) & e^{-i\alpha} \cos(\phi) \end{pmatrix}.$$
(12)

The main results of the following discussion are summarized in Table I.

A. Four gubits

There are two possible configurations for four qubits, denoted in Table I as 4a and 4b. While for both configurations we obtained genuinely multiparticle entangled states with the desired requirements, state 4a is not pure. We show here the other state, 4b, which is pure and uniquely determined by its known two-body marginals.

$$|\psi_4\rangle = \frac{1}{\sqrt{87}}(5|\phi_1\rangle + \sqrt{10}|\phi_2\rangle + \sqrt{3}|\phi_3\rangle + 7|\phi_4\rangle), \quad (13)$$

where the component states are

$$|\phi_{1}\rangle = \frac{1}{\sqrt{2}} (e^{\frac{3\pi}{7}i} |1100\rangle - |0000\rangle),$$

$$|\phi_{2}\rangle = \frac{1}{\sqrt{5}} (e^{\frac{\pi}{4}i} |0101\rangle - |0111\rangle - |1000\rangle - |1001\rangle - |1111\rangle),$$

$$|\phi_{3}\rangle = \frac{1}{\sqrt{6}} (e^{\frac{-2\pi}{3}i} |0010\rangle + |0011\rangle + |0100\rangle + |1010\rangle +$$

$$+ |1101\rangle + |1110\rangle),$$

$$|\phi_{4}\rangle = \frac{1}{\sqrt{2}} (|0110\rangle - |1011\rangle).$$
(14)

This is the closest analytical state to the one obtained numerically. The values of the numerical result are given in the Appendix B.

The noise tolerance is defined as the maximal p, such that

$$\rho(p) = (1 - p)\rho + p\frac{1}{2^N},\tag{15}$$

has still all the desired properties. For the numerical state in the Appendix B it is given by $p_{\text{max}} \approx 0.35\%$.

B. Five qubits

We show here the five-qubit state labeled as 5a. This state is pure and uniquely determined by its known nearest-neighbor marginals as well. It is given by

$$|\psi_{5}\rangle = \frac{1}{\mathcal{N}_{1}} \left(\frac{1}{4} |\phi\rangle + \frac{3}{2} \sqrt{\frac{3}{10}} |\eta\rangle + \frac{1}{14} e^{\frac{2\pi i}{3}} |11101\rangle + \frac{2}{11} e^{\frac{-3\pi i}{13}} |11111\rangle \right), \tag{16}$$

where \mathcal{N}_1 is a normalization and the corresponding substates are

$$\begin{split} |\eta\rangle &= \sqrt{\frac{2}{15}} \left(\frac{\sqrt{6}}{2} |\eta_1\rangle + \sqrt{2} |\eta_2\rangle - 2|\eta_3\rangle \right), \\ |\eta_1\rangle &= \sqrt{\frac{1}{6}} (|00011\rangle - |00001\rangle - |01001\rangle + |01010\rangle \\ &- |10000\rangle + |10011\rangle) \\ |\eta_2\rangle &= \frac{1}{3\sqrt{2}} (e^{\frac{\pi i}{8}} |01100\rangle + e^{\frac{\pi i}{8}} |11001\rangle + 4|11110\rangle), \\ |\eta_3\rangle &= \frac{1}{2} (|11010\rangle + |11100\rangle + |11000\rangle + |00000\rangle), \quad (17) \end{split}$$

and

$$|\phi\rangle = \frac{1}{\mathcal{N}_2} \left(\frac{1}{2} |\phi_1\rangle + \frac{\sqrt{2}}{3} e^{\frac{\pi i}{4}} |\phi_2\rangle + \frac{\sqrt{3}}{5} |\phi_3\rangle + 2|\phi_4\rangle \right),$$

$$|\phi_1\rangle = \frac{1}{2} \left(e^{\frac{\pi i}{4}} |00010\rangle - \frac{1}{2} |01011\rangle - \frac{1}{2} |01101\rangle + |01110\rangle - \frac{1}{2} |01111\rangle - \frac{1}{2} |10111\rangle + |11011\rangle \right),$$

$$|\phi_2\rangle = \frac{1}{\sqrt{2}} (|00110\rangle + |01000\rangle),$$

$$|\phi_3\rangle = \frac{1}{\sqrt{3}} (|00100\rangle + |00101\rangle + |10101\rangle),$$

$$|\phi_4\rangle = \frac{1}{2} (|10010\rangle + |10100\rangle + |10110\rangle - |10001\rangle). (18)$$

The numerically obtained state is given in the Appendix B.

Due to the severe limitation on the information regarding the marginals, the numerically obtained state has a very low noise robustness ($p_{\rm max}\approx 0.11\%$), so only for little noise the entanglement of the global state can be proven from the separable known marginals only.

C. Six qubits

In this case, there are six possible nearest-neighbor configurations, five of which are pure and uniquely determined. Due to its size, we present one example of the obtained states the state in numeric form in the Appendix B. The noise tolerance for this numerical six-qubit state is $p_{\text{max}} \approx 0.02\%$, and the expectation value of the optimal witness, together with this state, while negative, is of the order of 10^{-4} . All other marginal configurations that have been tested are presented in Table I.

V. GENERALIZATION TO MORE PARTICLES

The purpose of this last section is to present a general method for constructing arbitrarily large states by using the numerically found ones as building blocks. The main idea of this generalization was already presented in Ref. [18]. This method ensures that the constructed states retain the properties of the states found for a small number of particles. Note that we found pure genuinely multiparticle entangled states which are uniquely determined by their known two-body

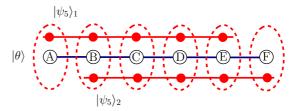


FIG. 3. Constructing a state with the desired properties for a simple six-party configuration. Here, it is assumed that the marginals ρ_{AB} , ρ_{BC} , ρ_{CD} , ρ_{DE} , and ρ_{EF} are known. See text for further details.

marginals. It is important to stress that without this unique determination and the purity the proposed method would not work

Before describing the method in detail, we point out a disadvantage of this generalization, namely that one must resort to higher-dimensional systems, where each party does not consist of only a qubit. The state we use here to exemplify is the linear five-qubit state. The first example is for a simple six-party system, depicted in Fig. 3.

The state we want to construct is $|\theta\rangle$. The parties A and F have a single qubit while the ones from B to E have two qubits. We depict the two-party marginals by blue lines. All we need to do is to distribute two copies of the pure five-qubit state $|\psi_5\rangle$ in Eq. (16) as represented by the thick red lines among the six parties. Let us explain why this construction works: Every two-party marginal is a direct product of separable states since the marginals of $|\psi_5\rangle$ are separable. Thus it is itself separable. From the fact that $|\psi_5\rangle$ is uniquely determined by its known two-body nearest-neighbor marginals it follows that one also knows the state $|\psi_5\rangle$ and the way copies of this state have been distributed among the parties. This also means that the global state itself, namely $|\theta\rangle$, is uniquely determined by its two-body nearest-neighbor marginals as well. The constructed state is pure and cannot be factorized for any bipartition of the system, so it is genuinely multiparticle entangled and this entanglement is proven from the nearest-neighbor two-body marginals only.

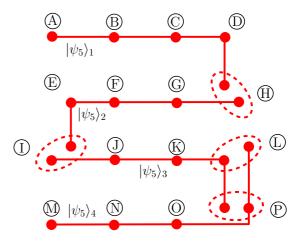


FIG. 4. Covering a two-dimensional lattice with linear numerically found states. See text for further details.

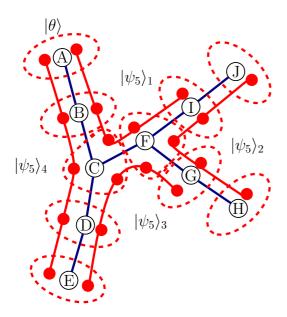


FIG. 5. Constructing a state with the desired properties for an arbitrary configuration. See the text for further details.

If we consider a 4×4 two-dimensional lattice, as depicted in Fig. 4, it can be fully covered by using four copies of the linear five-qubit state. Nodes H, I, L, and P contain two qubits, one from each copy of the state, so we require a total of 20 qubits to construct the desired lattice state.

These ideas can be used for an arbitrary configuration. Consider the 10 parties (A to J) in Fig. 5. Each of the parties has at least one qubit (H and J) and at most three (C and F). By repeating the same algorithm as above, and distributing as few copies of the five-qubit state as possible, while still covering every party by at least one copy, we obtain a 10-particle state, with the desired properties as the one above. Due to the fact that with our SDP we were able to go as high as six qubits, one could take advantage of this and use the linear six-qubit state instead. While less robust to noise, an arbitrary configuration would require less copies of the state, thus helping to reduce the dimensionality of some of the systems (for example, C and F in Fig. 5 are three-qubit systems).

VI. CONCLUSION

In this paper we considered an interesting class of states, namely genuinely multiparticle entangled states whose two-body reduced density matrices are all separable, nevertheless one can prove the global entanglement from some marginals only. We found examples of this phenomenon for all possible configurations of four, five, and six qubits. We also showed how these examples can be used to find more general states for more particles.

While this paper only looks at two-body marginals, the problem could be taken one step further by also treating higher-order marginals and proving the entanglement of the global state just with the knowledge of those marginals. This gives more information about the state, but on the other hand, the condition on the separability of the marginals becomes more restrictive. Another option would be to further constrain the witness by allowing the observers to perform only a

subset of possible measurements (for example, only σ_z and σ_x measurements). Similarly, it would be interesting to consider nonlocality and ask whether all the phenomena observed for entanglement can also be found for nonlocal correlations. Here, the recent results in Refs. [28,29] may be useful.

As previously discussed, the states presented here have a rather low noise tolerance (for example, 0.02% for the six-qubit state), and it decreases with the increase in the number of qubits. This is mainly due to the strong constraint on nearest-neighbor information only. Nevertheless it would be interesting, though challenging, to see an experimental study of the effects discussed here.

ACKNOWLEDGMENTS

We thank Nikolai Wyderka for help with the numerical calculations. This work has been supported by the DAAD, the ERC (Consolidator Grant No. 683107/TempoQ), and the DFG.

APPENDIX A: SEMIDEFINITE PROGRAMMING

An SDP can be formulated as the problem of minimizing a variable $x \in \mathbb{R}^m$ in the form,

min
$$c^T x$$
,
subject to $F(x) = F_0 + \sum_{i=1}^m x_i F_i$,
 $F(x) \ge 0$. (A1)

The vector $c \in \mathbb{R}^m$ and the m+1 symmetric matrices $F_0, \ldots, F_m \in \mathbb{R}^{n \times n}$ represent the problem data, while the $F(x) \ge 0$ constraint means that F(x) is a positive semidefinite matrix, $z^T F(x)z \ge 0$, or, alternately, all eigenvalues of F(x) are non-negative.

An SDP is a convex optimization problem since for $F(x) \ge 0$ and $F(y) \ge 0$, for all $\lambda \in [0, 1]$ we have

$$F[\lambda x + (1 - \lambda y)] = \lambda F(x) + (1 - \lambda)F(y) \geqslant 0, \quad (A2)$$

hence both the objective function and the constraint are convex.

To a given SDP one can associate the so-called dual semidefinite program (from now on it will be referred to as SDD), which is of the form,

$$\max - \text{Tr}(F_0 Z),$$
subject to $\text{Tr}(F_i Z) = c_i,$

$$Z \ge 0.$$
(A3)

again, for all i = 1, ..., m. In this case, the variable is the matrix $Z = Z^T \in \mathbb{R}^{n \times n}$. Henceforth we refer to the original SDP as the primal problem and to the SDD as the dual problem and call a matrix Z to be dual feasible if $\text{Tr}(F_i Z) = c_i$ and $Z \ge 0$.

One important property of SDPs and their associated duals is that one sets bounds on the optimal value of the other. If Z

is dual feasible and x is primal feasible, then we have

$$c^{T}x + \operatorname{Tr}(ZF_{0}) = \sum_{i=1}^{m} \operatorname{Tr}(ZF_{i}x_{i}) + \operatorname{Tr}(ZF_{0})$$
$$= \operatorname{Tr}(ZF(x)) \geqslant 0, \tag{A4}$$

since $Tr(AB) \ge 0$ if $A \ge 0$ and $B \ge 0$. This reduces to

$$-\operatorname{Tr}(F_0 Z) \leqslant c^T x,\tag{A5}$$

so the dual objective value of any dual feasible point Z is smaller than or equal to the primal objective value of any primal feasible point x. If α is the optimal value of the SDP $\alpha = \min\{c^T x | F(x) \ge 0\}$, then we have for any dual feasible Z that $-\operatorname{Tr}(ZF_0) \le \alpha$. Analogously if β is the optimal value of the SDD, then $\beta \le c^T x$. This means that dual feasible matrices impose a lower bound on the primal problem and

primal feasible points impose an upper bound on the dual problem. What one can generally prove is that, in most cases, the strong condition $\alpha = \beta$ holds.

Theorem 2. The condition $\alpha = \beta$ holds if any of the following requirements is true.

- (1) The primal problem is strictly feasible, that is, there exists feasible x such that F(x) > 0.
- (2) The dual problem is strictly feasible, that is, there exists feasible Z such that $Z = Z^T > 0$.

A proof of this theorem can be found in Ref. [30].

APPENDIX B: EXAMPLES OF STATES

We present here the numerical form for some of the states discussed in Sec. IV. The coefficients of the states have been approximated by fractions and the states are written in a not normalized way.

The four-qubit state from Sec. IV for the configuration 4b is given by

$$|\psi_4\rangle \sim \left(-\frac{2}{33} + \frac{5i}{38}, \frac{1}{21} + \frac{2i}{13}, \frac{50}{149} + \frac{3i}{35}, -\frac{1}{17} + \frac{3i}{25}, \frac{7}{26} - \frac{5i}{28}, -\frac{3}{32} + \frac{10i}{61}, \frac{7}{62} + \frac{6i}{17}, -\frac{2}{17} + \frac{i}{111}, \frac{5}{23} + \frac{8i}{29}, \frac{3}{31} + \frac{5i}{41}, \frac{2}{41} - \frac{5i}{34}, -\frac{1}{13} + \frac{11i}{30}, -\frac{1}{289} + \frac{i}{51}, -\frac{1}{270} + \frac{i}{24}, -\frac{1}{58} + \frac{7i}{24}, \frac{11}{31}\right).$$

The numerical form of the five-qubit state for configuration 5a, presented in Sec. IV is given by

$$|\psi_5\rangle \sim \left(-\frac{3}{35} - \frac{i}{22}, \frac{4}{31} + \frac{i}{40}, \frac{4}{29} - \frac{i}{22}, -\frac{1}{28} + \frac{4i}{29}, \frac{4}{35} - \frac{2i}{25}, -\frac{1}{24} + \frac{i}{19}, -\frac{6}{35} - \frac{5i}{28}, \frac{2}{33} - \frac{4i}{45}, \frac{1}{32} - \frac{i}{3}, \frac{3}{35} - \frac{19i}{94}, -\frac{5}{24} - \frac{3i}{16}, \frac{1}{74} - \frac{2i}{33}, -\frac{4}{27} + \frac{i}{207}, -\frac{1}{186} - \frac{2i}{39}, \frac{5}{41} - \frac{2i}{13}, \frac{2}{19} + \frac{5i}{34}, -\frac{2}{27} + \frac{i}{6}, \frac{3}{29} - \frac{8i}{33}, -\frac{1}{8} - \frac{5i}{36}, \frac{7}{30} - \frac{3i}{40}, -\frac{4}{31} - \frac{5i}{28}, \frac{1}{7} - \frac{3i}{35}, -\frac{11}{36} + \frac{i}{83}, \frac{1}{50} - \frac{2i}{35}, \frac{1}{10} - \frac{8i}{41}, \frac{1}{26} - \frac{i}{50}, \frac{4}{39} - \frac{2i}{29}, -\frac{2}{29} - \frac{2i}{19}, -\frac{1}{18} - \frac{i}{295}, -\frac{2}{27} - \frac{2i}{23}, -\frac{1}{18} - \frac{4i}{33}, \frac{1}{10}\right).$$

Due to its size, we only present the linear six-qubit state (configuration 6a) in numerical form,

$$\begin{split} |\psi_6\rangle \sim & \left(\frac{3}{77}, 0, \frac{1}{55}, -\frac{4}{61} - \frac{6i}{85}, -\frac{2}{97}, 0, 0, \frac{3}{107}, -\frac{10}{59}, \frac{1}{133} - \frac{7i}{167}, -\frac{7}{211}, -\frac{7}{211}, -\frac{1}{27} + \frac{21i}{106}, \right. \\ & \left. -\frac{23}{172} - \frac{6i}{121}, -\frac{11}{70}, \frac{1}{106} - \frac{8i}{193}, -\frac{7}{211}, \frac{9}{167}, \frac{13}{168}, -\frac{33}{97}, \frac{10}{103} + \frac{17i}{77}, \frac{13}{168}, \frac{8}{61}, \frac{8}{83}, \frac{16}{43}, 0, \right. \\ & \left. \frac{1}{128} - \frac{11i}{84}, \frac{29}{83}, 0, \frac{47}{168}, \frac{16}{43}, \frac{9}{167}, 0, 0, -\frac{1}{117}, -\frac{17}{358} + \frac{15i}{188}, -\frac{1}{79} + \frac{10i}{191}, 0, 0, -\frac{7}{181} + \frac{i}{25}, \right. \\ & \left. \frac{2}{63} + \frac{9i}{103}, 0, 0, \frac{10}{91}, \frac{5}{127} + \frac{9i}{79}, 0, \frac{2}{59} + \frac{5i}{72}, -\frac{3}{137}, -\frac{3}{107}, -\frac{6}{161} + \frac{4i}{59}, -\frac{8}{159} + \frac{4i}{93}, \right. \\ & \left. \frac{28}{159} + \frac{29i}{217}, -\frac{3}{137}, -\frac{3}{107}, -\frac{3}{107}, -\frac{5}{62} + \frac{2i}{17}, \frac{3}{137}, 0, \frac{3}{137}, -\frac{3}{107}, -\frac{2}{43} - \frac{7i}{87}, \frac{1}{174}, 0, -\frac{3}{65} + \frac{6i}{125} \right). \end{split}$$

This state is also pure and uniquely determined by its two-body nearest-neighbor marginals, while still retaining the desired properties, namely the state should be genuinely multiparticle entangled and the entanglement should be proven from the separable nearest-neighbor two-body marginals only.

R. Horodecki, P. Horodecki, M. Horodecki, and K. Horodecki, Rev. Mod. Phys. 81, 865 (2009).

^[2] O. Gühne and G. Tóth, Phys. Rep. 474, 1 (2009).

^[3] A. J. Coleman, Rev. Mod. Phys. 35, 668 (1963).

^[4] N. Linden, S. Popescu, and W. K. Wootters, Phys. Rev. Lett. 89, 207901 (2002).

- [5] A. Klyachko, arXiv:quant-ph/0409113.
- [6] L. Diósi, Phys. Rev. A 70, 010302 (2004).
- [7] N. S. Jones and N. Linden, Phys. Rev. A 71, 012324 (2005).
- [8] M. Walter, B. Doran, D. Gross, and M. Christandl, Science 340, 1205 (2013).
- [9] A. Sawicki, M. Walter, and M. Kus, J. Phys. A: Math. Theor. 46, 055304 (2013).
- [10] C. Schilling, C. L. Benavides-Riveros, and P. Vrana, Phys. Rev. A 96, 052312 (2017).
- [11] N. Wyderka, F. Huber, and O. Gühne, Phys. Rev. A 96, 010102 (2017)
- [12] G. Tóth, Phys. Rev. A 71, 010301(R) (2005).
- [13] G. Tóth, C. Knapp, O. Gühne, and H. J. Briegel, Phys. Rev. A 79, 042334 (2009).
- [14] L. E. Würflinger, J-D. Bancal, A. Acín, N. Gisin, and T. Vertési, Phys. Rev. A 86, 032117 (2012).
- [15] J. Tura, R. Augusiak, A. B. Sainz, T. Vertési, M. Lewenstein, and A. Acín, Science 344, 1256 (2014).
- [16] Z. Wang, S. Singh, and M. Navascues, Phys. Rev. Lett. 118, 230401 (2017).
- [17] L. Chen, O. Gittsovich, K. Modi, and M. Piani, Phys. Rev. A 90, 042314 (2014).
- [18] N. Miklin, T. Moroder, and O. Gühne, Phys. Rev. A 93, 020104(R) (2016).

- [19] P. Steinbach, *Field Guide to Simple Graphs* (Design Lab, Albuquerque, 1999), Vol. 3.
- [20] R. Otter, Ann. Math. 49, 583 (1948).
- [21] For $k \ge 1$ particles, the number of configurations to check is $1, 1, 1, 2, 3, 6, 11, 23, 47, 106, \ldots$; see sequence A000055 in the On-Line Encyclopedia of Integer Sequences, available at www.oeis.org.
- [22] B. Jungnitsch, T. Moroder, and O. Gühne, Phys. Rev. Lett. 106, 190502 (2011).
- [23] A. Peres, Phys. Rev. Lett 77, 1413 (1996).
- [24] M. Horodecki, P. Horodecki, and R. Horodecki, Phys. Lett. A 223, 1 (1996).
- [25] C. Lancien, O. Gühne, R. Sengupta, and M. Huber, J. Phys. A: Math. Theor. 48, 505302 (2015).
- [26] G. Sagnol, PICOS: A Python Interface for Conic Optimization Solvers; see http://picos.zib.de.
- [27] L. Vandenberghe and S. Boyd, SIAM Rev. 38, 49 (1996).
- [28] F. Baccari, D. Cavalcanti, P. Wittek, and A. Acín, Phys. Rev. X 7, 021042 (2017).
- [29] M. Fadel and J. Tura, Phys. Rev. Lett. 119, 230402 (2017).
- [30] Yu. Nesterov and A. Nemirovski, *Interior Point Polynomial Methods in Convex Programming: Theory and Applications*, SIAM Series in Applied Mathematics (SIAM, 1994).