

Ring Dirac solitons in nonlinear topological systems

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We study solitons of the two-dimensional nonlinear Dirac equation with asymmetric cubic nonlinearity. We show that with the nonlinearity parameters specifically tuned, a high degree of localization of both spinor components is enabled on a ring of certain radius. Such ring Dirac soliton can be viewed as a self-induced nonlinear domain wall and can be implemented in nonlinear photonic graphene lattice with Kerr-like nonlinearities. Our model could be instructive for understanding localization mechanisms in nonlinear topological systems.

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I. INTRODUCTION

The Dirac equation is a paradigmatic model of modern physics that describes a plethora of systems ranging from relativistic particles to electrons in graphene, as well as sound [1], light [2], and cold atoms [3] in artificial lattices. Dirac-type models with spin-orbit interactions now attract special attention in condensed-matter physics and optics, being applicable to the topological insulators [4–6] hosting edge states, immune to disorder. While the linear Dirac equation is now well understood, the physics of the classical nonlinear Dirac model, despite its rich history [7–10], still has a number of open problems. The absence of the rigorous Vakhitov-Kolokolov criterion [11] significantly complicates the stability analysis compared to the case of the nonlinear Schrödinger equation [12–18].

There exists a variety of qualitatively different interaction mechanisms introducing nonlinear corrections in the Dirac equation. In relativistic field theory, the equations have to obey Lorentz invariance, which still leaves Soler [19], Thirring [20,21], and Gross-Neveu [22] nonlinear models. Condensed-matter systems, such as Bose condensates, are not restricted by the Lorentz invariance, which further enriches the family of nonlinear Dirac equations [23–25]. Moreover, the results depend on the dimensionality of the problem. Two-dimensional (2D) Dirac systems deserve special attention since they feature such interesting phenomena as the valley Hall effect and Klein tunneling and are relatively feasible both in the solid state [26] and optics [2,27,28]. A nonlinear 2D Dirac equation can be applied to the emerging field of nonlinear topological photonics [29–37] aiming for dynamically tunable disorder-robust guiding of light.

Recently, a stable 2D soliton of the nonlinear Dirac equation was found by Cuevas-Maraver *et al.* [38,39]. The main result of Ref. [38] is the existence and stability of the soliton in a wide range of parameters for both cubic and quintic nonlinearities. However, the numerical calculation has also

revealed an interesting feature in the radial dependence of the spinor amplitude with zero angular momentum ($m = 0$). Instead of the expected monotonous decrease from the initial value at $r = 0$ to zero at $r = \infty$, the amplitude features a weak flat maximum at some radius $r = r^*$. Such feature was also previously seen in the 1D Soler model and termed as a “hump” [17].

In this work, we analyze the generic 2D nonlinear Dirac equation with asymmetric cubic nonlinearity. We present the physical interpretation of the humped solution as a radial localization of the soliton at the self-induced domain wall, where the band gap in the Dirac equation changes sign; see Sec. II A. Such localization is typical for linear topological edge states [4] and hints at an interesting link between nonlinear localization and topological properties. Next, we optimize the nonlinearity parameters in order to achieve the strong degree of localization. We find a stable solution with $m = 0$, where both spinor components have prominent maxima at the ring where $r = r^*$, and, hence, we term it as a “ring Dirac soliton.” The exact analytical solution of the considered nonlinear Dirac model for the 1D case is given in Sec. II B. The stability and existence analysis for the ring Dirac soliton is presented in Sec. II C. Finally, in Sec. III, we propose a scheme to realize our model in an artificial photonic graphene lattice with Kerr-like optical nonlinearities.

II. RING DIRAC SOLITONS

A. Self-induced domain walls

We start with the 2D nonlinear Dirac equation written for the two-component wave function $\chi = [\chi_1, \chi_2]$,

$$\begin{aligned} i \frac{\partial \chi_1}{\partial t} &= E_1(\chi_1, \chi_2) \chi_1 - i(\partial_x + i \partial_y) \chi_2, \\ i \frac{\partial \chi_2}{\partial t} &= E_2(\chi_1, \chi_2) \chi_2 - i(\partial_x - i \partial_y) \chi_1. \end{aligned} \quad (1)$$

Here,

$$\begin{aligned} E_1(\chi_1, \chi_2) &= \Delta + a_1 |\chi_1|^2 + b |\chi_2|^2, \\ E_2(\chi_1, \chi_2) &= -\Delta + a_2 |\chi_2|^2 + b |\chi_1|^2 \end{aligned} \quad (2)$$

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are the positions of the band edges, affected by the cubic nonlinearity, with Δ being the band-gap half width for zero nonlinearity. In Eqs. (2), we consider a general form of the cubic nonlinearity, which can be asymmetric ($a_1 \neq a_2$). The only restriction is the reciprocity of the cross-coupling nonlinear terms, $\partial E_1/\partial|\chi_2|^2 = \partial E_2/\partial|\chi_1|^2 = b$. We are interested in the solutions with harmonic time dependence and radial symmetry,

$$\chi_1(r, \varphi, t) = \psi_1(r)e^{im\varphi - i\omega t}, \quad (3)$$

$$\chi_2(r, \varphi, t) = i\psi_2(r)e^{i(m-1)\varphi - i\omega t}, \quad (4)$$

so that Eqs. (1) simplify to the ordinary nonlinear differential equations with respect to the radius r :

$$\begin{aligned} \omega\psi_1 &= E_1(\psi_1, \psi_2)\psi_1 + \left(\frac{d}{dr} + \frac{1-m}{r}\right)\psi_2, \\ \omega\psi_2 &= E_2(\psi_1, \psi_2)\psi_2 - \left(\frac{d}{dr} + \frac{m}{r}\right)\psi_1. \end{aligned} \quad (5)$$

In what follows, we focus on the solitons with zero angular momentum, $m = 0$ since the high-momentum states were shown to be unstable [38].

In order to solve Eqs. (5) numerically, we first discretize them using the Chebyshev spectral method, following Refs. [40,41]. This scheme provides high precision even for relatively small sets of basis functions. The singularity at $r = 0$ is naturally handled [40] by looking only for even solutions for ψ_1 and odd solutions for ψ_2 . After the discretization is performed, we apply the numerical shooting technique [42] to find the solutions, vanishing at $r = \infty$.

The results of the calculation are presented in Fig. 1. We start the analysis with the case of symmetric nonlinearity,

$$a_1 = a_2 = -b = -1, \quad (6)$$

corresponding to the 2D Soler model of Ref. [38]. The obtained spatial distributions of the spinor components are shown in Fig. 1(a). At the soliton center, $r = 0$, the component ψ_1 has some nonzero value, while the component ψ_2 is zero. The latter reflects the fact that while the total angular momentum of the soliton is zero, the orbital momentum for the component ψ_2 is equal to -1 ; see Eq. (4). We would like to draw attention to the fact that both spinor components depend on the radius nonmonotonously. They have maxima for the nonzero value of $r = r^* \approx 2$ (indicated by the vertical line) before decaying to zero at $r = \infty$. This maximum is practically unresolved for the component ψ_1 , although it becomes more prominent as the soliton frequency decreases. To the best of our knowledge, the physical interpretation of this maximum has so far not been presented.

The origin of such hump can be understood if one examines the radial dependences of the band edges, shown by the band-edge positions $E_{1,2}(r)$, presented in Fig. 1(c). At large radii where the nonlinear corrections vanish, they tend to the linear band-gap edges $\pm\Delta$. The soliton frequency ω lies inside the band gap, in agreement with the exponential decay of the amplitude. When the radius decreases and the soliton components grow, the nonlinearity induces the crossing of band edges. Their positions at $r = 0$ are swapped as compared

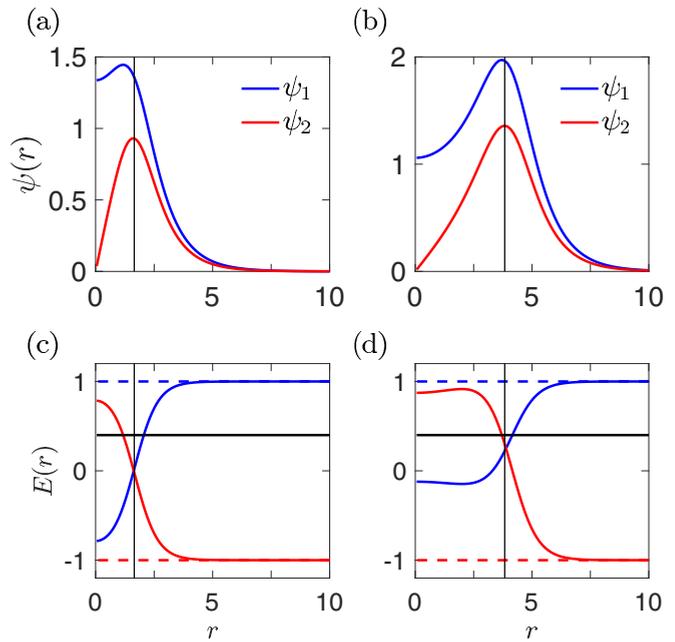


FIG. 1. (a),(b) Radial dependence of the spinor components ψ_1 (blue curve) and ψ_2 (red curve). (c),(d) Radial distributions of the band edges E_1 and E_2 for upper and lower bands shown by blue and red curves, respectively. Dashed lines indicate the band edges for vanishing nonlinearity at $E = \pm\Delta = \pm 1$. The thick horizontal line indicates the soliton frequency $\omega = 0.4$. Left (a),(c) and right (b),(d) panels correspond to $\alpha = 1$ and $\alpha = 1.67$, respectively. Vertical lines indicate the position of the maximum of ψ_2 .

to the case $r \rightarrow \infty$. The crossing point matches the maxima of $\psi_{1,2}$. Spatial localization of the eigenmodes at the band crossing in the Dirac spectrum is very intuitive in the linear regime and lies at the heart of the topological edge states [4,43,44]. In this case, the domains with opposite band orders are described by certain integer topological invariants and the domain wall hosts a localized state. The possibility of topological characterization of nonlinear edge states is so far unclear. However, the general phenomenon behind the localization in topological insulators and the maximum of spinor components in the considered nonlinear Dirac equation is the same band crossing. As such, one can interpret the Dirac soliton in Fig. 1(a) as a self-induced domain wall between the circular core with $E_1 < E_2$ and the outlying space with $E_1 > E_2$.

The maximum in Fig. 1(a) for ψ_1 is not particularly prominent. It becomes sharper as the frequency decreases; however, at low frequencies $|\omega| \lesssim 0.14$, the soliton loses stability with respect to the radial perturbations with the angular momentum $m' = 2$ [38]. Hence, it is an interesting question whether one can tune the nonlinearity to make the maximum more prominent while simultaneously keeping the soliton frequency the same and the soliton stable.

The signature of the self-induced domain wall would be a realization of the band-crossing condition,

$$E_1(\chi^{(1)}) = \omega, \quad E_2(\chi^{(2)}) = \omega, \quad (7)$$

at the frequency ω for the same value $\chi^{(1)} = \chi^{(2)}$. One can see from Fig. 1(c) that the bands cross at $E_1 = E_2 = 0$

relatively far below the soliton frequency $\omega = 0.4$, so that the radial localization is weak. The spinors $\chi^{(1)}$ and $\chi^{(2)}$ in Eq. (7) can be estimated by extending the evanescent linear asymptotic solutions of Eqs. (5) with the ratio of spinor components $\chi_1^{(1,2)}/\chi_2^{(1,2)} = \sqrt{(1+\omega)/(1-\omega)}$ from $r \rightarrow \infty$ to smaller values of r . Substituting this ratio into Eq. (7), we find

$$\xi \equiv \left(\frac{\chi_1^{(1)}}{\chi_1^{(2)}} \right)^2 = -\frac{1-\omega a_2(1-\omega) + b(1+\omega)}{1+\omega a_1(1+\omega) + b(1-\omega)}. \quad (8)$$

The ideal situation, when both bands cross the frequency ω at the same time, corresponds to $\xi = 1$. Our recipe to improve the radial localization at a given frequency is to adjust the nonlinearity by making ξ closer to unity. Inspection of Eq. (8) shows that this condition is further simplified when the symmetry relation $a_1/b = b/a_2$ holds, so that

$$a_1 = -1, \quad a_2 = -\alpha^2, \quad b = \alpha, \quad (9)$$

and

$$\xi = \alpha \frac{1-\omega}{1+\omega}. \quad (10)$$

Hence, one can expect that ξ becomes closer to unity and the radial localization is improved when $\alpha > 1$ for $\omega > 0$ and $\alpha < 1$ for $\omega < 0$.

In order to test this analytical prediction, we show in Figs. 1(b) and 1(d) the results for asymmetric nonlinearity coefficients satisfying Eq. (9) with $\alpha = 1.67$. While the structure of the solution remains formally the same as in Figs. 1(a) and 1(c), where $\alpha = 1$, it now features a prominent maximum for both ψ_1 and ψ_2 components, clearly pinned to the nonlinear band-edge crossing point. The distinction between the symmetric and asymmetric cases is most clearly seen in the two-dimensional maps of the soliton, $|\chi_{1,2}(x, y)|^2$, shown in

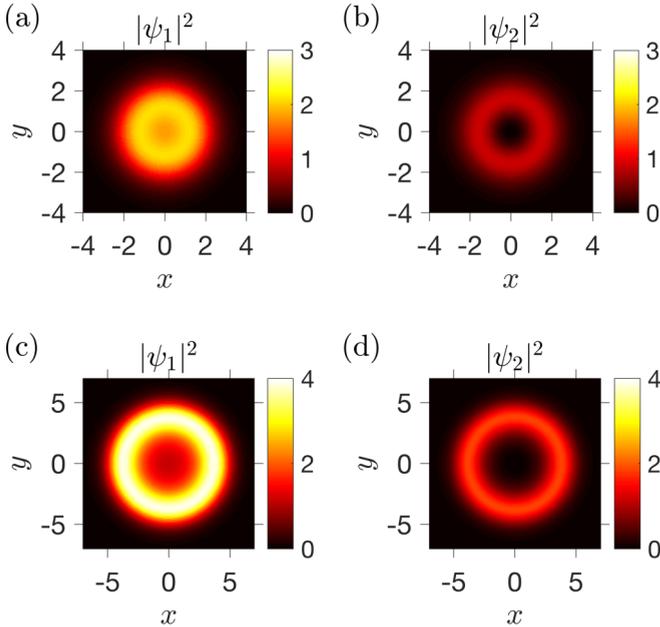


FIG. 2. Spatial distributions of the soliton spinor components (a),(c) $|\chi_1|^2$ and (b),(d) $|\chi_2|^2$, corresponding to the parameters of Fig. 1, calculated for (a),(b) $\alpha = 1$ and (c),(d) $\alpha = 1.67$.

Fig. 2. A ring at $r \approx 4$ is clearly visible for both spinor soliton components in the asymmetric case [Figs. 2(b) and 2(d)], while it is practically unresolved in Fig. 2(a) in the symmetric case. Various solitonic and vortex solutions of the Dirac equation are known, including ring solitons with $|m| > 1$, see, e.g., a detailed analysis in Ref. [45]. Here, we reveal an existence of the $m = 0$ Dirac solitons with rings for both spinor components.

B. Exact solution in 1D

In order to gain deeper insight in the properties of the ring Dirac solitons, we consider a simplified one-dimensional problem instead of the cylindrically symmetric two-dimensional one. The 1D problem with symmetric nonlinearity is known to admit exact analytical solutions [46]. It turns out that the nonlinearity of the type given by Eq. (9) admits them as well. In the 1D case, the derivative over x in Eqs. (1) can be suppressed and they reduce to

$$\begin{aligned} \omega \chi_1 &= E_1(\chi_1, \chi_2) \chi_1 + \frac{d\chi_2}{dy}, \\ \omega \chi_2 &= E_2(\chi_1, \chi_2) \chi_2 - \frac{d\chi_1}{dy}. \end{aligned} \quad (11)$$

Equations (11) have a Hamiltonian structure,

$$\frac{d\chi_1}{dy} = \frac{\partial H}{\partial \chi_2}, \quad \frac{d\chi_2}{dy} = -\frac{\partial H}{\partial \chi_1},$$

with the Hamiltonian

$$H(\chi_1, \chi_2) = \frac{\omega - \Delta}{2} \chi_1^2 + \frac{\Delta + \omega}{2} \chi_2^2 + \frac{1}{4} (\chi_1^2 - \alpha \chi_2^2)^2. \quad (12)$$

For localized soliton solutions, $\chi_{1,2}(\infty) \rightarrow 0$, and, hence, $H = 0$. We use the substitution

$$\chi_1(y) = A(y) \cos \varphi(y), \quad \chi_2(y) = A(y) \sin \varphi(y), \quad (13)$$

so that Eq. (12) yields

$$A^2 = \frac{2(\Delta \cos 2\varphi - E)}{(\cos^2 \varphi - \alpha \sin^2 \varphi)^2}. \quad (14)$$

Substituting Eq. (13) into Eq. (11), we obtain an ordinary differential equation for φ that turns out to be independent of α ,

$$\frac{d\varphi}{dy} = -E + \Delta \cos 2\varphi, \quad (15)$$

and has the solution

$$\varphi = \arctan \left[\sqrt{\frac{\Delta - \omega}{\Delta + \omega}} \tanh(\sqrt{\Delta^2 - \omega^2} y) \right]. \quad (16)$$

The final expressions for $\chi_{1,2}$ are obtained by substituting Eqs. (16) and (14) into Eq. (13).

C. Existence and stability analysis

In order to determine the spectral stability of the soliton solution $\chi^{(0)}$, we perform a standard linearization procedure. The solution is sought at the frequency ω' in the form

$$\chi^{(1)} = \chi^{(0)} e^{-i\omega t} + U e^{-i\omega' t} + V e^{+(i\omega' - 2i\omega)t}, \quad (17)$$

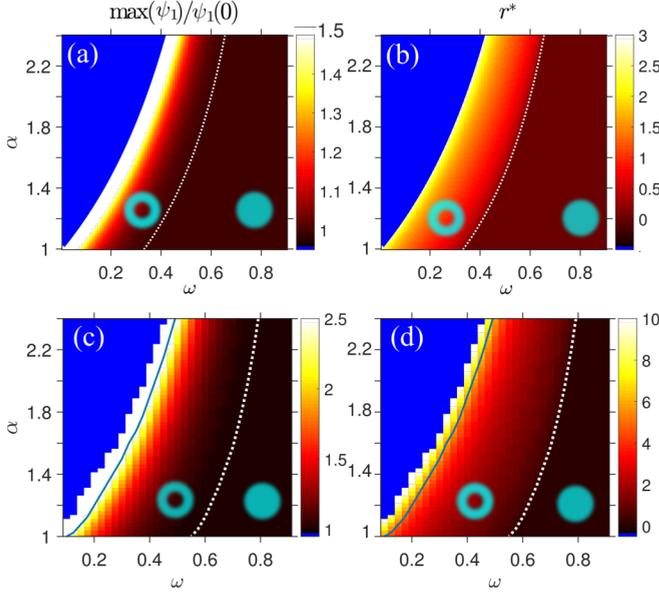


FIG. 3. Shape of the soliton depending on its frequency ω and the nonlinearity asymmetry α . (a),(c) Ratio of the maximum of the component χ_1 at the point r^* to its value at $r = 0$. (b),(d) Position of the soliton maximum r^* . (a) and (b) have been calculated analytically for the 1D soliton solution given by Eq. (13); (c) and (d) correspond to the numerical calculation in 2D. (c),(d) The blue line bounds the region where the soliton is spectrally unstable and, in the blue region, the soliton does not exist. The dotted white line bounds the region where the soliton has a ring shape, i.e., $r^* > 0$. The calculation has been performed for $\Delta = 1$.

where $\chi^{(0)}$ is the unperturbed soliton profile, and the spinors U and V have the form

$$U = \begin{pmatrix} u_1 e^{i(m+m')\varphi} \\ i u_2 e^{i(m+m'-1)\varphi} \end{pmatrix}, \quad V = \begin{pmatrix} v_1 e^{i(m-m')\varphi} \\ i v_2 e^{i(m-m'-1)\varphi} \end{pmatrix}, \quad (18)$$

and m' is the angular momentum of the perturbation. The resulting system of linear equations for the spinors $u = [u_1, u_2]^T$, $v = [v_1, v_2]^T$ reads

$$\omega' \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} H_+ & H_0 \\ -H_0 & 2\omega - H_- \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}, \quad (19)$$

with

$$H_{\pm} = \begin{pmatrix} \Delta + 2a_1\psi_1^2 + b\psi_2^2 & D_{+,m\pm m'} + b\psi_1\psi_2 \\ -D_{-,m\pm m'} + b\psi_1\psi_2 & -\Delta + 2a_2\psi_2^2 + b\psi_1^2 \end{pmatrix},$$

$$H_0 = \begin{pmatrix} a_1\psi_1^2 & b\psi_1\psi_2 \\ b\psi_1\psi_2 & a_2\psi_2^2 \end{pmatrix},$$

where the differential operators are

$$D_{+,m} = \frac{\partial}{\partial r} + \frac{1-m}{r}, \quad D_{-,m} = \frac{\partial}{\partial r} + \frac{m}{r}.$$

The calculated stability and existence diagram for the ring soliton depending on its frequency and nonlinearity asymmetry α is presented in Fig. 3. Figures 3(a) and 3(c) show the relative amplitude of the maximum, $\psi_1(r^*)/\psi_1(0)$, while Figs. 3(b) and 3(d) present the maximum position. We start the analysis from the exact 1D solution, obtained in the previous section. The soliton exists and has a double-hump profile with maxima at

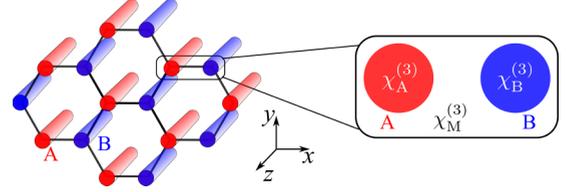


FIG. 4. Schematic of a photonic graphene structure with waveguides having the opposite sign of Kerr nonlinearity than the matrix, $\chi_{A,B}^{(3)}\chi_M^{(3)} < 0$.

$y = \pm r^*$ in the region where

$$\frac{1}{2} \frac{1+\omega}{1-\omega} < \alpha < \frac{1+\omega}{1-\omega}. \quad (20)$$

For lower values of α , the hump disappears and the maximum is in the coordinate origin, i.e., $r^* = 0$. The boundary of the corresponding region is indicated by a black dashed curve. For α larger than $(1+\omega)/(1-\omega)$, the solution does not exist. The main result of the calculation is the possibility to adjust the soliton shape by controlling the nonlinearity. For a given soliton frequency, the increase of the α parameter transforms the ordinary soliton to the double-hump one and enhances the maximum for the ψ_1^* component, in agreement with the calculation in Fig. 1.

Figures 3(c) and 3(d) show the phase diagram for the 2D ring soliton solution. It has qualitatively the same structure as the one in the 1D case. However, the ring soliton region where $r^* > 0$ (bounded by a dotted white curve) is considerably wider in the 2D case than in the 1D case; cf. Figs. 3(b) and 3(d). The blue line indicates the stability region. An increase of the nonlinearity asymmetry first makes the ring soliton unstable and then it ceases to exist. For both symmetric and asymmetric nonlinearity, the instability develops first for the perturbation with $m' = 2$.

III. IMPLEMENTATION IN NONLINEAR LATTICES

Here, we consider a model example of nonlinear photonic graphene based on an array of waveguides arranged in a honeycomb lattice; see Fig. 4. In the linear optical regime, this waveguide platform has already been used to demonstrate topological edge states of light [27,28,47]. Our suggestion is to embed waveguides with defocusing Kerr nonlinearity ($\chi^{(3)} < 0$) in a focusing nonlinear matrix with $\chi^{(3)} > 0$. The tight-binding equations governing the propagation of light in this system along the z direction have the following form:

$$-i \frac{\partial \psi_{A,j}}{\partial z} = E_{A,j} \psi_{A,j} + t \sum_{(j,j')} \psi_{B,j'},$$

$$-i \frac{\partial \psi_{B,j}}{\partial z} = E_{B,j} \psi_{B,j} + t \sum_{(j,j')} \psi_{A,j'},$$

$$E_{A,j} = \Delta + a_1 |\psi_{A,j}|^2 + \frac{b}{3} \sum_{(j,j')} |\psi_{B,j'}|^2,$$

$$E_{B,j} = -\Delta + a_2 |\psi_{B,j}|^2 + \frac{b}{3} \sum_{(j,j')} |\psi_{A,j'}|^2. \quad (21)$$

Here, $\psi_{A,j}$ and $\psi_{B,j}$ are the smooth envelopes of electric field \mathcal{E} at the sites A and B of the unit cell j ; $\mathcal{E}(z,j,t) \propto e^{ik_z z - i\omega t} \psi_j(z)$, where ω is the frequency and k_z is the wave vector along the waveguide axis. The parameter t describes the tunneling, $\sum_{(j,j')}$ denotes the sum over nearest neighbors of the cell j , and Δ is the detuning of the modes of the waveguides A and B and can be controlled by varying the waveguide radii. We consider only the linear tunneling terms but take into account both local ($\alpha a_{1,2}$) and nonlocal (αb) Kerr nonlinearities. Discrete nonlinear lattices manifest interesting phenomena such as self-induced gap soliton formation [48,49]. In the case of Dirac systems with symmetric nonlinearity, the effects of discreteness were recently analyzed in Ref. [25]. For the purpose of this work, it is sufficient to apply the smooth envelope approximation near the Dirac points. We start with the solution of Eqs. (21) in the Bloch form,

$$\psi_{A,j} = \psi_A e^{ik \cdot r_j}, \quad \psi_{B,j} = \psi_B e^{ik \cdot r_j}, \quad (22)$$

which results in

$$\begin{aligned} -i \frac{\partial \psi_A}{\partial z} &= (\Delta + a_1 |\psi_A|^2 + b |\psi_B|^2) \psi_A + g_k \psi_B, \\ -i \frac{\partial \psi_B}{\partial z} &= (-\Delta + a_2 |\psi_B|^2 + b |\psi_A|^2) \psi_B + g_k^* \psi_A, \end{aligned} \quad (23)$$

where $g_k = t[e^{ik_x d} + 2e^{-ik_x d/2} \cos(k_y d)]$ and d is the distance between nearest neighbors. Applying the $\mathbf{k} \cdot \mathbf{p}$ expansion near the Dirac points

$$\kappa_x = k_x, \quad \kappa_y = k_y \mp \frac{4\pi\sqrt{3}}{9d}, \quad (24)$$

we obtain the following equations:

$$\begin{aligned} -i \frac{\partial \psi_A}{\partial z} &= (\Delta + a_1 |\psi_A|^2 + b |\psi_B|^2) \psi_A + v(i\kappa_x \mp \kappa_y) \psi_B, \\ -i \frac{\partial \psi_B}{\partial z} &= (-\Delta + a_2 |\psi_B|^2 + b |\psi_A|^2) \psi_B - v(i\kappa_x \pm \kappa_y) \psi_A, \end{aligned} \quad (25)$$

where $v = 3t/2$ and the sign \pm corresponds to two different valleys. In the smooth envelope approximation, when κ is replaced by $-i\nabla$, Eqs. (25) are equivalent to the nonlinear Dirac equations (1) and (2) for each of the two valleys. The condition $a_{1,2}b < 0$, required for the ring Dirac soliton formation, can be realized by controlling the nonlinear response of the waveguides and of the matrix. Namely, defocusing nonlinearity in each of the waveguides, $\chi_{A,B}^{(3)} < 0$, decreases the wave vector along z and, hence, $a_1, a_2 < 0$. On the other hand, the nonlocal Kerr term results from the spatial overlap between the evanescent tails of the electric fields from neighboring waveguides, penetrating in the matrix. Thus, when the matrix has a focusing Kerr nonlinear response with $\chi_M^{(3)} > 0$, increase of the field intensity in the given waveguide will increase the wave vector for its neighbors and, hence, $b > 0$.

A very promising theoretical result of the chiral polariton vortex propagation in the honeycomb lattice of micropillars along the interface was recently reported in Ref. [36]. The interface bounds two regions with inverted staggering, $E_A < E_B$ and $E_B > E_A$. In our case, the staggering is not built in the linear structure, but arises due to the interplay of focusing and defocusing nonlinearity.

Implementation of the cubic nonlinearity with modulated sign seems to be a challenging but feasible task; see a detailed review in Ref. [50]. For example, one could consider an optofluidic platform [51,52] with photonic crystal fibers filled by liquids. Strong fast focusing nonlinearity is available in chalcogenide glass fibers [53]. Chalcogenide waveguides with high nonlinear refractive index $n_2 \sim 4 \times 10^{-14} \text{ cm}^2/\text{W}$ [54] have enabled demonstration of self-focusing for cm-long samples at the $1.5 \mu\text{m}$ wavelength [55]. The main difficulty would be to balance the focusing nonlinearity of the fiber material with slow but strong thermal defocusing nonlinearity of the liquids, where values up to $n_2 = -1.6 \times 10^{-5} \text{ cm}^2/\text{W}$ have been reported [56]. In the pulsed regime, this could be done by controlling the repetition rate. Alternatively, one could consider solutions where the thermal defocusing nonlinearity is relatively weak, $n_2 \sim -10^{-13} \text{ cm}^2/\text{W}$ [57]. In addition to the photonic crystal waveguide platform, similar effects could potentially be realized for excitonic polaritons in arrays of coupled micropillars with embedded quantum wells [2] and for cold-atom lattices [3] with nonlinearity controlled by Feshbach resonances [58].

IV. CONCLUSION

To summarize, we have theoretically studied rotationally symmetric soliton solutions of a two-dimensional nonlinear Dirac equation with asymmetric cubic nonlinearity. It has been demonstrated that the radial distribution of the soliton amplitude strongly depends on the nonlinearity parameters. By adjusting the nonlinearity, we were able to find a spectrally stable ring Dirac solution where both spinor components of the soliton have maxima at a certain radius. The radial localization is explained by the crossing of the band-gap edges in the Dirac equation, induced by the nonlinearity. Hence, the obtained solution can be interpreted as a self-induced nonlinear domain wall. A condition relating the radial localization degree to the nonlinearity parameters has been derived. We present a conceptual scheme to realize a ring Dirac soliton in a nonlinear photonic graphene lattice with defocusing waveguides in the focusing matrix or vice versa. Remarkably, the formation of solitons at the self-induced domain walls is intuitively quite similar to the localization of edge states at the boundary between domains with distinct topological invariants. However, despite detailed studies of edge modes in nonlinear lattices [50], no topological classification comparable with the established classification of topological insulators [59] is available for nonlinear edge states. Still, even though generalizations of the Berry phase in nonlinear systems are known [60], the possibility of rigorous nonlinear bulk-boundary correspondence remains an open question. We believe that our model can be applicable to a variety of nonlinear topological systems spanning from photonics to cold-atom lattices and could provide important insights for further developments in the nonlinear topological physics.

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