Nonequilibrium atom-surface interaction with lossy multilayer structures

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The impact of lossy multilayer structures on nonequilibrium atom-surface interactions is discussed. Specifically, the focus lies on a fully non-Markovian and nonequilibrium description of quantum friction, the fluctuationinduced drag force acting on an atom moving at constant velocity and height above the multilayer structures. Compared to unstructured bulk material, the drag force for multilayer systems is considerably enhanced and its behavior as a function of both the atom's velocity and distance from the surface exhibits different regimes. These features are linked to the appearance of coupled interface polaritons within the superlattice structures. Our results are not only useful for an experimental investigation of quantum friction but also highlight a way to tailor the interaction by simply modifying the structural composition of the multilayer systems.

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I. INTRODUCTION

The notion of vacuum changed dramatically after the rise of quantum mechanics. The existence of quantum fluctuations even at zero temperature and the possibility of structuring the vacuum has led to the discovery of many new interesting phenomena. In this context many vacuum fluctuation-induced interactions such as the Casimir and Casimir-Polder effect [1] have been investigated. Strongly related to the Casimir-Polder force is quantum friction, a drag force that even at zero temperature opposes the relative motion of two or more objects in vacuum [2]. One of the most studied configurations consists of an atom (or a microscopic object) moving parallel to a surface at constant height and velocity [3-6]. In such a system, quantum friction has a simple interpretation in terms of the interaction between the moving microscopic object and its image within the material below. The motion of the image is delayed due to the frequency dispersion of the material permittivity, leading to both a modification of the equilibrium Casimir-Polder force perpendicular to the surface and a component of the force parallel to the surface that opposes the motion. Already in this simple picture, we can intuitively understand the relevance of two mechanisms at work in the quantum frictional process: The strength of the coupling between the microscopic object and its image and the resistance felt by the image when dragged through the material. The latter can be related to the dynamics of the charge carriers within the material composing the substrate and, in particular to its resistivity. Instead, the coupling strength strongly depends on the electromagnetic densities of states characterizing the system. Altering either one of these aspects will eventually lead to a modification of quantum friction. A currently popular class of systems where this can be implemented is nanostructured substrate materials [7–9]. In the framework of fluctuation-induced forces, they have already been considered both in theoretical analyses (see, for example, Refs. [3,10–13]) and in experiments [14–18]. One prominent example is given by nanoscaled multilayer structures, where a specific pattern of distinct layers are repeatedly stacked

forming a superlattice [19-21]. When carefully designed, they are known for exhibiting effective hyperbolic dispersion relations [20,22,23], which have applications in many fields of research [24–26]. In the present work, we investigate how the characteristic behavior of quantum friction and specifically its strength and functional dependence on the velocity and position of the atom is modified when the planar medium is a two-component superlattice of alternating layers with metallic and dielectric properties. The paper is organized as follows. In Sec. II, we briefly review the theory of quantum friction, highlighting the features connected with the properties of the surface, which can lead to a modification of the interaction through nanostructuring. We introduce in Sec. III our material models, analyzing the properties and the physical parameters, which are relevant to the quantum frictional process. Finally, in Sec. IV, we merge the insights of the previous two sections and explicitly calculate the quantum frictional force on an atom moving above a superlattice.

II. QUANTUM FRICTION

Physically, quantum friction can be derived from the Lorentz force: If we choose the z axis to be perpendicular to the surface (see Fig. 1), the force lies in the (x, y) plane against the direction of motion. This means that if the atom moves at constant height z_a above a flat surface with constant velocity **v**, then $\mathbf{F} = F\mathbf{v}/v$ ($v = |\mathbf{v}|$) [2]. In our description, the atom is described in terms of a time-dependent dipole operator $\hat{\mathbf{d}}(t)$: For simplicity, we further assume a rigid dipole configuration $\hat{\mathbf{d}}(t) = \mathbf{d}\hat{q}(t)$, where **d** is the static dipole vector and $\hat{q}(t)$ describes the dipole's internal dynamics. For systems at temperature T = 0, it has been shown [2,27] that the quantum frictional force **F** is given as

$$\mathbf{F} = -2\int_0^\infty d\omega \int \frac{d^2\mathbf{k}}{(2\pi)^2} \mathbf{k} \operatorname{Tr}[\underline{S}(\mathbf{k} \cdot \mathbf{v} - \omega; \mathbf{v}) \cdot \underline{G}_I(\mathbf{k}, z_a, \omega)].$$
(1)



FIG. 1. A schematic description of the system considered in this work. An atom (or microscopic object) moves at constant velocity and constant height above a half-space made by periodic sequence of alternating conductive (ϵ_A) and dielectric (ϵ_B) layers with corresponding thicknesses d_A and d_B . The spectrum of vacuum fluctuations is structured through the properties of the multilayered structure and gives rise to a nonequilibrium atom-surface interaction, which opposes the motion of the atom. This quantum frictional force is affected by the appearance of electromagnetic resonances due to the interlayer interaction of plasmon-polaritons at the dielectric-metal interfaces and can be tailored by acting on the geometry and the material properties of the individual layers.

Here, \mathbf{k} is the component of the wave vector parallel to the surface, <u>G</u> is the Fourier transform with respect to the planar coordinates of the electromagnetic Green's tensor. The tensor

$$\underline{S}(\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\tau \ e^{i\omega\tau} \ \langle \hat{\mathbf{d}}(\tau) \hat{\mathbf{d}}(0) \rangle_{\text{NESS}}$$
(2)

represents the power spectrum corresponding to the dipoledipole correlator for the system's nonequilibrium steady state (NESS) and describes the strength of the fluctuations affecting the atomic system. The subscripts *I* and *R* appearing in the previous and the following expressions denote the real and the imaginary part of the quantities they are appended to (e.g., $\underline{G}_I = \text{Im}\{\underline{G}\}, \underline{G}_R = \text{Re}\{\underline{G}\}$, etc.). Assuming that $\hat{q}(t)$ can be described in terms of a harmonic oscillator, the power spectrum can be written as [28]

$$\underline{S}(\omega; \mathbf{v}) = \frac{\hbar}{\pi} \theta(\omega) \underline{\alpha}_{I}(\omega; \mathbf{v}) + \frac{\hbar}{\pi} \underline{J}(\omega; \mathbf{v}), \qquad (3)$$

where $\underline{\alpha}(\omega; \mathbf{v})$ is the velocity-dependent dressed atomic polarizability (see Appendix A). The first term on the right-hand side (r.h.s.) corresponds to the result one would obtain using the so-called local thermal equilibrium (LTE) approximation. Within this approximation, it is assumed that the atom is in equilibrium with its immediate surroundings, allowing the application of the fluctuation-dissipation theorem [29]. The locally equilibrated atom is subsequently coupled to the substrate material. However, a full nonequilibrium description yields the additional term $\underline{J}(\omega; \mathbf{v})$, which substantially contributes to the quantum frictional process (see Appendix A and Refs. [27,28,30]).

The physics of quantum friction is connected to that of the quantum Cherenkov effect through the anomalous Doppler effect [2,4,31]. In simple terms, we have that, through the Doppler shift appearing in Eq. (1), this process brings negative frequencies of the electromagnetic spectrum into the integration region, which is physically relevant for the interaction. Previous work has shown that, depending on the atom's velocity, quantum friction is characterized by the combination of a nonresonant and a resonant contribution. The resonant part occurs when the system's resonances, such as atomic transition frequencies or polaritonic surface modes existing at the vacuum-substrate interface, participate in the interaction. Usually, they become relevant only for velocities high enough to generate a Doppler shift, which displaces the resonances into the aforementioned relevant frequency range. As a rough rule of thumb, this occurs for $v/z_a > \omega_r$, where ω_r is the resonance frequency under consideration. Similarly, the nonresonant part gives the dominant contribution for the force at low velocities and is directly related to the low-frequency optical response of the substrate. Specifically, this region is strongly affected by the dissipative behavior of the material(s) composing the substrate. In this nonresonant regime the force is to a good approximation described by

$$\mathbf{F} \approx -2\frac{\hbar}{\pi} \int \frac{d^2 \mathbf{k}}{(2\pi)^2} \,\mathbf{k} \,\theta(\mathbf{k} \cdot \mathbf{v}) \int \frac{d^2 \tilde{\mathbf{k}}}{(2\pi)^2} \int_0^{\mathbf{k} \cdot \mathbf{v}} d\omega \,\mathrm{Tr}[\underline{\alpha}_0 \cdot \underline{\sigma}_I(\tilde{\mathbf{k}}, z_a, [\mathbf{k} + \tilde{\mathbf{k}}] \cdot \mathbf{v} - \omega)] \mathrm{Tr}[\underline{\alpha}_0 \cdot \underline{\sigma}_I(\mathbf{k}, z_a, \omega)] -2\frac{\hbar}{\pi} \int \frac{d^2 \mathbf{k}}{(2\pi)^2} \,\mathbf{k} \int \frac{d^2 \tilde{\mathbf{k}}}{(2\pi)^2} \theta(\tilde{\mathbf{k}} \cdot \mathbf{v}) \int_{\mathbf{k} \cdot \mathbf{v}}^{[\mathbf{k} + \tilde{\mathbf{k}}] \cdot \mathbf{v}} d\omega \,\mathrm{Tr}[\underline{\alpha}_0 \cdot \underline{\sigma}_I(\tilde{\mathbf{k}}, z_a, [\tilde{\mathbf{k}} + \mathbf{k}] \cdot \mathbf{v} - \omega) \cdot \underline{\alpha}_0 \cdot \underline{\sigma}_I(\mathbf{k}, z_a, \omega)].$$
(4)

Here, the dyadic $\underline{\alpha}_0 = \mathbf{d}\mathbf{d}$ describes the static polarizability for our model. In the above expression we have also used that, due to the properties of the trace and of the polarizability, we can replace the Green's tensor by its (symmetric) diagonal part, $\underline{\sigma}(\mathbf{k}, z_a, \omega)$. Since quantum friction strongly decays with increasing atom-surface separation (see also Sec. IV), the dominant contribution of the above expressions come from the system's near-field region. In this region $\underline{\sigma}(\mathbf{k}, z_a, \omega)$ can be written as

$$\underline{\sigma}(\mathbf{k}, z_a, \omega) \approx r^p(\omega, k) \operatorname{diag}\left[\frac{k_x^2}{k^2}, \frac{k_y^2}{k^2}, 1\right] \frac{ke^{-2kz_a}}{2\epsilon_0}.$$
 (5)

Here, ϵ_0 is the vacuum permittivity, $k = |\mathbf{k}|$, and $r^p(\omega, k)$ is the reflection coefficient of the substrate for the *p*-polarized electromagnetic radiation.

The previous equations show that the quantum frictional interaction is mainly connected with the *p*-polarized electromagnetic field (the s-polarized field gives a small contribution of the order v^2/c^2 , with c the speed of light) and is dominated by wave vectors $k \lesssim 1/z_a$ and frequencies $0 < \omega \lesssim v/z_a$. It is interesting to note that, if in this regime we can write $r_I^p(\omega,k) \approx 2(\omega\epsilon_0)^n \rho_n(k)$, Eq. (4) gives a velocity dependence $\dot{F} \propto v^{2n+1}$, while the distance dependence is related to the detail of the generalized resistivity $\rho_n(k)$. For n = 1 one speaks of ohmic materials, while n < 1 and n > 1 indicate, respectively, subohmic and superohmic behavior. This feature has been connected to the non-Markovian properties of the electromagnetic atom-surface interaction [2,27] and explains why many of the authors have obtained $F \propto v^3$ for the lowvelocity asymptotic expression of the quantum frictional force on an atom moving above a substrate made of a homogeneous (ohmic) material [5]. Since the nature of the planar medium determines the functional dependence of the force, tailoring the properties of the substrate allows for a control of the interaction.

III. ELECTROMAGNETIC SCATTERING NEAR NANOSTRUCTURES

The above expressions highlight the dependence of the quantum frictional force on the optical response of the substrate and show the important role of the reflection coefficients of the substrate. The literature offers many different approaches for calculating these quantities for nanostructures. However, most of the papers focus on frequency ranges, wave vectors and, in general, material characteristics, which are not those that are relevant for the evaluation of the quantum frictional force. In order to define the notation and give a consistent framework to our considerations, we present in this section an analysis, which focuses on these aspects.

We start by considering the expression for the reflection coefficients of a flat surface. In general, they can be written as [32]

$$r^{\sigma}(\omega,k) = \delta^{\sigma} \frac{Z_0^{\sigma}(\omega,k) - Z_m^{\sigma}(\omega,k)}{Z_0^{\sigma}(\omega,k) + Z_m^{\sigma}(\omega,k)},\tag{6}$$

where the index $\sigma = s, p$ denotes the polarization state of light and we have introduced $\delta^{s/p} = \mp$. Further $Z_m^{\sigma}(\omega,k)$ and $Z_0^{\sigma}(\omega,k)$ denote, respectively, the surface impedance for the substrate material and the material surrounding it (for simplicity, in the subsequent discussions, we assume this material to be vacuum). The surface reflection coefficients are sensitive to the substrate material properties and the geometry of the system. For our forthcoming analyses, it is interesting to consider first the case of a slab of thickness *D* suspended in vacuum and made by a homogeneous material characterized by the spatially local complex permittivity function $\epsilon(\omega)$ [33]. In this case Eq. (6) simplifies as follows [34]:

$$r_{\text{slab}}^{\sigma}(\omega,k) = r_{\text{bulk}}^{\sigma}(\omega,k) \frac{1 - e^{2ik_z D}}{1 - \left[r_{\text{bulk}}^{\sigma}(\omega,k)e^{ik_z D}\right]^2},$$
(7)

where $k_z = \sqrt{\epsilon(\omega)\frac{\omega^2}{c^2} - k^2}$ (Im $\{k_z\} \ge 0$, Re $\{k_z\} \ge 0$), and $r_{\text{bulk}}^{\sigma}(\omega,k)$ is the interface reflection coefficient given by the usual Fresnel expressions [35]. For a spatially local,



FIG. 2. Dispersion relations of the symmetric and antisymmetric surface plasmon-polariton modes of a slab of thickness *D* consisting of a material described by a Drude model without dissipation, i.e., $\epsilon(\omega) = 1 - \omega_p^2/\omega^2$. For $kD/2 \gg 1$ both modes merge to the surface plasmon polariton at ω_{sp} for a half-space problem.

isotropic, and homogeneous substrate material we have that the impedance in Eq. (6) can be written as

$$Z_{\rm m}^{s}(\omega,k) \equiv Z_{\rm bulk}^{s}(\omega,k) = \frac{\frac{\omega^{2}}{c^{2}}}{\sqrt{\frac{\omega^{2}}{c^{2}}\epsilon(\omega) - k^{2}}},$$
(8a)

$$Z_{\rm m}^{p}(\omega,k) \equiv Z_{\rm bulk}^{p}(\omega,k) = \frac{\sqrt{\frac{\omega^{2}}{c^{2}}}\epsilon(\omega) - k^{2}}{\frac{\omega^{2}}{c^{2}}\epsilon(\omega)}, \qquad (8b)$$

while $Z_0^{\sigma}(\omega, k)$ can be obtained for our vacuum by setting $\epsilon(\omega) \equiv 1$. The exponential in Eq. (7) represents the phase that is accumulated via the propagation and decay through the slab. The coefficient $r_{\text{slab}}^{\sigma}(\omega, k)$ is characterized by two resonances, physically related to the interaction between the surface polaritons existing on either side of the slab [36,37]. This is best seen in the near-field region, where just one of the two polarizations contributes to the scattering process and the reflection coefficients $r_{\text{bulk}}^{\sigma}(\omega, k)$ take on the form

$$r_{\text{bulk}}^{p}(\omega,k) \approx \frac{\epsilon(\omega)-1}{\epsilon(\omega)+1}, \quad r_{\text{bulk}}^{s}(\omega,k) \approx 0.$$
 (9)

The dispersion relations of the above-mentioned polaritonic modes are given by the solutions of (see also Fig. 2)

$$\epsilon(\omega) = -\begin{cases} \coth\left(\frac{kD}{2}\right) & \to \text{ symmetric} \\ \tanh\left(\frac{kD}{2}\right) & \to \text{ antisymmetric.} \end{cases}$$
(10)

The two coupled surface polaritons are labeled symmetric and antisymmetric in relation to the properties of the electric fields they are associated with. Due to the different field distributions within the slab, the symmetric polariton has a lower energy (or frequency) than antisymmetric, with the uncoupled surface polariton's energy lying in between both. The splitting between of the symmetric and the antisymmetric surface polariton increases as 1/kD and it is, therefore, more pronounced for thin slabs, for which the coupling between the surface excitations is stronger. If different dielectric materials were used below and above the slab, additional leaky modes would come into play as elaborated in Ref. [38]. The solutions of Eq. (10) are clearly visible in the imaginary part of the reflection coefficient as shown in Fig. 3, where they are also compared to the resonance of a semi-infinite homogeneous substrate. In Fig. 3 we consider



FIG. 3. Frequency dependence of the imaginary part of the reflection coefficient in the near-field limit. Two geometries with the same Drude material [Eq. (11)] are considered: A semi-infinite bulk (dotted red line) and a finite slab (solid black line). As parameters we chose typical values for gold [40] $\omega_p = 9 \text{ eV}$ and $\gamma = 35 \text{ meV}$, $\epsilon_A^{\infty} = 1$, a slab thickness of $D = 2 \text{ nm} \approx 10^{-3} c/\omega_p$ and $k = \omega_p/c$. For the half-space case, a resonance appears at the frequency $\omega_{sp} \approx \omega_p/\sqrt{2}$, while for the slab two resonances are visible, one above, the other below ω_{sp} .

a metal described by the Drude model

$$\epsilon(\omega) = \epsilon^{\infty} - \frac{\omega_{\rm p}^2}{\omega(\omega + i\gamma)},\tag{11}$$

where $\epsilon^{\infty} > 0$ describes the response of the material at large frequencies, γ denotes a phenomenological damping constant, and $\omega_{\rm p}$ the plasma frequency. In this case the resonances in the reflection coefficient are associated with the so-called surface plasmon polaritons. For a bulk-vacuum interface, in the near-field limit, the resonance is located at $\omega_{\rm sp} = \omega_{\rm p}/\sqrt{1 + \epsilon^{\infty}}$, while in the case of the slab they depend on the wave vector and both tend to $\omega_{\rm sp}$ for $kD \to \infty$.

Notice that, in Fig. 3 the behavior at low frequencies (i.e., frequencies much smaller than the resonance frequency) is similar for both the bulk and the slab and describe an ohmic response of both structures. Indeed, in this region, assuming that the material composing the slab or the bulk is ohmic, an expansion of the imaginary part of the reflection coefficient gives

$$r_I^p(\omega,k) \stackrel{\omega \ll \omega_{\rm sp}}{\approx} \omega \epsilon_0 \begin{cases} 2\rho & \text{for bulk} \\ 2\rho \coth[Dk] & \text{for slab} \end{cases}$$
(12)

Here, ρ represents the material resistivity $[\rho = \gamma/(\epsilon_0 \omega_p^2)]$ for the Drude model]. Notice that, since k > 0, the imaginary part of the reflection coefficient at low frequencies increases with thinner slabs. In addition, we would have obtained the same result even if the ohmic layer were deposited above a dielectric bulk instead of being suspended in vacuum. These results can be understood in relation to the behavior the symmetric polaritonic resonance, which in case of metals is sometimes called short-range plasmon polaritons [37,39]. The field corresponding to the symmetric mode is indeed more confined within the slab material and thus exhibits a stronger dissipative response than both the single-interface resonance (bulk reflection coefficient) and the antisymmetric mode (which is sometimes also referred to as the long-range plasmon polaritons [37,39]). For a superlattice structure made by a semi-infinite stack of alternating layers of two different materials (labeled A and B hereafter) with respective thickness $d_{\rm A}$ and $d_{\rm B}$ [41], the expressions for the reflection coefficients become more involved. To calculate them we need to replace the surface impedance in Eq. (6) with that of the superlattice, $Z_{\sup}^{\sigma}(\omega,k)$. This can be calculated through the transfer matrix formalism [42]. Within this approach, one propagates the electromagnetic field through each layer and fulfills the boundary conditions at each interface. For instance, the propagation through the layer A is given by

$$\begin{pmatrix} \mathbf{E} \\ c \mathbf{B} \end{pmatrix}_{z=z_0^-+d_{\mathrm{A}}}^{\sigma} = \mathbb{M}_{\mathrm{A}}^{\sigma}(d_{\mathrm{A}}) \begin{pmatrix} \mathbf{E} \\ c \mathbf{B} \end{pmatrix}_{z=z_0^-}^{\sigma}, \quad (13)$$

where z_0^- indicates the position directly in front of the interface. The transfer matrix through the local material A reads

$$\mathbb{M}_{A}^{\sigma}(d_{A}) = \begin{pmatrix} \cos\left(k_{z}^{A} d_{A}\right) & i \delta^{\sigma} \sin\left(k_{z}^{A} d_{A}\right) Z_{A}^{\sigma} \\ i \delta^{\sigma} \sin\left(k_{z}^{A} d_{A}\right) / Z_{A}^{\sigma} & \cos\left(k_{z}^{A} d_{A}\right) \end{pmatrix}.$$
(14)

For nonlocal materials the transfer matrix takes a different form and explicit expressions can be found in Ref. [43]. If we stack the layers A and B we can describe the propagation through the combined block of thickness $d_{sl} = d_A + d_B$ with the transfer matrix $\mathbb{T} = \mathbb{M}_B \mathbb{M}_A$ or $= \mathbb{M}_A \mathbb{M}_B$, depending on the stacking sequence [23]. Using the Bloch theorem [44] for periodic structures, we obtain [45]

$$Z_{\sup}^{\sigma}(\omega,k) = \frac{\mathbb{T}_{12}^{\sigma}}{\exp(i\beta^{\sigma}d_{\mathrm{sl}}) - \mathbb{T}_{11}^{\sigma}} = \frac{\exp(i\beta^{\sigma}d_{\mathrm{sl}}) - \mathbb{T}_{22}^{\sigma}}{\mathbb{T}_{21}^{\sigma}} \quad (15)$$

The Bloch wave vector β^{σ} can be related to the other parameters of the system through the implicit dispersion relation

$$\cos(\beta d_{\rm sl}) = \cos\left(k_z^{\rm A} d_{\rm A}\right) \cos\left(k_z^{\rm B} d_{\rm B}\right) - \frac{1}{2} \left(\frac{\epsilon_{\rm A} k_z^{\rm B}}{\epsilon_{\rm B} k_z^{\rm A}} + \frac{\epsilon_{\rm B} k_z^{\rm A}}{\epsilon_{\rm A} k_z^{\rm B}}\right)$$
$$\times \sin\left(k_z^{\rm A} d_{\rm A}\right) \sin\left(k_z^{\rm B} d_{\rm B}\right). \tag{16}$$

Since most of our considerations will address the p polarization (see the discussion above), we drop hereafter the superscript (analogous expressions hold for the s polarization). In addition, we focus on systems composed of alternating conducting and dielectric layers, where the stacking sequence starts with a conducting layer.

Similarly to the coupled surface polaritons found in the slab, an ensemble of excitations linked to the interaction among all the interface modes of the stacking sequences appears in the superlattice system. We refer to this ensemble as collective interface plasmon polaritons (CIPPs) and their electromagnetic behavior at the vacuum-superlattice interface is, to some extent, similar to that of bulk plasmons occurring in the nonlocal description of metals [36,46,47].

Indeed, nanostructuring adds to the optical response of the medium certain features, which are mathematically reminiscent of spatial nonlocality, although the individual constituents are described in terms of a spatially local permittivity [48]. However, in contrast to bulk plasmons in nonlocal metals, the CIPP fields inside the nanostructured materials are always transverse. In the near-field approximation their dispersion relations are solutions of (see Ref. [36])

$$\frac{\epsilon_{\rm A}(\omega)}{\epsilon_{\rm B}(\omega)} = -C(k,\beta) \pm \sqrt{C^2(k,\beta) - 1},\tag{17}$$



FIG. 4. Top: Dispersion relation of the ω_{-} branch on a double logarithmic scale. The thick black solid lines mark the edges of the branch with $\beta d_{sl} = 0, \pi$. Some intermediate values for the Bloch vector are also represented (dashed gray lines). The shaded area refers to a region, where the modes become overdamped. For different values of β , the value of $k_0(\beta)$, below which the modes become overdamped, varies and shifts to lower k for higher β . Bottom: Negative imaginary part of the ω_{-} modes. A clearly visible jump occurs for $k \sim k_0(\beta)$ and the damping increases from $\gamma/2$ to γ . Inset: Dispersion relation of the ω_{\pm} branches, again with the different lines referring to different values of β , in analogy to the top panel.

where

$$C(k,\beta) = \frac{\cosh(kd_{\rm A})\cosh(kd_{\rm B}) - \cos(\beta d_{\rm sl})}{\sinh(kd_{\rm A})\sinh(kd_{\rm B})}.$$
 (18)

Adopting the notation used in Ref. [36], we write $C(k,\beta) = \sqrt{C^2(k,\beta) - 1} = \exp[\pm \psi(k,\beta)]$. Upon using the Drude model as in Eq. (11) for material A (metal) and a dielectric constant for material B [49], the explicit dispersion relation reads

$$\omega_{\pm}(k,\beta) = -\frac{i\gamma}{2} + \sqrt{\frac{\omega_{\rm p}^2}{\epsilon_{\rm A}^\infty + \epsilon_{\rm B} \exp[\mp\psi(k,\beta)]}} - \frac{\gamma^2}{4}.$$
 (19)

The ω_+ denote two different branches of possible solutions of Eq. (17). Similar to the result of Eq. (10) for slabs, the two branches can be associated with symmetric (ω_{-}) and antisymmetric (ω_+) modes. In fact, depending on the number of supercells, a finite superlattice structure exhibits many distinct symmetric and antisymmetric modes parametrized by discrete values of the Bloch vector [50]. When the periodic pattern is repeated an infinite number of times, the distinct lines of a finite superlattice structure blur into a continuum [36] (see Fig. 4). Within such a limit, the real part of the Bloch vector β_R continuously varies within the Brillouin zone $[0,\pi/d_{\rm sl}]$, while the imaginary part β_I has to be positive in order to obtain a decaying field away from the surface. For nondissipative material, as a function of the Bloch vector each branch spans two areas on the (k,ω) plane, which characterize the continua of the symmetric and antisymmetric modes. These

areas are bounded by the curves obtained from Eq. (19) for $\beta = 0$ and $\beta = \pi/d_{sl}$. Due to damping within the metallic material some of the low-frequency modes belonging to the symmetric ω_{-} branch become overdamped for small wave

vectors. This occurs for the ω_{-} branch for $(kd_{sl} \ll 1; \text{see Fig. 4})$

$$k < k_0(\beta) = \frac{\gamma}{\omega_p} \sqrt{\epsilon_{\rm B} \frac{1 - \cos(\beta d_{\rm sl})}{2d_{\rm A} d_{\rm B}}}.$$
 (20)

In this overdamped region, the modes exhibit a purely imaginary frequency. For example, the lower boundary of the ω_{-} branch obtained for $\beta = \pi/d_{sl}$ tends to $-i\gamma$ for $k < k_0(\pi/d_{sl})$. For $\beta = 0$, the frequencies is pure imaginary only for k = 0, indicating that the frequency of the modes near the upper bound of the ω_{-} branch and the lower bound of the ω_{+} branch have a nonvashing real part for all wave vectors.

Composite nanostructures such as those discussed above are often described through the so-called effective medium approximation (EMA) [51]. This approach relies on the fact that for wavelengths larger than the characteristic geometric length scale of the system (in our case, the thickness of the supercell $d_{\rm sl}$), the electromagnetic field cannot resolve the details of the system. Instead, the electromagnetic field effectively averages the structural details so that the nanostructures can be described through an effective dielectric function. This approach drastically simplifies the description of complex nanostructures, revealing features, which are often obscured by an involved mathematical machinery. Depending on the geometry of the composite system, the resulting effective dielectric function may indeed exhibit properties that are different from those of the constitutive elements. For instance, for our superlattice structures, the EMA describes the system as an uniaxial crystal with a dielectric tensor $\underline{\epsilon}_{\text{EMA}}(\omega) = \text{diag}[\epsilon_{\perp}(\omega), \epsilon_{\parallel}(\omega), \epsilon_{\parallel}(\omega)]$ whose entries are given by [20,45]

$$\epsilon_{\perp}(\omega) = \epsilon_{\rm A}(\omega) f + \epsilon_{\rm B}(\omega) (1 - f), \qquad (21a)$$

$$\epsilon_{\parallel}(\omega) = \left[\frac{f}{\epsilon_{\rm A}(\omega)} + \frac{1-f}{\epsilon_{\rm B}(\omega)}\right]^{-1},\tag{21b}$$

where $f = d_A/d_{sl}$ gives the filling factor of material A. Equations (21) correspond to the propagation of the electromagnetic field parallel (ϵ_{\parallel}) or orthogonal (ϵ_{\perp}) to the optical axis of the crystal, in our case the *z* axis. Compared to an isotropic bulk material, in an uniaxial crystal the dielectric response differs along the different principal axes. Specifically, in uniaxial crystals with the optical axis perpendicular to the surface, ordinary waves are associated with the *s* polarization, whereas extraordinary waves are associated with the *p* polarization [52]. For such systems, the surface impedances are sensitive to the anisotropy and are given by [53]

$$Z_{\text{EMA}}^{s}(\omega,k) = \frac{\frac{\omega^{2}}{c^{2}}}{\sqrt{\frac{\omega^{2}}{c^{2}}\epsilon_{\perp}(\omega) - k^{2}}}$$
(22a)

$$Z_{\text{EMA}}^{p}(\omega,k) = \frac{\sqrt{\frac{\omega^{2}}{c^{2}}\epsilon_{\parallel}(\omega) - k^{2}}}{\frac{\omega^{2}}{c^{2}}\sqrt{\epsilon_{\perp}(\omega)\epsilon_{\parallel}(\omega)}}.$$
 (22b)



FIG. 5. Limiting behavior of the superlattice's reflection coefficient (*p* polarization) versus the full calculation. The imaginary part of the reflection coefficient is plotted as a function of ω . The conducting material's dielectric function, $\epsilon_A(\omega)$, is described by a Drude model with the same parameters as in Fig. 3. The dielectric is vacuum ($\epsilon_B = 1$), while the filling factor and the wave vector are set to f = 0.2 and $k = 10^{-1}c/\omega_p$. The full tranfer-matrix-based calculation exhibits features, which can be directly connected to the continuum of modes in the ω_{\pm} branches. For frequencies ω higher than the lower bound of the ω_{-} branch, the EMA calculation (dashed black line) shows a very good agreement with the transfer-matrix approach (solid red line). At small frequencies ω , the full transfer-matrix calculation is equivalent to the behavior of the very first conducting layer of the structure (gray dotted line). The shaded areas represent the hyperbolic regime with Re{ $\epsilon_{\perp}(\omega)$ }Re{ $\epsilon_{\parallel}(\omega)$ } < 0.

In the near field, the corresponding reflection coefficients take on the form

$$r_{\text{EMA}}^{p}(\omega,k) \approx \frac{\epsilon_{\text{eff}}(\omega) - 1}{\epsilon_{\text{eff}}(\omega) + 1}, \quad r_{\text{EMA}}^{s}(\omega,k) \approx 0,$$
 (23)

where we have introduced the effective dielectric function as the geometric mean of the perpendicular and parallel components of the dielectric according to $\epsilon_{\text{eff}}(\omega) = \sqrt{\epsilon_{\parallel}(\omega)\epsilon_{\perp}(\omega)}$.

If we now consider the case where $|\epsilon_A(\omega)| \gg |\epsilon_B(\omega)|$ we can, for a certain frequency range, reduce this effective dielectric function to

$$\epsilon_{\rm eff}(\omega) \approx \sqrt{\frac{f}{1-f}} \epsilon_{\rm A}(\omega) \epsilon_{\rm B}(\omega)} = \sqrt{\frac{d_{\rm A}}{d_{\rm B}}} \epsilon_{\rm A}(\omega) \epsilon_{\rm B}(\omega)}.$$
 (24)

If in this limit $\epsilon_{\rm B} > 0$ is a constant [49], then $\epsilon_{\rm eff}(\omega) \propto \sqrt{\epsilon_{\rm A}(\omega)}$. In essence, this yields a criterion when the EMA provides a significant deviation from the ordinary optical response of a bulk system made purely by the material A. To see this more clearly, consider, as an example, an ohmic material, which at low frequencies behaves as $\epsilon_{\rm A}(\omega) \approx i(\omega\epsilon_0\rho)^{-1}$ (e.g., a Drude metal for $\omega < \gamma$). Within the effective medium description, for the reflection coefficient we then have

$$r_I(\omega,k) \approx \sqrt{\omega\epsilon_0} \sqrt{2\frac{\rho}{\epsilon_{\rm B}} \frac{d_{\rm B}}{d_{\rm A}}}.$$
 (25)

Therefore in the case of a metal-dielectric superlattice structure, the EMA predicts that for $\omega < \gamma$ the behavior of the reflection coefficient is no longer ohmic but subohmic.

Figures 5 and 6 display the above features and certain structures related to the CIPP modes. Using the different approaches described above (Bloch waves and EMA), both plots





FIG. 6. Analogous comparison as in Fig. 5 but this time for $k = 10^{-3}c/\omega_{\rm p}$. The EMA holds over a larger frequency range and for lower frequencies ω . A subohmic behavior $(r_{\rm I} \propto \sqrt{\omega})$ is visible in the Bloch-wave calculations. At low frequencies, the EMA breaks down and effectively only the first slab is responsible for the scattering properties of the entire structure.

display the frequency dependence $r_I^p(\omega,k)$ for two distinct values of the wave vector, one above and one below the value $k_0(\pi/d_{\rm sl})$ that delineates the overdamped region. Notice that the EMA agrees with the full calculation only above a certain frequency. The breakdown of the approximation occurs for frequencies around the lower boundary of the ω_{-} branch. This can be understood by recalling that in this region $\beta d_{\rm sl} \approx \pi$ (see Fig. 4), while previous work [45] has shown that the expressions in Eqs. (21) are only compatible with $\beta d_{\rm sl} \ll 1$. In both plots, we can see that for $\omega < \gamma$ the EMA description enters the subohmic regime discussed above. This behavior is also featured by the full calculation as long as γ lies above the lower boundary of the ω_{-} branch. Indeed, in Fig. 6, due to the choice of the wave vector, the ω_{-} branch is stretched to lower frequencies ω and the lower bound is not marked by a distinct edge as that appearing in Fig. 5. The subohmic feature of the superlattice occurs in the region where the modes of the ω_{-} branch becomes overdamped, connecting it to the collective low-frequency behavior of the (nonresonant) CIPP. Conversely, the shoulder appearing in Fig. 5 can be interpreted as resulting from the coalescence of all the (infinite) CIPP resonances occurring in the semi-infinite superlattice.

The EMA also provides the framework for another interesting aspect of superlattice structures (or in general uniaxial crystals), namely the appearance of hyperbolic dispersions [20]. Indeed, depending on the sign of Re{ $\epsilon_{\parallel,\perp}$ }, isofrequency surfaces in the three-dimensional (3D) wave-vector space can be either ellipsoids or hyperboloids. The latter occurs when $\operatorname{Re}\{\epsilon_{\parallel}\}\operatorname{Re}\{\epsilon_{\perp}\} < 0$ and, depending on which of the permittivities is negative, one distinguishes between hyperbolic material of type I (Re{ ϵ_{\parallel} } < 0 and Re{ ϵ_{\perp} } > 0) or of type II ($\operatorname{Re}\{\epsilon_{\parallel}\} > 0$ and $\operatorname{Re}\{\epsilon_{\perp}\} < 0$). Distinct from a usual dispersion, in hyperbolic materials a large number of wave vectors can be connected with a narrow range of frequencies leading to a significant increase in the system's density of states [20]. In Figs. 5 and 6 the shaded areas indicate where our superlattice behaves as a hyperbolic material. For a metal, modeled by a Drude model, with low damping ($\gamma \ll \omega_{\rm p}$) and a dielectric with constant $\epsilon_{\rm B} > 0$, the frequencies where the



FIG. 7. Wave-vector dependence of the imaginary part of the *p* polarized reflection coefficient for $\omega = \sqrt{2} \times 10^{-4} \omega_{\rm sp}$. The material parameters were chosen analogous to Fig. 3 with $d_{\rm A} = d_{\rm B} = 10$ nm (~6 × 10⁻³ $c/\omega_{\rm p}$). The results for the full Bloch-wave calculation (red line), the EMA (black dash-dotted line) and the slab description (dashed gray line) are normalized by the imaginary part of the reflection coefficient for a metallic half-space. The full calculation is well described by the EMA at low *k* (near orthogonal incidence) and it recovers the slab and the bulk results for $k > k_t$ and $k > 1/d_{\rm A}$, respectively.

relative sign flips are given by

$$\omega_{\rm h1} \sim \omega_{\rm p} \sqrt{\frac{f}{f\epsilon_{\rm A}^{\infty} + (1-f)\epsilon_{\rm B}}},$$
(26a)

$$\omega_{\rm h2} \sim \omega_{\rm p} \sqrt{\frac{1-f}{f\epsilon_{\rm B} + (1-f)\epsilon_{\rm A}^{\infty}}}, \quad \omega_{\rm h3} \sim \frac{\omega_{\rm p}}{\sqrt{\epsilon_{\rm A}^{\infty}}}.$$
 (26b)

We notice that, under the condition of validity of the EMA, this behavior is essentially related with the location of the ω_{\pm} branches, establishing a direct connection with the CIPP [54]. Interestingly, this offers another perspective on the features we observe in $r_I(\omega)$. Indeed, if we exclude the subohmic region, where the material dissipation is relevant, the shoulders appearing in the plots (in particular in Fig. 5) can be seen as a manifestation of the hyperbolic behavior of the semiinfinite superlattice. In fact, due to the change in sign of the permittivities, in this region Im{ $\epsilon_{eff}(\omega)$ } and therefore $r_I(\omega)$ can be substantially different from zero even for a vanishingly small material damping. This additional loss channel can be understood by the deep penetration of the CIPPs, which allows us to accumulate even very small losses throughout the whole semi-infinite superlattice substrate.

The above plots also highlight the relevance of the wave vector regarding the validity of the EMA, showing that the smaller the value of k (near to orthogonal incidence) becomes, the better is the quality of the EMA. Importantly, both Figs. 5 and 6 reveal that at low frequencies, below the area described by the ω_{-} branch of the CIPP, the EMA description ceases to be valid. In this case, the optical response of the superlattice structure essentially reduces to that of the first metallic layer in the system, recovering the ohmic behavior of a single slab. Physically, this can be understood as the result of a shorter penetration of the field into the structure: The EMA breaks down for penetration depths, which are shorter than the thickness of the supercell (the field is no longer able to resolve deeper-lying layers).

a fixed frequency: For small wave vectors, the full result is indeed well represented by the EMA, while for large wave vectors we recover the slab's reflection coefficient. When this occurs, the transition between the ohmic and the subohmic behavior is characterized by the wave vector $k_t(\omega)$, which for small frequencies can be written as

$$k_t \approx \sqrt{\omega\epsilon_0} \sqrt{\frac{2\rho\epsilon_{\rm B}}{d_{\rm A}d_{\rm B}}},$$
 (27)

and can be obtained by comparing the results in Eqs. (12) and (25). For $k < k_t$ the superlattice is well described by the reflection coefficient provided by the EMA, while for $k > k_t$ the slab description and eventually the bulk description for $k > 1/d_A$.

IV. QUANTUM FRICTION WITH SUPERLATTICE STRUCTURES

The analyses presented in the previous sections allow for a quantitative assessment of quantum friction as well as for a deeper qualitative understanding of the behavior of the force in systems involving semi-infinite superlattice substrates. Even if most of the following analytical expressions rely on the near-field approximation, the numerical calculations consider the entire retarded interaction and are thus exact. For the conducting layer, in addition to the Drude model in Eq. (11) with the parameters used to describe gold ($\omega_p = 9 \text{ eV}, \epsilon^{\infty} = 5$ and $\gamma = 1.1 \times 10^{-5} \omega_p$ [58]), we also consider doped silicon

$$\epsilon_{\rm dop}(\omega) = \epsilon_{\rm Si}(\omega) - \frac{\omega_{\rm pSi}^2}{\omega(\omega + i\gamma_{\rm Si})}.$$
 (28)

In the previous model, the free charge carriers are described by an additional Drude term, while the intrinsic permittivity of silicon is given by

$$\epsilon_{\rm Si}(\omega) = \epsilon_{\rm Si}^{\infty} - \frac{\left(\epsilon_{\rm Si}^0 - \epsilon_{\rm Si}^{\infty}\right)\omega_0^2}{\omega^2 - \omega_0^2} \tag{29}$$

with $\epsilon_{Si}^{\infty} = 1.035$, $\epsilon_{Si}^{0} = 11.87$ and $\omega_0 \approx 4.34$ eV [59]. Due to the variability of the doping, we gain access to a wide range of values for the resistivity, $\rho_{dSi} = \gamma_{Si}/(\epsilon_0 \omega_{pSi}^2)$, while maintaining the same basic material description. The dielectric material B is instead chosen to be intrinsic silicon with the permittivity given in Eq. (29) or, for simplicity, vacuum (i.e., $\epsilon_B = 1$). Other experimentally relevant dielectrics are titanium dioxide [55], silicon dioxide [56], or silicon nitride [57]. In general, however, the expressions presented in the previous section indicate that the value of the permittivity function for the dielectric layer mostly produces a shift or a rescaling of the features induced by the conducting material [see for example Eqs. (19) and (25) as well as Fig. 9 and the expression below].

Let us start our analysis by focusing on the nonresonant regime, where the force is essentially connected to wave vectors $k \leq 1/z_a$ and frequencies $0 < \omega \leq v/z_a$. In Sec. III we have shown that, depending on the frequencies and the wave vectors, the optical response of superlattice structures effectively changes, featuring behavior typical of a homogeneous bulk, a thin slab or, using the EMA description, an uniaxial crystal. Similarly we can expect that, as a function of the atom's

velocity and distance from the surface, the quantum frictional force explores all the previously discussed regimes.

At very low velocities and very short distances, despite the fact that a wide range of frequencies can participate in the interaction, from the point of view of quantum friction the semi-infinite superlattice behaves as an ohmic medium, indicating a force, which is proportional to v^3 . The analysis of the previous section suggests indeed that, as long as $k_t z_a \ll 1$, the superlattice is equivalent to a metallic bulk or at most a metallic slab. In fact, in agreement with the behavior depicted in Fig. 7, for $z_a \ll d_A$ we recover the expression for the force acting on an atom moving above a homogeneous substrate composed of an ohmic material [28]

$$\bar{F} \sim \bar{F}_{\text{bulk}} \stackrel{v \ll c}{\approx} -\frac{864}{5\pi^3} \hbar \alpha_0^2 \rho^2 \frac{v^3}{(2z_a)^{10}}.$$
(30)

As explained above, the v^3 scaling is rooted in the linear-infrequency (ohmic) behavior of the imaginary part of reflection coefficient at small frequencies ω (see Fig. 5). The z_a^{-10} dependence results, instead, from a combined dependence on k and ω of the total Green's tensor. For ohmic materials the proportionality to the square of resistivity ρ can be directly understood from the functional behavior of Eq. (4). In Eq. (30) and in all subsequent analytical expressions the bar (e.g., \bar{F}) indicates the average over all dipole angles. For simplifying the evaluation, however, our numerical analysis considers the case $\mathbf{d} = \sqrt{\alpha_0/3} (1,1,1)$, where $\alpha_0 = \text{Tr}[\underline{\alpha}_0/3]$.

When the distance increases, keeping the low-velocity limit, the optical response is still ohmic at low frequencies but with a resistivity that effectively increases according to Eq. (12). In this regime, despite the fact that the force still remains proportional to v^3 , the semi-infinite superlattice is effectively represented by its first layer and its thickness, d_A , appears as an additional length scale of the system. This modifies the functional dependence of quantum friction on the atom-surface separation and for $z_a \gtrsim d_A$ we obtain

$$\bar{F} \sim \bar{F}_{\text{slab}} \approx \bar{F}_{\text{bulk}} C_{\text{slab}}(z_a/d_A).$$
 (31)

The monotonous and positive function $C_{\text{slab}}(x)$, whose explicit form is given in Appendix A, is such that $C_{\text{slab}}(x \to 0) =$ 1, recovering the limit of Eq. (30), and $C^{\text{slab}}(x \gg 1) \propto x^2$. Importantly, Eq. (31) scales as z_a^{-8} for $z_a \gtrsim d_A$. Therefore the force decays slower with z_a than in Eq. (30), leading to an enhancement of several orders of magnitude with respect to the bulk result (see Fig. 8). In simple terms, this geometry-induced modification and the corresponding increase in the value of the force can be understood as a consequence of the fact that, while the intrinsic resistivity of the material is constant, the layer's resistance effectively increases as its thickness is reduced.

With a further increase in the atom-surface separation, the changes in the behavior of the quantum frictional force acting on an atom moving at constant velocity above the semi-infinite superlattice become more profound, as the interaction starts to perceive the substrate as being well-described by the EMA. According to Eq. (27), in the nonresonant regime we roughly expect such change of behavior to occur when

$$vz_a \gtrsim \frac{d_{\rm A}d_{\rm B}}{2\rho\epsilon_0\epsilon_{\rm B}},$$
(32)



FIG. 8. Quantum frictional force on an atom moving above a superlattice (red solid line) as a function of the atom-surface separation. The force is normalized to the bulk result [Eq. (30)]. At large separations, the superlattice can be approximated by an EMA description (dotted black line), which yields a z_a^{-9} law. At small distances, instead, the superlattice can essentially be replaced by the topmost (conducting) layer (gray dashed line). The result for a metallic slab features the transition to bulk behavior, $z_a^{-8} \rightarrow z_a^{-10}$ occurring as soon as $z_a \ll d_A$. As material parameters we used doped silicon with $\omega_{\rm pSi} = 0.0725$ eV, $\gamma_{\rm Si} = 0.0247$ eV and $d_{\rm A} = d_{\rm B} = 1$ nm ($\sim 7 \times 10^{-12} c/\omega_{\rm pSi}$).

which also indicates the necessity of sufficiently large velocities (for $v \rightarrow 0$ the recover the ohmic behavior). In this region we have that

$$\bar{F} \sim \bar{F}_{\text{EMA}} \approx -\hbar\alpha_0^2 \frac{6\rho}{\pi^2 \epsilon_0 \epsilon_{\text{B}}} \frac{d_{\text{B}}}{d_{\text{A}}} \frac{v|v|}{(2z_a)^9}.$$
 (33)

We first notice that the force no longer grows quadratically but linearly with the resistivity of the material. The effective subohmic description introduced by the EMA does not only lead to a change in the velocity dependence of the force $(v^3 \rightarrow v^2)$, as discussed in Sec. II), but also to an additional modification of its functional dependence on the atom-surface separation.

Figure 8 depicts the quantum frictional force for fixed velocity as a function of the atom-surface separation z_a . We observe that with the superlattice structuring, we access the three different regimes discussed above: At short distances, we recover the bulk expression $F \propto z_a^{-10}$ given in Eq. (30); for intermediate separations $z_a \gtrsim d_A$, the slab regime where $F \propto z_a^{-8}$ occurs; finally, for sufficiently large separations, the EMA regime is reached, yielding $F \propto z_a^{-9}$.

The velocity dependence of the quantum frictional force is presented in Fig. 9. At sufficiently low velocities, we recover the v^3 law, which is connected to ohmic response of the superlattice and this essentially originates from its first layer. However, for increasing velocities a broader range of frequencies contributes to the interaction and eventually the region where the structure changes its behavior from ohmic to subohmic becomes relevant. This corresponds to a change of the velocity dependence of the force from v^3 to v^2 . In agreement with Eq. (33), Fig. 9 also shows that, when the material between the metallic layers is silicon ($\epsilon_{\rm B} > 1$), quantum friction is weaker than the force obtained when vacuum is chosen as interjacent medium. However, as predicted by Eq. (32), the transition to the v^2 behavior occurs at lower velocities.

Finally, it is interesting to consider the characteristic of the resonant contribution to quantum friction in systems involving



FIG. 9. Velocity dependence of the quantum frictional force, normalized to the value of the slab configuration at $v = 10^{-5} c$. The atom moves above a superlattice with doped silicon as conducting layer and intrinsic silicon (dashed red line) [see Eq. (29)] or vacuum (solid red line) as dielectric layer. The distance is fixed at $z_a \approx$ $70 c/\omega_p^{Si}$ (~1 μ m for the materials considered). The other parameters are the same of in Fig. 8. In both cases, the full calculations via the Bloch-wave approach features a transition from v^3 behavior at low velocities (dashed black line), typical of ohmic materials, to the v^2 dependence characteristic of the subohmic behavior ($r_I \propto \sqrt{\omega}$) of the EMA (dotted gray line).

semi-infinite superlattices. As described in Sec. III and shown in Fig. 5, for certain parameters we observe large values of r_I due to the coalescence of the resonances occurring in the ω_{\pm} branches. This behavior, which is connected with the hyperbolic dispersion of the structure, is particularly evident for a superlattice composed of low-damping materials, where the subohmic regime is less pronounced. For these frequencies, even if the material has very weak dissipation, the continuum of modes in the ω_{-} branch (and similarly but at higher frequencies



FIG. 10. Resonant enhancement of quantum friction due to the CIPP modes. The quantum frictional force acting on an atom moving above superlattice structures is enhanced due to the interaction with the coalescence of the CIPP resonances in the ω_{-} branch [Eq. (19)]. In order to clearly reveal the effect of CIPP modes, we have chosen a large atomic transition frequency ($\omega_a = 10.2 \text{ eV}$, as, e.g., for hydrogen) and a Drude metal with low-damping constant $\gamma = 1.1 \times 10^{-5} \omega_p$ with $\omega_p = 9 \text{ eV}$ (further parameters are $\epsilon_A^{\infty} = 5$, $d_A = d_B = 1 \text{ nm}$, and $z_a = 10$ nm). For comparison, in addition to the full Bloch-wave calculations (red solid line), the plot shows the asymptote for small velocities (gray dotted line) and the calculations for a Drude bulk substrate (dashed black line). The offset for low velocities between the bulk substrate and the superlattice results can be understood by the different z_a dependence as displayed in Fig. 8. Inset: The full Bloch-wave calculation is normalized by its low-velocity limit, which coincides with the result of the slab configuration.

for the ω_+ branch) effectively behaves as an energy sink, which, through a nonradiative coupling with the atom, can efficiently transport energy away from the surface through the superlattice. Depending on the velocity and the distance of the atom, this frequency region can give rise to a resonant contribution, which leads to an additional increase of the force. The interaction generating the CIPP also shifts this frequency range to a frequency below ω_{sp} , lowering the corresponding resonant velocity threshold and adding a certain degree of tunability via the thickness of the layers. In Fig. 10, we indeed observe a steady increase of the quantum frictional force that occurs at a relatively low velocity. Due to the broadband nature of the ω_{-} band, this resonant contribution differs from that generated by an isolated resonance (see for example Refs. [2,28]) and the system features a smoother transition out of the nonresonant regime.

V. CONCLUSIONS

Modern technologies allow for the structuring of materials at the size of nanometers, prompting novel applications in several areas of physics. In this work, we have shown that such nanostructuring can be very interesting with regards to nonequilibrium atom-surface interactions and in particular for controlling the strength and the functional dependencies of the quantum frictional force on an atom moving at constant velocity and height above multilayered structures. Indeed, when these structures consist of a semi-infinite superlattice of alternating metallic and dielectric layers, the spectrum of vacuum fluctuations is considerably modified relative to that of an homogeneous medium and can be tuned by changing the thickness and the material properties of the layers. In these systems, the frequency spectrum is characterized by the appearance of coupled interface plasmon-polariton (CIPP) modes: They arise from the electromagnetic interaction among the charge-carrier densities existing at the metal-dielectric interfaces and can be considered as the generalization of the surface plasmon-polariton resonances appearing at metallic surfaces. Mathematically, for semi-infinite superlattices, the CIPP modes manifest themselves as two continua characterized by well-prescribed symmetries of the associated electromagnetic field. Their behavior is also connected with the properties of the superlattice to exhibit hyperbolic dispersions. We have seen that CIPP modes affect the quantum frictional forces in different ways depending on the speed of the atom and on its distance from the surface. At low velocity, the force is strongly connected with the low-frequency behavior of the surface's p-polarized reflection coefficient, $r^{p}(\omega,k)$. In superlattices, depending on the wave vector, we have observed a change in behavior of the imaginary part of the reflection coefficient, from ohmic $(r_I^p \propto \omega)$ to subohmic $(r_I^p \propto \sqrt{\omega})$. The former can be ascribed to the electromagnetic response of the first metallic layer in the stacking sequence, while the latter is related to an overdamped (nonresonant) subset of the CIPP modes. We have shown that, for the quantum frictional force, this behavior can lead to enhancements of several orders of magnitude relative to the case of a homogeneous bulk substrate, as well as to a modification of the power law describing its functional dependence on the atom-surface separation $(z_a^{-10} \rightarrow z_a^{-8} \rightarrow z_a^{-9})$, see Fig. 8). Similarly, the velocity dependence changes from $\propto v^3$, typical of the ohmic response, to $\propto v^2$ induced by $r_I^p \propto \sqrt{\omega}$ (see Fig. 9). The threshold distances and velocities, where these transitions take place, depend on the material properties and geometrical parameters of the system [Eq. (32)]. Finally, at higher velocities resonant phenomena can become important. An analysis of the relevant expressions shows that the velocity threshold, when this occurs, is usually rather high due to the large typical values of the involved resonance frequencies. However, we have shown that in superlattice systems, by reducing the layers' thickness, the interaction among all the surface plasmon polaritons at the different material interfaces lead to a displacement of the continuum of CIPP resonances to lower energy, allowing for a more accessible resonant enhancement of the quantum frictional force (see Fig. 10). This behavior has been further connected with the hyperbolic properties of the semi-infinite superlattice. Indeed even for low dissipative materials, the increase in the density of states connected with the hyperbolic dispersion creates an additional channel through which energy can be carried deep into the substrate.

These results highlight once more the role of geometry and material properties in fluctuation-induced phenomena and indicate a pathway for future experimental investigations of nonequilibrium atom-surface effects. While the geometry can be used to control (enhance or suppress) the interaction by changing the functional dependence of the quantum frictional force, the material properties offer a direct access to the proportionality constants. As an example, using high-resistivity materials such as GaAs ($\rho_{GaAs} \approx 10^9 \,\Omega cm$) in a superlattice structure (vacuum as a dielectric, for simplicity) with 10 nm thick layers, our analysis predicts a quantum friction force of $F \approx -15$ fN acting on a ⁸⁷Rb atom moving at a height of $z_a = 0.1 \ \mu m$ above the multilayer surface with a velocity of $v = 5 \times 10^{-4} c$. This value of the quantum frictional force corresponds to an acceleration of about 10^{11} m/s², which is within the presently available experimentally measurable accuracy. An experimental confirmation of quantum frictional forces would be of high fundamental interest and can provide a deeper understanding of the underlying physics of nonequilibrium quantum-fluctuation-induced phenomena.

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APPENDIX: DEFINITIONS AND LOW-VELOCITY LIMIT

The definition of the quantum frictional force essentially depends on two susceptibilities, the atomic polarizability, characterizing the moving microscopic object, and the Green's tensor that characterizes the electromagnetic properties of the nanostructured substrate. In general, the Green's tensor can be written as the sum of the vacuum contribution \underline{G}_0 and a scattered contribution \underline{g} . While the expression for the former can be found in textbooks (see for example Ref. [35]), for flat surfaces g the latter takes the form [60]

$$\underline{g}(\mathbf{k}, z_a, \omega) = \frac{e^{-2\kappa z_a}\kappa}{2\epsilon_0} \bigg[r^p(\omega, k) \mathbf{p}_+ \mathbf{p}_- + \frac{\omega^2}{c^2\kappa^2} r^s(\omega, k) \mathbf{ss} \bigg].$$
(A1)

Here, we have introduced $\kappa = \sqrt{k^2 - \omega^2/c^2}$ (Re{ κ } > 0 and Im{ κ } < 0). Further, $k^2 = k_x^2 + k_y^2$ and r^{σ} are the reflection coefficients for the two polarizations, $\sigma = s, p$, and

$$\mathbf{s} = \frac{\mathbf{k}}{k} \times \frac{\mathbf{z}}{z}, \quad \mathbf{p}_{\pm} = \frac{k}{\kappa} \frac{\mathbf{z}}{z} \mp i \frac{\mathbf{k}}{k}.$$
 (A2)

In these expressions, z represents the vector in z direction (perpendicular to the surface of the substrate). In terms of the Green's tensor we can also define the velocity-dependent polarizability tensor

$$\underline{\alpha}(\omega, \mathbf{v}) = \frac{\underline{\alpha}_0 \omega_a^2}{\omega_a^2 - \omega^2 - \Delta_a(\omega; \mathbf{v}) - i\omega\gamma_a(\omega; \mathbf{v})}, \quad (A3)$$

where the dyadic $\underline{\alpha}_0 = \mathbf{d}\mathbf{d}$ is the static polarizability and have introduced the abbreviations

$$\Delta_a(\omega) = \omega_a^2 \int \frac{d^2 \mathbf{k}}{(2\pi)^2} \operatorname{Tr}[\underline{\alpha}_0 \cdot \underline{G}_R(\mathbf{k}, z_a, \omega + \mathbf{k} \cdot \mathbf{v})], \quad (A4a)$$

and

$$\gamma_a(\omega) = \frac{\omega_a^2}{\omega} \int \frac{d^2 \mathbf{k}}{(2\pi)^2} \operatorname{Tr}[\underline{\alpha}_0 \cdot \underline{G}_I(\mathbf{k}, z_a, \omega + \mathbf{k} \cdot \mathbf{v})], \quad (A4b)$$

which, respectively, describe the induced frequency shift and damping. The polarizability also appears in the expression of the nonequilibrium correction to the fluctuation-dissipation theorem

$$\underline{J}(\omega; \mathbf{v}) = \int \frac{d^2 \mathbf{k}}{(2\pi)^2} [\theta(\omega + \mathbf{k} \cdot \mathbf{v}) - \theta(\omega)]$$
(A5)
 $\times \underline{\alpha}(\omega; \mathbf{v}) \cdot \underline{G}_I(\mathbf{k}, z_a, \omega + \mathbf{k} \cdot \mathbf{v}) \cdot \underline{\alpha}^*(\omega; \mathbf{v}),$

which occurs in Eq. (3).

Altogether, the above expressions allow the evaluation of the nonrelativistic value of the quantum frictional force given in Eq. (1). The structure of Eq. (3) indicates that the quantum friction force can be decomposed into a contribution related to the local thermal equilibrium (LTE) approximation and a full nonequilibrium correction. This separation is also visible in the low-velocity approximation of the force given in Eq. (4), where the first term on the r.h.s. is the result within the LTE, F^{LTE} , while the second, F^J , is entirely due to the tensor $\underline{J}(\omega; \mathbf{v})$.

Equation (4) also shows that the low-velocity behavior of the force is connected to the low-frequency features of the nanostructures' optical response and eventually with the low-frequency expansion of the imaginary part of the reflection coefficients. We have seen in the main text that for metaldielectric superlattice structures, at sufficiently small atomsurface separations, the optical response is dominated by the first (metallic) layer. Effectively, the quantum frictional force felt by the atom is the same as that produced by a metallic slab, i.e., $F_{sup} \approx F_{slab}$. Using the expressions in Eq. (12) this allows for the following estimates. For the LTE term, we obtain

$$\frac{F_{\text{slab}}^{\text{LTE}}}{F_{\text{bulk}}^{\text{LTE}}} = C_{\text{slab}}^{\text{LTE}} \left(\frac{z_a}{D}\right) \\
\xrightarrow{v \to 0} \frac{\int_0^\infty dk \, k^6 e^{-2kz_a} \coth(kD)}{\int_0^\infty dk \, k^6 e^{-2kz_a}} \\
\times \frac{\int_0^\infty dk \, k^2 e^{-2kz_a} \coth(kD)}{\int_0^\infty dk \, k^6 e^{-2kz_a}}, \quad (A6)$$

where $F_{\text{bulk}}^{\text{LTE}}$ is the LTE contribution to the quantum frictional force in the case of a homogeneous semi-infinite substrate. Its value

$$\bar{F}_{\text{bulk}}^{\text{LTE}} \approx -\frac{21}{20} \frac{90}{\pi^3} \hbar \alpha_0^2 \rho^2 \frac{v^3}{(2z_a)^{10}}$$
(A7)

has already been calculated in Ref. [28], where the bar indicates the average over the dipole angles. The function that gives the correction induced by the finite thickness is defined as

$$\mathcal{C}_{\text{slab}}^{\text{LTE}}\left(\frac{z_a}{D}\right) = \left[1 - 2\frac{\zeta\left(7, \frac{z_a}{D}\right)}{(D/z_a)^7}\right] \left[1 - 2\frac{\zeta\left(3, \frac{z_a}{D}\right)}{(D/z_a)^3}\right], \quad (A8)$$

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where

$$\zeta(s,x) = \sum_{n=0}^{\infty} \frac{1}{(n+x)^s}$$
(A9)

is the Hurwitz zeta function. Upon applying the same strategy to the nonequilibrium contribution we obtain an analogous expression that reads as

$$\bar{F}_{\text{bulk}}^{J} \approx -\frac{87}{80} \frac{72}{\pi^3} \hbar \alpha_0^2 \rho^2 \frac{v^3}{(2z_a)^{10}}$$
(A10)

and the corresponding correction function

$$\mathcal{C}_{\text{slab}}^{J}\left(\frac{z_{a}}{D}\right) = \left[1 - 2\frac{\zeta\left(5, \frac{z_{a}}{D}\right)}{(D/z_{a})^{5}}\right]^{2}.$$
 (A11)

Adding the two contributions, we can define the total correction function introduced in Eq. (31)

$$C_{\text{slab}}\left(\frac{z_a}{D}\right) = \frac{F_{\text{bulk}}^{\text{LTE}}C_{\text{slab}}^{\text{LTE}}\left(\frac{z_a}{D}\right) + F_{\text{bulk}}^{J}C_{\text{slab}}^{J}\left(\frac{z_a}{D}\right)}{F_{\text{bulk}}^{\text{LTE}} + F_{\text{bulk}}^{J}}, \quad (A12)$$

which clearly inherits the properties of the functions defined above. For $z_a \gg D$ we have that

$$\bar{F} \approx \bar{F}_{\text{slab}} \stackrel{z_a \gg D}{\approx} - \frac{\hbar \alpha_0^2 \rho^2}{D^2 \pi^3} \frac{v^3}{(2z_a)^8} \frac{2043}{160}.$$
(A13)

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