

Nonlinear graphene plasmonics: Amplitude equation for surface plasmons

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Using perturbation expansion of Maxwell equations, an amplitude equation is derived for nonlinear transverse magnetic (TM) and transverse electric (TE) surface plasmon waves supported by graphene. The equation describes the interplay between in-plane beam diffraction and nonlinearity due to light intensity induced corrections to graphene conductivity and susceptibility of dielectrics. For strongly localized TM plasmons, graphene is found to bring the superior contribution to the overall nonlinearity. In contrast, nonlinear response of the substrate and cladding dielectrics can become dominant for weakly localized TE plasmons.

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I. INTRODUCTION

Applications of graphene in photonics and optoelectronics have been actively discussed in recent years [1,2]. In particular, graphene plasmonics is considered a promising alternative to conventional plasmonics with noble metals [3]. Recently, hybrid metal-graphene plasmonic structures have been proposed as the propitious platform for novel optical devices [4].

Graphene supports two types of surface plasmons: transverse magnetic (TM) and transverse electric (TE) modes [5,6]. TM graphene plasmon is in many ways analogous to the surface plasmon excited at a metal-dielectric interface [7], although specific features of collective electron excitation in the purely two-dimensional graphene lead to qualitative differences in the spectra of plasmons in these two systems [6]. Compared to its metal analog, TM plasmon supported by graphene offers substantial enhancement of the field localization, accompanied by the considerable decrease of the propagation loss—all being crucial for potential applications of surface plasmons in miniature photonic components. The existence of TE plasmon is directly related to the linear (Dirac) spectrum of electrons in graphene [5]; there is no analog of such surface wave in conventional plasmonics. TE plasmon is only weakly localized at the surface, however, it is characterized by considerably low propagation losses even at room temperature. Spectral characteristics of TE and TM graphene plasmons are defined by the charge density, which can be controlled chemically [8] or electrically [9]. This tunability represents another important advantage of graphene plasmons over metal plasmons.

Optical properties of doped graphene are encapsulated in the induced surface current \mathcal{K} . So far, graphene plasmons have been studied under the assumption of a linear relation between the current \mathcal{K} and the field amplitude \mathcal{E} : $\mathcal{K} = \sigma \mathcal{E}$ [10]. This is true only at low light intensities, while generally the dependence $\mathcal{K}(\mathcal{E})$ is predicted to be highly nonlinear [11,12]. The particularly strong nonlinear response of graphene has been confirmed in several experiments, including direct measurements with optical Kerr gate [13] and z -scan [14] techniques, as well as observation of four-wave mixing with graphene flakes [15] and a range of nonlinear effects in a graphene-coated photonic crystal nanocavity [16]. Altogether these findings put forward the great potential of graphene for building functional nanophotonic devices.

In this work we consider nonlinear surface waves supported by graphene in the simple planar geometry shown in Fig. 1. Allowing for light intensity corrections to the surface current and to the susceptibility of dielectrics surrounding graphene, as well as introducing diffraction due to a finite beam width in the unbound (y) direction, we develop asymptotic expansion of Maxwell equations and boundary conditions to obtain an amplitude equation for quasi-TM and quasi-TE surface waves. The asymptotic expansion procedure is similar to that recently developed for semiconductor and metal nanowaveguides [17,18]. Further, we analyze the relative contribution from dielectrics and graphene to the overall effective nonlinearity of the system for the two types of plasmons, and the impact of geometry on the nonlinearity enhancement.

II. SETUP AND ASYMPTOTIC EXPANSION OF MAXWELL EQUATIONS

We consider the planar geometry, in which single-layer graphene is sandwiched in-between two dielectrics. We choose the x axis to be perpendicular to the interfaces, z is the direction of propagation, and y is the unbound direction in which light can diffract (see Fig. 1). For monochromatic fields $\vec{\mathcal{E}} = \frac{1}{2} \vec{E} e^{-i\omega t} + \text{c.c.}$ and $\vec{\mathcal{H}} = \frac{1}{2} \vec{H} e^{-i\omega t} + \text{c.c.}$, in each dielectric domain we solve stationary Maxwell equations:

$$\vec{\nabla} \times \vec{\nabla} \times \vec{E} = \frac{\vec{D}}{\epsilon_0}. \quad (1)$$

Here spatial coordinates are normalized to the inverse wave number $k = 2\pi/\lambda = \omega/c$. For homogeneous isotropic dielectrics, the displacement vector takes the form

$$\vec{D} = \epsilon_0[\epsilon \vec{E} + \vec{N}], \quad (2)$$

$$\vec{N} = \frac{1}{2} \chi_3 (|\vec{E}|^2 \vec{E} + \frac{1}{2} \vec{E}^2 \vec{E}^*). \quad (3)$$

Adapting complex amplitude notation to the surface current $\vec{\mathcal{K}} = \frac{1}{2} \vec{K} e^{-i\omega t} + \text{c.c.}$, $\vec{K} = [0, K_y, K_z]^T$, the boundary conditions can be written as

$$\Delta[E_y] = 0, \quad \Delta[E_z] = 0, \quad (4)$$

$$-\Delta[H_y] = ic\epsilon_0 \Delta[\partial_z E_x - \partial_x E_z] = K_z, \quad (5)$$

$$-\Delta[H_z] = ic\epsilon_0 \Delta[\partial_x E_y - \partial_y E_x] = -K_y, \quad (6)$$

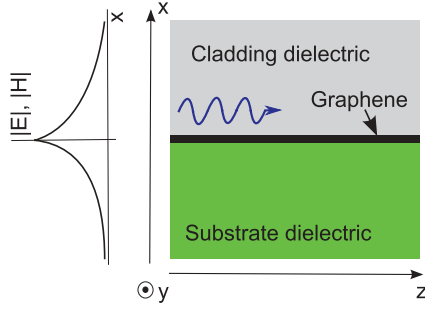


FIG. 1. (Color online) Schematic illustration of a surface plasmon propagating along a graphene sheet. Fields are exponentially localized in x (across the interface), as shown in the left panel.

where operators Δ and Θ are defined as

$$\Delta[f(x)] = \lim_{\delta \rightarrow 0} [f(x - \delta) - f(x + \delta)], \quad (7)$$

$$\Theta[f(x)] = \frac{1}{2} \lim_{\delta \rightarrow 0} [f(x - \delta) + f(x + \delta)]. \quad (8)$$

Taking into account first order nonlinear corrections to the relationship between surface current and electric field amplitude $\tilde{K}(\tilde{E})$ [12] and neglecting the effect of higher harmonics generation, we obtain

$$K_{y,z} = \Theta \left[\sigma_1 E_{y,z} + \frac{\sigma_3}{2} \left(|\tilde{E}|^2 E_{y,z} + \frac{1}{2} \tilde{E}^2 E_{y,z}^* \right) \right]. \quad (9)$$

If the nonlinear response is neglected altogether ($\sigma_3 = 0$, $\chi_3 = 0$), and no losses due to electron-phonon scattering or defects are considered at zero temperature [$\text{Re}(\sigma_1) = 0$], the above system admits solutions in the form of surface plasmons propagating in the z direction: $E, H \sim e^{i\beta z}$. Field amplitudes in such solutions are exponentially localized at the interface $x = 0$ and constant along the unbound direction y . For the case of the positive (negative) imaginary part of conductivity σ_1 only TM (TE) surface plasmon exists [5].

Below we consider a weakly dissipative case, so that $\sigma_1 = \sigma_1^{(R)} + i\sigma_1^{(I)}$ and $\sigma_1^{(R)}/\sigma_1^{(I)} \sim s \ll 1$, where s is a dummy small parameter. This assumption is valid for a highly doped graphene $|\mu| \gg kT$ and $\hbar\omega < 2|\mu|$, where μ is the chemical potential [5]. Furthermore, we assume that nonlinear corrections to the dielectric susceptibility $\sim \chi_3 |\tilde{E}|^2$ and graphene conductivity $\sim \sigma_3 |\tilde{E}|^2$ are of the same order of smallness $O(s)$. We let the mode amplitude ψ vary slowly with the propagation distance $\partial_z \psi \ll \beta \psi$, and consider weak diffraction $\partial_y \psi \neq 0$. Using asymptotic expansion of the Maxwell equation (1) and the boundary conditions (4)–(6), below we derive the propagation equation for the mode amplitude ψ .

Note, with the account of diffraction, the separation into TM and TE modes can no longer be performed; instead one deals with quasi-TM and quasi-TE modes.

III. QUASI-TM SURFACE PLASMON

We seek a guided mode solution in the form

$$E_x = [A_x(\psi, x) + B_x(\psi, x) + O(s^{5/2})]e^{i\beta z}, \quad (10)$$

$$E_y = [C(\psi, x) + O(s^2)]e^{i\beta z}, \quad (11)$$

$$E_z = [A_z(\psi, x) + B_z(\psi, x) + O(s^{5/2})]e^{i\beta z}, \quad (12)$$

where $\psi = \psi(z, y)$ is a slowly varying function: $\partial_z \psi \sim s$, $\partial_y \psi \sim s^{1/2}$, $A_{x,z} \sim s^{1/2}$, $C \sim s$, and $B \sim s^{3/2}$. The chosen orders of smallness are justified below by consistently solving boundary value problems, which emerge in different orders of s . Following substitution into Maxwell equations, in the order $O(s^{1/2})$ we obtain the following boundary value problem:

$$\hat{L}_{\text{TM}} \vec{A} = 0, \quad (13)$$

$$\Delta[A_z] = 0, \quad \Delta[i\beta A_x - \partial_x A_z] = \alpha_1^{(I)} \Theta[A_z], \quad (14)$$

where $\vec{A} = [A_x, A_z]^T$, $\alpha_1 = \sigma_1/(c\epsilon_0)$, and operator \hat{L}_{TM} is defined as

$$\hat{L}_{\text{TM}} = \begin{bmatrix} \beta^2 - \epsilon & i\beta \partial_x \\ i\beta \partial_x & -\partial_{xx}^2 - \epsilon \end{bmatrix}. \quad (15)$$

We choose the solution in the form $\vec{A} = I^{1/2} \psi(z, y) \vec{e}$, where $\vec{e} = [e_x, e_z]^T$ is the linear surface plasmon mode:

$$x < 0: e_z = e^{q_s x}, \quad e_x = \frac{-i\beta}{q_s} e^{q_s x}, \quad (16)$$

$$x > 0: e_z = e^{-q_c x}, \quad e_x = \frac{i\beta}{q_c} e^{-q_c x}, \quad (17)$$

$$q_{s,c} = \sqrt{\beta^2 - \epsilon_{s,c}}, \quad (18)$$

where ϵ_s and ϵ_c correspond to dielectric layers at $x < 0$ (substrate) and $x > 0$ (cladding), respectively. Propagation constant β is defined through the dispersion relation [6]

$$\frac{\epsilon_s}{\sqrt{\beta^2 - \epsilon_s}} + \frac{\epsilon_c}{\sqrt{\beta^2 - \epsilon_c}} = \alpha_1^{(I)}. \quad (19)$$

The normalization factor I is chosen in a way that $|\psi|^2$ is the power density (measured in watts per meter) carried in the z direction [17]:

$$I = \frac{2\beta k}{\epsilon_0 c Q}, \quad (20)$$

$$Q = \int_{-\infty}^{+\infty} \epsilon |e_x|^2 dx = \frac{\beta^2}{2} \left(\frac{\epsilon_s}{q_s^3} + \frac{\epsilon_c}{q_c^3} \right). \quad (21)$$

Collecting terms of the order $O(s)$ we obtain

$$(\beta^2 - \epsilon)C - \partial_{xx}^2 C = -I^{1/2} \partial_y \psi (i\beta e_z + \partial_x e_x), \quad (22)$$

$$\Delta[C] = 0, \quad \Delta[\partial_x C - I^{1/2} \partial_y \psi e_x] = -\alpha_1^{(I)} \Theta[C]. \quad (23)$$

From $\vec{\nabla} \cdot \vec{E} = 0$ in the order $O(s^{1/2})$ it follows that $i\beta e_z + \partial_x e_x = 0$, and therefore C solves the homogeneous equation. It is nonzero due to simultaneous diffraction ($\partial_y \psi \neq 0$) and discontinuity of the e_x component at the interface [see Eq. (23)]. Substituting $C = I^{1/2} \partial_y \psi e_y$, it is easy to see that e_y satisfies the same homogeneous equation as e_z . Comparing boundary conditions for e_y and e_z , we obtain $e_y = (-i/\beta) e_z$.

In the order $O(s^{3/2})$ we obtain the following boundary value problem:

$$\hat{L}_{\text{TM}} \vec{B} = I^{1/2} \vec{J}, \quad (24)$$

$$\Delta[B_z] = 0, \quad (25)$$

$$\begin{aligned} \Delta[i\beta B_x + \partial_z \psi I^{1/2} e_x - \partial_x B_z] \\ = -i\alpha_1^{(R)} I^{1/2} \psi \Theta[e_z] + \alpha_1^{(I)} \Theta[B_z] \\ - \frac{i}{2} \alpha_3 I^{3/2} |\psi|^2 \psi \Theta \left[|\vec{e}|^2 e_z + \frac{1}{2} \vec{e}^2 e_z^* \right], \end{aligned} \quad (26)$$

where $\alpha_3 = \sigma_3/(c\epsilon_0)$ and

$$J_x = \partial_z \psi (2i\beta e_x - \partial_x e_z) + \partial_{yy}^2 \psi (e_x - \partial_x e_y) + |\psi|^2 \psi n_x, \quad (27)$$

$$J_z = -\partial_z \psi \partial_x e_x + \partial_{yy}^2 \psi (e_z - i\beta e_y) + |\psi|^2 \psi n_z, \quad (28)$$

where $n_{x,z} = I N_{x,z}(e_x, 0, e_z)$.

Next, we project Eq. (24) onto the linear mode \vec{e} :

$$\int_{-\infty}^{+\infty} (\vec{e}^* \cdot \hat{L}_{TM} \vec{B}) dx = I^{1/2} \int_{-\infty}^{+\infty} (\vec{e}^* \cdot \vec{J}) dx, \quad (29)$$

take $\int_{-\infty}^{+\infty} = \int_{-\infty}^0 + \int_0^{+\infty}$ in the left-hand side, apply integration by parts, and use the boundary conditions in Eqs. (14) and (26) to obtain

$$\begin{aligned} \int_{-\infty}^{+\infty} (\vec{e}^* \cdot \hat{L}_{TM} \vec{B}) dx \\ = \Delta[i\beta(e_z^* B_x + e_x^* B_z) - e_z^* \partial_x B_z + B_z \partial_x e_z^*] \\ = -\partial_z \psi I^{1/2} \Delta[e_x e_z^*] - i\alpha_1^{(R)} \psi I^{1/2} \Theta[|e_z|^2] \\ - \frac{i}{2} \alpha_3 |\psi|^2 \psi I^{3/2} \Theta \left[|\vec{e}|^2 |e_z|^2 + \frac{1}{2} \vec{e}^2 (e_z^*)^2 \right]. \end{aligned} \quad (30)$$

Finally, computing integrals in the right-hand side of Eq. (29), we obtain the amplitude equation

$$i \frac{\partial \psi}{\partial(z/k)} + \frac{1}{2\beta k} \frac{\partial^2 \psi}{\partial(y/k)^2} + i\Lambda \psi + \Upsilon |\psi|^2 \psi = 0, \quad (31)$$

where the nonlinear parameter Υ combines the contributions of graphene and dielectrics:

$$\Upsilon = g(\gamma_G + \gamma_D), \quad (32)$$

$$\gamma_G = \frac{i\alpha_3 k^2}{2\epsilon_0 c \beta^2 P^2} \Theta \left[|\vec{e}|^2 |e_z|^2 + \frac{1}{2} \vec{e}^2 (e_z^*)^2 \right], \quad (33)$$

$$\gamma_D = \frac{k^2}{2\epsilon_0 c \beta^2 P^2} \int_{-\infty}^{+\infty} \chi_3 \left(|\vec{e}|^4 + \frac{1}{2} |\vec{e}^2|^2 \right) dx, \quad (34)$$

$$P = \int_{-\infty}^{+\infty} |\vec{e}|^2 dx = \frac{2\beta^2 - \epsilon_s}{2q_s^3} + \frac{2\beta^2 - \epsilon_c}{2q_c^3}, \quad (35)$$

the surface-induced nonlinearity enhancement factor g is [17]

$$g = (1 + \eta)^{-2}, \quad (36)$$

$$\eta = \frac{-i}{\beta P} \Delta[e_z^* e_x] = -\frac{1}{P} \left(\frac{1}{q_s} + \frac{1}{q_c} \right), \quad (37)$$

and the effective linear absorption parameter is given by

$$\Lambda = g^{1/2} \frac{\alpha_1^{(R)} k}{2\beta P} \Theta[|e_z|^2]. \quad (38)$$

In the above derivations we used the auxiliary relation $g^{1/2} Q = \beta^2 P$, which can be obtained by using $i\beta e_z = -\partial_x e_x$ and by taking integral in Eq. (35) by parts [17].

The expression for the graphene nonlinear coefficient in Eq. (33) can be replaced by the integral similar to the one in Eq. (34), following introduction of an effective graphene nonlinear susceptibility:

$$\chi_3^{(gr)} = i\alpha_3 \delta(x) = \frac{i\sigma^{(3)}}{\epsilon_0 c} \delta(x), \quad (39)$$

where $\delta(x)$ is the Dirac δ function. Note, however, the different structure of the term under the integral, which is due to the surface nature of the nonlinear response in graphene [cf. Eqs. (9) and (3)]. In the limit of high localization, $\beta \gg \epsilon_{s,c}$, for the guided mode one obtains the simple relation $e_x = \pm i e_z$, and therefore

$$|\vec{e}|^2 |e_z|^2 + \frac{1}{2} \vec{e}^2 (e_z^*)^2 \approx \frac{1}{2} |\vec{e}|^4, \quad \vec{e}^2 \approx 0. \quad (40)$$

Apparently, in this limit, the effective nonlinear response of graphene is twice weaker than that of an infinitesimally thin Kerr medium with the susceptibility $\chi_3^{(gr)}$.

IV. QUASI-TE SURFACE PLASMON

For the case of the quasi-TE mode we use the ansatz

$$E_x = [C_x(\psi, x) + O(s^2)] e^{i\beta z}, \quad (41)$$

$$E_y = [A(\psi, x) + B(\psi, x) + O(s^{5/2})] e^{i\beta z}, \quad (42)$$

$$E_z = [C_z(\psi, x) + O(s^2)] e^{i\beta z}, \quad (43)$$

where $\partial_z \psi \sim s$, $\partial_y \psi \sim s^{1/2}$, $A \sim s^{1/2}$, $C_{x,z} \sim s$, and $B \sim s^{3/2}$. Following substitution into Maxwell's equations, in the order $O(s^{1/2})$ we obtain the following boundary value problem:

$$\hat{L}_{TE} A = 0, \quad (44)$$

$$\Delta[A] = 0, \quad \Delta[\partial_x A] = -\alpha_1^{(I)} \Theta[A], \quad (45)$$

$$\hat{L}_{TE} = \beta^2 - \epsilon - \partial_{xx}^2. \quad (46)$$

We choose the solution in the form $A = I^{1/2} \psi(z, y) e_y$, where e_y is the surface plasmon mode:

$$x < 0 : e_y = e^{q_s x}, \quad (47)$$

$$x > 0 : e_y = e^{-q_c x}, \quad (48)$$

$q_{s,c}$ are defined in Eq. (18), and the normalization factor I ensures $|\psi|^2$ gives the power density carried in the z direction:

$$I = \frac{4k}{\beta \epsilon_0 c P}, \quad (49)$$

$$P = \int_{-\infty}^{+\infty} |e_y|^2 dx = \frac{1}{2q_s} + \frac{1}{2q_c}. \quad (50)$$

The dispersion relation for the TE plasmon is given by

$$\sqrt{\beta^2 - \epsilon_s} + \sqrt{\beta^2 - \epsilon_c} = -\alpha_1^{(I)}. \quad (51)$$

In the order $O(s)$ we obtain

$$\hat{L}_{TM} \vec{C} = -I^{1/2} \partial_y \psi [\partial_x e_y, i\beta e_y]^T, \quad (52)$$

$$\Delta[C_z] = 0, \quad \Delta[i\beta C_x - \partial_x C_z] = \alpha_1^{(I)} \Theta[C_z], \quad (53)$$

where $\vec{C} = [C_x, C_z]^T$, and operator \hat{L}_{TM} is defined in Eq. (15). Substituting in the above equations $\vec{C} = I^{1/2} \partial_y \psi \vec{e}$ and eliminating e_x , we obtain

$$\hat{L}_{\text{TE}} e_z = i\beta \epsilon^{-1} \hat{L}_{\text{TE}} e_y = 0. \quad (54)$$

In other words, e_z solves the same homogeneous equation as e_y . Comparing boundary conditions for e_y , Eq. (45), and e_z , Eq. (53), we obtain $e_z = (i/\beta) e_y$ and $e_x \equiv 0$. It is easy to check that this choice also satisfies the condition $\vec{\nabla} \cdot \vec{E} = 0$ in the order $O(s)$.

In the order $O(s^{3/2})$ the following boundary value problem is obtained:

$$\hat{L}_{\text{TE}} \vec{B} = I^{1/2} [i2\beta \partial_z \psi e_y - \partial_{yy}^2 \psi (i\beta e_z + \partial_x e_x)], \quad (55)$$

$$\Delta[B] = 0, \quad (56)$$

$$\begin{aligned} \Delta[\partial_x B - \partial_y C_x] &= i\alpha_1^{(R)} I^{1/2} \psi \Theta[e_y] - \alpha_1^{(I)} \Theta[B] \\ &+ i\frac{3}{4} \alpha_3 I^{3/2} |\psi|^2 \psi \Theta[|e_y|^2 e_y]. \end{aligned} \quad (57)$$

Projecting Eq. (55) onto the mode e_y and following essentially the same steps as described in the previous section, in the left-hand side we obtain

$$\int_{-\infty}^{+\infty} e_y^* \hat{L}_{\text{TE}} B dx = -\Theta[e_y^* B - B \partial_x e_y^*]. \quad (58)$$

Performing projection in the right-hand side of Eq. (55), and using the boundary conditions in Eqs. (45) and (57), we obtain the amplitude equation (31) with the following coefficients:

$$\Upsilon_{\text{TE}} = \gamma_{G,\text{TE}} + \gamma_{D,\text{TE}}, \quad (59)$$

$$\gamma_{G,\text{TE}} = \frac{i3\alpha_3 k^2}{2\epsilon_0 c \beta^2 P^2} \Theta[|e_y|^4], \quad (60)$$

$$\gamma_{D,\text{TE}} = \frac{3k^2}{2\epsilon_0 c \beta^2 P^2} \int_{-\infty}^{+\infty} \chi_3 |e_y|^4 dx, \quad (61)$$

$$\Lambda_{\text{TE}} = \frac{\alpha_1^{(R)} k}{2\beta P} \Theta[|e_y|^2]. \quad (62)$$

For the quasi-TE mode the enhancement factor g is absent. Also, due to the linear mode being scalar, in this case the nonlinear response of graphene is completely analogous to that of a infinitesimally thin Kerr medium with the susceptibility $\chi_3^{(\text{gr})}$ in Eq. (39).

V. ANALYSIS AND DISCUSSION

Conductivity of graphene consists of intra- and interband contributions, $\sigma_1 = \sigma_{\text{intra}} + \sigma_{\text{inter}}$. For the case of a highly doped graphene $|\mu| \gg kT$, μ is the chemical potential, intra- and interband terms are given by the semiclassical formalism [5]

$$\sigma_{\text{intra}}(\Omega) = \frac{ie^2}{\pi \hbar} \frac{1}{\Omega + i\nu_{\text{intra}}}, \quad (63)$$

$$\sigma_{\text{inter}}(\Omega) = \frac{ie^2}{4\pi \hbar} \ln \frac{2 - |\Omega| - i\nu_{\text{inter}}}{2 + |\Omega| + i\nu_{\text{inter}}}, \quad (64)$$

where $\Omega = \hbar\omega/\mu$, excitation below interband absorption threshold is assumed: $\Omega < 2$, coefficients $\nu = \hbar/(|\mu|\tau)$ take into account losses due to electron scatterings at finite

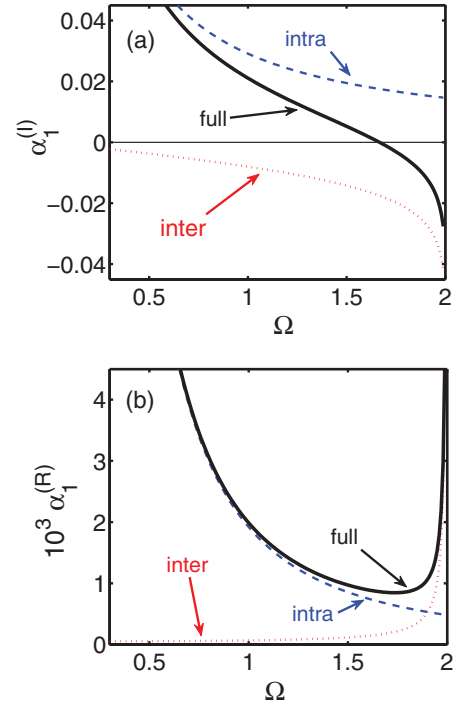


FIG. 2. (Color online) Dimensionless conductivity of graphene α_1 : imaginary (a) and real (b) parts. Dashed, dotted, and solid curves correspond to intra-, inter-, and full conductivity, respectively. The chemical potential is set to $\mu = 0.1$ eV, and relaxation times are $\tau_{\text{intra}} = 100$ fs and $\tau_{\text{inter}} = 1$ ps.

temperatures, and below we take $\tau_{\text{intra}} = 100$ fs and $\tau_{\text{inter}} = 1$ ps [6,16]. For the doping level of $\mu = 0.1$ eV we obtain $\nu_{\text{intra}} \approx 0.066$, $\nu_{\text{inter}} \approx 0.007$, and the interband absorption threshold is at $\omega_{\text{th}} = 2\mu/\hbar \approx 3 \times 10^{14}$ rad/s ($\lambda_{\text{th}} \approx 6.3 \mu\text{m}$). The corresponding dimensionless conductivity α_1 is plotted in Fig. 2. The imaginary part of α_1 changes its sign at $\Omega_0 \approx 1.67$, linear TM plasmons exist for $\Omega < \Omega_0$ (i.e., when $\alpha_1^{(I)} > 0$), while TE plasmons exist for $\Omega > \Omega_0$ ($\alpha_1^{(I)} < 0$) [5]. For the chosen doping level, Ω_0 corresponds to $\lambda_0 \approx 7.5 \mu\text{m}$.

The nonlinear conductivity coefficient σ_3 for graphene is given by [12]

$$\sigma_3(\Omega) = -i \frac{3}{32} \frac{e^2}{\pi \hbar} \frac{(eV_F)^2 \hbar^2}{\mu^4 \Omega^3} (1 + i\alpha_T). \quad (65)$$

Here we introduced coefficient α_T to account for two-photon absorption in graphene; recent experiments suggest $\alpha_T \approx 0.1$ [16]. The negative imaginary part of σ_3 suggests that the nonlinear response is of self-focusing type [cf. Eqs. (31), (33) and (60)].

Below we consider surface plasmons in configurations with air ($\epsilon = 1$) and silicon ($\epsilon = 12$) as dielectrics. For silicon we take $\chi_3 = (4/3)c\epsilon_0\epsilon_s n_2$, $n_2 = 4 \times 10^{-18} \text{ m}^2/\text{W}$. Two-photon absorption in silicon is negligible for $\lambda > 2 \mu\text{m}$ [19]. For simplicity we neglect dispersion of linear and nonlinear dielectric constants.

A. Quasi-TM plasmon

First, we consider TM plasmon in the configuration with silicon substrate and air cladding. The corresponding

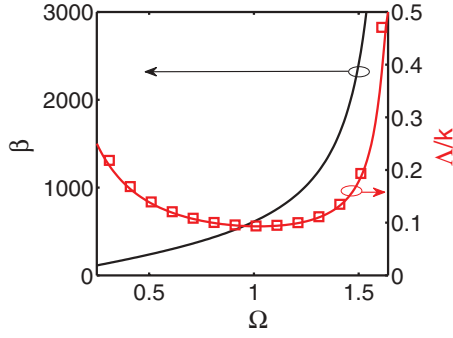


FIG. 3. (Color online) Dispersion of TM plasmon in the silicon-graphene-air geometry: propagation constant β and loss parameter Λ/k as functions of Ω . Imaginary part of β as computed from the full dispersion relation with complex-valued α_1 is shown with squares.

dispersion is plotted in Fig. 3. To validate our theory, the propagation loss parameter Λ/k is compared against the imaginary part of the propagation constant (see open squares in Fig. 3). The latter is computed from the full dispersion relation that takes into account complex-valued α_1 and obtained by replacing $\alpha_1^{(I)}$ with $-i\alpha_1$ in Eq. (19). The results are found to be in perfect agreement.

TM plasmon is characterized by a considerable light confinement in a wide range of frequencies: even at a frequency as low as $\Omega = 0.25$ ($\omega = 7.5 \times 10^{13}$ rad/s, $\lambda \approx 25 \mu\text{m}$) the propagation constant is $\beta \approx 240$, and it constantly grows as Ω increases toward the threshold value Ω_0 . Propagation losses are relatively low: $\Lambda/(k\beta) < 10^{-3}$ when $0.5 < \Omega < 1.6$, which is due to the low absorption rate in graphene below the interband absorption threshold [cf. Fig. 2(b)].

Due to the high localization of TM plasmon, the surface-induced enhancement factor g is large and is growing nearly exponentially with increasing Ω [see Fig. 4(a)]. This growth overbalances the decay of graphene nonlinear response $\sigma_3 \sim \Omega^{-3}$ [cf. Eq. (65)] and causes the considerable increase of the nonlinear coefficient Υ with frequency [see Fig. 4(b)].

Remarkably, the relative contribution of silicon substrate to the overall nonlinearity remains negligibly small within the entire frequency window of existence of TM plasmon, as illustrated in Fig. 4(b). Also, due to the large β , the diffraction term in Eq. (31) can be neglected for typical beam widths $L_y > 1 \mu\text{m}$. Indeed, for $\Omega = 1$ ($\lambda \approx 12.4 \mu\text{m}$) and the beam width of $L_y = 10 \mu\text{m}$ the diffraction length is $L_D = L_y^2 \beta k \approx 50 \text{ mm}$, which is more than six orders of magnitude larger than the apparent plasmon wavelength $\lambda_p = 2\pi/(\beta k) \approx 10 \text{ nm}$. Neglecting nonlinear response of dielectrics and beam diffraction, as well as disregarding linear and nonlinear absorption ($\sigma_1^{(R)} = \sigma_3^{(R)} = 0$), one can find stationary solutions of Maxwell equations $\vec{E}(x, y, z) = I\psi_0 \vec{e}(x, y; \beta_{\text{NL}}) e^{i\beta_{\text{NL}} z}$ with the nonlinear boundary conditions in Eqs. (4)–(6) analytically. The corresponding dispersion relation reads as

$$\frac{\epsilon_s}{\sqrt{\beta_{\text{NL}}^2 - \epsilon_s}} + \frac{\epsilon_c}{\sqrt{\beta_{\text{NL}}^2 - \epsilon_c}} = \alpha_1^{(I)} + \frac{\alpha_3^{(I)}}{2} I \left[|\vec{e}|^2 |e_z|^2 + \frac{1}{2} \vec{e}^2 (e_z^*)^2 \right] |\psi_0|^2. \quad (66)$$

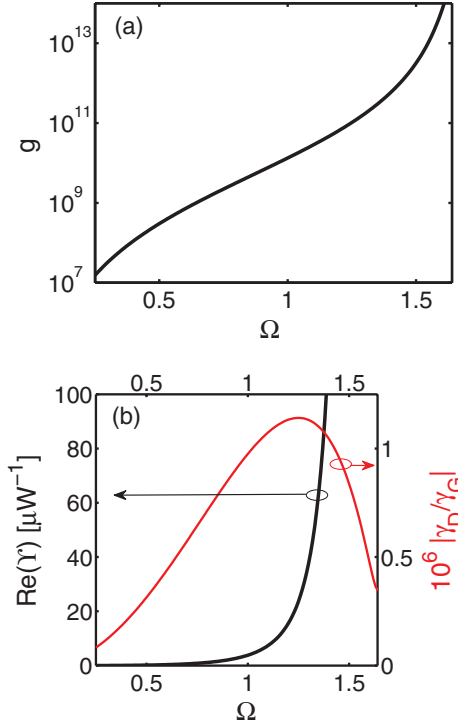


FIG. 4. (Color online) Effective nonlinearity of quasi-TM plasmon: (a) surface enhancement factor g ; (b) nonlinear coefficient Υ and the relative dielectric nonlinearity.

At the same time, substituting $\psi(y, z) \equiv \psi_0 e^{i\beta_{\text{NL}} z}$ into the amplitude equation (31) and assuming $\Lambda = \text{Im}(\Upsilon) = 0$, we obtain $\beta_{\text{NL}} = \beta + (\Upsilon/k)|\psi_0|^2$. Solving the dispersion relation in Eq. (66) numerically, we found both results to be in perfect agreement at low power densities $|\psi_0|^2$ (see Fig. 5).

B. Quasi-TE plasmon

As follows from the dispersion relation in Eq. (51), in order to excite TE plasmon in an asymmetric geometry with different substrate and cladding dielectrics one has to make the conductivity of graphene strong enough: $|\alpha^{(I)}| > \sqrt{|\epsilon_s - \epsilon_c|}$. We would like to note, however, in contrast to the

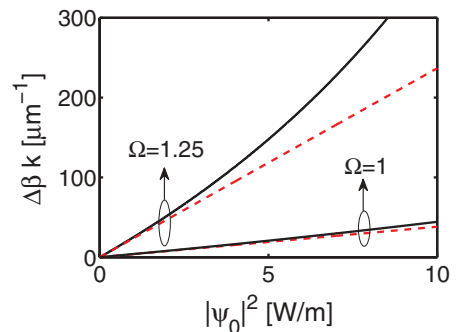


FIG. 5. (Color online) Nonlinear index shift $\Delta\beta = \beta_{\text{NL}} - \beta$ vs power density. Solid curves correspond to the numerical solution of the dispersion relation in Eq. (66) and dashed lines correspond to the result given by the amplitude equation (31): $\Delta\beta k = \Upsilon|\psi_0|^2$.

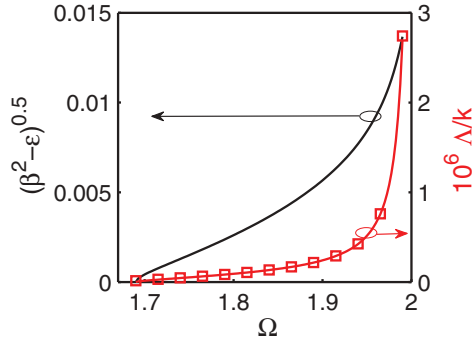


FIG. 6. (Color online) Dispersion of TE plasmon in the silicon-graphene-silicon geometry: plasmon localization factor $q = \sqrt{\beta^2 - \epsilon}$, propagation loss Δ/k , and imaginary part of the propagation constant (squares).

case of a conventional dielectric slab waveguide, here only the *difference* between the cladding and substrate dielectric constants matters. Apparently, for the chosen doping level of graphene, TE plasmon does not exist in the silicon-graphene-air configuration [cf. Fig. 2(a)]. Instead, we consider the fully symmetric configuration with silicon in the cladding and substrate: $\epsilon_s = \epsilon_c = 12$. The corresponding dispersion is plotted in Fig. 6. Due to the low values of $|\alpha^{(I)}|$, TE plasmon is only weakly localized. However, one benefits from much smaller propagation losses per plasmon period $T = 2\pi/(\beta k)$, compared to TM plasmons.

As the result of weak localization, typical values of the effective nonlinear coefficient Υ for TE plasmons are nearly 12 orders of magnitude below those for TM plasmons (see Fig. 7). Remarkably, for TE plasmon nonlinear contribution from the dielectrics is dominant over graphene; they become comparable only when the frequency Ω approaches the interband absorption threshold $\Omega_{th} = 2$.

With the account of small propagation constants β , the diffraction term and associated effects due to its interplay with the focusing nonlinearity become important for TE plasmons with typical widths of the order of several micrometers. Taking $\Omega = 1.9$ (corresponding to $\lambda \approx 6.5 \mu\text{m}$), for $L_y = 5 \mu\text{m}$ the diffraction length becomes $L_D = L_y^2 \beta k \approx 30 \mu\text{m}$, and the plasmon period is $2\pi/(\beta k) \approx 0.5 \mu\text{m}$. However, due to the low nonlinearity, one requires considerably high powers to observe basic effects such as self-focusing. For instance, to form a spatial soliton of width L_y the peak power density should be $|\psi_0|^2 = (\Upsilon L_D)^{-1} \approx 3 \times 10^{10} \text{ W/m}$, and

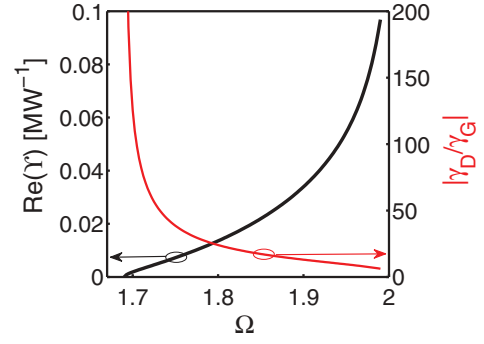


FIG. 7. (Color online) The same as Fig. 4(b) but for quasi-TE plasmon in the silicon-graphene-silicon geometry.

therefore the total power must be of the order of several megawatts.

VI. SUMMARY

Using asymptotic expansion of Maxwell equations and boundary conditions, we have derived an amplitude equation for nonlinear TM and TE surface plasmon waves in the dielectric-graphene-dielectric planar configuration. Induced surface current in graphene shows strongly nonlinear response to the applied electromagnetic field. We have shown that this leads to the effective focusing Kerr-type nonlinearity. For TE plasmon this nonlinearity is fully analogous to that of an infinitesimally thin dielectric layer. However, for TM plasmon the structure of the corresponding nonlinear coefficient is different and reflects the unique surface-only response of graphene.

For typical doping levels of graphene of the order of 0.1 eV, TM plasmons are strongly localized. This causes the significant enhancement of nonlinearity; we predict that considerable nonlinear phase shifts can be observed for power densities as low as a few microwatts per meter. Remarkably, graphene contribution to the overall nonlinearity is shown to be strongly dominant over that of dielectrics in this case. In contrast, TE plasmons are only weakly localized, and the major part of the overall nonlinearity is due to a dielectric substrate and cladding. Typical values of the nonlinear coefficient for TE plasmons are found to be about 12 orders of magnitude below those for TM plasmons.

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