Planar multipole ion trap

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We report on the realization of a chip-based multipole ion trap manufactured using microelectromechanical systems technology, requiring minimal manual alignment of the electrodes. It provides ion confinement in an almost field-free volume between two planes of radiofrequency electrodes, deposited on glass substrates, which allows for optical access to the trap. An analytical model of the effective trapping potential is presented and compared with numerical calculations. Stable trapping of argon ions is achieved, and a lifetime of 16 s is measured. Electrostatic charging of the chip surfaces is studied and found to agree with a numerical estimate.

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I. INTRODUCTION

Microchip-based ion traps are being investigated in several laboratories worldwide for purposes ranging from mass spectrometry [1,2] to quantum information [3–5]. Such traps can be precisely manufactured using microelectromechanical system (MEMS) technology offering highly integrated setups. Radio-frequency Paul traps are being developed with ions trapped above the surface of a single chip [3,4] or between electrodes placed on different chips [6,7]. Different techniques are used for loading these traps, among them electrospray ionization [4] and photoionization of thermally evaporated atoms [3,5], of laser-ablated gas [8], or of lasercooled neutral atoms [9].

Here we present a planar microchip-based ion trap with a multipole arrangement of radiofrequency electrodes. Built from classically machined components, such multipole ion traps, in particular the 22-pole trap [10], are successfully used for the study of low-temperature ion-molecule reactions of astrophysical interest [11,12] and to investigate laserinduced reaction processes [13-17]. The multipole structure leads to an effective potential with a finite depth and a large field-free central region [10, 16, 18] that allows for buffer gas thermalization of the translational and rovibrational degrees of freedom of trapped molecular ions [15,19,20]. We have transformed the cylindrical design of a conventional 22-pole trap into a planar electrode structure, which allows for MEMS fabrication and requires only minimal manual alignment of the electrodes. The open geometry of this planar configuration, and the application of transparent indium tin oxide (ITO) electrodes, should allow us to overlap an optically trapped cloud of ultracold atoms with ions confined in the microchip-based trap. This may open up opportunities for sympathetic cooling of ions with ultracold atoms and for experimental investigations of ultracold ion-atom interactions.

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In this work, the operation of the planar trap and its characteristics are described. Numerical simulations of the trapping field and details of the MEMS process will be described elsewhere [21]. The paper is organized as follows: an analytical model of the effective potential of the chip-based multipole trap is presented in the next section, followed by a description of the trap setup in Sec. III. Experimental results on ion trapping and on the achieved trap lifetimes are discussed in Sec. IV. The analysis of surface charging effects are presented in Sec. V.

II. PROPERTIES OF THE CHIP-BASED MULTIPOLE ION TRAP

The basic components of the planar chip-based multipole ion trap are two sets of equally spaced and equally broad conducting stripes deposited on two insulating glass substrates that face each other. Figure 1 shows a schematic view of the trap; every second stripe is connected to an rf potential $U_0 \sin(\omega t)$, and the other stripes are connected to the opposing rf potential $-U_0 \sin(\omega t)$. As shown below, this leads to a repulsive effective potential in front of each of the two electrode planes, thus yielding confinement of ions between the two planes. The distance from the center of one stripe to the center of the next one is given by πx_0 , the stripe width is

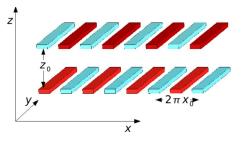


FIG. 1. (Color online) Schematic view of the planar multipole ion trap with equidistant electrodes in two nearby planes. The electrodes are alternatingly connected to two opposing radio-frequency potentials to provide confinement between the planes. Their width amounts to $500 \pm 5 \ \mu\text{m}$ at a spacing of $\pi x_0 = 1000 \pm 5 \ \mu\text{m}$ and $z_0 = 5.0 \pm 0.1 \ \text{mm}$.

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given by $\pi x_0/2$, and the distance between the two substrate surfaces is denoted z_0 . In the realization of our trap, we employ electrodes of $500 \pm 5 \ \mu m$ width and 100 nm thickness, an electrode spacing of $\pi x_0 = 1000 \pm 5 \ \mu m$, and a distance between the substrates of $z_0 = 5.0 \pm 0.1 \ mm$.

For an analytical description of the potential generated by the two planes of radiofrequency electrodes we assume the plane to carry an infinite number of stripes and the stripes to extend infinitely in the plane. We further assume quasistationary conditions, a good approximation for trap frequencies in the MHz regime, and obtain the potential $\Phi(\vec{r})\sin(\omega t)$ by solving the Laplace equation

$$\nabla^2 \Phi(\vec{r}) = 0. \tag{1}$$

Figure 1 shows the employed coordinate system. The boundary conditions of the periodic arrangement of stripes are given by a periodic trapezoidal function: the potential is constant along the electrode surfaces and linear between the electrodes. This potential is approximated by the first-order term of its Fourier series which reads $U(x,z=\pm z_0/2,t) = 1.15U_0 \cos(x/x_0)\sin(\omega t)$. This approximate boundary condition satisfies the requirement of opposite voltages on neighboring electrodes. For distances $\Delta z > x_0$ from the trap electrodes it is a good approximation, as shown below. For these boundary conditions an analytical solution for the electric field inside the trap is given by

$$\Phi(\vec{r}) = \Phi_0 \sinh(\hat{z})\cos(\hat{x}), \qquad (2)$$

where $\hat{z}=z/x_0$ and $\hat{x}=x/x_0$ are reduced variables. The value of Φ_0 is linked to the potential U_0 applied to the electrodes by $\Phi_0=1.15U_0/\sinh[z_0/(2x_0)]$.

The effective potential that an adiabatically trapped ion experiences in a rapidly oscillating rf field is given by [22,23]

$$V^{*}(\vec{r}) = \frac{q^{2}}{4m\omega^{2}} [\vec{\nabla}\Phi(\vec{r})]^{2}, \qquad (3)$$

where the charge and mass of the ion are denoted as q and m. For the given solution for the chip-based ion trap this yields

$$V^*(\vec{r}) = \frac{(1.15)^2 q^2 U_0^2}{4m\omega^2 x_0^2} \frac{\cosh(2\hat{z}) + \cos(2\hat{x})}{\cosh(z_0/x_0) - 1}.$$
 (4)

For $z \gg x_0$ this solution is approximately proportional to $\exp(2\hat{z})$. This is in contrast to cylindrical multipole ion traps of order *n*, such as the 22-pole trap (n=11) [10], which feature effective potentials proportional to $r^{(2n-2)}$.

The necessary condition of adiabatic motion for a trapped ion in a time-varying field is characterized by the adiabaticity parameter [23]

$$\eta(\vec{r}) = \frac{2q|\nabla|\nabla\Phi(\vec{r})||}{m\omega^2},\tag{5}$$

Reference [23] postulates that η has to be less than 0.3 to guarantee "safe operating conditions." We have thoroughly investigated trap loss out of multipole traps [18] and found trapping to occur up to a value of 0.38 for η . Where η reaches this maximum value the surface of the trapping vol-

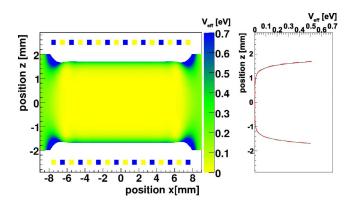


FIG. 2. (Color online) The right panel shows the analytically calculated effective trapping potential along the *z* direction (black line). The one-dimensional cut obtained from a two-dimensional numerical calculation of the effective potential (red line) cannot be distinguished from the analytical model. The result of the two-dimensional calculation is shown as a contour plot in the left panel for 16 stripes on each plane. One can clearly see the flat bottom and the steep walls of the effective potential. The nonadiabatic regions, where no stable trapping is possible, are colored in white.

ume is reached. The effective potential of this surface represents the maximum potential depth for trapped ions [18]. The right panel of Fig. 2 shows the effective trapping potential of the chip-based multipole ion trap in the region of space where adiabatic trapping is possible—i.e., where the adiabaticity criterion of $\eta < 0.38$ is fulfilled. The potential is calculated for Ar⁺ ions in a trap of amplitude $U_0=125$ V and frequency $\omega=2\pi\times5.75$ MHz. It can be seen that the effective potential is represented by a deep well with an almost flat, field-free bottom and with exponentially rising potential walls and a height of about 0.5 eV.

The electric field configuration for stable ion trapping has also been investigated in numerical simulations and the resulting effective trapping potentials and η parameters are evaluated [21]. From a two-dimensional simulation of the effective trapping potential using SIMION [24], a onedimensional cut along the z direction in the center of the trap (for x=y=0) is derived. It cannot be distinguished from the analytical model in the right panel of Fig. 2. Both results are found to agree within 1%, which proves the applicability of the analytical model in the region of the trap where adiabatic motion prevails. The full two-dimensional calculation in the xz plane is shown in the left panel of Fig. 2. We find that the confinement in the z direction is independent of the x position for almost the entire trap. One can also see that for small and large x values the confinement due to the rf field is much weaker than in the z direction. The same holds for small and large y values. A higher confining potential in the xy plane, which is needed for sufficiently long storage times, is achieved by superimposing additional electrostatic potentials.

III. REALIZATION OF THE TRAP AND LOADING SCHEME

Two planes of gold electrodes on top of two glass substrates that face each other form the ion trap. Design and



FIG. 3. (Color online) Photograph of one of the two ion trap chips mounted into its holder. The second chip (not shown) is mounted 5 mm above, facing the first chip. The metal bars surrounding the chip serve to shield the chip from electrostatic charging.

fabrication of the chip-based ion trap using MEMS technology will be described in a separate publication [21]. Figure 3 shows a picture of one of the two glass substrates with the rf electrodes, spaced at $\pi x_0 = 1000 \pm 5 \ \mu m$, and several static electrodes surrounding the comb structure. Besides providing three-dimensional trapping, these static electrodes are also used for the controlled extraction of trapped ions. The second glass chip is mounted facing the first one at a distance of $z_0=5\pm0.1$ mm.

The trap is kept in a vacuum chamber at a residual gas pressure of about 10^{-8} mbar generated by a 500 1/s turbo molecular pump. It is mounted in a holder fixed at one flange which also supports the electrical connections for the trap. The radiofrequency amplitude of the trap is generated by amplifying the signal of an rf oscillator (Hameg HM8032) in a high-frequency power amplifier (RFPA RF001100-8). To reach sufficiently high amplitudes the output is transformed by a coil on a high-frequency ferrite core located close to the trap outside the chamber. In this way peak amplitudes of $U_0=0-250$ V and frequencies in the range of $\omega/(2\pi) = 3-6.5$ MHz are applied.

Ions are created by electron impact on neutral atoms inside the trap. This is achieved by crossing a pulsed gas beam from a piezoelectric valve [25] with a pulsed 1-kV electron beam in the center of the trap. Creating the ions inside the trap is favored over ion transport and capturing techniques due to its simplicity but causes charging of non conducting parts (see Sec. V) as well as a higher background pressure for the first tenths of ms after the pulse. When ions are created the electron beam is adjusted by optimizing the ion signal on a channeltron detector, which is mounted opposite of the pulsed valve and is set up to detect and amplify individual ion pulses. The number of ions hitting the detector are measured using a single-channel discriminator and a counter. Large numbers of trapped ions are measured by digitizing the current signal of the channeltron with an oscilloscope. The data acquisition timing is controlled with an AVR Atmel microprocessor (AT90S8515).

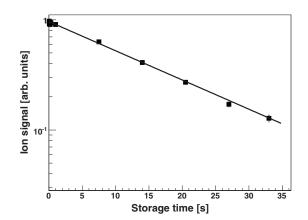


FIG. 4. Number of ions extracted from the trap after different storage times. The data points are averaged over a series of individual measurements. Where the accuracy of the average is not indicated by error bars it is denoted by the symbol size. The solid line is showing an exponential fit with a lifetime of 16 s.

IV. CHARACTERIZATION OF THE TRAP

Operation of the planar ion trap with Ar^+ ions has been achieved with the design parameters for the rf and dc potentials obtained from the numerical simulations—i.e., $\omega = 2\pi \times 5.75$ MHz and $U_0 = 125$ V. The best operating conditions are found by optimizing the electrostatic electrodes surrounding the trap. These optimal settings result in static voltages of up to a few volts. The setup is found to be stable against slight variations of single static potentials: varying the static potentials by less than 1 V from their optimum values decreases the lifetime due to a lower potential depth, but trapping is still possible.

For extraction the potential of the surrounding border electrode in the direction of the detector is lowered to -15 V. More negative extraction potentials lead to a decrease in ion signal as the ions are hitting the electrode. More positive extraction potentials lead to a smearing of the ion signal in the time domain as the ions close to the border are accelerated by the extraction potential, but the ions farther away are much less influenced. In experiments with few trapped ions, between several tens and up to about 200, the ions are counted individually, with the maximum count rate limited by overlapping ion signals in the counter. We use these data to calibrate the analog current signal of the channeltron detector to the ion number. In this way the largest observed analog signals of trapped ions are found to contain about 3000 ions.

For the ion trap we determine a 1/e decay time of 16 s from the measured decrease of the trapped ion signal with storage time (see Fig. 4), which corresponds to a loss rate of 0.06 s⁻¹. This lifetime can be compared to the evaporation limited lifetime over the rim of the trapping potential [18]: The evaporation rate is given by

$$k(T) = Ae^{-E_a/k_B T},\tag{6}$$

where the trap depth $E_a \approx 0.5$ eV is taken from the effective potential calculation of Sec. II. The temperature of the trapped ions is estimated to be roughly room temperature,

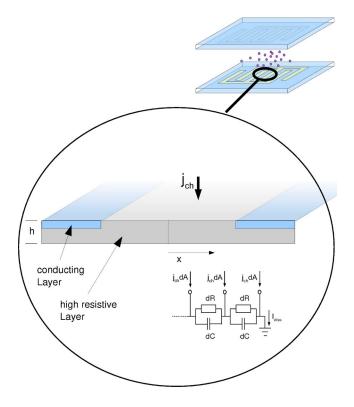


FIG. 5. (Color online) The picture shows a cut through the chip. The high-resistive region (substrate), enclosed by two conducting parts (electrodes), can be charged by a current of free electrons. The circuit diagram shows how the charging current that hits the surface elements, dA, is discharged along surface in the x direction, described by the differential resistances dR and capacitances dC.

controlled by collisions of the trapped ions with the gas injected into the trap chamber after ion formation. The prefactor *A* is assumed to be similar to the value obtained in the 22-pole ion trap, $A = 10^7 \text{ s}^{-1}$ [18]. This is reasonable given that the prefactor is of the same order of magnitude as the trapping frequency, which is set to be similar for the two traps. This yields an evaporation rate of about 0.02 s⁻¹, which is only a factor of 3 away from the measured storage time. This is considered a fair agreement when keeping in mind the exponential dependence of the evaporation rate on the trap depth E_a .

V. ELECTROSTATIC CHARGING

Avoiding stray charges and investigating their effects where they cannot be completely eliminated is a central issue in the design of microtrap structures where conducting and nonconducting areas are lying close to each other and to the center of the trap [3]. In our current trap design these charging effects are non-negligible and affect both trapping efficiency and storage time.

The steady-state potential of the glass surface induced by charging can be calculated assuming a constant current density j_{ch} that is flowing onto the surface and a resistivity-limited discharging current I_{dis} within the glass (see Fig. 5). The current inside the surface flows from the middle

of the high-resistive region (denoted as x=0) to the two neighboring electrode stripes. A surface area $x \Delta y$ (with $0 < x < \pi x_0/4$ perpendicular to the stripes and Δy parallel to the stripes) leads to a discharging current at the position xinside the glass of

$$I_{\rm dis}(x) = j_{\rm ch} x \,\Delta y. \tag{7}$$

Under steady-state conditions only the resistivity of the glass substrate and not the parallel capacity determines the potential (see equivalent circuit diagram in Fig. 5). This leads to a potential gradient at a position x between the stripes of

$$\frac{dU}{dx} = \frac{\rho}{h\Delta y} I_{\rm dis}(x), \tag{8}$$

where the discharging current I_{dis} flows through the area $h \Delta y$ in the glass chip and ρ denotes the specific resistance of the glass. Integration from x=0 to $x=\pi x_0/4$ yields the electric potential at the center of the high-resistive region (x=0) of

$$U_{\rm ch} = \frac{1}{2} \frac{\rho}{h} j_{\rm ch} \frac{(\pi x_0)^2}{16},\tag{9}$$

with respect to the electrodes. For an estimation of the amount of charge needed to significantly influence storage of ions we assume that a potential of 500 mV between two rf electrodes, a value similar to the depth of the effective potential, will preclude trapping of ions. The resistivity ρ of the glass substrate (thickness h=0.05 cm) is extrapolated from the material data sheet [26] to $\approx 10^{15} \Omega$ cm. Thus, a potential of 500 mV is obtained for a charging current density of about 5×10^5 electrons per cm² per second. For the two entire chips with their total glass surface of 2×4.5 cm², this means that a charge flux of about 5×10^6 elementary charges per second will have a significant influence on trapping and storage. At the typical repetition rate of the experiment of 10 cps, where each cycle includes loading the trap, storage, extraction and detection of the trapped ions, this yields a maximum allowable current of 5×10^5 charges per trap loading.

To investigate charging effects of the planar ion trap experimentally, the trapping efficiency is measured for different average currents of the electron beam used for ionization. We define the trapping efficiency as the number of ions trapped after 10 ms of storage time. This time is much shorter than the lifetime of trapped ions, but is also long enough to allow for complete randomization of ion trajectories. In the experiment, charging of the chips' surface stems from the electron beam, which is pulsed on only during loading of the trap. The average charging current can therefore be varied by changing the repetition rate of trap loading from 0.1 Hz to 20 Hz. The trapping efficiency is measured for many trapping cycles over a time span of several hours. In Fig. 6 the change in the trapping efficiency is shown when the repetition rate is changed from 2 Hz to 5 Hz and back to 2 Hz. With the higher repetition rate the charging increases and consequently the trapping efficiency decreases until the repetition rate is set back to 2 Hz and the charging is reduced again. The time constants for reaching steady-state trapping efficiencies upon increased and decreased surface charging are

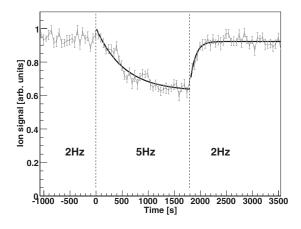


FIG. 6. The picture shows a decrease in trapping efficiency after changing from two loading cycles per second to five loading cycles per second. The increase on the right side of the graph is the result of switching back again to two loading cycles per second.

obtained by fitting a decay curve $A \exp(-t/\tau) + B$ and a growth curve $A[1 - \exp(-t/\tau')] + B$ to the data (solid line in Fig. 6). The obtained values for increased and decreased charging amount to $\tau \approx 600$ s and $\tau' \approx 100$ s, respectively. The observation of two different values may indicate that the increased charging is limited by the current j_{ch} whereas the decreased charging is only limited by the intrinsic capacitance and resitivity of the substrate.

To estimate the expected time constant for discharging the surface we use the equivalent circuit of the chip surface shown in Fig. 5. The time constant $\tau = dR \, dC$, which determines changes of the steady-state potential, depends on the resistance $dR = \frac{\rho}{h\Delta y} dx$ and capacity $dC = \epsilon_0 \epsilon_r \frac{h\Delta y}{dx}$. This yields the time constant

$$\tau = \epsilon_0 \epsilon_r \rho. \tag{10}$$

With ϵ_r =4.6 for the glass substrate [26] one obtains a typical time constant of about 400 s for changes of the charging potential of the glass substrate. Under the assumption that small changes of the trapping efficiency are to a first approximation proportional to small changes in the charging potential, one can compare this calculated time constant to the values obtained from the measured trapping efficiency. The order of magnitude agreement that one finds provides evi-

dence that charging of the glass surface is in fact the major cause for the observed changes in the trapping efficiency. Decreasing the resistivity of the glass substrate by an order of magnitude one can proportionally reduce the charging potentials of the substrate to an insignificant amount, while still maintaining small resistive losses for the driving rf amplitude.

VI. CONCLUSIONS AND OUTLOOK

We have presented a chip-based multipole ion trap based on a planar design, which features a large field-free trapping volume between two glass substrates carrying stripes of radiofrequency electrodes. An analytical model has been presented that describes the effective trapping potential in good agreement with numerical calculations. Trapping of ions has been demonstrated and the measured decay rate of trapped Ar⁺ ions follows the expectations from evaporative losses over the rim of the confining potential. The effect of surface charging, due to the highly resistive glass substrates, on the ion trapping efficiency has been experimentally studied. The charging potential and the observed time constant for reaching steady-state conditions have been successfully modeled using an appropriate equivalent circuit, which is based on the resistivity and capacity of the glass substrate.

As a next step, we will add a drift tube for the extracted ions to implement a Wiley-McLaren [27] type time of flight mass spectrometer. To characterize the density distribution of the trapped ions, photodetachment tomography experiments [16] will be carried out. Further improvements of the design and the fabrication techniques of the trap are under development, including electrode materials with high optical transmission [21]. This will allow the combination of the chipbased multipole ion trap with a magneto-optical trap for ultracold neutral atoms for experiments on interactions of trapped ions and clusters with ultracold atoms.

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