Robust and fast microwave-driven quantum logic for trapped-ion qubits

M. A. Weber ⁽⁰⁾, M. F. Gely, R. K. Hanley, T. P. Harty, A. D. Leu ⁽⁰⁾, C. M. Löschnauer, D. P. Nadlinger ⁽⁰⁾, and D. M. Lucas^{*} Clarendon Laboratory, Department of Physics, University of Oxford, Parks Road, Oxford OX1 3PU, United Kingdom

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Microwave-driven logic is a promising alternative to laser control in scaling trapped-ion based quantum processors. We implement Mølmer-Sørensen two-qubit gates on ${}^{43}Ca^+$ hyperfine clock qubits in a cryogenic (≈ 25 K) surface trap, driven by near-field microwaves. We achieve gate durations of 154 µs [with 1.0(2)% error] and 331 µs [0.5(1)% error], which approaches the performance of typical laser-driven gates. In the 331 µs gate, we demonstrate a Walsh-modulated dynamical decoupling scheme which suppresses errors due to fluctuations in the qubit frequency as well as imperfections in the decoupling drive itself.

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Quantum logic gates capable of reliably entangling qubits are a key to quantum technologies such as atomic clocks [1], quantum networking [2] and quantum information processors [3]. Trapped-ion based systems currently define the state-ofthe-art in many aspects of these technologies [4–7]. Usually, lasers are used to drive entangling gates, with the lowest reported gate errors at the 0.1% level, and corresponding gate durations in the 1.6 μ s to 100 μ s range [8–11]. Alternatively, quantum gates can be driven by electronic methods, with spatial magnetic field gradients generated using direct currents (DC) [12,13], radio-frequency (RF) currents [14,15] or microwave (MW) currents [16,17]. These laser-free approaches benefit from exceptional single-qubit control and ion addressability [18,19], the ability to embed waveguides into microfabricated ion traps, and the absence of photon scattering errors [8,20]. Compared to laser systems, MW technology also boasts lower cost, greater reliability and easier control over phase and amplitude, making MW driven logic an attractive route to scaling ion traps to larger systems. However, MW entangling gates, at speeds similar to laser-driven gates, have not been demonstrated with errors sufficiently low for error correction [21].

In this Letter, we demonstrate MW driven gates with durations close to laser gates, while maintaining errors below the $\approx 1\%$ error correction threshold [21]. As shown in Fig. 1, these gate operations are an order of magnitude faster than the previous state-of-the-art for low-error gates using MW gradients [22], five times faster than RF-gradient gates [23], and have significantly lower error compared with the fastest laser-free gates [24]. We obtain this speedup through the use of a low ion height (40 µm) in a cryogenically-operated surface trap, as well as the choice of a high-field qubit "clock" transition in ⁴³Ca⁺ at 28.8 mT. We also propose an approach to dynamical decoupling, where the qubit is resonantly driven during the gate to ensure protection against qubit-frequency drifts, but the phase of the resonant drive follows a Walsh sequence to ensure no net qubit rotation results from dynamical decoupling by the end of the gate. Such schemes have previously been considered for single-qubit gates [25].

Experiments are performed in a microfabricated segmented-electrode surface Paul trap, operated cryogenically at ≈ 25 K, with a 40 µm ion height. A cross-section of the electrode layout is shown in Fig. 2(a). The magnetic field strength generated by the counter-propagating MW currents, corresponding to the two arms of an on-chip $\lambda/4$ -resonator, is shown in Fig. 2(b). Upon cryogenically cycling the system, the trap has exhibited different MW field distributions, labeled A and B, which appear to be reproducible. We suspect this is due to structural changes induced by thermal contractions, as we have previously observed similar effects due to small changes in the on-chip RF path (see Ref. [30]). Both field distributions are featured in the different gate measurements discussed below. A more detailed description of the trap design is provided in Ref. [30]. A description of the control system and the MW drive chain can be found in Refs. [19,31].

As a qubit, we use the $|F = 4, M = 1\rangle$ and $|F = 3, M = 1\rangle$ hyperfine states within the $4S_{1/2}$ ground level manifold of ${}^{43}Ca^+$. The qubit transition, as well as neighboring states, are shown in Fig. 3. At our operating static magnetic field of 28.8 mT, the frequency of this transition is first-order insensitive to the static magnetic field, forming a "clock" transition. When compared to previous work [22], this π -polarized qubit enables ≈ 2 times faster two-qubit gate operations when driven by the same field. This arises from a larger matrix element and more efficient use of the linearly polarized MW gradients which are generated by our electrode geometry, see Ref. [30]. The techniques used for ion state-preparation and measurement (SPAM), loading and cooling are described in Ref. [30].

Entangling gates are mediated by a collective motional mode of the ions. In our case we use the in-plane radial "rocking" ("out-of-phase") mode of a two-ion crystal (referred to hereafter as the gate mode). This mode was chosen for its low heating rate $\lesssim 2$ quanta/s, limiting gate errors to

^{*}Contact author: david.lucas@physics.ox.ac.uk

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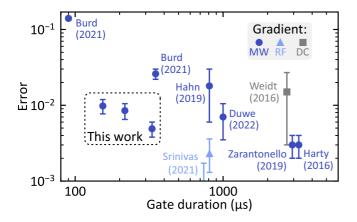


FIG. 1. State-of-the-art for laser-free entangling gates. Bell-state preparation errors and durations for a selection of two-qubit gates demonstrated with laser-free schemes. Different colors correspond to different methods of engineering spatial gradients: DC magnetic field gradients or "magic" scheme [26], RF gradient [23], or near-field MW gradient (as in this work) [22,24,27–29].

 $\lesssim 2 \times 10^{-4}$. To reduce the gate sensitivity to motional frequency fluctuations [32], we use dark resonance cooling of all modes followed by Raman sideband cooling to the ground state of the gate mode, with an average number of phonons

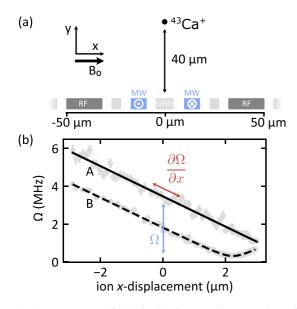


FIG. 2. Ion trap and field distribution. (a) Cross section of the electrode layout of the surface-electrode trap. A static magnetic field (labeled B_0) of 28.8 mT sets the quantization axis for the trapped ⁴³Ca⁺ ion. The qubit transition of the ion is driven by MW fields parallel to the quantization axis. This MW field component is measured and displayed in (b) as a Rabi frequency Ω scaled to the MW power used in gate implementations. The Rabi frequency is measured as a function of ion displacement in the in-plane radial direction *x*. The spatial gradient $\partial \Omega / \partial x$ is proportional to the gate Rabi frequency Ω_g , which sets the gate duration. The two MW field distributions shown, labeled A and B, correspond to measurements on two different dates, and reflect the change in trap properties attributed to structural changes in the trap upon thermal contraction when cryogenically cooling the trap to ≈ 25 K.

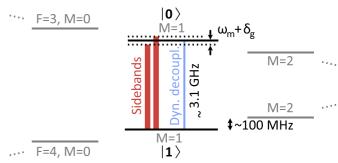


FIG. 3. Clock qubit transition. Relevant ${}^{43}Ca^+$ ground level hyperfine states, and the MW dynamical decoupling and sideband tones used to drive the gate. Compared to previous laser-free gate demonstrations in ${}^{43}Ca^+$ [22], this " π " qubit transition benefits from a more efficient coupling to the linearly polarized MW field, and a larger matrix element [30], contributing, with the trap design, to the measured decrease in gate time.

 $\lesssim 0.02$. Similarly, we ground-state cool the in-plane radial center-of-mass mode to an average number of phonons $\lesssim 0.1$, to reduce the impact of sideband dynamics driven on this spectator mode.

The two-qubit gates in this work are of the Mølmer-Sørensen (MS) type [33]. When driving the ion crystal with a single MW tone, the Rabi Hamiltonian is modulated by the ions' motion, following

$$\hat{H} = \hbar \omega_{\rm m} \hat{a}^{\dagger} \hat{a} + \frac{\hbar \omega_q}{2} \hat{S}_z + \hbar \left(\Omega \hat{S}_{x,+} + \frac{1}{\sqrt{2}} \frac{\partial \Omega}{\partial x} \hat{x} \hat{S}_{x,-} \right) \cos(\omega t), \qquad (1)$$

where Ω is the Rabi frequency, ω , ω_q and ω_m are the frequencies of the MW field, qubit transition, and motional mode, respectively. The displacement operator for the ion motion is $\hat{x} = x_{zpf}(\hat{a} + \hat{a}^{\dagger})$, with mode annihilation operator \hat{a} and zero-point fluctuations $x_{zpf} = \sqrt{\hbar/2m\omega_m}$, where *m* is the mass of a single ion. The components of the motional mode eigenvectors appear as a factor $1/\sqrt{2}$ [34,35]. The Pauli operators for the internal states of both ions (labeled 1 and 2) are combined into single expressions $\hat{S}_{x,\pm} = \hat{\sigma}_{x,1} \pm \hat{\sigma}_{x,2}$ and $\hat{S}_z = \hat{\sigma}_{z,1} + \hat{\sigma}_{z,2}$. In the presence of two tones, with frequencies near-resonant with the red and blue motional sidebands of the qubit transition [$\omega = \omega_q \pm (\omega_m + \delta_g)$], and of equal amplitude (Rabi frequency Ω), the Hamiltonian approximates to

$$\hat{H}_{g} \simeq \frac{\hbar\Omega_{g}}{2} \hat{S}_{x,-} (\hat{a}e^{-i\delta_{g}t} + \hat{a}^{\dagger}e^{i\delta_{g}t}),$$

$$\Omega_{g} = x_{zpf} \frac{\partial\Omega}{\partial x}$$
(2)

in the interaction picture. We will refer to Ω_g and δ_g as the gate Rabi frequency and detuning, respectively. Under the conditions $2\Omega_g \sqrt{N} = \delta_g$ and $t_g \delta_g = 2\pi N$, driving the sidebands for the gate duration t_g will implement a $N \in \mathbb{N}$ loop MS gate.

The dynamics of an MS gate are disturbed by the introduction of a miscalibrated, or fluctuating, a.c. Zeeman shift Δ described by the Hamiltonian $\hat{H}_z = \hbar \Delta \hat{S}_z/2$. Such errors can be suppressed by the introduction of a resonant MW tone

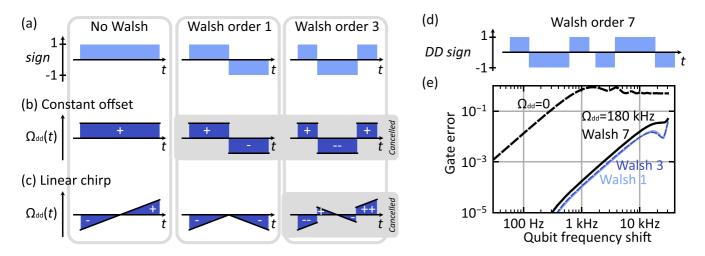


FIG. 4. Walsh modulated dynamical decoupling (a) Sign changes for Walsh sequences of order 0 (no Walsh), 1 and 3. The total sequence is of the same duration as an entangling gate. (b) Case where the continuous dynamical decoupling Rabi frequency Ω_{dd} remains constant throughout the gate. The qubit rotation driven by the decoupling tone [i.e., the integral of $\Omega_{dd}(t)$ over time] is canceled when Walsh 1 or 3 sequences are used. (c) In the case of a linear change in $\Omega_{dd}(t)$, a Walsh 3 sequence is required to cancel the qubit rotation (while still protecting against constant offsets in Ω_{dd}). (d) The Walsh 7 sequence used in the experiment, which additionally cancels quadratic changes in $\Omega_{dd}(t)$. (e) Numerical simulation of the gate error ($t_g = 331 \,\mu$ s, N = 2) in the presence of a static qubit-frequency shift. Using a $\Omega_{dd} = 180 \,\text{kHz}$ dynamical decoupling tone (with Walsh-7 modulation) significantly increases the gate's robustness to this error source.

[22,36] implementing continuous dynamical decoupling, with Hamiltonian

$$\hat{H}_{\rm dd} = \pm \frac{\hbar \Omega_{\rm dd}}{2} \hat{S}_{x,+}.$$
(3)

Since \hat{H}_{dd} commutes with the gate Hamiltonian \hat{H}_g , it will not disturb the gate dynamics, but may lead to an undesired qubit rotation by the end of the gate. To avoid this, one could use a calibrated Rabi frequency Ω_{dd} such that the gate time $t_g = 2M\pi/\Omega_{dd}$ with M an integer. However, such an approach is sensitive to Rabi-frequency fluctuations. Harty *et al.* avoid this constraint by inserting a π_y pulse half way through the gate interaction [22]. This method requires however that the Rabi frequency remains constant throughout the gate. Also, such pulses may only be inserted when the MS interaction closes a motional phase space loop, potentially forcing the use of a slower multi-loop gate.

Here we introduce an alternative method to cancel this undesired qubit rotation, by switching the sign of the dynamical decoupling drive according to a Walsh sequence. We note that Eq. (3) indicates a free choice of sign, corresponding to a π phase shift of the decoupling tone. As both choices for \hat{H}_{dd} commute with $\pm \hat{H}_{g}$, we may modulate the sign of the decoupling tone throughout the MS gate without disturbing the two-qubit gate dynamics. A first-order Walsh sequence corresponds to using two decoupling pulses with opposite signs. Any rotation accumulated in the first pulse is then canceled by the second, provided the drive strength Ω_{dd} is constant. To protect against both constant and linear variations of Ω_{dd} throughout the gate, a third-order sequence is required, as illustrated in Figs. 4(a)-4(c). A Walsh sequence of order 7 protects against quadratic changes, order 15 addresses cubic changes, etc.

We first report on the implementation of a single-loop and two-loop MS gate, with durations 154 μ s and 217 μ s respectively, without recourse to dynamical decoupling. The two sidebands are each driven with \approx 3.3 W drive tones, this power being measured at the entrance to the vacuum chamber. Based on the gate times achieved, we infer that this power generates a microwave field gradient of 89 T/m. We achieve a gate Rabi frequency of $\Omega_g = 2\pi \times 3.3$ kHz; this was accompanied by off-resonant driving of the qubit with Rabi frequency $\Omega = 2\pi \times 1.81$ MHz. At these powers, Ω is then comparable to the sideband detuning, which is close to the motional mode frequency $\omega_m = 2\pi \times 4.0$ MHz. To adiabatically suppress off-resonantly driven qubit rotations, we ramp the sideband amplitude following a sin² shape over a rise-/fall-time 2.8 µs $\gg 2\pi/\sqrt{\omega_m^2 + \Omega^2}$. Thermal transients of the trap properties and MW chain were minimised by maintaining the injected MW energy per shot constant, using dummy MW pulses (even when the apparatus is idle), see the Appendix.

We measure the error in preparing Bell states with these gates using standard tomography [37]. After correcting for the independently measured SPAM error of 0.12(1)% per ion, the single- and two-loop MS gates were measured to produce Bell states with errors of 0.98(21)% and 0.85(20)%, respectively. A parity measurement for the 217 μ s gate is shown in Fig. 5. We attribute the majority of the error to drifts of the motional frequency over the course of the gate characterization. Extrapolating from motional frequency measurements during the gate calibration measurements, we estimate that the motional mode drifted by \sim 390 Hz over \sim 2 min, giving rise to an error of $\sim 0.7\%$. The second significant error (0.17%) arises from Kerr coupling between the gate mode and the out-of-plane radial rocking mode [38]. Indeed, due to a small projection of the out-of-plane direction on the dark-state cooling laser beam paths ($\theta = 75^{\circ}$), the out-of-plane radial rocking mode remains thermally populated with approximately 20 phonons during the gate. This thermal phonon distribution couples to the inter-ion spacing thereby causing uncertainty in the gate-mode frequency. A hundredfold reduction in this error is obtained in the 331 µs gate discussed below by reducing the

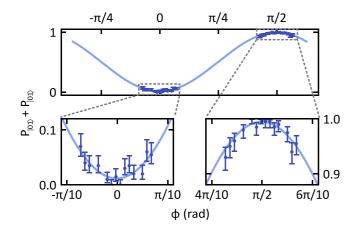


FIG. 5. Example of Bell-state preparation error measurement (217 µs gate). Following standard tomography techniques [37], the error in preparing a Bell-state $(|00\rangle + |11\rangle)/\sqrt{2}$ is inferred from the population of its constituent states $P_{|00\rangle}$ and $P_{|11\rangle}$, measured after a gate, and a measurement of coherence, which is shown here. Data points show a measurement of $P_{|01\rangle} + P_{|10\rangle}$ after subjecting the qubits to an entangling gate and a global $\pi/2$ rotation pulse with a varying phase ϕ . Coherence is measured as the ability to reproducibly rotate the Bell-state into $(|01\rangle + |10\rangle)/\sqrt{2}$ ($\phi = \pi/2$) or leave it unchanged $(\phi = 0)$ and hence corresponds to the contrast C of the oscillations in the presented data set. We concentrate data acquisition around $\phi = 0$ and $\phi = \pi/2$ in order to maximize the information content for a given data acquisition time. After a maximum-likelihood-estimate fit to the data (solid line), and subtraction of the independently measured SPAM error, the Bell-state preparation error is given by $1 - (C + P_{|00\rangle} + P_{|11\rangle})/2 = 0.85(20)\%.$

axial center-of-mass mode frequency from 2.2 to 1.1 MHz. However, this change brings the in-plane center-of-mass mode frequency closer to the gate mode frequency, creating an error of similar magnitude.

We secondly report on the implementation of a two-loop MS gate, with duration 331 µs, this time utilizing Walshmodulated dynamical decoupling. While qubit-frequency fluctuations are not expected to dominate the gate error, we aim to demonstrate here that the improved robustness offered by the scheme can be obtained without impacting the measured gate error. For the resonant decoupling tone, we use a 6 mW signal, producing a Rabi frequency $\Omega_{dd} = 2\pi \times$ 180 kHz, and which is modulated following the Walsh-7 sequence shown in Fig. 4(d). Sign changes are implemented by ramping down the resonant tone and subsequently ramping it up with a modified phase over the course of 0.24 µs. From gate simulations with this pulse scheme, dynamical decoupling provides protection from a wide band of qubitfrequency shifts, as shown in Fig. 4(e), which may come from drifts or miscalibrations of the a.c. Zeeman shift generated by the sideband drive. The a.c. Zeeman shift is calibrated to be $\Delta = 2\pi \times 46$ kHz in the 154 µs and 217 µs gate, and $\Delta = 2\pi \times 26$ kHz in this 331 µs gate. Other differences with the faster gates include the MW field distribution [A rather than B, see Fig. 2(b)], injected power (1.8 W per sideband, corresponding to 70 T/m and a gate Rabi frequency of $\Omega_g =$ $2\pi \times 2.1$ kHz), gate mode frequency (5.6 MHz), and pulse rise/fall-time (1 µs).

We measure a Bell state preparation error of 0.49(11)%for this 331 µs gate, after correcting for the SPAM error of 0.28(2)% per qubit. Again, we attribute the majority of the observed error to drifts of the gate mode frequency. Extrapolating mode frequency measurements acquired during the gate calibration suggest a ~130 Hz drift over the gate data acquisition, corresponding to an error of 0.2%. The second significant error (0.16%) comes from driving the sideband of a spectator motional mode, namely the in-plane radial centerof-mass mode with frequency $\omega_m + 2\pi \times 120$ kHz. This error could be mitigated by increasing the sideband tone ramp time to $\gtrsim 10 \ \mu$ s. For all gates measured in this work, other known error sources were estimated to be in the low 10^{-4} regime or below, amounting to a negligible contribution [31].

In conclusion, we have demonstrated microwave-driven entangling gates with gate times of 154 μ s, 217 μ s and 331 μ s and Bell-state preparation errors of 0.98(21)%, 0.85(20)%, and 0.49(11)% respectively. This work shows that microwavedriven gates can be as fast as laser-driven gates, while keeping

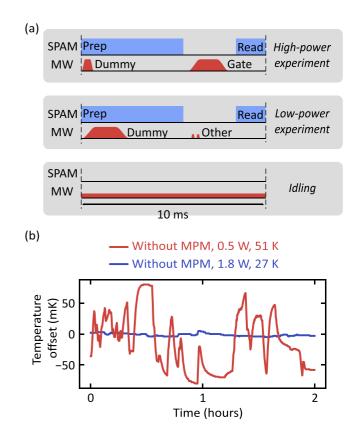


FIG. 6. Microwave power management (MPM). (a) Schematic of the MPM protocol in two example experiments, and during idling. The schematic shows the state-preparation and measurement steps (blue), and microwave pulses (red) injected over the course of a shot (fixed to a 10 ms duration). (b) Temperature variations over time for an arbitrary sequence of high- or low-power experiments, and idling periods, with and without microwave power management. The success of the MPM is even more striking when considering that in the data set with MPM approximately four times more microwave power is used (≈ 1.8 W per sideband rather than ≈ 0.5 W), and the temperature is significantly lower (27 K rather than 51 K), when compared to the data set without MPM.

gate errors below the $\approx 1\%$ error correction threshold. The dominant gate errors are technical in nature, and we expect that by engineering a more stable motional mode frequency, by speeding up both gate calibration and characterization [39,40], or by also using Walsh modulation in the sideband drive [41], the error could be lowered by an order of magnitude or more. Additionally, we have proposed and implemented a dynamical decoupling scheme for two-qubit gate operations which is robust to qubit frequency fluctuations and to imperfections of the decoupling drive itself. We note that this Walsh-modulated dynamical decoupling may also be used in conjunction with Walsh modulation of the sign of the sideband drive, allowing for gates which are robust against fluctuations of the microwave Rabi-, the qubit-, and the motional mode-frequency. This scheme may also find application in laser-driven gates for suppressing errors induced by a.c. Stark shifts [42] and in other use cases for continuous dynamical decoupling [43].

We note that microwave-driven gates with similar speeds, using a DC field gradient, have recently been demonstrated at the University of Siegen [44].

Note added in proof: RF-driven gates with similar speeds, and lower errors, have very recently been reported by Oxford Ionics Ltd [45].

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Appendix: Microwave power management protocol. The high microwave power necessary to drive fast gates causes significant fluctuations in the trap temperature, a problem which is exacerbated at cryogenic temperatures. This results in fluctuating microwave properties of the trap, which has numerous consequences for entangling gates and their characterization. For example, in the absence of any microwave power management (MPM), the microwave transfer pulses used for state-preparation, readout, and tomography, will fluctuate in their amplitude, introducing percent-level errors in the characterization of the gates. In this Appendix, we summarize the MPM protocol used during the calibration and characterization of entangling gates presented in this work. Further details regarding this technique can be found in Ref. [31].

We employ a MPM technique summarized in Fig. 6(a). First, we fix the duration of each data acquisition cycle, or "shot", to 10 ms. A shot typically comprises of a state-preparation and cooling step, microwave-driven manipulations of the qubit state, and readout. At the beginning of each shot, we use a "dummy" microwave pulse which ensures that the total microwave energy injected per shot is kept to a predefined constant value. We apply this dummy pulse during optical state preparation, where the internal state of the ion is pumped away from the qubit states, and thus the dummy pulses (applied with the same amplitude and frequencies as an entangling gate) have no effect on the qubits. When the system is idling, the microwaves are kept on, again at the same frequencies as an entangling gate, however at a smaller amplitude, to maintain the average injected power constant. As shown in Fig. 6(b), this substantially reduced thermal fluctuations.

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