Quantum vortex stability in draining fluid flows

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Quantum vortices with more than a single circulation quantum are usually unstable and decay into clusters of smaller vortices. One way to prevent the decay is to place the vortex at the center of a convergent (draining) fluid flow, which tends to force vortices together. It is found that while the primary splitting instability is suppressed in this way (and completely quenched for strong enough flows) a secondary instability can emerge in circular trapping geometries. This behavior is related to an instability of rotating black holes when superradiantly amplified waves are confined inside a reflective cavity. The end state of the secondary instability is dramatic, manifesting as a shock wave that propagates round the circular wall and nucleates many more vortices.

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I. INTRODUCTION

Quantum vortices are topological defects in the order parameter $\Psi(\mathbf{x}, t)$ describing a quantum fluid, e.g., Bose-Einstein condensates (BECs), polariton fluids, superfluid ⁴He, and photon superfluids. Their dynamics is of widespread interest due to their role in various important phenomena, including superfluid turbulence [1], topological phase transitions [2], and superconductivity [3]. The circulation of a quantum vortex is $\ell \kappa$, that is, ℓ units of circulation quantum $\kappa = h/M$, with *h* Planck's constant and *M* the mass of (bosonic) particles in the fluid. The integer ℓ counts the number of times the phase $\arg(\Psi)$ winds around the defect in the order parameter. The most basic quantum vortex has $|\ell| = 1$ and is called a singly quantized vortex (SQV), whereas a vortex with $|\ell| > 1$ is called a multiply quantized vortex (MQV).

Since the energy of a vortex scales with ℓ^2 , MQVs tend to split into clusters of SQVs as a result of an energetic instability. Hence, any mechanism that provides a reservoir to dissipate energy (e.g., coupling to a thermal bath) will cause an MQV to decay [4]. Furthermore, even in ideal conservative systems, vortices can couple to sound waves (phonons) in the fluid to produce a dynamical instability [5,6]. Because of this, many studies of quantum vortices typically employ configurations of SQVs.

There are however certain conditions under which MQVs do not decay. For example, energetic favorability of MQVs is found in rotating condensates with anharmonic (quartic) traps [7] or pinning potentials [8]. Furthermore, the dynamical splitting instability can be suppressed in finite-size systems which possess a discrete phonon spectrum [9]. Another stabilization mechanism involves filling the vortex core with a second condensate such that there is an energy barrier associated with splitting the MQV [10,11]. A well-known property of vortices (which follows from Kelvin's circulation theorem [12]) is that they tend to move under the influence of the local fluid velocity. Hence, a natural stabilizing mechanism involves placing an MQV at the focal point of a convergent fluid flow, e.g., by draining fluid from the system in a small region in the center. If the drain is strong enough, one would expect the convergence of the fluid to override the tendency of the MQV to split, rendering the vortex stable against fragmentation.

Convergent fluid flows in superfluid ⁴He were realized in [13–15] and the flow was reported to contain $O(10^4)$ vortex quanta. Motivated by these experiments, Ref. [16] simulated the evolution of vortex filaments around the drain at nonzero temperature, unveiling a formation mechanism for the vortex bundle above the drain. Three-dimensional simulations based on a Gross-Pitaevskii model containing a low number of vortices were performed in [17], which showed the convergent flow tends to focus vortices over the drain hole, twisting them into a bundle that funnels the flow into the drain below. More recently, a novel method of surface wave spectroscopy was used to constrain the core size of a macroscopic draining vortex containing $O(10^4)$ vortex quanta [18].

Multiply quantized vortex stability has also been demonstrated in exciton-polariton condensates, systems with inherent particle losses due to the finite lifetime of the polariton quasiparticles [19]. Simulations in [20] showed that a ringshaped laser beam induces particle fluxes toward the center, capable of stabilizing the MQV situated there. Furthermore, wave-vector-dependent losses can induce a convergent flow centered on each vortex, leading to an attractive force between that causes vortices to merge [21]. Stability of an $\ell = 15$ vortex was recently demonstrated in the experimental setup of [22], although in that case the fluid velocity is forced by the pump laser and the convergent flow is weak since the polariton decay is not restricted to a central region.

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In atomic BECs, convergent flows can be realized using an electron beam to ionize particles and deplete the condensate in a localized region. Numerical simulations in [23] showed that an $\ell = 2$ vortex can be stabilized by strong localized dissipation and that the vortex splits once dissipation is switched off. Giant vortex aggregates were reported in a rotating condensate in which a focused laser beam was used to remove atoms on the rotation axis [24]. These vortex aggregates were attributed to the combined effect of the Coriolis force and the radial influx of atoms.

In light of these results, one may expect that MQVs are unambiguously stabilized under a strong enough convergent flow. The purpose of this work is to demonstrate that this is not necessarily the case. It is shown that even when the primary splitting instability is quenched, secondary instabilities capable of driving the system far from equilibrium can arise. These secondary instabilities are related to the black hole bomb instability of Press and Teukolsky [25]. A rotating black hole is surrounded by an ergoregion, where fluctuations in a certain frequency range possess negative energies. Incoming radiation can scatter into these negative-energy states, causing the escaping fraction of radiation to become amplified. This process is called rotational superradiance [26]. The black hole bomb proposal involves encircling the system with a reflective mirror that scatters amplified radiation back into the black hole where it is further amplified, leading to a runaway process. A quantum vortex, which from the perspective of low-frequency sound waves can be viewed as an analogue rotating space-time [27], also possesses an ergosphere inside its core. Indeed, the MQV splitting instability can be viewed as a negative-energy bound state inside the ergosphere, which couples to sound waves outside the vortex to release energy [9,28,29]. Dissipation inside the vortex core leads to damping of this negative-energy mode, akin the classical formulation of black hole superradiance where the negative energy is absorbed by the horizon [30]. We will show that, when the vortex is located at the centered of a circularly symmetric trapping potential, superradiantly amplified sound can trigger the black hole bomb instability.

The structure of this paper is as follows. In Secs. II and III we describe the stationary draining vortex profiles of a quantum fluid. In Sec. IV we analyze the eigenmodes of the system for some illustrative parameters, demonstrating the effect of the convergent flow on stability. Section V provides an interpretation of the instabilities using a WKB approximation of the resonance formula for unstable eigenmodes. In Sec. VI numerical simulations of the fully nonlinear equations of motion are described, revealing the dramatic effect of the secondary instability on the late-time dynamics. Section VII concludes with a summary and implications of the results are discussed.

II. SETUP

For concreteness, we consider a tightly confined atomic BEC with quasi-two-dimensional (quasi-2D) dynamics in the $\mathbf{x} = (x, y)$ plane. In the mean-field approximation, the system is governed by the Gross-Pitaevskii equation (GPE)

$$i\hbar\partial_t\Psi = \left(-\frac{\hbar^2\nabla^2}{2M} + V(\mathbf{x}) - i\Gamma(\mathbf{x}) + g|\Psi|^2 - \mu\right)\Psi,\quad(1)$$

where Ψ is the order parameter, M is the mass of the particles (which are bosons), μ is the chemical potential, g is the 2D interaction parameter, $V(\mathbf{x})$ is a trapping potential, and $\Gamma(\mathbf{x})$ is a dissipation term. In the context of the BEC, localized dissipation can be achieved by illuminated the condensate with an ionizing beam [31]. The GPE applies equally to polariton condensates [22] and photon superfluids [32] and can even be considered as a phenomenological model of superfluid ⁴He on small scales [33]. We consider traps with a hard circular wall located $r = r_B$. Specifically, we use the function

$$V = \frac{V_0}{1 + (V_0 - 1)e^{a(r_B - r)}},$$
(2)

where V_0 is the height of the trap and *a* is a smoothing parameter. Unless specified otherwise, we mostly use $V_0 = a = 5$ and $r_B = 25$ in the dimensionless units defined below in (9). In the Madelung representation, $\Psi = \sqrt{n}e^{iM\Phi/\hbar}$, where $n(\mathbf{x})$ is the particle number density and $\Phi(\mathbf{x})$ a phase whose gradient gives the velocity field $\mathbf{v} = \nabla \Phi$. The GPE then separates into a Bernoulli equation

$$\partial_t \Phi + \frac{1}{2} \mathbf{v}^2 + \frac{gn + V(\mathbf{x}) - \mu}{M} = \frac{\hbar^2}{2M^2} \frac{\nabla^2 \sqrt{n}}{\sqrt{n}},\qquad(3)$$

where the term on the right-hand side is the quantum pressure modification and a continuity equation

$$\partial_t n + \nabla \cdot (n\mathbf{v}) = -2\Gamma(\mathbf{x})n.$$
 (4)

From (4) it is apparent that the function Γ acts a sink for the density. We consider a dissipation function localized at the center of the trap of the form

$$\Gamma = \Gamma_0 \frac{1 + \tanh[\kappa(r_0 - r)]}{2},\tag{5}$$

where $\Gamma_0 > 0$ is the strength of dissipation, r_0 is the radius of region where particles are lost, and κ is a smoothing parameter which we set equal to 2 in the units of (9). When $\Gamma_0 = 0$, the GPE conserves the total number of particles in the condensate $N = \int d^2 \mathbf{x} n$. For finite Γ_0 , N decreases according to

$$\partial_t N = -2 \int d^2 \mathbf{x} \, \Gamma n. \tag{6}$$

Particles then flow inward to replenish the depleted condensate inside the dissipation region, establishing a convergent fluid flow. This is the quantum analogue of the classical draining bathtub flow that forms over a physical fluid outlet [34,35]and the dissipation region can be viewed at the analogue of the drain hole. In order to establish a stationary state in the simulations of the following sections, particles will be resupplied near the edge of the trap to hold *N* fixed.

III. VORTICES

We search for stationary states containing vortices at the center of the trap. The condensate phase and velocity field are

$$\Phi = \frac{\hbar}{M} [\ell \theta + \Theta(r)], \quad \mathbf{v} = \frac{\hbar}{M} \left(\frac{\ell}{r} \hat{\mathbf{e}}_{\theta} + \partial_r \Theta \hat{\mathbf{e}}_r \right), \quad (7)$$

where **v** has the profile of a draining vortex. The radial part of the phase $\Theta(r)$ is an unknown function that must be solved for. Note that our assumption of a circular trap with the

draining vortex located at the centered implies the stationary background state described by (n, \mathbf{v}) is a function of *r* only.

We start by considering the nondraining case when $\Gamma_0 = 0$ and $v_r \equiv \mathbf{e}_r \cdot \mathbf{v} = 0$. In that case, the stationary solutions are the typical quantum vortices, whose velocity field is fully determined by the constraint of an irrotational fluid flow and the density *n* is the only function one has to solve for. The size of the vortex core is set by the healing length

$$\xi_0 = \hbar / \sqrt{M\mu_0},\tag{8}$$

where $\mu_0 = \mu(\Gamma_0 = 0)$. We can then simplify the calculation by defining the dimensionless quantities

$$\frac{\mathbf{x}}{\xi_0} \to \mathbf{x}, \quad \frac{\mu_0 t}{\hbar} \to t, \quad \frac{\mu}{\mu_0} \to \mu,$$
$$\frac{gn}{\mu_0} \to n, \quad \frac{M\Phi}{\hbar} \to \Phi. \tag{9}$$

In these units, the chemical potential for the nondraining vortex is unity by definition. In equilibrium, the density is determined by the equation

$$\frac{1}{2}\nabla_r^2 z + \left(1 - \frac{\ell^2}{2r^2} - V(r)\right) z = z^3,$$
 (10)

where $z = \sqrt{n}$ and $\nabla_r^2 = \frac{1}{r} \partial_r r \partial_r$.

The presence of a radial component of v complicates the flow pattern. To simplify the expressions, we work with the dimensionless quantities defined in (9). In equilibrium, Eq. (4) implies $\partial_r(rnv_r) = -2r\Gamma n$, which is solved by

$$v_r(r) = -\frac{2\int_0^r dr' r' \Gamma(r') n(r')}{n(r)r} \\ = \begin{cases} -D/r, & r \ll r_0 \\ -\Gamma_0 r/(\ell+1), & r \gg r_0, \end{cases}$$
(11)

where $D = 2 \int dr r \Gamma n/\mu$ is the drain constant and the integral is performed over the region where $\Gamma(r)$ has support. Hence, approaching the center from the boundary, the radial velocity magnitude increases as the fluid converges on the dissipation region. Inside the dissipation region, particles are lost and mass conservation causes a decrease in the radial velocity magnitude, with v_r vanishing at the very center. Using these properties of v_r , Eq. (3) implies the following asymptotics for the density:

$$n(r) = \begin{cases} \mu - (\ell^2 + D^2)/2r^2, & r \gg r_0 \\ r^{2\ell} [A + Br^2 + O(r^4)], & r \ll r_0, \end{cases}$$
$$B = A(A\delta_{\ell 0} - \mu)/(\ell + 1). \tag{12}$$

Here the value of *A* can only be determined from the full solution and $\delta_{\ell 0}$ is the Kronecker delta function. For $\ell = 0, A > 0$ since it is the value of the density at r = 0. It will turn out that $A < \mu$ so that B < 0, i.e., *n* has negative curvature at r = 0. This implies that the density is a nonmonotonic function of *r*. When $\ell \neq 0$, *A* is also positive since it determines the rate at which the density rises from zero at the vortex center.

To search for equilibrium states when $\Gamma_0 \neq 0$, we apply the following prescription. Starting from the nondraining solution, we switch on a finite value of Γ_0 so that the density in the





FIG. 1. Stationary draining flow profiles for $r_0 = 5$: (a) density n and (b) radial velocity magnitude $|v_r|$ for three illustrative values of Γ_0 , and the variation of (c) the chemical potential μ , (d) the drain rate D, and (e) the horizon radii r_h with Γ_0 .

region $r < r_0$ begins to deplete. We then resupply the depleted particles near the edge of the trap. The over density near r_B will cause the condensate to flow inward toward the center, establishing a convergent radial flow. The fixed particle number N is accommodated by a shift in the chemical potential. The details of this procedure are described in Appendix A 1.

In Fig. 1 we display some examples of the density and radial velocity profiles when there is no vortex present. The density exhibits a depression moving toward the center followed by a sudden rise at the very center. This is the behavior anticipated in (12). The magnitude of the radial velocity displays the properties anticipated in (11), although the behavior in the intermediate region can be intricate due to the nonmonotonic nature of the density. As expected, the chemical potential adjusts as we increase Γ_0 but keep N fixed. The general increase in μ results from v_r lowering the density in the dissipation region, thereby pushing atoms into the bulk and raising the asymptotic density level. However, the variation of $D(\Gamma_0)$ reveals a curious feature that beyond a certain Γ_0 , stronger dissipation can weaken radial flow, i.e., the more one tries to drain the fluid, the less one manages to achieve it. This is related to the macroscopic Zeno effect studied in [23], although in their case, the drain rate monotonically decreases at large Γ_0 since the chemical potential is fixed. We also display the locations r_h satisfying $(n - v_r^2)|_{r=r_h} = 0$. In the region where *n* is close to its asymptotic value, this represents the location where radial flow exceeds the sound speed \sqrt{n} , i.e., the acoustic horizon [36]. Note that, since v_r decreases toward the origin, the horizon necessarily comes as a black hole-white hole horizon pair.

In Fig. 2 we illustrate the effect of placing a vortex (in this case one with $\ell = 2$) in the center of the dissipation region. Since the density drops to zero on the vortex axis, there are fewer particles present in the dissipation region to be damped; hence the radial velocity is smaller when compared



FIG. 2. (a) Density and (b) radial velocity profiles when there is an $\ell = 2$ located at r = 0. The legend gives the dissipation function parameters in the format (r_0, Γ_0) . The radial velocities are much weaker than the $\ell = 0$ case since the vortex reduces the density in the dissipation region. Also shown is the dependence of (c) μ , (d) *D*, and (e) r_h on the dissipation strength for two different values of r_0 . Decreasing the size of the dissipation region weakens the draining flow.

with the $\ell = 0$ case. The black lines represent $r_0 = 5$ (same as Fig. 1) whereas the red lines are for $r_0 = 2$, illustrating that the draining flow is weaker when the dissipation region is smaller as one would expect.

IV. EIGENMODES

To find out whether the stationary profiles obtained above are stable, we analyze their perturbations. The perturbed order parameter may be written

$$\Psi = e^{i\Phi} \left(\sqrt{n} + \sum_{m \ge 0} (ue^{im\theta} + v^* e^{-im\theta}) \right), \qquad (13)$$

where u = u(r, t; m) and v = v(r, t; m) are the radial eigenfunctions. Under this decomposition, the linearized equations may be written as

$$i\partial_{t} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{bmatrix} \mathcal{D}_{+} - i\tilde{\Gamma} & n \\ -n & -\mathcal{D}_{-} - i\tilde{\Gamma} \end{bmatrix} \begin{pmatrix} u \\ v \end{pmatrix},$$
$$\mathcal{D}_{\pm} = -\frac{1}{2} \nabla_{r}^{2} + \frac{(\ell \pm m)^{2}}{2r^{2}} + \frac{v_{r}^{2}}{2} \mp iv_{r}\partial_{r} + 2n + V - \mu,$$
$$\tilde{\Gamma} = \Gamma + \nabla \cdot \mathbf{v}/2. \tag{14}$$

This implies

$$\partial_t \mathcal{N} = -2 \int d^2 \mathbf{x} \, \Gamma \rho_n, \qquad (15)$$

where $\mathcal{N} = \int d^2 \mathbf{x} \rho_n$ is the norm and $\rho_n = |u|^2 - |v|^2$ is the norm density, i.e., the norm is not conserved in the presence of a dissipative mechanism. Unlike the preceding section where

we resupplied N near r_B , we do not replenish the dissipated mode norm since our reinjection strategy in Sec. VI will assume all lost particles are resupplied to the axisymmetric background solution. Notice that the norm density (and hence the norm) can be either positive or negative.

In the stationary state, the operator on the right-hand side of (14) is t independent and the equation is separable. Writing $(u, v)^{T} = a(t)(\tilde{u}, \tilde{v})^{T}$, we find

$$\omega \begin{pmatrix} \tilde{u} \\ \tilde{v} \end{pmatrix} = \begin{bmatrix} \mathcal{D}_{+} - i\tilde{\Gamma} & n \\ -n & -\mathcal{D}_{-} - i\tilde{\Gamma} \end{bmatrix} \begin{pmatrix} \tilde{u} \\ \tilde{v} \end{pmatrix}$$
(16)

and $i\partial_t a = \omega a$, which is solved by $a(t) = a(0)e^{-i\omega t}$, where $\omega = \omega^r + i\omega^i \in \mathbb{C}$. The equation for the norm in (15) implies the modulus of *a* behaves like

$$|a(t)| = |a(0)|e^{\omega^{i}t}, \quad \omega^{i} = -\frac{1}{\mathcal{N}}\int d^{2}\mathbf{x}\,\Gamma\rho_{n}, \quad (17)$$

where ω^i is a spatial averaging of the dissipation function weighted by the norm density. For uniform dissipation, we find $\omega^i = -\Gamma$ and all modes are damped irrespective of the sign of their norm. When Γ varies in space, the sign of ω^i depends on the sign of the norm density in the dissipation region. In that case, both growing (i.e., unstable) and decaying modes can exist.

Note that the naive expectation that the dissipation function should damp positive-energy modes and enhance negativeenergy ones [where $\mathcal{H} = \text{Re}(\omega)\mathcal{N}$ is the mode energy] is not satisfied here. Unlike damping found in stochastic formulations of the GPE [37], the dissipative term in (1) decreases the particle number rather than the energy, which is the statement of (6). The important thing for modes is whether ρ_n in the dissipation region has the opposite sign to \mathcal{N} , as expressed by (17).

To solve (16) for the eigenvalues ω and radial eigenfunctions $(\tilde{u}, \tilde{v})^{\mathrm{T}}$, we diagonalize the matrix in square brackets using standard numerical algorithms (see Appendix A2). Figure 3 shows the eigenvalues ω obtained in this way for the $\ell = 2$ vortex. Figures 3(a) and 3(c) show the trajectories of the eigenvalues through the complex plane as Γ_0 is varied, for m = 1 [Fig. 3(a)] and m = 2 [Fig. 3(c)]. We also show the effect of varying the size of dissipation region by displaying results for $r_0 = 2$ (red lines) and $r_0 = 5$ (black lines). As Γ_0 increases, most modes in the spectrum tend to migrate down into the lower half plane where $Im(\omega) < 0$. However, certain modes can acquire a small positive imaginary part when the dissipation is turned on, with more unstable modes arising for smaller dissipation regions. This is further exemplified by Figs. 3(b) and 3(d), which display the variation of the eigenvalues $\text{Im}(\omega) > 0$ with Γ_0 . The mode with $\text{Im}(\omega) > 0$ at $\Gamma_0 = 0$ is the MQV splitting instability, which stabilizes as the dissipation is increased. However, other modes in the spectrum can be unstable for $\Gamma_0 \neq 0$, with the m = 1 modes displaying the largest tendency for instability.

V. WKB METHOD

There are three key features of the spectra in Fig. 3 that require explanation: (i) the quenching of the MQV splitting instability and (ii) the existence of secondary instabilities which are (iii) fewer in number for larger r_0 . To explain this behavior,



FIG. 3. (a) and (c) Eigenvalue trajectories through the complex plane as Γ_0 is varied. The trajectories start at the solid dots ($\Gamma_0 = 0$) and end on crosses ($\Gamma_0 = 0.5$). We show results for m = 1, 2 and $r_0 = 2$, 5. The inset in (a) shows in detail the trajectories of the modes inside the gray rectangle. Note the nonuniform spacing on the vertical axis. Also shown are unstable modes for (b) $r_0 = 2$ and (d) $r_0 = 5$. The conventions for the line style and color correspond to those in (a) and (c). For most modes in the spectrum (including the MQV instability) the localized dissipation tends to make the mode decay. However, certain modes attain a positive imaginary part when $\Gamma_0 > 0$, representing a new class of unstable modes. Fewer secondary instabilities are found for larger r_0 .

we apply the WKB method of [29], the application of which to our problem is detailed in Appendix B. The basis of the approximation is to write fluctuations as a superposition of ingoing and outgoing plane waves with a radial wave number p which varies with r due to the inhomogeneous flow field. Schematically, these two modes of wave motion oscillate as

$$\exp\left(i\int (p^{\pm} + i\Gamma\partial_{\omega}p^{\pm})dr + im\theta - i\omega t\right), \qquad (18)$$

where p^{\pm} are the two solutions to local dispersion relation, which asymptotically looks like the standard Bogoliubov one, i.e., $(\omega - \mathbf{v} \cdot \mathbf{k})^2 = nk^2 + k^4/4$, with $k = |\mathbf{k}|$. Note that this gets modified inside the vortex core (see Appendix B for details). Throughout the analysis, ω is treated as a real quantity and the imaginary part obtained at the end of the procedure as a next-to-leading-order correction once the boundary conditions have been imposed.

The term in the exponent of (18) proportional to Γ describes the decay of the wave amplitude in the direction of propagation. The $\exp(i \int p^{\pm} dr)$ has different behavior in three separate regions: two propagating regions where $\Omega = \omega - \mathbf{v} \cdot \mathbf{k}$ is positive and negative, respectively, and a zone separating the two where the wave tunnels. These regions are depicted in Fig. 4. Since $\rho_n \propto \Omega$ in the WKB approximation, a mode with a given ω and *m* has a positive (negative) norm density when it is in the green (pink) area. Since the energy density is proportional to $\text{Re}(\omega)\rho_n$, a frequency that crosses from the green to the pink region undergoes superradiant amplification (see [28,29] for details on this point).

We can derive a resonance condition for modes which satisfy the boundary conditions. For those ω which cross the tunneling region in Fig. 4, it is given by

$$4 \cot S_{01} \cot(S_{2B} + \pi/4) = e^{-2I_{12}}, \qquad (19)$$

where we have defined

$$2S_{ab} = \int_{r_a}^{r_b} (1 + i\Gamma\partial_{\omega})(p^+ - p^-)dr,$$

$$I_{12} = \int_{r_1}^{r_2} |\mathrm{Im}(p^+)|dr.$$
 (20)



FIG. 4. The WKB modes in (18) can exhibit three different behaviors: propagating with positive ρ_n (green region), propagating with negative ρ_n (red region), or tunneling (gray region). These regions are delineated by the turning points $r_{0,1,2}$. The curves shown are for the parameters $\Gamma_0 = 0.05$, $r_0 = 5$, $\ell = 2$, and (a) m = 1 and (b) m = 2. Note that for $m = \ell$, the inner turning point is $r_0 = 0$ by convention.

The derivation of this formula is given in Appendix B. The *S* integrals can be split into real and imaginary parts $S_{ab} = S_{ab}^r + iS_{ab}^i$, where these two terms are the phase integral from r_b to r_a then back again and the total damping accumulated along the trajectory, respectively. When the frequency needed to solve this condition has a small imaginary part, we make the replacement $S_{ab}^r \rightarrow S_{ab}^r + i\omega^i \partial_{\omega} S_{ab}^r$, while S_{ab}^i is evaluated for ω^r since Γ_0 is assumed small. The *I* integral is evaluated in a region where p^{\pm} are complex-conjugate pairs, and the effect of damping is ignored in computing it since its contribution to (19) is already exponentially small.

Before delving into the novel features of the spectrum when $\Gamma_0 > 0$, we first we show how (19) encodes the physics of the basic MQV splitting instability in the case $\Gamma_0 = 0$. This condition describes two types of eigenmode in the system. The phonon frequencies (i.e., modes which exist outside the vortex) are exponentially close to the zeros of $\cot(S_{2B} + \pi/4)$. Similarly, excitations of the vortex core have frequencies close to the zeros of $\cot S_{01}$. However, when the zeros of the two cotangent functions are close, the exponential on the righthand side of (19) leads to a coupling between the two types of eigenmode. Let $\cot S_{01}(\omega_v) = 0$ and $\cot[S_{2B}(\omega_p) + \pi/4] = 0$. In that case, we expand (19) around the zeros,

$$(\omega - \omega_p)(\omega - \omega_v) + \epsilon |\mathcal{T}_{\bar{\omega}}|^2 / T_p T_v \simeq 0, \qquad (21)$$

where $|\mathcal{T}_{\bar{\omega}}| \simeq e^{-I_{12}(\bar{\omega})}$ is the modulus of the transmission coefficient across the tunneling zone evaluated at the central frequency $\bar{\omega} = (\omega_p + \omega_v)/2$, $\epsilon = \operatorname{sgn}(S'_{01}S'_{2B})$ with the prime denoting an ω derivative, and $T_p = 2|S'_{2B}|$ and $T_v = 2|S'_{01}|$ are the crossing times for phonons and vortex modes. In our case, $\epsilon = +1$ for $\omega > 0$ (which superradiate) and $\epsilon = -1$ for $\omega < 0$ (which do not superradiate). The eigenfrequencies are then approximately given by

$$\omega \simeq \bar{\omega} \pm \sqrt{\Delta \omega^2 - \epsilon \gamma^2}.$$
 (22)

Hence, for nonsuperradiant states there is an avoided crossing, whereas for superradiant states we obtain a complexconjugate pair (one of which is unstable) when the mode coupling $\gamma = |\mathcal{T}_{\bar{w}}|/\sqrt{T_pT_v}$ is larger than the frequency splitting $\Delta \omega = (\omega_p - \omega_v)/2$. This coupling of the negative-energy vortex mode to a positive-energy phonon is precisely the reason for the dynamical splitting instability, as the MQV radiates energy into sound when it splits [see [28,29] for a comparison between the exact spectrum and the predictions of (19)].

For the discussion of $\Gamma_0 \neq 0$, let us rewrite (19) in the two equivalent forms

$$X + e^{2iS_{01}} + ie^{2iS_{2B}}(1 + Xe^{2iS_{01}}) = 0,$$
 (23)

$$1 + iXe^{2iS_{2B}} + e^{-2iS_{01}}(X + ie^{2iS_{2B}}) = 0,$$
(24)

where we have defined

$$X = \frac{1 + e^{-2I_{12}}/4}{1 - e^{-2I_{12}}/4},$$
(25)

which is the modulus of the reflection coefficient for superradiant modes and the inverse of the same for nonsuperradiant modes. The condition (23) is amenable to studying the MQV splitting instability when the propagation time between the vortex and r_B is sufficiently large that $|e^{2iS_{2B}}| \ll 1$ (e.g., for low frequencies the relevant condition is $r_B \gg 1/\omega^i$). Note that for this exponential to be small, we must have an unstable mode with $\omega^i > 0$, which only occurs for $\omega^r > 0$. If we assume $\omega^r \gg \omega^i$, the oscillation frequency is determined to leading order by $\cos S_{01}^r(\omega^r) = 0$, describing a mode in the vortex core, and the growth rate by

$$\omega^{i} = \frac{\log X - 2|S_{01}^{i}|}{T_{v}}.$$
(26)

The first term shows that these modes are unstable due to superradiance, since X > 1 and therefore the logarithm contributes positively. The second term results from dissipation and acts to reduce the amplitude of the instability, which is consistent with Fig. 3. Physically this makes sense since the dissipation acts in the region where the mode exists, and from (15) we expect dissipation to deplete the norm density (or by proxy the amplitude) rather than the energy. Therefore, in this case, superradiance tries to make the mode grow whereas dissipation tries to stop it from growing. This explains the first feature of Fig. 3 identified at the beginning of this section.

To understand the origin of the secondary instabilities, we study the second condition (24). Consider $\omega^r > 0$ modes in the limit where dissipation is sufficiently strong that $|e^{-2iS_{01}}| \ll 1$. To satisfy this condition, the vortex core should be large enough that the mode propagating inside it has enough time to be damped significantly, which is achieved in practice for large ℓ . For a small growth rate, the leading-order condition for the oscillation frequency is $\cos[S_{2B}^r(\omega^r) + \pi/4] = 0$ describing phonons trapped outside the vortex. The growth rate is given at leading order by

$$\omega^{i} = \frac{\log X - 2|S_{2B}^{i}|}{T_{p}},$$
(27)

where the logarithmic term again contributes positively due to superradiance. When dissipation is confined to the region where the mode propagates in the vortex core, $S_{2B}^i = 0$ and phonons become unstable, explaining the second finding of Fig. 3. Physically, the negative-energy part of the mode responsible for superradiant amplification gets damped out inside the dissipation region and (to leading order) the part of the wave which reflects back can be neglected. This is the same mechanism as the black hole bomb instability, where superradiant modes outside the black hole are confined by an external mirror and the horizon provides a perfectly absorbing inner boundary. When there is dissipation in the green region of Fig. 4, S_{2B}^{i} becomes nonzero and acts to weaken the instability, completely quenching it for large enough values. This explains the third finding of Fig. 3 that secondary instabilities are suppressed for large dissipation regions. Note that, although we have considered here two specific limits (first large r_B then large ℓ), we expect the same qualitative features to emerge in the spectrum for general r_B and ℓ .

VI. NUMERICAL SIMULATIONS

In this section we explore the predictions of Fig. 3 by simulating the full nonlinear equation in (1), demonstrating the effect of the convergent flow on a pair of initially separate



FIG. 5. Intensity plots of n(x, y) from three different simulations, which differ by the dissipation strength and the initial vortex locations. We used $r_0 = 5$ and $r_B = 25$ and the *x* and *y* limits for each panel are $[-r_B, r_B]$. (a1)–(a4) Low Γ_0 simulation. The insets ($r \in [0, r_B]$ on the horizontal axis and a.u. on the vertical axis) show the spatial profile of the largest Fourier mode in a time Fourier transform of $n_{m=2}$ between the times indicated in the main panels. The measured waveforms (black lines) are in good agreement with the eigenmode (red dashed lines) of the recombination mode at early times and the splitting mode at late times. (b1) and (b2) For higher dissipation, the vortices do not separate at late times. (c1)–(c4) For an asymmetric initial condition, the inspiral can trigger a secondary instability in the m = 1 mode. The inset compares the measured waveform with the corresponding m = 1 eigenmode. (d1)–(d3) Shape of the unstable mode near the boundary in the angular direction. At late times, the wave becomes sharply peaked, triggering a short-wavelength instability at the leading edge. (b3) and (b4) Total energy and the most highly occupied *m* components near the center of the trap as functions of *t*.

vortices. We take as our initial condition a stationary flow with $\Gamma_0 \neq 0$ but no vortex. We then imprint a pair of SQVs (both rotating counterclockwise) near the edge of the trapping potential. Particles lost due to dissipation are replenished at the edge of the trap such that *N* is conserved. Details of the procedure are described in Appendix A 3 and convergence checks are presented in Appendix A 6. Figure 5 shows the results of three such simulations.

In Figs. 5(a1)-5(a4) the amount of dissipation is small and we start with the vortices located symmetrically about the center at (x, y) = (12.7, 12.7) and the antipodal point. The vortices quickly spiral into the middle and, once they are separated by around three healing lengths, the motion is well described by the conjugate mode to the MQV splitting instability, which describes vortex recombination. Between Figs. 5(a2) and 5(a3) we Fourier transform $n_{m=2}$ over the interval t = [317.2, 410] and plot the ω component with the largest amplitude (black curve), which agrees well with the recombination mode predicted from (16) (red dashed line). The frequency is computed by performing a quadratic interpolation around the peak value of the Fourier transform at r = 1.4 (where the amplitude of the spatial waveform exhibits a maximum). The growth rate is found by performing a linear regression on log $|n_{m=2}(t, r = 1.4)|$ over the same time interval. We obtain a measured eigenfrequency 0.40(3) - 0.0206(4)i,¹ which we compare against 0.439 - 0.0293i from Fig. 3. The agreement is acceptable given that at this stage,

¹For the measured eigenfrequencies, the error in the real part is half the frequency resolution, while the error in the imaginary part is quoted from the 95% confidence bounds. The predicted values are quoted to three significant figures.

the system is in a highly nonequilibrium situation. Indeed, since N is fixed, the value of μ will shift to accommodate the nonzero occupation of various excited states, leading to differences with the spectrum of Fig. 2 which was computed in equilibrium. After a long time, the vortices separate by a small amount since the dissipation is not sufficient to quench the MQV splitting instability. The measured eigenfrequency of the splitting mode (obtained using the same method as above over the interval $t \in [1000, 1400]$ is 0.44(1) + 0.00150(3)i, whereas the predicted value is 0.440 + 0.00365i. The poor agreement in the imaginary part can be attributed to the effects of N conservation and nonlinearities for high mode amplitudes. We check this by performing a simulation starting from equilibrium with a small initial amplitude in the splitting mode, finding that, once the mode grows large enough, the growth rate drops to around the measured value above. The black curves in Figs. 5(b3) and 5(b4) are the total energy H, which is a slowly increasing function at late times, and the m = 2 mode amplitude which, after an initial transient, decreases and then increases exponentially, as expected from the discussion above.

In Figs. 5(b1) and 5(b2) we show results of a simulation prepared with the vortices at the same locations but a larger value of Γ_0 . The two SQVs combine much quicker in this case and residual fluctuations dissipate away, in keeping with the fact that the spectrum contains no unstable modes for m = 1, 2. The energy [blue curve in Fig. 5(b3)] decreases very slowly at late times while $|n_{m=2}|$ decreases exponentially, exhibiting a beating effect due to the superposition of two decaying co- and counterrotating modes. These results support the idea that a dense quantum vortex cluster can be prevented from splitting by a sufficiently strong dissipation mechanism.

In Fig. 5(c) we pick a configuration where the strongest unstable mode in the spectrum is one of the secondary instabilities with m = 1. Two SQVs are placed asymmetrically around the center at (x, y) = (12.7, 12.7) and (11.5, -10.2)to promote the excitation of this mode when they spiral into the middle and combine. Between Figs. 5(c2) and 5(c3)we display the m = 1 component of the density (which is the maximum of the time Fourier transform over the interval $t \in [500, 800]$) and find good agreement with the predicted waveform. The measured eigenfrequency of this mode is 0.083(11) + 0.00068(1)i while, the predicted value is 0.0767 + 0.00236i. The real part of the frequency agrees within the estimated error. The discrepancy in the imaginary part is again attributed to the large amplitude during the measurement window (see Appendix A4 for a discussion of this point). Measurement of $Im(\omega)$ at earlier times where the amplitude is smaller is complicated by the presence of a decaying counterrotating mode, which causes the beating effect in the (red) m = 1 curve in Fig. 5(b4). Figure 5(b3) shows that there is a drastic increase in the total energy, which is due to the damping of the negative-energy part of the wave in the dissipation region. Figures 5(d1)-5(d3) illustrate the shape of the growing m = 1 mode in the θ direction near the edge of the trap. At late times, the wavefront becomes sharply peaked, which can be attributed to the nonlinear excitation of the m = 2 wave [also shown in Fig. 5(b4)], which has roughly twice the frequency of the m = 1 component. In Fig. 5(d3) a short-wavelength instability (a shock wave) appears at the

leading edge of the overdense region and propagates around the trap wall. The observed self-steepening dynamics followed by the appearance of a shock wave is similar to that studied in the 1D setup of [38].

Further development of this state is depicted in detail in Fig. 6. We show the density [Fig. 6(a)], the velocity field [Fig. 6(b)], and the angular profile of the density near r_B [Fig. 6(c)] at four different instants of time. Eventually, the angular shock wave becomes large enough that additional vortices nucleate at the trap wall, before being dragged into the center by the draining flow, which is most apparent from Fig. 6(a). The vector maps in Fig. 6(b) represent the velocity field (with the arrows scaled with respect to the largest one in the plot). We highlight regions where $v_r > 0.06$ ($v_{\theta} > 0.45$) in magenta (yellow). The overlapping regions appear as red. We find that the radial velocity is directed outward in front of the m = 1 wave. This supplies additional particles to the leading edge of the overdense region resulting in a sharp peak that continues to grow. The angular velocity of the condensate is largest in the overdense region and decreases suddenly at the leading edge, in a manner consistent with known shock wave formation mechanisms [38]. By the end of the simulation, the mass of vortices in the center was precessing in the counterclockwise direction while more SQVs continued to nucleate from the trap edge.

We briefly comment on the robustness of these results. For the data presented in Figs. 5(c), 5(d), and 6, the trap height was increased to $V_0 = 10^3$ to ensure the shock wave near the trap edge was not a consequence of the mirror image condensates arising from the periodic boundary conditions. Results qualitatively similar to those performed with $V_0 = 5$ were observed. The same is also true when an asymmetric perturbation was added to the trapping potential V (see Appendix A 5). As a further check that the shock wave was not a consequence of the numerical resolution, we checked the effect of (first) doubling the space outside the $2r_B \times 2r_B$ condensate zone while keeping the same number of grid points and (second) changing the number of grid points to $N_x = 256$ (i.e., half the spatial resolution) and the time step to $\Delta t = 10^{-2}$. The shock wave was found to form in both cases, with minor difference expected due to the change in the precise seeding conditions at different resolutions. We comment further on the convergence of the numerical algorithm in Appendix A 6.

One may also wonder whether the dynamics depends on the particle resupply strategy. For the shock wave simulation, we checked the effect of keeping the number of particles resupplied at the boundary fixed at its initial equilibrium value. In this way, the total N was not conserved during the simulation (increasing or decreasing at different times) since the drain rate varies depending on where the vortices are relative to the central dissipation region. However, the m = 1instability was still observed to trigger a shock wave in this case. Changing N changes the background density and radial flow configuration; hence the properties of the m = 1 unstable mode (the frequency and growth rate) can be expected to change. However, Fig. 3 illustrates that the instability is present over a range of background parameters (in that case Γ_0), so provided the system does not enter a stability window, one would expect the same unstable behavior to arise in the case where N varies during the evolution.



FIG. 6. (a1)–(a4) Continuation of Fig. 5(c4) with the color axis increased to clearly show the overdense region. (b1)–(b4) Vector map of the velocity field at the same times, with regions where $v_r > 0.06$ ($v_{\theta} > 0.45$) highlighted in magenta (yellow). In (c1)–(c4) we see a shock wave being generated at the leading edge of the m = 1 wave, eventually propagating all the way round the trap edge. Once the shock wave reaches large enough amplitudes, corotating vortices (a3) nucleate near the boundary and (a4) move into the center to form a giant vortex mass.

VII. DISCUSSION

Multiply quantized vortices are generally expected to decay into clusters of singly quantized vortices. A natural mechanism purported to enhance the stability of MQVs involves a dissipation mechanism which induces a convergent (draining) flow in the system [18,20,21,23]. We have demonstrated that, in circularly symmetric trapping geometries (realizable experimentally [39,40]) stability is not guaranteed, challenging the perspective that a convergent fluid flow has a stabilizing influence on MQVs.

We considered a particle dissipation term used to model losses in Bose gases illuminated with a laser or electron beam [23,24,31], polariton condensates [19,20,22], and nonlinear optical condensates (the so-called photon superfluids) [32,41]. The model also captures phenomenological aspects of superfluid ⁴He flows in the thin-film regime, with the density acting as a proxy for the height field and the dissipation representing loss of fluid from the plane, e.g., due to a physical outlet.

The observed tendencies of our system are a consequence of the dissipation reducing the particle number rather than the total energy which, when combined with an amplification mechanism, can result in secondary instabilities. Our WKB method revealed that the relevant factor is where the confined mode exists relative to the localized dissipation region. Since the MQV splitting instability is confined to the vortex core, where dissipation acts, it can be quenched. When superradiant phonon modes are confined outside the dissipation region, the negative energy transmitted into the vortex core is absorbed while the mode occupation outside the vortex increases. However, if the dissipation region extends outside the vortex core, the occupation of phonon modes can similarly be reduced. We then demonstrated that secondary instabilities can have drastic implications for the late-time dynamics of the systems, growing so large as to generate a shock wave at the edge of the condensate which seeds the nucleation of many vortices near the trap wall.

Observation of these features is within current experimental capabilities of existing platforms implementing atomic BECs. For example, in [42] a 2D planar geometry containing vortices was realized in a ⁸⁷Rb condensate with a lifetime of 28 s. In this system, the healing length is on the order of 1 µm and the natural timescale is $\tau = \xi/c \sim 1$ ms, where *c* is the sound speed. If dissipative losses are induced with an electron beam (see, e.g., [23,31]), our results suggest that the secondary instability would begin on a timescale of $10^2-10^3\tau$, well within the condensate lifetime.

For polariton condensates, stability of an MQV with 15 circulation quanta was found in [22]. In that case, dissipation was uniform throughout the system; hence superradiant phonons are dissipated as well as the MQV splitting mode. The system size and phonon decay length were approximately 70 and approximately 8 healing lengths, respectively, explaining the absence of secondary instabilities. In our dimensionless units, their dissipative parameter is $\Gamma \sim 0.1$, for which the WKB treatment of Sec. V seems reasonable. Hence, our methods could be applied to provide insight into properties of superradiance in these systems.

Finally, since Gross-Pitaevskii based models are a useful phenomenological tool for studying the microscopic dynamics of quantum liquids [1], our results may help elucidate the behavior of superfluid vortex experiments. In superfluid ⁴He, the core of a macroscopic vortex cluster is either a depression in the liquid's surface over the drain hole (which provides the effective dissipation) or a fully formed throat which plunges through it [15,18]. Studies of the problem in three dimensions reveal the formation of a complex tangle of vortex lines over the drain [16,17]. A detailed understanding of the simpler 2D problem may help identify the key mechanisms at play and may be of further use in studying the effectively 2D dynamics of waves on the superfluid interface.

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APPENDIX A: NUMERICAL METHODS

1. Stationary profiles

First, we describe our numerical technique to find the stationary draining vortex profiles. We exploit the symmetry of the desired solution by factoring out the vortex winding $e^{i\ell\theta}$ so that the equation to solve is a function of *r* only. Using the units of (9), we write (1) in the form

$$i\partial_t z = \left(-\frac{\partial_r^2}{2} - \frac{\partial_r}{2r} + \frac{\ell^2}{2r^2} + V - i\Gamma + |z|^2\right)z, \qquad (A1)$$

where $z(r) = \sqrt{n(r)}e^{i\Theta(r)-i\mu t}$. The radial grid is $r_j \in [\Delta r, r_B + d]$, where $j = 1, ..., N_r$, with $N_r = 256$, and d = 5. For the radial derivatives, we use five-point finite-difference stencils accurate to $O(\Delta r^4)$, where Δr is the radial grid step size. The behavior in (12) implies that correct boundary conditions at r = 0 are Neumann for $\ell = 0$ and Dirichlet for $\ell \neq 0$. The boundary condition at the edge of the grid is arbitrary since it is applied deep in the region where *z* goes to zero under the potential barrier. We choose it to be a Dirichlet boundary condition.

Due to the dissipation in the center, any excitations of the ground state decay away. An implicit assumption here is that there are no unstable modes with m = 0, which turns out to be true (at least for the scenarios we are interested in). Therefore, starting from an arbitrary initial state, we should eventually arrive at a *z* corresponding to the ground state provided we evolve (A1) for long enough. The evolution is enacted using a fourth-order Runge-Kutta algorithm. Here $\Delta t = 2 \times 10^{-3}$ is taken for the time step, satisfying $\Delta t < \Delta r^2/2$, which ensures stability. This means that going to higher spatial resolution is

challenging since decreasing the spatial grid step size by a factor of 2 would increase the simulation time for the stationary states by a factor of 8, while the 2D simulations described in Appendix A 3 would take 16 times longer. After each time step, we compute the number of particles ΔN lost due to dissipation. These particles are then resupplied at the edge of the trap before the next time step according to the prescription

$$z\sqrt{1 + \Delta N\beta(r)/|z|^2} \to z,$$

$$\beta = \beta_0 \begin{cases} r - r_1, & r_1 < r \leqslant r_2 \\ 1, & r_2 < r \leqslant r_3 \\ r_B - r, & r_3 < r \leqslant r_B, \end{cases}$$
(A2)

where $r_1 = r_B - 4$, $r_2 = r_B - 3$, $r_3 = r_B - 1$, and β_0 is a normalization such that $2\pi \int dr r\beta = 1$. This ensures that the total number of particles is conserved throughout the simulation.

We estimate the chemical potential at each time step t_k using $\mu_k = -\text{Im}[\log(z_k/z_{k-1})]/\Delta t$, which gives a function over the *r* grid. The evolution is continued until the maximum value of $\mu_k - \mu_{k-1}$ in the region $r < r_B$ is below 5×10^{-6} . At this point there will still be residual fluctuations in *z*. Since these are decaying, we evolve for a further 2000 (10⁴) time steps for $\Gamma_0 > 0.05$ ($\Gamma_0 \leq 0.05$) and take the value of |z| as its average during this time. The phase is measured at each point r_j and fit with the function $\Theta_j - \mu_j t$. The first term in this fit gives the phase function in (7) from which obtain v_r by enacting a ∂_r stencil incorporating the Neumann boundary condition at the origin. The second term gives the chemical potential as a function of *r*. We observe that this is constant to a high precision and take its average over the region $r < r_B$.

To generate the solutions in Figs. 1 and 2, we start by calculating the nondraining solution with $\ell \neq 0$ using an imaginary-time prescription (see, e.g., Appendix A of [28]). This is the solution for $\Gamma_0 = 0$. We then use this as our initial condition for the largest value of Γ_0 simulated (which is 0.5). This is done since the strong dissipation here will quickly damp the solution to the desired equilibrium state. We then generate the solutions for all Γ_0 in descending order, each time taking the result from the previous computation as the initial condition.

2. Eigenmodes

To solve (16) for the eigenmodes, we use the same radial grid r_j and finite-difference stencils defined in the preceding section. We choose a Dirichlet boundary condition for the edge of r grid, although the results are insensitive to this choice in the frequency range probed. The boundary condition at r = 0 is more delicate. By expanding (u, v) around r = 0 and inserting into (16), we deduce that the leading-order behavior is $u \sim r^{|m+\ell|}$ and $v \sim r^{|m-\ell|}$. Hence, we apply a Dirichlet boundary condition whenever the exponent is different from zero. Since the next term in the series is multiplied by an extra factor of r^2 , we apply a Neumann boundary condition for a zero exponent. Equation (16) is then solved using a standard matrix diagonalization routine (we apply MATLAB's eig function).

3. Nonlinear dynamics in two dimensions

For the simulations in Sec. VI of the full equation (1), we take as our initial condition a stationary solution with $\Gamma_0 \neq 0$ and no vortex, say, Ψ_0 , and interpolate this onto a Cartesian (x, y) grid. We take $x_j \in [-(r_B + d), r_B + d]$ (and similarly for y_j), where $j = 1, \ldots, N_x$, with $N_x = 2N_r = 512$, so that the resolution is comparable to our radial code. A pair of SQVs is then imprinted. For this process, we first calculate the nondraining SQV density profile which asymptotes to unity, say, $n_1(r)$, and then extend the solution to a high value of r using the expected asymptotic behavior. This solution is recentered to the vortex coordinates (x_{ν}, y_{ν}) and the initial condition becomes

$$\Psi_{\text{init}} = \Psi_0(x, y) \prod_{\nu} n_1(x - x_{\nu}, y - y_{\nu}) \\ \times \frac{(x - x_{\nu}) + i\ell_{\nu}(y - y_{\nu})}{|\mathbf{x} - \mathbf{x}_{\nu}|},$$
(A3)

where the last factor ensures the defects have the correct phase winding. We take $\ell_{\nu} = 1$, with $\nu = 1, 2$ and \mathbf{x}_{ν} given in the main text. Since the vortices merge in the center during the simulation, we multiply Ψ_{init} by a factor $(N/\int d^2\mathbf{x}|\Psi_{\text{init}}|^2)^{1/2}$ so that the system has the same total number of particles as our equilibrium solutions in Fig. 2 (which, we recall, have the same *N* as a nondraining MQV with unit chemical potential by construction). The time evolution is then performed using a split-step Fourier spectral method. More specifically, given the solution at time t_k , we find Ψ at t_{k+1} according to

$$\begin{split} \tilde{\Psi}_1 &= e^{-i\Delta t (V - i\Gamma + |\Psi_k|^2)/2} \Psi_k, \\ \tilde{\Psi}_2 &= \mathcal{F}^{-1} [e^{-i\Delta t \mathbf{k}^2/2} \mathcal{F}(\tilde{\Psi}_1)], \\ \Psi_{k+1} &= e^{-i\Delta t (V - i\Gamma + |\tilde{\Psi}_2|^2)/2} \tilde{\Psi}_2, \end{split}$$
(A4)

where \mathcal{F} and \mathcal{F}^{-1} denote the 2D Fourier transform and its inverse on the (x, y) grid, with **k** coordinates in Fourier space, and we set $\Delta t = 4 \times 10^{-3}$. At the end of each time step, we resupply particles lost through dissipation at the edge of the trap with the same prescription used to find our stationary solutions in the radial simulations. In this way, the total particle number is conserved throughout the evolution. We can think of this as representing a scenario where a fixed number of particles remains in circulation.

4. Mode growth

In the simulations of Fig. 5, we found discrepancies between the measured eigenfrequencies and the predicted ones, particularly in the imaginary part. We attribute this to nonlinear effects at large mode amplitudes as well as our resupply strategy, which keeps N fixed at the expense of depleting the background for large mode occupations. We illustrate an example of this in Fig. 7 for the unstable m = 1 mode. We use the same parameters as in Fig. 5(c) except this time the initial condition is the stationary l = 2 vortex state seeded with the (normalized) m = 1 unstable mode multiplied by an amplitude 0.5. We measure the eigenfrequency for $t \leq 500$ and display the result in the figure. The growth rate and oscillation frequency are in excellent agreement with the predicted values at early times when the amplitude is small. At interme-



FIG. 7. Growth of the unstable m = 1 mode (black line) with the same parameters used for Fig. 5(c). The best fit to the absolute value over the window $t \leq 500$ is also shown (red line). The measured eigenfrequency (displayed in figure) is in excellent agreement with the predicted value of 0.0767 + 0.00236i

diate times, the growth rate starts to deviate from the initial value, with the amplitude saturating at late times. When the eigenfrequencies are measured in Fig. 5, the wave amplitudes are of the order 0.1, which is where the discrepancy starts in Fig. 7. This suggests that deviations in the growth rate are consistent with a nonlinear mechanism.

5. Asymmetric perturbations

We checked the effect of adding a small perturbation to the trapping potential V, using the expression

$$V = \frac{V_0}{1 + (V_0 - 1)e^{a[r_B - \tilde{r}(x, y)]}},$$

$$\tilde{r}(x, y) = \sqrt{x^2 + y^2/b^2},$$
 (A5)

which is an elliptical trap with eccentricity $e = \sqrt{1 - b^2}$. The initial condition for the 2D solver was obtained by first solving for the stationary n(r) and $v_r(r)$ profiles in the symmetric case and then separately performing an imaginary-time evolution of the 2D solver to find the profile of a nondraining l = 2vortex in the potential (A5). We then combine the two profiles such that the initial condition has the symmetric draining profile in the center and the asymmetric profile near the trap wall. Vortices are imprinted as described in Appendix A 3 at the locations shown in Fig. 5(c1). In Fig. 8 we display two illustrative snapshots for e = 0.2 and 0.5, where the times are the same as in Figs. 6(a1) and 6(a4), respectively. For e = 0.2, we observe the both the shock wave triggered by the m = 1instability and the subsequent vortex nucleation, although the vortex distribution is different from the symmetric case due to the elliptical trap deformation. For e = 0.5, a clear m = 1instability can be seen, although in this case, no shock wave



FIG. 8. Illustrative snapshots of the m = 1 instability's evolution in an elliptical trap with eccentricity *e*. For small *e* (left column), the shock wave is triggered and vortices still nucleate at the trap wall. Larger *e* (right column) appear stable against shock wave formation during the simulation time of t = 2400.

was triggered and no vortices nucleated at the edge of the trap during the simulation, which continued until t = 2400.

Importantly, this demonstrates that the shock wave phenomenon is not reliant on having a perfectly symmetric trap. Intuitively, we can expect that under a small asymmetric deformation of the reflective trap wall, the different m modes will couple to each other with a strength determined by the size of the trap deformation. Provided the energy leakage into a stable m mode is not sufficient to counteract the energy gain in the unstable mode, one would expect the shock-wave phenomenon to persist.

6. Convergence tests

Reliability of the numerical algorithm is demonstrated by checking for convergence of the unstable eigenmode frequency. The simulation parameters are the same as those used for Fig. 7 including the initial condition, except this time the resolution is varied. The m = 1 component of the density is Fourier transformed over the window $t \in [0, 500]$ when the growing mode is still in the regime of the linear theory. The oscillation frequency $\text{Re}(\omega)$ is measured by interpolating the peak in the Fourier transform with a quadratic function.

The results are displayed in Fig. 9. We show the effects of varying the time step Δt (with N = 256 fixed) and the number of radial grid points N (for $\Delta t = 4 \times 10^{-3}$). We use the prescription $N_x = 2N$ in the 2D solver and the value of Δt is used in both the stationary state (radial) solver and the full 2D solver. We find only a small variation in Re(ω) within the range of Δt and N probed. Furthermore, the variation follows the expected behavior, illustrated by the red curves, that is,



FIG. 9. Variation of the eigenfrequency measured in Fig. 7 with (a) Δt and (b) *N*. Results of the 2D simulations are shown as black crosses and the trend is shown as a red curve. The data are consistent with a linear dependence on Δt and a quadratic dependence on Δx , converging to a constant value as both these quantities go to zero.

linear in Δt and quadratic in $\Delta x \sim 1/N$ (due to the derivatives ∂_t and ∂_x^2 in the GPE), converging to constant values in the infinite-resolution limit. The spread about these curves is well within the frequency resolution of $\Delta \omega \simeq 0.013$.

APPENDIX B: WKB METHOD

In this Appendix we provide the details of the method leading to the resonance condition (19) in the main text. First, it is helpful to define new eigenfunctions g and f according to

$$\sum_{m \ge 0} e^{im\theta} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{bmatrix} g(\mathbf{x}, t) + if(\mathbf{x}, t)/2 \\ g(\mathbf{x}, t) - if(\mathbf{x}, t)/2 \end{bmatrix},$$
(B1)

which satisfy

$$(D_t - \tilde{\Gamma})f + ng + \frac{1}{4}\mathcal{D}_r g = 0,$$

$$(D_t - \tilde{\Gamma})g - \mathcal{D}_r f = 0,$$

$$\mathcal{D}_r = -\nabla^2 + \mathbf{v}^2 + 2(n + V - \mu),$$
 (B2)

and $D_t = \partial_t + \mathbf{v} \cdot \nabla$ is the material derivative. In the WKB approximation, we write

$$\begin{bmatrix} f \\ g \end{bmatrix} = \begin{bmatrix} \mathcal{A}(\mathbf{x}, t) \\ \mathcal{B}(\mathbf{x}, t) \end{bmatrix} e^{i\mathcal{S}(\mathbf{x}, t)}.$$
 (B3)

The amplitudes are assumed to vary gradually compared to the phase, that is, $|\partial \mathcal{A}| \ll |\mathcal{A}\partial \mathcal{S}|$ and $|\partial^2 \mathcal{S}| \ll (\partial \mathcal{S})^2$ (and similarly for \mathcal{B}) for **x** and *t* derivatives. Using the symmetry of the system, we can write

$$S = \int p(r)dr + m\theta - \omega t, \qquad (B4)$$

where $\nabla S \equiv \mathbf{k} = (p, m/r), -\partial_t S \equiv \omega$, and the decomposition into ω and *m* is exact since the background is independent

of t and θ . Under these assumptions, Eq. (B2) becomes

$$\Omega^{2} = nk^{2} + k^{4}/4, \quad \Omega = \omega - \mathbf{v} \cdot \mathbf{k}, \quad k^{2} = p^{2} + \tilde{m}^{2}/r^{2},$$

$$\tilde{m}^{2} = m^{2} + r^{2}\mathbf{v}^{2} + 2r^{2}(n + V - \mu)$$
(B5)

at leading order and

$$\partial_t \left(\frac{\Omega \mathcal{A}^2}{F}\right) + \nabla \cdot \left(\frac{\mathbf{v}_g \Omega \mathcal{A}^2}{F}\right) = -\frac{2\Gamma \Omega \mathcal{A}^2}{F},$$
$$F = n + \tilde{k}^2/4 \qquad (B6)$$

at next-to-leading order. A similar equation for the second amplitude can be derived using $\mathcal{B} = i\Omega \mathcal{A}/F$. In the derivation of (B5) and (B6) we have assumed that dissipation is a weak effect that enters at second order. Hence, the method applies only for low Γ_0 .

The first line of (B5) is the dispersion relation whose solutions $\mathbf{k} = \mathbf{k}(\omega, m; r)$ represent the local value of the wave vector for a given ω and m. The group velocity of the wave is then determined by $\mathbf{v}_g = (\partial_\omega \mathbf{k})^{-1}$; in particular, its radial component is $\hat{\mathbf{e}}_r \cdot \mathbf{v}_g = (\partial_\omega p)^{-1}$. Equation (B6) describes how amplitude is transported, with the term on the right-hand side acting as a damping term. Evaluating the norm density for a WKB mode gives $\rho_n = \Omega |\mathcal{A}|^2 / F$ (where this expression is evaluated on the real part of ω), so that (B6) describes how the norm is transported across the system. In particular, the sign of the norm density coincides with that of Ω and is transported in the direction of \mathbf{v}_g , that is, a fluctuation with $\Omega < 0$ has negative norm density. The mode energy is defined as

$$\begin{aligned} \mathcal{H} &= \int d^2 \mathbf{x} \bigg(\frac{1}{2} |\partial_r u|^2 + \frac{1}{2} |\partial_r v|^2 + \frac{(\ell + m)^2}{2r^2} |u|^2 \\ &- \frac{iv_r}{2} (u^* \partial_r u - u \partial_r u^* - v^* \partial_r v + v \partial_r v^*), \\ &+ \frac{(\ell - m)^2}{2r^2} |v|^2 + (2n + V - \mu)(|u|^2 + |v|^2) \\ &+ n(uv^* + u^*v) \bigg), \end{aligned}$$
(B7)

which we evaluate in the stationary regime with the aid of (14) to obtain

$$\mathcal{H} = \omega \mathcal{N} + i \int d^2 \mathbf{x} \, \Gamma \rho_n. \tag{B8}$$

From (17) it then follows that $\mathcal{H} = \operatorname{Re}(\omega)\mathcal{N}$, that is, a $\operatorname{Re}(\omega) > 0$ wave with $\Omega < 0$ (and therefore $\rho_n < 0$) has negative-energy density.

The dispersion relation (B5) has four distinct solutions representing the different allowed **k**. When Γ_0 is small, only two of these [which we call \mathbf{k}^{\pm} such that $\operatorname{Re}(p^+) > \operatorname{Re}(p^-)$] correspond to propagating solutions. The other two are evanescent everywhere and enforcing the boundary conditions sets their amplitudes to zero. Hence, the general solution can be written as

$$f = \sum_{\omega,m} e^{im\theta - i\omega t} \sum_{j=\pm} \frac{R^{j}(r)}{\sqrt{r}},$$
$$R^{j} = \alpha^{j} \sqrt{\frac{F^{j} \partial_{\omega} p^{j}}{\Omega^{j}}} \exp\left(i \int (p^{j} + i\Gamma \partial_{\omega} p^{j}) dr\right), \quad (B9)$$

where α^j is an adiabatically conserved integration constant that comes from solving (B6) and superscript *j* implies that the quantity is evaluated for one of the p^{\pm} solutions to the dispersion relation. The integrals in the exponent are evaluated relative to a reference point where the phase is known. Near r_B , p^+ corresponds to the outgoing mode with $\partial_{\omega}p^+ > 0$ while p^- is ingoing with $\partial_{\omega}p^- < 0$. Notice that the damping term in the exponent implies that the amplitude decays in the direction of the group velocity $(\partial_{\omega}p^j)^{-1}$, as one would expect.

The locations where the p^j change from real (propagating) solutions to complex (evanescent) solutions are the turning points r_{tp} . At these points $p_{tp}^+ = p_{tp}^-$ and the group velocity in the radial direction vanishes $(\partial_{\omega}p_{tp}^+)^{-1} = 0$. Intuitively, the wave propagating in one direction comes to rest instantaneously before propagating back in the other direction. Hence, the turning points are the locations where waves scatter off the inhomogeneous background. On the other side of r_{tp} , $p^j \in \mathbb{C}$ and the waves tunnel.

Looking at (B9), we can see that the amplitude diverges as a consequence of the radial group velocity vanishing at r_{tp} , signaling the breakdown of the WKB approximation. This is not a problem but rather a necessity. The WKB approximation encodes only the adiabatic variation of a given solution of the dispersion relation, i.e., the various solutions do not exchange energy with each other. To capture scattering (the transfer of energy between waves which travel in opposite directions) the WKB approximation must break down at certain locations.

There is a standard procedure to fix the breakdown of (B9), which we now describe. The full equations of motion are expanded in the vicinity of r_{tp} and an exact solution for the scattering waves is obtained. The asymptotic form of this solution is matched to the WKB modes on either side of r_{tp} to provide a relation between them. When waves propagate for $r < r_{tp}$ and are evanescent for $r > r_{tp}$, the relation is

$$\begin{pmatrix} R_{tp}^+ \\ R_{tp}^- \end{pmatrix} = e^{i\pi/4} \begin{pmatrix} 1 & -\frac{i}{2} \\ -i & \frac{1}{2} \end{pmatrix} \begin{pmatrix} R_{tp}^{\downarrow} \\ R_{tp}^{\uparrow} \end{pmatrix}, \qquad (B10)$$

while in the reverse scenario (evanescent for $r < r_{tp}$ and propagating for $r > r_{tp}$) we have

$$\begin{pmatrix} R_{tp}^{\uparrow} \\ R_{tp}^{\downarrow} \end{pmatrix} = e^{i\pi/4} \begin{pmatrix} \frac{1}{2} & -\frac{i}{2} \\ -i & 1 \end{pmatrix} \begin{pmatrix} R_{tp}^{+} \\ R_{tp}^{-} \end{pmatrix}.$$
 (B11)

Here a superscript \uparrow (\downarrow) denotes a wave which grows (decays) in the direction of increasing *r*.

In Fig. 4 of the main text we depict the dependence of the various turning points $r_{0,1,2}$ on ω for m = 1, 2. Between turning points, there is a region where the waves are evanescent and tunnel across the flow. This tunneling zone separates the region where $\Omega > 0$ ($\rho_n > 0$) from that with $\Omega < 0$ ($\rho_n < 0$). We then see that Re(ω) > 0 modes can have negative-energy densities [Re(ω) $\rho_n < 0$] inside the vortex core, provided they are below a certain threshold (for $m = \ell$ this threshold is $\omega = \mu$). Hence, when such a wave impinges on the vortex, it excites a state with negative energy in the core and (by energy conservation) gets amplified upon reflection. This is the phenomenon of rotational superradiant scattering familiar from black hole physics [26].

We can obtain a formula that describes the scattering of modes that cross this tunneling zone in the following way. First, using (B9), we define a number that shifts one of the R^{j} modes at r_{b} to a smaller radius r_{a} such that the WKB amplitude does not diverge for $r_{a} < r < r_{b}$, that is,

$$\mathcal{F}_{ab}^{j} = \sqrt{\frac{\Omega_{b}^{j} F_{a}^{j} \partial_{\omega} p_{a}^{j}}{\Omega_{a}^{j} F_{b}^{j} \partial_{\omega} p_{b}^{j}}} \exp\left(-i \int_{r_{a}}^{r_{b}} (1 + i\Gamma \partial_{\omega}) p^{j} dr\right),$$

$$R_{a}^{j} = \mathcal{F}_{ab}^{j} R_{b}^{j},$$
(B12)

where a single subscript indicates the location where a quantity is evaluated, e.g., $R_a^j = R^j(r_a)$. We then combine (B10)–(B12) to define a relation between propagating amplitudes on either side of the tunneling zone $r_1 < r < r_2$,

$$\begin{pmatrix} R_1^+ \\ R_1^- \end{pmatrix} = \mathcal{N}_{12} \begin{pmatrix} R_2^+ \\ R_2^- \end{pmatrix},$$

$$\mathcal{N}_{12} = \mathcal{F}_{12}^{\downarrow} \begin{bmatrix} 1 + f_{12}^2/4 & i(1 - f_{12}^2/4) \\ -i(1 - f_{12}^2/4) & 1 + f_{12}^2/4 \end{bmatrix},$$
(B13)

where

$$f_{12} = \exp\left(-\int_{r_1}^{r_2} \operatorname{Im}[(1+i\Gamma\partial_{\omega})p^{\downarrow}]dr\right).$$
(B14)

For a wide tunneling zone, f_{12} is assumed to be small and can be evaluated to leading order for $\Gamma = 0$. These relations can now be used to find a resonance condition for modes that cross the tunneling zone, by transporting the solution from r_0 in the vortex core (see Fig. 4) to the outer boundary at r_B ,

$$R_{0}^{+} = \mathcal{F}_{01}^{+} \mathcal{F}_{12}^{\downarrow} (\sigma_{+} \mathcal{F}_{2B}^{+} R_{B}^{+} + i\sigma_{-} \mathcal{F}_{2B}^{-} R_{B}^{-}),$$

$$R_{0}^{-} = \mathcal{F}_{01}^{-} \mathcal{F}_{12}^{\downarrow} (-i\sigma_{-} \mathcal{F}_{2B}^{+} R_{B}^{+} + \sigma_{+} \mathcal{F}_{2B}^{-} R_{B}^{-}),$$

$$\sigma_{\pm} = 1 \pm f_{12}^{2} / 4.$$
 (B15)

The final step is to impose the boundary conditions. In the vortex core, regularity of the solution requires us to have $R_0^- = iR_0^+$. At the outer boundary, we can assume that the density goes to a constant value and that the velocities are vanishingly small provided we impose a Neumann boundary condition there, that is, $R_B^+ = R_B^-$. Both of these steps are explained in detail in [29]. Inserting these relations into (B15) and rearranging yields the resonance condition (19). Note that the assumption of vanishingly small $v_r(r_B)$ means that squareroot factors in (B12) cancel on the boundary when computing $\mathcal{F}_{2B}^+/\mathcal{F}_{2B}^-$.

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