

Experimental analysis of image resolution of quantum imaging with undetected light through position correlations

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Image resolution of quantum imaging with undetected photons is governed by the spatial correlations existing between the photons of a photon pair that has been generated in a nonlinear process. These correlations allow for obtaining an image of an object with light that never interacted with that object. Depending on the imaging configuration, either position or momentum correlations are exploited. We hereby experimentally analyze how the crystal length and pump waist affect the image resolution when using position correlations of photons that have been generated via spontaneous parametric down conversion in a nonlinear interferometer. Our results support existing theoretical models for the dependency of the resolution on the crystal length. In addition, we probe the resolution of our quantum imaging scheme for varying pump waists over one order of magnitude. This analysis reveals the intricate dependency of the resolution on the strength of the correlations within the biphoton states for parameter combinations in which the crystal lengths are much larger than the involved photon wavelengths. We extend the existing models in this parameter regime to properly take nontrivial effects of finite pump waists into account and demonstrate that they match the experimental results.

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I. INTRODUCTION

In recent years, quantum imaging techniques have proven to be a very useful tool to overcome classical limitations [1,2]. For instance, when imaging at wavelengths outside the visible range, detection technologies are limited, especially for low-light-level applications, such as occurring in life sciences [3]. Quantum imaging with undetected light (QIUL) [4] is a technique that overcomes these detection limitations exploiting the capabilities of nonlinear interferometers [5–7]. It is based on the quantum interference effect of induced coherence [8,9] and exploits the spatial correlations existing between two photons, for example, generated via spontaneous parametric down-conversion (SPDC), to create an image of an object with light that did not illuminate it. This nonlinear process can be engineered to generate one beam at the desired probe wavelength for the sample, and the other beam, containing correlated partner photons, at the visible range to ease the detection. Therefore, the interest in understanding quantum imaging systems has rapidly grown not only for imaging applications [3,10,11], but also for holography [12,13], spectroscopy [14–16], and optical coherence tomography [17,18].

Image resolution is one of the main parameters that describes the quality of an imaging system, which for QIUL is governed by the spatial correlations of the photons. Several

works have experimentally exploited the momentum anticorrelations of SPDC biphoton states, i.e., imaging at the far-field plane (Fourier plane) of the nonlinear crystal [3,4,12,19–23]. Alternatively, one can also obtain the image of an object that is placed at the near-field plane (image plane) of the nonlinear crystal. When this is the case, the imaging system exploits position correlations of the photons [24]. Note that the term near-field is also used in the literature in a different context to indicate that the object is sufficiently close to the SPDC source such that near-field interactions in terms of evanescent modes can have an influence on the resolution limit. In such cases subdiffraction resolution imaging might be achieved by exploiting evanescent modes existing within wavelength-range distances [25]. Recently, QIUL has been implemented with the near-field configuration for the first time and, thus, demonstrating its experimental viability [26]. Exploiting position correlations is of particular interest due to the fact that the degree of correlation between the two photons of an SPDC pair does not depend on the pump beam spatial coherence [27,28]. That relaxes the requirements on the pump source, providing more flexibility to engineer a quantum imaging system.

The role of the parameters of the two-photon source on image resolution (pump waist, crystal length, and wavelengths of the down-converted photons) has been analyzed for both cases momentum [29] and position [30,31] correlations.

These works derived resolution limits for specific parameter regimes within different approximations that were specifically designed for the precise parameter regime under consideration. For instance, the crystal length can be neglected

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within a thin-crystal approximation [32] in the far-field configuration [29]. By contrast, the impact of a finite pump waist can usually be neglected for near-field configurations but the crystal length plays the dominant role for image resolution. In particular, it has been shown that shorter crystal lengths improve the resolution within the paraxial regime [30]. However, this improvement reaches a lower bound given by the diffraction limit. At this limit, the resolution is governed by the longer wavelength of the photon pair. For a detailed analysis providing a general model for such effects also beyond the commonly used paraxial regime, we refer to [31].

While the theory predictions in the far field have been experimentally demonstrated [29], this task remains missing in the near field. In this work, we experimentally study the resolution of QIUL for different parameter regimes based on position correlations. We demonstrate that, in this configuration, the main parameter governing the spatial resolution for sufficiently large crystals is the crystal length, in agreement with the theory [30,31]. Furthermore, we also vary the pump waist to show that it does not influence the resolution over a broad parameter range. In particular, if the wavelengths are in the visible or near-infrared regime and the crystal length is of the order of millimeters, the resolution stays almost unaffected for pump waists $\gtrsim 100 \mu\text{m}$. However, we observe slight deviations for strongly focused pump beams.

To properly account for these effects, the existing theoretical model for the system needs to be extended. Although recently developed numerical techniques [31] could also account for such effects, we generalize the existing analytical model for resolution limits in the near field [30] to derive an analytical dependency of the image resolution on the pump waist as well as the crystal length. This investigation also allows us to directly connect the image resolution with the strength of the quantum correlations encoded in the biphoton states. Moreover, it reveals that different physical information is stored in the visibility and the image function that might be used to describe the imaging system. Resolution can be determined via characteristic spreads quantifying the blurring seen in an image of an object. Spreads extracted from both functions almost coincide for sufficiently large pump waists in the near-field configuration such that the resolution limit can be obtained either from amplitude images (image function) or from visibility images (visibility). However, they deviate for decreasing pump waists showing that the correlation information between the photons is only properly reflected in the visibility. We show that these effects are corroborated in the obtained experimental results. As a side product, our analysis provides a new quantity to assess the quality of the imaging setup without needing any information about involved magnifications. In case the experimentally measured data stay sufficiently close to the corresponding theory predictions, we are able to introduce a tool to extract an estimator for the magnification value of the imaging configuration without the need to directly measure it.

II. EXPERIMENTAL SETUP

The experimental setup (Fig. 1) consists of an SU(1,1) nonlinear interferometer where a 4f system of lenses ensures

that the object lies in the image plane of the crystal. We denote this particular configuration as near field, i.e., image-plane imaging. This plane is then imaged into the camera through a different 4f lens system. In this way, position correlations enable the formation of the image [24]. For more details on the systems of lenses and the imaging configuration used, see Fig. 6. in Appendix A 1.

A pump beam of 96 mW pump power and pump wavelength $\lambda_p = 405 \text{ nm}$ is focused with lens L_p into a type-0 ppKTP crystal that generates a pair of correlated photons through SPDC at 730 and 910 nm wavelengths either during the forward propagation of a pump photon through the crystal (path A) or when it passes through the crystal in the backward direction (path D) after being reflected back by mirror M1. We refer to the light with wavelength $\lambda_u = 910 \text{ nm}$ as undetected (u) because it is never detected, although being the one illuminating the object. By contrast, the photons with wavelength $\lambda_d = 730 \text{ nm}$ are directed towards the camera but never interact with the object. Therefore we denote this beam as the detected beam d. The camera used for detection is a Prime BSI Scientific CMOS from Teledyne Photometrics with a pixel size of $6.5 \mu\text{m}$. Because of the sufficiently low pump power, the down-conversion process occurs in the low-gain regime and we can consider only one pair of down-converted photons (either forward or backward generated) to be present at a time in the interferometer. The probability amplitudes of the SPDC emission generated in the first and second passage through the nonlinear crystal are superposed and exhibit interference when indistinguishable. The required indistinguishability is achieved by careful alignment of the forward and backward beams which erases the which-path information. The interference pattern observed from the detected photons contains information of an object in the undetected beam path C due to the induced coherence without induced emission effect [8,9].

Using this quantum phenomenon, the image formation for QIUL works as follows: An undetected photon in path C (Fig. 1) with transverse wave vector \mathbf{q}_u and transverse position ρ_u interacts with an object placed at the image plane of the nonlinear crystal at the transverse position $\rho_o = M_u \rho_u$ where M_u is the total magnification obtained by photons of the undetected arm. This spatial information is linked to a photon with transverse position ρ_d in the detected beam due to the correlations of the SPDC biphoton states originating from the common creation event of the photon pair. This photon is detected at the camera position $\rho_c = M_d \rho_d$ with M_d denoting the total magnification for light in the detected path [6]. Therefore, a position on the object ρ_o is directly related to a position on the camera ρ_c .

The optimal visibility of the interference generated in such a scheme is achieved by accurate alignment of the optical components for indistinguishability of the beams (and to fulfill the imaging conditions), as well as precisely matching the interferometric arms to the same optical length. Image resolution is affected by the precision of this alignment as well.

The mirror M2 is mounted on top of a piezo stage to allow for the scanning of different interferometric phases, which allows us to apply the digital phase-shifting holography (DPSH) technique to extract images with amplitude and phase information of the object [12]. Amplitude images obtained

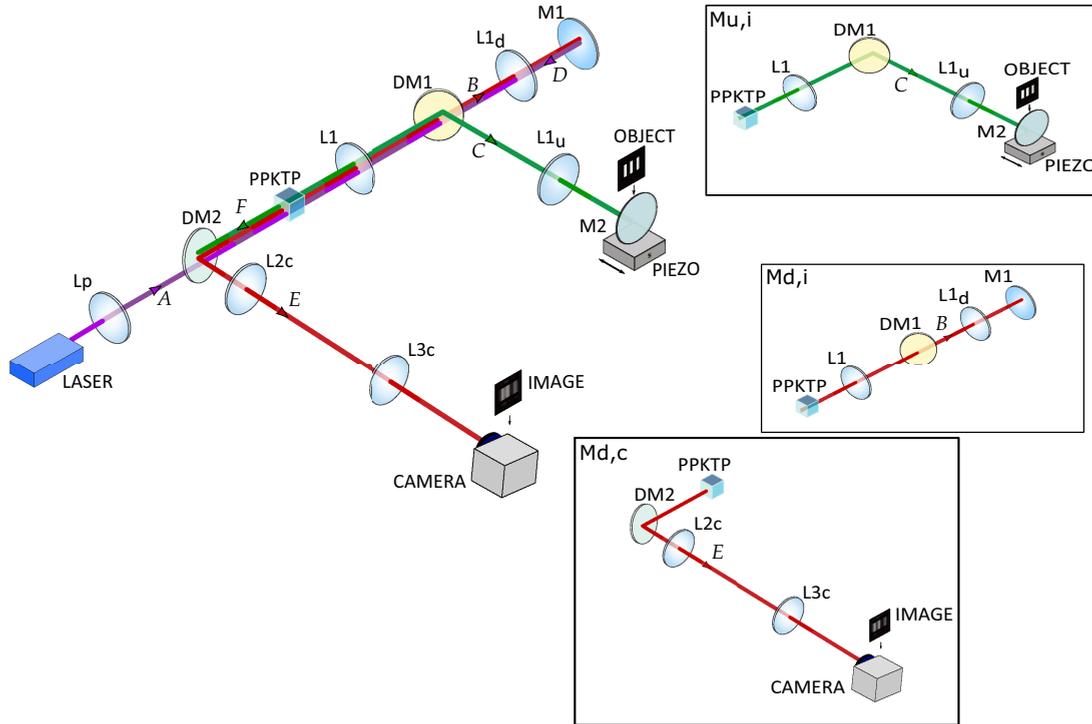


FIG. 1. Near-field configuration setup. A pair of down-converted photons is generated at the ppKTP crystal in either the forward pass of the pump (path A) through the crystal or in the backward pass (path D). The pump beam is focused at the crystal with L_p . We change the L_p focal length and its distance to the crystal accordingly to generate different pump waists at the center of the crystal. The undetected beam is reflected with DM1 towards the object while the detected and the pump beam are transmitted together. The DM2 reflects the detected beam towards the camera. The interferometer phase is varied by changing the position of the mirror M2 with a piezo translation stage. The lenses L1 and $L1_u$ (with equal focal lengths, $f_1 = 125$ mm) image the generated modes in the crystal onto the object plane, and back onto the crystal after being reflected back by the mirror M2. This configuration allows us to exploit the position correlations of the photon pairs. Lens $L1_d$ also has focal length f_1 . The lenses $L2_c$ ($f_2 = 75$ mm) and $L3_c$ ($f_3 = 200$ mm) image and magnify the object at the camera. Long pass and interference filters guarantee that only the 910 nm wavelength is detected. The insets show the different magnification systems present: magnifications of the undetected (detected) beam inside the interferometer [$M_{u,i}$ ($M_{d,i}$)], and the magnification of the detected beam before being detected on the camera ($M_{d,c}$).

from DPSH can be directly related to the value of the image function $G(\rho_c)$ at each camera pixel. The image function has been introduced as the difference of the maximum (I_{\max}) and minimum intensity (I_{\min}) at each position in the camera plane [30],

$$G(\rho_c) = I_{\max}(\rho_c) - I_{\min}(\rho_c). \quad (1)$$

Visibility, given by

$$V(\rho_c) = \frac{I_{\max}(\rho_c) - I_{\min}(\rho_c)}{I_{\max}(\rho_c) + I_{\min}(\rho_c)}, \quad (2)$$

at each pixel is also extracted as an image, which we call the visibility image. The latter can be used to analyze the system resolution and the strength of the position correlations.

The lenses inside the interferometer ($L1$, $L1_d$, and $L1_u$) introduce no magnification ($M_{u,i} = M_{d,i} = 1$) when the system of lenses is perfectly positioned. $M_{u,i}$ ($M_{d,i}$) is the magnification of the lens system in the interferometer undetected (detected) beam path. The detected beam passes through a second magnification system on its way to the camera ($M_{d,c}$) consisting of lenses $L2_c$ and $L3_c$ introducing a magnification of 2.67. Magnifying the image allows us to have more precision in the measurements due to the pixel size.

The total magnification seen by the detected beam is then $M_d = M_{d,i}M_{d,c}$. In practice, ensuring this precise magnification value ($M_d = 2.67$) is a challenging task and often difficult to realize. In the following, we elaborate on how we account for the impact of not ideally positioned lenses by extracting the relevant magnification value, here M_d , for each tested configuration from a nonlinear fit of the intensity and visibility profiles generated by a sharp edge on the camera. This newly introduced routine allows for higher accuracy than our experimental evaluation of the magnification, see Appendix A 2 for more details.

The actual resolution of the implemented quantum imaging scheme with undetected photons depends on various quantities coming either from the quantum nature of the underlying SPDC process, i.e., the correlation strength of the biphoton state, or the classical imaging system in terms of image formation and magnification. To isolate the impact of the underlying quantum correlations depending on the crystal length L and pump waist w_p , we need to know the precise total magnification from the lens system. This is important because the spreads measured in the camera plane explicitly depend on M_d in a multiplicative fashion as the detected photons creating the image precisely go through the corresponding lens system.

Therefore, we can construct magnification-adjusted spreads $\Delta_V = \frac{\Delta_{V,c}}{M_d}$ and $\Delta_G = \Delta_{G,c}/M_d$ where $\Delta_{V,c}$ and $\Delta_{G,c}$ denote the spreads measured in the camera plane. The subscripts V and G refer to whether the spreads were obtained from visibility or amplitude (image function) images, respectively. To extract information in the object plane, we multiply the magnification-adjusted visibility spread by the magnification of the undetected arm, $\Delta_o = M_u \Delta_V$, i.e., the total magnification of the system, relating camera and object planes, is given by $\Delta_{V,c}/\Delta_o = M_d/M_u$. The magnification-adjusted spreads provide information about the imaging system that root purely in the quantum nature of the implemented scheme and factor out any impact induced by the classical part, e.g., optical aberrations, imaging system misalignments, or magnifications. This is equivalent to realize a system where the lens configuration does not imply any magnification at all. As the main focus of our work will be on the impact of the quantum correlations on the spatial resolution, we focus on the magnification-adjusted spreads in the following.

Due to a low manufacturing precision of our target object for the measurement of the magnification, the experimental results obtained suffered from big error bars (see Appendix A 2 for more details). To minimize the uncertainty

coming from the magnification measurement, we propose a different strategy that allows us to construct an estimator for the magnification present in the system. First, we introduce a new parameter to quantify the quality of the experimental results without the need of knowing the system magnification. As the spreads measured in the camera, obtained either from image function or visibility, depend only linearly on M_d , we study their ratio

$$\frac{\Delta_{G,c}}{\Delta_{V,c}} = \frac{\Delta_G}{\Delta_V}, \quad (3)$$

which is a magnification-independent quantity by construction. Although this quantity cannot be related to the resolution of the system, we can use it to estimate the quality of the correlations and the overall alignment required to generate induced coherence. The advantage of this ratio is given by the fact that we are able to compare pure experimentally obtained data [left-hand side of Eq. (3)] to values that can be predicted by theory [right-hand side of Eq. (3)]. In case the experimentally obtained ratio stays close to the theory prediction, we can use the following functional dependency as a fit for the experimentally obtained data for the image function (cf. Sec. IV for a derivation):

$$G_{\text{ESF}}(x_c) = \exp \left\{ -\frac{4\pi(\lambda_d + \lambda_u)}{\lambda_d^2 L + 2\pi w_p^2(\lambda_d + \lambda_u)} \frac{x_c^2}{M_d^2} \right\} \left[1 - \operatorname{erf} \left\{ \frac{\sqrt{2}[\lambda_d \lambda_u L - 2\pi w_p(\lambda_d + \lambda_u)]}{\sqrt{[\lambda_d^2 L + 2\pi w_p(\lambda_d + \lambda_u)]} L w_p(\lambda_d + \lambda_u)} \frac{x_c - M_u \tilde{x}_o}{M_d} \right\} \right], \quad (4)$$

and visibility

$$V_{\text{ESF}}(x_c) = \frac{1}{2} \left[1 - \operatorname{erf} \left\{ \frac{\sqrt{2}[\lambda_d \lambda_u L - 2\pi w_p(\lambda_d + \lambda_u)]}{\sqrt{[\lambda_d^2 L + 2\pi w_p(\lambda_d + \lambda_u)]} L w_p(\lambda_d + \lambda_u)} \frac{x_c - M_u \tilde{x}_o}{M_d} \right\} \right], \quad (5)$$

to estimate the magnification of the detected photon beam, M_d . The subscript ESF denotes that we have evaluated the image function and visibility for a sharp edge model. Here, x_c denotes the horizontal coordinate in the camera plane and \tilde{x}_o accounts for a potential displacement of the object from the optimal position at the center of the undetected light beam. The impact of the parameter combination $M_u \tilde{x}_o$ on the resolution in the camera plane can also be analyzed by this fit routine, i.e., we are using a two parameter fit with fit parameters M_d and $M_u \tilde{x}_o$.

Strictly speaking, both fits (image function and visibility) should give the same magnification value. However using the fits, we implicitly assume that the underlying theoretical model matches perfectly the experimental realization. Due to experimental uncertainties, e.g., in the alignment or the determination of the other parameters of the system, there can be an ambivalence in the extraction of the magnification parameter M_d . This can potentially result in a deviation of M_d extracted from Eq. (4) from M_d obtained from Eq. (5). Nonetheless, as long as the magnification-independent ratio $\Delta_{G,c}/\Delta_{V,c}$ stays close to the theory prediction Δ_G/Δ_V , which implies that the theoretical model fits sufficiently well the experimental realization, the magnification extracted from both functions

will be (almost) the same. Therefore, we use the average of these two values as an estimator of M_d if this is the case. Note that this careful comparison is necessary. Using only one fit as an estimator of M_d could lead to wrong magnification values as a change in M_d can be compensated in a change of other system parameters. Then, one would extract an incorrect magnification value designed in such a way that the resulting resolution imitates the theory prediction.

III. EXPERIMENTAL RESULTS

In this section, we present the results on image resolution when exploiting position correlations in QIUL. To evaluate the effect of the crystal thickness on the resolution, the measurements were performed with three crystals of the same characteristics but different lengths L (2, 5, and 10 mm). Additionally, for each crystal, the resolution of the system is evaluated for different pump waists w_p (50, 142, 214, and 308 μm).

The resolution power of our system is obtained through the analysis of the edge response of the system to a sharp edge. The object is a blade of a knife edge placed at the image plane of the crystal (near-field configuration), right in

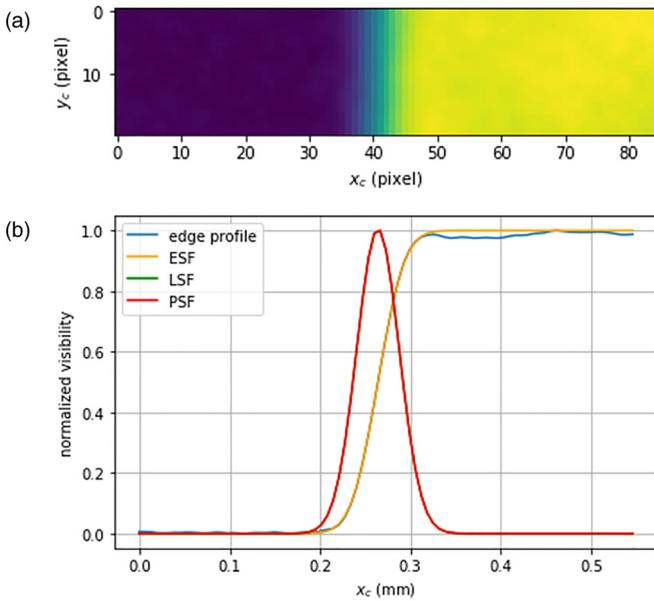


FIG. 2. Spread of an edge analysis. (a) Cut from the visibility image taken to analyze the spread of an edge blocking the left side of the beam. (b) The edge profile (blue, error-function shape) is extracted from the image, and fit with an ESF (orange, error-function shape, barely distinguishable by eye from the edge profile). From the ESF, the LSF (green, Gaussian shape) and PSF (red, Gaussian shape) are calculated. LSF and PSF overlap. Example extracted from data taken with a 2-mm-long crystal and 214 μm pump waist.

front of the mirror on the signal arm (M2 in Fig. 1) such that it is imaged parallel to the vertical y_c axis in the camera plane (see Fig. 2). Although we perform the experiment for a purely transmissive object, we would like to emphasize that one of the main advantages of the QIUL technique is given by the fact that a similar treatment can be done for phase objects as well [12].

The edge response is evaluated from both amplitude and visibility images at the camera plane. To do this, we first analyze the integrated intensities per pixel row to determine the y_c position with maximum intensity for each amplitude image. By doing this, we determine the optimal position where the detected beam has the strongest impact which minimizes errors induced by our theoretical approximations. Then, we fit the image and visibility functions evaluated for a sharp edge model, i.e., the corresponding edge spread functions (ESFs), to the experimentally obtained amplitude and visibility edge profile for the pixel row with maximum intensity, respectively. Many classical imaging schemes are linear and stationary or isoplanatic such that the impulse response function depends only on coordinate differences between the object and camera planes. In this case, the derivative of the ESF is equivalent to the line spread function (LSF) which, in turn, is directly related to the point spread function (PSF) when considering a Gaussian profile for the illumination [33] (see Fig. 2).

Exploiting position correlations for QIUL, these relations are fulfilled for visibility within our approximation as well as for the image function (amplitude) to a good approximation if the pump waist is sufficiently large. However, we would like to emphasize at this point that, for smaller pump waists, the

derivative of the ESF will not coincide with the LSF for the image function because the system is no longer isoplanatic which can be directly inferred from the joint probability distribution of detected and undetected photons, see Sec. IV. We also observe that, for sufficiently large pump waists ($\gtrsim 100 \mu\text{m}$ in our configuration) the analysis of amplitude images to extract the system resolution power gives similar results as visibility images, but they strongly differ for smaller pump waists. Only in the particular parameter regime where the conditions $w_p^2 \gg \lambda_u^2 L / (\lambda_d + \lambda_u)$ and $w_p^2 \gg \lambda_d^2 L / (\lambda_d + \lambda_u)$ are fulfilled, the image function might be used to determine the image resolution to a good approximation. We will elaborate on these points in detail in Sec. IV.

The resolution of an imaging system can be heuristically defined in various ways. Here, we follow the practical convention that we analyze the spread of the PSF at the point where its intensity decays to $1/e$ in order to directly compare our results with previous works [29,30]. This definition can in most cases also be transferred to a $1/e$ -width of the LSF or an $24/76$ -knife-edge width of the ESF being defined as the distance between the points of the measured curve that are 24% and 76% of the maximum value. While this analogy holds for visibility images, it is not the case for amplitude images (also see Sec. IV for a detailed discussion).

From the measured $\Delta_{G,c}$ and $\Delta_{V,c}$, the magnification-independent parameter introduced in Eq. (3) is calculated. We find that the percentage the experimental data deviates from the theory prediction is similar to the ratio between the extracted fit parameters M_d from Eq. (4) or (5). Therefore, we can use this ratio indeed as a classifier to determine the quality of the experimental implementation to match the underlying theory assumptions used to model the system as described at the end of Sec. II. Figure 3 compares the experimentally measured and theoretically predicted ratios. The fact that they are in good agreement allows us to extract an estimator for the magnification of the detected interferometer arm for each of these measurements. Therefore, we have access to the magnification-adjusted spreads encoding the influence of the quantum correlations on the resolution.

The results from the evaluation of the magnification-adjusted spreads Δ_V and Δ_G as detailed in Sec. II are given in Figs. 4 and 5, respectively. From the careful interpretation of these results, it is concluded that the physical meaning of what these two quantities encode is different. Visibility gives a measure on the indistinguishability of the beams and the correlation strength between the photons of an SPDC pair. These two quantities directly correlate to how good a point in the object is mapped onto the camera plane, i.e., they determine the image quality (resolution and contrast). This connection is also seen from the results in Fig. 4, which show that the resolution of the system improves for short crystals and stays constant when varying the pump waist as predicted in the existing literature [30,31], if the pump waist is sufficiently large. To be more precise, we are able to identify this regime in the region of parameter space where $w_p^2 \gg \lambda_u^2 L / (\lambda_d + \lambda_u)$ and $w_p^2 \gg \lambda_d^2 L / (\lambda_d + \lambda_u)$ hold. However, an interesting behavior arises for smaller pump waists. While decreasing the pump waist, the position correlations between the photon pairs deteriorate (which directly worsens image

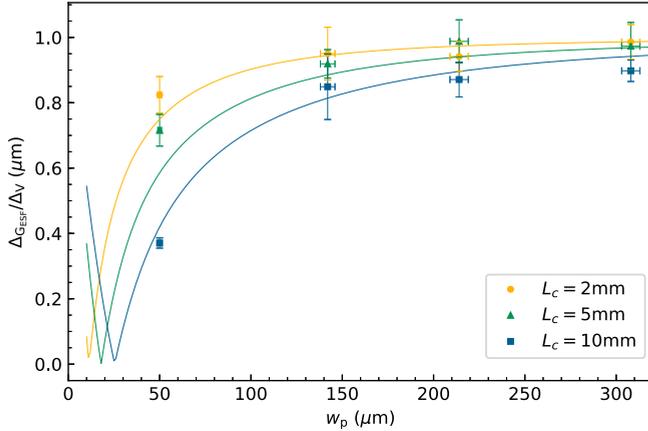


FIG. 3. Magnification-independent quality parameter. Ratio between the spread of the ESF derivative obtained from amplitude images (Δ_{GESF}) of a sharp edge and the corresponding spread obtained from visibility images (Δ_V). The solid lines show the theoretical predictions for each crystal length [2 mm in yellow (upper) curve; 5 mm in green (middle) curve; 10 mm in blue (lower) curve] when varying the pump waist. Experimental data are given in yellow circles (2 mm), green triangles (5 mm), and blue squares (10 mm). Since the experimental points fit the theory prediction, we conclude that the underlying physics is well described by our theory model and that the experimental uncertainties are kept within acceptable limits. Because this ratio does not depend on the system magnification, it is a useful quantity to describe the system performance purely induced by the underlying quantum-mechanical principles of the imaging scheme.

resolution as well) until they might be nonexistent, i.e., the SPDC biphoton state becomes separable. At that particular point, the resolution (or the visibility image PSF spread) diverges since the photons reaching the camera plane carry no spatial information on the object anymore. To explain the behavior observed for smaller pump waists (50 μm), it is necessary to extend the current existing models. This can be done either by following the lines of Ref. [31] using numerical techniques or by extending the existing analytical model as we do in Sec. IV.

For amplitude images, the interpretation of results presented in Fig. 5 has to be done more carefully. In Fig. 5, we depict the spreads obtained from amplitude images depending on the pump waist. For large pump waists, one obtains similar results for visibility and amplitude images when analyzing image resolution. However, for smaller pump waists, when the position correlations start to worsen (see corresponding points in Fig. 4), relating the amplitude image spread to resolution leads to misleading results. As the pump waist size approaches the value where the state becomes separable, the Gaussian contribution to the image function [see the exponential term in Eq. (7)] induces the main x_c dependence compared with the contribution of the error function which approaches a constant value. At the point where the spatial correlations are lost, the image function carries no spatial information about the object. Therefore, the spreads obtained from amplitude images for small pump waists rather give a measure on the detected beam size than image resolution.

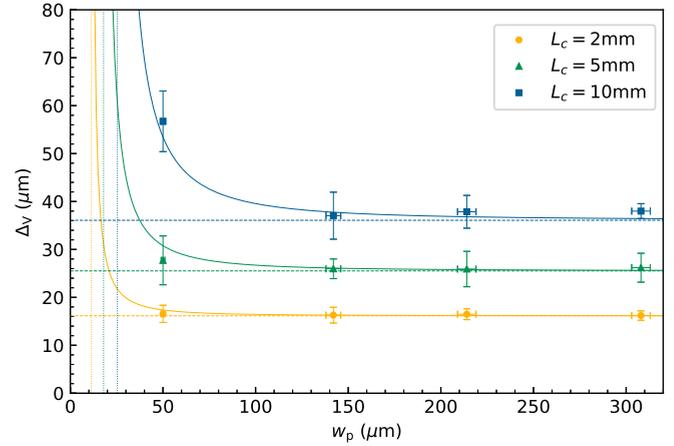


FIG. 4. Magnification adjusted visibility spreads for images taken through position correlations existing between SPDC photon pairs for a sharp edge. Spread extracted from visibility images (resolution) of a sharp edge for three crystals with different lengths when varying the pump waist. Experimental data are given in yellow circles (2 mm), green triangles (5 mm), and blue squares (10 mm) and compared with the theory prediction [2 mm in yellow (lower) solid curve; 5 mm in green (middle) solid curve; 10 mm in blue (upper) solid curve]. For comparison, we plot the limiting case of large pump waists as predicted in the literature [30] with dashed lines. For regimes where $w_p^2 \gg \lambda_d^2 L / (\lambda_d + \lambda_u)$ our extended theory model (see Sec. IV) converges towards the simplified one, and resolution is mainly dependent on the crystal length. However, for smaller pump waists, the resolution worsens as the spatial correlations stored in the SPDC state worsen such that the biphoton state even becomes separable, i.e., the spatial correlations are lost for a specific parameter configuration (marked with dotted vertical lines for each crystal length).

IV. THEORY AND DISCUSSION

For the specific parameter constellations realized in the experiments, we observe that, for large pump waists, the resolution limits stay almost constant with varying pump waist. These results verify the theoretical predictions done in the literature so far that were operating in a regime where the influence of finite pump waists can almost be ignored [30,31]. However, the experimental results also demonstrate that discrepancies can arise if sufficiently small pump waists are realized for fixed crystal lengths L and wavelengths λ_d and λ_u . Even more interestingly, we observe that spreads obtained from visibility images or amplitude images have a different dependency on w_p . While both spreads approach the same limit for large pump waists, the definition of resolution in terms of the induced spreads via the imaging system becomes ambiguous for small pump waists as the image function spread Δ_G decreases while the visibility spread Δ_V increases. To address these subtle points, we are filling the gap of deriving an analytical model in the paraxial regime that takes the impact of the pump waist on the resolution limits into account. With that, we have a formalism for image formation with position correlations at our disposal such that we are able to analyze the resolution capabilities for a wide range of different source parameters based on the experimental setup sketched

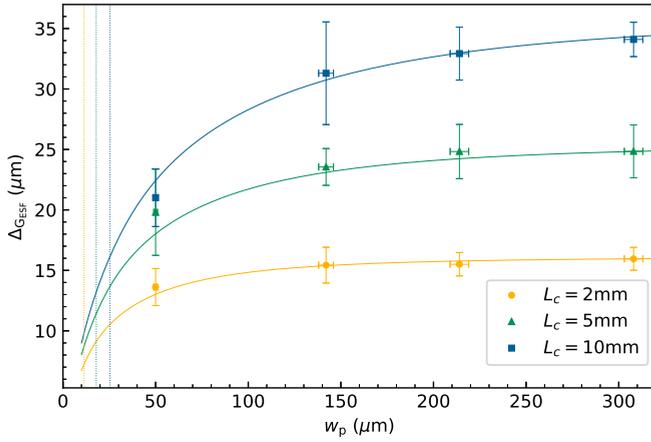


FIG. 5. Magnification adjusted spread Δ_{GESF} from amplitude images. The solid blue upper line is the theoretical prediction for a 10 mm crystal while the solid green middle curve and the yellow lower curve show the predictions for a 5 mm crystal and a 2 mm crystal, respectively. In case the pump waist gets smaller, the information on the object gets gradually erased between detected and undetected beams. At the point where the SPDC state becomes separable [marked with a yellow dotted line (left vertical line) for a 2 mm crystal, in green (middle vertical line) for 5 mm, and in blue (right vertical line) for 10 mm], the amplitude images only carry information on the detected beam which does not contain any spatial information about the object. The spread measured is then related to the detected beam size. For larger pump waists [$w_p^2 \gg \lambda_u^2 L / (\lambda_d + \lambda_u)$], the derivative of the amplitude ESF can be considered as a good approximation of the LSF which can be related to the PSF. Moreover, the image and visibility functions are approaching the same limiting function in the large pump waist regime. Therefore, for this regime, the ESF derivative value converges towards the resolution value given in Fig. 4 determined by the visibility images.

in Fig. 1 as well as to identify the physical interpretation of Δ_G and Δ_V .

One of the main ingredients for QIUL are the spatial correlations encoded in biphoton wave functions. Such correlated photon pairs are usually generated via SPDC and are the result of photons being born at approximately the same position [34]. In first-order perturbation theory and for collinear phase matching the photon pair state reads [32]

$$|\psi\rangle = \mathcal{N} \int d\mathbf{q}_d \int d\mathbf{q}_u P(\mathbf{q}_d + \mathbf{q}_u) \times \text{sinc}\left(\frac{L\lambda_p}{8\pi\lambda_d\lambda_u}(\lambda_d\mathbf{q}_d - \lambda_u\mathbf{q}_u)^2\right) |\mathbf{q}_d\rangle |\mathbf{q}_u\rangle, \quad (6)$$

where \mathcal{N} is a normalization constant and \mathbf{q}_d (\mathbf{q}_u) denotes the transverse wave vector of the detected (undetected) photon. Furthermore, we have the wavelength of the pump photon λ_p , the detected photon λ_d , and the undetected photon λ_u , the crystal length L , as well as the profile of a spatially coherent pump beam focused into the crystal. In our case, the latter is given by a Gaussian shape $P(\mathbf{q}_d + \mathbf{q}_u) = \exp\{-\frac{w_p^2}{4}(\mathbf{q}_d + \mathbf{q}_u)^2\}$ with w_p being the pump waist.

As we put the object at the image plane of the SPDC source, we exploit position correlations that are encoded in the joint probability density $\mathcal{P}(\boldsymbol{\rho}_d, \boldsymbol{\rho}_u)$. To analyze the properties

of our QIUL setup, we use the image function $G(\boldsymbol{\rho}_c)$ as well as the visibility $V(\boldsymbol{\rho}_c)$, see Eqs. (1) and (2), respectively. Following Ref. [30], the image function can be computed in our specific case via

$$G(\boldsymbol{\rho}_c) \sim \int d\boldsymbol{\rho}_o \mathcal{P}\left(\frac{\boldsymbol{\rho}_c}{M_d}, \frac{\boldsymbol{\rho}_o}{M_u}\right) |T(\boldsymbol{\rho}_o)|. \quad (7)$$

Analogously, we have for the visibility

$$V(\boldsymbol{\rho}_c) \sim \frac{\int d\boldsymbol{\rho}_o \mathcal{P}\left(\frac{\boldsymbol{\rho}_c}{M_d}, \frac{\boldsymbol{\rho}_o}{M_u}\right) |T(\boldsymbol{\rho}_o)|}{\int d\boldsymbol{\rho}_o \mathcal{P}\left(\frac{\boldsymbol{\rho}_c}{M_d}, \frac{\boldsymbol{\rho}_o}{M_u}\right)}. \quad (8)$$

The impact of an object is encoded in the transmission coefficient $T(\boldsymbol{\rho}_o)$. Simple models for an object are given by a Dirac δ function, $T \sim \delta(\boldsymbol{\rho}_o)$, modeling a point or a Heaviside function, $T = \Theta(x_o)$, modeling the impact of an edge being orthogonal to the x_o direction in the object plane. We denote the image function evaluated for the respective objects as G_{PSF} for a point and G_{ESF} for an edge. Similarly, we introduce the notation V_{PSF} (visibility PSF) and V_{ESF} (visibility ESF).

Due to the intricate momentum dependency of the SPDC state (6), it is a nontrivial task to find a closed-form expression for the joint probability density $\mathcal{P}(\boldsymbol{\rho}_d, \boldsymbol{\rho}_u)$ and thus for the image function or visibility. To obtain a qualitative understanding, we approximate the sinc by a Gaussian structure, $\text{sinc}(x^2) \rightarrow e^{-x^2}$, following the standard strategy usually done in the literature [30]. For this particular approximation, one obtains

$$\mathcal{P}(\boldsymbol{\rho}_d, \boldsymbol{\rho}_u) = \frac{8}{\pi w_p^2 L (\lambda_d + \lambda_u)} \times \exp\left\{-\frac{2(\lambda_u\boldsymbol{\rho}_d + \lambda_d\boldsymbol{\rho}_u)^2}{w_p^2(\lambda_d + \lambda_u)^2} - \frac{4\pi(\boldsymbol{\rho}_d - \boldsymbol{\rho}_u)^2}{L(\lambda_d + \lambda_u)}\right\} \quad (9)$$

for the joint probability density. So far, the resolution limit for the undetected photon scheme under investigation was analyzed in the limit where the first term in the exponential is merely slowly varying compared with the second term in the sum. Formally, this is equivalent with a plane-wave limit where $w_p \rightarrow \infty$. This is motivated by the fact that typical parameters realized in an experiment allow us to neglect the contributions from a finite pump waist. Indeed, our experimental data clearly show that this is a well-justified approximation over a large parameter range of the pump waist for fixed λ_d , λ_u , L . Nonetheless, we also demonstrated that we are able to probe regimes where the pump waist influences the imaging system. Therefore, we extend the existing analyses by including the impact of finite pump waists.

As a first example to describe the resolving power of the optical system sketched in Fig. 1 in a qualitative fashion, we analyze the PSF for the Gaussian approximation of the sinc function and obtain

$$G_{\text{PSF}}(\boldsymbol{\rho}_c) = \exp\left\{-\left[\frac{2\lambda_u^2}{w_p^2(\lambda_d + \lambda_u)^2} + \frac{4\pi}{L(\lambda_d + \lambda_u)}\right] \frac{\boldsymbol{\rho}_c^2}{M_d^2}\right\}, \quad (10)$$

as well as

$$V_{\text{PSF}}(\rho_c) = \exp \left\{ - \frac{2[2\pi w_p^2(\lambda_d + \lambda_u) - \lambda_d \lambda_u L]^2}{2\pi w_p^4(\lambda_d + \lambda_u)^3 L + w_p^2 \lambda_d^2 (\lambda_d + \lambda_u)^2 L^2 M_d^2} \rho_c^2 \right\} \quad (11)$$

for the image function PSF and visibility PSF, respectively. Here, we have used the fact that the PSFs obey a radial symmetry, thus, depending only on $\rho_c = |\rho_c|$. Furthermore, we normalized the maximum to one.

Usually, the quality of a QIUL system is quantified by the spreads of the image function or visibility. As aforementioned, we are using a 1/e-width for the PSFs, $G_{\text{PSF}}(\Delta_{G_{\text{PSF}},c}) = 1/e$ and $V_{\text{PSF}}(\Delta_{V,c}) = 1/e$. Note, that we have introduced a subscript PSF for the spread of the image function to indicate that this is a spread obtained from a PSF but dropped it for the visibility spread. The reason for this will become clear once we discuss the spreads of the ESFs. Eventually, we obtain the magnification adjusted PSF spreads by dividing the PSF spreads at the camera by the magnification of the detected arm, $\Delta_{G_{\text{PSF}}} = \Delta_{G_{\text{PSF},c}}/M_d$ and $\Delta_V = \Delta_{V,c}/M_d$, which read

$$\Delta_{G_{\text{PSF}}} = \sqrt{\frac{L(\lambda_d + \lambda_u)}{4\pi}} \sqrt{\frac{1}{1 + \frac{\lambda_u^2 L}{2\pi w_p^2(\lambda_d + \lambda_u)}}}, \quad (12)$$

$$\Delta_V = \sqrt{\frac{L(\lambda_d + \lambda_u)}{4\pi}} \frac{2\pi w_p^2(\lambda_d + \lambda_u) \sqrt{1 + \frac{\lambda_u^2 L}{2\pi w_p^2(\lambda_d + \lambda_u)}}}{2\pi w_p^2(\lambda_d + \lambda_u) - \lambda_d \lambda_u L}. \quad (13)$$

The first conclusion that we can draw from Eqs. (12) and (13) is that the spreads obtained from the image function as well as from the visibility coincide in the $w_p \rightarrow \infty$ limit. In particular, $\Delta_{G_{\text{PSF}}}$ coincides with the result in Ref. [30] in this limit where contributions of the pump waist on the resolution were neglected. For the image function spread, this is a good approximation as long as the inequality $\lambda_u^2 L / [2\pi w_p^2(\lambda_d + \lambda_u)] \ll 1$ is fulfilled. Interestingly, the two spreads either obtained from the image function or from visibility show different dependencies on w_p . For instance, Δ_V is well approximated by the pump waist independent limit $\sqrt{L(\lambda_d + \lambda_u)/4\pi}$ for $\lambda_d^2 L / [2\pi w_p^2(\lambda_d + \lambda_u)] \ll 1$ and $\lambda_d \lambda_u L / [2\pi w_p^2(\lambda_d + \lambda_u)] \ll 1$. Apart from the limiting case, there are a couple of important differences stored in both quantities that become manifest for finite pump waists. In case the pump waist is decreasing (for fixed other parameters), the values for Δ_V increase until they reach a singularity at $w_{p,\text{sing}}^2 = \lambda_d \lambda_u L / [2\pi(\lambda_d + \lambda_u)]$, cf. Fig. 4. By contrast, $\Delta_{G_{\text{PSF}}}$ is decreasing. Naively, one could conclude that the resolution improves with smaller pump waists by investigating the image function spread. However, the spread extracted from the visibility gets broader for smaller pump waists until it hits a singularity within our approximation. While this seems to be a contradiction at first sight, it is important to notice that both quantities store different information of the presented imaging scheme.

The fact that Δ_V diverges is not surprising if we carefully study the properties of the SPDC biphoton state enabling

imaging with undetected photons. If the condition $w_p = w_{p,\text{sing}}$ is fulfilled, the biphoton state becomes separable within the Gaussian approximation of the sinc function. Even more important, all spatial correlations between the detected and undetected photons are lost. This becomes transparent if one studies the joint probability distribution given in Eq. (9) which factorizes $\mathcal{P}(\rho_d, \rho_u) = \mathcal{P}_d(\rho_d)\mathcal{P}_u(\rho_u)$. As both photons of a pair are uncorrelated, the spatial information cannot be transmitted from the object to the camera. Therefore, the visibility becomes constant, cf. Eq. (10) for $w_p = w_{p,\text{sing}}$, and Δ_V diverges. Thus, Δ_V can be interpreted as a measure of the correlation strengths of the biphoton state. For large pump waists, there exist a high degree of spatial correlations. Lowering the pump waist, the correlations get worse until they vanish at the singularity. Technically speaking, the correlation strengths begin to increase again for $w_p < w_{p,\text{sing}}$. However, we might also approach a regime there were our assumptions, e.g., the paraxial approximation, break down. Furthermore, it is important to note that the singularity might be an artifact of the Gaussian approximation. By taking the actual sinc phase matching condition into account, we assume that the singular structure might get softened, depending whether a parameter combination exists such that the actual SPDC state given in Eq. (6) gets separable.

The role of the image function spread $\Delta_{G_{\text{PSF}}}$ is different. The image function encodes intensities at each camera pixel position. Even though the biphoton state might become separable for a specific parameter constellation, there is always the detected beam impinging onto the camera. In our currently analyzed case, it will have a Gaussian shape with a spread determined by $M_d \sqrt{L\lambda_d/4\pi}$ within our approximations. However, this spread is not a valid measure to quantify the spatial resolution capabilities of the undetected photon scheme. The detected photons in this case do not contain any spatial information of the object at all as the image function does not properly reflect the correlation strengths in an adequate manner. Therefore for wide-field imaging, we are using the spreads extracted from visibility information to quantify resolution limits. The image function spread rather provides information about the detected beam size. Only in the limit $w_p \rightarrow \infty$, image function and visibility store the same information as in this case the SPDC state becomes perfectly correlated.

Eventually, the (visibility) spread observed in the detection plane divided by the total system magnification M_d/M_u can be related to the minimum resolvable distance of an object via [30]

$$\begin{aligned} d_{\text{min,obj}(N_F)} &\approx 0.7\sqrt{2\pi} \frac{M_u}{M_d} \Delta_{V,c} \\ &= 0.7M_u \sqrt{\frac{L(\lambda_d + \lambda_u)}{2}} \\ &\quad \times \frac{2\pi w_p^2(\lambda_d + \lambda_u) \sqrt{1 + \frac{\lambda_u^2 L}{2\pi w_p^2(\lambda_d + \lambda_u)}}}{2\pi w_p^2(\lambda_d + \lambda_u) - \lambda_d \lambda_u L}. \end{aligned} \quad (14)$$

One can deduce from these analytical solutions that the dominating effects for the resolution are given by the crystal length L and the magnification of the undetected arm M_u for a wide

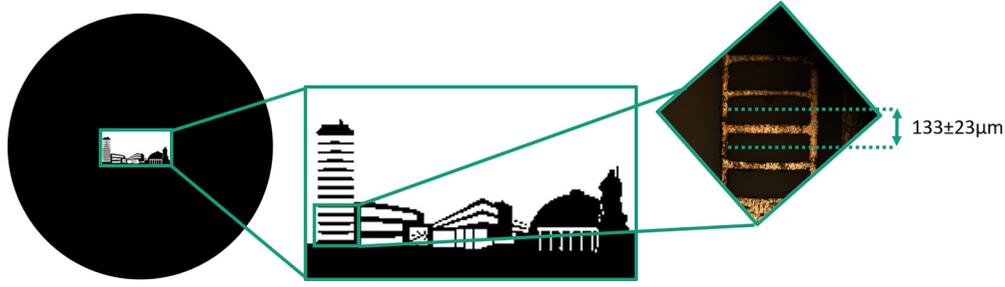


FIG. 7. In-house made object used for the magnification measurements. The object is laser cut on a thin metal sheet. Therefore its transmission is either zero or one for the probing light. It represents the Jena skyline, and the tower windows are used as slits for the magnification measurements. The distance between the center of the windows (slit distance) is measured to be $133 \pm 23 \mu\text{m}$. Where the uncertainty of the distance corresponds to the sum of the measuring device uncertainty and the manufacturing precision.

the photons of the biphoton state deteriorate. That results in the fact that wide-field imaging being not a suitable approach in case the spatial correlations between the photons are lost. However, QIUL would still be possible in this regime by using a scanning approach. In this case, the image resolution would not depend on quantum properties but rather depend on the bit depth of the camera, the scanning step size, and the undetected beam size.

To summarize, an improvement on image resolution can be mainly achieved by using shorter crystal lengths and by decreasing the magnification at the undetected path (M_u) as previously stated [30]. At the same time, it is important to stress out that M_u does not act as a classical magnification since it does not influence the detected dimensions on the camera but just modifies the spot size that probes the object. In addition, our results show that resolution gets worse as soon as the pump waist leaves the regime where $w_p^2 \gg \lambda_d \lambda_u L / (\lambda_d + \lambda_u)$ and $w_p^2 \gg \lambda_d^2 L / (\lambda_d + \lambda_u)$ are fulfilled.

Our work provides insights into the intricate relations between all source parameters and properties, providing us with a tool to optimize image resolution for different imaging applications.

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APPENDIX

1. Imaging configuration

Figure 6 gives detailed information on the imaging configuration used during the measurements presented.

2. Magnification measurement

An in-house made object (Fig. 7) was used to perform the magnification measurements by calculating the ratio between the object and its image dimensions. Due to the field of view (FOV) at the object plane, only the "windows of the tower" acting as parallel slits with a fixed distance are considered as our object. The object dimensions were measured with a Zygo- New View 7300 optical profiler. The roughness of the frame between the windows is the main error source of the

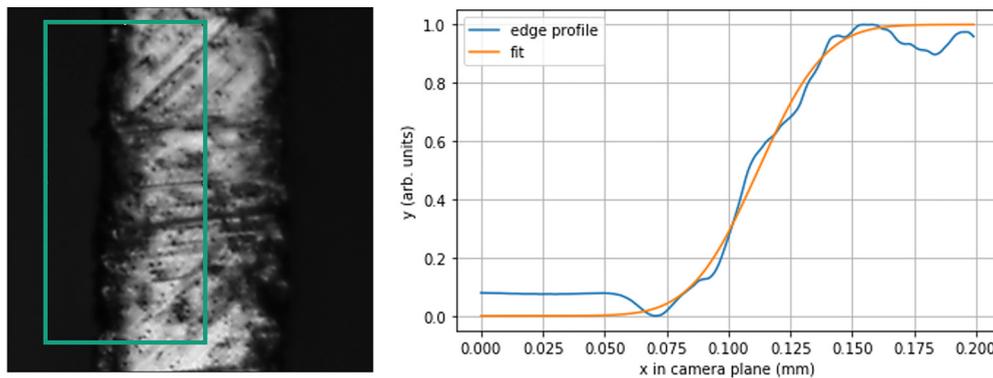


FIG. 8. Object manufacturing precision measurement. The image of a window edge was analyzed by plotting the averaged intensity edge profile along the x axis of the area marked in green. That profile is then fit with an error function and its spread evaluated at $1/e$ is taken as the manufacturing precision of one window edge. Notice that this value must be doubled to account for the two edges.

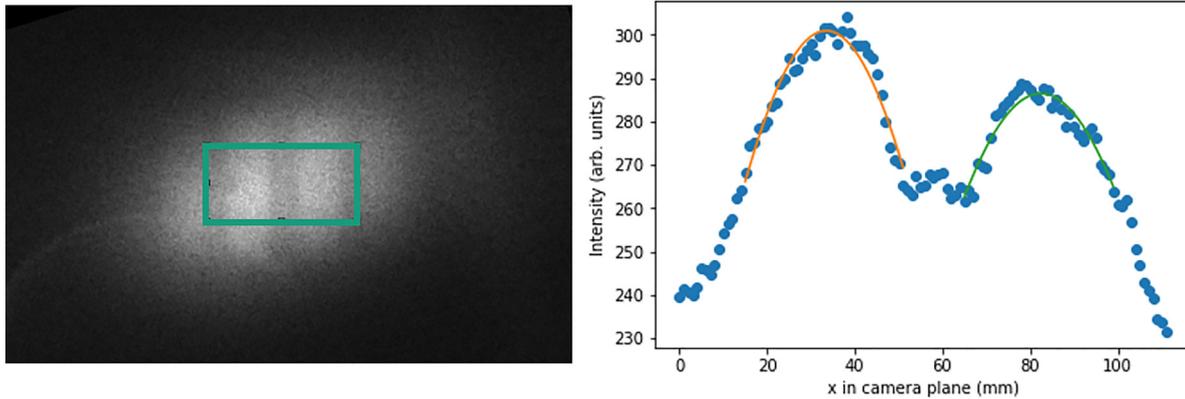


FIG. 9. Object-image dimensions analysis. Image of the tower windows taken with our setup but illuminating the object with the detected wavelength to obtain a classical image. The windows are treated as slits and their intensity profile are fit by Gaussian functions. The distance between two slits (windows) is then taken as the distance between the maxima of the Gaussian fits. This example is taken with a 5-mm-long crystal and a pump waist of 214 μm .

object dimension measurements, and therefore, it was also measured. The manufacturing precision of the object was analyzed from a picture taken under a $20\times$ magnification objective with an Olympus DP71 sensor which is coupled to an Olympus BX51TRF microscope with a U-TV0.63XC adapter. The unsharpness of one edge of the window frame is obtained by fitting an error function to its intensity profile (Fig. 8). From these measurements, we obtain that the distance between two window centers is $133 \mu\text{m} \pm 23 \mu\text{m}$.

To measure the distance between two windows on the image obtained with the QIUL system, the windows of the tower are treated as slits. For these measurements, the wavelength

that illuminates the object is the same as the detected, and the possibility to create light from the second pass of the pump through the crystal is avoided by blocking that path. The intensity profile from each slit (window) was fit with a Gaussian function, and the distance between slits (windows) is then the distance between the Gaussian peaks given in pixel units (Fig. 9). This distance is then converted to μm from the camera sCMOS camera pixel size of 6.5 μm . By taking this measurement right after the resolution measurements for each crystal length and pump waist combination, and comparing it to the object real dimensions, we calculated the experimental magnification values for each configuration.

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