## Multipartite entanglement and quantum error identification in D-dimensional cluster states

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An entangled state is said to be m-uniform if the reduced density matrix of any m qubits is maximally mixed. This is intimately linked to pure quantum error correction codes (QECCs), which allow us not only to correct errors but also to identify their precise nature and location. Here, we show how to create m-uniform states using local gates or interactions and elucidate several QECC applications. We first show that D-dimensional cluster states are m-uniform with m = 2D. This zero-correlation-length cluster state does not have finite-size corrections to its m = 2D uniformity, which is exact both for infinite lattices and for large enough, but finite, lattices. Yet at some finite value of the lattice extension in each of the D dimensions, which we bound, the uniformity is degraded due to finite support operators which wind around the system. We also outline how to achieve larger m values using quasi-D-dimensional cluster states. This opens the possibility to use cluster states to benchmark errors on quantum computers. We demonstrate this ability on a superconducting quantum computer, focusing on the one-dimensional cluster state, which, as we show, allows us to detect and identify one-qubit errors, distinguishing X, Y, and Z errors.

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#### I. INTRODUCTION

Bipartite entanglement is a well-understood concept, as it can be clearly quantified by the appropriate reduced density matrix [1,2]. Quantifying multipartite entanglement is much more challenging and has been studied in the literature using many distinct measures [3-13]. A common approach to multipartite entanglement relies on the entanglement across all possible bipartitions. This approach was first introduced in Ref. [14] in a study of the average entanglement of random pure states. Later studies led to the definition of m-uniformity: multiqubit states in which all the reduced density matrices of m qubits are maximally mixed [15-22].

A simple example of *m*-uniformity is given by the *n*-qubit Greenberger-Horne-Zeilinger (GHZ) state,  $|\psi\rangle_{\text{GHZ}} = (|0\rangle^{\otimes n} + |1\rangle^{\otimes n})/\sqrt{2}$ . Any one-qubit subsystem  $A_1$  corresponds to the reduced density matrix  $\rho_{A_1} = (|0\rangle\langle 0| + |1\rangle\langle 1|)/2$ , which is maximally mixed, i.e., proportional to the identity operator in the subsystem. Hence, the GHZ state is at least 1-uniform. For a subsystem  $A_2$  of any two qubits, one has  $\rho_{A_2} = (|00\rangle\langle 00| + |11\rangle\langle 11|)/2$ , which is not maximally mixed. Therefore, the GHZ state is only 1-uniform [20,23].

The notion of *m*-uniformity has deep links to quantum error correction codes (QECCs). In the case of quantum states that encode no logical information, Ref. [16] proved that any *m*-uniform state has the ability to locate and identify a quantum

error, assuming that it acted on at most  $\lfloor m/2 \rfloor$  qubits [15] or, equivalently, a sequence of at most  $\lfloor m/2 \rfloor$  single-qubits errors. The relationship between m-uniformity and QECCs was extended to states that encode a finite amount of quantum information [24] and is related to quantum information scrambling [25,26]. Note that m-uniformity is a sufficient, but not necessary, condition for error correction: A known example is Kitaev's toric code, which is only 3-uniform but can correct an extensive number of errors [27]. This code is an example of a nonpure QECC, which can correct errors even without being able to fully identify them. In contrast, m-uniform states give rise to pure, i.e., nondegenerate, QECCs, where the errors are first fully identified and only then corrected [2]. Hence, pure codes are particularly useful in benchmarking noisy quantum computers.

Creating states with large m-uniformity is a key challenge in quantum information. Earlier studies discussed how to perform this task using orthogonal arrays [19,20,28,29], numerical methods [17,30], graph states [31-33], and other constructions [22,34–36]. Special attention was drawn to nqubit states that are  $\lfloor n/2 \rfloor$ -uniform, also known as absolutely maximal entangled, which have important applications in quantum secret sharing and quantum teleportation [34,37]. Their existence was proven only for n = 2, 3, 5, 6 qubits [16,38]. Moreover, using theoretical enumerator tools from QECCs, useful bounds on their existence for qudits were derived [16,39]. In general, it is always possible to construct m-uniform states for a desired m if the number of qubits is large enough [18,20], but determining the minimal number of qubits required for a given m is, as far as we know, still an open question, although some lower bounds are known [18,24,40]. In addition, these constructed states may be highly nonlocal

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FIG. 1. One-dimensional cluster chain depicted using graphical notation of vertices and lines. The vertices represent the qubits, which are all prepared in the  $|+\rangle$  state. The lines connecting two qubits represent a controlled-Z gate. We notate a few commuting stabilizer operators appearing in Eq. (1) on their respective qubits.

and pose a challenge to prepare them on a quantum computer using low-depth circuits.

In this paper we address this challenge by focusing on cluster states, which can be realized as ground states of cluster Hamiltonians and are sometimes referred to as graph states [41]. Cluster Hamiltonians can be expressed as a sum of local terms, known as stabilizers, and are commonly used to describe condensed-matter systems. As we will explain, the degree of uniformity of these states is bounded by the support of the stabilizers, i.e., the size of the neighborhood that interacts with each qubit. The ground state of these Hamiltonians can be prepared exactly on quantum computers via shallow circuits of local unitary gates [42–44]. Cluster states in one and two dimensions have been studied in the context of symmetry-protected topological states of matter [43,45,46] and can be used in measurement-based quantum computation and teleportation [43,47–50].

We show that the cluster state in D dimensions is 2D-uniform. When considering the cluster state as a stabilizer QECC, it has no logical qubits encoded. Despite not containing a logical space, this state allows for quantum error detection of D individual errors. This ability of error detection stems from a connection between m-uniformity and QECCs that allows us to employ these states for benchmarking errors that may act on up to  $\lfloor m/2 \rfloor$  qubits in current noisy intermediate-scale quantum computers [51]. We demonstrate this procedure on a real quantum computer for D = 1. Finally, we provide examples of m-uniform subspaces in which a finite logical space is encoded.

This paper is organized as follows. In Sec. II we introduce the cluster states and determine their *m*-uniformity based on the stabilizer formalism. In Sec. III we review the connection to QECCs and deduce the quantum error detection ability of cluster states. We present a demonstration of this application in Sec. IV. In Sec. V we exemplify how *m*-uniform spaces, encoding logical information and also allowing us to detect errors, can be constructed. We conclude in Sec. VI.

## II. CLUSTER STATES AND THEIR MULTIPARTITE ENTANGLEMENT

The *D*-dimensional cluster Hamiltonian describes n qubits located on the vertices of a *D*-dimensional square lattice with axis lengths  $L_1, L_2, \ldots, L_D$ , where  $n = L_1 L_2 \cdots L_D$ , such that each qubit interacts with exactly 2D neighbors. Unless specified otherwise, we consider a finite system with periodic boundary conditions (PBCs) in each dimension. The one-dimensional (D = 1) cluster Hamiltonian, which is depicted

in Fig. 1, is defined as

$$H = -\sum_{i} Z_{i-1} X_i Z_{i+1}.$$
 (1)

The minus sign is motivated by the ferromagnetic ground state of the Ising model and its generalizations to the cluster Ising model [45,52–56]. In D>1 dimensions, we denote the location of each qubit using a lattice vector  $\mathbf{v}=(i_1,i_2,\ldots,i_D)$ , where  $i_k\in\mathbb{Z}$  and  $-L_k/2 < i_k\leqslant L_k/2$  for each dimension  $1\leqslant k\leqslant D$ . The basis vectors  $\{\mathbf{e}_i\}$  of the lattice have 1 in their ith entry and 0 elsewhere. The cluster Hamiltonian is then defined as

$$H = -\sum_{\mathbf{v}} X_{\mathbf{v}} \left( \prod_{i=1}^{D} Z_{\mathbf{v} - \mathbf{e}_i} Z_{\mathbf{v} + \mathbf{e}_i} \right) = -\sum_{\mathbf{v}} s_{\mathbf{v}}. \tag{2}$$

Here, each vertex induces an operator  $s_v$ . The  $s_v$  are referred to as stabilizers, as they fulfill two special properties [57]: (i) They square to one,  $s_v^2 = I$ , because they correspond to tensor products of Pauli matrices; (ii) they commute,  $[s_v, s_{v'}] = 0$ . These properties simplify the problem of finding the ground state.

These two properties ensure that the Hamiltonian in Eq. (2) is frustration free [58]; that is, any ground state of H is a simultaneous ground state of each  $s_v$ . In a more formal way, we note that the set of q stabilizers  $\{s_{\mathbf{v}}\}$  generates a  $\mathbb{Z}_2^q$  group called the stabilizer group S by considering all their multiplications [59,60]. To differentiate between the elements of Sand their generators we denote the generators of the stabilizer group by  $\{s_i\}$  (i = 1, ..., q) and the elements of this group by  $S_i$   $(i = 1, ..., 2^q)$ . Focusing on the cluster Hamiltonian with PBCs, q equals the number of qubits, q = n. Since  $S_i$ commute, they have a common set of eigenvectors, and their eigenvalues are all  $\pm 1$  because of the first property above. In this case, where the size of S equals the Hilbert space dimension, one has a basis given by the eigenvectors. Consider the unique eigenvector  $|CS\rangle$  such that  $s_i|CS\rangle = |CS\rangle$ for any i. By definition, it is the unique ground state of the cluster Hamiltonian in the cluster state in D dimensions, and its ground-state energy is -n. For later reference, we define the *support* of  $S_i$  as the number of nonidentity local Pauli matrices of  $S_i$ . For example, for the one-dimensional cluster state the support of each local term is  $supp(s_i) = 3$ , while for the *D*-dimensional cluster state we have supp $(s_i) = 2D + 1$ .

#### A. Reduced density matrices and stabilizer subgroups

The stabilizer formalism leads to an explicit way to construct reduced density matrices. By definition, the pure density matrix  $\rho$  of the cluster state corresponds to the projector into the +1 eigenvector of the generators of the stabilizer group  $P_i = \frac{I+s_i}{2}$  and can be written as [57]

$$\rho = \prod_{i=1}^{n} P_i = \frac{1}{2^n} \sum_{\sigma \in S} \sigma. \tag{3}$$

Using this expression, one can show that the reduced density matrix over the set of qubits A is [57]

$$\rho_A = \frac{1}{2^{|\mathcal{S}_A|}} \sum_{\sigma \in \mathcal{S}_A} \sigma,\tag{4}$$

where  $S_A$  is the subgroup of the stabilizer group S that has support *only* on the set of qubits A and  $|S_A|$  is the number of elements in  $S_A$ . For the subsystem A to be maximally mixed,  $S_A$  should be the trivial group containing only the identity element I, or

$$S_A = \{I\} \iff \rho_A \propto I. \tag{5}$$

As mentioned, if this property applies to all sets of *m* qubits, the state is defined to be *m*-uniform.

For example, consider the three-qubit cluster state in D=1 with PBCs, i.e., the stabilizer state generated by  $\{s_i\}=\{X_1Z_2Z_3,Z_1X_2Z_3,Z_1Z_2X_3\}$ , which is the ground state of  $H=-\sum_i s_i$ . The eight elements of the stabilizer group S consist of  $\{s_i\}\bigcup\{I,Y_1Y_2I_3,Y_1I_2Y_3,I_1Y_2Y_3,-X_1X_2X_3\}$ . We can see that while the reduced density matrix over any single qubit is maximally mixed, the reduced density matrix over two qubits is not proportional to the identity. For example, applying Eq. (4) for  $A=\{1,3\}$ , we have

$$\rho_A = \frac{1}{4}(I + Y_1 Y_3),\tag{6}$$

as  $S_A$  contains  $\{I, Y_1Y_3\}$ . Hence, this state is 1-uniform but not 2-uniform.

#### B. The 2D-uniform infinite D-dimensional cluster state

Proposition 1. For a *D*-dimensional cluster state on an infinite lattice, if  $|A| \leq 2D$ , then  $S_A$  is the trivial subgroup, consisting only of the identity matrix acting in subsystem A, where |A| is the number of qubits in subsystem A.

This follows from the intuitive fact that the generators of the stabilizer group for the cluster states on a large enough lattice, having support 2D+1, minimize the support of the stabilizer group. We provide a proof of this proposition in Appendix A. To show its generality, we also consider different lattice structures in Appendix B. From this proposition, it immediately follows that the D-dimensional cluster state is 2D-uniform on a large enough lattice.

The cluster state does not have finite-size corrections to its m=2D uniformity, which is exact both for infinite lattices and for large enough, but finite, lattices. Yet at a finite value of the lattice extension the uniformity is degraded due to finite support operators which wind around the system. The four-qubit one-dimensional (1D) cluster state, which is not 2-uniform, exemplifies this point.

This leaves the question of what the lower bound for the system size in a given dimension D is to preserve the 2D-uniformity. One can formally ask this question for a cluster state of  $L^D$  qubits with PBCs. In Appendix C we demonstrate that Proposition 1 in fact holds for any dimension, as long as  $L \ge 8$ . This proof does not saturate the lowest bound. In one dimension, five qubits with PBCs are sufficient to obtain 2D-uniformity [16]. By numerically inspecting the stabilizers and their multiplications for D = 1, 2, 3, we conjecture that the minimal size necessary for 2D-uniformity is L = 5 in each direction with PBCs.

### C. Extended cluster states

Can uniformity be increased by varying the range or support of stabilizers? For example, in one dimension, rather

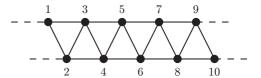


FIG. 2. Extended ZZXZZ cluster state with next-nearest-neighbor interactions. In this case, the commuting stabilizers are supported on five sites, e.g.,  $Z_1Z_2X_3Z_4Z_5$ ,  $Z_2Z_3X_4Z_5Z_6$ .

than considering the support-3 ZXZ operators in Eq. (1), one can consider the graph state defined by the stabilizers  $s_i^{(p)} = Z_{i-p} \cdots Z_{i-1} X_i Z_{i+1} \cdots Z_{i+p}$ . For p = 2, this state can be created by applying controlled-Z (CZ) gates on a ladder graph, as shown in Fig. 2. While for p = 1 we recover the cluster state which is 2-uniform, it is not hard to see that all p > 1 states on an infinite lattice are 3-uniform.

We provide a simple argument for the simple case of p=2, which can then be easily extended. The weight of a stabilizer generators sets an upper bound on the uniformity of a state, m < 5. Is the state 4-uniform? To show that the uniformity is actually smaller, one should find operators of a support 4 or less which acquire a finite expectation. Consider the stabilizer group element  $s_i s_{i+1} = Z_{i-p} \cdots Z_{i-1} X_i Z_{i+1} \cdots Z_{i+p} Z_{i-p+1} \cdots Z_i X_{i+1} Z_{i+2} \cdots Z_{i+p+1} = Z_{i-p} Y_i Y_{i+1} Z_{i+1+p}$ . The weight of this element is 4 for p=2. It is possible to check that there are no stabilizer group elements of a smaller support. Hence, the extended 1D cluster state for p=2 is at most 3-uniform.

The same result applies to stabilizers of the form  $Z_iX_{i+1}\cdots X_{i+p}Z_{i+p+1}$ , which are related to a family of topological states [61]. An analogous construction can be used to create cluster states with larger m-uniformity in D > 1 dimensions.

### III. CLUSTER STATES AS PURE QECCs

In this section, we review basic definitions of QECCs and explain their connection to m-uniformity. Consider a logical subspace of dimension  $2^k$ , corresponding to k logical qubits out of the Hilbert space of n physical qubits, and denote its basis states by  $\{|i\rangle\}$ . If, for a given positive integer d, the full set of operators, referred to as errors  $\{E_a\}$ , with  $\text{supp}(E_a) < d$ , satisfies

$$\langle i|E_a|j\rangle = C(E_a)\delta_{ij},$$
 (7)

then we say that the subspace is a QECC with distance d and denote it as [[n, k, d]]. Such a QECC allows the correction of errors with support  $\lfloor (d-1)/2 \rfloor$  [2].

For a general stabilizer code with a finite encoded subspace (k > 0) the distance is given by  $d = \min\{\sup[C(S) - S]\}$ , where C(S) is the centralizer of the stabilizer group, i.e., the set of Pauli strings that commute with all the stabilizers. In other words, d is the minimal support of operators that commute with S but not with the logical operators. A stabilizer state without an encoded space (k = 0) is a [n, 0, d] QECC with  $d = \min[\sup(S/\{I\})]$ .

A QECC is said to be *pure* or nondegenerate if Eq. (7) is satisfied by  $C(E_a) = 0$  for any  $E_a$  other than  $E_a = I$ .

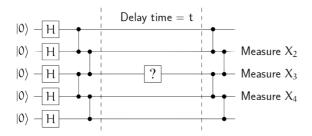


FIG. 3. Circuit used to benchmark error rates on qubit 3. First, a 1D cluster state is prepared with open-boundary conditions on the left. Then, during a delay of time t an error may occur. Finally, the measurements of the stabilizer generators on the right side are used to identify the error. On the real machine errors may occur on any qubit, but dealing with errors on any qubit would require PBCs, i.e., entangling qubits 1 and 5, which we avoid due to limitations of the actual machine.

Otherwise, the code is called nonpure or degenerate. Pure codes have the property that every error of support  $\lfloor (d-1)/2 \rfloor$  corresponds to a distinct syndrome and allows us to *identify* its location and its type  $(X,Y,\operatorname{or} Z)$ . Note that in the literature, error detection is referred to as the possibility to *know* that an error occurred but not to locate or to identify it. For example, the surface code is a  $[\lfloor 2d^2, 2, d \rfloor]$  QECC [62]. It allows us to detect d-1 errors and correct up to  $\lfloor (d-1)/2 \rfloor$  errors per cycle of stabilizer measurements [63]. However it allows us to locate and identify only a single one-qubit error.

According to the above definitions, m-uniformity can be related to pure QECCs: Ref. [16] showed that any muniform state is a pure [[n, 0, m+1]] QECC. This result can also be obtained from Sec. II A, together with the statement that any stabilizer state is a OECC with distance d = $\min[\sup(S/\{I\})]$ , and can be generalized to states with a finite number of logical qubits k [24]: If the basis vectors  $|i\rangle$  span an m-uniform subspace, which is a vector space  $\mathcal{V}$ such that each  $v \in \mathcal{V}$  is m-uniform, then one obtains a pure [[n, k, m + 1]] QECC, where  $k = \log_2[\dim(\mathcal{V})]$ . Then, using our key result in Sec. IIB, we deduce that the D-dimensional cluster state is a [n, 0, 2D + 1] QECC. For example, the 1D cluster state corresponds to a [n, 0, 3] QECC, allowing us to locate and identify one-qubit errors. This case is demonstrated in the next section. The two-dimensional (2D) cluster state corresponds to a [[n, 0, 5]] QECC and allows us to detect arbitrary two-qubit Pauli errors.

## IV. BENCHMARKING ERRORS USING THE CLUSTER STATE

From the above QECC properties, an m-uniform state can be used to benchmark errors on a quantum computer that act on at most  $\lfloor m/2 \rfloor$  qubits. Since the D-dimensional cluster state is 2D-uniform, it allows us to detect errors that act on D qubits. We now demonstrate this on the 1D cluster state.

Our noise benchmarking protocol is depicted in Fig. 3. We first prepare the cluster state from the product state using the unitary transformation U composed of Hadamard and CZ gates, assuming no errors occur at this stage. During a delay time t, an error or multiple errors may spontaneously occur, which is depicted as a question mark in Fig. 3. To detect this

error, assuming it acted on at most one qubit, we measure the error syndromes through the stabilizers. Present-day quantum computers do not facilitate direct measurement of such stabilizers because they involve simultaneous measurements of multiple qubits. Instead, the syndromes can be measured by reversing U with  $U^{\dagger}$ , assuming perfect fidelity, followed by single-qubit measurements, as shown in Fig. 3. By repeating this process many times we obtain a probability distribution of the errors.

The corresponding error-syndrome detection in a sufficiently long ( $n \ge 5$  qubits) 1D cluster state with PBCs is as follows: If no errors occurred, we always obtain a string of zeros. In the case of one  $Z_i$  error during the delay, we get 1 on the ith qubit, instead of 0. An  $X_i$  error evolves to a 101 pattern on the (i-1)th, ith, and (i+1)th qubits. The error  $Y_i$  combines the Z and X errors and results in a 111 pattern.

In the real machine that we use, qubits 1 and are physically separated and cannot be entangled directly. Hence, we focus on the open-boundarycondition cluster Hamiltonian defined by the stabilizers  ${X_1Z_2, Z_1X_2Z_3, Z_2X_3Z_4, Z_3X_4Z_5, Z_4X_5}.$ Then, the uniformity is spoiled near the edges, and for example,  $X_1$  and  $Z_2$  errors result in the same syndrome, 01000. Thus, we focus on errors that act only on the middle qubit, qubit 3. We added a question mark in Fig. 3 only on qubit 3 because this circuit allows us to deal with errors only at that qubit, even though in practice errors can occur on any qubit. Thus, assuming an error may have occurred only on qubit 3, the error syndromes 00100, 01010, and 01110 allow us to determine the probabilities of Z, X, and Y errors, respectively. We proceed to apply this protocol on (i) a noisy simulator that mimics the hardware noise and (ii) a real quantum computer.

Real quantum computers and noisy simulators that mimic their behavior experience both relaxation errors, which gradually change  $|1\rangle$  to  $|0\rangle$ , and dephasing errors, which gradually change  $|+\rangle$  to  $|-\rangle$  and vice versa. These processes correspond to X/Y and Z errors, respectively, and their characteristic times are commonly denoted by  $T_1$  and  $T_2$ . In superconducting circuits,  $T_1$  and  $T_2$  are generically of the order of 10– $100~\mu s$  and satisfy  $T_2 < T_1$ . We first consider a noisy simulator with physical parameters derived from the IBM quantum computer IBMQ Manila [64] (see Appendix D).

Figure 4(a) shows the probability of finding an X, Y, or Z error in the middle qubit as a function of the delay time (each point refers to the average over 100,000 shots). We find that the slope, i.e., rate of X and Y errors, is smaller than the slope of Z errors, in agreement with the expected relation  $T_2 < T_1$ .

In addition to the slopes, we can see that the curves in Fig. 4(a) are shifted differently from the origin. We associate this shift with state-preparation-and-measurement (SPAM) errors that occur while we prepare the cluster state and measure the stabilizers. These errors occur with a probability that does not depend on the delay time and correspond to a vertical shift of the error curves. Let us denote this readout error as  $R_i$  for the ith qubit and assume that it has probability  $p_i = p \ll 1$ . As a result of this error, the pattern 00100 occurs as a result of either a  $Z_3$  error or an  $R_3$  error. In contrast, X and Y error patterns may be created and equivocally detected as a result of two and three  $R_i$  errors, respectively, which have a smaller probability,  $p^3 \ll p^2 \ll p$ . Thus, Z errors occur

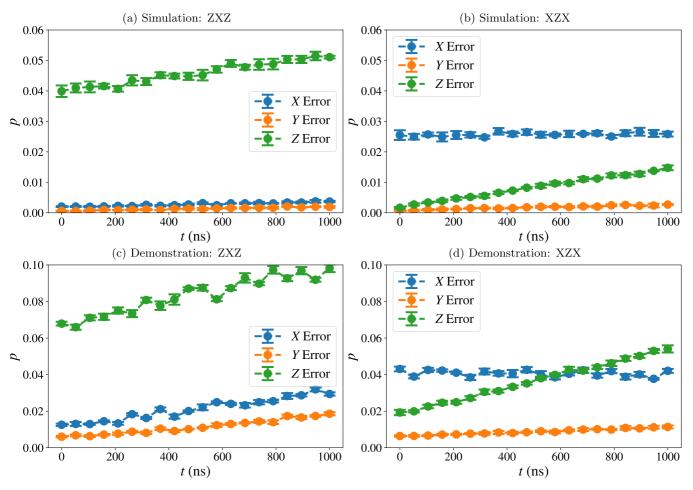


FIG. 4. (a) Noisy simulator results of the error benchmarking protocol for the cluster state. The errors are calculated from the measurement results as a function of the delay t as in the text. Each point is generated from five realizations of 20 000 shots, from which we extract the standard deviation. The slope quantifies the creation of errors by time, where the shift from the origin is the result of the measurement errors. (b) The same for the cluster after  $X \longleftrightarrow Z$  transformation. During the state preparation (at zero delay) the errors of X and Z are inverted with respect to (a), while during the waiting time (i.e., the slopes) they are the same. (c) and (d) Quantum computer results for the same circuits.

more frequently due to SPAM errors, in agreement with the observed result. To support this error model, we consider a transformed cluster state with  $X \leftrightarrow Z$ , with stabilizers of the form XZX. This state can be prepared by simply applying an additional layer of Hadamard gates before and after the delay. In this case, the error  $Z_3$  has syndrome 01010, which can be mistakenly generated by two readout errors. On the other hand, the  $X_3$  error has syndrome 00100 and can occur due to a single  $R_3$  readout error. In Fig. 4(b) we present the results from the transformed protocol. When normalizing the readout errors on the middle qubit [the readout error in Fig. 4(a) is approximately twice that in Fig. 4(b); see Appendix. D], we notice that the X error probability is now shifted by approximately the same amount as the Z error in Fig. 4(a), and vice versa. In contrast, we find that the slopes of the errors in the original and transformed circuits are comparable. This finding confirms our hypothesis that the shift of the curves is associated with SPAM errors, while the slopes are due to processes that occur during the waiting time.

The corresponding results for the real IBM quantum computer IBMQ Manila are shown in Figs. 4(c) and 4(d). The observed slopes are higher than in the simulator, indicating

that QISKIT simulators underestimate the noise in the hardware. For example, the simulator does not take into account the crosstalk between neighboring qubits [64], which negatively affects the evolution of entangled states. From the slopes we estimate

$$T_1 \approx \left(\frac{dp_{X,Y}}{dt}\right)^{-1} \approx 100 \text{ µs}, \ T_2 \approx \left(\frac{dp_Z}{dt}\right)^{-1} \approx 30 \text{ µs}.$$
 (8)

We emphasize that while longitudinal  $(T_1)$  and transversal  $(T_2)$  error rates are typically measured using separate experiments, our quantum error detection approach based on m-uniform states involves a single experiment. Performing this error analysis in longer chains may allow one to quickly find the qubits with the smallest error rates and improve the computational fidelity.

### V. m-UNIFORM LOGICAL SPACES

The cluster state discussed so far does not encode a logical subspace. Is it possible to supplement its error detection ability with an encoded subspace? Here, we exemplify this possibility via a measurement-based protocol [57,65–67].

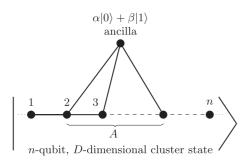


FIG. 5. To encode information in the cluster state, an ancilla qubit is coupled to a subset of qubits A. The bonds represent controlled-Z gates.

Consider one ancilla qubit prepared in the desired state  $\alpha|0\rangle + \beta|1\rangle$  and a 2*D*-uniform state, i.e., the *D*-dimensional cluster state  $|CS\rangle$  with *n* qubits. We couple the ancilla qubit to an arbitrary set of |A| qubits of the cluster state via CZ gates, as shown in Fig. 5. By measuring the ancilla in the *X* basis and postselecting the X = +1 outcome, we obtain the state

$$|\phi\rangle = \alpha |\text{CS}\rangle + \beta \prod_{i \in A} Z_i |\text{CS}\rangle$$
 (9)

(see Appendix E for a derivation). The state  $|\phi\rangle$  encodes one logical qubit. As shown in Appendix F, the inequality

$$|A| > 2D(2D+1) \tag{10}$$

is a sufficient condition for the encoding in Eq. (9) to be 2D-uniform. Thus, if the ancilla qubit is entangled with more than 2D(2D+1) qubits of a 2D-uniform cluster state, then the resulting logical space is also 2D-uniform.

#### VI. SUMMARY

In this work we explored *m*-uniformity, a measure of multipartite entanglement, in cluster states. *m*-uniform states maximize the entanglement between any *m* qubits and their surroundings and can be used for quantum error detection. In contrast to previous studies that focused on quantum states that maximize the uniformity, here, we considered the uniformity of cluster states, which are ground states of local frustration-free Hamiltonians and can be realized on quantum computers with local gates. Our key result is that *D*-dimensional cluster states are 2*D* uniform.

We introduced an application of m-uniformity in benchmarking quantum errors. While the amount of uniformity can highly underestimate the support of correctable errors, here, we emphasized the observation that the uniformity determines the support of identifiable errors distinguishing X, Y, and Z errors. The D-dimensional cluster states allow us to detect errors acting independently on D qubits. We demonstrated how the 1D cluster state can be used to benchmark errors on a quantum device. This approach allowed us to clearly observe the dominance of one type of errors (Z) over the others (X and Y) on the specific machine explored in this work. Applications of the 2D cluster state to benchmark two-qubit errors and their correlations are left for future study.

An interesting question that deserves further investigation is whether the quantum error detection ability extends beyond the special cluster states considered here. A natural candidate for the extension of our work is offered by symmetry-protected topological (SPT) states. These states include the cluster states as special cases and were shown to share common properties, for instance, as universal resources of measurement-based quantum computations [68,69]. To address the error correction capabilities of SPT states it may be useful to extend the concept of symmetry-resolved entanglement [43,70–77] to the multipartite regime.

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S.S. and D.A. contributed equally to this work.

## APPENDIX A: PROOF OF PROPOSITION 1

We present a proof by contradiction. Consider subsystem A containing  $|A| \leq 2D$  qubits. Let us assume that the subgroup  $S_A$  is not the trivial group. That is, at least one matrix  $\sigma \neq I$  in  $S_A$  exists. Since  $S_A$  is a subgroup of S,  $\sigma$  is the product of generators of S,

$$\sigma = s_{\mathbf{v}_1} s_{\mathbf{v}_2} \cdots s_{\mathbf{v}_r},\tag{A1}$$

where r > 0. The form of the stabilizer generators of the cluster state  $s_{\mathbf{v}}$  is such that there is an X acting on a qubit at  $\mathbf{v}$ . These X cannot turn into the identity in the product in Eq. (A1), as the X for different generators act on different sites. Hence, the set A contains at least r nonidentity Pauli operators.

From the set  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$  there exists one  $\mathbf{v}_h$  that has the highest value of the first coordinate.  $s_{\mathbf{v}_h}$  is a generator of S with support on qubits in  $\{\mathbf{v}_h, \mathbf{v}_h \pm \mathbf{e}_i\}$ , that is,  $\mathbf{v}_h$  and its nearest neighbors. As we selected  $\mathbf{v}_h$  to have the maximal first coordinate, the element  $\sigma$  must contain the Pauli operator  $Z_{\mathbf{v}_h+\mathbf{e}_1}$  because no other stabilizers from the product can cancel it. Therefore,  $\mathbf{e}_h + \mathbf{e}_1$  should be contained in A as the support of  $\sigma$  is in A.

Similarly, from the set  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$ , one generator  $\mathbf{v}_l$  whose first coordinate is the minimal one exists. Therefore,  $\mathbf{v}_l - \mathbf{e}_1$  should also be contained in A.

In one dimension we conclude that any nonidentity  $\sigma$  in A must contain at least r+2 Paulis. Continuing this argument to D dimensions, we conclude that  $\operatorname{supp}(\sigma) \geqslant r+2D$ . This contradicts our assumption that A consists of fewer than 2D+1 qubits. Therefore, if  $|A| \leqslant 2D$ , then  $S_A = \{I\}$ .

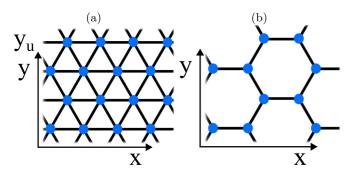


FIG. 6. Vertices represent qubits, and bonds represent controlled-Z gates as in the main text. (a) Triangular lattice. The coordination  $y_u$  is the maximal stabilizer-generator y coordinate (see the text). (b) Hexagonal lattice.

## APPENDIX B: UNIFORMITY OF DIFFERENT 2D LATTICES

In this Appendix we consider the uniformity of different 2D lattices. We focus on the triangular and hexagonal lattices [see Figs. 6(a) and 6(b)]. Here, we consider only infinite lattices. Our analysis, which is summarized in Table I, can be generalized further to different types of lattice structures, such as the 2D Archimedean lattices.

The 2D triangular lattice graph state is generated by stabilizers  $s_v$  of support 7 on any vertex v; thus, the uniformity is at most 6. As in the proof for the 2D cluster state on a square lattice, we prove that the support of any stabilizer is at least 7. Let us focus on stabilizer  $\sigma = \prod_v s_v$ . First, we notice that each vertex v shares at most two neighbors with the vertex  $w \neq v$ ; thus, each additional stabilizer generator at  $s_v$  removes at most support 2 from each other generator. Therefore, as one generator has support 7, two generators have at least support 2(7-2)=10, and k generators have more than support k(7-2[k-1]), which is less than 7 only for four or more generators. Hence, we assume from now on that  $\sigma$  has at least four generators, and all that is left to prove is that  $\sigma$  contains three Z in addition to the four existing X/Y at v for each  $s_v$ .

As in the proof for the square lattice, we focus on the uppermost generators, denoting their y coordinate as  $y_u$  [see Fig. 6(a)]. If there is only one generator  $s_u$  on  $y = y_u$ , it is clear that  $\sigma$  contains two Z on  $y = y_u + 1$  induced by  $s_u$ . If there is more than one such vertex,  $\sigma$  still contains two Z on  $y = y_u + 1$  from the rightmost and leftmost generators at  $y = y_u$ . Similarly, the analysis is the same for the lowermost generators. Therefore,  $\sigma$  has at least four Z, as required. Thus, we have proved that the 2D triangular lattice is 6-uniform.

Let us now focus on the graph state of the 2D hexagonal lattice [see Fig. 6(b)]. As one generator has now support 4, we

TABLE I. The uniformity of different 2D lattice structures.

Lattice	Uniformity			
Square	4			
Triangular	6			
Hexagonal	3			

prove that this lattice is 3-uniform. Proceeding as in the case of the triangular lattice, we focus on  $\sigma = \prod_v s_v$ . Here, each vertex shares at most one neighbor with any other vertex; thus, k generators have more than support m = k(4 - [k - 1]), which is less than 4 only for five or more generators. However, five generators trivially, due to their X/Y, have more than support 4. Hence, the 2D hexagonal lattice graph state is 3-uniform.

## APPENDIX C: 2D-UNIFORMITY OF FINITE CLUSTER STATES

In this Appendix we prove for PBCs that the cluster state with at least eight vertices in each dimension is 2*D*-uniform.

As in Eq. (A1), we consider a subsystem A consisting of 2D or fewer qubits and want to show that no element of the stabilizer group  $S_A$ , other than the identity, fits into it. This follows from Claim 1 below.

First, let us define the "distance" on the lattice.

Definition 1. The Hamming distance between two vertices  $\mathbf{v}$  and  $\mathbf{w}$ , denoted by  $|\mathbf{v} - \mathbf{w}|$ , is the number of edges in the shortest path on the graph from  $\mathbf{v}$  to  $\mathbf{w}$ .

Equivalently, the Hamming distance between two vertices  $\boldsymbol{v}$  and  $\boldsymbol{w}$  is equal to the minimum number of basis vectors  $\boldsymbol{e}_i$  that need to be added to or subtracted from  $\boldsymbol{v}$  to result in  $\boldsymbol{w}$ .

Claim 1. Let  $S_A$  be the stabilizers of the *D*-dimensional cluster state within subsystem *A* such that  $|A| \leq 2D$ . If  $s_{\mathbf{v_1}} s_{\mathbf{v_2}} s_{\mathbf{v_3}} \cdots s_{\mathbf{v_r}} \neq I \in S_A$ , then  $|\mathbf{v_i} - \mathbf{v_j}| \leq 4$  for all  $\mathbf{v_i}, \mathbf{v_j} \in \{\mathbf{v_1}, \mathbf{v_2}, \dots, \mathbf{v_r}\}$ .

Before proving Claim 1 by introducing two lemmas, let us draw our main conclusion from it. Consider a specific vertex  $\mathbf{v_i} \in \{\mathbf{v_1}, \mathbf{v_2}, \dots, \mathbf{v_r}\}$ . From Claim 1, all other vertices lie within a "sphere" of radius r, and hence, all of the Pauli operators involved in  $s_{\mathbf{v_1}}s_{\mathbf{v_2}}s_{\mathbf{v_3}}\cdots s_{\mathbf{v_r}}$  are localized within a sphere of radius r+1. Let us use Jung's theorem [78,79], which relates the diameter of a set to the radius of its bounding sphere, to bound the radius r. Jung's theorem states that  $r \leq 4\sqrt{\frac{D}{2(D+1)}} < \sqrt{8}$ . Hence, there is a sphere that encloses all  $\mathbf{v_i}$  with diameter  $2r < 2\sqrt{8} < 6$ , which implies that we have

at most six vertices in each axis in the sphere. To the sphere diameter we add 2 to cover nearest neighbors, which we denote  $d^* = 2(\sqrt{8} + 1) < 8$ , as each stabilizer generator interacts with only its nearest neighbors. Since the system length 8 is greater than  $d^*$ , we can apply the proof by contradiction of the infinite lattice case in Appendix A since the definition of the "highest" or "lowest" value of the D coordinates exists within the sphere.

To prove Claim 1, we discuss properties of the stabilizer generators for the *D*-dimensional cluster state. The stabilizer generators  $s_v$  of the cluster state have support over 2D + 1 vertices

$$\{v,v\pm e_i\}, \tag{C1}$$



FIG. 7. Qubit scheme of IBMQ Manila.

TABLE II. All the properties (as of its last calibration with respect to the circuit run) of the IBM quantum computer IBMQ Manila, which we used to get the results for the quantum demonstration in Fig. 4(c) on 12 January 2023, 12:13 p.m. Pacific standard time. CNOT = controlled-NOT.

Qubit name	Frequency (GHz)	T <sub>1</sub> (μs)	T <sub>2</sub> (μs)	Readout error	ID error	$\sqrt{X}$ error	PAULI-X error	CNOT error
Q0	4.9623	187.8607	99.2866	$4.71 \times 10^{-2}$	$2.1453 \times 10^{-4}$	$2.1453 \times 10^{-4}$	$2.1453 \times 10^{-4}$	$6.5306 \times 10^{-3}$
Q1	4.8379	150.3745	73.712	$1.89\times10^{-2}$	$2.2034 \times 10^{-4}$	$2.2034 \times 10^{-4}$	$2.2034 \times 10^{-4}$	$[6.5306 \times 10^{-3}, 8.5347 \times 10^{-3}]$
Q2	5.0373	154.846	25.6775	$3.35 \times 10^{-2}$	$2.5892 \times 10^{-4}$	$2.5892 \times 10^{-4}$	$2.5892 \times 10^{-4}$	$[8.5347 \times 10^{-3}, 6.8509 \times 10^{-3}]$
Q3	4.951	193.3112	63.4785	$2.52 \times 10^{-2}$	$2.0920 \times 10^{-4}$	$2.0920 \times 10^{-4}$	$2.0920 \times 10^{-4}$	$[6.8509 \times 10^{-3}, 7.1415 \times 10^{-3}]$
Q4	5.0651	156.7893	40.7793	$3.39 \times 10^{-2}$	$6.3812 \times 10^{-4}$	$6.3812 \times 10^{-4}$	$6.3812 \times 10^{-4}$	$7.1415 \times 10^{-3}$

where  $\{\mathbf{v} \pm \mathbf{e_i}\}$  is the neighborhood of  $\mathbf{v}$ . The product of stabilizer generators  $s_{\mathbf{v}}$  and  $s_{\mathbf{w}}$  does not have support over the intersection of their neighborhoods due to cancellations of Z. We show below how two stabilizer generators can, at most, intersect at two qubits.

Lemma 1. The neighborhoods of two stabilizer generators  $s_v$  and  $s_w$  overlap at most in two vertices for lattices with PBCs where all axes are of length  $\geq 5$ .

*Proof.* Equation (C1) implies that  $s_{\mathbf{v}}$  has support in a ball of radius 1 around  $\mathbf{v}$ . Therefore,  $s_{\mathbf{v}}$  and  $s_{\mathbf{w}}$  intersect only if  $|\mathbf{v} - \mathbf{w}| \leq 2$ . Let us check the intersection case by case.

(i) If  $|\mathbf{v} - \mathbf{w}| = 1$ , then there exists an  $\mathbf{e}_{\mathbf{k}}$  such that

$$\mathbf{v} + \mathbf{e}_{\mathbf{k}} = \mathbf{w}.\tag{C2}$$

The distancebetween neighborhood points of v and w is

$$|\mathbf{v} \pm \mathbf{e_i} - \mathbf{w} \mp \mathbf{e_i}| = |\mathbf{e_i} \mp \mathbf{e_i} - \mathbf{e_k}| \geqslant 1. \tag{C3}$$

This implies that the neighborhoods of  $\mathbf{v}$  and  $\mathbf{w}$  are disjoint.

(ii) If 
$$|\mathbf{v} - \mathbf{w}| = 2$$
, then

$$\mathbf{v} + \mathbf{e}_{\mathbf{k}_1} + \mathbf{e}_{\mathbf{k}_2} = \mathbf{w} \tag{C4}$$

for some indices  $k_1$  and  $k_2$ . Let us check the intersection case by case.

(i) For  $k_1 = k_2$ ,

$$\mathbf{v} + 2\mathbf{e}_{\mathbf{k}_1} = \mathbf{w} \Rightarrow \mathbf{v} + \mathbf{e}_{\mathbf{k}_1} = \mathbf{w} - \mathbf{e}_{\mathbf{k}_1}. \tag{C5}$$

The neighborhoods intersect at only one point  $\mathbf{v} + \mathbf{e}_{\mathbf{k}_1}$ .

(ii) For  $k_1 \neq k_2$ ,

$$v + e_{k_1} + e_{k_2} = w$$
 (C6)

$$\Rightarrow \mathbf{v} + \mathbf{e}_{\mathbf{k}_1} = \mathbf{w} - \mathbf{e}_{\mathbf{k}_2},\tag{C7}$$

and additionally,

$$\Rightarrow \mathbf{v} + \mathbf{e}_{\mathbf{k}_2} = \mathbf{w} - \mathbf{e}_{\mathbf{k}_1}. \tag{C8}$$

Therefore, the neighborhoods intersect at two points:  $\mathbf{v} + \mathbf{e}_{\mathbf{k}_1}$  and  $\mathbf{v} + \mathbf{e}_{\mathbf{k}_2}$ .

The fact that the neighborhoods of two stabilizer generators intersect at most at two vertices implies the following lemma.

Lemma 2. Let  $\sigma = s_{\mathbf{v}_1} s_{\mathbf{v}_2} \cdots s_{\mathbf{v}_r} \in \mathcal{S}_A$ . Then, for any  $s_{\mathbf{v}_i}$  there is a set of D+1 points in A that are localized around  $\mathbf{v}_i$  with at most distance 2.

*Proof.* Let us write  $\sigma = s_{\mathbf{v}_1} s_{\mathbf{v}_2} \cdots s_{\mathbf{v}_r} \in \mathcal{S}_A$ . Consider  $s_{\mathbf{v}_k} \in \{s_{\mathbf{v}_1}, s_{\mathbf{v}_2}, s_{\mathbf{v}_3}, \dots, s_{\mathbf{v}_r}\}$ .  $s_{\mathbf{v}_k}$  has support over 2D neighboring qubits of  $\mathbf{v}_k$ , which we denote as  $\mathcal{N}(\mathbf{v}_k)$ . From Lemma 1, any other stabilizer generator in  $\{s_{\mathbf{v}_1}, s_{\mathbf{v}_2}, s_{\mathbf{v}_3}, \dots, s_{\mathbf{v}_r}\}/\{s_{\mathbf{v}_k}\}$  intersects with at most two vertices in  $\mathcal{N}(\mathbf{v}_k)$ . Then, for  $v_j \in \mathcal{N}(\mathbf{v}_k)$ , either  $v_j \in A$ , or it is in the intersection of  $s_{\mathbf{v}_k}$  and another stabilizer generator. As each intersection contains at most two points in  $\mathcal{N}(\mathbf{v}_k)$ , the minimal number of points  $\mathbf{w} \in A$  that are localized within distance 2 around  $\mathbf{v}_k$  such that  $|\mathbf{w} - \mathbf{v}_k| \leq 2$  is D + 1 (including  $\mathbf{v}_k$  itself).

*Proof of Claim 1.* Consider a *D*-dimensional cluster Hamiltonian with PBCs and subsystem *A*. Let us prove Claim 1 by contradiction. Assume that  $s_{\mathbf{v}_1} s_{\mathbf{v}_2} s_{\mathbf{v}_3} \cdots s_{\mathbf{v}_r} \neq I \in \mathcal{S}_A$  and  $|A| \leq 2D$ . For any  $s_{\mathbf{v}_i}$  in  $\{s_{\mathbf{v}_1}, s_{\mathbf{v}_2}, s_{\mathbf{v}_3}, \ldots, s_{\mathbf{v}_r}\}$  we get at least *D* vertices in *A* that are at most distance 2 away from  $\mathbf{v}_i$  from Lemma 2. Choosing  $\mathbf{v}_i$  and  $\mathbf{v}_j$  such that  $|\mathbf{v}_i - \mathbf{v}_j| > 4$ , then the *D* extra points from  $\mathbf{v}_i$  and  $\mathbf{v}_j$  cannot overlap, and hence, the total number of points in *A* becomes greater than 2*D*.

# APPENDIX D: SPECIFICATIONS OF THE QUANTUM COMPUTER IBMQ MANILA

In this Appendix we provide the different parameters of the quantum computer IBMQ Manila (see scheme in Fig. 7) at the running time of the quantum circuits and their noisy simulations. The noise parameters are extracted from the last calibration before the circuits ran (see Tables II and III). The noisy simulations were done using the usual QISKIT software

TABLE III. All the properties (as of its last calibration with respect to the circuit run) of the IBM quantum computer IBMQ Manila, which we used to get the results for the quantum demonstration in Fig. 4(d) on 14 Jan 2023, 5:23 p.m. Pacific standard time.

Qubit name	Frequency (GHz)	<i>T</i> <sub>1</sub> (μs)	T <sub>2</sub> (μs)	Readout error	ID error	$\sqrt{X}$ error	PAULI-X error	CNOT error
Q0	4.9623	82.21	115.5179	$2.20\times10^{-2}$	$1.8141 \times 10^{-4}$	$1.8141 \times 10^{-4}$	$1.8141 \times 10^{-4}$	$6.2379 \times 10^{-3}$
Q1	4.8379	172.9769	72.0529	$3.05 \times 10^{-2}$	$2.6893 \times 10^{-4}$	$2.6893 \times 10^{-4}$	$2.6893 \times 10^{-4}$	$[6.2379 \times 10^{-3}, 9.5845 \times 10^{-3}]$
Q2	5.0372	125.2094	28.3401	$1.73 \times 10^{-2}$	$2.2990 \times 10^{-4}$	$2.2990 \times 10^{-4}$	$2.2990 \times 10^{-4}$	$[9.5845 \times 10^{-3}, 6.4435 \times 10^{-3}]$
Q3	4.951							$[6.4435 \times 10^{-3}, 6.9814 \times 10^{-3}]$
Q4	5.0651	141.3944	40.0803	$2.98 \times 10^{-2}$	$7.2360 \times 10^{-4}$	$7.2360 \times 10^{-4}$	$7.2360 \times 10^{-4}$	$6.9814 \times 10^{-3}$

#### Listing 1. Python Code.

 $\# \ Qiskit \ version: \ \{ \ 'qiskit-terra \ ': \ '0.23.3 \ ', \ 'qiskit-aer \ ': \ '0.12.0 \ ', \ 'qiskit-ignis \ ': \ '0.6.0 \ ', \ 'qiskit-ibmq-provider \ ': \ '0.20.2 \ ', \ 'qiskit \ ': \ '0.42.1 \ ', \ 'qiskit-nature \ ': \ None, \ 'qiskit-finance \ ': \ None, \ 'qiskit-optimization \ ': \ None, \ 'qiskit-machine-learning \ ': \ None \}$ 

# Extracting calibration at the time of the quantum demonstration
calib\_props = IBMQ.load\_account().get\_backend('ibmq\_manila').properties(datetime=
 insert\_datetime)

# Initiating noise model
NoiseModel.from\_backend\_properties(calib\_props)

package with the standard noise model (see Listing 1 and Ref. [80]). To get the full calibration properties at the time of running the circuits, see Listing 1.

### APPENDIX E: DERIVATION OF EQUATION (9)

In this Appendix we derive Eq. (9). Connecting the *i*th qubit of the cluster state  $|CS\rangle$  with the ancilla (n+1) qubit yields

$$CZ_{i,n+1}|CS\rangle(\alpha|0\rangle + \beta|1\rangle),$$
 (E1)

where  $CZ_{i,n+1} = (1/2)(I + Z_i + Z_{n+1} - Z_iZ_{n+1})$  is the controlled-Z gate acting on the ith and (n+1)th qubits. Therefore, the expression in Eq. (E1) can be expanded as

$$\frac{1}{2}(I + Z_i + Z_{n+1} - Z_i Z_{n+1})(\alpha | CS \rangle | 0 \rangle + \beta | CS \rangle | 1 \rangle)$$

$$= \alpha | CS \rangle | 0 \rangle + \beta Z_i | CS \rangle | 1 \rangle$$

$$= \frac{1}{\sqrt{2}}((\alpha | CS \rangle + \beta Z_i | CS \rangle) | + \rangle + (\alpha | CS \rangle - \beta Z_i | CS \rangle) | - \rangle).$$
(E2)

Measuring the (n + 1)th qubit in the X basis and postselecting the X = +1 eigenvector yield the encoded state

$$\alpha |\text{CS}\rangle + \beta Z_i |\text{CS}\rangle.$$
 (E3)

This procedure can be generalized to the case where the ancilla qubit is connected to an arbitrary set *A* of qubits, leading to Eq. (9).

# APPENDIX F: 2D-UNIFORM CLUSTER STATE WITH A LOGICAL SUBSPACE

In this Appendix we derive a lower bound for the number of qubits A of the cluster state that the central qubit needs to

be entangled with in order for the resulting logical space to retain the 2D-uniformity of the cluster state.

We first denote the encoded state in Eq. (9) as

$$|\phi\rangle = \alpha |\text{CS}\rangle + \beta \mathcal{Z}_A |\text{CS}\rangle,$$
 (F1)

where  $\mathcal{Z}_A = \prod_{i \in A} Z_i$ . Now,  $|\phi\rangle$  is *m*-uniform iff  $\langle \phi | \hat{O}(m) | \phi \rangle = 0$  for  $\hat{O}(m)$  being a string of up to *m* Pauli matrices acting nontrivially in *A*. We will show that m = 2D. This leads to the requirement

$$0 = \langle \phi | \hat{O}(m) | \phi \rangle = |\alpha|^2 \langle \text{CS} | \hat{O}(m) | \text{CS} \rangle + \alpha^* \beta \langle \text{CS} | \hat{O}(m) \mathcal{Z}_A | \text{CS} \rangle + \alpha \beta^* \langle \text{CS} | \mathcal{Z}_A \hat{O}(m) | \text{CS} \rangle + |\beta|^2 \langle \text{CS} | \mathcal{Z}_A \hat{O}(m) \mathcal{Z}_A | \text{CS} \rangle. \quad (F2)$$

Since  $|CS\rangle$  is 2D-uniform and the operator  $\mathcal{Z}_A \hat{O}(m) \mathcal{Z}_A$  acts on at most m qubits, the first and fourth terms of the right-hand side of Eq. (F2) vanish for m = 2D.

We assume that |A| > m. The second term,  $\langle CS|\hat{O}(m)\mathcal{Z}_A|CS\rangle$ , is zero if  $\hat{O}(m)\mathcal{Z}_A$  is not contained in the generalized Bloch expansion [81] of |CS\). Since |CS\) is a stabilizer state, all of its Bloch expansion terms are generated by the stabilizers  $\{s_v\}$ . Now,  $\hat{O}(m)$  contains a maximum of m-X and/or Y. Therefore,  $\hat{O}(m)\mathcal{Z}_A$  is a product of at most m stabilizer generators  $s_i$ . Since each stabilizer generator contributes 2D Z, the product of m such stabilizer generators is an operator with Z acting on a maximum of 2Dm qubits. Also,  $\hat{O}(m)\mathcal{Z}_A$  contains a minimum of |A|-m Z. Therefore, a sufficient condition for  $\hat{O}(m)\mathcal{Z}_A$  to be excluded from the Bloch expansion of  $|\phi\rangle$  is for the maximum number of qubits that can be acted upon by Z coming from the stabilizer generators to be less than the minimum number of Z possible in  $\hat{O}(m)\mathcal{Z}_A$ . This yields

$$2Dm < |A| - m \Rightarrow m(2D + 1) < |A|$$
. (F3)

Substituting m = 2D, we obtain the anticipated condition

$$2D(2D+1) < |A|$$
. (F4)

The same argument applies for the third term in Eq. (F2). In one dimension, this lower bound gives  $|A| \ge 7$ .

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