Noise thresholds for classical simulability of nonlinear boson sampling

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Boson sampling, a computational problem conjectured to be hard to simulate on a classical machine, is a promising candidate for an experimental demonstration of quantum advantage using bosons. However, inevitable experimental noise and imperfections, such as loss in the interferometer and random counts at the detectors, could challenge the sampling task from entering the regime where quantum advantage is achievable. In this work we introduce higher-order nonlinearities as a means to enhance the computational complexity of the problem and the protocol's robustness against noise, i.e., to increase the noise threshold that allows us to perform an efficient classical simulation of the problem. Using a phase-space method based on the negativity volume of the relevant quasiprobability distributions, we establish a necessary nonclassicality condition that any experimental proof of quantum advantage must satisfy. Our results indicate that the addition of single-mode Kerr nonlinearity at the input-state preparation level, while retaining a linear-optical evolution, makes the boson-sampling protocol more robust against noise and consequently relaxes the constraints on the noise parameters required to show quantum advantage.

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I. INTRODUCTION

Boson sampling is a well-defined computational problem, first introduced by Aaronson and Arkhipov [1] and conjectured to be computationally hard to simulate on a classical computer, that consists of sampling from the output distribution of N photons undergoing evolution via a passive linear-optical network (LON). A passive interferometer does not contain active optical elements that alter the total photon number; that is, the network comprises only beam splitters, phase shifters, and mirrors. The hardness of the task stems from the fact that the transition amplitude between the initial state and the measurement outcome involves the computation of the permanent of a complex matrix [2], a problem that is believed to be #P-hard [3]. The best-known classical algorithm for computing matrix permanents, i.e., Ryser's formula, scales exponentially with the dimension of the problem [4]. Under some plausible complexity-theoretic assumptions, simulating boson sampling-even approximately-has been proven to be a classically intractable computational task, and for this reason, it is a promising candidate to experimentally show quantum advantage, i.e., the ability to outperform any classical computer on a specific task. In fact, the advancement that photonic quantum technologies have seen in recent years [5] has brought proving the quantum advantage within reach with current technological capabilities.

Several variants of the original task which lie in the same complexity class have been considered, mostly focusing on using different classes of input states such as photon-added coherent states [6], generalized cat states [7], and photonadded or photon-subtracted squeezed vacuums [8]. Most notably, Gaussian boson sampling (GBS) [9] constitutes a more experimentally feasible candidate to prove quantum advantage [10], as it does not require single-photon generation, but rather exploits squeezed light as the initial state. Additionally, GBS has application in counting the perfect matchings of graphs [11], measuring graph similarity [12], and simulating vibronic molecular spectra [13].

However, inevitable noise in experimental realizations of boson sampling might render the task classically efficiently simulable. The effect of noise in boson sampling and its connection to efficient the classical simulability of the related computational problem have been extensively explored, considering partial photon distinguishability, losses, mode mismatching, and random counts of the detectors [14-22]. In some cases one is able to provide sufficient conditions for efficient classical simulations of boson-sampling experiments that are expressed in the form of inequalities that involve the noise parameters at play [14,15]. A possible way to make the realization of boson sampling more robust against noise and defects is to enhance the computational complexity of the task and thus relax the constraints on noise parameters required for an experimental demonstration of quantum advantage. In this context, when we say that a boson-sampling protocol becomes more robust against noise, we mean that the noise thresholds sufficient for an efficient classical simulation to be feasible do increase.

It was recently suggested [23] that we should introduce nonlinear photon-photon interactions into the boson-sampling framework as a way to increase the task's complexity. In Ref. [23] the authors considered Fock states as the input, and the nonlinearity was introduced within the otherwise linear evolution. They provided an upper bound on complexity using a simulation method that allows us to effectively induce nonlinear gates using linear-optical elements, auxiliary modes, and photons and postselection on photodetection measurement outcomes.

We introduce single-mode nonlinear gates in a noisy Gaussian boson-sampling problem as a way to increase its computational complexity and to relax the constraints on the maximum threshold of noise parameters necessary to prove quantum advantage. These higher-order nonlinearities are introduced at the state-preparation level because, as we show in the next sections, the techniques we employ to compute these thresholds require the initial state to undergo a linear-optical evolution. To this end, we use the formalism introduced by Rahimi-Keshari et al. [15], who presented general sufficient conditions for the efficient classical simulation of a generic quantum optics experiment, with boson sampling being a special case. This formalism is particularly helpful in studying how noise and imperfections, e.g., photon loss and subunit efficiency of the photodetectors, affect the classical intractability of boson-sampling tasks. The method is based on expressing the output probability distribution as a function of ordered phase-space quasiprobability distributions (PQDs) of the input state, the output measurements, and the transition function associated with the specific quantum process. If for specific operator orderings all of these PQDs are non-negative, then an efficient classical simulation is feasible. This result further identifies negativity as a necessary condition and as a resource to achieve quantum speedup [24,25].

Previous works studying boson-sampling protocols with nonclassical input states mostly focused on proving, using an array of case-dependent techniques, that such tasks are at least as hard to simulate as boson sampling [6-9]. In this paper we approach the problem from a different angle. We introduce noise in the system, in the form of loss and nonideal detection, and gauge the enhancement in complexity due to the introduction of nonlinear gates by probing an increase of the noise thresholds sufficient for an efficient classical simulation to be feasible. Our results show how adding single-mode Kerr nonlinearities at the state-preparation level makes the bosonsampling task more robust to the inevitable experimental noise and imperfections that may jeopardize achieving quantum advantage. In particular, in order to carry out analytical calculations, we consider a specific family of discrete values of the Kerr parameter that, in turn, leads to generalized squeezed cat states or superpositions of vacuum states squeezed in different directions as initial states.

This paper is structured as follows. In Sec. II we revise some key facts about the phase-space formalism of quantum mechanics, including the concepts of characteristic functions and ordered PQDs, and outline Rahimi-Keshari *et al.*'s sufficient condition for an efficient classical simulation of a generic quantum optics experiment. In Sec. III we introduce our model of the nonlinear noisy boson-sampling problem and outline the techniques used to compute noise thresholds for efficient classical simulability. Sections IV and V are dedicated to investigating how two closely related families of initial states, both containing self-Kerr nonlinearities, are able to increase these noise thresholds. Last, in Sec. VI we draw conclusions and give some final remarks.

II. SUFFICIENT CONDITIONS FOR EFFICIENT CLASSICAL SIMULATION OF QUANTUM OPTICS

A generic bosonic experiment is described in terms of an M-mode input state ρ_{in} , an M-mode quantum process described by a CP map \mathcal{E} , and a measurement on the output state $\rho_{out} = \mathcal{E}(\rho_{in})$ described by a positive operator-valued measure (POVM). The POVM elements { Π_n } satisfy the condition $\sum_n \Pi_n = \mathcal{I}$, where \mathcal{I} is the identity operator on the M-mode Hilbert space. The output probability distribution p(n) of the experiment is thus given by the Born rule $p(n) = \text{Tr}\rho_{out}\Pi_n$. In Ref. [15], a sufficient condition for efficient classical simulability of the experiment was established based on the well-developed theory of *s*-ordered phase-space quasiprobability distributions (*s*-PQDs). In particular, the *s*-PQD of a generic M-mode quantum state ρ is defined as

$$W_{\rho}^{(s)}(\boldsymbol{\beta}) = \int \frac{d^{2M}\boldsymbol{\xi}}{\pi^{2M}} \, \Phi_{\rho}^{(s)}(\boldsymbol{\xi}) e^{\boldsymbol{\beta}\boldsymbol{\xi}^{\dagger} - \boldsymbol{\xi}\boldsymbol{\beta}^{\dagger}}, \tag{1}$$

where $\Phi_{\rho}^{(s)}(\boldsymbol{\xi})$ is the *s*-ordered characteristic function of ρ ,

$$\Phi_{\rho}^{(s)}(\boldsymbol{\xi}) = \mathrm{Tr}\rho D(\boldsymbol{\xi}) e^{\frac{\boldsymbol{\xi} \boldsymbol{\xi} \boldsymbol{\xi}^{\dagger}}{2}}.$$
 (2)

Here, $s = \text{diag}(s_1, \ldots, s_M)$ is a diagonal matrix containing the *M* ordering parameters $s_j \in \mathbb{R}$, and $D(\boldsymbol{\xi})$ is the usual *M*-mode displacement operator,

$$D(\boldsymbol{\xi}) = e^{\boldsymbol{\xi} \boldsymbol{a}^{\dagger} - \boldsymbol{a} \boldsymbol{\xi}^{\dagger}},\tag{3}$$

with $a = (a_1, \ldots, a_M)$ being the vector of annihilation operators. The Husimi Q function, the Wigner function, and the Glauber-Sudarshan P function are obtained for $s = -\mathbb{I}_M$, s = 0, and $s = \mathbb{I}_M$, respectively, where \mathbb{I}_M denotes the $M \times M$ identity matrix. The definition of *s*-PQD is then straightforwardly extended to any Hermitian operator, such as the elements of a POVM. It is worth noting that the *s*-PQD of a Hermitian operator is a real function and that the *s*-PQD of a quantum state is also normalized to 1. It is then possible to express the output probability distribution of outcomes p(n) in terms of quasiprobability distributions of the input state and of the POVM elements as

$$p(\boldsymbol{n}) = \int d^{2M} \boldsymbol{\beta} \int d^{2M} \boldsymbol{\alpha} \, \pi^M W_{\Pi_n}^{(-s)}(\boldsymbol{\beta}) T_{\mathcal{E}}^{(s,t)}(\boldsymbol{\alpha}, \boldsymbol{\beta}) W_{\rho_{\text{in}}}^{(t)}(\boldsymbol{\alpha}).$$
⁽⁴⁾

Here, $W_{\Pi_n}^{(-s)}$ is the (-s)-PQD of the POVM element Π_n , $W_{\rho_{in}}^{(t)}$ is the *t*-PQD of the input state, and $T_{\mathcal{E}}^{(s,t)}$ is the transition function associated with the quantum process \mathcal{E} . The latter is defined as

$$T_{\mathcal{E}}^{(s,t)}(\boldsymbol{\alpha},\boldsymbol{\beta}) = \int \frac{d^{2M}\boldsymbol{\zeta}}{\pi^{2M}} e^{\frac{s\boldsymbol{\xi}^{\dagger}}{2}} e^{\boldsymbol{\beta}\boldsymbol{\xi}^{\dagger} - \boldsymbol{\zeta}\boldsymbol{\beta}^{\dagger}} \int \frac{d^{2M}\boldsymbol{\xi}}{\pi^{2M}} e^{-\frac{\boldsymbol{\xi}\boldsymbol{\xi}^{\dagger}}{2}} \times e^{\boldsymbol{\xi}\boldsymbol{\alpha}^{\dagger} - \boldsymbol{\alpha}\boldsymbol{\xi}^{\dagger}} \operatorname{Tr}\mathcal{E}(D^{\dagger}(\boldsymbol{\xi}))D(\boldsymbol{\zeta}).$$
(5)

One can show that

$$\mathcal{E}(D^{\dagger}(\boldsymbol{\xi})) = e^{\frac{\boldsymbol{\xi}\boldsymbol{\xi}^{\dagger}}{2}} \int \frac{d^{2M}\boldsymbol{\gamma}}{\pi^{M}} e^{\boldsymbol{\gamma}\boldsymbol{\xi}^{\dagger} - \boldsymbol{\xi}\boldsymbol{\gamma}^{\dagger}} \mathcal{E}(|\boldsymbol{\gamma}\rangle\langle\boldsymbol{\gamma}|).$$
(6)

Hence, the action of the LON on a coherent-state input, i.e., $\mathcal{E}(|\gamma\rangle\langle\gamma|)$, is everything we need in order to compute the transition function. We are now ready to enunciate a sufficient

condition for efficient classical simulation of the sampling problem outlined above. If there exist values of s and t such that the PQD of the input, the PQD of the POVM, and the transition function are all non-negative and well behaved (i.e., they do not diverge more severely than a δ function), then a classical simulation of the sampling problem can be carried out efficiently. We point out that this formalism allows us to consider only *exact* simulations; that is, with this simulation strategy the samples are drawn according to p(n) and not from an approximation of this probability distribution. We also stress the fact that this condition is only sufficient and, indeed, there might be other efficient simulation methods where this condition is not satisfied.

III. THE MODEL

Our model consists of a modification of GBS. The latter is a sampling problem where M single-mode squeezed states are injected in an $M \times M$ linear-optical interferometer and are then measured with on-off photodetectors at its output ports. The *s*-PQD of a generic M-mode Gaussian state ρ reads

$$W_{\rho}^{(s)}(\boldsymbol{\beta}) = \frac{2^{M}}{\pi^{M}} \frac{1}{\sqrt{\det \boldsymbol{\sigma} - \tilde{s}}} e^{-2(\boldsymbol{\beta} - \boldsymbol{\alpha})^{\mathsf{T}}(\boldsymbol{\sigma} - \tilde{s})^{-1}(\boldsymbol{\beta} - \boldsymbol{\alpha})}, \quad (7)$$

where σ and α are, respectively, the covariance matrix and the vector of the first moments of ρ and \tilde{s} is an ordering matrix defined as

$$\tilde{s} = \bigoplus_{j=1}^{M} s_j \mathbb{I}_2.$$
(8)

Note that the conventions we use are such that for a singlemode coherent state $|\alpha\rangle$ the covariance matrix is the identity matrix $\sigma = \mathbb{I}_2$ and the vector of the first moments reads $\alpha =$ (Re α , Im α).

The *s*-PQD of a Gaussian state is well defined and has the Gaussian form in Eq. (7) as long as

$$\boldsymbol{\sigma} - \tilde{\boldsymbol{s}} \geqslant \boldsymbol{0}; \tag{9}$$

otherwise, the *s*-PQD becomes a more singular δ function and does not allow for efficient sampling. It thus follows that the *s*-PQD of a coherent state $|\alpha\rangle$ is well behaved for $s \leq 1$ and that the *s*-PQD of a squeezed vacuum $S(\xi) |0\rangle$ is properly defined for $s \leq e^{-2r}$ (r > 0). Here, the complex squeezing parameter is $\xi = re^{i\phi}$. We recall that the single-mode squeezing operator is defined as

$$S(re^{i\phi}) = e^{\frac{r}{2}(e^{i\phi}a^{\dagger 2} - e^{-i\phi}a^2)},$$
(10)

where *a* and a^{\dagger} are bosonic operators.

It is well known that ideal GBS is not classically efficiently simulable [9]. This is not necessarily true anymore if we introduce noise to the system and thus consider a realistic experimental implementation of the sampling problem.

An *M*-mode passive LON is associated with an $M \times M$ transfer matrix *L* satisfying $LL^{\dagger} \leq \mathbb{I}$, which describes how the input modes are linearly mixed by the interferometer. For a lossless LON *L* is simply a unitary matrix. Hence, a lossy LON takes an *M*-mode coherent state $|\boldsymbol{\gamma}\rangle$ to another coherent state, i.e.,

$$\mathcal{E}(|\boldsymbol{\gamma}\rangle\langle\boldsymbol{\gamma}|) = |\boldsymbol{\gamma}L\rangle\langle\boldsymbol{\gamma}L|. \tag{11}$$

This expression stems from a simple model in which we consider M additional environmental modes in the vacuum state that interact with the system's actual M modes via a lossless 2M-mode LON, whose unitary transfer matrix U is given by

$$\boldsymbol{U} = \begin{pmatrix} \boldsymbol{L} & \boldsymbol{N} \\ \boldsymbol{P} & \boldsymbol{Q} \end{pmatrix}. \tag{12}$$

Equation (11) then follows from tracing out the degrees of freedom of the environment, i.e.,

$$\mathcal{E}(|\boldsymbol{\gamma}\rangle\langle\boldsymbol{\gamma}|) = \mathrm{Tr}\mathcal{U}|\boldsymbol{\gamma}, \boldsymbol{0}\rangle\langle\boldsymbol{\gamma}, \boldsymbol{0}|\mathcal{U}^{\dagger}$$

= Tr| $\boldsymbol{\gamma}L, \boldsymbol{\gamma}N\rangle\langle\boldsymbol{\gamma}L, \boldsymbol{\gamma}N| = |\boldsymbol{\gamma}L\rangle\langle\boldsymbol{\gamma}L|,$ (13)

where \mathcal{U} is the unitary operator associated with the larger 2*M*-mode interferometer. *L* is a submatrix of *U*; hence, the unitarity of the latter guarantees that $L^{\dagger}L \leq \mathbb{I}$. If one further assumes that all paths in the network suffer the same amount of loss, then *L* is simply a unitary matrix multiplied by a factor $\sqrt{\eta_L}$ with $0 \leq \eta_L \leq 1$. In Appendix B we describe how thermal noise can be added to our model and how the conclusions of this work are affected by it.

We also consider noisy on-off photodetection characterized by subunit efficiency η_D and by a random count probability p_D . Following Ref. [15], the POVM elements of this measurement are given by

$$\Pi_0 = (1 - p_D) \sum_{m=0}^{\infty} (1 - \eta_D)^m |m\rangle \langle m|, \qquad (14)$$

$$\Pi_1 = \mathbb{I} - \Pi_0, \tag{15}$$

where $0 \le \eta_D \le 1$ and $0 \le p_D \le 1$. By noting that Π_0 is an un–normalized thermal state one obtains the following (*-s*)-PQD:

$$W_{\Pi_0}^{(-s)}(\boldsymbol{\beta}) = \frac{1 - p_D}{\pi} \frac{1}{1 - \eta_D \left(\frac{1 - s}{2}\right)} \exp\left[\frac{-\eta_D |\boldsymbol{\beta}|^2}{1 - \eta_D \left(\frac{1 - s}{2}\right)}\right], \quad (16)$$

which is non-negative—and properly defined—for $s \ge 1 - \frac{2}{n_0}$. Since $\Pi_0 + \Pi_1 = \mathbb{I}$, we also have that

$$W_{\Pi_1}^{(-s)}(\boldsymbol{\beta}) = \frac{1}{\pi} - W_{\Pi_0}^{(-s)}(\boldsymbol{\beta}).$$
(17)

One then easily proves that $W_{\Pi_1}^{(-s)}$ is non-negative for

$$s \geqslant 1 - \frac{2p_D}{\eta_D} \equiv \overline{s}.$$
 (18)

Hence, the noisy photodetection (-s)-PQD is non-negative for $s \ge \overline{s}$. If we then consider M identical photodetection measurements at the end of our LON, the (-s)-PQD of the measurement is just the product of the $(-s_j)$ -PQD of the single-mode measurements, i.e.,

$$W_{\Pi_n}^{(-s)} = \Pi_{k=1}^M W_{\Pi_{n_k}}^{(-s_k)}.$$
(19)

Consequently, the total (-s)-PQD is non-negative for $s_k \ge \overline{s} \quad \forall k$.

The last thing that we need to consider is the transition function $T_{\mathcal{E}}^{(s,t)}$ associated with a LON described by the transfer matrix *L*. In Ref. [15], Rahimi-Keshari *et al.* proved that it

has the form of a multivariate Gaussian function, and hence is non-negative and well behaved, if and only if

$$\mathbb{I}_M - L^{\dagger}L - s + L^{\dagger}tL \ge 0.$$
⁽²⁰⁾

In Appendix B we show how this inequality is modified once thermal effects are taken into account.

If the input state *t*-PQD is non-negative for $t \le \overline{t}$ and the (-s)-PQD of the measurement is non-negative for $s \ge \overline{s}$, then Eq. (20) is satisfied if and only if

$$\mathbb{I}_M - L^{\dagger}L - \bar{s} + L^{\dagger}\bar{t}L \ge 0.$$
⁽²¹⁾

If we further consider a lossy LON described by the transfer matrix $L = \sqrt{\eta_L} U$ and identical noisy detection at each output port as outlined above, i.e., $\bar{s} = \bar{s}\mathbb{I} = (1 - \frac{2p_D}{\eta_D})\mathbb{I}$, it is then possible to recast the previous condition as

$$\left(\frac{2p_D}{\eta_D} - \eta_L\right) \mathbb{I}_M + \eta_L \bar{t} \ge 0.$$
(22)

We can now compute \bar{t} for different input states and use the previous inequality to compute noise thresholds sufficient for classical simulability.

As a first example we might consider input coherent states, i.e., $\bar{t} = \mathbb{I}_M$. As expected, inequality (22) tells us that such a sampling problem is efficiently classically simulable even in the absence of noise, as this problem is equivalent to sampling from an *M*-mode coherent state. On the other hand, if we consider *M* single-mode squeezed vacuum states as input, i.e., $\bigotimes_{j=1}^M S(r) |0\rangle$, then Eq. (9) implies that the input state *t*-PQD is well defined and non-negative for $t < \bar{t} = e^{-2r} \mathbb{I}_M$. Hence, in this scenario, the sampling problem can be simulated efficiently if the noise parameters satisfy

$$\frac{p_D}{\eta_D} \geqslant \frac{\eta_L}{2} (1 - e^{-2r}). \tag{23}$$

We stress, once again, that these noise thresholds for efficient classical simulation provide only a sufficient condition. We also point out that Eq. (23) is consistent with the condition for classical simulability of noisy Gaussian boson sampling obtained in Ref. [14]. In that work the authors proved that a sufficient condition for the existence of an efficient classical simulation of a noisy GBS experiment as described above, up to error ε , is given by

$$\operatorname{sech}\left\{\frac{1}{2}\Theta\left[\ln\left(\frac{1-2q_D}{\eta_L e^{-2r}+1-\eta_L}\right)\right]\right\} > e^{-\varepsilon^2/4M},\qquad(24)$$

where $q_D = \frac{p_D}{\eta_D}$ and $\Theta(x) = \max(x, 0)$ is the ramp function.

We now aim to tackle the following question. How do these noise thresholds for efficient classical simulation change when higher-order nonlinearities are introduced in the model? Answering this question will tell us if, with the addition of higher-order nonlinearities, we can afford to allow more noise in a hypothetical experimental setup but still have a sampling problem that is not efficiently classically simulable. There is obviously a lot of freedom in how to introduce nonlinearities in a boson-sampling protocol. In fact, they can be added to the input-state preparation stage, within the evolution or as part of the measurement. However, it is clear that if we want to apply condition (22) in this new setting, we still need to retain a linear-optical interferometer. We will thus add the nonlinear operations at the input-state preparation level.

As a simple example of this paradigm, we consider singlemode Kerr nonlinearities, i.e., $U(\chi) = e^{-i\chi a^{\dagger 2}a^{2}}$, where $\chi \in \mathbb{R}$ is the Kerr parameter. Using Baker-Campbell-Hausdorff identities, one easily displays the action of $U(\chi)$ on the annihilation operator *a* (we provide the proof in Appendix C), namely,

$$U^{\dagger}(\chi)aU(\chi) = e^{-2i\chi a^{\dagger}a}a.$$
(25)

Equation (25) shows that the Kerr transformation is an energydependent phase rotation of the mode. In the following sections we consider two closely related classes of initial states: $S(r)U(\chi) |\alpha\rangle$ and $U(\chi)S(r) |0\rangle$.

IV. INPUT STATE $S(r)U(\chi) |\alpha\rangle$

Let us consider a sampling problem like the one described in the previous section, where the *M*-mode input state is now given by M copies of $S(r)U(\chi)|\alpha\rangle$. The strategy to obtain the noise thresholds for efficient classical simulability remains the same: compute the *t*-PQD of the initial state, find the value \bar{t} for which the function is non-negative for every $t \leq \bar{t}$, and, finally, use Eq. (22) to compute the desired threshold. We remind the reader that since the input state is a tensor product of identical states, we have $\bar{t} = \bar{t} \mathbb{I}_M$. Unfortunately, one soon realizes it is not possible to obtain an analytical, easy-to-use, closed formula for the *t*-PQD of $S(r)U(\chi) |\alpha\rangle$ for a generic value of χ . A way around this is to consider discrete values of the Kerr parameter, specifically $\chi = \frac{\pi}{m}$ with m being an integer. Notice how this corresponds to discrete-time Kerr-type interactions. In this scenario, $U(\chi) |\alpha\rangle$ produces a superposition of coherent states (catlike states) that lie on a circumference in the phase space [26]. In fact, the operator

$$U(\chi = \pi/m) \equiv U^{(m)} = e^{-i\frac{\pi}{m}\hat{n}(\hat{n}-1)}$$
(26)

has nice periodic properties that allow for a useful Fourier representation of the operator which, in turn, leads us to

$$|\psi_m\rangle \equiv U^{(m)} |\alpha\rangle = \sum_{q=0}^{m-1} f_q^{(o)} \left|\alpha e^{-\frac{2\pi i q}{m}}\right\rangle, \quad m = \text{odd}, \quad (27)$$

$$|\psi_m\rangle \equiv U^{(m)} |\alpha\rangle = \sum_{q=0}^{m-1} f_q^{(e)} \left|\alpha e^{-\frac{2\pi i q}{m} + \frac{i\pi}{m}}\right\rangle, \quad m = \text{even.} \quad (28)$$

The coefficients that appear in the sums are given by

$$f_q^{(o)} = \frac{1}{m} \sum_{k=0}^{m-1} e^{\frac{2\pi i q}{m} k} e^{-\frac{i\pi}{m} k(k-1)},$$
(29)

$$f_q^{(e)} = \frac{1}{m} \sum_{k=0}^{m-1} e^{\frac{2\pi i q}{m} k} e^{-\frac{i \pi}{m} k^2}.$$
 (30)

For example, with m = 2 one obtains the well-known Yurke-Stoler cat state up to a phase shift, namely,

$$|\psi_2\rangle = \frac{1}{\sqrt{2}}|i\alpha\rangle + \frac{i}{\sqrt{2}}|-i\alpha\rangle.$$
 (31)

We point out that Ref. [7] presents evidence that boson sampling using arbitrary superpositions of coherent states as input is likely to implement a classically hard problem. It is also worth noting that for m = 1, i.e., $\chi = \pi$, we have $U(\chi = \pi) = e^{-i\pi\hat{n}(\hat{n}-1)} = \mathcal{I}$. Hence, unlike squeezing, Kerr nonlinearity does not always produce a nonclassical effect on a classical initial state.

Hence, our input state is a superposition of squeezed coherent states

$$S(r)U^{(m)} |\alpha\rangle = \sum_{q=0}^{m-1} f_q^{(o)} S(r) \left| \alpha e^{-\frac{2\pi i q}{m}} \right\rangle, \quad m = \text{odd}, \quad (32)$$
$$S(r)U^{(m)} |\alpha\rangle = \sum_{q=0}^{m-1} f_q^{(e)} S(r) \left| \alpha e^{-\frac{2\pi i q}{m} + \frac{i\pi}{m}} \right\rangle, \quad m = \text{even}.$$

Consequently, the *t*-PQD of the input state $S(r)U(\chi) |\alpha\rangle$ is readily obtained once we have the *t*-PQD of $S(r) |\alpha\rangle\langle\gamma| S^{\dagger}(r)$. One can prove that the *t*-ordered characteristic function of this operator reads

$$\phi^{(t)}(\xi) = \operatorname{Tr}S(r) |\alpha\rangle\langle\gamma| S^{\dagger}(r)D(\xi)e^{\frac{1}{2}|\xi|^{2}}$$

= $e^{\frac{1}{2}\{-|\xi\mu-\xi^{*}\nu+\alpha-\gamma|^{2}+[\gamma^{*}(\xi\mu-\xi^{*}\nu+\alpha)+\alpha^{*}(\xi\mu-\xi^{*}\nu)-c.c.]\}}$
 $\times e^{\frac{t}{2}|\xi|^{2}}.$ (34)

where $\mu = \cosh(r)$ and $\nu = \sinh(r)$. In order to obtain Eq. (34) one has to use $S^{\dagger}(r)D(\xi)S(r) = D(\xi\mu - \xi^*\nu)$ and the well-known composition rule of consequent displacement operators, i.e.,

$$D(\alpha)D(\beta) = D(\alpha + \beta)e^{\frac{1}{2}(\alpha\beta^* - \alpha^*\beta)}.$$
 (35)

We can then Fourier transform the characteristic function and obtain an analytical expression for the *t*-PQD of $S(r) |\alpha\rangle\langle\gamma| S^{\dagger}(r)$ and, in turn, the *t*-PQD of our input state. The last step to obtain the desired noise thresholds consists of finding the value \bar{t} for which the *t*-PQD of the initial state is non-negative for all $t \leq \bar{t}$. This is achieved by numerically computing the *volume of negativity* \mathcal{N} of the *t*-PQD as a function of the ordering parameter *t*, i.e.,

$$\mathcal{N}(t) = \int d^2 \boldsymbol{\beta} |W^{(t)}(\boldsymbol{\beta})| - 1.$$
(36)

We have strong numerical evidence that the *t*-PQD of $S(r)U^{(m)} |\alpha\rangle$ becomes non-negative for $t \leq \overline{t} = -1 \quad \forall \alpha \in \mathbb{C}, \quad \forall r > 0 \text{ and } m \geq 2$. Figure 1 displays, with a specific example, the typical features of the negativity volume associated with the input state $S(r)U(\chi = \pi/m) |\alpha\rangle$ *t*-PQD. Finally, using $\overline{t} = -1$ in Eq. (22) yields the sufficient condition for efficient classical simulability

$$\frac{p_D}{\eta_D} \geqslant \eta_L. \tag{37}$$

Recall that, without Kerr nonlinearity, the threshold was $\frac{p_D}{\eta_D} \ge \frac{\eta_L}{2}(1 - e^{-2r})$. Hence, more noise is needed to simulate the nonlinear system, which suggests that the Kerr nonlinearity does, indeed, increase the complexity of the sampling problem. In Appendix B we discuss how this result is affected once we consider finite-temperature effects. Note that the *t*-PQD with t = -1, i.e., the Husimi Q function, is non-negative by



FIG. 1. The negativity volume $\mathcal{N}(t)$ of the *t*-PQD associated with the input state $S(r = 0.2)U(\chi = \pi/3) |\alpha = 1\rangle$. As can be seen from the inset, the function reaches zero for t = -1. Similar plots and behavior, i.e., negativity volume approaching zero monotonically at t = -1, are obtained for every r > 0, $\alpha \in \mathbb{C}$ and for every integer m > 1.

definition for *every* state ρ . In fact, we can show that

-0.6

-0.8

$$W_{\rho}^{(-1)}(\beta) \equiv Q_{\rho}(\beta) = \frac{1}{\pi} \langle \beta | \rho | \beta \rangle.$$
(38)

-0.4

-0.2

This means that a sampling experiment like the one described above, i.e., lossy LON and noisy detection, is actually classically efficiently simulable for every input state if $\frac{p_D}{\eta_D} \ge \eta_L$. Hence, we have proved that, using the Rahimi-Keshari general method of simulation, a noisy sampling problem as described above with $S(r)U^{(m)} |\alpha\rangle$ as the input state requires the "maximum" amount of noise in order to be classically efficiently simulable.

V. INPUT STATE $U(\chi)S(r) |0\rangle$

We can now focus on another closely related class of initial states, namely, $U(\chi)S(r)|0\rangle$. For generic values of the Kerr parameter χ , we once again encounter difficulties in the analytical calculation of the characteristic function in a closed formula. However, like for the previous model, if we consider $\chi = \frac{\pi}{m}$ and apply $U^{(m)}$ to a squeezed vacuum state $S(r)|0\rangle$, we obtain a quantum superposition of squeezed vacuum states [26]

$$U^{(m)}S(r)|0\rangle = \sum_{q=0}^{m-1} f_q^{(o)} S\left(re^{-\frac{4\pi i q}{m}}\right)|0\rangle, \quad m = \text{odd}, \quad (39)$$

$$U^{(m)}S(r)|0\rangle = \sum_{q=0}^{m-1} f_q^{(e)} S\left(r e^{\frac{-4\pi i q + 2\pi i}{m}}\right)|0\rangle, \quad m = \text{even.} \quad (40)$$

The coefficients $f_q^{(o)}$ and $f_q^{(e)}$ are still given by Eqs. (29) and (30), respectively. Recalling how the annihilation operator transforms under the single-mode squeezing unitary operation (10),

$$S^{\dagger}(re^{i\phi})aS(re^{i\phi}) = \mu a + e^{i\phi}va^{\dagger}, \qquad (41)$$

t



FIG. 2. The negativity volume $\mathcal{N}(t)$ of the *t*-PQD associated with the input state $U(\chi = \pi/3)S(r = 1)|0\rangle$. As can be seen from the inset, the function reaches zero for t = -1. Similar plots and behavior, i.e., negativity volume approaching zero monotonically for t = -1, are obtained $\forall r > 0$ and either odd m > 1 or even m > 4.

where $\mu = \cosh(r)$ and $\nu = \sinh(r)$, the *t*-PQD of Eqs. (39) and (40) is readily obtained once we have the *t*-PQD of $S(re^{i\phi})|0\rangle\langle 0|S^{\dagger}(re^{i\psi})$. As outlined in Appendix A, we find the characteristic function of this dyadic

$$\phi^{(t)}(\xi) = \operatorname{Tr}S(re^{i\phi})|0\rangle\langle 0|S^{\dagger}(re^{i\psi})D(\xi)e^{\frac{t}{2}|\xi|^2}$$
(42)

to have the following form:

$$\phi^{(t)}(\xi) = \tilde{\mu}^{-\frac{1}{2}} e^{-\frac{1}{2}|\xi\mu - \xi^* v e^{i\phi}|^2 + \frac{\tilde{\nu}}{2\tilde{\mu}} e^{-i\tilde{\phi}} (\xi\mu - \xi^* v e^{i\phi})^2 - \frac{i\Phi}{4} + \frac{t}{2}|\xi|^2}.$$
(43)

Here, $\mu = \cosh(r)$, $\nu = \sinh(r)$, $\tilde{\mu} = \cosh(\tilde{r})$, and $\tilde{\nu} =$ $\sinh(\tilde{r})$. The remaining parameters $\tilde{r}, \tilde{\phi}$, and Φ are defined by Eqs. (A3) and (A4), respectively. A Fourier transform of the characteristic function yields the analytical expression of the *t*-PQD of $S(re^{i\phi})|0\rangle\langle 0|S^{\dagger}(re^{i\psi})$. With this we straightforwardly obtain the *t*-PQD of the initial state, numerically compute its volume of negativity, and find the threshold value \overline{t} for which the *t*-PQD is non-negative $\forall t < \overline{t}$. We once again find strong numerical evidence that the *t*-PQD of $U(\chi =$ $\pi/m S(r) |0\rangle$ becomes non-negative for $s \leq \overline{t} = -1 \forall r > 0$ and either odd m > 1 or even m > 4. Figure 2 displays, with a specific example, the typical features of the negativity volume associated with the input state $U(\chi = \pi/m)S(r) |0\rangle$ t-PQD. The reason for this unusual behavior is that $U^{(m)}S(r)|0\rangle$ with m = 2 or m = 4 are Gaussian states and, as such, their t-PQD is non-negative by definition for every value of the ordering parameter t for which the function is well defined and the negativity volume is strictly zero. In particular, one finds that in these two cases $\overline{t} = e^{-2r}$, i.e., the result one obtains for a squeezed vacuum with squeezing parameter r; hence, the Kerr nonlinearity does not provide any advantage in these scenarios. However, these two "anomalies" vanish if we add displacement to our initial state and thus consider $U(\chi)S(r)|\alpha\rangle$, as we will show for m = 2 shortly. [Note how this choice would also constitute a fairer comparison to the other state we considered, namely, $S(r)U(\chi)|\alpha\rangle$.] First of all, we show that $U^{(2)}S(r)|0\rangle = S(-r)|0\rangle$. This can easily be

seen by expanding the squeezed vacuum on the Fock basis,

$$S(r) |0\rangle = \frac{1}{\sqrt{\cosh r}} \sum_{n=0}^{\infty} [\tanh r]^n \frac{\sqrt{(2n)!}}{2^n n!} |2n\rangle, \qquad (44)$$

and using $U^{(2)} |2n\rangle = (-1)^n |2n\rangle$.

This in turn means that $U^{(2)}S(r)U^{(2)\dagger} = S(-r)$. With this identity we can write

$$U^{(2)}S(r) |\alpha\rangle = U^{(2)}S(r)U^{(2)\dagger}U^{(2)} |\alpha\rangle = S(-r)U^{(2)} |\alpha\rangle,$$
(45)

and we immediately realize that this state is just the squeezed cat state we already discussed in the previous section. Hence, if we add the displacement to the initial state, we once again obtain $\bar{t} = -1$ even for m = 2. We expect the same to happen $\forall m > 1$, given the catlike structure of $U^{(m)}S(r) |\alpha\rangle$.

VI. CONCLUSIONS

In this work we have investigated the possibility of introducing higher-order nonlinearities into the Gaussian boson-sampling framework to enhance the computational complexity of the task and consequently increase the inefficiencies that allow for a classical simulation to be feasible. Using a phase-space formalism based on the negativity of the relevant PQDs, we have established a necessary nonclassicality test that any experimental demonstration of quantum advantage must satisfy. This sufficient condition for an efficient classical simulation for noisy boson sampling is formulated in terms of inequalities that involve the noise parameters characterizing the system. In this paper we have used noise to gauge how inefficient it is to simulate a given bosonsampling task classically. Our results indeed suggest that the addition of single-mode Kerr nonlinearity at the input-state preparation level, while retaining a linear-optical evolution, makes the protocol more robust to noise and relaxes the constraints on the noise parameters required to show quantum advantage. A possible limitation of the formalism we employed is that it only allows us to make predictions about the existence of efficient classical exact simulations. Future efforts might focus on approximate simulation methods of noisy boson-sampling tasks in the presence of nonlinear operations as well as studying the role of thermal effects in a general multimode setting. Another interesting direction for future research is investigating the role of other classes of higher-order nonlinearities, different from single-mode Kerr operations, in increasing the computational complexity of boson-sampling problems.

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APPENDIX A

Here, we outline the techniques employed in the calculation of the characteristic function of $S(re^{i\phi})|0\rangle\langle 0|S^{\dagger}(re^{i\psi})$: . .,

.,

$$\begin{split} \phi^{(t)}(\xi) &= \operatorname{Tr}S(re^{i\phi})|0\rangle\langle 0|S^{\dagger}(re^{i\psi})D(\xi)e^{\frac{i}{2}|\xi|^{2}} \\ &= \langle 0|S^{\dagger}(re^{i\psi})D(\xi)S(re^{i\phi})|0\rangle e^{\frac{i}{2}|\xi|^{2}} \\ &= \langle 0|S^{\dagger}(re^{i\psi})S(re^{i\phi})S^{\dagger}(re^{i\phi})D(\xi)S(re^{i\phi})|0\rangle e^{\frac{i}{2}|\xi|^{2}}. \end{split}$$
(A1)

We can then use $S^{\dagger}(re^{i\phi})D(\xi)S(re^{i\phi}) = D(\xi\mu - \xi^*\nu e^{i\phi}).$

Before moving on, it is useful to show how to compose two single-mode squeezing operations. Let us consider a generic single-mode squeezing operation $S(\xi_i)$ with squeezing parameter $\xi_i = r_i e^{i\phi_i}$, and let us define $\zeta_i \doteq \tanh(r_i) e^{i\phi_i}$. We can then prove [27] the following identity:

$$S(\xi_1)S(\xi_2) = S(\xi_3)e^{i\Phi(\xi_1,\xi_2)(\frac{a^{\prime}a+1/2}{2})},$$
 (A2)

where

$$\zeta_3 = \frac{\zeta_1 + \zeta_2}{1 + \zeta_1^* \zeta_2} \tag{A3}$$

t 1 5 12

and

$$\Phi(\xi_1, \xi_2) = -i \ln\left(\frac{1 + \zeta_1 \zeta_2^*}{1 + \zeta_1^* \zeta_2}\right).$$
 (A4)

Recall that su(1, 1) generators $\{K_+, K_-, K_0\}$ satisfy the commutation rules [28]

$$[K_{-}, K_{+}] = 2K_{0}, \quad [K_{0}, K_{\pm}] = \pm K_{\pm}.$$
 (A5)

The single-mode bosonic representation of this algebra is given by

$$K_{+} = \frac{a^{\dagger 2}}{2}, \quad K_{-} = \frac{a^{2}}{2}, \quad K_{0} = \frac{1}{2} \left(a^{\dagger} a + \frac{1}{2} \right).$$
 (A6)

An easy way to verify the squeezing composition rule (A2) is to use the following matrix representation of su(1, 1):

$$K_{+} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad K_{-} = \begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix},$$
$$K_{0} = \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix}.$$
 (A7)

Using the properties of the su(1, 1) algebra, one can also prove the following well-known decomposition of the single-mode squeezing operator:

$$S(re^{i\phi}) = e^{\frac{\nu e^{i\phi}}{2\mu}a^{\dagger 2}} \mu^{-a^{\dagger}a-1/2} e^{-\frac{\nu e^{-i\phi}}{2\mu}a^{2}}.$$
 (A8)

Hence, using Eq. (A2), we can write

$$S(-re^{i\phi})S(re^{i\psi}) = S(\tilde{r}e^{i\tilde{\phi}})e^{i\Phi(\frac{a^{i}a+1/2}{2})},$$
 (A9)

where $\tilde{r}, \tilde{\phi}$, and Φ are defined by Eqs. (A3) and (A4), respectively. Using Eq. (A8), we then finally obtain the characteristic function of $S(re^{i\phi})|0\rangle\langle 0|S^{\dagger}(re^{i\psi})$ displayed in Eq. (43) of the main text.

APPENDIX B

In order to take thermal effects into account we consider a modification of the loss model described in the main text, where each of the M additional environmental modes are now in a thermal state. It then follows that the action of the lossy LON is now described by the map

$$\mathcal{E}'(|\boldsymbol{\gamma}\rangle\langle\boldsymbol{\gamma}|) = \mathrm{Tr}\mathcal{U}|\boldsymbol{\gamma}\rangle\langle\boldsymbol{\gamma}|\otimes\nu_{\mathrm{th}}^{\otimes M}\mathcal{U}^{\dagger}, \qquad (B1)$$

where \mathcal{U} is, once again, the unitary operator associated with the larger 2*M*-mode interferometer. v_{th} represents a thermal state, i.e.,

$$\nu_{\rm th} = \frac{1}{1+\bar{n}} \left(\frac{\bar{n}}{1+\bar{n}} \right)^{a^{\rm T}a},\tag{B2}$$

where \overline{n} is the mean number of photons and a and a^{\dagger} are the annihilation operator and creation operator of the mode, respectively. We remind the reader that the action of the quantum channel \mathcal{E} on an *M*-mode coherent state is all we need to compute the transition function $T_{\mathcal{E}}^{(s,t)}$ and that the latter is independent of the input states and the final measurements.

In order to make the calculations easier, let us consider the single-mode M = 1 case, i.e., a toy model where the lossy LON is just a beam splitter, characterized by transmittivity $(\cos \theta)^2 = \eta_L$, that couples a coherent state $|\gamma\rangle$ with a thermal state $v_{th}(k)$, and we then trace over the environmental degrees of freedom. Here, k > 1 is the value of the quadrature variances of the thermal state and can also be expressed as $k = 2\overline{n} + 1$, where \overline{n} is the mean number of photons.

First, it is useful to see what happens in the zerotemperature case; that is, we specialize Eq. (11) for a single mode and obtain

$$\mathcal{E}(|\gamma\rangle\langle\gamma|) = |\gamma\cos\theta\rangle\langle\gamma\cos\theta| \equiv |\tilde{\gamma}\rangle\langle\tilde{\gamma}|, \qquad (B3)$$

where we defined $\tilde{\gamma} = \gamma \cos \theta$. Hence, in this scenario, the transfer matrix is simply a real number $L = \cos \theta = \sqrt{\eta_L}$.

Moving onto the finite-temperature case, using the Gaussian formalism, we easily show that

$$\mathcal{E}'(|\gamma\rangle\langle\gamma|) = \operatorname{Tr}_{\mathrm{env}}\{\mathcal{U}(\theta)(|\gamma\rangle\langle\gamma|\otimes\nu_{\mathrm{th}})\mathcal{U}^{\dagger}(\theta)\}$$
$$= D(\tilde{\gamma})\nu_{\mathrm{th}}(\lambda)D^{\dagger}(\tilde{\gamma}), \tag{B4}$$

where $\mathcal{U}(\theta)$ is now the beam-splitter unitary operator, $\lambda =$ $(\cos \theta)^2 + k(\sin \theta)^2$ is a real parameter strictly greater than 1, and the trace is taken over the environmental degrees of freedom. We can then compute

$$\operatorname{Tr}\mathcal{E}'(|\gamma\rangle\langle\gamma|)D(\zeta) = \operatorname{Tr}D(\tilde{\gamma})\nu_{\mathrm{th}}(\lambda)D^{\mathsf{T}}(\tilde{\gamma})D(\zeta)$$
$$= e^{\zeta\tilde{\gamma}^*-\zeta^*\tilde{\gamma}}\operatorname{Tr}\nu_{\mathrm{th}}(\lambda)D(\zeta). \tag{B5}$$

The trace in the last expression is evaluated by exploiting the *P*-function representation of the thermal state, i.e.,

$$\operatorname{Tr}\mathcal{E}'(|\gamma\rangle\langle\gamma|)D(\zeta) = \operatorname{Tr}\int d^{2}\beta P(\beta)|\beta\rangle\langle\beta|D(\zeta)$$
$$= e^{-\frac{\lambda}{2}(\zeta_{1}^{2}+\zeta_{2}^{2})}, \qquad (B6)$$

where

$$P(\beta) = \frac{2}{\pi(\lambda - 1)} e^{-\frac{2}{\lambda - 1}(\beta_1^2 + \beta_2^2)}$$
(B7)

is the *P* function of $v_{\text{th}}(\lambda)$. Now plugging Eq. (B6) into Eq. (6) and using the identity

$$\int d^2\beta e^{\zeta\beta^*-\zeta^*\beta} = \pi^2\delta^{(2)}(\zeta), \tag{B8}$$

we obtain

$$\operatorname{Tr}\mathcal{D}^{\dagger}(\xi)D(\zeta) = \pi \,\delta^{(2)}(\xi - \zeta \cos \theta) e^{\frac{|\zeta|^2}{2}(\cos^2 \theta - \lambda)}.$$
 (B9)

Substituting this last expression into Eq. (5) yields the transition function $T_{\mathcal{E}'}^{(s,t)}$:

$$T_{\mathcal{E}'}^{(s,t)}(\alpha,\beta) = \int \frac{d^2\zeta}{\pi^2} e^{-\frac{|\xi|^2}{2}(t\cos^2\theta - s + \lambda - \cos\theta)} \times e^{\zeta(\alpha^*\cos\theta - \beta^*) - \zeta^*(\alpha\cos\theta - \beta)}.$$
 (B10)

Hence, the function is well behaved and has Gaussian form as long as

$$t(\cos\theta)^2 - s + \lambda - (\cos\theta)^2 \ge 0.$$
 (B11)

On the other hand, inequality (20) for a single mode reads

$$t(\cos\theta)^2 - s + 1 - (\cos\theta)^2 \ge 0.$$
 (B12)

Hence, we have obtained a very similar inequality where thermal effects are entirely accounted for in the parameter $\lambda > 1$. Note that the zero-temperature expression is retrieved for $\lambda = 1$. We can finally use the technique outlined in the main text to compute the noise thresholds that allow for an efficient simulation of the sampling task on a classical machine. In particular, we find

$$\frac{p_D}{\eta_D} \geqslant \eta_L + \frac{1-\lambda}{2}.$$
 (B13)

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If we then express λ in terms of \overline{n} and η_L , we obtain

$$\frac{p_D}{\eta_D} \ge \eta_L - \overline{n}(1 - \eta_L). \tag{B14}$$

The term $\overline{n}(1 - \eta_L)$ represents the correction to the results we presented in main text [Eq. (37)] for the M = 1 case when temperature effects are taken into account. As expected, the additional thermal noise has the effect of *reducing* the noise in the detection, which is sufficient to efficiently simulate the task on a classical machine. We also notice that if

$$\overline{n} \geqslant \frac{\eta_L}{1 - \eta_L},\tag{B15}$$

then the right-hand side of inequality (B14) becomes negative, and the sampling problem becomes classically simulable even with ideal detectors. This is, indeed, expected, as we know that boson sampling with thermal state inputs—or any other classical input state—is efficiently simulable. As a result, we envision a transition in the computational complexity of the problem as the temperature of the environment grows.

APPENDIX C

Here, we provide the proof to obtain the identity (25). We exploit the Baker-Campbell-Hausdorff formula

$$e^{A}Be^{-A} = B + [A, B] + \frac{1}{2!}[A, [A, B]] + \cdots$$
 (C1)

with the following substitutions:

$$A = i\chi a^{\dagger 2}a^2, \qquad B = a. \tag{C2}$$

We then obtain

$$U^{\dagger}(\chi)aU(\chi) = a - 2i\chi(a^{\dagger}a)a + \frac{(-2i\chi)^{2}}{2!}(a^{\dagger}a)^{2}a + \cdots$$
$$= \sum_{n=0}^{\infty} \frac{(-2i\chi a^{\dagger}a)^{n}}{n!}a = e^{-2i\chi a^{\dagger}a}a.$$
(C3)

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