

Graph-theoretic approach to quantum error correctionRobert R. Vandermolen ^{*}*Department of Science and Mathematics, Saint Mary-of-the-Woods College, Saint Mary-of-the-Woods, Indiana 47876, USA*Duncan Wright [†]*Department of Mathematical Sciences, Worcester Polytechnic Institute, Worcester, Massachusetts 01609, USA* (Received 25 October 2021; revised 20 February 2022; accepted 14 March 2022; published 29 March 2022)

We investigate a class of quantum error-correcting codes to correct errors on both qubits and higher-state quantum systems represented as qudits. These codes arise from an original graph-theoretic representation of sets of quantum errors. In this framework, we represent the algebraic conditions for error correction in terms of edge avoidance between graphs providing a visual representation of the interplay between errors and error-correcting codes. Most importantly, this framework supports the development of quantum codes that correct against a predetermined set of errors, in contrast to current methods. A heuristic algorithm is presented, providing steps to develop codes that correct against an arbitrary noisy channel. We benchmark the correction capability of reflexive stabilizer codes for the case of single-qubit errors by comparison to existing stabilizer codes that are widely used. In addition, we present two instances of optimal encodings: an optimal encoding for fully correlated noise, which achieves a higher encoding rate than previously known, and a minimal encoding for single-qudit errors on a four-state system.

DOI: [10.1103/PhysRevA.105.032450](https://doi.org/10.1103/PhysRevA.105.032450)**I. INTRODUCTION**

Error-correcting codes are essential tools in communication theory as they provide the means for the reliable delivery of data over noisy communication channels. In classical computing theory we found that the ability to correct single-bit errors is not only fundamental, but sufficient for most purposes [1]. This classical computing mindset has influenced the current approach to quantum error correction, with the majority of work focusing on the correction of single-qubit flip, phase, and phase-flip errors, characterized by tensors of Pauli-spin operators [2–6].

Among the approaches influenced by classical computing, surface codes have made remarkable achievements, for instance, proving that fault tolerance is theoretically possible to achieve once certain levels of fidelity are reached [7–9]. However, the proof relies on the assumption that the errors to be corrected are uncorrelated across both time and space. Recently, the validity of this assumption has been brought into question by the experimental observation of correlated errors across both time and space [10]. Practically, the assumption of uncorrelated errors can lead to lower rates of error correction and fidelity [11]. For these reasons, the ability to correct correlated errors has become increasingly relevant. Moreover, the wealth of research in engineering a quantum computer has resulted in a wide variety of architectures such as superconducting qubits [12], quantum dots [13], trapped

ions [14], photonics [15], and more [16]. Each systems' qubit architecture comes with an intrinsic error set, incentivizing error correcting codes that are developed to correct a predefined set of errors.

The reflexive stabilizer codes introduced in this paper are not only capable of correcting correlated errors, but the framework allows for the development of codes that correct any given error set. This approach to quantum error correction uses edge avoidance in a special class of graphs to avoid arbitrary error sets, including those correlated across space. Furthermore, these codes are developed for qudits, allowing for implementation when more than two energy levels are measurable, such as the silicon-based quantum dot [17]. All codings will be done into strings of qudits, represented by \mathbb{C}^d , the computational basis of dimension d . It is worth noting that this is not the first application of graph theory in quantum error-correcting codes, see, e.g., [18].

The paper is organized as follows. In Sec. II we recall essential background in quantum error correction, stabilizer codes, and graph theory. Definitions and useful properties are presented for, among others, the Pauli error operators and Cayley graphs. In Sec. III A we give the specific graphs we consider to encode quantum errors. Next, in Sec. IV the reflexive stabilizer codes are introduced alongside their graph representation. To show the initial benefit of these codes, we give a minimal encoding of a single qudit on a four-state system in Sec. VI B. Further, in Sec. VI A we consider fully correlated noise and achieve an optimal encoding by reflexive stabilizer codes, improving on the results of [19]. We present a heuristic algorithm to build a reflexive stabilizer code that corrects a given error set in Sec. V before concluding in Sec. VII.

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II. PRELIMINARIES

We briefly review the relevant terms and notations used throughout this paper. All codewords will be represented as strings (or the superposition of strings) of qudits from the quantum d -ary alphabet \mathbb{C}^d , where $d = p^m$ such that p is prime and m is an integer. Unlike classical computing, we also consider codewords that are the superposition of those strings from the computational basis. Moreover, we set $\omega = \exp(2\pi i/p)$ as the primitive p th root of unity.

As with other stabilizer codes (see, e.g., [6,20]), errors will be labeled with strings from the field \mathbb{F}_d on $d = p^m$ elements. Given a linear subset $C \subseteq \mathbb{F}_d^n$, we denote by C^\perp the orthogonal subspace with respect to the inner product $\langle a, b \rangle = \sum_{i=1}^n a_i b_i$, for a chosen basis $\{e_i\}$ of \mathbb{F}_d^n over \mathbb{F}_d . That is,

$$C^\perp = \{v \in \mathbb{F}_d^n \mid \langle v, a \rangle = 0, \quad \forall a \in C\}. \quad (1)$$

We define the weight of C as the minimum Hamming weight $w(c)$, i.e., the number of nonzero entries, across all the elements $c \in C$,

$$\text{wt}(C) = \min\{w(c) \mid c \in C \setminus \{\bar{0}\}\}, \quad (2)$$

where $\bar{0}$ is the string of all zeros. We similarly denote the string of all ones by $\bar{1}$.

For ease of calculation, we fix a basis for \mathbb{F}_d over \mathbb{F}_p , labeled $\{f_i : i \in \{1, \dots, m\}\}$, and represent elements in terms of this basis as, for example, $a = \sum_{i=1}^m \alpha_i f_i$ and $b = \sum_{i=1}^m \beta_i f_i$. Furthermore, given these representations, we define the inner product $*$ on \mathbb{F}_d by

$$a * b = \sum_{i=1}^m \alpha_i \beta_i. \quad (3)$$

A. Error group

Single qudit errors are defined using the generalized Pauli matrices $X(a)$ and $Z(b)$ for each $a, b \in \mathbb{F}_d$, whose action on $|x\rangle \in \mathbb{C}^d$ is given by

$$X(a)|x\rangle = |x+a\rangle \quad \text{and} \quad Z(b)|x\rangle = \omega^{b*x}|x\rangle, \quad (4)$$

where ω is the primitive p th root of unity. The operators $X(a)$ and $Z(b)$ are referred to as the flip and phase errors, respectively. We will refer to the operator $Y(a) = \omega X(a)Z(a)$ as the phase-flip error. For qubits, i.e., when $p = d = 2$, one quickly notes that the standard Pauli matrices are given by

$$X(0) = Z(0) = \mathbb{1}_2 \quad X = X(1) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad (5a)$$

$$Z = Z(1) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \quad Y = iXZ = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}. \quad (5b)$$

Notice that the inner product $*$, appearing in Eq. (4) and defined in Eq. (3), is in one-to-one correspondence with a trace operator $\text{tr}_* : \mathbb{F}_d \mapsto \mathbb{F}_p$ defined by the basis $\{f_i\}_i^m$. Often in the literature (see, e.g., [6]), a trace operator is used in the definition of the generalized Pauli operators, yet the definition is independent of the choice of trace operator (see again [6]). For this reason, in this paper, we make use of the inner product definition, choosing a notation similar to that in [5].

For errors on an n -qudit system, we concatenate the Pauli operators to define the **error operator**

$$D_{a,b} = X(a_1)Z(b_1) \otimes \dots \otimes X(a_n)Z(b_n), \quad (6)$$

for each $a = (a_1, \dots, a_n), b = (b_1, \dots, b_n) \in \mathbb{F}_d^n$. One will verify that

$$D_{a,b}^{-1} = D_{-a,-b} \quad \text{and} \quad D_{a,b} D_{c,d} = \omega^{-(b,c)} D_{a+c,b+d}. \quad (7)$$

Hence, the collection of n -qudit errors generates the multiplicative **error group**

$$\mathcal{E}_n = \{\omega^\kappa D_{a,b} \mid a, b \in \mathbb{F}_d^n, \kappa \in \{0, \dots, p-1\}\}. \quad (8)$$

We will refer to any nontrivial subset \mathcal{E} of \mathcal{E}_n as an **error set**. We will assume that $\mathbb{1} = D_{\bar{0},\bar{0}}$ is in every error set as one should always protect against no error.

For a more thorough introduction to quantum error correction, see, e.g., [2,3,5,6,20–24]. Next we introduce the basics of quantum stabilizer codes.

B. Stabilizer codes

Briefly, the objective of quantum stabilizer codes is to be able to protect from any error of a commutative subgroup of errors S and correct any error from a larger set of errors $S \subset \mathcal{E} \subset \mathcal{E}_n$. The reader less familiar with stabilizer codes is referred to [2,3,5,20].

Let S be a commutative subgroup of errors containing the center \mathcal{Z} . A **quantum stabilizer code** R is any joint eigenspace of the operators in S . We refer to S as the **stabilizer** of R . In practice, R will be represented by a collection of orthogonal eigenvectors $|\Phi_1\rangle, |\Phi_2\rangle, \dots$, which we refer to as code words. Necessary and sufficient conditions for R to protect from any error in a given error set \mathcal{E} were established in [3,24] and are as follows: for any two distinct code words $|\Phi_1\rangle$ and any two errors $E_1, E_2 \in \mathcal{E}$, we must have

$$\langle \Phi_1 | E_1^{-1} E_2 | \Phi_2 \rangle = 0, \quad (9a)$$

$$\langle \Phi_1 | E_1^{-1} E_2 | \Phi_1 \rangle = \langle \Phi_2 | E_1^{-1} E_2 | \Phi_2 \rangle. \quad (9b)$$

Intuitively, these conditions guarantee that, regardless of the errors that might occur to distinct code words, their perturbed states remain distinguishable by quantum measurement and have equal weight. It is of note that we will always assume $\mathbb{1} \in \mathcal{E}$ as one should always protect from no errors occurring.

Due to its appearance in Eq. (9) and its pervasiveness in the theory, we will refer to $E_1^{-1} E_2$ as a **conjugate error** of \mathcal{E} . Furthermore, we will denote the set of conjugate errors of \mathcal{E} by

$$\mathcal{E}^2 = \{E_1^{-1} E_2 \mid E_1, E_2 \in \mathcal{E}\}. \quad (10)$$

For the error-correction capabilities of stabilizer codes an additional subset of errors is important, namely the **centralizer** of S , which we denote by S^\perp , i.e., the elements of \mathcal{E}_n which commute with all elements of S . The following theorem follows identically to that in [5, Theorem 1] and [6, Theorem 3]. We include it for later reference and ease of the reader.

Theorem II.1. Let S be a commutative subgroup of \mathcal{E}_n which contains the center, i.e., $\mathcal{Z} \subset S$. Further, let $\mathcal{E} \subset \mathcal{E}_n$ be an error set. Then any stabilizer code for S is an error-correcting code which will correct any error from \mathcal{E} if and

only if every conjugate error $E \in \mathcal{E}^2$ satisfies either $E \in S$ or $E \notin S^\perp$.

Commutativity of the error operators is characterized by the relation

$$D_{a,b}D_{c,d} = \omega^{(a,b)\star(c,b)}D_{c,d}D_{a,b}, \tag{11}$$

where

$$(a, b) \star (c, d) = \langle b, c \rangle - \langle a, d \rangle \tag{12}$$

is the symplectic inner product on \mathbb{F}_d^{2n} . Explicitly, two error operators $\omega^k D_{a,b}$ and $\omega^{k'} D_{c,d}$ commute if and only if $(a, b) \star (c, d) = 0$.

One may recognize that these are simply a discrete form of the commutativity relations for the Weyl operators.

C. Graph theory

Graph theory has been used both theoretically and experimentally in quantum error-correcting codes before. For instance, graph state codes have been studied and generated experimentally as a form of measurement-based quantum computation [18]. In this work, we rely on graph theory as well.

The main contribution of the current paper lies in the graph-theoretic representation of quantum stabilizer codes and the associated error sets. Before introducing these specialty graphs in the following section, we must first recall some of the basic terminology of graphs.

A graph $G = (V, E)$ consists of a collection of vertices V connected by a set of edges E . Throughout, we consider only undirected graphs meaning simply that the edges are directionless. Two vertices u and v connected by an edge $e = (u, v)$ are said to be adjacent, and the edge e is said to be incident to both u and v . Whenever $u = v$, the edge (u, u) is referred to as a **loop**; we will also refer to the looped vertex u as a loop. Whenever u and v are distinct, we refer to the edge (u, v) as a **simple** edge. A graph is **complete** whenever each pair of distinct vertices is adjacent.

In what follows, it is convenient to distinguish between the set of loops and the set of simple edges of a graph $G = (V, E)$. To this end, we will decompose the edge set E into two sets: The set of simple, or nonlooped, edges will be denoted by \hat{E} and will be referred to as the **simple edges of G**, and we denote by \mathcal{L}_G the **loop set of G**. When convenient, and without risk of confusion, we will refer to a vertex $a \in \mathcal{L}_G$ as opposed to the more accurate $(a, a) \in \mathcal{L}_G$.

The **component** of a vertex $v \in V$ is the subgraph of G consisting of only those vertices V' that can be reached from v (via consecutive edge-traversals) and those edges incident to the vertices in V' . Lastly, the **complement** of a (simple) graph G is the graph G^\perp on the same vertex set such that two vertices are adjacent in G^\perp if and only if they are not adjacent in G . For a more thorough introduction to graph theory see, e.g., [25].

III. GRAPHS FOR QUANTUM ERROR CORRECTING

Next we develop the specialty graphs that we utilize to assist in and visualize quantum error correction. The novel graph-theoretic representations of both quantum stabilizer

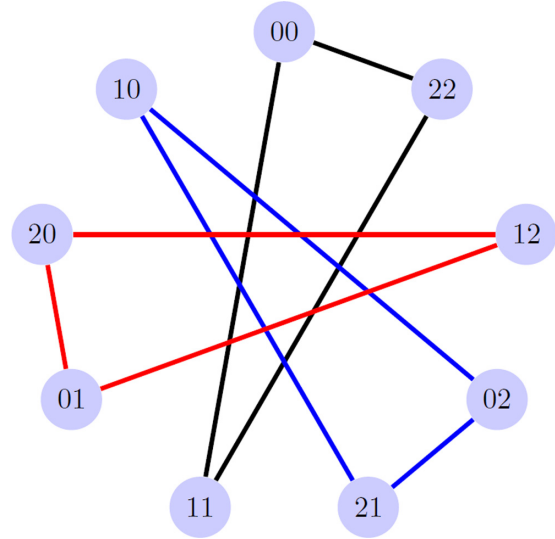


FIG. 1. The LUC graph $G_C = G_C^{(\bar{0})}$ with connecting set given in Example III.1. The connecting set $C = \{00, 11, 22\} \subset V_C = \mathbb{F}_3^2$ (shown in black) is one of exactly three complete components. Since $\mathcal{L}_{\{\bar{0}\}} = \mathbb{F}_3^2$, there are loops at every vertex.

codes and error sets allows one to easily identify the errors that an encoding will correct and, more importantly, an encoding that will correct a predetermined error set. Specifically, we will define an error avoidance graph for an arbitrary error set, as well as linear undirected Cayley graphs.

A. LUC graphs

In this paper, we will use Cayley graphs to represent the encoding of our stabilizer codes. In short, Cayley graphs provide a means to represent a group action as a graph. A Cayley graph $G_C = (V_C, E_C)$ is defined by a subset C of its vertex set known as the **connecting set**. We restrict our attention to Cayley graphs whose connecting set C is a linear subgroup of the additive group $V_C = \mathbb{F}_d^n$. In this case the edge set E_C is the collection of pairs $(a, a + c)$ for $a \in V_C$ and $c \in C$. Note that, since the group identity $\bar{0}$ is necessarily in C , there is a loop at every vertex. We will refer to such a G_C as a **linear undirected Cayley (LUC) graph**.

In what follows we will be interested in subgraphs of LUC graphs obtained by deleting particular loops. Given a linear subset $C_1 \subseteq C$ we set $G_C^{C_1} = (V_C^{C_1}, E_C^{C_1})$ to be the subgraph of G_C with edge set $E_C^{C_1} = \hat{E}_C \cup \mathcal{L}_{C_1}$ where $\mathcal{L}_{C_1} = C_1^\perp$. That is, the only loops remaining from G_C are at the vertices in C_1^\perp . The reason for this convention will become clear in Sec. IV. We will also refer to any graph $G_C^{C_1}$ as a LUC graph. Notice that $G_C^{(\bar{0})} = G_C$. We consider such a LUC graph in the following example. For more on Cayley graphs, in their full generality, see [26].

Example III.1. Consider a three-state quantum system ($d = 3$) of two qudits ($n = 2$) and a connecting set $C = \{00, 11, 22\} \subseteq \mathbb{F}_3^2$. In this case, we have the LUC graph $G_C = G_C^{(\bar{0})}$ with vertex set $V_C = \mathbb{F}_3^2$ and edge set $E_C = \hat{E}_C \cup \mathcal{L}_{\{\bar{0}\}}$ shown in Fig. 1. Note that G_C consists of three complete components and that the component containing 00 contains

exactly those vertices in C . These observations can be generalized and are made formal in the following theorem.

Theorem III.2. Let C be a linear subspace of \mathbb{F}_d^n where $d = p^m$. The LUC graph G_C has exactly $d^{n-\dim(C)}$ number of complete components. Moreover, the component which contains $\bar{0}$ is exactly C .

Proof. Due to the linearity of \mathbb{F}_d^n , it is enough to show the connected component, H , containing $\bar{0}$ is complete and contains exactly the elements from C . It is clear that $\bar{0}$ is connected to exactly those $c \in C$. Moreover, if $b \notin C$, then $b - a \notin C$ for any $a \in C$. Hence the connected component containing $\bar{0}$ contains exactly the elements of C . Lastly, by linearity of C , if $a, b \in C$, then $b - a \in C$ and thus $(a, b) \in \hat{E}_C$. Thus H is complete.

B. Error avoidance graph

Next, we show how to associate a graph to the conjugate errors of an error set. This association allows one to determine an encoding that will correct a predetermined set of errors, in contrast to many current quantum error-correcting codes. Moreover, we will show that such an encoding can be found to be relying only on graph-theoretic principles.

Fix an error set \mathcal{E} acting on a d -state quantum system of n qudits. We denote by $G_{\mathcal{E}} = (V_{\mathcal{E}}, E_{\mathcal{E}})$ the graph with vertices $V_{\mathcal{E}} = \mathbb{F}_d^n$ and edge set

$$E_{\mathcal{E}} = \{(a, b) \mid \omega^k D_{ab} \in \mathcal{E}^2\}. \quad (13)$$

In essence, $E_{\mathcal{E}}$ encodes the conjugate errors \mathcal{E}^2 by effectively connecting codewords that would fail the necessary distinctness conditions given in Eq. (9). (This idea will be made formal in the next section.) For this reason, we refer to $G_{\mathcal{E}}$ as the **error avoidance graph**.

The nontrivial loops indicate the possible strings at which flip and phase errors must occur simultaneously in \mathcal{E}^2 , whereas the trivial loop (at $\bar{0}$) indicates no error occurring.

Example III.3. We consider a system of three qubits with correlated errors from the set

$$\mathcal{E} = \{\mathbb{1}, D_{e_1, e_2}, D_{e_3, e_3}, D_{e_2, e_1}\}. \quad (14)$$

The nonloop edges are given by

$$\hat{E}_{\mathcal{E}} = \{(010, 100), (011, 101)\} \quad (15)$$

and the loop set is given by

$$\mathcal{L}_{\mathcal{E}} = \{000, 110, 001\}. \quad (16)$$

The graph $G_{\mathcal{E}}$ is shown in Fig. 2 with the loop set indicated by dark blue nodes.

IV. REFLEXIVE STABILIZER CODES

In this section, we define a novel class of quantum stabilizer codes which arise from the connecting sets of LUC graphs. It is the interplay between the error avoidance and LUC graphs which allows us to develop our class stabilizer codes with error avoidance at the forefront.

Let C be a linear subspace of \mathbb{F}_d^n and $C_1 \subset C$. The **reflexive stabilizer** of C with respect to C_1 is the subgroup of the error group \mathcal{E}_n generated by

$$S_C^{C_1} = \langle D_{aa}, D_{b0} : a \in C^\perp, b \in C_1 \rangle. \quad (17)$$

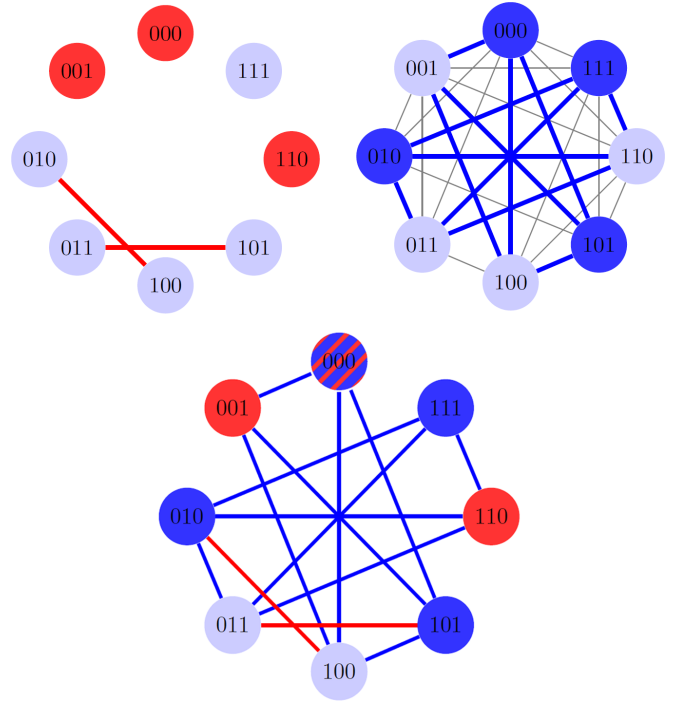


FIG. 2. (Top left) The error avoidance graph $G_{\mathcal{E}}$ for the error set $\mathcal{E} = \{\mathbb{1}, D_{e_1, e_2}, D_{e_3, e_3}, D_{e_2, e_1}\}$. Red nodes indicate loops from $\mathcal{L}_{\mathcal{E}}$. (See Example III.3.) (Top Right) The LUC graph $G_C^{C_1}$ from Example IV.4 with $C = \{000, 100, 001, 101\}$ and $C_1 = \langle 101 \rangle$ shown in blue. Gray edges indicate the unused simple edges obtained from the complement of $G_{\mathcal{E}}$. (Bottom) The two graphs $G_{\mathcal{E}}$ and $G_C^{C_1}$ drawn together. Notice that the only edge in common is the loop at $\bar{0}$, satisfying the condition of Corollary IV.3.

One quickly sees that $S_C^{C_1}$ is commutative as $(a, a) \star (b, b) = 0$ and $(a, a) \star (b, \bar{0}) = 0$ by Eqs. (12) and (1). Therefore a reflexive stabilizer is indeed a quantum stabilizer. The following lemma gives the form of the centralizer of a reflexive stabilizer $S_C^{C_1}$.

Lemma IV.1. Let C be a linear subspace of \mathbb{F}_d^n and $C_1 \subset C$, then the centralizer of $S_C^{C_1}$ is given by

$$(S_C^{C_1})^\perp = \langle D_{ab} \mid a - b \in C, \text{ and } b \in C_1^\perp \rangle. \quad (18)$$

Proof. This follows from Es. (11) and (12) as, for any $x \in C^\perp$, we have $(x, x) \star (a, b) = 0$ exactly when $x(a - b) = 0$. Also, for any $y \in C_1$, we have $(y, 0) \star (a, b) = 0$ only when $yb = 0$.

Recall that a quantum stabilizer code is any joint eigenspace of the operators in its stabilizer. We will denote by $R_C^{C_1}$ the **reflexive stabilizer code** (RSC) with reflexive stabilizer $S_C^{C_1}$. One quickly notes that an RSC $R_C^{C_1}$ will encode $k = \dim(C) - \dim(C_1)$ logical qudits into an n physical qudit system. A constructive form of reflexive stabilizer codes is given in Appendix A.

The following theorem summarizes the errors sets that $R_C^{C_1}$ can correct; it is simply a rewording of Theorem II.1 in terms of the LUC and error avoidance graphs. The details of the proof can be found in Appendix B.

Theorem IV.2. Let $d = p^m$ for some prime p , $C_1 \subset C \subset \mathbb{F}_d^n$ be linear subspaces, and let \mathcal{E} be an error set. If the only edges

common to both $G_{\mathcal{E}}$ and $G_C^{C_1}$ are incident to $\bar{0}$ or a vertex outside C_1^\perp , then the reflexive stabilizer code $R_C^{C_1}$ can correct any error \mathcal{E} . In short, if we have

$$E_C^{C_1} \cap E_{\mathcal{E}} \subseteq \{(a, b) \mid a \notin C_1^\perp \text{ or } a = 0\}. \quad (19)$$

The following corollary is a simplification of Theorem IV.2 which is easier to verify.

Corollary IV.3. Let $d = p^m$, $C_1 \subset C \subset \mathbb{F}_d^n$, and let \mathcal{E} be as in Theorem IV.2. If

$$E_C^{C_1} \cap E_{\mathcal{E}} = \{(\bar{0}, \bar{0})\}, \quad (20)$$

then $R_C^{C_1}$ can correct any single error from \mathcal{E} .

By Corollary IV.3, finding a reflexive stabilizer code capable of correcting an error set \mathcal{E} is as simple as finding a connecting set C such that G_C avoids the edges of $G_{\mathcal{E}}$. This is illustrated in the following example. It is worth noting that this condition, as opposed to that in Theorem IV.2, does not always allow for an encoding of the maximum number of physical qudits.

Example IV.4. Consider the error set $\mathcal{E} = \{\mathbb{1}, D_{e_1, e_2}, D_{e_3, e_3}, D_{e_2, e_1}\}$ on the system of three qubits discussed in Example III.3. We must first choose a connecting set C such that the simple edges \hat{E}_C of G_C avoid those in $G_{\mathcal{E}}$. One possible option is

$$C = \{000, 100, 001, 101\}. \quad (21)$$

Next, we choose a subspace $C_1 \subseteq C$ so that the loop set, \mathcal{L}_{C_1} , of $G_C^{C_1}$ intersects $\mathcal{L}_{\mathcal{E}}$ only at $(\bar{0}, \bar{0})$. Thus Eq. (20) is satisfied and we have that $R_C^{C_1}$ will correct any single error from the given error set \mathcal{E} . (See Fig. 2.)

In Appendix C we benchmark reflexive stabilizer codes against the well-known CSS codes. Specifically, we show that reflexive stabilizer codes have the same single-qubit error correction capabilities as their CSS counterparts. Moreover, we give a one-to-one correspondence between them.

V. HEURISTIC ALGORITHM

In this section we will lay out the concise steps for a heuristic algorithm to build a reflexive stabilizer code which will correct a given error set according to Theorem IV.2. Briefly, the steps are as follows. (S0) Fix an error set \mathcal{E} . (S1) Construct its error avoidance graph $G_{\mathcal{E}}$. (S2) Find a C_0 whose LUC graph G_{C_0} avoids the simple edges of $G_{\mathcal{E}}$. (S3) If possible, extend C_0 to a subspace C and simultaneously choose a subcode $C_1 \subset C$ that together satisfy Eq. (19). Theorem IV.2 then gives confirmation that the code $R_C^{C_1}$ can correct any single error from \mathcal{E} .

Step 0: Start with an error set \mathcal{E}

One major benefit of RSCs is that they provide a means of finding a code that correct against a predetermined error set associated to a noisy channel. This is in contrast to most codes in the literature where one starts with a code and then searches for the errors it corrects. In this paper, we choose error sets that are either convenient for theoretical analysis or are illustrative of the concepts we are developing. However, future works will focus on error sets that appear in physical quantum computers such as those found in [10].

Step 1: Build the error avoidance graph $G_{\mathcal{E}}$

The error avoidance graph $G_{\mathcal{E}}$, as defined in Sec. IV, encodes the conjugate errors produced by a noisy channel as edges. Besides the certain conditions outline earlier, we wish to avoid these edges with the LUC graph of a reflexive stabilizer code.

Step 2: Find a LUC graph G_{C_0} which avoids $\hat{E}_{\mathcal{E}}$

Find a maximal connecting set C_0 whose LUC graph G_{C_0} avoids the simple edges $\hat{E}_{\mathcal{E}}$ of $G_{\mathcal{E}}$. Starting with this LUC graph, one can obtain a lower bound on the rate of error correction by exploring possible subspaces of C_0 that satisfy Eq. (20). However, Theorem IV.2 allows for a weakening of this condition, thereby allowing for a higher rate of error correction. Extending C_0 for this purpose is addressed in the next step. Sometimes it is enough to not extend C_0 , see, e.g., Examples IV.4.

Step 3: Loop avoidance and extensions

We attempt to find a linear extension $C \supset C_0$ and a linear subspace $C_1 \subset C$ such that the conditions of Theorem IV.2 are satisfied. In particular, we need $C_1^\perp \cap \mathcal{L}_{\mathcal{E}} = \{\bar{0}\}$ and $\hat{E}_C \cap \hat{E}_{\mathcal{E}} \subseteq \{(a, b) \mid a \notin C_1^\perp\}$.

Conclusion

Finally, the reflexive stabilizer code $R_C^{C_1}$ can be defined using the C_1 and C from Step 3. Following Theorem IV.2, $R_C^{C_1}$ will correct any single error from the error set \mathcal{E} .

We apply this heuristic algorithm in the following section to obtain two instances of optimal encodings.

VI. OPTIMAL ENCODING

In this section we examine two instances of optimal encodings using reflexive stabilizer codes. The first example is of a channel of qubits inflicted by fully correlated noise. The second example encodes a single qudit on a four state system into four qudits inflicted by single-qudit errors. This code is perfect in the same sense as the PERFECT CODE developed in [27] which embeds a single qubit into a five-qubit system.

A. Fully correlated noise

We now present our first example to illustrate the power of this alternative approach to quantum error correction, and we do so in the case of qubits. This first case we present will be concerned with fully correlated noise, i.e., characterized by the error set $\mathcal{E} = \{\mathbb{1}, D_{\bar{1}, \bar{0}}, D_{\bar{1}, \bar{1}}, D_{\bar{0}, \bar{1}}\}$. For these operators

$$D_{\bar{1}, \bar{0}} = X^{\otimes n}, \quad D_{\bar{1}, \bar{1}} = Y^{\otimes n}, \quad \text{and} \quad D_{\bar{0}, \bar{1}} = Z^{\otimes n} \quad (22)$$

we use the term fully correlated, as whenever a flip, phase, or phase-flip errors occurs, it does so on all qubits simultaneously. In [19] the authors showed that a physical system of $n > 2$ qubits can protect against fully correlated noise with a maximum number $n - 1$ or $n - 2$ logical qubits when n is odd or even, respectively, a result which improved on the a similar encoding from [28]. With the use of the powerful new tool of reflexive stabilizer codes we show that this previously thought upper limit, in the even case, of $n - 2$ logical qubits can be reduced to $n - 1$. One argument for the physical realization of such noise, is that on a most practical qubit chips the distance between qubits is often measured in the micrometers, while a likely candidate for environmental noise such as an electromagnetic wave has a wavelength on the order of millimeters.

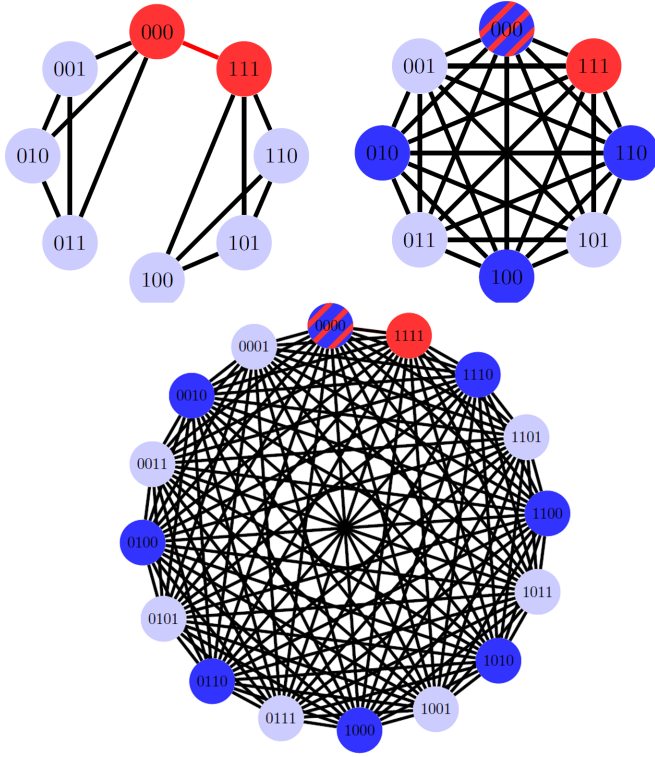


FIG. 3. Illustration of Example VI.1 when $n = 3$. (Top) The error avoidance graph $G_{\mathcal{E}}$ for the fully correlated error is shown in red. Overlaid in blue is the LUC graph of G_{C_0} , where $C_0 = \langle e_1, e_2 \rangle$. The simple edges are disjointed, as specified by Step 2 of the heuristic algorithm. (Bottom) Following Step 3 of the heuristic algorithm, we extend C_0 to the set $C = \mathbb{F}_2^n$ and choose the subset $C_1 = \langle e_n \rangle$. The resulting LUC graph $G_C^{C_0}$ contains edges between all eight distinct pairs of vertices. Moreover, the only common edge is incident to 1111 which lies outside of C_1^\perp , satisfying the condition of Theorem IV.2.

It is this disparity of distances that make it natural to assume that all qubits on the chip are affected by the same error simultaneously.

As our approach shows improvement on a previously thought maximum encoding we take care to give illustrations of the graphs involved for both odd and even n in Fig. 3. To begin by building the avoidance graph for our fully correlated noise, note that the conjugate errors $\mathcal{E}^2 = \mathcal{E}$, and hence the edge set of $G_{\mathcal{E}}$, is independent of n . Importantly, the non-looped edges and the loop set for the fully correlated error set are given by

$$\hat{E}_{\mathcal{E}} = \{(\bar{0}, \bar{1})\} \text{ and } \mathcal{L}_{\mathcal{E}} = \{\bar{1}\}, \quad (23)$$

respectively.

Example VI.1. We consider any integer $n > 2$, and to emphasize the application of the heuristic algorithm, we label the individual steps.

(S0) Fix the fully correlated error set \mathcal{E} (defined above). (S1) We can construct the error avoidance graph $G_{\mathcal{E}}$ by making use of Eq. (23). (We illustrate $G_{\mathcal{E}}$ for $n = 3$ qubits at the top left of Fig. 3.) (S2) Next, our goal is to find a LUC graph which can avoid the simple edges of $G_{\mathcal{E}}$. This can be accomplished with the connecting set $C_0 = \langle e_1, \dots, e_{n-1} \rangle$.

Notice that we must extend C_0 to obtain the maximal encoding of $n - 1$ logical qubits. Indeed this is true regardless of the C_0 chosen in this step, as dimension arguments would then force $C_1 = \{\bar{0}\}$ which violates the condition of Theorem IV.2.

(S3) We extend C_0 by adding the remaining basis vector, i.e., setting $C = \mathbb{F}_2^n$. Simultaneously, we choose $C_1 = \langle e_n \rangle$. Then $\mathcal{L}_{C_1} = C_1^\perp$ is the set of all strings with the n th entry a zero (shown as blue nodes in Fig. 3 for the case $n = 3$) and is, moreover, disjoint from $\mathcal{L}_{\mathcal{E}}$ except at $\bar{0}$. Lastly, the single nonzero endpoint of $\hat{E}_{\mathcal{E}}, \bar{1}$, is not contained in C_1^\perp (shown top right for $n = 3$ and bottom for $n = 4$ in Fig. 3). Thus the desired properties of Theorem IV.2 are satisfied.

We conclude that the reflexive stabilizer code $R_C^{C_1}$ must correct any error from the fully correlated error set \mathcal{E} . Moreover, $R_C^{C_1}$ encodes $n - 1$ logical qubits into the system of n physical qubits, obtaining the maximum regardless if n is odd or even.

The previous example is summarized in the following theorem.

Theorem VI.2. For any $n > 2$, there exists a reflexive stabilizer code $R_C^{C_1}$ encoding $n - 1$ logical qubits into n physical qubits that protects against the fully correlated error set. The RSC is constructed with $C = \mathbb{F}_2^n$ and $C_1 = \langle e_n \rangle$.

In Theorem VI.2 we provide constructive examples of RSCs that protect against fully correlated error which encode the maximum number of logical qubits as there is no way to encode n logical qubits into n physical qubits. By surpassing the previously thought maximum encoding in [19] and a similar result in [28], we see the true power of this graph theoretic approach. Encoding the errors as edges that need to be avoided a simple answer arises for a once complicated situation. Furthermore, by simple inspection of the error avoidance graph we can create a new code with the same encoding rate by setting $C_1 = \langle v \rangle$ for any $v \in \mathbb{F}_2^n$ with the only condition that the weight of v is odd.

B. Perfect code in a four-state system

We now construct a perfect code in a four-state system analogous to the PERFECT CODE for qubits given in [27]. This reflexive stabilizer code achieves the optimal encoding of a single qudit which protects against single-qudit errors.

The basic principal in quantum error correction is the concept that each error transforms distinct code words into distinct orthogonal subspaces. This becomes quite restrictive on the minimal number of physical qudits one can embed into. For now, we present only the minimal length for a specific example, namely the case of a four-state system ($d = 4$). This topic, in its full generality, is the subject of future work.

In analogy to [27], we are interested in protecting against single qudit flip and phase errors. This error set on n qudits is given by

$$\mathcal{E} = \{\mathbb{1}, \alpha D_{e_i, \bar{0}}, \alpha D_{\bar{0}, e_i} \mid 1 \leq i \leq n, 1 \leq \alpha \leq 3\}. \quad (24)$$

In other words, the embedding space requires an orthogonal subspace for each of the three flip and three phase errors on each qudit plus one for the unperturbed state. This makes a total of $6n + 1$ errors to protect against. To encode $k = 1$ logical qudits, we must quadruple this to have enough space to accommodate for each of the $d = 4$ embedded states. Thus,

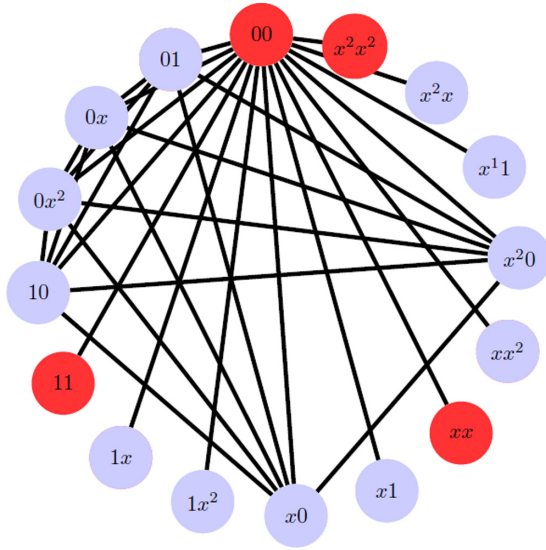


FIG. 4. The error avoidance graph $G_{\mathcal{E}}$ for the set of all single-qudit errors on a four-state quantum system of two qudits. The field of four elements is denoted as $\mathbb{F}_4 = \{0, 1, x, x^2\}$ where $x^2 + x + 1 = 0$. The quantity of edges makes it impossible to find an RSC to correct against all possible errors. [See also Eq. (25).]

we require $4(6n + 1)$ distinct dimensions in our Hilbert space. That is, we have the condition

$$4(6n + 1) \leq 4^n. \tag{25}$$

The smallest number satisfying this equation is $n = 4$, meaning we must have four physical qudits to encode a single logical qudit.

Before proceeding, we summarize the properties of the error avoidance graph for single-qudit errors.

Theorem VI.3. Let \mathcal{E} be the set of single-qudit errors on a d -state quantum system of n qudits. Then $G_{\mathcal{E}}$ has loops at all vertices with exactly one nonzero entry and $\bar{0}$, and has simple edges between $\bar{0}$ and the vertices of weight two and between distinct vertices of weight one:

$$E_{\mathcal{E}} = \{(a, b) \mid w(a) = w(b) = 1 \text{ or } a = \bar{0} \text{ and } w(b) \leq 2\}. \tag{26}$$

By plotting the error avoidance graph for small n , one immediately sees the difficulty of avoiding all single-qudit errors. As an example, we show $G_{\mathcal{E}}$ for $n = 2$ in Fig. 4.

As a consequence of Theorem VI.3, we have the following corollary. The details are expounded in Appendix C.

Corollary VI.4. Let $C_1 \subset C \subset \mathbb{F}_d^n$ be linear subspaces such that $\text{wt}(C) \geq 3$ and $\text{wt}(C_1^\perp) \geq 2$. The reflexive stabilizer code $R_C^{C_1}$ can correct any single-qudit error.

We are now ready to construct our perfect code on a four-state system.

Example VI.5. Let \mathcal{E} be the set of single-qudit errors described above. The PERFECT CODE for a four-state system will embed a single logical qudit into the optimal four physical qudit system, set by Eq. (25). First, set $C \subset \mathbb{F}_4^4$ to be the two-dimensional connection set consisting of the following

vectors:

$$\begin{matrix} 0000, & 1x10, & xx^2x0, & x^21x^20, \\ x^2x^201, & 110x, & xx0x^2, & x111 \\ x^2xxx, & 1x^2x^2x^2, & 10x1, & x0x^2x, \\ x^201x^2, & 0x^21x, & 01xx^2, & 0xx^21. \end{matrix}$$

Note that $\text{wt}(C) = 3$. According to Corollary VI.4, we must find a $C_1 \subset C$ of dimension 1 such that $\text{wt}(C_1^\perp) \geq 2$. The subset $C_1 = \{0000, x111, x^2xxx, 1x^2x^2x^2\}$ satisfies these conditions. Thus $R_C^{C_1}$ can correct any single-qudit error.

VII. DISCUSSION

In this work, we introduced an alternative approach to quantum error correction motivated by graph theory. We developed two graphs (error avoidance graphs and LUC graphs) to visualize error sets and reflexive stabilizer codes, respectively, and reposed the algebraic conditions of error correction in terms of edge avoidance. This approach, summarized as a heuristic algorithm, places the error sets at the forefront by providing a means to construct an encoding that protects against a predetermined noisy channel. This viewpoint is attractive because it allows for the development of codes that protect errors in a variety quantum computer architectures regardless of the intrinsic set of errors present. Furthermore, this viewpoint promotes a collaborative mindset by recognizing that the engineers tasked with developing a quantum computer have limited control over the suppression of errors.

Another benefit to this approach is that it allows for the correction of correlated errors directly and without additional assumptions. For instance, it is common in the literature to presume independence of errors. When applied to a set of correlated errors, this presumption manifests by effectively requiring for correction against a larger error set, which can lead to lower rates of error correction and fidelity [11]. Moreover, recent experimental observations of correlated errors bring into question the validity of this assumption [10]. For these reasons, the ability to correct correlated errors has become increasingly relevant.

Lastly, we argue that RSCs are not only easy to use, but practical as well: We benchmarked the error correction rates for RSCs against the industry-standard CSS codes, showing that RSCs have the same capabilities for single qubit error correction. We developed RSCs in a framework that allows for error correction on multistate quantum system represented as qudits, generalizing the two-state system represented by qubits. The relevance of this framework is supported by recent experiments demonstrating that more than two energy levels are measurable in a system of silicon-based quantum dots [17]. In addition, we present two constructive instances of optimal encodings: a maximal encoding of qubits that corrects fully correlated noise and a perfect code which minimally encodes a single qudit on a four-state system against single-qudit errors. The first example improves on the previously proven “optimal” encoding rate shown in [19], demonstrating even further the ease of use of the graph-theoretic representation.

This introductory work on reflexive stabilizer codes establishes the utility of the graph-theoretic approach employed, and displays a number of practical and theoretical applications. However, with the alternative approach comes a wealth

of unanswered questions and avenues for future research. The connection between quantum error correcting codes and edge avoidance in graphs has opened up a rich vein of future research opportunities. Below we provide a small list of questions to help guide future explorations.

The first set of questions address fundamental existence and uniqueness conditions for error sets and reflexive stabilizer codes. Their wording is designed to make them accessible to researchers in graph theory and quantum information science and to promote collaboration between the same.

Question 1. What necessary and sufficient conditions on a given error set \mathcal{E} or, equivalently, an error avoidance graph $G_{\mathcal{E}}$ guarantee the existence of a RSC $R_C^{C_1}$ or, equivalently, a LUC graph $G_C^{C_1}$ that corrects those errors?

Question 2. Given two error sets \mathcal{E} and \mathcal{E}' or, equivalently, two error avoidance graphs $G_{\mathcal{E}}$ and $G_{\mathcal{E}'}$, what properties guarantee a common RSC to protect against each set?

Question 3. When is it true that two given error sets \mathcal{E} and \mathcal{E}' produce isomorphic error avoidance graphs $G_{\mathcal{E}}$ and $G_{\mathcal{E}'}$?

The last two questions are more specific in scope. First, we look at quantum random walks. This field of study already lies at the intersection of quantum information and algebraic graph theory. Moreover, they were shown to be universal for quantum computation by exploiting perfect or group-state transfer on graphs [29–31]. The last question is an option to incorporate graph theory techniques into the study of quantum error correcting codes, and is related to the works [32,33].

Question 4. What LUC graphs have state transfer with quantum random walks, continuous or discrete [34]?

Question 5. Using limiting properties of graphs or graphons, can one find a Gilbert-Varshamov (GV) bound for reflexive stabilizer codes?

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APPENDIX A: CONSTRUCTING REFLEXIVE STABILIZER CODE

Here we provide a constructive form for reflexive stabilizer codes. To do so, we must construct a joint eigenspace for the stabilizer $S_C^{C_1}$.

First, we examine the eigenspaces of $X(1)Z(1)$ in \mathbb{C}^p , where p is a prime. The eigenvalues for $X(1)Z(1)$ are the p th roots of unity ω^k , where each eigenspace is one dimensional. The eigenvalue ω^k is spanned by the eigenstate

$$|\psi_k\rangle = \frac{1}{\sqrt{d}} \sum_{a \in \mathbb{F}_p} \alpha_a |a\rangle, \quad (\text{A1})$$

where $\alpha_0 = 1, \alpha_{p-1} = \omega^{k+1}$ and, for $1 \leq i \leq p-2, \alpha_i = \omega^{T_i^k}$ for $T_i^k = \frac{i(i-1-2k)}{2}$.

Notice that, for qubits ($d = 2$), the eigenstates for $\pm i$ are exactly the conjugate (Hadamard) basis states

$$|\psi_0\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle), \quad (\text{A2})$$

$$|\psi_1\rangle = \frac{1}{\sqrt{2}}(-|0\rangle + |1\rangle). \quad (\text{A3})$$

For all other $a \in \mathbb{F}_p$, Eq. (11) yields the relation

$$X(a)Z(a) = \omega^{\frac{a(a-1)}{2}} [X(1)Z(1)]^a. \quad (\text{A4})$$

Hence the eigenstates for $X(a)Z(a)$ are exactly those for $X(1)Z(1)$ given in Eq. (A1). We can then extend to $a = \sum_{i=1}^m \alpha_i f_i \in \mathbb{F}_d$, using the alternative definition for the Pauli operators given in [6], to obtain

$$X(a)Z(a) = \omega^{\tau_a} \bigotimes_{i=1}^m [X(1)Z(1)]^{\alpha_i}, \quad (\text{A5})$$

$$\tau_a = \frac{1}{2} \sum_{i=1}^m \alpha_i (\alpha_i - 1). \quad (\text{A6})$$

Equation (A5) is used to extend the states $|\Psi_k\rangle$ in Eq. (A1) to eigenstates for each $a \in \mathbb{F}_d$. By taking tensor products, we extend further to $a \in \mathbb{F}_d^n$ for an arbitrary n -state, d -level quantum system.

Given a LUC $G(C)$ and a linear subspace $C_1 \subset C$ we define the **reflexive quantum stabilizer code** (RSC) of $G(C)$ and C_1 as

$$R_{C_1}^C = \left\{ |\Phi_{c'}\rangle = \frac{1}{\sqrt{|C_1|}} \sum_{c \in C_1} D_{c,\bar{0}} |\Psi_{c'}\rangle \mid c' \in C \right\}, \quad (\text{A7})$$

where $|\Psi\rangle = \bigotimes_{i=1}^n |\psi_{c_i}\rangle$, for $c = (c_1, \dots, c_n)$.

APPENDIX B: LEMMAS FOR ERROR-CORRECTING THEOREM

This section contains the lemmas leading up to Theorem IV.2. We will restate the conditions of Theorem II.1, given again below, in terms of the edges of the LUC and error avoidance graphs. The first lemma gives conditions for a conjugate error to avoid $(S_C^{C_1})^\perp$ of a reflexive stabilizer code $R_C^{C_1}$.

Lemma B.1. Let $d = p^m$ for some prime p , $C_1 \subset C \subset \mathbb{F}_d^n$ be linear subspaces, and \mathcal{E} an error set. The set of nontrivial conjugate errors $E = \omega^k D_{a,b} \in \mathcal{E}^2$ that lie outside of $(S_C^{C_1})^\perp$, i.e., the set $\mathcal{E}^2 \setminus ((S_C^{C_1})^\perp \cup \mathbb{1})$, is characterized by the following graph-theoretic relation on $G_{\mathcal{E}}$ and $G_C^{C_1}$:

$$E_C^{C_1} \cap E_{\mathcal{E}} \subseteq \{(a, b) \mid b \notin C_1^\perp\}. \quad (\text{B1})$$

Proof. Recall the form of $(S_C^{C_1})^\perp$ given in Lemma (IV.1):

$$(S_C^{C_1})^\perp = \langle D_{ab} \mid a - b \in C, \text{ and } b \in C_1^\perp \rangle. \quad (\text{B2})$$

Fix a conjugate error $E = \omega^k D_{a,b} \in \mathcal{E}^2$. First, suppose that $a \neq b$ and therefore $(a, b) \in \hat{E}_{\mathcal{E}}$. Then, by Lemma IV.1, $E \notin (S_C^{C_1})^\perp$ exactly when $b - a \notin C$, i.e., $(a, b) \notin E_C^{C_1}$, or $b \notin C_1^\perp$. Equation (B1) is exactly this condition when restricted to the simple edges.

Next, suppose that $a = b$. Then, since $\bar{0} \in C$, $E \notin (S_C^{C_1})^\perp$ exactly when $b \notin C_1^\perp$. Equation (B1) is exactly this condition when applied to loops.

The next lemma gives conditions for a conjugate error to be in $S_C^{C_1}$ of a reflexive stabilizer code $R_C^{C_1}$.

Lemma B.2. Let $d = p^m$ for some prime p , $C_1 \subset C \subset \mathbb{F}_d^n$ be linear subspaces and \mathcal{E} an error set. The set of conjugate errors $E = \omega^k D_{a,b} \in \mathcal{E}^2$ that lie inside of $S_C^{C_1}$, i.e., the set $\mathcal{E}^2 \cap S_C^{C_1}$, is characterized by the following graph-theoretic relations on $G_\mathcal{E}$ and $G_C^{C_1}$:

$$\hat{E}_C^{C_1} \cap \hat{E}_\mathcal{E} \subseteq \{(a, b) \mid a - b \in C_1\} \quad (\text{B3})$$

and

$$\mathcal{L}_\mathcal{E} \subseteq C^\perp. \quad (\text{B4})$$

Proof. Fix a conjugate error $E = \omega^k D_{a,b} \in \mathcal{E}^2$. First, suppose that $a \neq b$ and therefore $(a, b) \in \hat{E}_\mathcal{E}$. Then, by Eq. (17), $E \in S_C^{C_1}$ exactly when $a - b \in C_1$. Equation (B3) is exactly this condition.

Next, suppose that $a = b$. Then, by Eq. (17), $E \in S_C^{C_1}$ exactly when $a \in C^\perp$. Equation (B4) is exactly this condition.

Taking Lemma B.1 and the fact that $\bar{0} \in C_1$ from Lemma B.1 yields Theorem IV.2. Below is the most general version of Theorem IV.2.

Theorem B.3. Let $d = p^m$ for some prime p , $C_1 \subset C \subset \mathbb{F}_d^n$ be linear subspaces, and $G_C^{C_1}$ be a LUC graph. Then $R_C^{C_1}$ can correct any error from an error set \mathcal{E} , if

$$\hat{E}_C^{C_1} \cap \hat{E}_\mathcal{E} \subseteq \{(a, b) \mid b \notin C_1^\perp \text{ or } a - b \in C_1\} \quad (\text{B5})$$

and

$$\mathcal{L}_\mathcal{E} \cap C_1^\perp \subseteq C^\perp. \quad (\text{B6})$$

APPENDIX C: COMPARISON TO CSS CODES

Reflexive stabilizer codes and CSS codes are in one-to-one correspondence via a change in error basis. That is, choosing a basis for the error group which is instead generated by Y and Z rather than X and Y from Example 5. Specifically, if we define

$$\tilde{D}_{\bar{a}, \bar{b}} = \bigotimes_{i=1}^n Y^{a_i} Z^{b_i}, \quad (\text{C1})$$

a natural isomorphism arises between the two codes. By maintaining the standard basis on \mathbb{F}_2^{2n} , i.e., the parameter space of the error basis, we can build a linear isomorphism

$$\varphi : \mathbb{F}_2^{2n} \rightarrow \mathbb{F}_2^{2n}, \quad (\text{C2})$$

$$(a, a) \mapsto (a, 0), \quad (\text{C3})$$

$$(b, 0) \mapsto (0, b), \quad (\text{C4})$$

which induces an automorphism on \mathcal{E}_n , $\Phi : \mathcal{E}_n \rightarrow \mathcal{E}_n$. It is now a simple exercise to show that the above isomorphism takes the stabilizer for a reflexive stabilizer code $R_C^{C_1}$ (with $d = 2$) to a stabilizer of a CSS code. Further, one easily verifies that $\langle a, b \rangle = 0$ if and only if $\langle \varphi(a), \varphi(b) \rangle = 0$, and thus $R_C^{C_1}$, with stabilizer S , can correct any error from \mathcal{E} if and only if $\Phi(S)$ induces a CSS code which corrects any error from $\Phi(\mathcal{E})$ for any error set \mathcal{E} .

The traditional approaches of error correction for CSS codes is that of considering t single-qubit flip, phase, or phase-flip errors. That is, we consider the error set

$$\mathcal{E} = \{D_{p,0}, D_{0,p}, D_{p,p}\}, \quad (\text{C5})$$

where $p = \sum a_i e_i$ where no more than t of the $a_i = 1$ and rest are zero, i.e., the error set of at most t -flips, t -phases, and t -phase-flips. For this error set we note the following relationship:

$$\Phi(\mathcal{E}) = \mathcal{E}, \quad (\text{C6})$$

and hence the reflexive code obtained as an image of a CSS code under the automorphism Φ^{-1} corrects the same t single-qubit errors. Therefore the next theorem follows directly from the isomorphism in Eq. (C2) and Theorem 1 in [20].

Theorem C.1. Let $C_2 \subset C_1 \subset \mathbb{F}_d^n$ be linear subspaces, then the code $R_{C_1}^{C_2}$ can both correct up to t single-qubit flip, phase, or phase-flip errors where

$$t = \min \left\{ \left\lfloor \frac{\text{wt}(C_1) - 1}{2} \right\rfloor, \left\lfloor \frac{\text{wt}(C_2^\perp \setminus C_1) - 1}{2} \right\rfloor \right\}. \quad (\text{C7})$$

Additionally, by the same relationship we arrive at the following result from Theorem 2 in [5].

Theorem C.2. There exists a family of reflexive stabilizer codes with asymptotic rate

$$R = 1 - 2\delta \log_2(3) - H_2(2\delta), \quad (\text{C8})$$

where δ is the fraction of qubits that are subject to decoherence and $H_2(\delta) = -\delta \log_2(\delta) - (1 - \delta) \log_2(1 - \delta)$ is the binary entropy function.

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