

Witnessing Bell violations through probabilistic negativity

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Bell's theorem shows that no local hidden-variable model can explain the measurement statistics of a quantum system shared between two parties, thus ruling out a classical (local) understanding of nature. In this paper we demonstrate that by relaxing the positivity restriction in the hidden-variable probability distribution it is possible to derive quasiprobabilistic Bell inequalities whose sharp upper bound is written in terms of a negativity witness of said distribution. This provides an analytic solution for the amount of negativity necessary to violate the Clauser-Horne-Shimony-Holt inequality by an arbitrary amount, therefore revealing the amount of negativity required to emulate the quantum statistics in a Bell test.

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I. INTRODUCTION

It has now been 60 years since John Stewart Bell wrote his famous paper on the Einstein-Podolsky-Rosen (EPR) paradox [1], and 50 years since the first experimental Bell test [2]. The majority of physicists are perfectly happy to concede that in the laboratory we see experimental results consistent with the postulates of quantum mechanics. However, the implications of these mathematical postulates on the “reality” of the wave function is still very much up for debate [3–8].

These Bell experiments remain as some of the most important demonstrations for the reality of the quantum state and the death of a “local realism” picture of nature. In such an experiment a physical system is distributed between spatially separated observers and we allow these observers to perform measurements on their local system. The emerging statistics prove that physical systems are not bound to behave locally (in accordance to local hidden-variable models). Rather, the statistics are consistent with the postulates governing quantum mechanics.

In this work we remove the postulates of quantum mechanics and instead allow a physical system to be distributed according to a quasiprobability (hidden-variable) distribution that is allowed to take negative values. Although we are perfectly content with real negative numbers in physics, negative quasiprobabilities (despite receiving support from individuals such as Dirac [9] and Feynman [10] and having a solid mathematical foundation [11,12]) have been a long-debated issue in theoretical physics [13]. See, for example, the extensive discussion surrounding the interpretation of negative values in the Wigner distribution [14,15]. In the majority of considerations, quasiprobability distributions are used to describe states

that are not directly observed; that is, all observable measurement statistics must be governed by ordinary probability distributions. As an example, a Wigner function may assign a negative quasiprobability to a particle having a particular combination of position and momentum, but any physical measurement, constrained by Heisenberg uncertainty, will have an all-positive outcome distribution. This feature ensures that no outcome is ever predicted to be seen occurring a negative number of times [10], and similarly protects the quasiprobability physicist from falling victim to “Dutch book” arguments [16, Chap. 3].

An important motivator for this work is the result of Al-Safi and Short [17], which showed that it is possible to simulate all nonsignalling correlations (those which adhere to the principles of special relativity) [18,19] if one allows negative values in a probability distribution. However, physical reality does not explore this full set of correlations, but rather, is restricted to those achievable by quantum correlations. Therefore the question that we pose in this paper is the following:

“What are the restrictions on the negativity in a hidden-variable probability distribution such that it can emulate the statistics seen in a physical Bell experiment?”

To answer this question we construct Clauser-Horne-Shimony-Holt (CHSH) inequalities for two parties [20] whose degree of violation is witnessed by the amount of negativity present in the hidden-variable probability distribution. Our witness yields a value of 0 for a quasiprobability distribution which is entirely positive, such as that which would describe an ordinary classical system.

To put this result in context, the authors of [17] showed that negativity in the hidden-variable distribution can produce nonlocality. A contribution by the authors of [21] then observed in numerics the correlation that stronger nonlocality requires more negativity. Here we develop this into a precise analytical bound.

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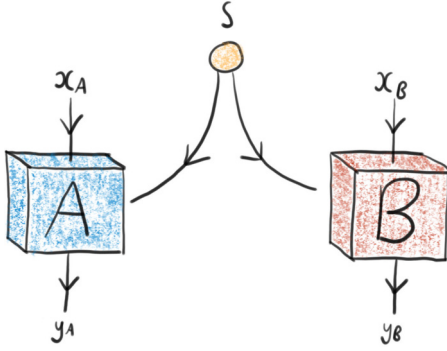


FIG. 1. A source S distributes a system between two spatially separated observers Alice (A) and Bob (B). Alice and Bob choose to measure their local part of the system with measurements x_A, x_B , with possible outcomes $y_A, y_B \in \{-1, +1\}$. The statistics of their measurement outcomes depending upon the physical system being distributed by the source.

II. SETUP

Let us consider the following experimental setup, depicted in Fig. 1. A source S distributes a system between two observers, the k th observer can choose some measurement $x_k \in \{0, 1, \dots, X_k\}$ and record some outcome $y_k \in \{1, 2, \dots, Y_k\}$, the possible values of k being $\{A, B\}$. A specific experimental setup is characterized by the conditional probability

$$P(y_A, y_B | x_A, x_B). \quad (1)$$

The physical theory governing the behavior of the system and experiment determines the achievability of certain conditional probability distributions resulting from these experiments. We are interested in the following three physical theories.

(i) *Classical theory* admits probability distributions (1) of the following form:

$$\sum_{\lambda_A, \lambda_B} P_A(y_A | x_A, \lambda_A) P_B(y_B | x_B, \lambda_B) P_\Lambda(\lambda_A, \lambda_B), \quad (2)$$

where $P_\Lambda(\lambda_A, \lambda_B)$ is a probability distribution defined over local hidden variables. With each choice of hidden variable we associate a local scenario governed by ordinary local probability distributions $P_k(y_k | x_k, \lambda_k)$ for the observables y_A, y_B . The hidden-variable probability distribution P_Λ determines how such local scenarios are mixed, and the probability distributions $P_k(y_k | x_k, \lambda_k)$ are called “ λ_k -local” because they belong to the scenario associated with a particular value of λ_k , not to be confused with the (observable) marginal probability distributions that are obtained by marginalizing the total probability distribution, Eq. (2).

The physical substance of Eq. (2) is worth discussing. λ_A labels all degrees of freedom associated to the signal transmitted from the source to Alice. This is referred to as a hidden variable, as Alice is not able to directly access λ_A . She is limited to observations of measurement outcomes y_A , which depend on both the choice of measurement x_A , and the signal itself, and even when these are both fixed the measurement outcomes may still be random, encapsulated in $P_A(y_A | x_A, \lambda_A)$. Similarly, the source itself may not always prepare the signals

deterministically. This is encoded in the local-hidden-variable distribution $P_\Lambda(\lambda_A, \lambda_B)$.

(ii) *Quantum theory* endows us with a Hilbert space structure for our quantum states that admits probability distributions (1) of the following form:

$$\text{Tr}[(M_{y_A|x_A}^{(A)} \otimes M_{y_B|x_B}^{(B)})\rho], \quad (3)$$

where $\rho \geq 0$ and $M_{y_k|x_k}^{(k)}$ are positive operator-valued measures (POVMs) [22] for each k .

(iii) *Nonsignalling theory*, our third physical theory, prohibits the sending of information faster than the speed of light [18,19]. Such a theory has the conditions on its conditional probability distribution that for any $k \in \{A, B\}$,

$$\sum_{y_k} P(y_A, y_B | x_A, x_B) \quad (4)$$

is independent of x_k . These three physical theories range from the most restrictive (classical), to the least restrictive (nonsignalling), with quantum theory existing somewhere between the two [18].

Representing the full set of correlations that the quantum conditional probability distribution in Eq. (3) allows one to reach is a notorious problem, and the set has recently been shown to be not closed [23]. Therefore we instead restrict ourselves to studying the achievable bounds that these conditional probabilities allow one to reach in nonlocal experiments; the original and most famous of which being the Bell inequality [1].

Definition 1 (Bell inequality). Given observers A and B , each with measurement choice $x_k \in \{0_k, 1_k\}$ with outcomes $y_k \in \{-1, +1\}$, experiments performed on the systems adhere to the bound

$$|E(0_A, 0_B) - E(0_A, 1_B) + E(1_A, 0_B) + E(1_A, 1_B)| \leq X, \quad (5)$$

where both the correlation measure $E(x_A, x_B) = \sum_{y_A, y_B} y_A y_B P(y_A, y_B | x_A, x_B)$ and bound $X \in \mathbb{R}^+$ are theory dependent. The left-hand side of this inequality is often called the score of the experiment.

Each physical theory admits different conditional probability distributions, and hence a different achievable bound X . Classical theory has the CHSH bound $X = 2$ [20], quantum theory has the Tsirelson bound of $X = 2\sqrt{2}$ [24], and nonsignalling distributions $X = 4$ [18]. We are interested in the achievable bounds of a classical system’s probability distribution when the hidden-variable distribution in said probability distribution can be negative.

III. RESULTS

We now define an important object for this work, the *quasiprobability distribution*.

Definition 2 (Quasiprobability distribution). We define a quasiprobability distribution as $\tilde{P}_\Lambda : \Lambda_1 \times \dots \times \Lambda_N \rightarrow \mathbb{R}$ where $\Lambda_i \subset \mathbb{R}$ and $|\Lambda_i| < \infty \forall i$ that is properly normalized such that

$$\sum_{\lambda_1, \dots, \lambda_N} \tilde{P}_\Lambda(\lambda_1, \dots, \lambda_N) = 1. \quad (6)$$

It can be seen that the collection of functions adhering to the above definition forms a convex set, which we will denote

$\tilde{\mathcal{P}}$, a super set of the convex set of positive probability distributions $\mathcal{P} \subset \tilde{\mathcal{P}}$. We must now determine how to quantify the presence of negativity in our quasiprobability distributions. To this end we will use a well-known method for quantitatively detecting properties of a quantum state, witnesses [25–28]. Let us therefore proceed by defining a *negativity witness*.

Definition 3 (Negativity witness). Given some properly normalized probability distribution P , a well-defined *negativity witness* is one which

$$\mathcal{N}(P) = 0 \quad \forall P \in \mathcal{P}. \quad (7)$$

We may additionally require such a witness to “faithfully” detect negativity

$$\mathcal{N}(P) > 0 \quad \forall P \in \tilde{\mathcal{P}} \setminus \mathcal{P}. \quad (8)$$

In the following, we consider classical local hidden-variable models as defined in Eq. (2), but we replace the hidden-variable probability distribution P_Λ with a quasiprobability distribution \tilde{P}_Λ ,

$$\sum_{\lambda_A, \lambda_B} P_A(y_A|x_A, \lambda_A) P_B(y_B|x_B, \lambda_B) \tilde{P}_\Lambda(\lambda_A, \lambda_B). \quad (9)$$

This corresponds to a scenario where different local statistics of observations, governed by λ -local (ordinary) probability distributions $P_k(y_k|x_k, \lambda_k)$, are mixed according to a quasiprobability distribution \tilde{P}_Λ . However, when \tilde{P}_Λ takes negative values, we should no longer think of the model as an ignorance mixture of valid local scenarios, but rather as a nonlocal model [17]. Furthermore, when compared with ordinary hidden-variable models not all combinations of hidden-variable and λ -local probability distributions are valid; only those combinations which lead to well-defined $P(y_A, y_B|x_A, x_B)$ are valid, i.e., comprised of values between 0 and 1 (the normalization condition is always fulfilled). Previous numerical work has focused on negativity arising not from a quasiprobability hidden-variable distribution, but rather from the total (joint) probability distribution while only requiring valid marginal distributions [21]. However, since the total probability distribution governs observable outcome statistics, obtained when Alice and Bob communicate their results with each other, negativity would imply that certain correlations are expected to be seen occurring a negative number of times. In the Appendices we provide an instructive example which exhibits valid marginals but negativity in the total probability distribution. In contrast such situations are excluded in our model.

In addition to the correlation function between two measurements x_A and x_B , $E(x_A, x_B)$, it will also be useful to define λ_k -local expectation values corresponding to an imagined scenario where observer k is able to perform measurement x_k in the local scenario corresponding to λ_k ,

$$\langle k \rangle_{\lambda_k}^{x_k} := \sum_{y_k} y_k P_k(y_k|x_k, \lambda_k). \quad (10)$$

This λ_k -local expectation value will be useful to formulate our results, but does not correspond to the actual observations which are themselves governed by Eq. (9).

We are now in a position to state the main result of this paper, the quasiprobabilistic Bell inequality.

Theorem 1 (Quasiprobabilistic Bell inequality). Given observers A and B , each with measurement choice $x_k \in \{0_k, 1_k\}$ with outcomes $y_k \in \{-1, +1\}$ whose systems are distributed according to some quasiprobability distribution \tilde{P}_Λ , then the quasiprobabilistic Bell inequality holds:

$$\begin{aligned} |E(0_A, 0_B) - E(0_A, 1_B) + E(1_A, 0_B) + E(1_A, 1_B)| \\ \leq 2 + \mathcal{N}(\tilde{P}_\Lambda), \end{aligned} \quad (11)$$

where

$$\mathcal{N}(\tilde{P}_\Lambda) := \begin{cases} \mathcal{N}_+(\tilde{P}_\Lambda) & \text{if } E(1_A, 0_B) + E(1_A, 1_B) < 0, \\ \mathcal{N}_-(\tilde{P}_\Lambda) & \text{else,} \end{cases} \quad (12)$$

is a negativity witness and

$$\begin{aligned} \mathcal{N}_\pm(\tilde{P}_\Lambda) := \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B})] \\ \times (|\tilde{P}_\Lambda(\lambda_A, \lambda_B)| - \tilde{P}_\Lambda(\lambda_A, \lambda_B)). \end{aligned}$$

The proof (see the Appendix) of this theorem begins analogously with Bell’s proof of the CHSH bound [29], but diverges when the assumption $P \in \mathcal{P}$ is made in Bell’s proof. The above result shows that if an arbitrary amount of negativity is allowed in the hidden-variable probability distribution then the upper bound of Eq. (11) can be arbitrarily large. However, it should be noted that a natural limit of 4 in the relevant Bell tests (i.e., for the upper bound in the quasiprobabilistic Bell inequality) is imposed by the requirement that $P(y_A, y_B|x_A, x_B)$ is a well-defined, valid probability distribution [30].

The previous result of Al-Safi and Short [17] showed that it was possible to violate said inequality up to this no-signalling bound of $X = 4$. Therefore, to emulate the physical results seen in Bell tests (Tsirelson bound) one needs a negative probability distribution whose witness equals $\mathcal{N}(\tilde{P}_\Lambda) = 2(\sqrt{2}-1)$. In the following examples section we show that for any $\mathcal{N}(\tilde{P}_\Lambda) \leq 2$, there exist quasiprobabilistic hidden-variable models with valid local measurement statistics that saturate inequality (11). We would hope that if a physical mechanism was discovered that allowed a hidden-variable probability distribution to have the appearance of negativity,¹ one would expect that said physical mechanism was limited in such a way that it resulted in the Tsirelson bound and more generally was able to reconstruct the limits on quantum correlations.

It is also important to note that although said witness $\mathcal{N}(\tilde{P}_\Lambda)$ is a valid witness according to definition 3 it is not necessarily a “faithful” one. However, this can be rectified, at the cost of loosening the bound, by redefining said witness.

For example the function $\mathcal{N}'(\tilde{P}_\Lambda) := \sum_{\lambda_A, \lambda_B} 4(|\tilde{P}_\Lambda(\lambda_A, \lambda_B)| - \tilde{P}_\Lambda(\lambda_A, \lambda_B))$ is defined to be both a valid and “faithful” witness.

There are numerous generalizations of the famous CHSH inequalities, such as multiple parties [32], arbitrary numbers of possible outcomes [33], and so on [34]. These would no doubt be interesting to study, but we leave it to future work to explore these other generalizations and instead focus on the

¹See this recent contribution for a discussion on possible operational interpretations [31].

scenario in which Alice and Bob have access to an arbitrary number of measurement settings [35].

Theorem 2. Given observers A and B , each with $n \geq 2$ measurements $x_k \in \{0_k, 1_k, \dots, n-1_k\}$ with outcomes $y_k \in \{-1, +1\}$ whose systems are distributed according to some quasiprobability distribution \tilde{P}_Λ ,

$$\left| \sum_{i=0}^{n-1} E(i_A, i_B) + \sum_{i=1}^{n-1} E(i_A, i-1_B) - E(0_A, n-1_B) \right| \leq 2n-2 + \mathcal{N}_n(\tilde{P}_\Lambda), \quad (13)$$

where $\mathcal{N}_n(\tilde{P}_\Lambda) = \sum_{i=1}^{n-1} \mathcal{N}^{(i)}(\tilde{P}_\Lambda)$ is a negativity witness with

$$\mathcal{N}^{(x)}(\tilde{P}_\Lambda) := \begin{cases} \mathcal{N}_+^{(x)}(\tilde{P}_\Lambda) & \text{if } E(0_A, x_B) + E(0_A, x-1_B) < 0, \\ \mathcal{N}_-^{(x)}(\tilde{P}_\Lambda) & \text{else,} \end{cases} \quad (14)$$

where

$$\mathcal{N}_\pm^{(x)}(\tilde{P}_\Lambda) := \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{x_A} \langle B \rangle_{\lambda_B}^{x_B} + \langle A \rangle_{\lambda_A}^{x_A} \langle B \rangle_{\lambda_B}^{x-1_B})] \times (|\tilde{P}_\Lambda(\lambda_A, \lambda_B)| - \tilde{P}_\Lambda(\lambda_A, \lambda_B)).$$

The proof of the above theorem can be found in the Appendix, it utilizes proof by induction by chaining together the inequalities from theorem 1. In the next section we show that the bound in theorem 2 can be saturated. Namely, for any $\mathcal{N}_n(\tilde{P}_\Lambda) \leq 2$, there exist well-defined $P(y_A, y_B | x_A, x_B)$, characterized by a quasiprobability hidden-variable distribution $\tilde{P}_\Lambda(\lambda_A, \lambda_B)$ that saturate inequality (13). In addition, analogously to the two measurement result, at the cost of loosening the bound we can ensure that the above witness is also “faithful” by choosing for all x , $\mathcal{N}^{(x)}(\tilde{P}_\Lambda) = \mathcal{N}'(\tilde{P}_\Lambda)$.

Example. To understand how to saturate the Bell inequality from Theorem 1, we rewrite the left-hand side of Eq. (11) as

$$\left| \sum_{\lambda} \mathcal{M}(\lambda) \tilde{P}_\Lambda(\lambda) \right|. \quad (15)$$

$$\begin{aligned} & \frac{4 + \mathcal{N}}{12} \begin{array}{c|cccc} & \text{yAyB} & & & \\ \text{xAxB} & -- & -+ & +- & ++ \\ \hline 00 & 1 & 0 & 0 & 0 \\ 01 & 0 & 1 & 0 & 0 \\ 10 & 1 & 0 & 0 & 0 \\ 11 & 0 & 1 & 0 & 0 \end{array} + \frac{4 + \mathcal{N}}{12} \begin{array}{c|cccc} & \text{yAyB} & & & \\ \text{xAxB} & -- & -+ & +- & ++ \\ \hline 00 & 0 & 0 & 1 & 0 \\ 01 & 0 & 0 & 1 & 0 \\ 10 & 1 & 0 & 0 & 0 \\ 11 & 1 & 0 & 0 & 0 \end{array} \\ & + \frac{4 + \mathcal{N}}{12} \begin{array}{c|cccc} & \text{yAyB} & & & \\ \text{xAxB} & -- & -+ & +- & ++ \\ \hline 00 & 0 & 0 & 0 & 1 \\ 01 & 0 & 0 & 0 & 1 \\ 10 & 0 & 0 & 0 & 1 \\ 11 & 0 & 0 & 0 & 1 \end{array} - \frac{\mathcal{N}}{4} \begin{array}{c|cccc} & \text{yAyB} & & & \\ \text{xAxB} & -- & -+ & +- & ++ \\ \hline 00 & 0 & 0 & 1 & 0 \\ 01 & 0 & 0 & 0 & 1 \\ 10 & 1 & 0 & 0 & 0 \\ 11 & 0 & 1 & 0 & 0 \end{array} \\ & = \frac{1}{12} \begin{array}{c|cccc} & \text{yAyB} & & & \\ \text{xAxB} & -- & -+ & +- & ++ \\ \hline 00 & 4 + \mathcal{N} & 0 & 4 - 2\mathcal{N} & 4 + \mathcal{N} \\ 01 & 0 & 4 + \mathcal{N} & 4 + \mathcal{N} & 4 - 2\mathcal{N} \\ 10 & 8 - \mathcal{N} & 0 & 0 & 4 + \mathcal{N} \\ 11 & 4 + \mathcal{N} & 4 - 2\mathcal{N} & 0 & 4 + \mathcal{N} \end{array}. \quad (17) \end{aligned}$$

Here we have replaced the hidden variables λ_A and λ_B with a single hidden variable λ because our example only uses a single hidden variable λ . Further, $\mathcal{M}(\lambda) := \langle A \rangle_{\lambda}^{0_A} \langle B \rangle_{\lambda}^{0_B} - \langle A \rangle_{\lambda}^{0_A} \langle B \rangle_{\lambda}^{1_B} + \langle A \rangle_{\lambda}^{1_A} \langle B \rangle_{\lambda}^{0_B} + \langle A \rangle_{\lambda}^{1_A} \langle B \rangle_{\lambda}^{1_B}$ are the scores of each of the λ -local distributions, that is, $-2 \leq \mathcal{M}(\lambda) \leq 2$ holds.

For a given value of the negativity witness, we exceed the local bound maximally by the simple strategy of weighting classical distributions with $\mathcal{M}(\lambda) = +2$ with positive quasiprobability, while simultaneously taking a classical distribution with $\mathcal{M}(\lambda) = -2$ with negative weight. To ensure that the total probability distribution $P(y_A, y_B | x_A, x_B)$ is well defined we make a choice of three deterministic classical distributions with positive weight and a fourth with negative weight. Our four deterministic classical distributions can be denoted $[(-, -)_A, (-, +)_B]$, $[(+, -)_A, (-, -)_B]$, $[(+, +)_A, (+, +)_B]$, and $[(+, -)_A, (-, +)_B]$. Here, our notation means that the distributions can be produced by assigning the first pair of symbols to Alice and the second to Bob. Each party chooses to read either the first or second of the symbols given to them (this choice reflects their measurement setting x_k) while the outcome of their measurement is determined by the symbol itself; that is, $y_k = +1$ ($y_k = -1$) for a plus (minus) sign. This experimental description of distributing classical information makes clear that these distributions are local, with our hidden variable λ indicating which of these sets the source that actually produces.

The source produces each of the distributions according to the following quasiprobability distribution:

$$\tilde{P}_\Lambda(\lambda) = \begin{cases} \frac{4+\mathcal{N}}{12} & \text{for } \lambda = 1, 2, 3, \\ -\frac{\mathcal{N}}{4} & \text{for } \lambda = 4, \end{cases} \quad (16)$$

where $\mathcal{M}(\lambda) = 2$ if $\lambda = 1, 2, 3$ and $\mathcal{M}(\lambda) = -2$ if $\lambda = 4$. We can use tables to represent λ -local probability distributions and the total probability distribution is then given as the weighted sum of such tables

The requirement that the resulting total probability distribution must be valid implies $\mathcal{N} \leq 2$ which corresponds to the no-signalling limit. Furthermore, it is easy to check that said distribution indeed gives a value of \mathcal{N} for the negativity witness.

The quasiprobabilistic Bell inequality score for this experiment is $2 + \mathcal{N}$, which upon substituting Eq. (16) into the negativity witness, can be seen to saturate the bound. In the Appendix we discuss how one can generalize the above to the n -measurement scenario.

IV. CONCLUSION

We showed that there exists a relationship between the amount of negativity allowed in a local-hidden-variable distribution and the degree to which said distribution can demonstrate nonlocality in a Bell experiment. In particular, theorem 2 introduces a quasiprobabilistic Bell inequality, which gives us a sharp bound in the scenario of two parties with n inputs (corresponding to a choice between n measurements) and can be used straightforwardly to reconstruct quantum statistics using nothing more than local, separable classical probability distributions and a quasiprobability distribution over them (granted an appropriately well-spent budget of negativity).

The negative quasiprobability is essential precisely because the distribution is over *local* states (local hidden variables). If one allows nonlocal hidden variables then it is possible to describe all quantum computing (including Bell tests) with entirely positive probabilities [36].

Our work sits within the long-established tradition of trying to understand quantum theory through interpretative lenses which remove some particular aspect from a classical world view. Such approaches are wide and varied, including superdeterminism [37,38]; retrocausality [39]; invoking an irreducible role for subjectivity in physics [7,40,41]; taking physical reality to consist of interacting, separate realms [42,43]; allowing the relativity of pre and postselection [44]; taking Hilbert space to be literal [45]; and so on. Here we add to this list in that we present an additional way to recapture the nonlocal features of quantum theory: through having a finite amount of negativity allowed in a hidden-variable distribution over scenarios which are, in themselves, entirely local and classical. We are not claiming that such quasidistributions are “real” only, more modestly, that such a perspective could not be ruled out at this stage. Such a perspective may even provide new ways of looking at open quantum problems, such as determining the source of quantum advantages for computing [46].

Pursuing this line of reasoning, we would hope that our results may help to determine the fundamental restrictions on a system’s quasiprobability hidden-variable distribution such that it captures the full character of physical correlations. Put another way; we know that zero negativity can capture the set of classical correlations, while unbounded negativity can capture the nonsignalling set. Given that the set of quantum correlations lies between these two, what are the restrictions on the quasiprobability hidden-variable distribution which would suffice to identify the full set of quantum correlations? We leave this question for future work.

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APPENDIX A: PROOF OF THEOREM 1

Theorem. Given observers A and B , each with measurement choice $x_k \in \{0_k, 1_k\}$ with outcomes $y_k \in \{-1, +1\}$ whose systems are distributed according to some quasiprobability distribution \tilde{P}_Λ , then the quasiprobabilistic Bell inequality holds:

$$|E(0_A, 0_B) - E(0_A, 1_B) + E(1_A, 0_B) + E(1_A, 1_B)| \leq 2 + \mathcal{N}(\tilde{P}_\Lambda), \quad (\text{A1})$$

where

$$\mathcal{N}(\tilde{P}_\Lambda) := \begin{cases} \mathcal{N}_+(\tilde{P}_\Lambda) & \text{if } E(1_A, 0_B) + E(1_A, 1_B) < 0, \\ \mathcal{N}_-(\tilde{P}_\Lambda) & \text{else,} \end{cases} \quad (\text{A2})$$

is a negativity witness, and

$$\begin{aligned} \mathcal{N}_\pm(\tilde{P}_\Lambda) := & \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B})] \\ & \times (|\tilde{P}_\Lambda(\lambda_A, \lambda_B)| - \tilde{P}_\Lambda(\lambda_A, \lambda_B)). \end{aligned}$$

Proof. The first part of the proof follows Bell’s 1971 derivation of the CHSH inequality [29]. For brevity in the proof we will just write \tilde{P}_Λ as P .

We start by rewriting the correlation function

$$\begin{aligned} E(x_A, x_B) := & \sum_{y_A, y_B} y_A y_B \sum_{\lambda_A, \lambda_B} P_A(y_A | x_A, \lambda_A) \\ & \times P_B(y_B | x_B, \lambda_B) P(\lambda_A, \lambda_B) \\ = & \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{x_A} \langle B \rangle_{\lambda_B}^{x_B} P(\lambda_A, \lambda_B), \end{aligned} \quad (\text{A3})$$

where $\langle k \rangle_{\lambda_k}^{x_k} := \sum_{y_k} y_k P_k(y_k | x_k, \lambda_k)$, is the λ_k -local expectation value for observer k performing measurement x_k . Starting with the following difference between correlation functions:

$$\begin{aligned} & E(0_A, 0_B) - E(0_A, 1_B) \\ = & \sum_{\lambda_A, \lambda_B} (\langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} - \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B) \\ = & \sum_{\lambda_A, \lambda_B} (\langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} - \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{1_B} \pm \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} \\ & \mp \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B) \end{aligned}$$

$$\begin{aligned}
&= \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B) \\
&\quad - \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{1_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B}) P(\lambda_A, \lambda_B), \quad (\text{A4})
\end{aligned}$$

where the “ \pm ” in equation (A4) is to be understood as either “+” in all terms or “−” in all terms. Taking the absolute value of both sides and using the triangular inequality

$$\begin{aligned}
&|E(0_A, 0_B) - E(0_A, 1_B)| \\
&\leq \left| \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B) \right| \\
&\quad + \left| \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{1_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B}) P(\lambda_A, \lambda_B) \right|. \quad (\text{A5})
\end{aligned}$$

Starting with the first term on the right-hand side of inequality (A5), we again apply the triangular inequality

$$\begin{aligned}
&\left| \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B) \right| \\
&\leq \sum_{\lambda_A, \lambda_B} |\langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B)| \\
&= \sum_{\lambda_A, \lambda_B} |\langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B}| |(1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B)|. \quad (\text{A6})
\end{aligned}$$

As $y_k \in \{-1, +1\}$ we can say $|\langle k \rangle_{\lambda_k}^{x_k}| \leq 1 \forall k$, we can write

$$\begin{aligned}
&\left| \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{0_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B) \right| \\
&\leq \sum_{\lambda_A, \lambda_B} |(1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) P(\lambda_A, \lambda_B)| \\
&= \sum_{\lambda_A, \lambda_B} |(1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B})| |P(\lambda_A, \lambda_B)| \\
&= \sum_{\lambda_A, \lambda_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B}) |P(\lambda_A, \lambda_B)|, \quad (\text{A7})
\end{aligned}$$

where we used the fact that $(1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B})$ is necessarily nonnegative because of the choice of eigenvalues $y_k \in \{-1, +1\}$.

Similarly, we find for the second term on the right-hand side of inequality (A5)

$$\begin{aligned}
&\left| \sum_{\lambda_A, \lambda_B} \langle A \rangle_{\lambda_A}^{0_A} \langle B \rangle_{\lambda_B}^{1_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B}) P(\lambda_A, \lambda_B) \right| \\
&\leq \sum_{\lambda_A, \lambda_B} (1 \pm \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B}) |P(\lambda_A, \lambda_B)|. \quad (\text{A8})
\end{aligned}$$

By adding inequalities (A7) and (A8) we find the following upper bound for the left-hand side of inequality (A5)

$$\begin{aligned}
&|E(0_A, 0_B) - E(0_A, 1_B)| \\
&\leq \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B})] |P(\lambda_A, \lambda_B)|. \quad (\text{A9})
\end{aligned}$$

So far the proof followed Bell’s 1971 derivation [29] of the CHSH inequality. In Bell’s derivation, one assumes that the joint probability distribution is positive, $P(\lambda_A, \lambda_B) \geq 0$, which, using the definition of the correlation function and the triangle inequality, leads to the well-known CHSH inequality $|E(0_A, 0_B) - E(0_A, 1_B) + E(1_A, 0_B) + E(1_A, 1_B)| \leq 2$.

We have to take another approach because here $P(\lambda_A, \lambda_B)$ can be a quasiprobability distribution and thus take negative values. For each of the two inequalities (A9) (corresponding to the choice for “ \pm ”), we define a negativity witness $\mathcal{N}_{\pm}(P)$ for some normalized distribution $P \in \tilde{\mathcal{P}}$ as the difference obtained by replacing $|P(\lambda_A, \lambda_B)|$ with $P(\lambda_A, \lambda_B)$ in the right-hand side of inequality (A9)

$$\begin{aligned}
\mathcal{N}_{\pm}(P) &:= \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B})] \\
&\quad \times [|P(\lambda_A, \lambda_B)| - P(\lambda_A, \lambda_B)]. \quad (\text{A10})
\end{aligned}$$

Note that, although this negativity witness is perfectly valid according to the definition in the main text, it is not faithful because $2 \pm (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B})$ may be zero for $P \in \tilde{\mathcal{P}} \setminus \mathcal{P}$, i.e., $\mathcal{N}_{\pm}(P)$ may be zero for a quasiprobability distribution. Nevertheless we can now write inequality (A9) as

$$\begin{aligned}
&|E(0_A, 0_B) - E(0_A, 1_B)| \\
&\leq \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B})] \\
&\quad \times P(\lambda_A, \lambda_B) + \mathcal{N}_{\pm}(P). \quad (\text{A11})
\end{aligned}$$

The first term on the right-hand side of inequality (A11) can then be simplified using the definition of the correlation function (A3) and that $P(\lambda_A, \lambda_B)$ is normalized

$$\begin{aligned}
&\sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B})] P(\lambda_A, \lambda_B) \\
&= \sum_{\lambda_A, \lambda_B} 2P(\lambda_A, \lambda_B) \pm \sum_{\lambda_A, \lambda_B} (\langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{1_B} \\
&\quad + \langle A \rangle_{\lambda_A}^{1_A} \langle B \rangle_{\lambda_B}^{0_B}) P(\lambda_A, \lambda_B) \\
&= 2 \pm [E(1_A, 0_B) + E(1_A, 1_B)]. \quad (\text{A12})
\end{aligned}$$

Thus, inequality (A11) becomes

$$\begin{aligned}
&|E(0_A, 0_B) - E(0_A, 1_B)| \\
&\leq 2 \pm [E(1_A, 0_B) + E(1_A, 1_B)] + \mathcal{N}_{\pm}(P). \quad (\text{A13})
\end{aligned}$$

Now, we choose the inequality corresponding to “+” if $[E(1_A, 0_B) + E(1_A, 1_B)]$ is negative, and the inequality corresponding to “−” else. This allows us to write

$$\begin{aligned}
&|E(0_A, 0_B) - E(0_A, 1_B)| \\
&\leq 2 - |E(1_A, 0_B) + E(1_A, 1_B)| + \mathcal{N}(P), \quad (\text{A14})
\end{aligned}$$

where we defined

$$\mathcal{N}(P) := \begin{cases} \mathcal{N}_+(P) & \text{if } E(1_A, 0_B) + E(1_A, 1_B) < 0, \\ \mathcal{N}_-(P) & \text{else.} \end{cases} \quad (\text{A15})$$

From inequality (A14), we obtain

$$\begin{aligned}
&|E(0_A, 0_B) - E(0_A, 1_B)| \\
&+ |E(1_A, 0_B) + E(1_A, 1_B)| \leq 2 + \mathcal{N}(P), \quad (\text{A16})
\end{aligned}$$

and with one final use of the triangular inequality we find a CHSH-type inequality for arbitrary $P \in \tilde{P}$,

$$\begin{aligned} & |E(0_A, 0_B) - E(0_A, 1_B) + E(1_A, 0_B) + E(1_A, 1_B)| \\ & \leq 2 + \mathcal{N}(P), \end{aligned} \quad (\text{A17})$$

completing the proof.

APPENDIX B: PROOF OF THEOREM 2

Theorem. Given observers A and B , each with $n \geq 2$ measurements $x_k \in \{0_k, 1_k, \dots, n-1_k\}$ with outcomes $y_k \in \{-1, +1\}$ whose systems are distributed according to some quasiprobability distribution \tilde{P}_Λ ,

$$\begin{aligned} & \left| \sum_{i=0}^{n-1} E(i_A, i_B) + \sum_{i=1}^{n-1} E(i_A, i-1_B) - E(0_A, n-1_B) \right| \\ & \leq 2n-2 + \mathcal{N}_n(\tilde{P}_\Lambda), \end{aligned} \quad (\text{B1})$$

$$\left| \sum_{i=0}^k E(i_A, i_B) + \sum_{i=1}^k E(i_A, i-1_B) - E(0_A, k_B) \right| \quad (\text{B3})$$

$$= \left| \sum_{i=0}^{k-1} E(i_A, i_B) + \sum_{i=1}^{k-1} E(i_A, i-1_B) - E(0_A, k_B) + E(k_A, k_B) + E(k_A, k-1_B) \right| \quad (\text{B4})$$

$$= \left| \sum_{i=0}^{k-1} E(i_A, i_B) + \sum_{i=1}^{k-1} E(i_A, i-1_B) - E(0_A, k_B) + E(k_A, k_B) + E(k_A, k-1_B) + E(0_A, k-1_B) - E(0_A, k-1_B) \right| \quad (\text{B5})$$

$$\leq \left| \sum_{i=0}^{k-1} E(i_A, i_B) + \sum_{i=1}^{k-1} E(i_A, i-1_B) - E(0_A, k-1_B) \right| + |E(k_A, k_B) + E(k_A, k-1_B) + E(0_A, k-1_B) - E(0_A, k_B)| \quad (\text{B6})$$

$$\leq 2k-2 + \sum_{i=1}^{k-1} \mathcal{N}^{(i)}(\tilde{P}_\Lambda) + 2 + \mathcal{N}^{(k)}(\tilde{P}_\Lambda) \quad (\text{B7})$$

$$= 2(k+1) - 2 + \mathcal{N}_{k+1}(\tilde{P}_\Lambda), \quad (\text{B8})$$

which concludes the induction. The inequality in line (B6) is the triangle inequality, and we proceed from that line by using the induction hypothesis and theorem 1 for measurements 0_A , k_A for Alice, and $k-1_B$, and k_B for Bob.

APPENDIX C: SATURATION OF THE n -MEASUREMENT QUASIPROBABILISTIC BELL INEQUALITY

We can generalize the two-measurement example from the main text to n measurements in the following way. Using Eq. (A3), we rewrite the left-hand side the n -measurement Bell inequality as

$$\left| \sum_{\lambda} \mathcal{M}(\lambda) \tilde{P}_\Lambda(\lambda) \right|, \quad (\text{C1})$$

where we use only a single hidden variable λ , and

$$\mathcal{M}(\lambda) := \sum_{i=0}^{n-1} \langle A \rangle_{\lambda}^{i_A} \langle A \rangle_{\lambda}^{i_B} + \sum_{i=1}^{n-1} \langle A \rangle_{\lambda}^{i_A} \langle A \rangle_{\lambda}^{i-1_B} - \langle A \rangle_{\lambda}^{0_A} \langle A \rangle_{\lambda}^{n-1_B} \quad (\text{C2})$$

where $\mathcal{N}_n(\tilde{P}_\Lambda) = \sum_{i=1}^{n-1} \mathcal{N}^{(i)}(\tilde{P}_\Lambda)$ is a negativity witness with

$$\begin{aligned} & \mathcal{N}^{(x)}(\tilde{P}_\Lambda) \\ & := \begin{cases} \mathcal{N}_+^{(x)}(\tilde{P}_\Lambda) & \text{if } E(0_A, x_B) + E(0_A, x-1_B) < 0, \\ \mathcal{N}_-^{(x)}(\tilde{P}_\Lambda) & \text{else,} \end{cases} \end{aligned} \quad (\text{B2})$$

where $\mathcal{N}_{\pm}^{(x)}(\tilde{P}_\Lambda) := \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{x_A} \langle B \rangle_{\lambda_B}^{x_B} + \langle A \rangle_{\lambda_A}^{x_A} \langle B \rangle_{\lambda_B}^{x-1_B})] (|\tilde{P}_\Lambda(\lambda_A, \lambda_B)| - \tilde{P}_\Lambda(\lambda_A, \lambda_B))$.

Proof. The proof is similar to the creation of chained CHSH inequalities, see [47] for an intuitive description, and works by induction in n .

Anchor step $n=2$: see Theorem 1.

Inductive step. Suppose that Theorem 2 holds for $n=k$. We will prove the theorem for $n=k+1$. Starting from the left-hand side of equation (B1) for $n=k+1$, we find

are the scores of each of the λ -local distributions, that is $-(2n-2) \leq \mathcal{M}(\lambda) \leq 2n-2$ holds.

We again consider four classical scenarios, three of which achieve a score of $2n-2$ but now the last achieving a score of $2n-6$. The source produces each of the distributions according to the following quasiprobability distribution:

$$\tilde{P}_\Lambda(\lambda) = \begin{cases} \frac{4+\mathcal{N}_n}{12} & \text{for } \lambda = 1, 2, 3, \\ -\frac{\mathcal{N}_n}{4} & \text{for } \lambda = 4, \end{cases} \quad (\text{C3})$$

where $\lambda = 1, 2, 3$ corresponds to classical distributions with score $2n-2$, and $\lambda = 4$ to $2n-6$. We can see that this distribution saturates the n -measurement quasiprobabilistic Bell inequality from theorem 2,

$$\begin{aligned} & (2n-2)\tilde{P}_\Lambda(1) + (2n-2)\tilde{P}_\Lambda(2) + (2n-2)\tilde{P}_\Lambda(3) \\ & + (2n-6)\tilde{P}_\Lambda(4) = 2n-2 + \mathcal{N}_n. \end{aligned} \quad (\text{C4})$$

We now need to come up with the λ -local probability distributions which result in a well-defined $P(y_A, y_B | x_A, x_B)$ and

gives the correct value for the witness \mathcal{N}_n . To do this we can generalize the classical distributions from the main text for

$$\begin{aligned} & \left[\overbrace{(-, \dots, -)}^n_A, \overbrace{(-, \dots, -, +)}^{n-1}_B \right]^{\lambda=1}, \quad \left[\overbrace{(+, -, \dots, -)}^{n-1}_A, \overbrace{(-, \dots, -)}^n_B \right]^{\lambda=2}, \quad \left[\overbrace{(+, \dots, +)}^n_A, \overbrace{(+, \dots, +)}^n_B \right]^{\lambda=3}, \\ & \left[\overbrace{(+, -, \dots, -)}^{n-1}_A, \overbrace{(-, \dots, -, +)}^{n-1}_B \right]^{\lambda=4}. \end{aligned} \quad (C5)$$

It is easy to check that all such distributions achieve for $\lambda = 1, 2, 3$ a score $2n - 2$, and for $\lambda = 4$, $2n - 6$. Since the distribution for $\lambda = 4$ enters into the total probability distribution, $P(y_A, y_B | x_A, x_B)$, with negative weight, the other λ -local distributions (with $\lambda = 1, 2, 3$) must compensate for that negativity to ensure that the total probability distribution is valid.

It is easy to see that this is indeed the case by observing that for each combination of Alice and Bob's signs for $\lambda = 4$ that same combination of symbols appear in the same places for at least one of the other distributions. We also find that requiring positivity of the total probability distribution also gives us the no-signalling condition:

$$\tilde{P}_\Lambda(\lambda) + \tilde{P}_\Lambda(4) \geq 0 \text{ for } \lambda = 1, 2, 3 \Rightarrow \mathcal{N}_n \leq 2 \quad \forall n \geq 2. \quad (C6)$$

The final thing to check is that said distributions in Eq. (C5) coupled with the quasiprobability distribution in Eq. (C3) gives the required value \mathcal{N}_n for the negativity witness $\mathcal{N}_n(\tilde{P}_\Lambda) = \sum_{i=1}^{n-1} \mathcal{N}^{(i)}(\tilde{P}_\Lambda)$ with

$$\begin{aligned} & \mathcal{N}^{(x)}(\tilde{P}_\Lambda) \\ & := \begin{cases} \mathcal{N}_+^{(x)}(\tilde{P}_\Lambda) & \text{if } E(0_A, x_B) + E(0_A, x - 1_B) < 0, \\ \mathcal{N}_-^{(x)}(\tilde{P}_\Lambda) & \text{else,} \end{cases} \end{aligned} \quad (C7)$$

where $\mathcal{N}_\pm^{(x)}(\tilde{P}_\Lambda) := \sum_{\lambda_A, \lambda_B} [2 \pm (\langle A \rangle_{\lambda_A}^{x_A} \langle B \rangle_{\lambda_B}^{x_B} + \langle A \rangle_{\lambda_A}^{x_A} \langle B \rangle_{\lambda_B}^{x-1_B})] (|\tilde{P}_\Lambda(\lambda_A, \lambda_B)| - \tilde{P}_\Lambda(\lambda_A, \lambda_B))$.

n measurements, using the same notation as previously, such classical distributions are,

First, we can see by going through the distributions in Eq. (C5) that for all measurement choices x , $E(0_A, x_B) + E(0_A, x - 1_B) > 0$ meaning that the witness we calculate for all x in the sum of $\mathcal{N}_n(\tilde{P}_\Lambda)$ is $\mathcal{N}_-^{(x)}(\tilde{P}_\Lambda)$. We then go through the expectation values in the definition of $\mathcal{N}_-^{(x)}(\tilde{P}_\Lambda)$ for all x for the $\lambda = 4$ distribution given in Eq. (C5), from which we can see

$$\begin{aligned} & 2 - (\langle A \rangle_4^{x_A} \langle B \rangle_4^{x_B} + \langle A \rangle_4^{x_A} \langle B \rangle_4^{x-1_B}) \\ & = \begin{cases} 0 & \text{for } x = 1, \dots, n-2, \\ 2 & \text{for } x = n-1, \end{cases} \end{aligned} \quad (C8)$$

meaning that upon calculating $\mathcal{N}_n(\tilde{P}_\Lambda) = \sum_{i=1}^{n-1} \mathcal{N}^{(i)}(\tilde{P}_\Lambda)$, we get

$$\begin{aligned} \mathcal{N}_n(\tilde{P}_\Lambda) & = 2(|\tilde{P}_\Lambda(4)| - \tilde{P}_\Lambda(4)) \\ & = \mathcal{N}_n, \end{aligned} \quad (C9)$$

as required.

APPENDIX D: VALID MARGINALS DO NOT IMPLY A VALID TOTAL PROBABILITY DISTRIBUTIONS

In the following, we present an example of a negative total probability distribution that exhibits valid marginal probabilities for all observers. We consider the setting of Theorem 1 in the paper with two observers each having two measurements each with two outcomes. Similarly to the example saturating the bound from Theorem 1, we construct a quasiprobabilistic mixture of four different scenarios each of which can be created locally by the source,

$$\begin{aligned} & \frac{4 + \mathcal{N}}{8} \left(\begin{array}{c|cccc} & x_A x_B & & & \\ \hline & 00 & 01 & 10 & 11 \\ \hline y_A y_B & -- & -+ & +- & ++ \\ \hline & 1 & 0 & 0 & 0 \\ & 1 & 0 & 0 & 0 \\ & 1 & 0 & 0 & 0 \\ & 1 & 0 & 0 & 0 \end{array} \right) + \left(\begin{array}{c|cccc} & x_A x_B & & & \\ \hline & 00 & 01 & 10 & 11 \\ \hline y_A y_B & -- & -+ & +- & ++ \\ \hline & 0 & 0 & 0 & 1 \\ & 0 & 0 & 0 & 1 \\ & 0 & 0 & 0 & 1 \\ & 0 & 0 & 0 & 1 \end{array} \right) - \frac{\mathcal{N}}{8} \left(\begin{array}{c|cccc} & x_A x_B & & & \\ \hline & 00 & 01 & 10 & 11 \\ \hline y_A y_B & -- & -+ & +- & ++ \\ \hline & 0 & 1 & 0 & 0 \\ & 0 & 1 & 0 & 0 \\ & 0 & 1 & 0 & 0 \\ & 0 & 1 & 0 & 0 \end{array} \right) \\ & + \left(\begin{array}{c|cccc} & x_A x_B & & & \\ \hline & 00 & 01 & 10 & 11 \\ \hline y_A y_B & -- & -+ & +- & ++ \\ \hline & 0 & 0 & 1 & 0 \\ & 0 & 0 & 1 & 0 \\ & 0 & 0 & 1 & 0 \\ & 0 & 0 & 1 & 0 \end{array} \right) = \frac{1}{8} \left(\begin{array}{c|cccc} & x_A x_B & & & \\ \hline & 00 & 01 & 10 & 11 \\ \hline y_A y_B & -- & -+ & +- & ++ \\ \hline & 4 + \mathcal{N} & -\mathcal{N} & -\mathcal{N} & 4 + \mathcal{N} \\ & 4 + \mathcal{N} & -\mathcal{N} & -\mathcal{N} & 4 + \mathcal{N} \\ & 4 + \mathcal{N} & -\mathcal{N} & -\mathcal{N} & 4 + \mathcal{N} \\ & 4 + \mathcal{N} & -\mathcal{N} & -\mathcal{N} & 4 + \mathcal{N} \end{array} \right). \end{aligned} \quad (D1)$$

Clearly, each of the tables corresponds to a trivial deterministic strategy where the outcomes are independent from the measurements chosen by Alice or Bob. It can also be seen

that the total probability distribution [the right-hand side of Eq. (D1)] is negative for $\mathcal{N} > 0$. Nevertheless, it is easy to check that the corresponding marginals are valid probability

distributions which predict equiprobable outcomes independent from the measurements chosen by Alice and Bob,

$$p(y_A|x_A) = \sum_{y_B} p(y_A, y_B|x_A, x_B) \quad (\text{D2})$$

$$= \frac{1}{2} \quad \forall y_A, x_A, x_B, \quad (\text{D3})$$

$$p(y_B|x_B) = \sum_{y_A} p(y_A, y_B|x_A, x_B) \quad (\text{D4})$$

$$= \frac{1}{2} \quad \forall y_B, x_A, x_B. \quad (\text{D5})$$

Equation (D1) would correspond to an experiment, where Alice and Bob each find outcomes according to a valid (marginal) distribution. However, as soon as they would communicate their findings with each other, their *joint* outcome statistics would be governed by a negative probability distribution, a contradiction with the laws of probability. A rather extreme scenario which potentially avoids this contradiction could be a setting where communication is fundamentally impossible for the observers, e.g., involving event horizons. In common scenarios, where communication is possible, one must impose that the total probability distribution is valid. We impose this stronger condition throughout.

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