Role of reflections in the generation of a time delay in strong-field ionization

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The problem of time delay in tunneling ionization is revisited. The origin of time delay at the tunnel exit is analyzed, underlining the two faces of the concept of the tunneling time delay: the time delay around the tunnel exit and the asymptotic time delay at a detector. We show that the former time delay, in the sense of a delay in the peak of the wave function, exists as a matter of principle and arises due to the sub-barrier interference of the reflected and transmitted components of the tunneling electronic wave packet. We exemplify this by describing the tunneling ionization of an electron bound by a short-range potential within the strong-field approximation in a "deep tunneling" regime. If sub-barrier reflections are extracted from this wave function, then the time delay of the peak is shown to vanish. Thus, we assert that the disturbance of the tunneling wave packet by the reflection from the surface of the barrier causes a time delay in the neighborhood of the tunnel exit.

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I. INTRODUCTION

In both classical and quantum mechanics, the passage of time is always defined with respect to some dynamical variable (for instance, the hands of a clock). In the absence of a canonical quantum-mechanical time operator, the definition and measurement of time in quantum mechanics are challenging since dynamical observables are inherently non-deterministic. Despite the conceptual difficulties involved, operational techniques with which to measure time have been developed (see, e.g., Refs. [1–9] for overviews).

One of the main applications of these time measurement protocols is the study of the time taken for a particle to tunnel through a barrier, known as tunneling time. Several definitions of the tunneling time exist, such as the Wigner time [10–14], the Büttiker-Landauer time [15], the Pollak-Miller time [16], the Larmor time [17–21], the dwell time [22], etc. [23–27]. Each definition corresponds to a specific aspect of the measurement process and, in general, these do not coincide.

The tunneling phenomenon plays an essential role in the strong-field ionization process of atoms and in the related field of attoscience. State-of-the-art techniques in attosecond science are now able to provide exceptional time and space resolution, reaching tens of attoseconds time and Angström-space resolution. In particular, the attoclock technique provides time resolution of tunneling ionization [28], and has inspired researchers to experimentally address the

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challenging problem of tunneling time [29–33], i.e., how much time, if any, elapses during the quantum tunneling process.

This question strikes at the fundamentals of quantum mechanics but experiments have often been followed by controversial discussion [26,29–67] in the strong-field community arguing either for or against the existence of a tunneling induced time delay between ionized electron wave packet and ionizing laser field.

In this respect we emphasize the distinction between two concepts of the tunneling time in strong-field ionization, namely, the time delay near the tunnel exit (the classically expected coordinate for the tunneled electron to emerge) and the asymptotic time delay [37]. While the latter is relevant to attoclock experiments, the former, known also as the Wigner time delay, can be calculated theoretically and measured in a Gedanken experiment with a so-called virtual detector [68,69]. In both cases, time delay arises due to sub-barrier dynamics.

The asymptotic time delay is derived from the asymptotic photoelectron momentum distribution (PMD). It is defined by the classical backpropagation of the peak of the photoelectron asymptotic wave function up to the tunnel exit [43–46,70,71]. A theoretical description of the experimental asymptotic time delay is challenging because of the entanglement of Coulomb field effects with those of the tunneling delay. In a regime far from over-the-barrier ionization (OTBI), the asymptotic time delay is vanishing [36,37] However, in regimes approaching the OTBI the asymptotic delay is not negligible; it was in fact found to be negative [42–44] and shown to arise due to interference of direct and under-the-barrier recolliding trajectories [52].

In the tunneling region, the tunneling time delay is deduced by following the peak of the electron wave function, the so-called Wigner trajectory. A few de Broglie wavelengths away from the tunnel exit, the electron dynamics are quasiclassical and the classical trajectory is accurately

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described by the eikonal of the wave function in the Wentzel-Kramers-Brillouin (WKB) approximation. However, near the tunnel exit, the WKB approximation fails and a full quantum-mechanical description is given by the Wigner trajectory. Near the tunnel exit this description diverges strongly from the classical one but nevertheless approaches it asymptotically, as one moves toward a detector. The Wigner time delay has been calculated numerically with the virtual detector method in Refs. [33–36], showing positive time delay and nonvanishing longitudinal velocity at the tunnel exit.

In this paper we investigate the Wigner time delay in tunneling ionization, which a virtual detector in a Gedanken experiment would observe. We concern ourselves chiefly with understanding the principles of the tunneling delay, and to this end we consider a simple, time-dependent model of a one-dimensional (1D) atom, with an electron bound by a short-range potential, which is ionized by a half-cycle laser pulse.

At first sight, such abstraction may seem overly simplistic; nonetheless, it takes into account all the necessary features of tunneling ionization. First, ionization occurs mainly in the direction of the electric field so a 1D treatment is appropriate. Likewise, no real laser pulse is a half-cycle sinusoid but by considering one such laser we ensure no continuum electron-to-atomic core recollisions take place, which convolute the physical picture. Such an interpretation is rendered clearer by having analytic expressions, unattainable with a pure Coulomb atomic potential but feasible with a short-range potential.

In this manner, the time-dependent wave function is described within the strong-field approximation (SFA). The components of the wave function which are reflected by the tunneling barrier are identified by analyzing the saddle points of the time integral of the wave function. We show that the interference of reflected and transmitted components of the wave function generates the Wigner time delay, while the same delay vanishes when the reflected components are neglected. Additionally, the scalings with respect to the laser field strength of the Wigner time delay and group velocity at the tunnel exit are derived and interpreted.

We work well below the OTBI regime, in what we term the *deep tunneling* regime. While in this regime the asymptotic tunneling time delay is vanishing we show that the Wigner time at the tunnel exit (calculated in the first-order SFA) is not only nonzero, but sizable, as already noted in Ref. [37]. This is in contrast to the asymptotic time delay, where the first-order SFA result is vanishing and the second-order SFA is required to obtain a nonvanishing asymptotic time delay (attributable to sub-barrier recollisions and interference of paths).

The structure of the paper is as follows: in Sec. II we introduce the basic ionization model, calculate the SFA time-dependent wave function, and construct the Wigner trajectory from the latter. To elucidate our method of analyzing the contribution of reflections to the wave function, in Sec. III we consider a simpler, analytic, model of ionization: an electron in a constant electric field. The analyticity of this model allows us to relate the reflected components of the wave function to the contribution of the specific saddle points of the integral representation of the wave function. We apply this concept to the SFA wave function in Sec. IV, whereby we show that

neglecting reflections results in a zero Wigner time delay. Lastly, in Sec. V, we summarize and interpret our results and discuss the implications of these on the interpretation of attosecond streaking experiments. For the reader unacquainted with strong-field physics, the Wigner time delay for scattering by a square potential barrier was previously analyzed in Refs. [7,72], where the significance of reflections to the time delay was alluded to. In Appendix A this problem is revisited and the role of reflections is explicitly presented. Atomic units (a.u.) are used exclusively throughout this paper.

II. TIME DELAY IN STRONG-FIELD IONIZATION

The Wigner time, developed for scattering problems [10,11,13], considers the time taken for the peak of the wave packet to travel a given distance. For tunneling through a time-independent barrier, the Wigner time can be derived via the energy derivative of the phase of the tunneling wave function ψ :

$$\tau_W(x) = -i \frac{\partial}{\partial \mathcal{E}} \ln \frac{\psi(x)}{|\psi(x)|}.$$
 (1)

The peak of the ionized wave packet leads to the asymptotic formation of a well-defined peak in the attoclock PMD, which is subsequently measured and interpreted.

As the peak of the wave packet follows the trajectory $\tau_W(x)$, the Wigner group delay velocity of the wave packet can be defined:

$$v_W(x) = \left(\frac{\partial \tau_W(x)}{\partial x}\right)^{-1}.$$
 (2)

When a monochromatic wave is incident on a finite potential barrier, the propagation inside the barrier is a superposition of an exponentially suppressed wave (transmission) with a growing exponential wave, namely, the reflection by the surface of the barrier (see, e.g., Appendix A). The goal of this paper is to establish the causal effect of wave-function refections inside the barrier on the time delay in strong-field ionization.

In order to do this, we calculate the time-dependent ionized electron wave function at the position where the electron appears in the continuum, thereby allowing us to deduce the peak of the wave packet with respect to time. The Wigner time delay can be calculated as the energy derivative of the phase of the wave function via Eq. (1) in a static field but in a time-dependent laser field this prescription fails as energy is not conserved. Correspondingly, we derive the Wigner time delay at the tunnel exit explicitly as the delay of the peak of the wave packet, rather than from the energy derivative of the phase of the wave function.

A. The model

Consider an electron initially bound in a 1D short-range potential:

$$V(x) = -\kappa \,\delta(x) \tag{3}$$

with a binding energy $I_p = \kappa^2/2$, and with a corresponding ground-state wave function $\psi_0(x,t) = \sqrt{\kappa} \exp(-\kappa |x| + iI_p t)$.

We describe the generation of the peak of the ionized wave packet due to tunneling ionization near the tunnel exit. For this reason, we wish to avoid recollisions in the continuum and so a half-cycle laser field is employed in our model. The laser electric field,

$$E(t) = -E_0 \cos^2(\omega t), \tag{4}$$

is switched on at $\omega t_0 = -\pi/2$. In a half-cycle laser field the ionization happens mostly near the peak of the field. Here, nonadiabatic effects are governed by the second derivative of the field at the peak $E''(0)/E(0) = 2\omega^2 \equiv \omega_{\rm eff}^2$, where we define the effective frequency $\omega_{\rm eff} = \sqrt{2}\omega$.

We consider the tunnel ionization regime and keep constant the Keldysh parameter [73]:

$$\gamma = \sqrt{\frac{I_p}{2U_p}} \ll 1,\tag{5}$$

where $U_p = E_0^2/(4 \omega_{\rm eff}^2)$ is the ponderomotive potential. Thus, when varying the field strength E_0 , we vary the frequency $\omega = \gamma E_0/(\sqrt{2}\kappa)$ accordingly.

Moreover, we consider the so-called deep tunneling regime, wherein $E_0 \ll E_{\rm th}$, and $E_{\rm th}$ is the threshold field of OTBI. This threshold can be estimated as the field strength where the coordinate-saddle point of the SFA-matrix element, i.e., the starting point $x_s \approx \sqrt{\kappa/E_0}$ of the quantum orbit, becomes comparable to the tunnel exit x_e , which for the shortrange potential corresponds to the condition $E_{\rm th} \approx \kappa^3/4$ [74].

The superposition of the laser field with the atomic potential creates a potential barrier, through which an electron can tunnel, with a characteristic classical tunnel exit $x_e = I_p/E_0 = 10$ a.u. [75]. While this is a rudimentary estimate, it is in agreement with a tunnel exit derived quantum mechanically in our parameter regime as shown in Sec. IV B.

B. Time evolution of the wave function

Our investigation is based on the SFA wave function describing the electron dynamics in tunneling ionization. We define the Wigner trajectory and tunneling time delay employing the virtual detector approach [34,35,68,69] based on the SFA wave function. The ionization dynamics are described by the Schrödinger equation

$$i\frac{\partial}{\partial t}\Psi(x,t) = (H_0 + H_i)\Psi(x,t),\tag{6}$$

with the atomic Hamiltonian

$$H_0 = -\frac{1}{2} \frac{\partial^2}{\partial x^2} + V(x),\tag{7}$$

and the interaction Hamiltonian with the laser field

$$H_i = xE(t). (8)$$

The standard SFA is employed for the solution of the Schrödinger equation. In the interaction picture with Hamiltonian $H = H_0 + H_i$, the time-evolution operator $U(t, t_0)$ satisfies the Dyson integral equations [76]

$$U(t,t_0) = U_0(t,t_0) - i \int_{t_0}^t dt' \, U(t,t') H_i(t') U_0(t',t_0), \quad (9)$$

where U_0 is the evolution operator corresponding to the Hamiltonian H_0 . A perturbation series can be constructed by

replacing the full evolution operator $U(t, t_0)$ in the Dyson integral with the evolution operator corresponding to the Hamiltonian H_i , namely,

$$U_f(t,t') = \int dp |\Psi_p(t)\rangle \langle \Psi_p(t')|, \qquad (10)$$

where $|\Psi_p\rangle$ are the Volkov states [77]. Each order in the perturbation theory corresponds to a sub-barrier recollision in our half-cycle laser field. As each sub-barrier recollision implies a longer tunneling path, each term in this series is suppressed by the Keldysh exponent $\exp(-2\kappa^3/3E_0)$ and so, in contrast to the near OTBI regime, in the deep tunneling regime a first-order expansion in the SFA suffices (i.e., neglecting sub-barrier recollisions) [52].

Consequently, the electron state during the interaction takes the form $|\psi(t)\rangle = |\psi_0(t)\rangle + |\psi_i(t)\rangle$ where $|\psi_0(t)\rangle$ is the eigenstate of the atomic Hamiltonian H_0 and

$$|\psi_i(t)\rangle = -i \int_{-\infty}^{\infty} dp \int_{t_0}^{t} dt' |\Psi_p(t)\rangle \langle \Psi_p(t')| H_i(t') |\psi_0(t')\rangle$$
(11)

describes the electron dynamics induced by the laser field, which generates the Wigner trajectory. It is the dominant part of the wave function at distances far from the core, and therefore, we concentrate on the analysis of its behavior. Denoting the electronic kinetic momentum as

$$\mathcal{P}(t) \equiv p + A(t),\tag{12}$$

with the laser vector potential $A(t) = -\int_{-t_0}^{t} E(t') dt'$, the 1D Volkov state in the length gauge is

$$|\Psi_p(t)\rangle = |\mathcal{P}(t)\rangle e^{-iS(t)}$$
 (13)

with a plane-wave component $\langle x | p \rangle = (2\pi)^{-\frac{1}{2}} \exp(i p x)$ and the Volkov phase

$$S(t) = \frac{1}{2} \int_{-\tau}^{t} d\tau \, \mathcal{P}(\tau)^{2}. \tag{14}$$

We can expand the overlap in (11) using a resolution of identity in a dummy variable x':

$$\langle \Psi_{p}(t')|H_{i}(t')|\psi_{0}(t')\rangle = \frac{e^{i(I_{p}t'-S(t'))}}{\sqrt{2\pi}}E(t')\int_{-\infty}^{\infty}dx'\,e^{i\mathcal{P}(t')x'-\kappa|x'|}x'. \quad (15)$$

While this integral is soluble, we do not evaluate it but rather first integrate (11) with respect to p and then x'. With the notation $\Delta f_n(t,t') = f_n(t) - f_n(t')$, and defining the integrals $f_n(t) = \int_0^t dt' A(t')^n$, we may perform the initial integral over

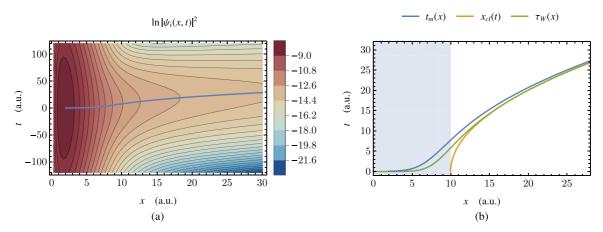


FIG. 1. (a) Ionization amplitude $|\psi_i(x,t)|^2$ as defined in Eq. (17). At every cross section in x, the temporal peak of the wave function was determined (plotted in blue) which can be interpreted as the trajectory of the peak. (b) Comparison of trajectories in the region near the tunnel exit, x_e . The displayed curves are the peak trajectory [blue, given by the maximum of $|\psi_i(x,t)|^2$], the classical trajectory (orange, given by the Newton equation starting at the tunnel exit), and the Wigner trajectory [green, given by Eq. (25)]. Under the barrier (x < 10, shaded blue), there is an increasing delay of the peak with respect to the laser peak. Outside the barrier, the peak trajectory rapidly converges with the classical and Wigner electron trajectory. Near the atomic core (x < 2), the bound state, $|\psi_0(x)| \gg |\psi_i(x)|$, dominates the full wave function $|\psi(x)| = |\psi_0(x)| + |\psi_i(x)|$ so the meaning of a trajectory for ionization is lost.

p which is a simple Gaussian integral. The resulting expression

$$\psi_{i}(x,t) = \int_{t_{0}}^{t} dt' \int_{-\infty}^{\infty} dx' \frac{x'\sqrt{\kappa} E(t')}{\sqrt{2\pi i(t-t')}} \exp\left[i\left(I_{p}t' + i\kappa|x'| + x[A(t) - A(t')] + \frac{i[(x-x') - \Delta f_{1}(t,t')]^{2}}{2(t-t')} - \frac{\Delta f_{2}(t,t')}{2}\right)\right]$$
(16)

may then be finally integrated in x' to yield

$$\psi_{i}(x,t) = \int_{t_{0}}^{t} dt' \sqrt{\kappa} E(t') \left(\frac{z_{-}^{2}[1 + \operatorname{erf}(z_{-})]e^{-z_{+}^{2}}}{z - \kappa} + \frac{z_{+}^{2}[1 - \operatorname{erf}(z_{+})]e^{-z_{-}^{2}}}{z + \kappa} \right) \exp(i\zeta) \equiv \int_{t_{0}}^{t} dt' \exp[i \Phi(x, t, t')]$$
(17)

where we have defined $z_{\pm} = \sqrt{\frac{i}{2}(t-t')}(z\pm\kappa)$ for

$$z = -i\left(A(t') + \frac{x - \Delta f_1(t, t')}{t - t'}\right)$$
 (18)

and where

$$\zeta = I_p t' + x A(t) + \tag{19}$$

$$(t - t') \left(\frac{[x - \Delta f_1(t, t')]^2}{2(t - t')^2} + \kappa^2 + z^2 \right) - \frac{\Delta f_2(t, t')}{2}. \quad (20)$$

Our aim is to calculate the wave function and Wigner time delay in the interaction region around the tunnel exit by studying the phase Φ . Thus, in deviation to standard SFA studies, the time integral is calculated up to the finite observation time t, meaning the integration must be performed numerically. The usual saddle-point integration method is valid only for sufficiently large values of t, placing one well outside the tunneling region.

C. Analysis

For the numerical integration of the SFA wave function Eq. (17) an electric-field strength $E_0=0.05$ a.u. and Keldysh parameter $\gamma=\sqrt{2}/10\approx0.14$ were chosen to ensure deep

tunneling is considered. With these parameters, our half-cycle laser pulse spans [-314, 314] a.u. We present results for the case of hydrogen, for which $I_p = \kappa^2/2 = 1/2$ a.u., implying an OTBI threshold field $E_{\rm th} \approx 0.25$ a.u. The time integration was carried out with the standard numerical integration routine of MATHEMATICA 12 to a precision of 30 digits.

We build the Wigner trajectory from the partial wave function ψ_i , which in the SFA describes the electronic dynamics induced by the laser field during the tunneling ionization process. From this laser driven perturbation ψ_i , in regions further from the atomic core, the outgoing ionized wave emerges. Note, however, that in the interaction region close to the atomic core, the laser driven bound and free parts are inseparable. The space-time probability distribution, $|\psi_i(x,t)|^2$, is presented in Fig. 1. From this distribution the Wigner trajectory is derived as follows: the probability time distribution at each space point x is invoked [see Fig. 2(a) for the case of the tunnel exit coordinate $x = x_e$] and the maximum $t_m(x)$ of this distribution is derived. The Wigner trajectory is represented by the function $t_m(x)$, which runs along all maximum points of the space-time distribution.

We underline that the wave function ψ_i vanishes after the laser field is switched off. Thus, ψ_i does not include the possible net excitations of the atomic states due to interaction with the laser field. This is a feature of the SFA, where the

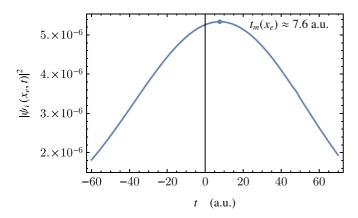


FIG. 2. Probability distribution $|\psi_i(x_e, t)|^2$ vs time at the classical tunnel exit $x_e = I_p/E_0$. This distribution is peaked at a greater time, $t_m \approx 7.6$ a.u. ≈ 183 as, marked by the dot, than the peak of the laser pulse.

exact time-evolution operator in the final state is replaced by the Volkov propagator, representing the continuum electron in the laser field.

We note the maximum of the wave function displays a time delay with respect to the peak of the field. The tunneling time delay under the barrier (x < 10) increases when moving towards the tunnel exit. Outside the barrier, this trajectory rapidly approaches the classical electron trajectory (beginning at the classical tunnel exit with zero momentum). The slight deviation is due to quantum-mechanical corrections to the quasiclassical wave function not far from the tunnel exit.

The main idea advocated in this paper is that the Wigner time delay during tunneling is closely related to reflections arising during tunneling dynamics. It is straightforward in the simple case of tunneling through a box potential to show that reflections are responsible for the tunneling time delay, as is done in Appendix A. However, unlike in the separable box potential case, a given wave function is not easily deconstructible as a simple superposition of reflected and transmitted components corresponding to simple decaying or growing exponentials. Instead, the transmitted and reflected components are completely encapsulated in the wave function, making it rather more problematic to disentangle. This is ultimately achieved in Sec. V for the SFA wave function presented in this paper but in order to highlight the main aspects of the method we discuss beforehand a simpler example, that of tunneling in a constant electric field.

III. TIME DELAY IN A CONSTANT FIELD

The adiabatic model of ionization, namely, atomic ionization in a constant field, will be helpful for our purposes as it is analytically tractable. Moreover, it will provide us with a reference with which to compare our earlier time-dependent model.

A. Ionization in an adiabatic field

Consider a bound electron of energy $-I_p$ in 1D δ potential ionized by a constant electric field E_0 . The continuum eigenstate of the electron in this field is given by the solution to the

time-independent Schrödinger equation:

$$-\frac{1}{2}\frac{d^2\psi}{dx^2} + (I_p - E_0 x)\psi(x) = 0,$$
 (21)

which has as a general analytical solution a superposition of the Airy functions of the first and second kind:

$$\psi(x) = c_1 \operatorname{Ai}(\tilde{x}) + c_2 \operatorname{Bi}(\tilde{x}), \tag{22}$$

where

$$\tilde{x} = \left(\frac{2}{E_0^2}\right)^{\frac{1}{3}} (I_p - E_0 x). \tag{23}$$

The requirement that the wave function be a traveling wave as $x \to \infty$ imposes the condition $c_1 = ic_2$ so that the wave function takes the form

$$\psi(x) = T[\operatorname{Bi}(\tilde{x}) + i \operatorname{Ai}(\tilde{x})], \tag{24}$$

where T can be determined by matching this wave function to the bound-state solution of the atom; this prefactor plays a role in the ionization amplitudes but is irrelevant to the phase of the wave function. We calculate the Wigner time delay for this wave function via the energy derivative of the phase:

$$\tau_W(x) = i \frac{\partial}{\partial I_p} \ln \frac{\psi}{|\psi|} = \frac{2^{\frac{1}{3}}}{\pi E_0^{\frac{2}{3}}} \frac{1}{\operatorname{Ai}(\tilde{x})^2 + \operatorname{Bi}(\tilde{x})^2}.$$
 (25)

The constant field model allows one to estimate the scaling of the Wigner time delay, given by Eq. (1), at the tunnel exit $x_e = I_p/E_0$:

$$\tau_W(x_e) = \frac{3^{4/3} \Gamma(\frac{2}{3})^2}{2^{5/3} \pi} \frac{1}{E_0^{2/3}}.$$
 (26)

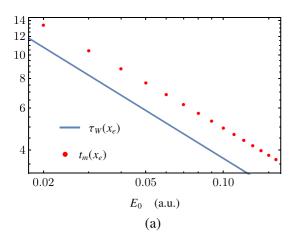
Using Eq. (2), we derive the scaling of the Wigner group velocity of the electron at the tunnel exit,

$$v_W(x_e) = \frac{2(\frac{2}{3})^{2/3} \sqrt{\pi} \Gamma(\frac{7}{6})}{\Gamma(\frac{2}{3})^2} E_0^{1/3}, \tag{27}$$

and find it consistent with the estimate of the scaling of the electron momentum $p_e \sim E_0 \tau_W$ in Ref. [52].

We compare the Wigner time delay and the group delay velocity in the constant field case with the exact time-dependent SFA calculations in Fig. 3. The time delay in the SFA scales with the electric field in a similar manner to the adiabatic case, $\tau_W(x_e) \propto 1/E_0^{2/3}$, but shifted in time by a constant. This shift stems from the fact that the Wigner trajectory is derived via the energy derivative of the phase of the wave function (which corresponds to following the peak of the wave packet, neglecting its spreading), while the time integration responsible for the formation of the ionization wave packet in SFA is calculated exactly numerically.

The scaling of the Wigner group velocity using the SFA is also in agreement with the adiabatic estimate, $v_W(x_e) \propto E_0^{1/3}$. However, the relative error between these two grows with the field strength, becoming appreciable at higher field strengths when approaching the OTBI threshold. This is consistent with the simple estimate for the threshold for OTBI, $E_{\rm th} \approx 0.25$ a.u., where a tunneling description no longer applies.



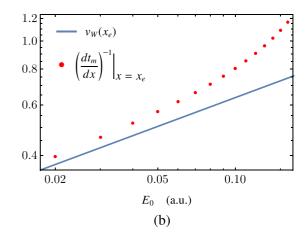


FIG. 3. Log-log plots of the scaling with respect to field strength, E_0 , of the (a) Wigner time delay and (b) group velocity at the classical tunnel exit, $x_e = I_p/E_0$, for the time evolved SFA wave function (red dots) and the adiabatic constant field wave function (blue lines). For the time evolved wave function, the maxima in time, t_m , of the probability distribution $|\psi(x_e, t)|^2$ and its derivative were calculated; for the adiabatic case, results follow from Eqs. (26) and (27). The agreement in the trends is good, deteriorating as one approaches the OTBI threshold $E_{th} \approx 0.25$ a.u.

Note that the Wigner trajectory in the constant field case is determined from the solution of the time-independent Schrödinger equation (energy eigenstate), while in the SFA case it is determined from the time-dependent wave function. In the first case, the Wigner trajectory is defined as the derivative of the wave-function phase with respect to the energy, which corresponds to determining the coordinate of the peak of the electron wave packet at a fixed time moment, i.e., determining the motion of the wave-packet peak. In contrast, in the SFA case we explicitly determine the maximum of the wave function in time for a fixed coordinate.

B. Reflections in a constant field

To investigate the effect of under-the-barrier reflected components, we need to isolate their contribution to the full wave function. The analytical wave function of Eq. (24) consists of a superposition of Airy functions $\mathrm{Ai}(\tilde{x})$ and $\mathrm{Bi}(\tilde{x})$ which can be given interpretation as the under-the-barrier reflected and transmitted components of the tunneling wave function, respectively.

This interpretation can be generally understood by considering the Airy functions, as shown in Fig. 4. The Bi component of the wave function decays exponentially as it approaches the tunnel exit, $x = x_e$, from the atomic core at x = 0, and hence can be seen to correspond to the transmission component; likewise, the exponentially growing Ai component corresponds to wave-function reflection.

This interpretation can be formally established by considering the integral representation of the Airy functions:

$$\operatorname{Ai}(\tilde{x}) = \frac{1}{2\pi i} \int_{\gamma_1} ds \, \exp\left(\tilde{x} \, s - \frac{s^3}{3}\right),\tag{28}$$

$$\operatorname{Bi}(\tilde{x}) = \frac{1}{2\pi} \int_{\gamma_2 - \gamma_2} ds \, \exp\left(\tilde{x} \, s - \frac{s^3}{3}\right),\tag{29}$$

where the complex plane integration paths γ_i are indicated in Fig. 5(a). These integrals converge when their end points lie in the slices of the complex plane defined by $-\frac{\pi}{6} < \theta < \frac{\pi}{6}$,

 $\frac{\pi}{2} < \theta < \frac{5\pi}{6}$, and $\frac{7\pi}{6} < \theta < \frac{3\pi}{2}$, where in polar $\{r, \theta\}$ coordinates $s = r \exp(i\theta)$. In these regions, shaded blue in Fig. 5, the integrand vanishes rapidly as $r \to \infty$.

The majority of the contributions to the Airy integrals thus come from around the saddle points,

$$s_{+} = \pm \sqrt{\tilde{x}},\tag{30}$$

of the argument of the integrand. The Airy contours, γ_i , can be deformed into paths that to go through these saddle points and, using the standard technique of saddle-point integration method [78], asymptotic expressions for the Airy integrals can be determined.

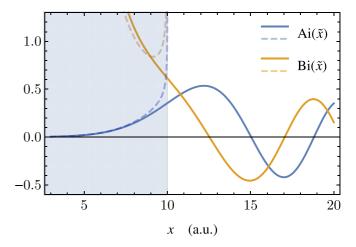


FIG. 4. The solution to the electron in a constant field problem is given by a superposition of Airy functions of the first and second kind, $Ai(\tilde{x})$ and $Bi(\tilde{x})$, plotted in blue and orange, respectively. These functions have very accurate asymptotic expansions, shown dashed, which can be derived by considering the saddle points of the Airy integrals (28) and (29). Under the barrier, x < 10 (shaded blue), these expansions show that the wave-function components $Ai(\tilde{x})$ and $Bi(\tilde{x})$, respectively, correspond to the reflected and transmitted components of the wave function.

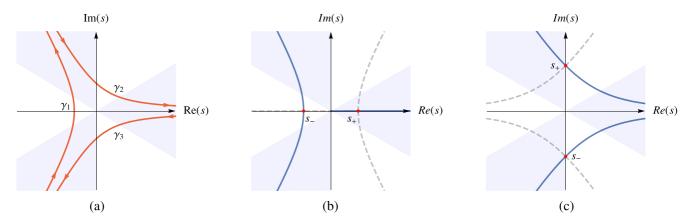


FIG. 5. The Airy integral $\int_{\gamma} ds \exp(\tilde{x} s - s^3/3)$ is defined on the complex s plane; it converges when the end points of its infinite contour, γ , lie in the shaded areas. The canonical contours defining the Airy function of the first (γ_1) and second $(\gamma_2 - \gamma_3)$ kind are shown in (a). Contributions to the Airy integral arise principally from portions of the contour near the saddle points of the integrand function $\exp(\tilde{x} s - s^3/3)$. The configuration of the saddles $s_{\pm}(x) = \pm \sqrt{\tilde{x}}$ (red dots) in the complex plane is shown for positions (b) inside the barrier $(\tilde{x} > 0)$ and (c) outside the barrier $(\tilde{x} < 0)$. Through each saddle point pass two perpendicular level curves, the path of steepest descents (solid blue) and the path of steepest ascents (dashed gray). Deforming the defining contours in (a) through the steepest descents contours in (b) and (c) provides asymptotic expansions for the Airy function, as in Eqs. (31) and (32).

The saddle points, and the respective paths of steepest descents and ascents, are illustrated in Figs. 5(b) and 5(c); since these are dependent on \tilde{x} the application of the saddle-point method is different for the two cases of inside ($\tilde{x} > 0$) and outside ($\tilde{x} < 0$) the potential barrier. As shown in Fig. 5(b), for $\tilde{x} > 0$ we may deform the contour γ_1 smoothly into the path of steepest descents for the saddle point s_- and in doing so obtain the asymptotic approximation

$$Ai(\tilde{x}) = \frac{\exp\left(-\frac{2}{3}\tilde{x}^{\frac{3}{2}}\right)}{2\sqrt{\pi}\,\tilde{x}^{\frac{1}{4}}} + O(\tilde{x}^{-\frac{3}{2}}). \tag{31}$$

Likewise, we may deform the contours γ_2 and $-\gamma_3$ to both go through the steepest descent path of the saddle point s_+ and hence deduce the asymptotic form of the Bi(x) function under the potential barrier:

$$Bi(\tilde{x}) = \frac{\exp\left(+\frac{2}{3}\tilde{x}^{\frac{3}{2}}\right)}{\sqrt{\pi}\,\tilde{x}^{\frac{1}{4}}} + O(\tilde{x}^{-\frac{3}{2}}). \tag{32}$$

From a tunneling particle's perspective, one may identify the Ai(x) function and its saddle point s_- with the reflected part of the wave function, and the saddle point s_+ , or the Bi(x) function with the transmitted part of the wave function: the transmitted wave decays as it moves to the tunnel exit, while the reflected wave propagates from the exit decaying exponentially toward the atomic core, as shown in Fig. 4.

In the following section, this relation between sub-barrier reflections and the contribution of one saddle point to the time integrand of the wave-function amplitude is applied to the problem of ionization in a time-dependent field. This then allows us to investigate the role of sub-barrier reflection in the formation of a tunneling time delay.

IV. WIGNER TIME AND REFLECTIONS IN THE SFA

As shown in Sec. III, we may reasonably ascribe the saddle point of the integrand of the wave function to under-the-

barrier reflection or transmission. To reveal the contribution of the reflection to the tunneling time delay, we investigate the complex continuation of the integrand function of the SFA wave function, Eq. (17). The insight developed previously, namely, the relation of a specific saddle point of the integrand function to reflectionlike behavior in the wave function, is used to extract the contribution of reflections to the wave function by modifying the path of integration of the complex plane.

In general, the complex t'-plane picture of the phase Φ in Eq. (17) has many similarities to that of adiabatic ionization. However, it depends continuously not only on the coordinate x but now also on observation time t, making its analysis somewhat more involved. In adiabatic ionization, there was only one degree of freedom, \tilde{x} , and the saddle points were either purely real or imaginary.

As shown in Fig. 6, in the time-dependent case there are also two saddle points of relevance in the SFA integral denoted t_{\pm} . Their arrangement in the complex t' plane is dependent on x and t but, as in the adiabatic case, the real coordinate x determines whether they are vertically or horizontally aligned (in or outside the barrier); the observation time t merely shifts the axis of symmetry which is always observed around the line t' = t. A more detailed discussion of the configuration of saddle points in (x, t) parameter space may be found in Appendix B.

A. Extracting reflections

In the adiabatic case, a partial integration over only the contour containing the saddle point s_{-} would exclude the exponentially growing contributions to the wave function, i.e., the reflections, associated with the saddle point s_{+} .

We use the same principle in the time-dependent case; in Fig. 6 we identify the saddle point corresponding to reflections, denoted t_+ (represented by a circle), and the secondary saddle point t_- (represented by a triangle). When we consider

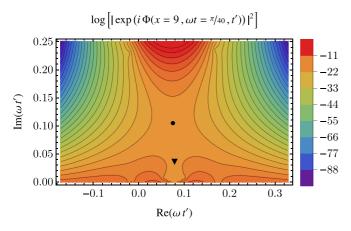


FIG. 6. Complex t' plane of the argument $\Phi(x, t, t')$ of the wavefunction integral $\psi_i = \int_{t_0}^t dt' \exp(i \Phi)$, for parameters x = 9 and $\omega t = \pi/40$. For these configurations there are two saddle points, denoted by a circle and triangle, the former of which, t_+ , corresponds to reflections. The saddle-point method can be used to solve the wave-function integral, when the path is taken over both saddle points. We use a partial path given by (33) to remove the contribution of reflections by integrating over only one of the saddle points. Other possible configurations of the saddle points are shown in Fig. 11.

the wave function under the potential barrier, we can split the integration contour in Eq. (17) into two parts: from the start of the pulse, $t_0 = -\pi/(2\omega)$, to the upper saddle point, t_+ , and from t_+ to the real time t.

The contributions of these two contours to the wave function are shown in Fig. 7. The former integral has the form of a growing exponential and so can ostensibly be identified as the reflected part of the wave function while the latter is a decaying exponential identifiable as the transmitted part. To neglect contributions from the reflections to the full wave

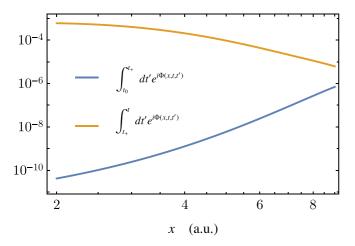


FIG. 7. Log-log plot of the relative contributions to the wavefunction amplitude from the portion of the integration path up to the saddle point (blue) and from the saddle point to the given real time t (orange) for various positions x under the classical barrier (i.e., far from the atomic core, but smaller than the tunnel exit). The behaviors are approximately decaying and growing exponentials, respectively, analogous to transmitted and reflected parts of the wave function.

function we identify the following wave function:

$$\psi_{\rm nr}(x,t) = \begin{cases} \int_{t_0}^{t_+} dt' \exp[i \, \Phi(x,t,t')] & x > x_e \\ \int_{t_-}^{t} dt' \exp[i \, \Phi(x,t,t')] & x < x_e \end{cases}$$
(33)

Our method of distinguishing the reflection contribution is based on the distinguishability of the saddle-point contributions to the wave-function integral. This is not possible when the two saddle points are so close that the cubic term in the expansion of the phase $\Phi(x, t, t')$ becomes non-negligible [79], i.e., when

$$\left| \frac{\frac{\partial^3}{\partial t'^3} \Phi(x, t, t')}{\left(\frac{\partial^2}{\partial t'^2} \Phi(x, t, t')\right)^{\frac{3}{2}}} \right|_{t'=t_+} \gtrsim 1$$
(34)

for either saddle point t_{\pm} . This occurs in the region very near the barrier boundary and at the peak of the laser pulse, as discussed further in Sec. IVB. In this case, the reflection cannot be separated in the wave function in a meaningful manner.

We find that when reflections are extracted from the wave function using Eq. (33) the Wigner time delay under the barrier vanishes, as evident in both panels of Fig. 8. That is, when reflections are neglected, there is no time delay between the peak of the electron probability distribution and the peak of the laser field. Moreover, outside the barrier, the trajectory of the peak rapidly becomes classical.

Plotted also in Fig. 8(b) is the trajectory for an electron in a constant field, given by Eq. (25). For parameters in the deep tunneling regime, the SFA trajectory (given by the peak of the wave function), and the classical trajectory, the constant field trajectory displays very similar behavior as the pulse elapses (the trajectories do not completely coincide far away due to the time dependence of the field and the need to match a tunnel exit, respectively).

At a detector infinitely far away such as one in an attoclock experiment, a signature of time delay would be absent for the deep tunneling conditions detailed in this paper. Thus, it is of importance to distinguish between a time delay of the peak of the wave function near the tunnel exit and an asymptotic time delay at a detector. Since in attoclock experiments the asymptotic momentum distribution is measured, i.e., the asymptotic time delay, one expects to find a zero time delay in the deep tunneling regime. However, near the tunnel exit, quantum-mechanical considerations must be taken into account and a quantum-mechanical treatment such as the one exposed here exhibits an explicit nonzero Wigner delay.

B. Tunnel exit from the SFA

We may also use the saddle-point analysis of Eq. (17) to extract relevant physical information about the electron dynamics. In particular, and in analogy to the constant field scenario, the topology of the saddle points through the complex t' plane reveals the functional behavior of the electronic wave packet.

The paths of these two saddle points, for two representative choices of time t while varying x, are shown in Fig. 9, closely resembling those corresponding to Figs. 5(b) and 5(c). Much as in the constant field case, where the saddles are purely

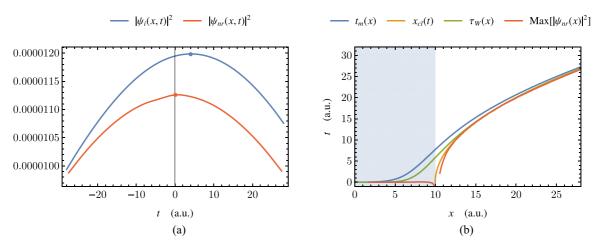


FIG. 8. (a) Temporal probability distributions at the position x = 8 a.u. (under the barrier, near the tunnel exit), for the ionized wave function, ψ_i , and the pseudo-wave-function neglecting reflections, ψ_{nr} . The physical wave function has accrued a Wigner time delay with respect to the laser field, whereas the maximum of the pseudo-wave-function is synchronous with the laser field peak. (b) Trajectories in the (x,t) plane via the maximum of the wave function ψ_i [given by $t_m(x)$], the maximum of the wave function neglecting reflections ψ_{nr} , and the energy derivative of the constant field wave function $\tau_W(x)$. The classical electron trajectory, $x_{cl}(t)$, starting at the tunnel exit at the peak of the laser field is also shown. Under the barrier, the probability distribution neglecting reflections $|\psi_{nr}|^2$ shows zero time delay. In regions where Eq. (34) does not apply, mostly near the classical tunnel exit, we may not identify reflections or plot a subsequent trajectory.

real or imaginary, as given by Eq. (30) and Fig. 5, the pair of saddle points in the SFA is aligned around the line given by Re[t'] = t; this alignment is either vertical or horizontal depending on the coordinate x. For a fixed observation time t, there corresponds a coordinate x of closest approach between the saddle points. For the peak of the pulse, t = 0, there exists a coordinate x_t where the saddle points merge completely, as they do in the case $\tilde{x} = 0$ for the constant field electron.

Thus, two lines, t = 0 and $x = x_t$, define separatrices for the behavior of the saddle points and their contributions to the integral: the behavior of the wave function can be seen to

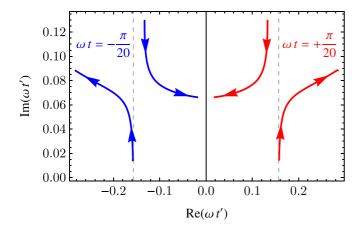


FIG. 9. Positions of the upper and lower saddle points of the integral (17) in the complex t' plane with varying x and for fixed $\omega t = \pm 0.1\pi/2$ (blue and red, respectively). The saddles draw smooth curves with varying x, where the arrows indicate growing values of x. For values of $x \le 7$, the lower saddle point disappears below the imaginary axis. Each pair of curves is centered around the line $\text{Re}(\omega t') = \omega t$, shown in dashed line. For the case $\omega t = 0$, not shown, the two lines meet one point corresponding to $x = x_t$.

change depending on whether $x > x_t$. This is a phenomenon exactly analogous to the merging of the saddle points for the constant field case of Sec. III: there, the merging of the saddle points occurs at the classical exit, $\tilde{x} = 0$, and separates the regions of evanescence and oscillation in the wave function.

We may use this parallel to identify the merging point as a measure of the tunnel exit. In our paper, for a field strength of $E_0 = 0.05$ and $\gamma = 0.14$, we find that this exit takes the value $x_t \approx 10.2$ a.u.; this is in good agreement with the classically expected tunnel exit $x_e = I_p/E_0 = 10$ a.u. More precise agreement is achieved with the probability averaged tunnel exit:

$$x_K = \frac{\int dt' \frac{I_p}{|E(t')|} \exp\left(-\frac{2\kappa^3}{3|E(t')|}\right)}{\int dt' \exp\left(-\frac{2\kappa^3}{3|E(t')|}\right)} \approx 10.35 \text{ a.u.},$$
 (35)

where the integration runs over the whole laser pulse.

V. CONCLUSIONS

In this paper, we have analyzed the tunneling time delay in strong-field ionization for a simple model of an atom with a short-range potential. The wave function was calculated to first order in the SFA for any intermediate time, enabling a quantum treatment of dynamics in the region where quasiclassical descriptions break down, viz., around the classical tunnel exit. For a given coordinate, the peak of the wave packet shows a time delay with respect to the peak of the laser field and this time delay is positive at the classical tunnel exit.

We argue that reflections of the electron wave packet under the tunneling barrier are fundamentally responsible for this nonzero time delay around the tunnel exit. This is a general phenomenon, present in any regime of strong-field ionization, as well as in any tunneling process. In particular, a simple showcase is presented in Appendix A for the case of tunneling through a box potential. To identify and separate contributions of reflected components to the wave function, we first considered the analytically soluble case of an electron in a constant electric field. In addition to providing a benchmark to our SFA wave function, the constant field wave function can be deconstructed by analyzing its definition as an integral in the complex plane; this integral is dominated by two saddle points, allowing us to unambiguously identify the transmitted and reflected wavefunction components as contributions to the integral from the regions around each saddle point.

We apply this observation to the SFA wave function by defining an integration contour that purposefully neglects the contribution of the reflection saddle point, and obtain a pseudo-wave-function distribution that has zero time delay with respect to the peak of the laser field everywhere under the barrier. Moreover, the tunnel exit is unequivocally determined from the SFA theory as the spatial co-ordinate at which the saddle points merge at the peak of the laser field.

Finally, we emphasize the distinction between the time delay present at the tunnel exit (theoretically measurable using a virtual detector) and an (experimentally observed) asymptotic delay. We have shown within the first-order SFA that the signature of the time delay in the electron wave function vanishes since the ionized electron propagates to the detector as the classical (i.e., with zero time delay) and the quantum-mechanical electron share equivalent asymptotic trajectories. Thus, the asymptotic time delay associated with the direct ionization path is always vanishing. Nevertheless, a more accurate estimate of the asymptotic time delay via the second-order SFA in Ref. [52] has shown that interference of the direct and the sub-barrier ionization paths generates nonvanishing negative asymptotic time delay in the near threshold of the OTBI regime, which fades out in the deep tunneling regime.

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APPENDIX A: TUNNELING THROUGH A BOX POTENTIAL BARRIER

In this Appendix we consider the role of quantum reflections in the tunneling time delay for an electron wave packet tunneling through a one-dimensional box potential. This is perhaps the simplest example of tunneling time delay since the wave function is readily separable (and of analytic solution) in the regions inside and outside the barrier, allowing the contributions of reflections to the time delay to be clearly identified.

It should be mentioned that this model differs from true strong-field ionization in that it considers the scattering of a wave packet incident on a potential barrier; in actual ionization the electron originates *from within* a potential barrier. Be that as it may, this paper provides a simple, intuitive picture of tunneling time delay, suitable even for the uninitiated.

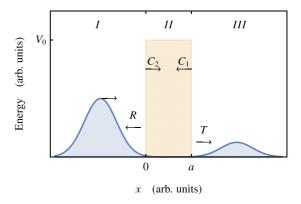


FIG. 10. Pictorial representation of the square barrier potential for an incident monochromatic wave. The wave function is a piecewise solution of the Schrödinger equation for the three regions shown, given by Eqs. (A2) and (A3).

1. The box potential

Consider a wave packet

$$\Psi(x,t) = \int dp f(p-p_0) \psi(p) e^{-i\mathcal{E}(p)t}$$
 (A1)

with energy $\mathcal{E}(p) = p^2/2$, incident on a potential barrier $V(x) = V_0$ for $0 \le x \le a$ and zero elsewhere, where $f(p-p_0)$ is some distribution peaked at p_0 (e.g., a Gaussian), as shown Fig. 10. Each *p*-component wave function obeys the time-independent Schrödinger equation with the piecewise solution

$$\psi_{\rm I}(x) = e^{ipx} + Re^{-ipx},\tag{A2}$$

$$\psi_{II}(x) = C_1 e^{qx} + C_2 e^{-qx}, \tag{A3}$$

$$\psi_{\rm III}(x) = Te^{ipx},\tag{A4}$$

with momenta $p = \sqrt{2\mathcal{E}}$, $q = \sqrt{2(V_0 - \mathcal{E})}$. The amplitude of the incoming wave has been set to unity, without loss of generality, and the coefficients C_1 and C_2 are the typical reflection and transmission coefficients under the barrier, respectively.

Matching the above solutions and their derivatives at the boundaries yields the coefficients

$$C_1 = \frac{(-2i\chi)(1+i\chi)e^{-\xi}}{(1-i\chi)^2 e^{\xi} - (1+i\chi)^2 e^{-\xi}},$$
 (A5)

$$C_2 = \frac{(-2i\chi)(1-i\chi)e^{\xi}}{(1-i\chi)^2 e^{\xi} - (1+i\chi)^2 e^{-\xi}},$$
 (A6)

$$R = \frac{(1+\chi^2) (e^{-\xi} - e^{\xi})}{(1-i\chi)^2 e^{\xi} - (1+i\chi)^2 e^{-\xi}},$$
 (A7)

and

$$T = \frac{(-4i\chi)e^{-ipa}}{(1-i\chi)^2 e^{\xi} - (1+i\chi)^2 e^{-\xi}}.$$
 (A8)

We have introduced the dimensionless parameters $\chi = p/q$ and $\xi = q \, a$ which, loosely speaking, determine the relative length and height of the barrier, respectively.

2. Time delay

The wave packet after transmission is of the form

$$\Psi_{\text{III}} = \int dp |T(p)| \exp\{i[\varphi(p) + px - \mathcal{E}(p)t]\}, \quad (A9)$$

where $T = |T|e^{i\varphi}$. The maximum of this amplitude occurs when the phase in Eq. (A9) vanishes, that is, when (after some rearrangement)

$$x = p_0 t - \left[\frac{\partial \varphi}{\partial p} \right]_{p=p_0}.$$
 (A10)

In the absence of a potential barrier, the peak travels at the classical velocity (in atomic units) p_0 . Equation (A10) shows that the barrier causes a delay of the peak in reaching a given position x, a delay which is given by the energy derivative of the transmission phase φ . Thus,

$$\tau = \frac{1}{p_0} \left[\frac{\partial \varphi}{\partial p} \right]_{p=p_0} + \frac{a}{p_0} \tag{A11}$$

gives the time delay of the peak after crossing the barrier, i.e., the tunneling time. For the box potential, one finds

$$\tau = \frac{a}{p_0} \frac{\frac{1}{2\xi} \left(\chi + \frac{1}{\chi}\right)^2 \tanh(\xi) + \frac{(1-\chi^2)}{2} \operatorname{sech}^2(\xi)}{1 + \frac{1}{4} \left(\chi - \frac{1}{\chi}\right)^2 \tanh^2(\xi)}.$$
 (A12)

This can be expanded for large ξ :

$$\tau \approx \frac{a}{p_0} \left(\frac{2}{\xi} - \frac{8e^{-2\xi}\chi^2(\chi^2 - 1)}{(\chi^2 + 1)^2} \right),$$
 (A13)

where the leading-order term can be identified as stemming from single reflections from the edges of the barrier, and the next-order term can be identified as the delay due to interference of single and double reflections from the barrier edges (i.e., waves that recoil twice before exiting). Higherorder terms correspond to interference of reflections at higher orders.

This is identical to the interference of direct and recolliding trajectories as described in Ref. [52]. Note that the latter is negative in the near-threshold tunneling regime of large χ and scales as a tunneling exponent $\propto e^{-2\xi}$. The main body of the present paper is concerned with a single-order description of tunneling, whereas higher-order reflections would be described by higher-order terms in the SFA.

3. Quantum reflections and time delay

What is the origin of this time delay? For longer barriers, $\xi \gg 1$, the tunneling time τ becomes

$$\lim_{\xi \gg 1} \tau \approx \frac{2\chi}{p_0^2},\tag{A14}$$

vanishing when $\chi \ll 1$. Thus, the time delay is vanishing for $\xi \gg 1$ and $\chi \ll 1$. With this knowledge, we can analyze the exact wave function inside the barrier. The reflection coefficient C_1 in the given limiting conditions, $\xi \gg 1$ and $\chi \ll 1$,

$$C_1 \approx -2i\chi e^{-2\xi},\tag{A15}$$

vanishes asymptotically. This suggests an intuitive link between the reflection of wave components and the retardation of the wave packet.

In the box potential case, in contrast to the tunneling problem, there exists, however, a second reflection: the reflection from incidence on the first surface of the barrier, described by the coefficient R. Classically, R = -1, and there is no time delay at reflection. However, in the quantum case $R + 1 \neq 0$, inducing a time delay of the electron wave packet from entry into the barrier. In the limit $\xi \gg 1$ and $\chi \ll 1$, we have $R \approx -(1 + 2i\chi)$, i.e.,

$$|R+1| \approx \chi \ll 1. \tag{A16}$$

Analyzing the exact wave function, we can conclude that the time delay vanishes when the reflection from the barrier surface is classical, and when the reflection inside the barrier is negligible.

One can deduce the time delay caused by reflection at the entry by applying the Wigner delay formula, Eq. (1), at x = 0. For $\xi \gg 1$, $R \approx -(1 + i\chi)/(1 - i\chi)$ and

$$\tau_{\text{entry}} = \frac{-i}{p_0} \left. \frac{\partial}{\partial p} \ln \left(\frac{\psi_{\text{I}}(x)}{|\psi_{\text{I}}(x)|} \right) \right|_{x=0} \approx \frac{\chi}{p_0^2} = \frac{1}{2} \lim_{\xi \gg 1} \tau. \quad (A17)$$

Thus, one can conclude the time taken for the peak of the electron wave packet to travel through the box potential is caused in equal parts by the reflections of the wave packet on the barrier entry (x = 0) and exit (x = a) surfaces.

APPENDIX B: CONFIGURATIONS OF SADDLE POINTS

The configurations of the saddle points of the argument $\Phi(x, t, t')$ of the wave-function integral $\psi_i = \int_{t_0}^t dt' \exp(i \Phi)$ in the complex t' plane, for a large (x, t) parameter range, are presented as a table in Fig. 11. The laser pulse evolves from left to right in this figure and mostly shifts the reference line around which the saddle points are centered, namely, Re[t'] = t. It should be noted, by the definition in Eq. (17), that a singularity is always to be observed at the point t' = t.

As one moves down the table, configurations of the complex t' plane are shown for spatial coordinates inside, neighboring, and outside the tunneling barrier (x = 7, 10, and 14 a.u., respectively). There are marked differences between each observation coordinate but the behavior is reminiscent of the complex plane configuration for the Airy integral, displayed in Fig. 5. Indeed, the two pictures can easily be reconciled by a $\pi/2$ -rad clockwise rotation.

Inside the barrier, the saddle points are vertically aligned along the line Re[t'] = t. As one increases the observation coordinate and approaches the tunnel exit, $x \approx 10$, the two saddle points approach each other vertically; as one exits the region neighboring the tunnel exit, $x \gg 10$, the saddles then separate from each other on the horizontal.

As one approaches the peak of the laser field, t = 0, the distance of closest approach around the tunnel exit shrinks. At the exact peak, this distance is zero; that is, the saddle points merge. This phenomenon is directly comparable to the merging of saddle points for the Airy integral at the classical tunnel exit. Thus, we are able identify a new tunnel exit, x_t , from the complex plane landscape, a topic discussed in Sec. IV B.

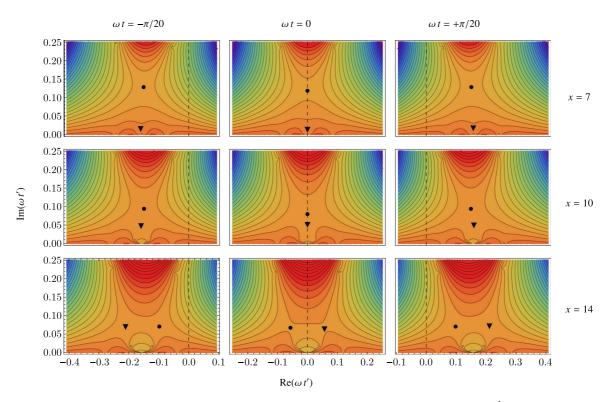


FIG. 11. Configurations of the saddle points of the argument $\Phi(x, t, t')$ of the wave-function integral $\psi_i = \int_{t_0}^t dt' \exp(i\Phi)$ in the complex t' plane, for parameter ranges x = 7, 10, 14 and $\omega t = -\pi/20$, 0, $+\pi$, 20. The dashed line corresponds to t' = 0 and each plot is centered around the (scaled) observation time ωt . The scale and color coding are identical to those of Fig. 6. As x increases the two saddle points approach vertically and, after a closest approach, separate horizontally. For the peak of the pulse, $\omega t = 0$, this closest approach is zero and the two saddle points merge at the point x_t . Otherwise, varying t skews the relative orientation of the saddle points around the line Re[t'] = t.

The identification of the exact value for the coordinate x_t to a desired precision is in principle achievable by a binary search or global minimization of the dis-

tance function for the saddle points. However, such precision was deemed unnecessary for the purposes of this paper.

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