

Full-field quantum imaging with a single-photon avalanche diode cameraHugo Defienne^{1,*}, Jiuxuan Zhao^{2,*}, Edoardo Charbon^{2,‡} and Daniele Faccio^{1,§}¹*School of Physics and Astronomy, University of Glasgow, Glasgow G12 8QQ, United Kingdom*²*Advanced Quantum Architecture Laboratory (AQUA), Ecole Polytechnique Federale de Lausanne (EPFL), 2002 Neuchatel, Switzerland*

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Single-photon avalanche diode (SPAD) arrays are essential tools in biophotonics, optical ranging and sensing, and quantum optics. However, their small number of pixels, low quantum efficiency, and small fill factor have so far hindered their use for practical imaging applications. Here, we demonstrate full-field entangled photon-pair correlation imaging using a 100-kpixel SPAD camera. By measuring photon coincidences between more than 500 million pairs of positions, we retrieve the full point spread function of the imaging system and subsequently high-resolution images of target objects illuminated by spatially entangled photon pairs. We show that our imaging approach is robust against stray light, enabling quantum imaging technologies to move beyond laboratory experiments towards real-world applications such as quantum light detection and ranging.

DOI: [10.1103/PhysRevA.103.042608](https://doi.org/10.1103/PhysRevA.103.042608)**I. INTRODUCTION**

Quantum properties of light have inspired a range of new imaging modalities [1] including interaction-free protocols [2,3], quantum lithography [4] and holography [5], as well as sensitivity-enhanced [6,7] and super-resolution schemes [8,9]. While these imaging methods differ in terms of the type of illumination and optical arrangement, they all rely on characterizing high-order spatial correlation functions of light [10]. An essential device for implementing practical quantum imaging is therefore an optical sensor that is able to efficiently and rapidly measure photon coincidences between many spatial positions. Typical quantum imaging experiments count coincidences between two single-pixel single-photon avalanche diodes (SPADs) that are each scanned over their own subspaces to build up a measurement point by point [11,12]. Such procedures are photon inefficient, thus making quantum imaging a tedious and prohibitively time-consuming process even for a relatively small number of positions.

During recent decades, single-photon sensitive cameras have progressively replaced raster-scanning techniques for coincidence counting, enabling the characterization of high-dimensional entangled states [13–16] and the implementation of proof-of-principle quantum imaging experiments [17–19]. These cameras are typically intensified charge-coupled devices (iCCD) or complementary metal oxide semiconductor (iCMOS) cameras, which have an image intensifier placed before the sensor [20], and electron-multiplied (EM) CCD cameras that incorporate an on-chip gain stage before the charge reading stage [21]. These technologies provide a large number of pixels to detect photons with high quantum efficiency (up to 95% for EMCCD cameras) but also have

important drawbacks, including a relatively low frames rate (of the order of 100 Hz) and the presence of significant electronic noise. For example, quantum imaging approaches based on multipixel coincidence counting with an EMCCD camera require tens of hours to retrieve a single image of an object illuminated by entangled pairs [5,18,19], which severely limits their use in practice.

Similarly to intensified and EM cameras, single-photon avalanche diode (SPAD) detectors offer single-photon level sensitivity, but with unparalleled speed, temporal resolution, and very low noise [22]. Their implementation in standard CMOS technology [23] has triggered the development of digital SPAD-based cameras [24,25]. Thus far, these imaging devices have shown their capabilities in fluorescence lifetime imaging [26–30], light detection and ranging (LiDAR) [31–34], non-line-of-sight imaging [35], and imaging through scattering media [36]. In quantum optics, a few experimental studies have used SPAD cameras for characterizing spatial correlations [37] and entanglement [38,39] between entangled pairs. Furthermore, two recent works report imaging based on single photons [40] and photon pairs [41] detected by small SPAD arrays (up to 32×32 pixels), but using a point-by-point scanning approach and classically illuminated objects, respectively. Here, full-field imaging of quantum-illuminated targets with a SPAD camera is achieved.

In this work, we demonstrate a full-field quantum illumination imaging approach based on massively parallel photon coincidence counting performed using a 100 kpixel SPAD camera.

II. IMAGING WITH PHOTON PAIRS

As shown in Fig. 1(a), our quantum imaging scheme uses a source of spatially entangled photon pairs to illuminate an object located at a distance ~ 0.5 m and a SPAD camera to detect back-reflected photons. The object is located in the far field of the source such that the pairs are spatially anticorrelated when interacting with it [42]. The object used here is a cat-shaped absorptive layer attached to a mirror and aligned so as to be illuminated by one-half of the illumination beam. The

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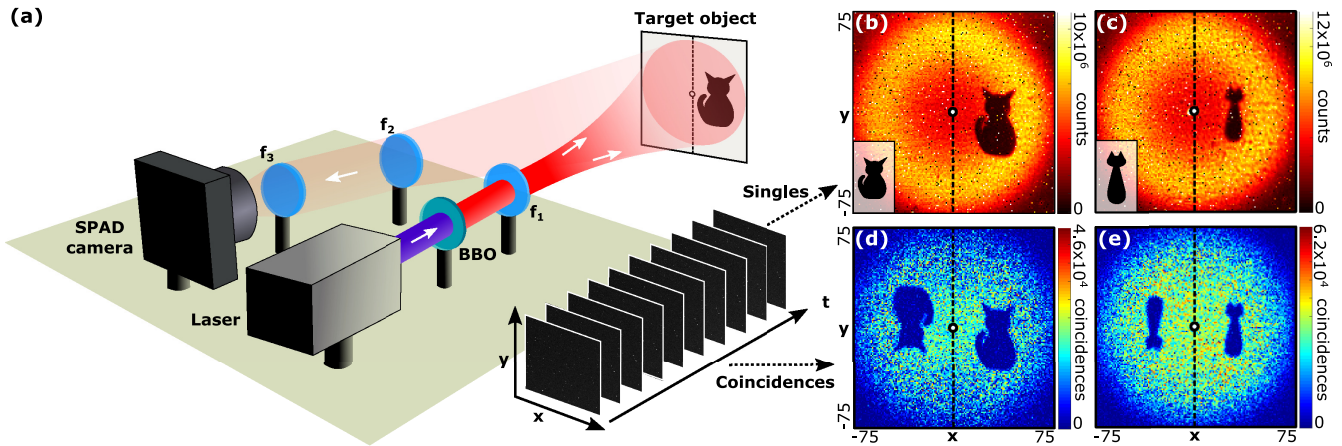


FIG. 1. Experimental setup. (a) Light emitted by a pulsed laser (347 nm) illuminates a β -barium borate (BBO) crystal (1 mm thick) to produce spatially entangled photon pairs (694 nm) by type-I spontaneous parametric down conversion (SPDC). After the crystal, pump photons are filtered out by long-pass filters (not shown). A lens $f_1 = 45$ mm is positioned a few millimeters after the crystal to direct photon pairs towards a target object located approximately at a focal distance from the lens. The target is composed of a mirror with one-half covered by a cat-shaped absorptive layer. Back-reflected photons are collected by the SPAD camera using two lenses $f_2 = 100$ and $f_3 = 50$ mm positioned approximately at the focal distance f_2 from the target and at the distance f_3 from the camera (distance between lenses is arbitrary). (b),(c) Summing all frames measured by the SPAD camera enables one to reconstruct an intensity image with different cat-shaped objects visible on one-half (original cat-shaped objects in inset). (d),(e) Identifying photon coincidences between symmetric pairs of pixels enables one to retrieve images showing symmetric shapes of the objects on the other half of the sensor. These images show signal-to-noise ratio (SNR) of $\text{SNR} = 4.19(9)$ and $\text{SNR} = 3.4(1)$, respectively. A total of $M = 10^7$ frames were acquired in each case. Image coordinate units are in pixels. Colorbar units are in number of photons and number of coincidences.

SPAD camera used in our study is the SwissSPAD2 [43]. It has an active imaging area composed of 512×512 pixels with a pitch of $16.38 \mu\text{m}$, a fill factor of 10.5%, and quantum efficiency of approximately 25% at 700 nm, which corresponds to an effective quantum efficiency of $\eta = 2.6\%$. The camera is designed to achieve a frame rate of 977 000 binary frames per second (fps) and allows sub-40-ps gate shifts with a low dark-count rate of 0.26 counts per second per μm^2 . In all measurements reported in this work, we used the eight-bit acquisition mode of the SPAD camera: each frame was obtained by accumulating 256 successive one-bit measurements, the latter requiring 350 ns each. The camera was operated in the internally triggered global shutter mode. We verified that the recorded frames were mostly composed of 1 and 0 values because of the weak detection efficiency and a photon-pair rate of $\sim 10^4$ per second. In the present demonstration, the overall effective acquisition speed is approximately 370 fps, which is more than 1000 times lower than the speed achieved in previous imaging works using the same camera [29,43]. Indeed, the prototype used in this work can only be connected to the computer using a USB cable, which strongly limits the data transfer rate and therefore the effective speed of the whole imaging process. However, it is essential to note that such limitation is only of a technical nature and is not linked to the camera itself.

A. Multipixel coincidence measurement

Figures 1(b) and 1(c) show images of two different cat-shaped target objects reconstructed by accumulating photons on the sensor over $M = 10^7$ frames and summing them together. The two cat shapes are well resolved as well as the typical ring shape of the photon-pair illumination beam

spreading over an area of 150×150 pixels. Furthermore, the single-photon level sensitivity of the SPAD camera also enables one to detect photon coincidences between all pairs of pixels. For example, Figs. 1(d) and 1(e) show coincidence rates measured between all symmetric pairs of pixels of the sensor at positions (\mathbf{r} and $-\mathbf{r}$) for the objects. We observe that a rotated image of the target object now appears on the part of the illumination beam that does not interact with the object. Indeed, when a photon from an entangled pair is detected at pixel \mathbf{r} , its twin is detected simultaneously at pixel $-\mathbf{r}$, but only if it is not absorbed by the target object: this is a result of the anticorrelation structure of entangled pairs in the far field [42]. This ability to perform coincidence measurements between many pixels in parallel for retrieving an image is at the heart of all quantum imaging schemes based on entangled photons [3,5,7,18]. However, while measuring photon coincidence is conceptually simple, it is in general a very challenging task in practice, especially when performed between a large number of pixels and in the presence of sensor noise and stray light.

In quantum optics, measuring coincidence is conventionally performed by multiplying the binary outcomes (0 or 1) of two synchronized single-photon detectors and averaging over many acquisitions. By analogy, one may think of retrieving entangled photon correlations in our experiment by simply multiplying the photon-count value $I_\ell(\mathbf{r}_i)$ at any pixel i (in position \mathbf{r}_i) of the ℓ th frame ($\ell \in \llbracket 1; M \rrbracket$) by the value at another pixel j (in position \mathbf{r}_j) of the same frame, and then averaging over all the frames, $C_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{M} \sum_{\ell=1}^M I_\ell(\mathbf{r}_i) I_\ell(\mathbf{r}_j)$. However, such an approach assumes that each frame contains, at most, two pixels of value one, each of them resulting from the successful detection of the two photons from the same

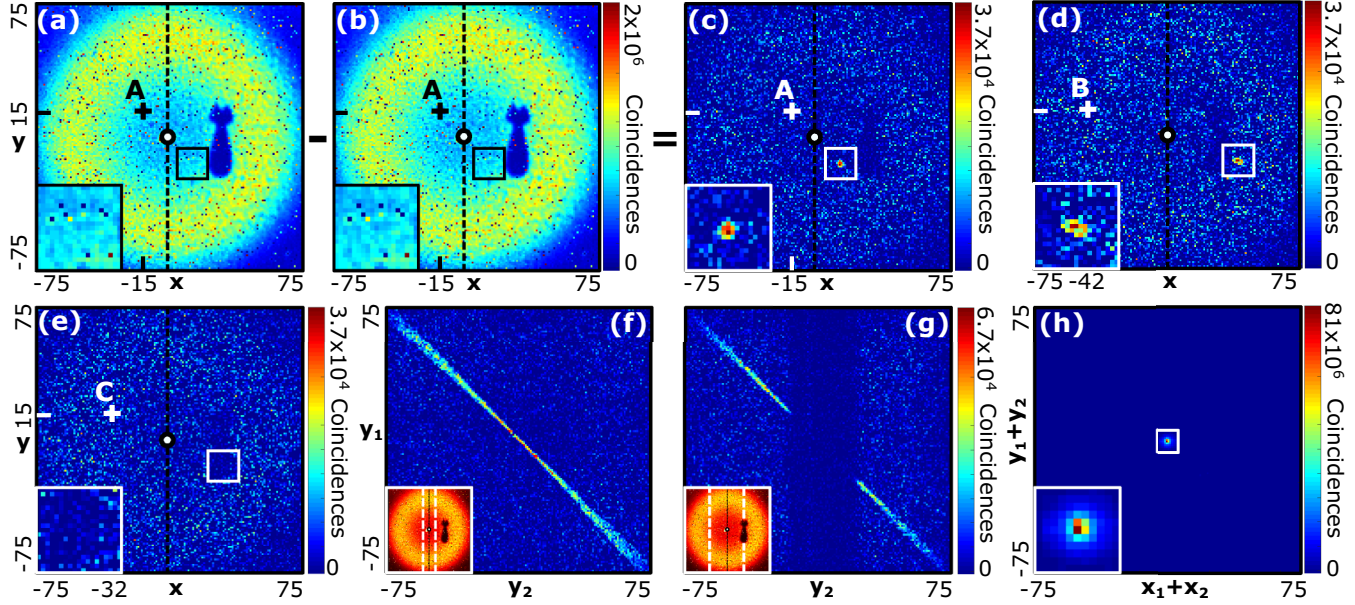


FIG. 2. Results of full-field quantum imaging. (a) “Total coincidences” image $\mathcal{C}(\mathbf{r}, \mathbf{A})$ reconstructed by multiplying the value measured at pixel $\mathbf{A} = (-15, 15)$ in each frame by all values of the other pixels in the same frame and then averaging over the set. (b) “Accidentals” image $\mathcal{A}(\mathbf{r}, \mathbf{A})$ reconstructed by multiplying the value measured at pixel \mathbf{A} in each frame by all values of the other pixels in the next frame and then averaging over the set. (c) Conditional image $\Gamma(\mathbf{r}, \mathbf{A})$ obtained by subtracting (b) from (a), showing a peak of genuine coincidences at position $-\mathbf{A}$ (zoom in inset). (d),(e) Conditional images $\Gamma(\mathbf{r}, \mathbf{B})$ with $\mathbf{B} = (-42, 15)$ and $\Gamma(\mathbf{r}, \mathbf{C})$ with $\mathbf{C} = (-32, 15)$, respectively (zoom in inset). (f),(g) Joint probability distributions $\Gamma(x_1, y_1, x_2, y_2)$ between pixel pairs located on columns $(x_1 = -5, x_2 = 5)$ and $(x_1 = -30, x_2 = 30)$, respectively (insets show the selected columns). (h) Projection of the JPD along the sum coordinates $\mathbf{r}_1 + \mathbf{r}_2$ (zoom in inset). $M = 10^7$ frames were acquired for reconstructing the JPD. Image coordinate units are in pixels. Note that the very high and very small values observed in the images (a) and (b) originate from hot pixels (see Appendix). The spatial fluctuations visible in the rings in images (a) and (b) originate from the support on which the cat-shaped mask is printed, which is not perfectly reflective. Colorbar units are in number of photons and number of coincidences.

entangled pair. In practice, each frame is composed of many other “ones” resulting from dark-counts events, hot pixels, crosstalk, detection of multiple photon pairs, and stray light falling on the sensor. While hot pixels and cross talk are effects inherent to the electronic architecture of the SPAD camera and can be characterized beforehand to be removed (see Appendix), dark counts, stray light, and the detection of multiple pairs cannot necessarily be monitored in practical imaging situations. All these undesired events produce a large amount of accidental coincidences that dilute the information from genuine coincidences, i.e., coincidence originating from correlations between entangled photon pairs. The absence of any genuine coincidence information in favor of accidentals is clearly visible in Fig. 2(a), which shows the image $\mathcal{C}_M(\mathbf{r}_i, \mathbf{A})$ reconstructed by multiplying the value measured at an arbitrary pixel $\mathbf{A} = (-15, 15)$ by all the others in each frame and then averaging over the set of M frames. To overcome this issue, we use the image processing model detailed in [44] and previously demonstrated with EMCCD cameras [18] in which the joint probability distribution (JPD) $\Gamma(\mathbf{r}_i, \mathbf{r}_j)$ of entangled pairs (i.e., statistics of genuine coincidences) is estimated by multiplying values measured at pixel i in each frame by the difference of values measured at pixel j between two successive frames:

$$\Gamma_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{M} \sum_{\ell=1}^M I_{\ell}(\mathbf{r}_i)[I_{\ell}(\mathbf{r}_j) - I_{\ell-1}(\mathbf{r}_j)], \quad (1)$$

where Γ_M is the estimator of Γ for M measured frames. Equation (1) can be understood by expanding it the form of a subtraction of the term $\mathcal{C}_M(\mathbf{r}_i, \mathbf{r}_j)$ (i.e., the traditional coincidence measure defined above) by another average term $\mathcal{A}_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{M} \sum_{\ell=1}^M I_{\ell}(\mathbf{r}_i)I_{\ell-1}(\mathbf{r}_j)$ (that one may relate to the accidentals). Note that in the rest of the manuscript, notations of the estimators $\{\Gamma_M, \mathcal{C}_M, \mathcal{A}_M\}$ are indicated with those of the corresponding mean values $\{\Gamma, \mathcal{C}, \mathcal{A}\}$ for clarity, except when specified. In Fig. 2(b), an image $\mathcal{A}(\mathbf{r}, \mathbf{A})$ is computed using the second term in the case $\mathbf{r}_j = \mathbf{A}$. At first glance, this image is identical to that shown in Fig. 2(a). However, the subtraction between these two images shown in Fig. 2(c) reveals a coincidence peak positioned at the symmetric position of pixel \mathbf{A} relative to the center. This peak is now only composed of genuine coincidences and the whole image represents a conditional projection $\Gamma(\mathbf{r}, \mathbf{A})$ relative to pixel \mathbf{A} of the JPD of the photon pairs. Indeed, because the minimum time interval between two successive frames acquired by the SPADs ($10.2 \mu\text{s}$) is larger than the coherence time of the photon pairs (~ 10 fs), the probability of detecting two photons from the same entangled pair in two successive images is null. Therefore, the second term in the expansion of Eq. (1) estimates coincidences that originate only from nontemporally correlated events, including dark counts, hot pixels, stray photons, and photons from different pairs, but not those produced by two photons from the same pair. A subtraction between these two terms leaves only an average

value of genuine coincidences that is precisely an estimation of $\Gamma(\mathbf{r}_i, \mathbf{r}_j)$.

B. Spatially-resolved joint probability distribution

The full measured JPD Γ contains up to 500 million coincidence coefficients, which represents a very large amount of information. One way to visualize this is to consider only conditional projections $\Gamma(\mathbf{r}, \mathbf{R})$ relative to a single reference pixel \mathbf{R} , as shown, for example, in Fig. 2(c) for $\mathbf{R} = \mathbf{A}$. Figures 2(d) and 2(e) show examples of two other conditional projections $\Gamma(\mathbf{r}, \mathbf{B})$ and $\Gamma(\mathbf{r}, \mathbf{C})$ relative to two arbitrarily chosen positions $\mathbf{B} = (-42, 15)$ and $\mathbf{C} = (-32, 15)$, respectively. In particular, we observe the absence of a coincidence peak in Fig. 2(e) due to the presence of the object at position $-\mathbf{C}$. To reconstruct and image the object, the intensities of these coincidence peaks are represented as a function of the positions of reference pixels \mathbf{r} , which, for anticorrelated photon pairs, corresponds to projecting the antidiagonal component $\Gamma(\mathbf{r}, -\mathbf{r})$ of the JPD. Images obtained with this method are shown in Figs. 1(d) and 1(e). Beyond conditional and antidiagonal projections, the JPD can also be viewed in a lower-dimensional space by selecting only two columns of pixels of the SPAD camera. For example, Figs. 2(f) and 2(g) show the coincidence distribution between pixels located on pairs of symmetric columns ($x_1 = -5, x_2 = 5$) and ($x_1 = -30, x_2 = 30$), respectively. The presence of an intense coincidence signal across the antidiagonals confirms again the anticorrelation behavior of the photons in the target plane. An exception is the center of the image in Fig. 2(g) because of the presence of the object across column $x_2 = 30$. Interestingly, Fig. 2(f) shows a broadening of the correlation width for pixels far from the center of the ring, an effect that is also visible in the conditional image $\Gamma(\mathbf{r}, \mathbf{B})$ in Fig. 2(d) (see zoom in inset). Such broadening results from the presence of off-axis spherical aberrations in our imaging system that distorts the point spread function (PSF). Finally, projecting the JPD along the sum coordinate $\mathbf{x}_1 + \mathbf{x}_2$ in Fig. 2(h) provides an estimate of the average correlation width, $\sigma = 1.1$ pixels, of entangled pairs, providing, therefore, a quantitative measure of the average spatial resolution of our imaging system [13,14].

Summarizing so far, we have shown that the SPAD array is able to produce a high-quality measurement of the JPD and that this allows a complete mapping of the imaging system PSF. Indeed, not only does it provide information about the object, but it also allows one to characterize the spatial resolution and optical aberrations in the system, which can be used for implementing aberration correction techniques [45,46] (see the Appendix for more details about the JPD projections).

C. Signal-to-noise ratio analysis

The total number of frames, M , acquired by the SPAD camera to reconstruct the JPD strongly influences the performance of our quantum imaging scheme and the quality of the retrieved images. For example, Figs. 3(a) and 3(b) show two coincidence images $\Gamma(\mathbf{r}, -\mathbf{r})$ of the same object retrieved from 2×10^5 and 34×10^5 frames, respectively. We observe that the signal-to-noise ratio (SNR), defined as the average coincidence intensity in a constant region of the image di-

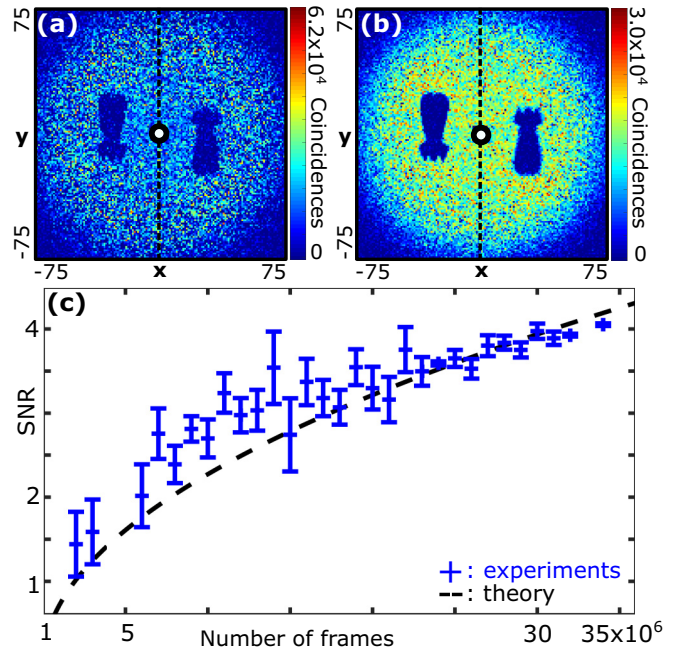


FIG. 3. Signal-to-noise ratio of the coincidence images. Coincidence images $\Gamma(\mathbf{r}, -\mathbf{r})$ reconstructed using (a) $M = 2.10^6$ and (b) $M = 34.10^6$ frames acquired by the SPAD camera showing signal-to-noise ratios $\text{SNR} = 1.4(6)$ and $\text{SNR} = 4.05(9)$, respectively. (c) SNR values in the coincidence image measured for different numbers of frames (blue curve) and a least-squares fit (weighted with the uncertainties) of the form $a\sqrt{N}$ (black dashed line) with best-fit parameter value $a = 7.2 \times 10^{-4}$ with a correlation coefficient of $r^2 = 0.74$. Image coordinate units are in pixels. Color bar units are in number of photons and number of coincidences.

vided by the standard deviation of the noise, is much lower in Fig. 3(a) [$\text{SNR} = 1.4(6)$] than in Fig. 3(b) [$\text{SNR} = 4.05(9)$]. The SNR value is linked to the experimental parameters via

$$\text{SNR} = \frac{\sqrt{\langle N_g \rangle / s}}{\sqrt{1 + 2\langle N_a \rangle / [s\langle N_g \rangle]}} \sqrt{M}, \quad (2)$$

where s is the number of pixels illuminated on the camera; $\langle N_g \rangle = 2\eta^2 \langle m \rangle$ is the average number of genuine coincidences per frame, with η the photon-detection efficiency of the camera and $\langle m \rangle$ is the average number of photon pairs emitted by the source during the time of an exposure; and $\langle N_a \rangle \approx (2\eta \langle m \rangle + \langle n \rangle)^2$ is the average number of accidental coincidences per frame, with $\langle n \rangle$ being the average number of noise events per frame including dark counts and stray photons [see the Appendix for a derivation of Eq. (2)]. When reasoning at a fixed number of frames, M , Eq. (2) captures all underlying mechanisms of our quantum image processing technique. By using a large exposure time and free-running triggering (i.e., not triggering on the pump laser), we effectively enable multiple photon pairs to be detected in each frame, which increases the number of genuine coincidences per frame, and thus the SNR. However, this comes at the price of detecting a large amount of accidental coincidences per frame which, although they are subtracted “on the fly” in Eq. (1), cause an additional noise that decreases the SNR. Figure 3(c) shows that the data

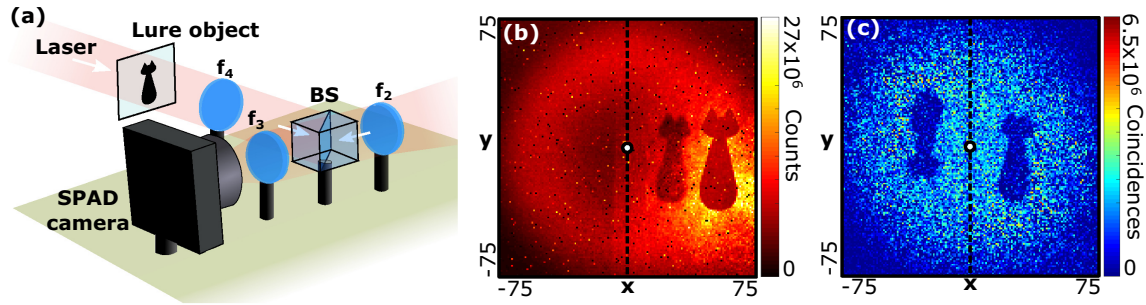


FIG. 4. Robustness to classical noise (stray light). (a) A “noise” image produced by illuminating a lure object by laser light (633 nm) is superimposed onto the quantum signal reflected by the target object on the SPAD camera by adding a beam splitter (BS) and a lens f_4 in the experimental setup. f_4 is positioned at the focal distance from the lure object. (b) The intensity image shows the two cat-shaped objects next to each other on one-half of the sensor. (c) The coincidence image $\Gamma(\mathbf{r}, -\mathbf{r})$ shows only the target object illuminated by entangled photons, with a SNR = 2.1(4). A total of $M = 10^7$ frames were acquired and all coordinate units are in pixels. Colorbar units are in number of photons and number of coincidences.

follow the generic trend of Eq. (2), i.e., that the SNR increases proportionally to \sqrt{M} .

In order to provide some intuition regarding the comparative performance of our quantum imaging approach and of the importance of capturing more than one photon pair per frame, we can compare the results in Fig. 3 to the SNR evaluated for an ideal situation in which the JPD is sampled by detecting, at most, one pair of photons per frame so as not to record any accidental coincidences ($\langle N_a \rangle = 0$). In practice, this could be achieved by triggering the camera from a pulsed pump laser and using a very low-noise sensor (i.e., with negligible dark counts and stray photons). This would give $\text{SNR}^{(id)} = a_t \sqrt{N}$ with $a_t = \eta \sqrt{2\langle m \rangle} / s$ (see the Appendix). We assume the same photon-detection efficiency of the SPAD array, i.e., $\eta = 2.6\%$ (pixel quantum efficiency 25% multiplied by the fill factor 10.5%), and the same number of illuminated pixels, $s \approx 17\,600$ (beam radius of 75 pixels). The number of photon pairs emitted per exposure time (i.e., per pulse) is estimated to be $\langle m \rangle \sim 10^{-4}$ (see the Appendix). The resulting theoretical value in this ideal situation is then $a_t \sim 10^{-6}$ and is two orders of magnitude lower than the value $a = 7.2 \times 10^{-4}$ measured in our experiment [Fig. 3(c)]. Our quantum imaging approach that relies on capturing multiple photon pairs in each frame therefore significantly outperforms a one-pair-by-one-pair coincidence measurement scheme.

III. APPLICATION TO QUANTUM ILLUMINATION

Finally, we show that one important advantage of our quantum imaging protocol is that it is resilient to stray classical light falling on the sensor, including photons emitted by a natural light source as well as artificial light signals possibly created to spoof the target detection [47,48]. This robustness has already been seen with EMCCD measurements [49,50] and is extended here to our SPAD camera-based measurements. A “noise” image is produced by illuminating a similar cat-shaped object using a classical light source [Fig. 3(a)]. This image is positioned next to the image produced by the target object illuminated by quantum light using a beam splitter so that it is impossible to distinguish the “quantum” image from the noise image by performing conventional imaging measurements on the camera [Fig. 4(b)]. However, the noise

image disappears when measuring the coincidence image $\Gamma(\mathbf{r}, -\mathbf{r})$, as shown in Fig. 4(c). Indeed, the use of Eq. (1) to process the set of frames measured by the SPAD camera and to reconstruct the JPD discards all detection events that are not genuinely correlated in time, which is the case for photons emitted by a coherent light source. However, classical light falling on the sensor acts as an additional source of noise, which decreases the SNR in the reconstructed coincidence image, as shown when comparing the SNR in the image of Fig. 4(c) [SNR = 2.1(4)] to that in Fig. 1(e) obtained without stray light [SNR = 4.19(9)] and with the same number of frames. However, the decrease in SNR can be compensated for by acquiring more frames for reconstructing the JPD, as shown in Fig. 3(c).

IV. CONCLUSIONS

In conclusion, we have demonstrated a full-field quantum illumination imaging approach using a 100-kpixel SPAD camera. Imaging is performed using a scheme based on reconstruction of the joint probability distribution (JPD) of the entangled photon pairs that also allows one to characterize optical aberrations and the spatial resolution of the imaging system. We investigated the impact of the number of frames measured by the SPAD on the quality of the reconstructed quantum image and demonstrated that our technique outperforms those based on measuring only one pair per frame, using an equivalent camera and photon-pair source. Finally, we also showed that our quantum imaging protocol is resilient against the presence of stray classical light falling on the sensor.

SPAD cameras are a rapidly growing technology with enormous potential for quantum imaging. Compared to EMCCD cameras, they currently suffer from a lower fill factor and photon-detection efficiency, but provide potential real-world benefits in terms of the frame rate that could enable rapid characterization of entanglement and quantum images. Moreover, the lower SNR that may arise due to the low fill factor (resulting in loss of coincidences due to loss of one photon of a pair) can be offset by acquiring more frames, which in turn is now perfectly feasible in future works due to the potential high camera frame rates, or by use of concentrators or microlenses on the array. Indeed, optimized data transfer

protocols could allow the SwissSPAD2 to operate at its maximum speed (977 000 fps) and thus perhaps reach an effective imaging frame rate of 1 fps (10^6 frames for each coincidence image). Furthermore, note that there are also other research SPAD cameras that can be operated at higher speed up to 800 000 fps [51] and even some commercial models (e.g., PhotonForce) that can reach 300 000 fps. One may thus envisage, in the future, building a quantum video camera. In addition, the time-gating capability of the SPAD camera could possibly be combined with our quantum imaging protocol to provide depth information for LiDAR application, potentially using a different configuration in which one photon is kept stored on the emitter side, while the other is sent towards the object [52–54]. Beyond imaging, the ability to rapidly measure and extract information from photon coincidences performed between many pixels in parallel is essential for the development of high-dimensional quantum information processing technologies, including high-dimensional quantum communication and computation schemes [55,56].

All data relevant to this work are available from Ref. [57]. Additional data and codes may be requested from the corresponding authors upon reasonable request.

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APPENDIX

Details of the experimental setup. The nonlinear crystal is a β -barium-borate crystal of size $5 \times 5 \times 1$ mm cut for type-I phase-matched SPDC pumped at 355 nm with a half opening angle of 3 degrees (Newlight Photonics). The pump is the third harmonic at 347 nm of a femtosecond pulsed laser with 100 MHz repetition rate, 80 mW average power, and beam diameter of approximately 0.5 mm (Chromacity). The average number of photon pairs produced per pulse is of the order of 10^{-4} (10^4 photons per second). This number was estimated from an intensity measurement performed without an object and accounting for the sensor noise (characterized beforehand) and photon-detection efficiency ($\eta = 2.6\%$).

Details of the Γ measurement. Equation (1) estimates the spatial JPD Γ from a finite number of frames M acquired with the SPAD camera. This equation is derived from a theoretical model of photon-pair detection detailed in [44]. In this work, a

link is established between the JPD and the measured frames at the limit $N \rightarrow +\infty$:

$$\Gamma(\mathbf{r}_i, \mathbf{r}_j) = A \ln \left(1 + \frac{\langle I(\mathbf{r}_i)I(\mathbf{r}_j) \rangle - \langle I(\mathbf{r}_i) \rangle \langle I(\mathbf{r}_j) \rangle}{(1 - \langle I(\mathbf{r}_i) \rangle)(1 - \langle I(\mathbf{r}_j) \rangle)} \right), \quad (\text{A1})$$

where A is a constant coefficient that depends on both the quantum efficiency of the sensor and the power of the pump laser, and

$$\langle I(\mathbf{r}_i)I(\mathbf{r}_j) \rangle = \lim_{N \rightarrow +\infty} \frac{1}{N} \sum_{l=1}^N I_l(\mathbf{r}_i)I_l(\mathbf{r}_j), \quad (\text{A2})$$

$$\langle I(\mathbf{r}_i) \rangle = \lim_{N \rightarrow +\infty} \frac{1}{N} \sum_{l=1}^N I_l(\mathbf{r}_i). \quad (\text{A3})$$

Equation (A1) is obtained under hypotheses [44] that are all verified in our work, including that (i) the quantum efficiency is the same for all pixels of the sensor and (ii) the number of pairs produced by SPDC during the exposure time follows a Poisson distribution [58]. Moreover, in our experiment, the probability of detecting a photon per pixel per frame is much lower than one ($\langle I(\mathbf{r}) \rangle \ll 1$), which allows us to express Eq. (A1) as follows:

$$\Gamma(\mathbf{r}_i, \mathbf{r}_j) \approx \langle I(\mathbf{r}_i)I(\mathbf{r}_j) \rangle - \langle I(\mathbf{r}_i) \rangle \langle I(\mathbf{r}_j) \rangle. \quad (\text{A4})$$

In the practical case where only a finite number of frames M is measured, the first term on the right-hand side in Eq. (A4) is estimated by multiplying pixel values within the same frame,

$$\langle I(\mathbf{r}_i)I(\mathbf{r}_j) \rangle \approx \mathcal{C}_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{N} \sum_{l=1}^N I_l(\mathbf{r}_i)I_l(\mathbf{r}_j). \quad (\text{A5})$$

The second term on the right-hand side of Eq. (A4) is estimated by multiplying the pixel values between successive frames,

$$\langle I(\mathbf{r}_i) \rangle \langle I(\mathbf{r}_j) \rangle \approx \mathcal{A}_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{N} \sum_{l=1}^N I_l(\mathbf{r}_i)I_{l-1}(\mathbf{r}_j). \quad (\text{A6})$$

Combining Eqs. (A4)–(A6) finally leads to Eq. (1).

Projections of the JPD. In our experiment, the measured JPD Γ takes the form of a four-dimensional matrix containing $(150 \times 150)^2 \approx 5 \times 10^8$ elements, where 150×150 corresponds to the size of the illuminated region of the camera sensor. The information content of Γ is analysed using four types of projections:

(1) The sum-coordinate projection, defined as

$$\Gamma_+(\mathbf{r}_1 + \mathbf{r}_2) = \sum_{\mathbf{r}} \Gamma(\mathbf{r}_1 + \mathbf{r}_2 - \mathbf{r}, \mathbf{r}). \quad (\text{A7})$$

It represents the probability of detecting pairs of photons generated in all symmetric directions relative to the mean position $\mathbf{r}_1 + \mathbf{r}_2$.

(2) The minus-coordinate projection, defined as

$$\Gamma_-(\mathbf{r}_1 - \mathbf{r}_2) = \sum_{\mathbf{r}} \Gamma(\mathbf{r}_1 - \mathbf{r}_2 + \mathbf{r}, \mathbf{r}). \quad (\text{A8})$$

This represents the probability for two photons of a pair to be detected in coincidence between pairs of pixels separated by

an oriented distance $\mathbf{r}_1 - \mathbf{r}_2$. In our work, this projection is used to characterize the crosstalk (see next section).

(3) A conditional image $\Gamma(\mathbf{r}_1|\mathbf{r}_2)$ is a slice of Γ normalized to its marginal probability,

$$\Gamma(\mathbf{r}_1|\mathbf{r}_2) = \frac{\Gamma(\mathbf{r}_1, \mathbf{r}_2)}{\sum_{\mathbf{r}_1} \Gamma(\mathbf{r}_1, \mathbf{r}_2)}. \quad (\text{A9})$$

It represents the probability of detecting one photon at position \mathbf{r}_1 given that the other arrives at position \mathbf{r}_2 . When the marginal probability is almost uniform, one may use either $\Gamma(\mathbf{r}_1|\mathbf{r}_2)$ or $\Gamma(\mathbf{r}_1, \mathbf{r}_2)$ as the conditional projection.

(4) A projection of Γ onto two columns of pixels located at x_1 and x_2 is defined as

$$\Gamma_{x_1x_2}(y_1, y_2) = \Gamma(x_1, y_1, x_2, y_2). \quad (\text{A10})$$

Similarly, a projection of Γ onto two rows of pixels located at y_1 and y_2 is defined as

$$\Gamma_{y_1y_2}(x_1, x_2) = \Gamma(x_1, y_1, x_2, y_2). \quad (\text{A11})$$

These projections are bidimensional joint probability distributions between two horizontal (or vertical) spatial axes.

Derivation of the SNR. The derivation of Eq. (2) is divided in four sections. In the first section, we further expand the expression of the measured JPD Γ_M [Eq. (1)] under the form of the summation of three terms associated with accidental and genuine coincidences. In the second section, we identify signal and noise in each term treated separately, to finally infer the SNR of Γ_M in the third section. In the fourth section, we derive the SNR in the case of an ideal coincidence measurement scheme (no accidentals). Throughout the demonstration, we consider that Γ_M is reconstructed from a set of $M + 1$ frames measured by the SPAD camera. Each frame I_ℓ ($\ell \in \llbracket 0; M \rrbracket$) is composed of $s = \sqrt{s} \times \sqrt{s}$ pixels of binary values $\{0, 1\}$. This derivation is inspired from the derivation of SNR formulas in the case of EMCCD cameras and multi-element detector arrays [59–61].

1. Rewriting of Eq. (1) with genuine and accidental coincidences

We consider the expanded form of Eq. (1),

$$\Gamma_M(\mathbf{r}_i, \mathbf{r}_j) = \mathcal{C}_M(\mathbf{r}_i, \mathbf{r}_j) - \mathcal{A}_M(\mathbf{r}_i, \mathbf{r}_j), \quad (\text{A12})$$

in which we rewrite each term \mathcal{C}_M and \mathcal{A}_M as

$$\mathcal{C}_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{M} \sum_{\ell=1}^M I_{\ell\ell}(\mathbf{r}_i, \mathbf{r}_j), \quad (\text{A13})$$

$$\mathcal{A}_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{M} \sum_{\ell=1}^M I_{\ell(\ell-1)}(\mathbf{r}_i, \mathbf{r}_j). \quad (\text{A14})$$

$I_{\ell\ell}$ and $I_{\ell(\ell-1)}$ are two new quantities called the ℓ th coincidence frame and the ℓ th cross-coincidence frame, respectively. They are defined via

$$I_{\ell\ell}(\mathbf{r}_i, \mathbf{r}_j) = I_\ell(\mathbf{r}_i)I_\ell(\mathbf{r}_j), \quad (\text{A15})$$

$$I_{\ell(\ell-1)}(\mathbf{r}_i, \mathbf{r}_j) = I_\ell(\mathbf{r}_i)I_{\ell-1}(\mathbf{r}_j). \quad (\text{A16})$$

A coincidence image $I_{\ell\ell}$ is composed of s^2 pixel-pair binary values $\{0, 1\}$. When a given pixel pair $(\mathbf{r}_i, \mathbf{r}_j)$ of $I_{\ell\ell}$ displays a value of 1, it means that both pixels \mathbf{r}_i and \mathbf{r}_j have recorded

a detection event during the acquisition of the frame I_ℓ , i.e., $I_{\ell\ell}(\mathbf{r}_i, \mathbf{r}_j) = 1 \Leftrightarrow I_\ell(\mathbf{r}_i) = 1 \wedge I_\ell(\mathbf{r}_j) = 1$. This so-called coincidence detection event is either a (a) *genuine coincidence* or (b) *accidental coincidence*. A genuine coincidence is a coincidence event that originates from the detection of two photons from the same entangled pair. An accidental coincidence is a coincidence event that originates from the detection of two photons from two different entangled pairs, or from one photon from a pair and a noise event, or from two noise events. Noise events include dark noise, stray photon, and single photon remaining after the absorption of one photon from a pair. Using these definitions, a coincidence event is either a genuine or an accidental coincidence, but cannot be both or something else. Each coincidence frame $I_{\ell\ell}$ can then be uniquely written as

$$I_{\ell\ell} = I_{\ell\ell}^G + I_{\ell\ell}^A, \quad (\text{A17})$$

where $I_{\ell\ell}^G$ contains only the genuine coincidences and $I_{\ell\ell}^A$ only the accidental coincidences.

Furthermore, a cross-coincidence image $I_{\ell(\ell-1)}$ is also composed of s^2 pixel-pair binary values $\{0, 1\}$. When a given pixel pair $(\mathbf{r}_i, \mathbf{r}_j)$ of $I_{\ell(\ell-1)}$ displays a value of 1, it means that the pixels \mathbf{r}_i and \mathbf{r}_j from two successive frames I_ℓ and $I_{\ell-1}$ have recorded a detection event during their respective acquisition time, i.e., $I_{\ell(\ell-1)}(\mathbf{r}_i, \mathbf{r}_j) = 1 \Leftrightarrow I_\ell(\mathbf{r}_i) = 1 \wedge I_{\ell-1}(\mathbf{r}_j) = 1$. However, because the time between two successive frames ($1 \mu\text{s}$) is larger than the coherence time of the photon pairs (~ 10 fs), these coincidence detections are only accidentals. We then use the following notation for $I_{\ell(\ell-1)}$:

$$I_{\ell(\ell-1)} = I_{\ell(\ell-1)}^A. \quad (\text{A18})$$

Finally, these new notations allow us to write the measured JPD Γ_M as

$$\Gamma_M = \frac{1}{M} [G_M + A'_M - A_M], \quad (\text{A19})$$

where

$$G_M(\mathbf{r}_i, \mathbf{r}_j) = \sum_{\ell=1}^M I_{\ell\ell}^G(\mathbf{r}_i, \mathbf{r}_j), \quad (\text{A20})$$

$$A'_M(\mathbf{r}_i, \mathbf{r}_j) = \sum_{\ell=1}^M I_{\ell\ell}^A(\mathbf{r}_i, \mathbf{r}_j), \quad (\text{A21})$$

$$A_M(\mathbf{r}_i, \mathbf{r}_j) = \sum_{\ell=1}^M I_{\ell(\ell-1)}^A(\mathbf{r}_i, \mathbf{r}_j). \quad (\text{A22})$$

2. Signal and noise associated with G_M , A'_M , and A_M

Using the quantities defined in Eqs. (A20)–(A22), the SNR of Γ_M can be written as

$$\text{SNR}_M = \frac{G_M + A'_M - A_M}{\sqrt{\Delta G_M^2 + \Delta A'^2_M + \Delta A_M^2}}, \quad (\text{A23})$$

where ΔG_M^2 , $\Delta A'^2_M$, and ΔA_M^2 are the variances associated with the measured quantities G_M , A'_M , and A_M , respectively. Equation (A23) is obtained by assuming that all the terms G_M , A_M , or A'_M are statistically independent from each other. This is verified for G_M with respect to A'_M or A_M because any coincidence event is either an accidental or a genuine

coincidence, and cannot be both. However, the two terms A_M and A'_M are not totally independent because they are calculated using a common frame I_ℓ . To strictly ensure their independence, one would need to compute the two terms $\mathcal{C}_M(\mathbf{r}_1, \mathbf{r}_2)$ and $\mathcal{A}_M(\mathbf{r}_1, \mathbf{r}_2)$ using two different set of M frames. In the following, we will consider this situation and treat them as independent. Note that this assumption does not change the dependence of the SNR on the square root of the number of frame $\text{SNR} \sim \sqrt{M}$, or the qualitative roles played by the total number of genuine and accidental coincidences in the prefactor of Eq. (2), which are the two points we used in our work to draw our conclusions.

Genuine coincidence term. Since it is only composed of genuine coincidences, the term G_M is, by definition, an estimator of the JPD Γ . After acquiring M frames, the value $G(\mathbf{r}_i, \mathbf{r}_j)$ returned at a given pixel pair (i, j) can therefore be expressed as

$$G_M(\mathbf{r}_i, \mathbf{r}_j) = \langle N_g \rangle M \Gamma(\mathbf{r}_i, \mathbf{r}_j), \quad (\text{A24})$$

where $\langle N_g \rangle$ is the average total number of genuine coincidences per coincidence frame. $\langle N_g \rangle$ can be written as a function of the quantum efficiency η of the sensor and the average total number of pairs produced during the time of an exposure $\langle m \rangle$,

$$\langle N_g \rangle = 2\eta^2 \langle m \rangle. \quad (\text{A25})$$

Equation (A24) corresponds exactly to the well-known problem of sampling a probability distribution Γ using M successive measurements, each containing $\langle N_g \rangle$ detection events on average. Because $\langle N_g \rangle \ll s$, we can assume that the number of genuine coincidences produced per frame follows a Poisson distribution and has a square-root relationship between the signal and noise,

$$\Delta G_M^2(\mathbf{r}_i, \mathbf{r}_j) = \langle N_g \rangle M \Gamma(\mathbf{r}_i, \mathbf{r}_j). \quad (\text{A26})$$

Accidental coincidence terms. Since it is only composed of accidental coincidences, the terms A'_M and A_M are two independent estimators of the product of marginal probability distributions $\Gamma(\mathbf{r}_i)\Gamma(\mathbf{r}_j)$, where $\Gamma(\mathbf{r}_i) = \sum_{r_j} \Gamma(\mathbf{r}_i, \mathbf{r}_j)$. After acquiring M frames, the values $A_M(\mathbf{r}_i, \mathbf{r}_j)$ and $A'_M(\mathbf{r}_i, \mathbf{r}_j)$ returned at a given pixel pair (i, j) can therefore be expressed as

$$A'_M(\mathbf{r}_i, \mathbf{r}_j) \approx A_M(\mathbf{r}_i, \mathbf{r}_j) = \langle N_a \rangle M \Gamma(\mathbf{r}_i)\Gamma(\mathbf{r}_j), \quad (\text{A27})$$

where $\langle N_a \rangle$ is the average total number of accidental coincidence per frame. In Eq. (A27), we used the fact that in our experiment, the number of genuine coincidences per frame is negligible compared to the number of accidental coincidences, $\langle N_g \rangle \ll \langle N_a \rangle$, which allows us to consider that the average number of accidentals in the coincidence frames equals the number of accidentals in the cross-coincidence frames. As shown in Figs. 2(a)–2(c), this assumption is verified in our experiment. The average total number of accidental coincidences can then be written as the square of the average total number of detection events per frame,

$$\langle N_a \rangle = (2\eta^2 \langle m \rangle + 2\eta(1 - \eta)\langle m \rangle + \langle n \rangle)^2 \quad (\text{A28})$$

$$= (2\eta \langle m \rangle + \langle n \rangle)^2, \quad (\text{A29})$$

where the term $2\eta^2 m$ corresponds to the total number of detections per frame that originate from whole entangled pairs, $2\eta(1 - \eta)m$ is the total number of detections per frame that originate from single photons created after absorption of one of the two photons from a pair, and $\langle n \rangle$ is the average total number of noise events per frame (dark noise and stray light). Because $\langle N_a \rangle \ll s^2$, we can assume that the number of accidental coincidences produced per frame follows a Poisson distribution and has a square-root relationship between the signal and noise,

$$\Delta A'^2_M(\mathbf{r}_i, \mathbf{r}_j) = \Delta A^2_M(\mathbf{r}_i, \mathbf{r}_j) = \langle N_a \rangle M \Gamma(\mathbf{r}_i, \mathbf{r}_j). \quad (\text{A30})$$

Finally, combining Eqs. (A23), (A24), (A26), (A27), and (A30) enables one to write the SNR of the measure JPD Γ_M at a given pair of pixels $(\mathbf{r}_i, \mathbf{r}_j)$ via

$$\text{SNR}_M(\mathbf{r}_i, \mathbf{r}_j) = \frac{\sqrt{\langle N_g \rangle \Gamma(\mathbf{r}_i, \mathbf{r}_j)}}{\sqrt{1 + 2 \frac{\langle N_a \rangle \Gamma(\mathbf{r}_i)\Gamma(\mathbf{r}_j)}{\langle N_g \rangle \Gamma(\mathbf{r}_i, \mathbf{r}_j)}}} \sqrt{M}. \quad (\text{A31})$$

3. SNR in our experiment

In our experiment, entangled photon pairs measured by the SPAD camera are anticorrelated (i.e., far field of the crystal) with a correlation width of approximately 1 pixel [Fig. 2(h)]. We can then consider that Γ takes the form of

$$\Gamma(\mathbf{r}_i, \mathbf{r}_j) = \frac{1}{s} \delta(\mathbf{r}_i + \mathbf{r}_j), \quad (\text{A32})$$

where s is the number of pixels uniformly illuminated by the photon-pair beam. As a result, the product of the marginal probability distributions takes the following form:

$$\Gamma(\mathbf{r}_i)\Gamma(\mathbf{r}_j) = \frac{1}{s^2}. \quad (\text{A33})$$

Finally, the SNR between symmetric pairs of pixels $(\mathbf{r}, -\mathbf{r})$ written in Eq. (2) is obtained by combining Eqs. (A32), (A33), and (A31).

4. SNR in an ideal measurement scheme

In an ideal coincidence measurement scheme, the JPD is sampled by detecting, at most, one pair of photons per frame so as not to record any accidental coincidences ($\langle N_a \rangle = 0$). In practice, this is achieved by triggering the camera on the pump laser frequency and using a very low-noise sensor (i.e., dark counts are negligible). In this case, only the term $\mathcal{C}_M(\mathbf{r}_1, \mathbf{r}_2)$ needs to be calculated to estimate the JPD Γ . The SNR between a given pixel pair $(\mathbf{r}_i, \mathbf{r}_j)$ then becomes

$$\text{SNR}_M^{(\text{id})}(\mathbf{r}_i, \mathbf{r}_j) = \sqrt{2\eta^2 \langle m \rangle \Gamma(\mathbf{r}_i, \mathbf{r}_j) M}. \quad (\text{A34})$$

Assuming that photon pairs are perfectly anticorrelated over an illuminated area containing s pixels, we combine Eqs. (A32) and (A34) to calculate the SNR between symmetric pixels in an ideal coincidence measurement scheme,

$$\text{SNR}_M^{(\text{id})}(\mathbf{r}, -\mathbf{r}) = \eta \sqrt{2 \langle m \rangle / s M}. \quad (\text{A35})$$

Hot pixels and crosstalk. *Hot pixels:* Figure 5(a) shows a 100×100 pixels image acquired by the SPAD camera with the shutter closed (no photons falling on the sensor). The bright pixels with value above 200 are considered to be hot pixels of the sensor (pixel values are encoded here in

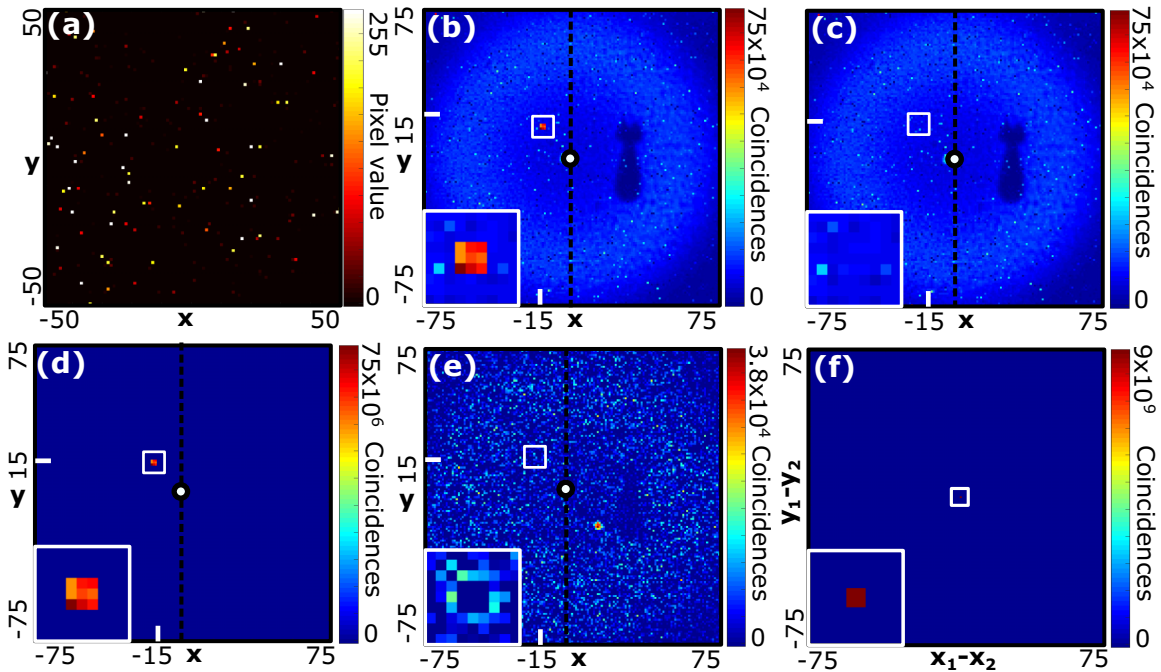


FIG. 5. (a) Single SPAD image acquired with no light falling on the sensor (shutter closed). (b) Image $\mathcal{C}(\mathbf{r}, \mathbf{A})$ reconstructed by multiplying the value measured at pixel $\mathbf{A} = (-15, 15)$ in each frame by all values of the other pixels in the same frame and then averaging over the set, without removing the crosstalk effect. (c) Image $\mathcal{A}(\mathbf{r}, \mathbf{A})$ reconstructed by multiplying the value measured at pixel \mathbf{A} in each frame by all values of the other pixels in the next frame and then averaging over the set, without removing the crosstalk effect. (d) Conditional image $\Gamma(\mathbf{r}, \mathbf{A})$ obtained by subtracting (b) by (c), showing a peak of crosstalk at position \mathbf{A} (zoom in inset). (e) Conditional image $\Gamma(\mathbf{r}, \mathbf{A})$ after crosstalk removal. (f), Projection of the measured JPD on the minus coordinates $\mathbf{r}_1 - \mathbf{r}_2$. Colorbar units are in number of photons and number of coincidences.

eight-bits). In the SPAD camera used in our experiment, they represent approximately 2% of the total number of pixels. To remove them, we define a threshold at 200 and set all pixel values above this threshold in each frame to 0.

Crosstalk: Crosstalk is a phenomenon by which, when a pixel detects a photon, it has a nonzero probability of also triggering its neighboring pixels. Therefore, crosstalk produces strong correlations between pixels, which is an important issue when one also wants to use the camera for measuring photon correlations. For example, Figs. 5(b) and 5(c) show the images $\mathcal{C}(\mathbf{r}, \mathbf{A})$ and $\mathcal{A}(\mathbf{r}, \mathbf{A})$. These images are exactly the same as those shown in Figs. 2(b) and 2(c), but before removing the crosstalk effects. In Fig. 5(b), which is obtained by multiplying pixel values pairwise within the same frame, we observe the presence of a peak composed of 3×3 pixels centered around \mathbf{A} . This peak is a signature of crosstalk

effects between direct neighboring pixels, and is thus absent in Fig. 5(c), which is obtained by multiplying pixel values pairwise between different frames. As shown in Fig. 5(d), the crosstalk peak dominates all the information contained in the resulting conditional image $\Gamma(\mathbf{r}, \mathbf{A}) = \mathcal{C}(\mathbf{r}, \mathbf{A}) - \mathcal{A}(\mathbf{r}, \mathbf{A})$. In all the measurements reported in this manuscript, the crosstalk effects are removed by setting the reference pixel \mathbf{A} together with its nine neighboring pixels $\mathbf{A} \pm \mathbf{e}_x \pm \mathbf{e}_y$ to 0 [Fig. 5(e)]. This operation is applied to all of the conditional images that composed the measured JPD. Finally, Fig. 5(f) shows a projection of the measured JPD on the minus coordinates $\mathbf{r}_1 - \mathbf{r}_2$, which enables one to characterize quantitatively the average crosstalk effect of the sensor. A peak of width 2×2 pixels, shown in the inset, confirms that crosstalk is present only between a given pixel and its direct neighbors.

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