

Transfer-matrix theory of surface spin-echo experiments with moleculesJ. T. Cantin^{1,*}, G. Alexandrowicz,^{2,3} and R. V. Krems¹¹*Department of Chemistry, University of British Columbia, Vancouver, BC, Canada V6T 1Z1*²*Schulich Faculty of Chemistry, Technion–Israel Institute of Technology, Technion City, Haifa 32000, Israel*³*Department of Chemistry, Swansea University, Singleton Park, Swansea SA2 8PP, Wales, United Kingdom*

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³He beam spin-echo experiments have been used to study surface morphology, molecular and atomic surface diffusion, phonon dispersions, phason dispersions, and phase transitions of ionic liquids. However, the interactions between ³He atoms and surfaces or their adsorbates are typically isotropic and weak. To overcome these limitations, one can use molecules instead of ³He in surface spin-echo experiments. The molecular degrees of freedom, such as rotation, may be exploited to provide additional insight into surfaces and the behavior of their adsorbates. Indeed, a recent experiment has shown that orthohydrogen can be used as a probe that is sensitive to the orientation of a Cu(115) surface [O. Godsi, G. Corem, Y. Alkoby, J. T. Cantin, R. V. Krems, M. F. Somers, J. Meyer, G.-J. Kroes, T. Maniv, and G. Alexandrowicz, *Nat. Commun.* **8**, 15357 (2017)]. However, the additional degrees of freedom offered by molecules also pose a theoretical challenge: a large manifold of molecular states and magnetic-field-induced couplings between internal states. Here, we present a fully quantum-mechanical approach to model molecular surface spin-echo experiments and connect the experimental signal to the elements of the time-independent molecule-surface scattering matrix. We present a one-dimensional transfer-matrix method that includes the molecular hyperfine degrees of freedom and accounts for the spatial separation of the molecular wave packets due to the magnetic control fields. We apply the method to the case of orthohydrogen, show that the calculated experimental signal is sensitive to the scattering matrix elements, and perform a preliminary comparison to experiment. This paper sets the stage for Bayesian optimization to determine the scattering matrix elements from experimental measurements and for a framework that describes molecular surface spin-echo experiments to study dynamic surfaces.

DOI: [10.1103/PhysRevA.101.062703](https://doi.org/10.1103/PhysRevA.101.062703)**I. INTRODUCTION**

A major thrust of recent experimental work has been to achieve control over the longitudinal motion of atomic and molecular beams [1–8]. Controlled beams can be used for a variety of applications, ranging from loading molecules into traps [9–11], to measuring cross sections for molecular scattering with extremely high energy resolution [12–15], to precision spectroscopy [16–18], to controlled chemistry [19]. The development of methods for the initial state selection and control over both the longitudinal and transverse motion of molecular beams has also paved the way for matter-wave interferometry [20–22], nanolithography [23–25], and precision studies of molecule-surface scattering. Although molecule-surface collisions have been a subject of numerous studies [26–29], combining the latest advances in molecular-beam control with surface scattering experiments opens opportunities for probing new regimes of molecule-surface energy exchange and obtaining detailed information about surface properties. This is well exemplified by ³He spin-echo (HeSE) experiments [30–33] aiming to probe the structure of surfaces, as well as quantum matter adsorbed on surfaces, by scattering a beam of ³He in superpositions of nuclear-spin states off a surface and observing the perturbation of the resulting

interferometry signal. Analogous to neutron spin-echo experiments [34,35], HeSE experiments have been shown to detect the impact of gravity (on the energy scale of ≈ 10 neV) on the kinetic energy of atoms in the beam [30]. When used to study surfaces, HeSE experiments can be classified as a subset of quasielastic helium atom scattering experiments [26]. Surface-sensitive HeSE experiments [31–33] have been used to study surface morphology [36], molecular and atomic surface diffusion [32,33,37–41], interadsorbate forces [38,42], phonon dispersions [32,33,43], phason dispersions [44], structures and phase transitions of ionic liquids [45], and friction between adsorbates and surfaces [46–48]. HeSE experiments have provided information about potential-energy surfaces [32,33,49] and surface-adsorbate interactions [32,33,50] and are frequently combined with microscopic calculations to both test theory and gain insight into surface-adsorbate interactions [39,51,52].

The use of ³He as probe particles in HeSE experiments can sometimes be limited by the weak interaction strength between ³He and surfaces or their adsorbates. In addition, ³He offers no internal degrees of freedom to absorb energy or induce anisotropic interactions. Therefore, an important recent goal has been to extend surface spin-echo experiments to molecular beams [53]. Molecules offer rotational degrees of freedom and anisotropic, state-dependent interactions, which could be exploited to gain new insights into surface dynamics. For example, it was recently shown that orthohydrogen (*o*-H₂) can be used as a sensitive probe of surface morphology

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[53]: the experiment was able to discern how the interaction between an o -H₂ molecule and a Cu(115) surface depends on the orientation of the rotational plane of the hydrogen molecule relative to the surface. In addition, one could exploit the transfer of rotational energy from the probe molecules to surface adsorbates (or vice versa) in order to study the relative effects of the rotational and translational motion on the dynamics of the adsorbates. However, the increased complexity of molecules (compared to ³He atoms) makes the analysis of the spin-echo experiments complicated and requires one to account for the interplay of the translational, nuclear-spin, and rotational degrees of freedom in strong magnetic fields of differing orientations, in addition to the molecule-surface scattering event.

Surface spin-echo experiments with molecules involve passing a molecular beam through a series of magnetic fields to control molecular wave packets before and after the scattering event. A proper analysis of the resulting experimental signal must be based on (i) the solutions of the time-dependent Schrödinger equation accounting for the development of entanglement between the translational motion and the internal states of molecules in the beam, as the beam transverses the magnetic fields of the spin-echo apparatus, and (ii) the description of the molecule-surface scattering events in the relevant frame of reference by the scattering matrix involving all relevant molecular states. This is a challenging task because the potential-energy surfaces for molecule-surface interactions are difficult to compute with sufficient accuracy [54–60], the calculations of the cross sections for molecule-surface scattering are extremely time consuming [61,62], and the orientation and strength of magnetic fields necessarily change throughout the spin-echo apparatus. An alternative formulation can be developed to treat the molecule-surface scattering matrix elements as varying parameters to be determined from the experimental interferometry signal by one of the algorithms used in optimal control theory [63–68] or reinforcement machine learning designed to solve the inverse problem [69,70]. In order for such a formulation to be practical, it is necessary to develop a rigorous method for the description of molecular dynamics inside the spin-echo apparatus, before and after the molecular wave packets interact with the surface. This method must be efficient to allow for multiple feedback control loops, be accurate to ensure the proper description of interferometry dynamics, and integrate rigorously the surface scattering matrix amplitudes into the resulting output signal.

In this paper, we exploit the transfer-matrix method [71,72] to develop such a theoretical framework. The transfer-matrix method [71,72] has been applied in various fields, such as for solving the two-dimensional (2D) Ising model in statistical mechanics [73], calculating reflection and transmission coefficients in optics [74] and mesoscopic quantum transport [75], determining photonic band structures [76], and examining the tunneling of a molecule through potential barriers [77,78]. The general and efficient framework we present can be used to analyze the coherent propagation of closed-shell molecules through a series of static magnetic fields with different magnitudes and orientations, as well as through one or more scattering events.

We apply this framework to surface-sensitive interferometry experiments that use closed-shell molecules to study static surfaces. Specifically, we develop a fully quantum-mechanical model of surface-sensitive molecular hyperfine interferometry experiments by deriving a one-dimensional transfer-matrix method that includes the internal hyperfine degrees of freedom of the probe molecules and that accounts for the eigenbasis changes between local regions of the magnetic field. We account for the experimental geometry with rotation matrices and describe the molecule-surface interaction with a scattering transfer matrix (a transformed version of the standard scattering matrix).

The method is applied to an o -H₂ hyperfine interferometry experiment. By comparing the theoretical results with experimental measurements, we illustrate the importance of integrating over the velocity distribution of molecules in the beam. We further show that information about the scattering matrix elements is encoded in the experimental signal. In particular, we demonstrate that the experimental signal is sensitive to the magnitude and phase of the diagonal elements of the scattering transfer matrix. We also show that the signal is sensitive to scattering events that change the projection quantum numbers of the molecular hyperfine states. Such dynamical processes are described by scattering transfer matrices with nonzero diagonal and off-diagonal matrix elements. This sets the stage for determining, in part or in whole, the scattering transfer-matrix elements of a particular molecule-surface interaction by comparing the computed and experimentally measured signals.

Finally, we compare our method with a semiclassical method, which is described briefly in the supplementary material of Ref. [53] for o -H₂ and in more detail in Ref. [79] for spin-1/2 particles. Within this semiclassical method, the internal molecular degrees of freedom are treated quantum mechanically, while the center-of-mass degree of freedom is treated classically. Through this comparison, we demonstrate that the present method can be extended to study *dynamic*, instead of static, surfaces by surface spin-echo experiments with molecules.

The remainder of this paper is organized as follows. In Sec. II, we describe a generic molecular hyperfine interferometry experiment. We then discuss, in Sec. III, the molecular state after the state-selecting magnetic lens. In Sec. IV, we time evolve the molecular state and integrate the result over the length of the detection window to obtain the relationship between the system eigenstates and the detector current. To obtain the system eigenstates, we derive and apply, in Sec. V, a transfer-matrix formalism that includes internal degrees of freedom. We also discuss the rotation and scattering transfer matrices used to account for the apparatus geometry and the molecule-surface interaction, respectively. In Sec. VI, we demonstrate the application of this theoretical framework to the case of o -H₂, illustrate the need to integrate over the velocity distribution, illustrate the sensitivity of the calculated signal to various features of the scattering transfer matrix, and perform a preliminary comparison with experiment. We compare the method of the present paper to the semiclassical method discussed by Godsi *et al.* [53] in Sec. VII. Section VIII concludes the paper.

II. DESCRIPTION OF A MOLECULAR HYPERFINE INTERFEROMETRY EXPERIMENT

A surface-sensitive molecular hyperfine interferometer uses a beam of molecules to probe various surface properties. To do this, a set of magnetic fields is used to simultaneously manipulate the internal hyperfine states of the probe molecules and create a spatial superposition of molecular wave packets. These wave packets sequentially impact the sample surface and scatter in all directions. A second set of magnetic fields collects the molecules scattered in a narrow solid angle. This second set of magnetic fields further manipulates the molecular wave packets, partially recombining them and allowing for molecular self-interference. Wave packets with particular hyperfine states are then passed into a detector. A schematic of the experiment is depicted in Fig. 1. We now discuss the different stages of the experiment in more detail.

The beam source must produce a continuous (or pulsed) beam of molecules with a sufficiently narrow velocity profile, mean velocity suitable for a particular experiment, sufficiently high flux, and a density low enough to ensure that the molecules are noninteracting. One current apparatus [53] uses a supersonic expansion to produce such a beam. One can also envision experiments with slow molecular beams produced by extraction (sometimes with hydrodynamic enhancement) from a buffer-gas cooled cell [9] or with molecular beams controlled by electric-field [80] or magnetic-field deceleration [81]. Deceleration provides control over the mean velocity and narrows the velocity spread [1], which could be exploited for novel interferometry-based applications.

The experiment selects molecules in particular hyperfine states by employing a magnetic lens the magnetic field of

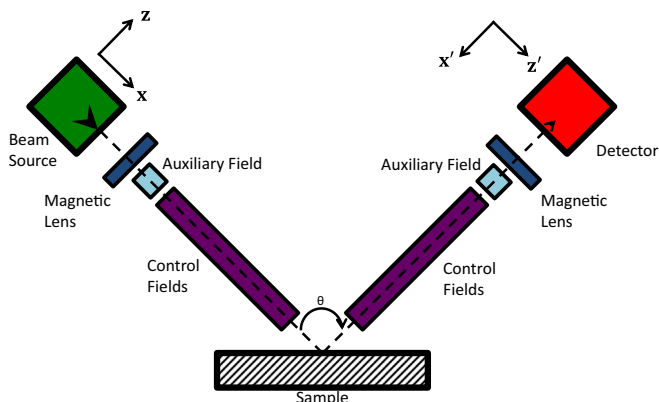


FIG. 1. A generic molecular hyperfine interferometer consists of a beam source (green), magnetic lenses (dark blue), auxiliary fields (light blue), control fields (purple), the sample (hatched rectangle) in an ultra-high-vacuum chamber, and the detector (red). See Sec. II for more details on each component. The arrows and dashed line indicate the direction and path of the molecular beam, which is initially along the $+x$ direction and then along the $-x'$ direction after scattering. The two branches of the apparatus are separated by an angle θ . z and z' denote the direction of the quantization axes before and after scattering, respectively. This definition of the quantization axes has been chosen to match the experiment by Godsi *et al.* [53] and to simplify rotating the quantization axes in the transfer-matrix method. The y and y' axes are identical and point into the page.

which has a gradient in the radial direction. A cylindrically symmetric field gradient is used to ensure sufficient molecular flux. The lens focuses molecules with low-field seeking states and defocuses molecules with high-field seeking states, allowing for purification of the molecular beam. After the lens, a unique quantization axis for the internal states is developed by using an auxiliary field that adiabatically rotates all magnetic moments until they lie along a single direction perpendicular to the beam path. The end of this auxiliary field is a strong dipolar field aligned along the z direction that defines the quantization axis. Hexapole magnets can be used as a magnetic lens as their magnetic-field gradients are sufficiently cylindrically symmetric [53,82,83]. More details about the internal states of the molecules immediately after the magnetic lens can be found in Sec. III.

Solenoids the magnetic fields of which are parallel to the beam propagation path are used to manipulate the molecular hyperfine states. These solenoids are helically wrapped wire coils whose corresponding magnetic fields are generated by an electric current passing through each coil. These solenoids are labeled as the control fields in Fig. 1. Arbitrary magnetic-field profiles can be obtained by changing the solenoid winding patterns and/or using multiple successive solenoids.

The hyperfine states of a molecule change energy as the molecule enters a magnetic field. These changes to the hyperfine energy levels cause simultaneous changes in the molecular momenta, as the total energy is conserved. That is, when molecules enter a solenoid, molecules in low-field seeking states slow down and those in high-field seeking states speed up. Furthermore, because the direction of the magnetic field in a control field is not along the z axis, the molecules are in a superposition of hyperfine states, with respect to the quantization axis defined by the magnetic field. Thus, the differences in momenta cause the different components of each molecular wave packet to spatially separate as the wave packet traverses the solenoid. Upon exiting the solenoid, the components of each wave packet return to their original momenta, but remain spatially separated. That is, each wave packet is now in an extended spatial superposition.

Each of these spatially separated wave-packet components comprises a superposition of the field-free hyperfine states. The exact superpositions of each wave-packet component, as well as the spatial separations between the components, depend on the magnetic-field profile of the first branch. Each of the wave-packet components sequentially impacts the sample surface and scatters in all directions. However, the experiment only captures those molecules that pass through a particular solid angle. While a current experiment [53] fixes the angle between the two branches, one can in principle explore many different scattering geometries by varying both the angle between the two branches of the apparatus and the orientation of the sample.

After scattering, the collected molecules enter another set of control fields in the second branch of the apparatus. The hyperfine states again change in energy and momenta. In a ^3He spin-echo experiment, if the second magnetic-field profile is identical but opposite in direction to the magnetic-field profile of the first branch, the spatially separated wave-packet components realign (to first order) as they traverse the magnetic field(s), producing a spin echo. This allows the

wave-packet components to interfere with each other. Interestingly, it has recently been shown [79] that echoes are also produced when the device operates with the fields in the same direction. With an arbitrary hyperfine Hamiltonian, such a realignment is only partial, though still useful. Experiments can be performed that explore either this spin-echo region or different relationships between the two magnetic-field profiles, which may allow for a variety of insights about the sample surface. For example, the two field profiles can be different or the field magnitudes can be varied simultaneously, keeping $B_1 = -B_2$. These different regimes of operation may produce different echoes, which can be collectively analyzed to provide more insight into molecule-surface interactions.

Additionally, as the spatially separated wave-packet components hit the surface sequentially, rather than simultaneously, any temporal changes in the surface that are on the timescale of the impact-time separation can differentially impact the phases of each wave-packet component. This may result in different interference patterns or even loss of coherence. This loss of coherence is the basis for the sensitivity of HeSE measurements to surface motion [84]. Here, as in the recent experiment by Godsi *et al.* [53], we focus on surfaces the dynamics of which are either much faster or much slower than the molecule-surface or wave-packet-surface interaction times. Note, however, that the current framework is suitable for extension to interaction regimes where the surface dynamics are comparable to these timescales.

After leaving the last solenoid of the second branch, the wave packets pass through another auxiliary field that begins with a strong dipolar field in the z' direction. The auxiliary field then adiabatically connects magnetic moments aligned along the quantization axis to the radial direction of the final hexapole lens. This hexapole lens then focuses wave packets with low-field seeking hyperfine states into the ionization detector and defocuses the rest. Finally, the ionization detector produces a current that is proportional to the molecular flux into the detector port. We describe how to calculate the molecular flux that enters the detector port in Sec. IV and the related transfer-matrix formalism in Sec. V.

Analyzing the detector current as a function of the magnetic-field profiles, the apparatus geometry, and the sample orientation can provide information about the interaction of the molecules with the sample surface. We discuss one possible analysis scheme in Sec. VI.

Molecular hyperfine Hamiltonian

In principle, the only requirement for a molecular species to be suitable for molecular hyperfine interferometry is that the molecule have internal degrees of freedom whose energies are magnetic-field dependent. Such a requirement could be fulfilled by the presence of a nuclear spin, a rotational magnetic moment, or even an electronic spin. In practice, however, if the energy dependence on the magnetic field is too weak relative to the kinetic energy, state selection and state manipulation are difficult. On the other hand, if the dependence is too strong, the molecules may be difficult to control. Given these restrictions, we deem molecules that have a closed shell and are in an electronic state with zero orbital angular momentum to be most suitable for molecular hyperfine interferometry.

In this case, the dominant interactions induced by magnetic fields are due to the nuclear magnetic spins of the molecules.

The hyperfine states of such a closed-shell molecule with zero orbital angular momentum arise from coupling between the nuclear spin and the rotational degrees of freedom. Interactions of these hyperfine states with a magnetic field arise from the response of the nuclear and rotational magnetic moments to the external magnetic field. We assume that the hyperfine Hamiltonian, also referred to here as the Ramsey Hamiltonian [85], is of the following form:

$$\hat{H}^R(\vec{B}) = U(\hat{I}^2, \hat{J}^2, \hat{I} \cdot \hat{J}, I, J) + V(\hat{I}^2, \hat{I} \cdot \vec{B}, I, \vec{B}^2) + Q(\hat{J}^2, \hat{J} \cdot \vec{B}, J, \vec{B}^2), \quad (1)$$

where \vec{B} is the vector of the external magnetic field, assumed to be uniform across the molecule; \hat{I} and \hat{J} are the nuclear spin and rotational angular momentum operators, respectively; I and J are the nuclear spin and rotational angular momentum quantum numbers, respectively; U contains all spin-rotational couplings (such as $\hat{I} \cdot \hat{J}$ or $\hat{I}^2 \hat{J}^2$); V contains all interactions of the nuclear spins with the magnetic field (such as $\hat{I} \cdot \vec{B}$); and Q contains all interactions of the rotational angular momentum with the magnetic field (such as $\hat{J} \cdot \vec{B}$). Both V and Q are assumed to be proportional to positive powers of $|\vec{B}|$.

At large magnetic fields, V and Q dominate, making the eigenbasis $|Im_I Jm_J\rangle$, where m_I and m_J are the projections of the angular momenta \vec{I} and \vec{J} onto the external magnetic field direction, respectively. At zero field, \hat{H}^R is diagonalized by $|IJFM\rangle$, where $\hat{F} = \hat{I} + \hat{J}$ is the total angular momentum operator and M is the projection of \vec{F} onto a chosen quantization axis. At intermediate fields, the eigenbasis is a function of the magnetic field and can be represented as a superposition of either $|IJFM\rangle$ or $|Im_I Jm_J\rangle$ states. Note that M is a good quantum number at all field strengths. We call an eigenstate of \hat{H}^R a Ramsey state, which we denote as $|R\rangle$ and which has the energy E_R . The number of eigenstates of \hat{H}^R is N_R , such that $1 \leq R \leq N_R$.

We treat the apparatus as a one-dimensional system and account for the actual geometry by rotating the basis of the hyperfine states at the appropriate locations (see Sec. VB). The total Hamiltonian can thus be written as

$$\hat{H}(x) = \frac{\hat{p}^2}{2m} + \hat{H}^R(\vec{B}(x)) \quad (2)$$

where \hat{p} is the center-of-mass momentum operator, m is the molecular mass, and x is the position of the molecule in the apparatus. The magnetic field $\vec{B}(x)$ is now spatially dependent, reflecting the magnetic-field profiles of the two branches of the apparatus.

In principle, the total Hamiltonian should incorporate molecule-surface interaction terms, such as the molecule-surface interaction potential. However, instead of treating the molecule-surface interactions explicitly, we include the interactions effectively through the use of a scattering transfer matrix (see Sec. VC). This allows us to separate the details of the molecule-surface interaction from the propagation of the molecules through the apparatus. We can then treat the molecular propagation analytically while allowing for the scattering matrix to be determined by the level of theory practical for a particular system. Even more importantly, this

approach allows us to treat the scattering matrix elements as free parameters that can be determined by fitting the calculated signal to an experimental signal. For the present paper, we treat the scattering matrix elements as arbitrary parameters, focusing primarily on the development of a theoretical formalism to describe the molecular propagation. We choose particular values for the scattering matrix elements only when we apply the formalism specifically to $o\text{-H}_2$ (Sec. VI). We also assume that the surface is static on timescales relevant to the experiment, such that the scattering matrix is time independent.

The system eigenstates $|ER\rangle$ are defined by the total Hamiltonian (2) through $\hat{H}|ER\rangle = E|ER\rangle$. Note that the system eigenstate $|ER\rangle$ is N_R degenerate and that any linear combination of these states with the same label E is also an eigenstate of \hat{H} . This degeneracy occurs as, while the N_R different Ramsey states may have different energies, the kinetic energy can always be selected to maintain the same total energy. For the sake of convenience, we choose the orthonormal basis to be that defined by $\hat{H}^R(\vec{B}(x))|ER\rangle = E_R|ER\rangle$ for $x \leq 0^-$. The zero of x is defined to be immediately after the magnetic lens, while $y^\pm \equiv \lim_{\delta \rightarrow y^\pm} \delta$. We use these limit definitions as we will deal with discontinuities in the magnetic field when working with the transfer-matrix formalism (Sec. V). As an example of the use of this notation, the statement that both one-sided limits are equal at the point x [i.e., $\lim_{a \rightarrow x^-} f(a) = \lim_{b \rightarrow x^+} f(b)$] can be written as $f(x^-) = f(x^+)$.

The above definition of $|ER\rangle$ produces, for all x , a unique labeling of the system eigenstate $|ER\rangle$ by the total energy E and the internal state R , where R is a Ramsey state in the high magnetic field located immediately after the magnetic lens (i.e., at $x = 0^-$). Note that, because of this definition, $\hat{H}^R(\vec{B}(x))|ER\rangle \neq E_R|ER\rangle$ for $x \geq 0^+$; that is, the system eigenstates are superpositions of the *local* Ramsey states for $x \geq 0^+$. This unique labeling of the system eigenstates is valid for all x as the eigenstate wave functions have a well-defined phase relationship throughout the entire apparatus. See Sec. VA for more details on the specifics of this phase relationship.

III. IMPACT OF THE MAGNETIC LENS ON THE MOLECULAR STATES

The magnetic lenses are designed to focus molecules with certain hyperfine states either onto the sample or into the detector. The remaining molecules are either defocused or insufficiently focused and contribute significantly less to the experimental signal. Roughly, high-field seeking states are defocused, some of the low-field seeking states are well focused, and the rest of the low-field seeking states are partially focused. The actual proportions of each hyperfine state in the molecular beam must be measured or calculated from simulation. These magnetic lenses typically use large magnetic fields and large magnetic-field gradients to perform this focusing [82,83].

In general, magnetic lenses may take different forms, but we will consider lenses that have one key feature: the internal degrees of freedom of the outgoing molecular wave packets are decohered in the high-magnetic-field basis (i.e.,

$|Im_I J m_J\rangle$). More precisely, we assume that the wave packet exiting the magnetic lens is a mixed state of the form

$$\rho_0 = \sum_{R_0} P_{R_0} |\Psi_{R_0 k_0}\rangle \langle \Psi_{R_0 k_0}|, \quad (3)$$

where

$$|\Psi_{R_0 k_0}\rangle = \int dr \psi_{R_0 k_0}(r) |rR_0\rangle; \quad (4)$$

$\psi_{R_0 k_0}(r) \equiv \langle r | \Psi_{R_0 k_0} \rangle$ is the wave function of a molecule in state $|R_0\rangle$; ρ_0 is the initial (time $t = 0$) density matrix; $|rR_0\rangle \equiv |r\rangle |R_0\rangle$; $|r\rangle$ is an eigenstate of the position operator; $|R_0\rangle$ is an eigenstate of $\hat{H}^R(\vec{B}_{\text{lens}})$; \vec{B}_{lens} is a high-magnitude z -aligned magnetic field; k_0 is the experimentally determined mean wave number of the wave packet; and P_{R_0} is the probability that the hyperfine state vector of the molecule is $|R_0\rangle$. Note that ρ_0 is diagonal in $|R_0\rangle$ but not in $|r\rangle$ (or $|k\rangle$, the momentum basis). Also, $\vec{B}_{\text{lens}} = \vec{B}(x = 0^-)$ corresponds to the final portion of the auxiliary field (i.e., a strong, z aligned, dipolar field), not the field inside the hexapole magnet itself (see Sec. II).

That such a form of the wave packet is valid follows from the work by Utz *et al.* [86]. The authors show that the two wave packets arising from a spin- $\frac{1}{2}$ particle passing through a Stern-Gerlach apparatus are quickly decohered with respect to one another, even before they separate spatially. That is, the quantum dynamics themselves cause decoherence between the spin degrees of freedom (but not the spatial); a measurement or coupling to an external bath is not required. This decoherence occurs as the large magnetic-field gradients cause a rapid oscillation in the off-diagonal terms of the extended Wigner distribution. That is, the phase relationship between the spin-up and spin-down components oscillates heavily in both the position and momentum bases, destroying coherence.

Given that the magnetic lenses we consider act like a Stern-Gerlach apparatus for the molecular hyperfine states, it is reasonable to assume that the internal hyperfine degrees of freedom will also decohere. Thus, we need only determine the values of P_{R_0} for a specific magnetic lens. These can be found via semiclassical calculations [53,87], may be measured experimentally [87], or may potentially be determined by solving the full three-dimensional Schrödinger equation within the lens.

The mean velocity v_0 and velocity spread σ_v of the molecules in the molecular beam can be measured experimentally [53]. Both of these values are determined from the position and profile of scattering peaks obtained from the scattering of the probe molecules by appropriate sample surfaces [53]. We assume that the initial wave function of a molecule $\psi_{R_0 k_0}(r)$ is Gaussian and is characterized by $k_0 \equiv mv_0/\hbar$ and $\sigma_k \equiv m\sigma_v/\hbar$, where m is the mass of the molecule. More precisely,

$$\begin{aligned} \psi_{R_0 k_0}(r) &= \int dk \frac{1}{(2\pi\sigma_k^2)^{\frac{1}{4}}} e^{-\frac{(k-k_0)^2}{4\sigma_k^2}} \frac{e^{ikr}}{\sqrt{2\pi}} \\ &= \sqrt{\sigma_k} \left(\frac{2}{\pi}\right)^{\frac{1}{4}} e^{ik_0 r} e^{-r^2\sigma_k^2} \end{aligned} \quad (5)$$

where $k_0^{R_0}$ is taken to be k_0 . Though $k_0^{R_0}$ may in fact depend slightly (on the order of ppm) on R_0 , we show later that the experimental signal is insensitive to small changes in $k_0^{R_0}$.

IV. WAVE-PACKET PROPAGATION AND SIGNAL CALCULATION

The primary measured value of the experiment is a current that is proportional to the molecular flux entering the detector. This measured current is a function of the magnetic fields, the scattering geometry, and the surface properties. The molecular flux entering the detector can be calculated as the product of the molecular flux incident to the apparatus and the probability that a molecule entering the apparatus will successfully pass through the apparatus and be detected. It is this probability of detection $P_{\text{detection}}$ that is sensitive to the experimental parameters and surface properties. Note that the incident molecular flux could be either continuous or pulsed, as long as the density is low enough that the molecules can be considered noninteracting.

As the detector has a finite time response, the probability of detection is given by

$$P_{\text{detection}} = \frac{1}{\tau} \int_{t_1}^{t_2} dt \langle \hat{C}(t) \rangle, \quad (6)$$

where t_1 and t_2 are the initial and final times of the detection window $\tau = t_2 - t_1$, and $\langle \hat{C}(t) \rangle$ is the expectation value of the detector measurement operator \hat{C} . This expectation value is given by

$$\langle \hat{C}(t) \rangle = \text{Tr} \hat{\rho}(t) \hat{C}, \quad (7)$$

where $\hat{\rho}(t) \equiv \hat{U} \rho_0 \hat{U}^\dagger = \sum_{R_0} P_{R_0} |\Psi_{R_0 k_0}(t)\rangle \langle \Psi_{R_0 k_0}(t)|$ is the time evolved density matrix, $\hat{U} \equiv e^{-i\frac{\hat{H}}{\hbar}t}$ is the time evolution operator, ρ_0 is the density matrix (3) at $t = 0$, and $|\Psi_{R_0 k_0}(t)\rangle \equiv \hat{U} |\Psi_{R_0 k_0}\rangle$.

Given that the detector consists of a magnetic lens that focuses molecules with particular states into a measuring apparatus, such as an ionization detector [53], and that the internal degrees of freedom of these molecules are decohered by the second magnetic lens (see Sec. III), we can model the detector with a diagonal operator:

$$\hat{C} = \sum_{R_D} \int dx c_{R_D}(x) |xR_D\rangle \langle xR_D|. \quad (8)$$

The matrix elements of \hat{C} are the probabilities $c_{R_D}(x)$ of detecting, at position x , a molecule whose internal state is a high-field eigenstate $|R_D\rangle$ of \hat{H}^R . Note that $c_{R_D}(x) = 0$ for $x < x_D$, the detector position.

Using the time evolution operator, we determine the time dependence of the density matrix $\rho(t)$ to be

$$\rho(t) = \sum_{R_0 R R'} \int dE \int dE' P_{R_0} e^{-\frac{i}{\hbar}(E-E')t} \alpha_{k_0 R_0}^{ER} \alpha_{k_0 R_0}^{*E'R'} \times |ER\rangle \langle E'R'|, \quad (9)$$

where $\alpha_{k_0 R_0}^{ER} \equiv \int dr \psi_{R_0 k_0}(r) \Phi_{R_0}^{*ER}(r)$ is the overlap between the initial wave function $\psi_{R_0 k_0}(r)$ and the system eigenstate wave function $\Phi_{R_0}^{ER}(r) \equiv \langle rR_0 | ER \rangle$.

We can evaluate $\langle \hat{C}(t) \rangle$ by inserting a resolution of the identity $\sum_{R_D} \int dr |rR_D\rangle \langle rR_D|$, where $\hat{H}^R(\vec{B}(x)) |R_D\rangle = E_{R_D} |R_D\rangle$ for $x \geq x_D^+$ and x_D is the starting location of the detector (see Fig. 2). In other words, $|R_D\rangle$ is a Ramsey state in the strong dipolar magnetic field of the detector auxiliary field. The result is

$$\langle \hat{C}(t) \rangle = \sum_{R_D, R'_D} \int dr \int dr' \langle r'R'_D | \rho(t) | rR_D \rangle \langle rR_D | \hat{C} | r'R'_D \rangle \quad (10)$$

where we have evaluated the trace in the $|r'R'_D\rangle$ basis and

$$\begin{aligned} \langle r'R'_D | \rho(t) | rR_D \rangle &= \sum_{R_0 R R'} \int dE \int dE' P_{R_0} e^{-\frac{i}{\hbar}(E-E')t} \alpha_{k_0 R_0}^{ER} \alpha_{k_0 R_0}^{*E'R'} \Phi_{R'_D}^{ER}(r') \\ &\times \Phi_{R_D}^{*E'R'}(r). \end{aligned} \quad (11)$$

We emphasize that R and R_D are indices of *different* sets of Ramsey states, i.e., $\langle R | R_D \rangle \neq \delta_{RR_D}$, unless the magnetic fields at the first magnetic lens ($x = 0^-$) and the detector magnetic lens ($x = x_D^+$) happen to be identical.

We also have

$$\begin{aligned} \langle rR_D | \hat{C} | r'R'_D \rangle &= \sum_{R'_D} \int dz c_{R'_D}(z) \delta(r-z) \delta_{R_D R'_D} \delta(r'-z) \delta_{R'_D R'_D} \\ &= c_{R_D}(r) \delta(r'-r) \delta_{R'_D R_D}, \end{aligned} \quad (12)$$

which, when inserted with Eq. (11) into Eq. (10), results in

$$\begin{aligned} \langle \hat{C}(t) \rangle &= \sum_{R_0 R R'} \int dE \int dE' P_{R_0} e^{-\frac{i}{\hbar}(E-E')t} \alpha_{k_0 R_0}^{ER} \alpha_{k_0 R_0}^{*E'R'} \\ &\times \left(\sum_{R_D} \int dr \Phi_{R_D}^{ER}(r) \Phi_{R_D}^{*E'R'}(r) c_{R_D}(r) \right). \end{aligned} \quad (13)$$

The initial wave packet is almost entirely confined to the region $r \leq 0^-$, as $\psi_{R_0 k_0}(r)$ has a Gaussian profile (5) with spatial width on the order of 10 Å (as determined from the measured velocity distribution for $o\text{-H}_2$ [53]). Thus, we can evaluate $\alpha_{k_0 R_0}^{ER} \equiv \int dr \psi_{R_0 k_0}(r) \Phi_{R_0}^{*ER}(r)$ if we know $\Phi_{R_0}^{ER}(r)$ for $r \leq 0^-$. Given the definition of the eigenstate $|ER\rangle$, discussed in Sec. II, we show in Sec. V A that $\Phi_{R_0}^{ER}(r) = A_R e^{irk^{ER}} \delta_{RR_0}$ for $r \leq 0^-$ [see Eq. (34)], where $k^{ER} \equiv \frac{\sqrt{2m(E-E_R)}}{\hbar}$ [see Eq. (23)]. Combined with the definition (4) of $\psi_{R_0 k_0}(r)$,

$$\begin{aligned} \alpha_{k_0 R_0}^{ER} &\approx \int dr \delta_{RR_0} A_R^* \sqrt{\sigma_k} \left(\frac{2}{\pi} \right)^{\frac{1}{4}} e^{i(k_0^{R_0} - k^{ER})r} e^{-r^2 \sigma_k^2} \\ &= \delta_{RR_0} \Gamma_{k_0 R_0}^{ER} \end{aligned} \quad (14)$$

where $\Gamma_{k_0 R_0}^{ER} = A_R^* \frac{(2\pi)^{\frac{1}{4}}}{\sqrt{\sigma_k}} e^{-\frac{(k_0^{R_0} - k^{ER})^2}{4\sigma_k^2}}$. Thus,

$$\begin{aligned} \langle \hat{C}(t) \rangle &= \sum_{R_0} \int dE \int dE' P_{R_0} e^{-\frac{i}{\hbar}(E-E')t} \Gamma_{k_0 R_0}^{ER_0} \Gamma_{k_0 R_0}^{*E'R_0} \\ &\times \left(\sum_{R_D} \int dr \Phi_{R_D}^{ER_0}(r) \Phi_{R_D}^{*E'R_0}(r) c_{R_D}(r) \right), \end{aligned} \quad (15)$$

where we have performed the sums over R and R' .

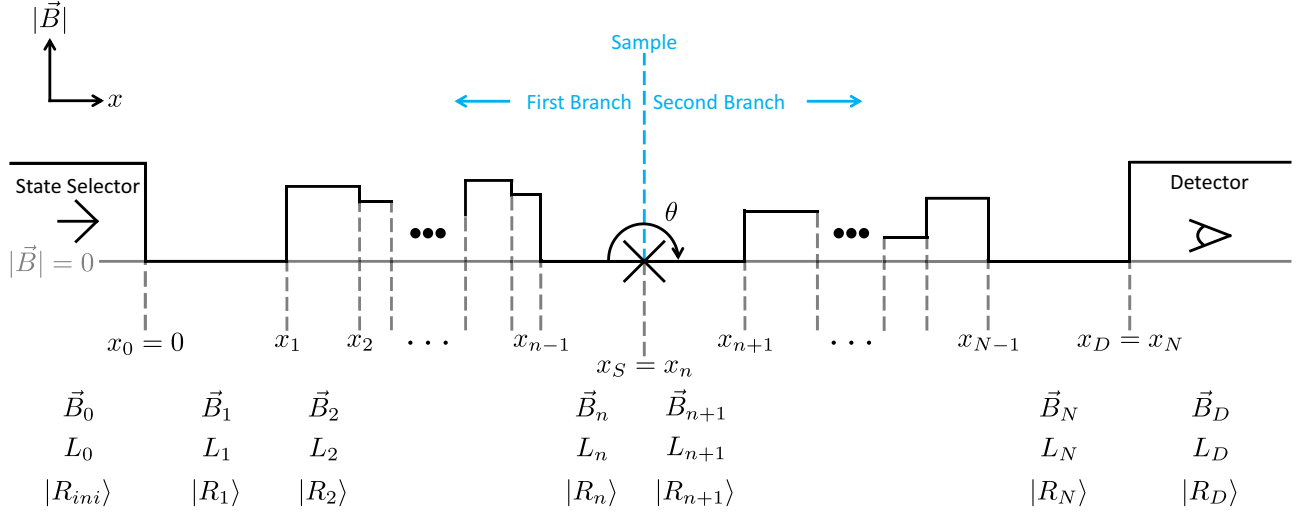


FIG. 2. Generic field profile of a molecular hyperfine interferometry experiment. The actual magnetic-field profiles of the experiment are approximated by $N + 2$ regions of length L_i and constant magnetic field \vec{B}_i (black line). The true field profile is asymptotically approached as $N \rightarrow \infty$. We assume large magnetic fields in the regions of the state selector (large arrow) and the detector (eye), which, when combined with the dephasing discussed in Sec. III, allows us to neglect propagation in the selector and detector regions. That is, the exact locations of x_0 and x_D are unimportant as long as x_0 is in the high-field region of the state selector, x_D is in the high-field region of the detector, and all propagation is treated coherently between the two points. The initially Gaussian wave packet propagates from x_0^- along the first branch to the sample surface (cross) at x_S and then, after scattering, propagates along the second branch to x_D^+ . The two branches are separated by an angle θ . The vertical axis indicates the magnitude of the magnetic field $|\vec{B}|$ (the direction is not depicted for clarity), with $|\vec{B}| = 0$ indicated by the gray solid line. $|R_i\rangle$ denotes the set of eigenstates of $\hat{H}^R(\vec{B}_i)$, Eq. (1), in each region.

If the detection window $t_2 - t_1$ is large enough that the entire wave packet passes through the detection region defined by $c_{R_D}(z)$ we have

$$\begin{aligned}
 P_{\text{detection}} &= \frac{1}{\tau} \int_{t_1}^{t_2} dt \langle \hat{C}(t) \rangle \approx \frac{1}{\tau} \int_{-\infty}^{\infty} dt \langle \hat{C}(t) \rangle \\
 &= \sum_{R_0} \int dE \int dE' P_{R_0} \frac{2\pi\hbar}{\tau} \delta(E - E') \Gamma_{k_0 R_0}^{ER_0} \Gamma_{k_0 R_0}^{*E'R_0} \\
 &\quad \times \left(\sum_{R_D} \int dr \Phi_{R_D}^{ER_0}(r) \Phi_{R_D}^{*E'R_0}(r) c_{R_D}(r) \right) \\
 &= \sum_{R_0} \int dE P_{R_0} |\Gamma_{k_0 R_0}^{ER_0}|^2 \\
 &\quad \times \left(\sum_{R_D} \int dr \frac{2\pi\hbar}{\tau} |\Phi_{R_D}^{ER_0}(r)|^2 c_{R_D}(r) \right), \quad (16)
 \end{aligned}$$

where $\frac{2\pi\hbar}{\tau} \delta(E - E') = \frac{1}{\tau} \int_{-\infty}^{\infty} dt e^{-\frac{i}{\hbar}(E-E')t}$.

Physically, one can see that the probability of detection is proportional to the overlap $|\Gamma_{k_0 R_0}^{ER_0}|^2$ of the initial wave packet and a system eigenstate multiplied by the overlap $\int dr \frac{2\pi\hbar}{\tau} |\Phi_{R_D}^{ER_0}(r)|^2 c_{R_D}(r)$ of the same system eigenstate and the detection region, as expected.

Substituting for $|\Gamma_{k_0 R_0}^{ER_0}|^2$ and given that

$$\begin{aligned}
 \Phi_{R_D}^{ER_0}(r) &\equiv \langle rR_0 | ER \rangle \\
 &= e^{ik_{R_D} r} \langle R_D | ER_0 \rangle \\
 &\equiv e^{ik_{R_D} r} \beta_{R_D}^{ER_0}
 \end{aligned}$$

for $r \geq x_D^+$ [see Eq. (34)], we have

$$\begin{aligned}
 P_{\text{detection}} &= \sum_{R_0} P_{R_0} |A_{R_0}|^2 \int dE \frac{(2\pi)^{\frac{1}{2}}}{\sigma_k} e^{-\frac{(k^{ER_0} - k_0^{R_0})^2}{2\sigma_k^2}} \\
 &\quad \times \sum_{R_D} c_{R_D} \frac{2\pi\hbar}{\tau} |\beta_{R_D}^{ER_0}|^2 \quad (17)
 \end{aligned}$$

where $c_{R_D} \equiv \int dr c_{R_D}(r)$ and $\beta_{R_D}^{ER_0} \equiv \langle R_D | ER_0 \rangle$, the projection of the system eigenstate $|ER_0\rangle$ onto the detector eigenstate $|R_D\rangle$ at x_D^+ . For the purposes of comparing to experiment, only the dependence of $P_{\text{detection}}$ on the experimental parameters is needed, not its absolute value. Also, the value of $A_{R_0} = 1$ as $A_R e^{irk^{ER}} \equiv \langle rR_0 | ER_0 \rangle = e^{irk^{ER}}$ (for $r \leq 0^-$) because of the specific definition of the system eigenstates (see Sec. II). Additionally, one can see that $P_{\text{detection}}$ is not sensitive to minor (on the order of ppm) changes in $k_0^{R_0}$ as $\sigma_k \propto k_0$ in experiment [53]. Finally, in Eq. (17), only $\beta_{R_D}^{ER_0}$ is dependent on the magnetic fields, the scattering geometry, and the surface properties. It is thus sufficient to work with the following equation:

$$P_{\text{detection}} \propto \sum_{R_0} P_{R_0} \int dE e^{-\frac{(k^{ER_0} - k_0^{R_0})^2}{2\sigma_k^2}} \sum_{R_D} c_{R_D} |\beta_{R_D}^{ER_0}|^2. \quad (18)$$

To determine the values of $\beta_{R_D}^{ER_0}$, we derive and apply the transfer-matrix method with internal degrees of freedom (Sec. V).

the wave vector $|E\tilde{R}\rangle$ is the same everywhere in the system. Thus, by writing the wave vector $|E\tilde{R}\rangle$ in the two different bases corresponding to the eigenstates of \hat{H}^R on each side of the field, we see that the coefficients at a specific value of x are related by a basis transformation:

$$\begin{aligned} |E\tilde{R}^-\rangle &= |E\tilde{R}^+\rangle, \\ \sum_{R^-} \int dx \Phi_{R^-}^{E\tilde{R}}(x) |xR^-\rangle &= \sum_{R^+} \int dx \Phi_{R^+}^{E\tilde{R}}(x) |xR^+\rangle, \\ \sum_{R^-R^+} \int dx \Phi_{R^-}^{E\tilde{R}}(x) \langle R^+|R^-\rangle |xR^+\rangle &= \sum_{R^+} \int dx \Phi_{R^+}^{E\tilde{R}}(x) |xR^+\rangle \\ \Rightarrow \Phi_{R^+}^{E\tilde{R}}(x) &= \sum_{R^-} \Phi_{R^-}^{E\tilde{R}}(x) \langle R^+|R^-\rangle, \end{aligned} \quad (26)$$

where $|E\tilde{R}^\pm\rangle$ is the wave vector written in the basis of $|R^\pm\rangle$; $|R^\pm\rangle$ are the eigenstates of $\hat{H}^R(\vec{B}(0^\pm))$ on the left ($-$) and right ($+$) sides of the discontinuity at $x=0$, respectively; and $\sum_{R^+} |R^+\rangle \langle R^+|$ was inserted in the third line (recall that $|xR^-\rangle \equiv |x\rangle |R^-\rangle$). The values $\langle R^+|R^+\rangle$ are recognized as the matrix elements $S_{R^-R^+}$ of the matrix $\mathbf{S}_{R^-}^{R^+}$, the columns of which are the eigenstates of $\hat{H}^R(\vec{B}(0^+))$ written in the $|R^-\rangle$ basis.

Since $\Phi_{R^\pm}^{E\tilde{R}}(x) \in C^1(x)$ for each value of R separately, we can equate the two limits $\lim_{x \rightarrow 0^\mp} \Phi_{R^\pm}^{E\tilde{R}}(x)$ and the two limits of the derivative $\lim_{x \rightarrow 0^\mp} \frac{\partial}{\partial x} \Phi_{R^\pm}^{E\tilde{R}}(x)$. Solving the resultant equations for the coefficients A_{R^+} and B_{R^+} , we obtain (Appendix B)

$$A_{R^+} = \sum_{R^-} S_{R^-R^+}^* \Delta_{R^+R^-}^+ A_{R^-} + \sum_{R^-} S_{R^-R^+}^* \Delta_{R^+R^-}^- B_{R^-}, \quad (27)$$

$$B_{R^+} = \sum_{R^-} S_{R^-R^+}^* \Delta_{R^+R^-}^- A_{R^-} + \sum_{R^-} S_{R^-R^+}^* \Delta_{R^+R^-}^+ B_{R^-} \quad (28)$$

where $S_{R^-R^+}^* \equiv \langle R^+|R^-\rangle$, $\Delta_{R^+R^-}^\pm \equiv \frac{1}{2}(1 \pm \frac{k_{R^-}}{k_{R^+}})$, $k_{R^\pm} \equiv \sqrt{2m(E - E_{R^\pm})/\hbar}$, and $E_{R^\pm} \equiv \langle R^\pm|\hat{H}^R(\vec{B}(0^\pm))|R^\pm\rangle$. There are N_R such sets of equations, one for each value of R^+ . Working again with $\vec{\phi}_x = (A_1, A_2, \dots, A_{N_R}, B_1, B_2, \dots, B_{N_R})^T$, one can write the matrix equation

$$\vec{\phi}_{x^+} = \mathbf{K} \vec{\phi}_{x^-}, \quad (29)$$

where x^\mp indicates the location just before ($-$) or just after ($+$) the discontinuity located at x and \mathbf{K} is the $2N_R \times 2N_R$ discontinuity matrix

$$\mathbf{K} \equiv \begin{pmatrix} \mathbf{S}_{R^-}^{R^+ \dagger} \circ \Delta^+ & \mathbf{S}_{R^-}^{R^+ \dagger} \circ \Delta^- \\ \mathbf{S}_{R^-}^{R^+ \dagger} \circ \Delta^- & \mathbf{S}_{R^-}^{R^+ \dagger} \circ \Delta^+ \end{pmatrix} \quad (30)$$

where \circ denotes the elementwise Hadamard product, such that $(\mathbf{S}_{R^-}^{R^+ \dagger} \circ \Delta^\pm)_{R^+R^-} \equiv S_{R^-R^+}^* \Delta_{R^+R^-}^\pm$. This matrix allows one to calculate the coefficients of the wave function as one moves from one region of constant magnetic field to another through a discontinuity. Thus, if one breaks up any magnetic-field profile into a series of constant regions separated by discontinuities, one can systematically approach a perfect description of the propagation of a molecule with internal degrees of freedom through a magnetic field of arbitrary profile through

repeated application of \mathbf{K} and $\mathbf{\Pi}_x$. Furthermore, this approach is not restricted to molecules moving through magnetic fields. Many other types of quantum objects moving in a single dimension with internal degrees of freedom that couple to an external static potential can also be analyzed in this way.

The above analysis indicates that one needs to keep track of $2N_R$ components to build up the eigenstates of the system exactly. However, for the current application in mind, one only needs N_R components as the magnetic fields typically change the linear molecular momentum by such a small amount that the amplitudes B_R of the reflected part of the wave function are negligible. That is, any backscattering of the molecules by the magnetic fields is negligible and can be ignored.

For example, a typical velocity of the o -H₂ molecules in the experiment of Ref. [53] is $v_{H_2} = 1450$ m/s. This corresponds to the kinetic energy $E_{H_2} = \frac{1}{2}m_{H_2}v_{H_2}^2 = 5.31 \times 10^9$ kHz. The data reported by Ramsey [85] indicate that the maximum energy change for the hyperfine states of o -H₂ at 500 G is approximately -2550 kHz. The experiment of Ref. [53] has magnetic fields up to about 1000 G. For such fields, the energy changes are approximately linear, so we expect the maximum change in energy to be $\Delta E \approx -5100$ kHz. In the field-free region before the discontinuity, $k_{R^-} \approx m_{H_2}v_{H_2}/\hbar$ and, after the discontinuity in the field, $k_{R^+} \approx \sqrt{2m_{H_2}(E - \Delta E)/\hbar}$, as per Eq. (23). Then, $|\Delta_{R^+R^-}^-| \approx 2.4 \times 10^{-7}$ and $|\Delta_{R^+R^-}^+| \approx 1$, making \mathbf{K} approximately diagonal and illustrating the decoupling of the forward and backward channels under typical experimental conditions.

We thus only need to keep track of the A_R components, which correspond to the forward-propagating momenta. We can define a new coefficient vector:

$$\vec{\psi}_x \equiv (A_1, A_2, \dots, A_{N_R})^T. \quad (31)$$

The corresponding $N_R \times N_R$ propagation \mathbf{P}_x and discontinuity \mathbf{D} matrices are

$$\mathbf{P}_x \equiv \bigoplus_R e^{ik_{R^+}x} = \begin{pmatrix} e^{ik_{1x}} & & 0 \\ & \ddots & \\ 0 & & e^{ik_{N_R x}} \end{pmatrix}, \quad (32)$$

$$\mathbf{D} \equiv \mathbf{S}_{R^-}^{R^+ \dagger} \circ \Delta^+ \approx \mathbf{S}_{R^-}^{R^+ \dagger}, \quad (33)$$

where the matrix elements of $\mathbf{S}_{R^-}^{R^+ \dagger}$ are $S_{R^-R^+}^* \equiv \langle R^+|R^-\rangle$, $\hat{H}^R(\vec{B}(0^\pm))|R^\pm\rangle = E_{R^\pm}|R^\pm\rangle$, 0^\pm indicates the position just to the left ($-$) or right ($+$) of the discontinuity, and k_R is defined as in Eq. (23). Specifically, \mathbf{D} changes the basis of the vector $\vec{\psi}_x$ from $|R^-\rangle$ to $|R^+\rangle$. That is, $\vec{\psi}_x$ is always in the eigenbasis of $\hat{H}^R(\vec{B}(x))$. Finally, given that $B_R \approx 0$, the eigenstate coefficients are now

$$\Phi_{R^-}^{E\tilde{R}}(x) = A_R e^{ik_{R^+}x}. \quad (34)$$

Given that a generic transfer matrix \mathbf{M} has the property $\mathbf{M}\sigma_z\mathbf{M}^\dagger = \sigma_z$ [71], the decoupling of the forward and backward channels implies that the forward channel matrix \mathbf{M}_F (composed of a product of \mathbf{P}_x and \mathbf{D} matrices) is now unitary.

B. Rotation matrices

Scattering by the sample surface changes both the propagation direction and the internal states of the molecule. To take into account the change in the direction of the propagation path when applying the transfer-matrix formalism, we need only change the orientation of the quantization axis. However, to address the impact of scattering on the internal states, we need to apply a scattering matrix that is written with respect to a particular reference frame (which is often a sample-fixed frame; see Sec. V C). Thus, instead of just rotating the quantization axis from the first branch to the second branch (to account for the change in the direction of propagation), we need to first rotate from the initial reference frame (xyz in Fig. 1) to the reference frame of the scattering matrix. Then, after applying the scattering matrix, we need to rotate from the scattering matrix reference frame to the final reference frame ($x'y'z'$ in Fig. 1). To perform these rotations coherently, we apply $N_R \times N_R$ rotation matrices $\mathbf{R}(\phi, \Theta, \chi)$ to $\vec{\psi}_x$, where ϕ , Θ , and χ are the Euler angles in the ZYZ convention

$$\begin{aligned} \mathbf{R}_R(\phi, \Theta, \chi) &\equiv [\langle R' | \hat{R}(\phi, \Theta, \chi) | R \rangle] = \left[\sum_{FMF'M'} \langle R' | F'M' \rangle \langle F'M' | \hat{R}(\phi, \Theta, \chi) | FM \rangle \langle FM | R \rangle \right] \\ &= \mathbf{S}_{FM}^R \dagger \mathbf{R}_{FM}(\phi, \Theta, \chi) \mathbf{S}_{FM}^R, \end{aligned} \quad (35)$$

where $|FM\rangle \equiv |IJFM\rangle$ is an angular momentum state with total angular momentum F , z axis projection M , total nuclear-spin angular momentum I , and total rotational angular momentum J ; the subscripts of \mathbf{R}_R and \mathbf{R}_{FM} denote the basis of the matrix representation, $|R\rangle$ and $|FM\rangle$, respectively; \mathbf{S}_{FM}^R is the matrix the columns of which are the eigenstates $|R\rangle$ written in the $|FM\rangle$ basis; $\hat{R}(\phi, \Theta, \chi)$ is the rotation operator (with the same ZYZ convention mentioned above); and

$$\begin{aligned} \mathbf{R}_{FM}(\phi, \Theta, \chi) &= [\delta_{FF'} D_{M'M}^F(\phi, \Theta, \chi)] \\ &= [\delta_{FF'} e^{-i\phi M'} d_{M'M}^F(\Theta) e^{-i\chi M}], \end{aligned} \quad (36)$$

where $D_{M'M}^F(\phi, \Theta, \chi)$ are the Wigner D matrices and $d_{M'M}^F(\Theta)$ are the Wigner small d matrices [90]. Note that $\mathbf{R}_{FM}(\phi, \Theta, \chi)$ is diagonal in F , because of conservation of angular momentum, but not diagonal in M [90]. Thus, one must be careful to also perform a passive rotation on the local magnetic-field vector if rotations are performed in a region with nonzero field. Typically, however, the sample chamber is magnetically shielded.

We also note that the rotation may impact how to appropriately match the boundary conditions between the eigenstate immediately after rotation and the eigenstate at the start of the second branch. As the propagation matrices \mathbf{P}_x (32) are defined with respect to the momentum, which may be positive or negative, it is important to choose the sign of the momentum that results in the probability current flowing in the same direction as the molecular propagation. For example, using the axis definitions in Fig. 1, $+k_R$ is chosen for the first branch and $-k_R$ for the second branch.

(with Y and Z being the axes of a space-fixed frame; see Ref. [90]). In this way, we can account for both specular and nonspecular scattering geometries and for various orientations of the sample surface.

To change the orientation of the quantization axis, we perform passive rotations on the state vector $\vec{\psi}_x$. These passive rotations modify the basis of $\vec{\psi}_x$, but leave the physical state unchanged. For example, if we were to assume that the only impact of scattering was to change the propagation direction, we would need to perform a passive rotation of the state vector about the y axis by the angle θ to account for a change of angle θ in the propagation direction (for the definition of the axes shown in Fig. 1). We would perform this rotation by applying the equivalent active rotation of angle $-\theta$ to $\vec{\psi}_x$, that is, by using the matrix $\mathbf{R}(0, -\theta, 0)$.

For the general case, we work with the rotation matrices $\mathbf{R}(\phi, \Theta, \chi)$, the matrix elements of which, when written in the $|R\rangle$ eigenbasis of $\hat{H}^R(\vec{B}_{\text{loc}})$ where \vec{B}_{loc} is the local magnetic field, are

C. Scattering transfer matrices

Scattering by the sample surface can involve many complex phenomena that may change the internal state, the momentum, and the total energy of the scattering molecule. For the present paper, we focus on scattering processes that conserve the total energy of the molecules. Energy-conserving scattering may, however, include transfer of energy between the internal and translational degrees of freedom. Such scattering processes are described by a general, nondiagonal scattering matrix in the basis of the molecular states.

The interactions of the molecules with the sample surface can be phenomenologically described with the total scattering transfer matrix. This matrix is the $2N_R \times 2N_R$ matrix $\tilde{\Sigma}$ that relates the wave functions on the “left” side of the scattering event to those on the “right” (as opposed to the scattering matrix, which relates the incoming wave functions to the outgoing). However, because the initial wave packet (5) does not contain any negative momentum states, the magnetic fields of the solenoids do not cause significant backscattering (Sec. V A), and the detector only detects molecular flux in the forward-scattering direction, we need only work with the $N_R \times N_R$ matrix $\Sigma \equiv \mathbf{P}_{\text{fwd}} \tilde{\Sigma} \mathbf{P}_{\text{fwd}}^\dagger$, where \mathbf{P}_{fwd} is an $N_R \times 2N_R$ projection matrix onto the forward-scattering states. We define Σ in the $|Im_j Jm_j\rangle$ basis, where the $|Im_j Jm_j\rangle$ states are themselves defined with respect to the quantization axis that is normal to the surface sample. We choose this basis to relate to scattering calculations, which are frequently carried out in the $|Jm_j\rangle$ basis with a quantization axis normal to the sample surface. In principle, however, any suitable set of Ramsey states $|R_\Sigma\rangle$ could be chosen as the basis for the scattering transfer matrix and any suitable quantization axis could be chosen, to take advantage of relevant symmetries.

In general, the scattering transfer-matrix elements $\Sigma_{Im_i Jm_i l' m_i' J' m_i'}$ are functions of the incident energy E , the outgoing energy E' , the incident momentum \vec{k} , and the outgoing momentum \vec{k}' . As we are restricting ourselves to isoenergetic processes, $E = E'$. Also, Eq. (23) defines the magnitudes of the momentum before and after the scattering event. This leaves the scattering transfer-matrix elements as functions of only energy and the four angles that define the scattering geometry. These angles are (1) the angle between the two branches, (2) the angle between the surface normal and the scattering plane, (3) the angle between the first branch and the projection of the surface normal on the scattering plane, and (4) the azimuthal angle of the sample. The scattering plane is the plane defined by the two branches of the apparatus.

Given that the experiment only probes a single scattering direction at a time (see Sec. II and Fig. 1), the scattering transfer matrix will not, in general, be unitary. This incorporates state-dependent loss channels into the formalism. Additionally, the scattering transfer matrix is, in general, time dependent. Here, we assume that the timescales of the surface dynamics are significantly different from the molecule-surface or wave packet-surface interaction timescales and assume Σ to be time independent.

Because Σ is defined with respect to the surface normal, we use rotation matrices to appropriately change the basis of $\vec{\psi}$ before and after applying the scattering transfer matrix. We ensure that the total rotation corresponds to the change in propagation direction induced by scattering off of the sample surface and that the quantization axis is again coplanar with the two branches of the apparatus.

The scattering transfer-matrix elements for a specific molecule-surface interaction can be determined from scattering calculations [53,91]. Alternatively, they can be treated as free parameters and determined from the experimental measurements by solving the inverse scattering problem. Such a problem can potentially be solved efficiently using machine learning based on Bayesian optimization [69,92].

D. Calculation of eigenstate coefficients

To determine the dependence of the probability of detection (18) on the magnetic fields and the surface properties, we must determine the coefficients $\beta_{R_D}^{ER_0}$. This can be done by multiplying the initial coefficient vector $\vec{\psi}_{x_0}^{ER_0}$ (31) of a system eigenstate $|ER_0\rangle$ by a succession of transfer matrices to obtain the final coefficient vector $\vec{\psi}_{x_D}^{ER_0} \equiv (\beta_1^{ER_0}, \beta_2^{ER_0}, \dots, \beta_{N_R}^{ER_0})^T$:

$$\vec{\psi}_{x_D}^{ER_0} = \mathbf{S}_{R_N}^{R_D \dagger} \mathbf{M}_2 \mathbf{M}_\Sigma \mathbf{M}_1 \vec{\psi}_{x_0}^{ER_0}, \quad (37)$$

where \mathbf{M}_1 and \mathbf{M}_2 describe the propagation through the first and second branches of the apparatus, respectively, \mathbf{M}_Σ describes the scattering, and $\mathbf{S}_{R_N}^{R_D \dagger}$ changes the basis of the coefficient vector to the eigenbasis $|R_D\rangle$ of $\hat{H}^R(\vec{B}(x_D^+))$ at the location of the detector x_D . The \mathbf{M} matrices are defined as

$$\mathbf{M}_1 = \mathbf{P}_{L_n} \mathbf{S}_{R_{n-1}}^{R_n \dagger} \cdots \mathbf{P}_{L_2} \mathbf{S}_{R_1}^{R_2 \dagger} \mathbf{P}_{L_1} \mathbf{S}_{R_{\text{ini}}}^{R_1 \dagger}, \quad (38)$$

$$\mathbf{M}_\Sigma = \mathbf{S}_{FM}^{R_n \dagger} \mathbf{R}_{FM}(\alpha', \beta', \gamma') \Sigma_{FM} \mathbf{R}_{FM}(\alpha, \beta, \gamma) \mathbf{S}_{R_n}^{FM \dagger}, \quad (39)$$

$$\mathbf{M}_2 = \mathbf{P}_{L_N} \mathbf{S}_{R_{N-1}}^{R_N \dagger} \cdots \mathbf{P}_{L_{n+1}} \mathbf{S}_{R_n}^{R_{n+1} \dagger} \quad (40)$$

where R_{ini} refers to the eigenbasis $|R_{\text{ini}}\rangle$ of $\hat{H}^R(\vec{B}(0^-))$ at the initial location of the wave packet; R_i refers to the eigenbasis $|R_i\rangle$ of $\hat{H}^R(\vec{B}_i)$ in region i of the apparatus, as depicted in Fig. 2; FM refers to the $|JFM\rangle$ basis where $\vec{F} \equiv \vec{I} + \vec{J}$ and M is the projection on the local z axis; α , β , and γ are the Euler angles that rotate the reference frame of the first branch (xyz in Fig. 1) onto the reference frame of the scattering transfer matrix, whose quantization axis is normal to the sample surface (see Secs. VB and VC); α' , β' , and γ' are the Euler angles that rotate the scattering transfer-matrix reference frame onto the reference frame of the second branch ($x'y'z'$ in Fig. 1); L_i is the signed length of region i , as depicted in Fig. 2; the sign of L_i indicates the direction of propagation with respect to the local x or x' axis; N is the total number of regions between x_0 and x_D (see Fig. 2); n is the number of regions between the initial position of the wave packet $x_0 = 0$ and the sample position x_S ; $\Sigma_{FM} \equiv \mathbf{S}_{R_{IJ}}^{FM \dagger} \Sigma \mathbf{S}_{FM}^{R_{IJ} \dagger}$ is the scattering transfer matrix written in the $|JFM\rangle$ basis; $R_{IJ} \equiv Im_I Jm_J$; and Σ is the scattering transfer matrix in the $|Im_I Jm_J\rangle$ basis. Note the product of the two rotation matrices $\mathbf{R}_{FM}(\alpha', \beta', \gamma') \cdot \mathbf{R}_{FM}(\alpha, \beta, \gamma) = \mathbf{R}_{FM}(\phi, \Theta, \chi)$, where ϕ , Θ , and χ are the Euler angles that rotate the reference frame xyz onto the frame $x'y'z'$ (see Fig. 1). All of the Euler angles mentioned above are in the YZZ convention, with Y and Z being the axes of a space-fixed frame and as per the convention defined in Ref. [90]. Note also that while the scattering transfer matrix Σ is written here in the $|Im_I Jm_J\rangle$ basis, other suitable bases $|R_\Sigma\rangle$ may be used (see Sec. VC), where R_Σ refers to an arbitrary set of Ramsey states. In such a case, $\Sigma_{FM} \equiv \mathbf{S}_{R_\Sigma}^{FM \dagger} \Sigma \mathbf{S}_{FM}^{R_\Sigma \dagger}$. Also, note that the propagation matrices \mathbf{P}_{L_i} (32) are defined with momentum $+k_R$ if the molecular propagation is in the direction of the local x or x' axis or, conversely, with the momentum $-k_R$ if the molecular propagation is in the opposite direction of the local x or x' axis (see Sec. VB).

By defining a matrix $\Psi_{x_i}^E \equiv (\vec{\psi}_{x_i}^{E1}, \vec{\psi}_{x_i}^{E2}, \dots, \vec{\psi}_{x_i}^{EN_R})$, all $N_R \times N_R$ coefficients $\beta_{R_D}^{ER_0}$ can be simultaneously obtained from

$$\Psi_{x_D}^E = \mathbf{S}_{R_N}^{R_D \dagger} \mathbf{M}_2 \mathbf{M}_\Sigma \mathbf{M}_1 \Psi_{x_0}^E = \mathbf{S}_{R_N}^{R_D \dagger} \mathbf{M}_2 \mathbf{M}_\Sigma \mathbf{M}_1 \mathbb{1}_{N_R}, \quad (41)$$

where $\Psi_{x_0}^E \equiv \mathbb{1}_{N_R}$ because of the specific definition of the system eigenstates (see Sec. II). Using Eqs. (38)–(41), we can obtain $\beta_{R_D}^{ER_0}$, and thus $P_{\text{detection}}$ (18), as functions of the magnetic-field profile, the scattering matrix elements, and the scattering geometry.

VI. APPLICATION TO ORTHOHYDROGEN

The theoretical framework described in Secs. II–V connects the scattering transfer-matrix elements $\Sigma_{Im_i Jm_i l' m_i' J' m_i'}$ to the experimentally observed signal, which is proportional to $P_{\text{detection}}$ (18). By changing the magnetic-field profiles in the two arms of the apparatus, one can obtain information about how the scattering affects various hyperfine states. To illustrate our theoretical framework and to demonstrate the impact of the scattering transfer matrix on the experimentally observed signal, we consider a beam of rotationally cold $o\text{-H}_2$ and a simplified apparatus that contains only a few regions of constant magnetic field, as depicted in Fig. 3.

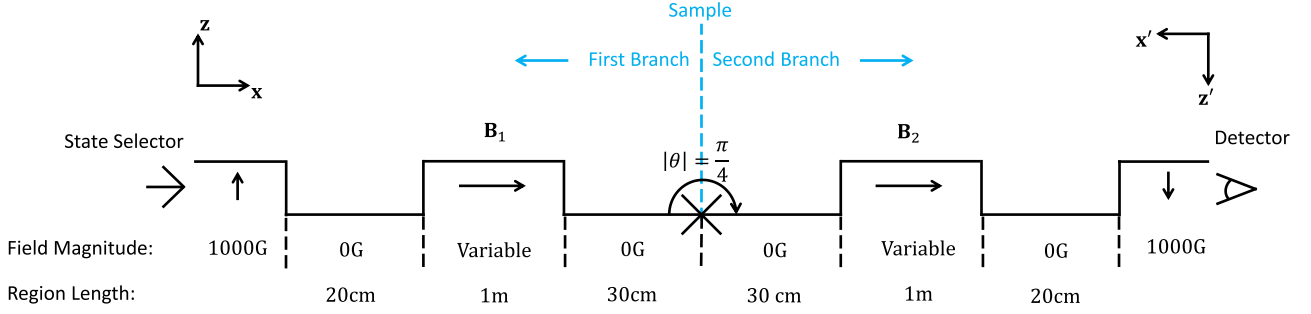


FIG. 3. A magnetic-field profile that approximates the true magnetic-field profile of an experiment using $o\text{-H}_2$. We combine this approximate field profile with the transfer-matrix formalism to calculate the observed signal. \mathbf{B}_i refers to the different magnetic-field vectors of the control fields. z' and x' refer to the new coordinate system defined to align with the second branch of the apparatus (see Fig. 1). The sample is located at the cross in the center of the diagram. The surface normal of the sample is assumed to bisect the angle between the two branches of the apparatus. The propagation direction is x before scattering and $-x'$ after scattering. The angle between x and $-x'$ (i.e., the angle between the two arms of the apparatus) is $\theta = 45^\circ$. \mathbf{B}_1 is directed along x and \mathbf{B}_2 is directed along $-x'$, as per the arrows. The fields just after the state selector and just before the detector are directed toward the z and z' directions, respectively, and as per the arrows. Additional computational parameters not shown above can be found in Appendix C.

A. Rotationally cold orthohydrogen hyperfine Hamiltonian

The Hamiltonian describing the relevant internal degrees of freedom of rotationally cold $o\text{-H}_2$ is [85]

$$\frac{\hat{H}_{o\text{H}_2}^R(\vec{B})}{h} = -\alpha \hat{I} \cdot \vec{B} - \beta \hat{J} \cdot \vec{B} - c \hat{I} \cdot \hat{J} + \frac{5d}{(2J-1)(2J+3)} \times \left[3(\hat{I} \cdot \hat{J})^2 + \frac{3}{2} \hat{I} \cdot \hat{J} - \hat{I}^2 \hat{J}^2 \right] \quad (42)$$

where, for simplicity, we have neglected magnetic shielding of the nuclear and rotational magnetic moments by the molecule and diamagnetic interactions of the molecule with the magnetic field; \vec{B} is the local magnetic field; \hat{I} is the nuclear-spin operator; \hat{J} is the rotational angular momentum operator; $\alpha \equiv \frac{\mu_I}{h} \approx 4.258$ kHz; $\beta \equiv \frac{\mu_J}{h} \approx 0.6717$ kHz; $c \approx 113.8$ kHz; $d \approx 57.68$ kHz; $I = 1$ is the total nuclear-spin angular momentum in units of \hbar ; $J = 1$ is the total rotational angular momentum in units of \hbar ; μ_I is the nuclear magnetic moment of a *single* nucleus; and μ_J is the magnetic moment due to molecular rotation. The first two terms describe the interaction of the nuclear and rotational magnetic moments with the external magnetic field, the third term describes the nuclear-spin-rotational magnetic interaction [85,93,94], and the terms proportional to d describe the magnetic spin-spin interaction of the two nuclei [85,93,94].

B. Experiment and observables

While there are many possible experimental protocols, we focus on the full interferometer mode used by Godsi *et al.* [53]. The experiment is performed by initiating a continuous flux of $o\text{-H}_2$ molecules through the apparatus and measuring the current of the ionization detector while varying the first and second control fields (B_1 and B_2 in Fig. 3).

In particular, B_1 is set to a specific value while B_2 is varied around the point $-B_1$ (i.e., about the spin-echo condition). In principle, B_2 could also be set to vary around $+B_1$, where spin echoes have also been observed [79], but we choose to vary B_2 about $-B_1$ to match the relevant experiment by Godsi *et al.* [53]. This variation of the magnetic fields results in oscillatory curves of the detector current versus B_2 , as shown

in Figs. 4(a)–4(c). These oscillations reflect the interference pattern that occurs when the various wave packets recombine after passing through the final control field (see Sec. II). This interference pattern contains information about how the individual hyperfine states of the molecule interact with the sample surface.

The x directed magnetic field of a solenoid changes the energies of all of the $N_R = 9$ hyperfine states and induces all $\binom{N_R}{2} = 36$ possible transitions. The frequencies of these transitions depend on the magnitude of the magnetic fields. By changing the magnitude of the second magnetic field, we are able to probe the rates of change of these transition frequencies with the magnetic field: the (generalized) gyromagnetic ratios $\gamma_{ij}(B) = \left| \frac{df_{ij}(B)}{dB} \right|$, where $f_{ij} \equiv \frac{1}{h} \Delta E_{ij} = \frac{E_i - E_j}{h}$, and E_i is the energy of Ramsey state i [53]. The Fourier transforms of the oscillatory curves that give these gyromagnetic ratios are shown in Figs. 4(d)–4(f). To obtain these results, we assumed that the surface normal of the sample lies in the scattering plane defined by the two branches and bisects the angle defined by the same two branches, such that $\alpha' = \alpha = \gamma' = \gamma = 0$, $\beta = 3\pi/8$, and $\beta' = -5\pi/8$, where $\beta + \beta' = -\pi/4 = -\theta$ [see Eq. (39) and Fig. 3]. Given this geometry and the axis definitions (Fig. 3), the propagation matrices are defined with $+k_R$ in the first branch and $-k_R$ in the second. We also assume that the scattering transfer matrix is the identity matrix and is independent of energy, i.e., we assume for the present calculation that the only impact of scattering is the change of propagation direction, as modeled with rotation matrices (Sec. VB).

The location of each feature in the spectra is reflective of a gyromagnetic ratio and is *independent* of the molecule-surface interactions, being only a function of the hyperfine energy-level structure of $o\text{-H}_2$. The relative height of each feature, however, is dependent on the molecule-surface interactions, as exemplified in the experimental spectrum shown in Fig. 4(f). From Fig. 4, one can see that integrating over the velocity distribution is important to produce the spin-echo effect and to bring the observed signal closer to experiment.

A different spectrum can be obtained for every possible value of B_1 and then combined to form a 2D map of the

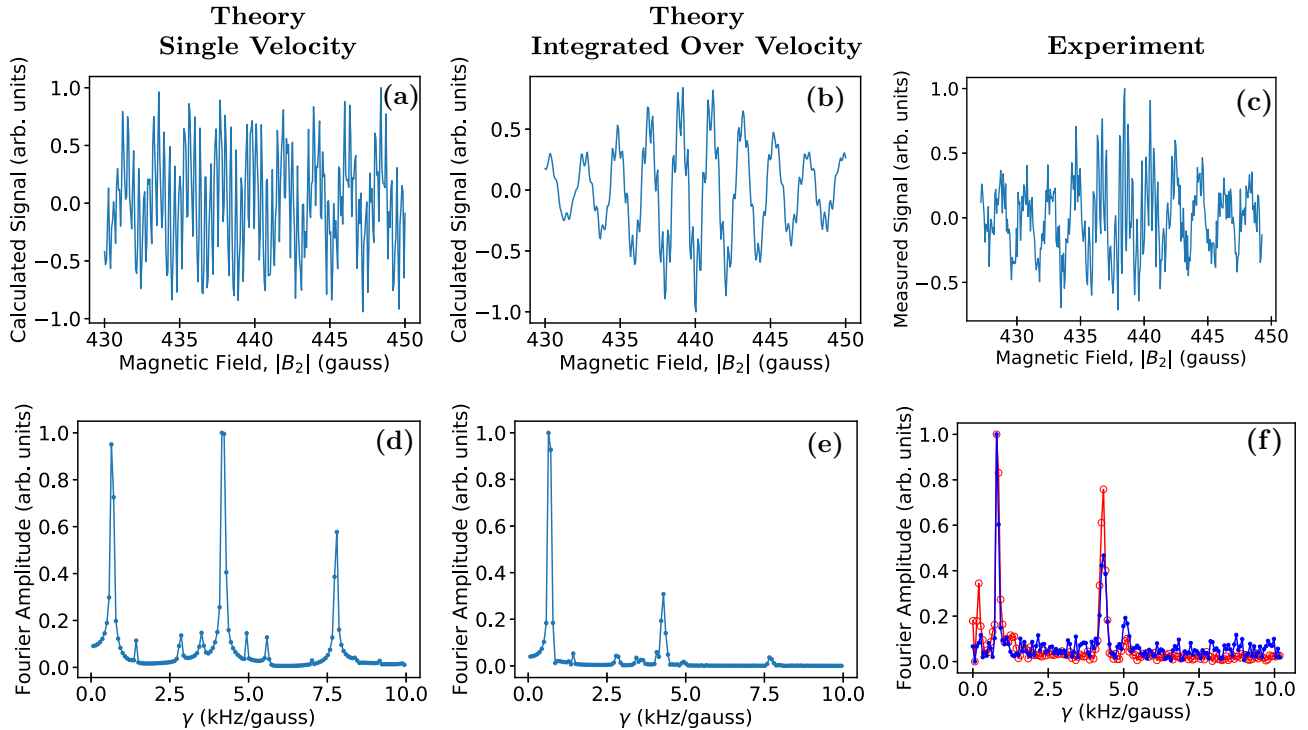


FIG. 4. Upper panels: Calculated and experimental signals close to the spin-echo condition vs the magnetic field of the second coil $|B_2|$. Lower panels: Fourier amplitudes of the upper panels vs the generalized gyromagnetic ratio γ . For panels (a), (b), (d), and (e), the field profile is depicted in Fig. 3; $B_1 = 440$ G; the scattering transfer matrix $\Sigma = \mathbb{1}_9$ and is constant for all energies; and the signal is sampled at a rate of 300 points per 20 G. Panels (a) and (d) only include a single velocity (or, equivalently, a single value of energy) in Eq. (18) while panels (b) and (e) include the full integral. For the experimental data shown in panel (c), $B_1 = 437$ G, the sample was the (111) surface of Cu and the signal was sampled every 0.065 G (a sampling rate of ≈ 308 points per 20 G). Panel (f) shows data for o - H_2 scattering off of Cu(111) (blue full circles) and Cu(115) (red open circles). All experimental data were obtained from Godsi *et al.* [53].

generalized gyromagnetic ratios and their contributing amplitudes as a function of B_1 , as shown in Fig. 5. This protocol is equivalent to observing the scattering of molecules with different internal hyperfine states as different values of the magnetic field in the first branch produce different superpositions of the hyperfine states. One can clearly see both the magnetic-field dependence of the gyromagnetic ratios, the

impact of integrating over the velocity distribution, and the stark similarities and differences between the experimental and theory plots.

We now examine the sensitivity of the calculated signals to various changes in the scattering transfer matrices. Figures 6 and 7 demonstrate the impact of random variations of the scattering transfer matrix Σ on the oscillatory plots (for $B_1 =$

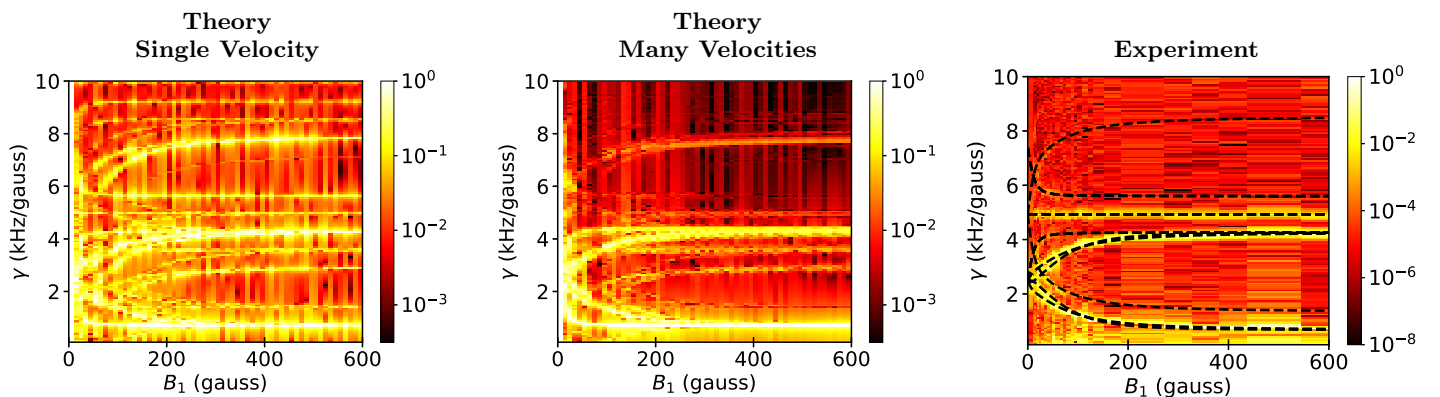


FIG. 5. Two-dimensional Fourier amplitude plots formed by the concatenation of spectra plots [such as Figs. 4(d)–4(f)] for various values of the magnetic field of the first solenoid B_1 . Color indicates the Fourier amplitude. For the theory plots, the field profile is depicted in Fig. 3; the scattering transfer matrix $\Sigma = \mathbb{1}_9$ and is constant for all energies; B_2 was varied from $-(B_1 - 10$ G) to $-(B_1 + 10$ G); the signal was sampled at a rate of 300 points per 20 G; and all data with a value less than $10^{-3.5}$ have been replaced with $10^{-3.5}$ for clarity. For the experimental plot, the sample was the (111) surface of Cu; all data with a value of less than 10^{-8} have been replaced with 10^{-8} for clarity; the dashed lines indicate transitions identified by Godsi *et al.* [53]; and the data were obtained from Godsi *et al.* [53].

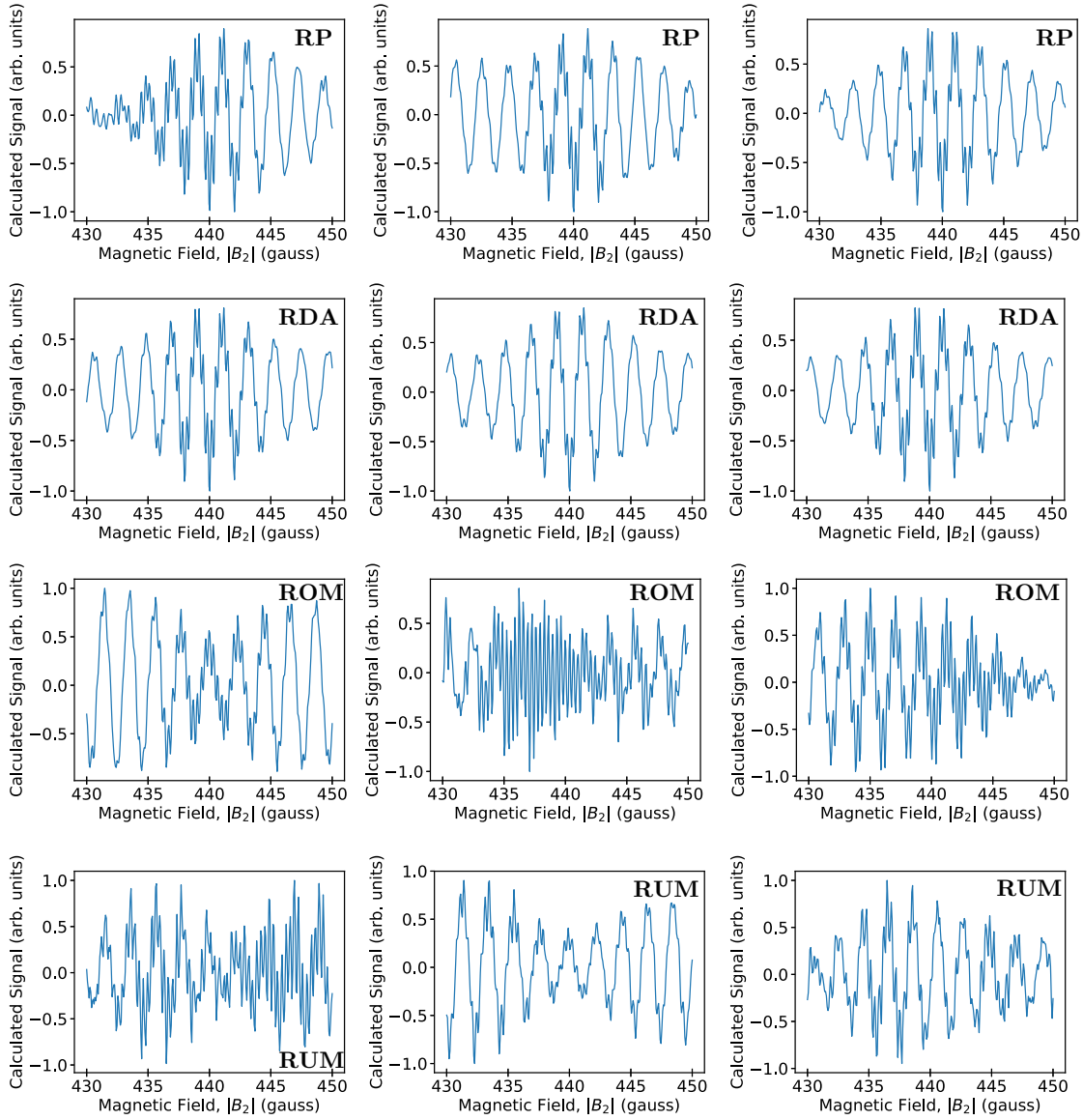


FIG. 6. Calculated signals close to the spin-echo condition as functions of the magnetic field of the second coil $|B_2|$. The field profile is depicted in Fig. 3; $B_1 = 440$ G; and the signal was sampled at a rate of 300 points per 20 G. Each of the plots was created with identical parameters, except for the scattering transfer matrices Σ . The scattering transfer matrices are identical for all energies and are randomly chosen for each plot as follows. First row, random phases (RP): $\Sigma = \bigoplus_{i=1}^9 e^{i\theta_i}$ is a diagonal unitary matrix whose nine phases θ_i are randomly chosen from a uniform distribution of width 2π . Second row, random diagonal amplitudes (RDA): $\Sigma = \bigoplus_{i=1}^9 A_i$ is a diagonal matrix whose diagonal elements are randomly chosen from a uniform distribution on the interval $[0, 1)$. Third row, random orthogonal matrices (ROM): Σ is an orthogonal matrix randomly drawn according to the Haar measure on $O(9)$. Fourth row, random unitary matrices (RUM): Σ is a unitary matrix randomly drawn according to the Haar measure on $U(9)$. Here, randomly drawing according to the Haar measure can be understood as analogous to drawing from the “uniform distribution” over the space of possible matrices [95].

440 G) and their spectra, respectively. For simplicity, we keep the matrix elements of Σ independent of energy.

The first row of each figure (labeled RP, for “random phases”) reflects the impact of differing phases imparted to each hyperfine state after scattering. Specifically, $\Sigma = \bigoplus_{i=1}^9 e^{i\theta_i}$ is a diagonal unitary matrix whose nine phases θ_i are randomly chosen from a uniform distribution of width 2π . Such a form of scattering would result from purely elastic scattering where the different hyperfine states probe the surface for different lengths of time (i.e., each state penetrates to a different depth or encounters a resonance with a

different lifetime). Significant differences in the relative peak amplitudes can already be seen at this point, indicating that the calculated signal is sensitive to these phases.

The second row of each figure (labeled RDA, for “random diagonal amplitudes”) reflects the impact of differing state losses due to scattering. Specifically, $\Sigma = \bigoplus_{i=1}^9 A_i$ is a diagonal matrix whose diagonal elements are randomly chosen from a uniform distribution on the interval $[0, 1)$. This form models the impact of different losses of each hyperfine state to different scattering directions, reactions with the surface, or adsorption to the surface. Again, sig-

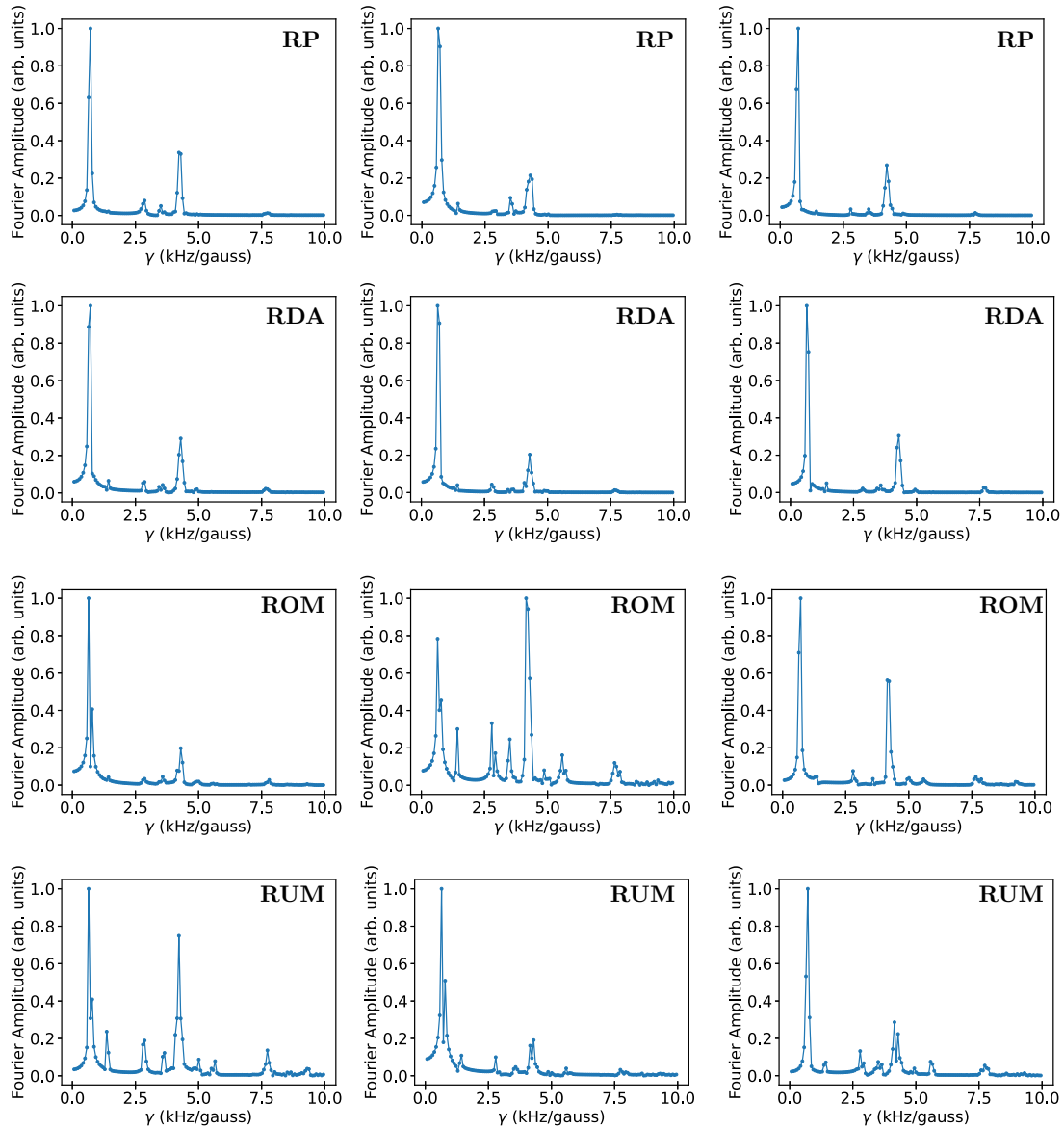


FIG. 7. Fourier transforms of the signals shown in Fig. 6 as functions of the generalized gyromagnetic ratio γ . The panel labels are described in the figure caption to Fig. 6.

nificant changes are observed, indicating sensitivity to these features.

The third and fourth rows (respectively labeled ROM, for “random orthogonal matrices,” and RUM, for “random unitary matrices”) probe the impact of inelastic (projection $m_l m_j$ -changing) scattering on the calculated signal. For the third row, Σ is an orthogonal matrix randomly drawn according to the Haar measure on $O(9)$, while Σ is a unitary matrix randomly drawn according to the Haar measure on $U(9)$ for the fourth row of each figure. Here, randomly drawing according to the Haar measure can be understood as analogous to drawing from the “uniform distribution” over the space of possible matrices [95]. The orthogonal matrices model inelastic scattering where no relative phase changes occur, while the unitary matrices model inelastic scattering where relative phase changes do occur. In both cases, there is no loss of total population during scattering. Clearly, the calculated

signals are also sensitive to inelastic-scattering events, both with and without relative phase changes. Finally, we can see that the number of peaks in the signal between 430 and 450 G varies as a function of the scattering matrix (compare the RDA and RUM plots in Fig. 6, for example).

VII. COMPARISON WITH A SEMICLASSICAL METHOD

The present approach is fully quantum mechanical, while, in their Supplemental Material, Godsi *et al.* [53] have described a semiclassical method for calculating $P_{\text{detection}}$ that they used to model the propagation of $o\text{-H}_2$ in their molecular hyperfine interferometer (see Ref. [79] for the case of spin-1/2 particles). This semiclassical method treats the internal degrees of freedom of the molecules quantum mechanically and the center-of-mass motion classically. As a result, the momentum changes induced by the magnetic field are ignored

and every internal state is described as propagating at the initial velocity v_0 of the molecule. The internal degrees of freedom are treated by applying the time evolution operator for the time period $t_i \equiv \frac{L_i}{v_0}$ spent in each magnetic field of length L_i . That is, the propagation is calculated in the molecular reference frame with a time-dependent Hamiltonian. Here, we compare the results of the semiclassical and fully-quantum approaches for $o\text{-H}_2$.

We compare the two methods under conditions close to the original application of the semiclassical method to flux-detection measurements [53]. We work with a field profile as shown in Fig. 3, but with the second arm assumed to be of zero length and $B_2 = 0$. The field B_1 is varied. For the sake of comparison, we also set the state selector and detector fields in the transfer-matrix method to 100 000 G so that the basis changes performed by the transfer-matrix method out of and into these regions match well the Clebsch-Gordon transformation from $|m_i m_j\rangle$ to $|Fm\rangle$ and its inverse, as used by the semiclassical method. Note that the off-diagonal elements of the full discontinuity matrix \mathbf{K} (30) are still only $\approx 10^{-5}$ at 100 000 G, such that their neglect still does not invalidate our fully quantum formalism at these large field strengths. We also retain the rotation from the first branch to the second branch and set the scattering matrix to $\mathbb{1}_9$. To maximize sensitivity of the comparison, we use only a single velocity when calculating $P_{\text{detection}}$ in both methods. All other parameters, including the state selector and detector relative state probabilities $\eta_{m_i m_j}$ and $\kappa_{m_i m_j}$, are as per Appendix D. This allows for a test that includes all incoming and outgoing states and their relative phases at experimentally relevant conditions.

The signals $P_{\text{detection}}(B_1)$ are calculated from B_1 to $B_1 + 10$ G for various values of B_1 . We include 1500 datapoints in these 10-G intervals. The calculated signals are compared between the two methods by calculating their relative absolute difference at identical conditions. This produces a relative absolute difference at each of the 1500 magnetic-field points. We then calculate the maximum, mean, and median relative absolute difference over the 10-G interval. Figure 8 shows how these maximum, mean, and median values vary as a function of B_1 . At low fields, there is no significant dependence on the magnetic field and the relative absolute difference is below the expected experimental error. This lack of dependence on B_1 is possibly due to some residual numerical error present in the implementation of one or both methods, which masks any underlying field dependence. At approximately 460 G, however, the error begins to increase with the magnetic field until it saturates at approximately 46 000 G at a relative absolute difference of approximately 1. This increase in error as a function of magnetic field points to a systematic difference between the two methods.

To illustrate the difference between the two approaches in more detail, we plot the Fourier transforms of the calculated signals at various magnetic-field strengths in Fig. 9. At field strengths below 1000 G, little difference is observed. At higher field strengths, the feature locations agree, while the Fourier amplitudes differ. The feature locations are determined by the eigenvalues of the Hamiltonian, identical in both methods, while the amplitudes are a function of the relative phases and amplitudes of the wave-function components. These amplitudes and phases are expected to differ between

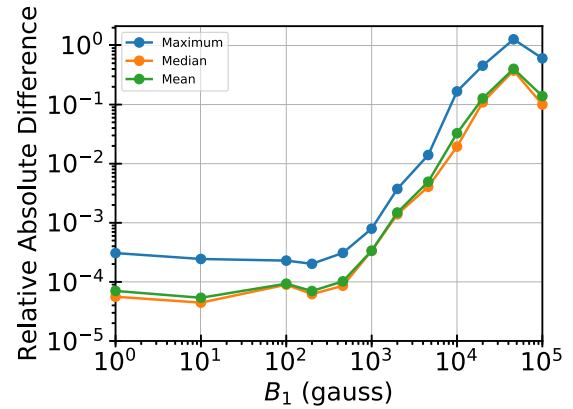


FIG. 8. Maximum, median, and mean relative absolute difference between the calculated signals obtained by the semiclassical method discussed in the Supplementary Material of Godsi *et al.* [53] and the present method, for various values of the controlling magnetic field. See Sec. VII for a description of the semiclassical method and the field profiles used. The relative absolute difference between the calculated signals is calculated point by point as a function of the magnetic field. The mean, median, and maximum values are then calculated over the magnetic-field interval spanned by the calculated signal. The calculated signal is sampled at a rate of 1500 points per 10 G; the magnetic field varies from B_1 to $B_1 + 10$ G for each calculated signal; a single velocity was included in the calculations; the scattering transfer matrix $\Sigma = \mathbb{1}_9$ and is constant for all energies. All other parameters are listed in Appendix D.

the two methods at sufficiently high fields because of the approximations made in the semiclassical method.

In particular, the semiclassical method accounts for *most* of the relative phase and amplitude changes induced by the controlling magnetic fields. It does this by time evolving the internal state vector for times that correspond to the time t_i spent in each magnetic field by a molecule moving at its unchanged initial velocity. However, the semiclassical method ignores the small changes in the molecular velocity caused by the magnetic fields. These changes to the velocity modify the time spent in each magnetic field for each individual component of the internal state vector. Thus, t_i should depend on the internal state $|R\rangle$. It is not immediately clear how to include these state-dependent velocity changes into the semiclassical method, however.

At low fields, these velocity changes and the dependence of t_i on $|R\rangle$ are negligible and the fully quantum calculations agree with the semiclassical results to at least 0.1% for fields below 1000 G. However, this agreement can only be expected to occur for surfaces that do not change between the surface-impact events of the spatially separated wave-packet components (discussed in Sec. II). The maximum temporal separation between these impact events, caused by the velocity changes, varies from a few to several hundred picoseconds. Many surfaces do change on this timescale, as has been measured in several ^3He spin-echo experiments [32,33,37,38]. In other words, the semiclassical method cannot be used to probe the dynamics of surfaces, while the method presented in this paper opens the possibility to account for the surface dynamics with molecular scattering experiments.

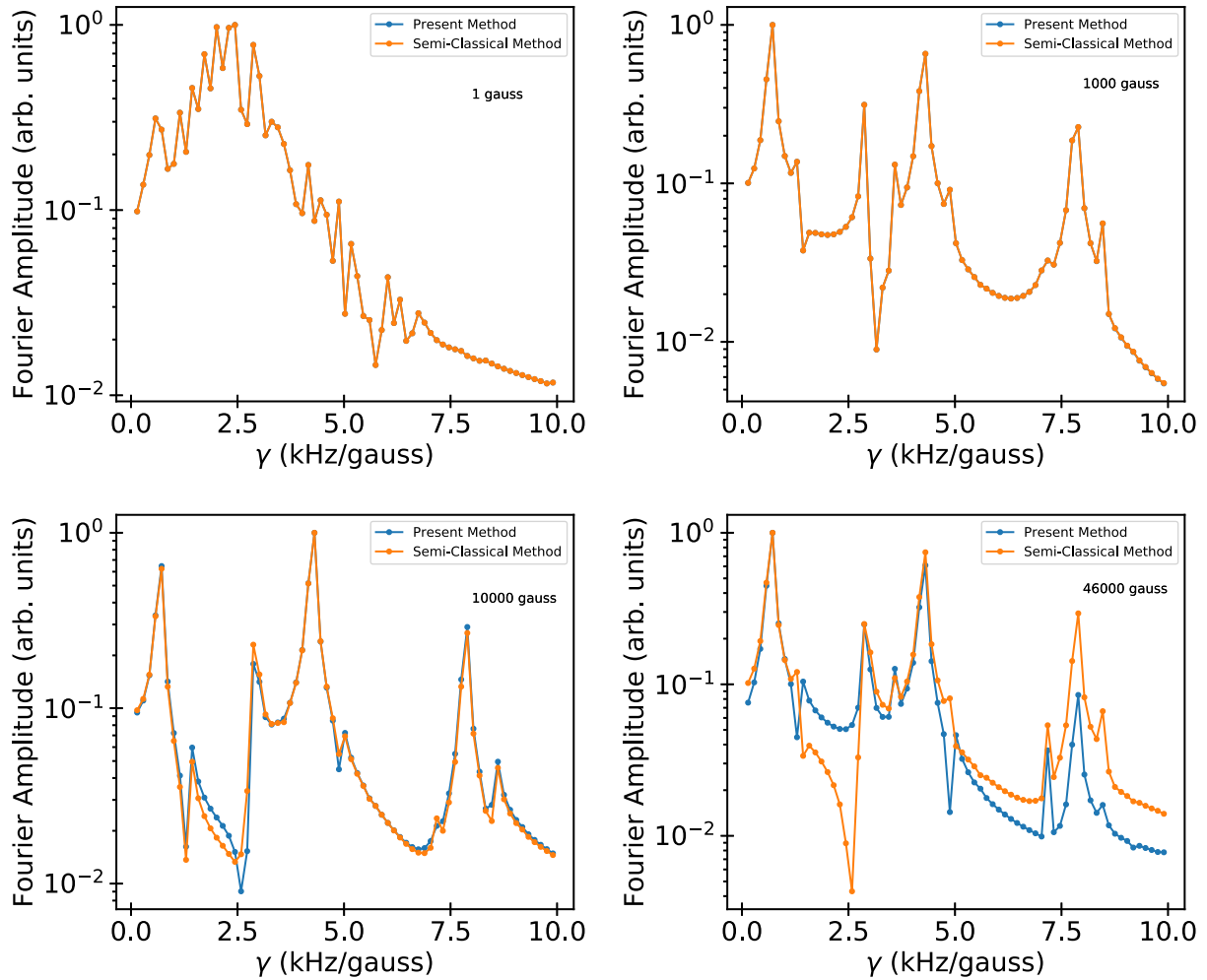


FIG. 9. Fourier amplitudes of the calculated signals at various magnetic-field values computed with the semiclassical method discussed in the Supplementary Material of Godsi *et al.* [53] (orange) and the present method (blue) as functions of the generalized gyromagnetic ratio γ . The calculation conditions are identical to those of Fig. 8.

VIII. CONCLUSION

In this paper, we have developed a theoretical framework for simulating a surface-sensitive molecular hyperfine interferometer. The approach treats the interferometer as an effective one-dimensional system, accounting for the real experimental geometry by rotating the quantization axis of the hyperfine states at the scattering point. The time evolution of the molecular states is described fully coherently and accounts for the mixing of the hyperfine states and momentum changes induced by the magnetic fields in the experiment. The present approach is fully quantum mechanical and includes a full description of the internal-state-dependent spatial superpositions imposed on the molecular wave packets by the controlling magnetic fields. This opens the possibility for a description of molecular scattering experiments that aim to probe surface dynamics on the picosecond to hundreds of picoseconds timescale. To build the framework, we have derived and implemented a transfer-matrix formalism that accounts for the internal (hyperfine) degrees of freedom of molecules and that allows for efficient computation of the experimental signal.

In the present paper, the molecule-surface interaction is accounted for by a scattering transfer matrix (a transformed version of the scattering matrix) that is suitable for the description of experiments where the surface changes either much more slowly or much more quickly than the molecule-surface or wave-packet-surface interaction times (i.e., the molecule-surface scattering event does not involve energy transfer between the surface and the molecule). The extension to arbitrary surface dynamics (currently under investigation) requires a time-dependent scattering transfer matrix that reflects the underlying time dependence of the molecule-surface interaction potential. Such a formalism would naturally incorporate energy transfers between the surface and the molecule during the scattering event. We have demonstrated, using the specific case of *o*-H₂, how the different features of the time-independent scattering transfer matrix, such as the phases of the diagonal elements, impact the experimental signal. In addition, we have shown that the experimental signal is sensitive to off-diagonal scattering matrix elements describing collisions that change the projection quantum numbers of the molecular hyperfine states without energy transfer between the molecule and the surface.

The present approach also sets the stage for solving the inverse scattering problem in molecular hyperfine interferometry by means of machine learning approaches, such as Bayesian optimization [69,92]. For example, one can use the results of the transfer-matrix computations presented here to train Gaussian process models of the predicted experimental signal [92]. The difference between the experimental observations and the results of the transfer-matrix computations can then be minimized by varying the scattering matrix elements, as described in our previous work [69]. The results of Bayesian optimization will determine the properties of the scattering matrix elements compatible with a given experimental measurement. These scattering matrix properties can then be used to gain physical insight into molecule-surface interactions and surface properties. They can also be used to test approximations used in *ab initio* calculations.

The formalism presented here is general to all closed-shell molecules and is flexible to describe various experimental

setups. It can be used to explore various experimental protocols and evaluate their effectiveness at determining various molecule-surface interactions and surface properties. Thus, this paper provides the theoretical framework necessary to interpret a wide range of molecular hyperfine interferometry experiments, which are poised to apply molecular-beam techniques to provide new information about molecule-surface interactions, surface morphologies, and surface dynamics.

ACKNOWLEDGMENTS

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APPENDIX A: SCHRÖDINGER EQUATION FOR EIGENSTATE COEFFICIENTS

Using Eq. (19), the time-independent Schrödinger equation is

$$\hat{H} |E\tilde{R}\rangle = E |E\tilde{R}\rangle, \quad (\text{A1})$$

$$\hat{K} |E\tilde{R}\rangle = (E - \hat{H}^R) |E\tilde{R}\rangle,$$

$$\begin{aligned} \sum_R \int dx \Phi_R^{E\tilde{R}}(x) \hat{K} |xR\rangle &= \sum_R \int dx \Phi_R^{E\tilde{R}}(x) (E - \hat{H}^R) |xR\rangle, \\ \sum_R \int dx \Phi_R^{E\tilde{R}}(x) \langle x_0 R_0 | \hat{K} |xR\rangle &= \sum_R \int dx \Phi_R^{E\tilde{R}}(x) \langle x_0 R_0 | (E - \hat{H}^R) |xR\rangle \end{aligned} \quad (\text{A2})$$

where \hat{H} is the total Hamiltonian (2) in the current region, $\hat{K} \equiv \frac{\hat{p}^2}{2m}$, we use \hat{H}^R as a shorthand for $\hat{H}^R(\vec{B}_{\text{loc}})$, and the last line was multiplied by $\langle x_0 R_0 |$.

The different terms can be evaluated as

$$\langle x_0 R_0 | \hat{K} |xR\rangle = \delta_{R_0 R} \langle x_0 | \int dk \frac{\hbar^2 k^2}{2m} |k\rangle \langle k|x\rangle = \int \frac{dk}{2\pi} \delta_{R_0 R} \frac{\hbar^2 k^2}{2m} e^{ik(x_0-x)}, \quad (\text{A3})$$

$$\langle x_0 R_0 | E |xR\rangle = \delta_{R_0 R} \delta(x - x_0) E, \quad (\text{A4})$$

$$\langle x_0 R_0 | \hat{H}^R |xR\rangle = \delta(x - x_0) H_{R_0 R}^R, \quad (\text{A5})$$

where $|k\rangle$ is a momentum state with wave number k , and m is the mass of the molecule. The additional factor of $(2\pi)^{-1}$ in Eq. (A3) comes from $\langle x|k\rangle \equiv (2\pi)^{-\frac{1}{2}} e^{ikx}$. After inserting these three equations into Eq. (A2) and evaluating most of the sums, we obtain

$$\int dx \int \frac{dk}{2\pi} \frac{\hbar^2 k^2}{2m} e^{ik(x_0-x)} \Phi_{R_0}^{E\tilde{R}}(x) = \Phi_{R_0}^{E\tilde{R}}(x_0) E - \sum_R H_{R_0 R}^R \Phi_R^{E\tilde{R}}(x_0). \quad (\text{A6})$$

Noting that $k^2 e^{ikx_0} = -\frac{\partial^2}{\partial x_0^2} e^{ikx_0}$ and $\int \frac{dk}{2\pi} e^{ik(x_0-x)} = \delta(x_0 - x)$, we obtain Eq. (20) after the relabeling $x_0 \rightarrow x$.

APPENDIX B: COEFFICIENT RELATIONS ACROSS A DISCONTINUITY

Since $\Phi_R^{E\tilde{R}}(x) \in C^1(x)$ for a specific value of R and given Eq. (26), we get the defining equations for the continuity of the wave function as

$$\begin{aligned} \lim_{x \rightarrow 0^-} \Phi_{R^+}^{E\tilde{R}}(x) &= \lim_{x \rightarrow 0^+} \Phi_{R^+}^{E\tilde{R}}(x), \\ \lim_{x \rightarrow 0^-} \sum_{R^-} \Phi_{R^-}^{E\tilde{R}}(x) S_{R^- R^+}^* &= \lim_{x \rightarrow 0^+} \Phi_{R^+}^{E\tilde{R}}(x), \end{aligned}$$

TABLE I. Relative probabilities of the state selector $\eta_{m_I m_J}$ and the detector $\kappa_{m_I m_J}$. The state selector probabilities P_{R_0} are calculated as $P_{R_0} = P_{m_I m_J} \equiv \eta_{m_I m_J} / \sum_{m_I m_J} \eta_{m_I m_J}$ and the detector coefficients c_{R_D} are calculated as $c_{R_D} = c_{m_I m_J} \equiv \kappa_{m_I m_J} / \sum_{m_I m_J} \kappa_{m_I m_J}$.

m_I	1	1	1	0	0	0	-1	-1	-1
m_J	1	0	-1	1	0	-1	1	0	-1
$\eta_{m_I m_J}$	0.0095	0.0138	0.0187	0.0416	0.0436	0.0606	0.3997	0.9015	1.0
$\kappa_{m_I m_J}$	0.0611	0.08	0.1027	0.3834	0.5705	0.8425	1.0	0.9422	0.7209

$$\lim_{x \rightarrow 0^-} \sum_{R^-} S_{R^- R^+}^* (A_{R^-} e^{ik_{R^-} x} + B_{R^-} e^{-ik_{R^-} x}) = \lim_{x \rightarrow 0^+} A_{R^+} e^{ik_{R^+} x} + B_{R^+} e^{-ik_{R^+} x} \quad [\text{Eq. (22)}],$$

$$A_{R^+} + B_{R^+} = \sum_{R^-} S_{R^- R^+}^* (A_{R^-} + B_{R^-}), \quad (\text{B1})$$

where $S_{R^- R^+}^* \equiv \langle R^+ | R^- \rangle$, $k_{R^\pm} \equiv \frac{\sqrt{2m(E - E_{R^\pm})}}{\hbar}$, and $E_{R^\pm} \equiv \langle R^\pm | \hat{H}^R(\vec{B}(0^\pm)) | R^\pm \rangle$. There are N_R such equations, one for each value of R^+ .

Correspondingly, the defining equations for the continuity of the first derivative of the coefficients are

$$\begin{aligned} \lim_{x \rightarrow 0^-} \frac{\partial}{\partial x} \Phi_{R^+}^{ER}(x) &= \lim_{x \rightarrow 0^+} \frac{\partial}{\partial x} \Phi_{R^+}^{ER}(x), \\ \lim_{x \rightarrow 0^-} \sum_{R^-} \frac{\partial}{\partial x} \Phi_{R^-}^{ER}(x) S_{R^- R^+}^* &= \lim_{x \rightarrow 0^+} \frac{\partial}{\partial x} \Phi_{R^+}^{ER}(x), \\ \lim_{x \rightarrow 0^-} \sum_{R^-} S_{R^- R^+}^* \frac{\partial}{\partial x} (A_{R^-} e^{ik_{R^-} x} + B_{R^-} e^{-ik_{R^-} x}) &= \lim_{x \rightarrow 0^+} \frac{\partial}{\partial x} (A_{R^+} e^{ik_{R^+} x} + B_{R^+} e^{-ik_{R^+} x}) \quad [\text{Eq. (22)}], \\ \lim_{x \rightarrow 0^-} \sum_{R^-} S_{R^- R^+}^* ik_{R^-} (A_{R^-} e^{ik_{R^-} x} - B_{R^-} e^{-ik_{R^-} x}) &= \lim_{x \rightarrow 0^+} ik_{R^+} (A_{R^+} e^{ik_{R^+} x} - B_{R^+} e^{-ik_{R^+} x}), \\ A_{R^+} - B_{R^+} &= \sum_{R^-} S_{R^- R^+}^* \frac{k_{R^-}}{k_{R^+}} (A_{R^-} - B_{R^-}). \end{aligned} \quad (\text{B2})$$

Solving Eqs. (B1) and (B2) for the coefficients A_{R^+} and B_{R^+} , we obtain Eqs. (27) and (28).

APPENDIX C: COMPUTATIONAL PARAMETERS USED FOR THE APPLICATION TO ORTHOHYDROGEN

We take the mean velocity $v_0 = 1436.14 \text{ m s}^{-1}$ and the velocity spread to be 4% full width at half maximum. When performing the integral of Eq. (18), we take a k -space grid spacing $\Delta k = 1 \times 10^4 \text{ cm}^{-1}$ and integrate from $-7\sigma_k$ to $+7\sigma_k$, where σ_k is the Gaussian width in momentum space as defined in Sec. III. For the magnetic-field profile and the angles between the two branches of the apparatus, see Fig. 3. The relative probabilities used for the state selector probabilities P_{R_0} and the detector coefficients c_{R_D} are given in Table I.

Where applicable, the parameters above were chosen to match those in the supplementary information of Godsi

et al. [53], apart for the relative probabilities in Table I. The relative probabilities in Table I were obtained from improved semiclassical calculations of the molecular propagation through the magnetic lens [53,87].

APPENDIX D: COMPUTATIONAL PARAMETERS USED FOR THE COMPARISON WITH THE SEMICLASSICAL METHOD

We take the mean velocity $v_0 = 1436.14 \text{ m s}^{-1}$. The relative probabilities used for the state selector probabilities P_{R_0} and the detector coefficients c_{R_D} are given in Table II. Where applicable, the parameters were chosen to match those in the supplementary information of Godsi *et al.* [53].

TABLE II. Relative probabilities of the state selector $\eta_{m_I m_J}$ and the detector $\kappa_{m_I m_J}$, as used in the comparison to the semiclassical method of Godsi *et al.* [53]. The state selector probabilities P_{R_0} are calculated as $P_{R_0} = P_{m_I m_J} \equiv \eta_{m_I m_J} / \sum_{m_I m_J} \eta_{m_I m_J}$ and the detector coefficients c_{R_D} are calculated as $c_{R_D} = c_{m_I m_J} \equiv \kappa_{m_I m_J} / \sum_{m_I m_J} \kappa_{m_I m_J}$.

m_I	1	1	1	0	0	0	-1	-1	-1
m_J	1	0	-1	1	0	-1	1	0	-1
$\eta_{m_I m_J}$	1.0000	0.9755	0.7901	0.1465	0.1111	0.0738	0.0343	0.0299	0.0258
$\kappa_{m_I m_J}$	1.00	0.96	0.93	0.53	0.42	0.37	0.21	0.19	0.16

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