Bounds on Scattering Phase Shifts. II*

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Though the Kato technique for obtaining bounds on the cotangent of the scattering phase shift, $\bar{\eta}_L$, is extremely general and powerful, an integration must be performed which can be quite troublesome, and some preliminary, albeit crude, information about $\bar{\eta}_L$ is required before the method can be applied. It is shown here that in the evaluation of the *upper* bound on $\cot \bar{\eta}_L$, the integration can often be eliminated without any significant increase in the value of the upper bound. It is also shown that the Kato formalism is often useful even when one does not possess the necessary *a priori* knowledge of $\bar{\eta}_L$; under realistic specified conditions, a bound can be obtained on $\bar{\eta}_L$ even when a bound on $\bar{\eta}_L$ can be improved. The bound on $\bar{\eta}_L$ is of interest in its own right. It may also help to provide the preliminary information necessary for the determination of bounds on $\cot \bar{\eta}_L$.

It is shown that if the potential V(r) is nonpositive, $\bar{\eta}_{L+}$ and/or $|\bar{\eta}_{L-}|$ must be larger than the Born phase shift η_{BL+} , where $\bar{\eta}_{L\pm}$ are the phase shifts associated with $\pm V$; if $V(r) \leq 0$ and if $|\bar{\eta}_{L\pm}| < \pi$, then $\cot \bar{\eta}_{L+}$ $-\cot \bar{\eta}_{L-} \leq 2 \cot \eta_{BL+}$. A slight generalization of the Schwinger integral variational principle gives similar results for phases related to $V \pm U$.

1. INTRODUCTION

TARIATIONAL techniques have proved invaluable in scattering theory, in the evaluation of phase shifts, for example. They nevertheless suffer from the serious disadvantage, compared to the corresponding variational calculations of binding energies, for instance, that they do not provide a bound on the phase shift. This disadvantage is most pronounced in problems of such difficulty that one cannot guess at a reasonable form for the trial function, though it is precisely for those problems that variational techniques are potentially most valuable. (We might for example be interested in a particular problem of scattering by a compound system which could not readily be handled by a machine.) For a poor trial function, the secondorder error involved in the variational calculation is not necessarily small. Further, there is the disheartening feature that the inclusion of additional parameters into the trial function may give worse rather than better results.

For these reasons, the general and powerful (and elegant) technique introduced by Kato¹ for obtaining upper and lower bounds on $\cot(\bar{\eta}_L - \theta)$ is of considerable significance. For nonrelativistic scattering by a central field, Kato deduced the inequality

$$-\alpha_{\theta L}^{-1} \epsilon_{\theta L}^{2} \leq k \cot(\bar{\eta}_{L} - \theta) - k \cot(\eta_{L} - \theta) + \int u_{\theta L} \mathfrak{L}_{L} u_{\theta L} dr \leq \beta_{\theta L}^{-1} \epsilon_{\theta L}^{2}, \quad (1.1)$$

where

$$\epsilon_{\theta L}^{2} = \int \rho^{-1} (\mathfrak{L}_{L} \mathfrak{u}_{\theta L})^{2} dr. \qquad (1.2)$$

The generality of the method consists in the fact that there are no restrictions on the central potential; in principle, it can also be applied to more complicated problems such as the scattering by a compound system. The power of the method lies in the latitude that one has in the choice of the normalization, θ , the trial function, $u_{\theta L}$, and the weight factor, ρ .

There remain nevertheless two disturbing questions. The first is the practical question concerning the difficulty of performing the integration that appears in Eq. (1.2). The second question, a more serious one in principle, is whether one can in fact determine the eigenvalues $\alpha_{\theta L}$ and $\beta_{\theta L}$, or bounds on them which preserve the inequality. Now, it is known^{1,2} that there is a wide variety of central potentials for which neither of the two questions proves to be very serious. In these cases, the integrals are not really too tedious, and it is not very difficult to obtain bounds on $\alpha_{\theta L}$ and $\beta_{\theta L}$. On the other hand, in scattering by a compound system, for example, these questions assume much more serious proportions. As is not too surprising, other questions arise in an attempt to obtain bounds on the phase shift for scattering by a compound system. These will be treated at a later date. It is more profitable to examine scattering by a fixed potential first, but from a point of view such that the results will prove useful for application to scattering by a compound system. Thus, techniques are sought whereby it will not be necessary to evaluate the integral in Eq. (1.2), since for scattering by a compound system the integration of the analog of Eq. (1.2) may well be prohibitively laborious.

² L. Spruch and M. Kelly, Phys. Rev. 109, 2144 (1958), preceding paper.

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¹T. Kato, Progr. Theoret. Phys. (Kyoto) **6**, 394 (1951). All of the references to Kato are to this article, and the terminology and notation follow this article and that of reference 2. See also Progr. Theoret. Phys. (Kyoto) **6**, 295 (1951), and Phys. Rev. **80**, 475 (1950).

Further, we seek techniques by means of which one can obtain $\alpha_{\theta L}$ and/or $\beta_{\theta L}$ with a minimum of *a priori* information about $\overline{\eta}_L$, or, assuming that one *cannot* obtain $\alpha_{\theta L}$ or $\beta_{\theta L}$, we seek any information which can still be extracted from the Kato formalism. (In the case of a fixed central potential, bounds on $\alpha_{\theta L}$ and $\beta_{\theta L}$ can generally be determined by comparison of the given potential with known solvable potentials^{1,2}; this is not generally possible in the case of scattering by a compound system, since there are no such realistic solvable potentials.)

With regard to the first question, concerning the elimination of the integration, we note that under specified conditions^{1,2} $\beta_{\theta L}$ is infinite. Under these circumstances, for the purposes of obtaining an upper bound on $\cot(\bar{\eta}_L - \theta)$, the integration need not be performed. The evaluation of an upper bound is then not essentially more complicated than the usual variational calculation. The conditions include the requirement that the potential be of a solvable form beyond some point a. We consider for the moment the simplest such example, that of a potential which vanishes identically beyond the point a. This suggests,² for a "potential" $W(\mathbf{r})$ which is non-negative but which does not vanish identically, that one define a cutoff potential $W^{c}(r)$ $=W(r)\Sigma(a-r)$, where $\Sigma(a-r)$ is a step function. By the appropriate choice of a, one can cause the $\beta_{\theta L}^{c}$, associated with $W^{c}(r)$, to be infinite, in which case $\bar{\eta}_L^c$, the *L*th phase shift associated with $W^c(r)$, can be bounded from above without performing the complicated integration. Since $W(r) \ge W^c(r)$, it follows that $\bar{\eta}_L > \bar{\eta}_L^c$, so that the bound obtained on $\bar{\eta}_L^c$ serves as a bound on $\bar{\eta}_L$ as well. While this has been shown to be a reasonable procedure² in general, there is sometimes a considerable loss in accuracy, in that it may be necessary to choose a rather small value of a. The difference between W and W^c may then be considerable, in which case even a close bound on $\bar{\eta}_L^c$ will be a poor bound on $\bar{\eta}_L$. It will be shown in Sec. 3 that the introduction of a constraint on the trial function, $u_{\theta L}$, makes possible an increase in the value of a, thereby decreasing the difference between W and W^c and therefore between $\bar{\eta}_L$ and $\bar{\eta}_L^c$, and making it possible to obtain a better upper bound on $\bar{\eta}_L$. Since it turns out that the constraint on $u_{\theta L}$ is almost always satisfied automatically, there is no real loss of freedom in the choice of $u_{\theta L}$.

Since there does not seem to be any way of eliminating the troublesome integral when one seeks a *lower* bound on $\cot(\bar{\eta}_L - \theta)$, it is only the upper bound which can ever be obtained relatively simply. This upper bound is of course of interest in its own right; there is in addition the pleasant feature associated with the presence of even only one bound that the inclusion of more free parameters in the trial function guarantees an improved result.

It will also be shown in Sec. 3 that it is still very

profitable to introduce the constraint on $u_{\theta L}$ where one *must* evaluate the integral, or where one prefers to evaluate the integral rather than lose any accuracy at all by introducing $W^c(r)$. If, as is usually the case, the constraint is automatically satisfied, one obtains an improved bound, as compared to that given in the formulation of Kato, without doing any additional calculation.

Turning now to the second question, concerning the prior knowledge of $\bar{\eta}_L$, we assume, in line with the previous discussion, that so little is known about $\bar{\eta}_L$ that $\alpha_{\theta L}$ and $\beta_{\theta L}$ cannot be determined. Even though one *cannot* then obtain a bound on $\cot(\bar{\eta}_L - \theta)$, it will be shown in Sec. 4 that under realistic specified conditions, the Kato method *does* give a bound on $\bar{\eta}_L$ itself. Further, a procedure analogous to iteration will be introduced in Sec. 5 whereby this bound on $\bar{\eta}_L$ may successively be improved. The bound on $\bar{\eta}_L$ is of course of interest in its own right; it may also help to provide the preliminary information necessary for the application of the Kato method to the determination of bounds on $\cot(\bar{\eta}_L - \theta)$.

In Sec. 2, a property of the Schwinger integral variational principle deduced by Kato will be used to develop a very simple but useful inequality involving the phases $\bar{\eta}_{L\pm}$ associated with $\pm W(r)$, and the Born phase shift. A similar inequality is deduced involving phases related to $W(r)\pm U(r)$ by starting with a slight generalization of the Schwinger principle.

2. EQUAL AND OPPOSITE POTENTIALS

A. Phase Shifts Associated with $\pm W$

Assume that the *L*th phase shift $\bar{\eta}_{L+}$ associated with $W(r) \ge 0$ satisfies $\bar{\eta}_{L+} < \pi$. Under these circumstances, as was shown by Kato, a bound on $k \cot \bar{\eta}_{L+}$ is provided by the Schwinger integral variational principle, that is,

$$k \cot \bar{\eta}_{L+} \leq \int W v_{L+}^2 d\mathbf{r} - \int d\mathbf{r} \int d\mathbf{r}' v_{L+} W G_L W v_{L+}, \quad (2.1)$$

where the only restriction on the trial function $v_{L+}(r)$ is that it must satisfy

$$k^{-1} \int kr j_L(kr) W(r) v_{L+}(r) dr = 1, \qquad (2.2)$$

and where the free-particle Green's function $G_L(r,r')$ is given by

$$G_L(\mathbf{r},\mathbf{r}') = -k^{-1}k\mathbf{r}_{<}j_L(k\mathbf{r}_{<})k\mathbf{r}_{>}n_L(k\mathbf{r}_{>}).$$
(2.3)

Assume further that the *L*th phase shift $\bar{\eta}_{L-}$ associated with -W(r) satisfies $\bar{\eta}_{L-} > -\pi$. Then, similarly,

$$k \cot \bar{\eta}_{L-} \ge \int (-W) v_{L-}^{2} dr - \int dr \int dr' v_{L-} (-W) G_{L} (-W) v_{L-}, \quad (2.4)$$

where the only restriction on $v_{L-}(r)$ is that it must satisfy

$$k^{-1}\int kr j_L(kr)[-W(r)]v_{L-}(r)dr = 1.$$
 (2.5)

From Eqs. (2.2) and (2.5), it is clear that it is permissible to choose $v_{L-}(r) = -v_{L+}(r)$. If this is done, it follows from (2.1) and (2.4) that

$$\cot \bar{\eta}_{L+} - \cot \bar{\eta}_{L-} \leq 2k^{-1} \int W(r) v_{L+}^{2}(r) dr,$$
 (2.6)

where $v_{L+}(r)$ satisfies (2.2). Equation (2.6), which gives a bound for one of the two phases if the other is known, has the pleasant feature that it does not contain $G_L(r,r')$; the question as to whether it is likely to provide a useful bound remains to be discussed.

The choice of $v_{L+}(r)$ will now be considered. We can write

$$\cot \bar{\eta}_{L+} - \cot \bar{\eta}_{L-} \leq F[v_{L+}], \qquad (2.7)$$

where the functional $F[v_{L+}]$ is given by

$$F[v_{L+}] = 2k \int W v_{L+}^2 dr \left[\int kr j_L(kr) W v_{L+} dr \right]^{-2}, \quad (2.8)$$

and where there are now no restrictions whatever on $v_{L+}(r)$. If, in the denominator, we use the fact that $W(r) \ge 0$ to write $W(r) = W^{\frac{1}{2}}(r)W^{\frac{1}{2}}(r)$, an application of Schwarz' inequality gives

$$\left[\int kr j_L(kr) W v_{L+} dr\right]^2 \leq \int [kr j_L(kr)]^2 W dr \int W v_{L+}^2 dr.$$

It then follows that

$$F[v_{L+}] \ge 2k \left[\int [krj_L(kr)]^2 W dr \right]^{-1}$$
$$= 2 \cot \eta_{BL+} = -2 \cot \eta_{BL-}, \quad (2.9)$$

where $\eta_{BL\pm}$ is the *L*th phase shift for $\pm W$ in the Born approximation. On the other hand,

$$F[v_{L+}=krj_L(kr)]=2\cot\eta_{BL+}.$$
(2.10)

It follows from Eqs. (2.7), (2.9), and (2.10) that once one has chosen $v_{L-}(r) = -v_{L+}(r)$, the *best* possible choice for $v_{L+}(r)$ is $krj_L(kr)$. In summary, we see that if $W(r) \ge 0$, if $\bar{\eta}_{L+} < \pi$, and if $\bar{\eta}_{L-} > -\pi$, then

$$\cot \bar{\eta}_{L+} - \cot \bar{\eta}_{L-} \leq 2 \cot \eta_{BL+}. \tag{2.11}$$

One might expect the bound given by (2.11) to be exceedingly poor, because of the choice $v_{L-}(r) = -v_{L+}(r)$. Actually, due to the presence of the Green's function in the Schwinger variational principle, it is somewhat misleading to think of $v_{L+}(r)$ and $v_{L-}(r)$ as the trial functions. Thus, the trial functions in the



FIG. 1. A comparison of $\cot \overline{\eta}_{L+} - \cot \overline{\eta}_{L-}$ (the solid curves) with its upper bound, $2 \cot \eta_{BL+}$ (the dashed curves), for the case of a square well of strength W_0 and range a. $\overline{\eta}_{L\pm}$ and η_{BL+} are the exact phase shifts associated with $\pm W$ and the Born approximation phase shift, respectively. The values of L and of ka for curves A, B, and C are L=0, 0, and 1, and $ka=5\pi/4$, 10π , and 2, respectively. The plus and minus signs on the graph represent the points at which $\overline{\eta}_{L+} = \frac{1}{2}\pi$ and at which $\overline{\eta}_{L-} = -\frac{1}{2}\pi$.

Kato formalism which give rise to the Schwinger variational principle are

$$u_{0L\pm}(r) = \cot \eta_{L\pm} kr j_L(kr) + \int G_L(\pm W) v_{L\pm} dr'. \quad (2.12)$$

Then, with $v_{L+}(r) = kr j_L(kr) = -v_{L-}(r)$, we have

 $u_{0L\pm}$

$$(\mathbf{r}) = \cot \eta_{L\pm} k r j_L(kr) + \int G_L(\mathbf{r},\mathbf{r}') W(\mathbf{r}') k r' j_L(kr') d\mathbf{r}'. \quad (2.13)$$

The choices of η_{L+} and η_{L-} are each completely arbitrary, so that there can be considerable difference between u_{0L+} and u_{0L-} . More important is the fact that if $\bar{\eta}_{L+}$ and $|\bar{\eta}_{L-}|$ are not too large, u_{0L+} and u_{0L-} should be fairly reasonable trial functions. (It is to be noted that if η_{L+} and $|\eta_{L-}|$ are less than $\frac{1}{2}\pi$, $\cot\eta_{L+}$ and $\cot\eta_{L-}$ will be of opposite sign, so that the "correction terms" involving the integral appear in (2.13) for u_{0L+} and u_{0L-} in effect with opposite signs, as they should.) Equation (2.11) should not therefore give too crude a bound for $\bar{\eta}_{L+}$ and $|\bar{\eta}_{L-}|$ not too large. As examples, we have plotted in Fig. 1 the bounds on and the exact values of $\cot\bar{\eta}_{L+} - \cot\bar{\eta}_{L-}$ for the case of a square well for a few sets of values of the parameters. It can be seen that, qualitatively, the bound becomes crude only when $\bar{\eta}_{L+}$ or $|\bar{\eta}_{L-}|$ is of the order of $\frac{1}{2}\pi$.

When Eq. (2.11) is valid, $\bar{\eta}_{L+}$ or $|\bar{\eta}_{L-}|$, or both, must be larger than η_{BL+} . Since η_{BL+} as defined by (2.9) is less than π (in fact, it is less than $\pi/2$), it follows without any prior information about $\bar{\eta}_{L+}$ or $|\bar{\eta}_{L-}|$, that if $W(r) \ge 0$, then at least one of $\bar{\eta}_{L+}$ and $|\bar{\eta}_{L-}|$ must be larger than η_{BL+} .

B. Phase Shifts Associated with $W \pm U$

The above results can be generalized somewhat. Let W(r) be a solvable "potential"; in particular, let the phase shift $\bar{\eta}_L$, the "absolute normalization" solution $f_L(r)$, and the (irregular) solution $g_L(r)$ which has the asymptotic form

$$\bar{g}_L(r) \rightarrow -\cos(kr - \frac{1}{2}L\pi + \bar{\eta}_L)$$
 (2.14)

be known. Let the Lth phase shifts associated with $W \pm U$ be $\bar{\eta}_L \pm \Delta \bar{\eta}_{L+}$, respectively. (The $\Delta \bar{\eta}_{L\pm}$ are of course not the phase shifts associated with $\pm U$.) No assumptions are made regarding the relative magnitudes or ranges of W and U. We seek a simple inequality of the form of Eq. (2.11) which involves the $\Delta \bar{\eta}_{L\pm}$.

Kato determined bounds not only for phase shifts but for "additional phase shifts" of the type $\Delta \bar{\eta}_{L\pm}$. If $U(r) \ge 0$ [no such assumption must be made for W(r)], and if $\Delta \bar{\eta}_{L+} < \pi$, the choice $\rho = U$ and $\theta = 0$ gives $\beta_{0L+}=1$, and the bound becomes

$$k \cot \Delta \bar{\eta}_{L+} \leq k \cot \Delta \eta_{L+} - \int u_{0L+} \mathcal{L}_{L+} u_{0L+} dr$$
$$+ \int U^{-1} (\mathcal{L}_{L+} u_{0L+})^2 dr, \quad (2.15)$$

where

$$\mathfrak{L}_{L\pm} = rac{d^2}{dr^2} + k^2 - rac{L(L+1)}{r^2} + W \pm U,$$

and where the trial function u_{0L+} must vanish at the origin and must have the asymptotic form

$$u_{0L+} \rightarrow \cos(kr - \frac{1}{2}L\pi + \bar{\eta}_L) + \cot\Delta\eta_{L+}\sin(kr - \frac{1}{2}L\pi + \bar{\eta}_L). \quad (2.16)$$

Choose

 $u_{0L+}(r) = \cot \Delta \eta_{L+} \bar{f}_L(r)$

+
$$\int g_L(\mathbf{r},\mathbf{r}')U(\mathbf{r}')v_{L+}(\mathbf{r}')d\mathbf{r}',$$
 (2.17)

where the Green's function G_L is given by

$$g_L(\mathbf{r},\mathbf{r}') = -k^{-1} \bar{f}_L(\mathbf{r}_{<}) \bar{g}_L(\mathbf{r}_{>}),$$
 (2.18)

and where the only restriction on v_{L+} is the normalization condition

$$k^{-1} \int \bar{f}_L(r) U(r) v_{L+}(r) dr = 1.$$
 (2.19)

Equation (2.15) then becomes

$$\cot\Delta \bar{\eta}_{L+} \leq k \bigg(\int U v_{L+}^2 dr - \int v_{L+} U \mathcal{G}_L U v_{L+} dr \bigg) \\ \times \bigg(\int U \bar{f}_L v_{L+} dr \bigg)^{-2}. \quad (2.20)$$

The right side of (2.20) is a slight generalization of the Schwinger integral variational expression for the phase shift. It does not seem to have appeared in print, though the corresponding generalization of the Schwinger integral variational principle for the scattering amplitude has been given.³

Equation (2.20) will not in fact often be useful as it stands, due to the presence of the Green's function. It can be of use, however, when employed in conjunction with the corresponding bound on $\cot \Delta \bar{\eta}_{L-}$ which arises if $\Delta \bar{\eta}_{L-} > -\pi$. An analysis identical to that of subsection A gives

$$\cot\Delta\bar{\eta}_{L+} - \cot\Delta\bar{\eta}_{L-} \leq 2k \left(\int U\bar{f}_L^2 dr\right)^{-1}.$$
 (2.21)

This bound can be expected to be useful if, roughly speaking, $\Delta \bar{\eta}_{L+}$ and $|\Delta \bar{\eta}_{L-}|$ are each rather less than $\frac{1}{2}\pi$.

Equations (2.11) and (2.21) have the virtue that the bounds are simple to calculate, for they do not involve the Green's function, and yet the bounds differ from the true value by a second-order term since they arise from variational forms.

3. INTRODUCTION OF $_{2}\beta_{\theta L}$

A. Advantage of Introducing $_{2}\beta_{\theta L}$

By definition, $-\beta_{\theta L}$ is that negative eigenvalue $\mu_{m'L}$ which is smallest in absolute magnitude, so that

$$(-\mu_{mL})^{-1} \leq (\beta_{\theta L})^{-1}$$
, for all *m*. (3.1)

(The value of m' depends upon the problem under consideration.) The second-order error term in the Kato variational principle is given by⁴

$$\int w_{\theta L} \mathfrak{L}_{L} w_{\theta L} dr = k \sum_{m} (-\mu_{mL})^{-1} b_{mL}^{2}, \qquad (3.2)$$

where w is the difference between the trial function and the exact function, where

$$\sum_{m} b_{mL}^2 = k^{-1} \int \rho^{-1} (\mathfrak{L}_L u_{\theta L})^2 dr = k^{-1} \epsilon_{\theta L}^2, \quad (3.3)$$

and where

$$b_{mL} = k^{-1} \int \phi_{mL} \mathfrak{L}_L u_{\theta L} dr \qquad (3.4)$$

$$= -\mu_{mL}k^{-1}\int w_{\theta L}\rho\phi_{mL}dr. \qquad (3.5)$$

³ See, for example, H. E. Moses, Phys. Rev. 96, 519 (1954). ⁴ A factor of k is missing from some of Kato's formulas, but not from any of his final results.

The ϕ_{mL} are the eigenfunctions of the associated eigenvalue problem. It follows that

$$\int w_{\theta L} \mathcal{L}_L w_{\theta L} d\mathbf{r} \leq (\beta_{\theta L})^{-1} \int \rho^{-1} (\mathcal{L}_L u_{\theta L})^2 d\mathbf{r}.$$
 (3.6)

It will be shown later that is often possible to choose the trial function $u_{\theta L}$ in such a way that $b_{m'L}=0$. (This is certainly not always possible for one cannot generally solve for $\phi_{m'L}$.) In those cases for which $b_{m'L}=0$, Eq. (3.2) becomes

$$\int w_{\theta L} \mathfrak{L}_L w_{\theta L} d\mathbf{r} = k \sum' (-\mu_{mL})^{-1} b_{mL}^2, \qquad (3.7)$$

where the prime on the sum denotes the exclusion of the value m=m', while Eq. (3.3) becomes

$$\sum' b_{mL}^2 = k^{-1} \int \rho^{-1} (\mathfrak{L}_L u_{\theta L})^2 dr.$$
 (3.8)

We now define

$$_{2}\beta_{\theta L} = -\mu_{m'-1,L},$$
 (3.9)

so that $-{}_{2}\beta_{\theta L}$ is the negative eigenvalue which is second smallest in absolute magnitude; hence

$$(-\mu_{mL})^{-1} \leq ({}_{2}\beta_{\theta L})^{-1}, \quad m \neq m',$$
 (3.10)

and it follows, if $b_{m'L} = 0$, that

$$\int w_{\theta L} \mathcal{L}_L w_{\theta L} d\mathbf{r} \leq ({}_2 \beta_{\theta L})^{-1} \int \rho^{-1} (\mathcal{L}_L u_{\theta L})^2 d\mathbf{r}.$$
(3.11)

There are three quite different possible advantages associated with (3.11) as opposed to (3.6). (a) There is the simple fact that ${}_{2}\beta_{\theta L}$ is larger than $\beta_{\theta L}$ so that the upper bound on the error term and on $\cot(\bar{\eta}_{L}-\theta)$ is reduced. (b) In the replacement of W(r) by a cutoff "potential," $W^{c}(r)$, which enables one to drop the difficult second-order error integral, it will be possible to choose a larger value of the cutoff point *a*. (c) There are circumstances for which ${}_{2}\beta_{\theta L}$ is infinite while $\beta_{\theta L}$ is finite.

Examples of these three cases will be treated in subsections C, D, and E, respectively. First, however, we will demonstrate with an example that there are in fact cases for which one can arrange to have $b_{m'L}=0$.

B. Possibility of Introducing $_{2}\beta_{\theta L}$

There exists one particularly important case for which it is trivial to solve for $\phi_{m'L}$, namely, that of a non-negative W(r) whose Lth phase shift is less than π . For the choice $\rho = W$ and $\theta = 0$, a solution of the associated eigenvalue problem which satisfies the necessary boundary and normalization conditions is

$$\phi_{m'L} = \phi_{0L} = Nkr j_L(kr), \qquad (3.12)$$

where the dimensionless constant N is determined from

the relation

$$k^{-1} \int \left[N k r j_L(kr) \right]^2 W(r) dr = 1.$$
(3.13)

(In this case, $\beta_{m'L} = \beta_{0L} = -\mu_{0L} = 1$, and $_{2}\beta_{0L} = -\mu_{-1, L}$ is greater than one.)

It follows from Eq. (3.5) that

$$b_{m'L} = b_{0L} = k^{-1} N \int (u_{0L} - \bar{u}_{0L}) W kr j_L(kr) dr. \quad (3.14)$$

It is then a consequence of the relation

$$\int \bar{u}_{0L} W k r j_L(kr) dr = k, \qquad (3.15)$$

which is just the usual exact expression for $k \sin \bar{\eta}_L$, written with $\theta=0$ normalization rather than absolute normalization, that $b_{m'L}=b_{0L}=0$ if u_{0L} satisfies

$$\int u_{0L}Wkrj_L(kr)dr = k, \qquad (3.16)$$

as well as the usual boundary conditions. Equation (3.16) is to be satisfied by adjustment of the parameters contained in u_{0L} . (Alternatively, it is possible to choose a trial function v_{0L} which satisfies the necessary boundary conditions, and then to subtract from v_{0L} that component which is not orthogonal with weight factor $\rho = W$ to ϕ_{0L} , i.e., to set

$$u_{0L} = v_{0L} - [Nkrj_L(kr)] \times \left[-N + Nk^{-1} \int v_{0L} Wkrj_L(kr) dr \right]$$

This trial function satisfies (3.16) and the boundary conditions automatically, i.e., without adjustment of any parameters, but it may be unwieldy.)

It is important to recognize that the constraint imposed upon u_{0L} by (3.16) is not an unnatural one; on the contrary, as seen from (3.15), the exact function \bar{u}_{0L} satisfies precisely this condition. Furthermore, for a very natural choice of the form of u_{0L} and for some very natural methods of determining the constants which characterize u_{0L} , Eq. (3.16) will automatically be satisfied. In particular if we write

$$u_{0L}(\mathbf{r}) = \cot \eta_L k r j_L(k \mathbf{r}) + Y_L(\mathbf{r}), \qquad (3.17)$$

where Y_L satisfies the necessary boundary conditions and depends upon various constants C_i but not on $\cot \eta_L$, and if, following Kato, we choose the C_i and $\cot \eta_L$ by minimization of

$$\epsilon_{0L}^2 = \int \rho^{-1} (\mathcal{L}_L u_{0L})^2 dr, \qquad (3.18)$$

minimization of ϵ_{0L}^2 with respect to $\cot \eta_L$ can readily be shown to lead to (3.16), for $\rho = W$. Similarly, for a trial function of the form given by (3.17), minimization of the entire expression for the bound on $k \cot \eta_L$ can also readily be shown to lead to (3.16). The latter case includes the special case for which $_2\beta_{0L}$ is infinite.

C. $_{2}\beta_{0L}$ as Opposed to $\beta_{\theta L}$

In subsection C, we will restrict our attention to non-negative W(r) whose Lth phase shift is less than π . Further, we choose $\rho = W$ and trial functions of the form given by Eq. (3.17). As was shown in subsection B, for $\theta = 0$ normalization one can then simply replace β_{0L} by $_{2}\beta_{0L}$. We note that $_{2}\beta_{0L}$ is clearly larger than $\beta_{\theta L}$ for all θ including $\theta = 0$.

For $\theta = 0$ normalization, it is obviously preferable to use $_{2}\beta_{0L}$ rather than β_{0L} , since one has the same trial function in each case and $_2\beta_{0L}^{-1}$ is smaller than β_{0L}^{-1} , so that the upper bound on $\cot \bar{\eta}_L$ is reduced. The question which naturally arises, however, is whether one should use $\theta = 0$ and $_{2}\beta_{0L}$, or whether one should use say $\theta = \frac{1}{2}\pi$. In the latter case one would, in general, have to use $\beta_{\frac{1}{2}\pi, L}$, since for $\theta = \frac{1}{2}\pi$ one cannot in general solve for $\phi_{m'L}$ and one cannot therefore introduce $_{2\beta_{\frac{1}{2}\pi, L}}$. It is not immediately clear which is preferable, for while $_{2}\beta_{0L}$ is larger than $\beta_{\frac{1}{2}\pi, L}$, the trial functions have different normalizations, and further, in one case one bounds $\cot \bar{\eta}_L$ while in the other case one bounds $\cot(\bar{\eta}_L - \frac{1}{2}\pi)$. It turns out to be preferable to use $\theta = 0$ and $_{2}\beta_{0L}$ rather than $\theta = \frac{1}{2}\pi$ and $\beta_{\frac{1}{2}\pi, L}$. To see this let the upper and lower bounds on $k \cot \bar{\eta}_L$ as determined by Kato, Eq. (1.1), for $\theta = \frac{1}{2}\pi$ normalization, be denoted by B_u and B_l , respectively, and let B_U denote the upper bound as determined with the use of $_{2}\beta_{0L}$. Then

$$B_{U} = k \cot \eta_{L} - \int u_{0L} \mathcal{L}_{L} u_{0L} dr + {}_{2} \beta_{0L}^{-1} \epsilon_{0L}^{2}, \quad (3.19)$$

or

$$B_{U} = B_{u} - (k \cot \eta_{L} - B_{u})^{2} (B_{u})^{-1} - \epsilon_{0L^{2}} (\beta_{\frac{1}{2}\pi, L}^{-1} - {}_{2}\beta_{0L}^{-1}). \quad (3.20)$$

The use of $\theta = \frac{1}{2}\pi$ normalization is permissible only for $\bar{\eta}_L < \frac{1}{2}\pi$, in which case $k \cot \bar{\eta}_L$ (and therefore B_u) is greater than zero, so that B_U is in fact a better bound than B_u . While the difference between them is only of second order, this difference may well be significant for those difficult problems for which one cannot readily obtain a good trial function.

In order to get a feel for the reduction in the upper bound on $\cot \bar{\eta}_L$ that can be effected through the introduction of $_{2}\beta_{0L}$, as opposed to $\beta_{\frac{1}{2}\pi,L}$, we will consider a specific problem. It will first be necessary, however, to derive an explicit expression for $_{2}\beta_{0L}$.

For $0 \le \rho = W \le b/r^2$ and for $\bar{\eta}_L \le \theta < \pi$, conditions which have been assumed to be satisfied in this subsection, it was shown previously^{1,2} that

$$\beta_{\theta L} \ge 1 + b^{-1} (2 - 2\theta \pi^{-1}) (3 - 2\theta \pi^{-1} + 2L). \quad (3.21)$$

Under these circumstances, the evaluation of a bound

on ${}_{2}\beta_{0L}$ consists of the determination of that value of μ for which the *L*th phase shift associated with $[(1+\mu)b - L(L+1)]r^{-2}$ is $-\pi$. This corresponds to the case $\bar{\eta}_L < \theta$ with θ approaching zero, so that, from Eq. (3.21), if $0 \le \rho = W \le b/r^2$ and if $\bar{\eta}_L < \pi$,

$$_{2\beta_{0L}} \ge 1 + b^{-1}(6 + 4L).$$
 (3.22)

Consider now the evaluation of an upper bound on $\cot \bar{\eta}_0$ and hence of a lower bound on $\bar{\eta}_0$ for

$$W(r) = (2/a_0^2) [(a_0/r) + 1] \exp(-2r/a_0), \quad (3.23)$$

the "static hydrogen potential" analyzed by Kato. He showed that $W \leq 0.5871 r^{-2}$, and chose as his trial function

$$u_{00}(r) = \cos kr + \cot \eta_0 \sin kr - [1 + C_1(r/a_0)] \exp(-2r/a_0), \quad (3.24)$$

which is of the form of Eq. (3.17). If the trial function is simplified by setting $C_1=0$, it is found for k=0 with $\theta=\frac{1}{2}\pi$ normalization that $\gamma\equiv k \cot \eta_0=0.1250$ and that

$$k \cot \bar{\eta}_0 \leq 0.1096 = B_u$$

while $\theta = 0$ normalization and the use of $_{2}\beta_{00} = 11.22$ (as compared to $\beta_{\frac{1}{2}\pi, 0} = 4.407$) give

 $k \cot \bar{\eta}_0 \leq 0.1070 = B_U.$

It is known from Kato's work that for k=0

 $0.10560 \le k \cot \bar{\eta}_0 \le 0.10598.$

Taking the most unfavorable case, that is, assuming that $k \cot \bar{\eta}_0 = 0.01560$, we find that the difference between B_U and $k \cot \bar{\eta}_0$ is only *one-third* of the difference between B_u and $k \cot \bar{\eta}_0$ even though the calculations of B_U and B_u are essentially identical in that the trial functions differ only in normalization.

The values of B_u for the trial function given by (3.24), with C_1 and $\cot \eta_0$ adjustable, have been tabulated by Kato for a number of values of k. Since he also tabulates $\gamma = k \cot \eta_0$, and ϵ_{00}^2 , the values of B_U can be determined immediately from Eq. (3.20). [Normally, of course, one would determine B_U from Eq. (3.19).] As was noted above, the difference between B_U and B_u is of second order, and since we are now using a rather good trial function, the improvement in B_U over B_u is not so great. Even so, for the least

TABLE I. Comparison of upper bounds on $k \cot \overline{\eta}_0$. B_u is determined from Eq. (1.1), while the determination of B_U depends upon the introduction of $_{2}\beta_{00}$. B_l is a lower bound.

ka_0	B_l	B_u	B_U	
0	0.10560	0.10598	0.10592	
0.068	0.10917	0.10952	0.10947	
0.136	0.11982	0.12008	0.12004	
0.272	0.16186	0.16192	0.16191	
0.384	0.21629	0.21632	0.21632	
0.608	0.37414	0.37468	0.37455	
1.000	0.78278	0.78643	0.78564	

TABLE II. Error introduced by cutting off the potential. A comparison of the difference between the true phase shift, $\bar{\eta}_0$, and the phase shift for the cutoff potential, $\bar{\eta}_0^c$, for L=0 scattering by the potential given by Eq. (3.23), for the choices $\theta = \pi/2$ and $\theta = 0$, respectively. The latter choice is possible only with the introduction of $_2\beta_{00}$. The symbol a(-b) represents $a \times 10^{-b}$.

ka ₀	0	0.068	0.136	0.272	0.384	0.608	1.000
$ \begin{array}{c} \bar{\eta}_0 - \bar{\eta}_0{}^c, \ \theta = \pi/2 \\ \bar{\eta}_0 - \bar{\eta}_0{}^c, \ \theta = 0 \end{array} $	0 0	$1(-19) \\ 4(-40)$	$4(-10) \\ 4(-20)$	1(-6) 3(-10)	$2(-4) \\ 2(-7)$	$4(-3) \\ 4(-5)$	$3(-2) \\ 2(-3)$

favorable assumption as to the true value of $k \cot \bar{\eta}_0$, the improvement is about 15% and is somewhat larger, as one might expect, for the value $ka_0=1$ for which B_u-B_l is largest, that is, in the region for which the trial function is least adequate (see Table I).

D. Increase of the Cutoff Point, a

If $\bar{\eta}_0 < \theta < \pi$ and if W(r) vanishes for $kr > ka = \pi - \theta$, then $\beta_{\theta 0} = \infty$, and the calculation of an upper bound on $\cot(\bar{\eta}_0 - \theta)$ is essentially no more complicated than a standard variational calculation.⁵ If $\bar{\eta}_0 < \theta < \pi$ and if W(r) does not vanish but is non-negative for kr > ka $=\pi-\theta$, a lower bound on $\bar{\eta}_0$ is provided² by the determination of a lower bound on $\bar{\eta}_0^c$, the L=0 phase shift associated with $W^{c}(r)$, where $W^{c}(r)$ is simply W(r)but cut off at the point r=a. Since here too $\beta_{\theta 0} = \infty$, the calculation of a lower bound on $\bar{\eta}_0^{\circ}$ reduces to a variational calculation. Finally, if $\bar{\eta}_0 < \pi$ and if W(r) is non-negative for all r, we introduce $_{2}\beta_{00}$. With the choice $a = k^{-1}\pi$, which is considerably larger than $a = k^{-1}(\pi - \theta)$ for θ not too small, we have $_{2}\beta_{00} = \infty$; once again, the evaluation of a lower bound on $\bar{\eta}_0^c$ and hence on $\bar{\eta}_0$ reduces to a variational calculation.

For W(r) non-negative, it follows from the monotonicity theorem that an increase in the value of areduces the error introduced by cutting off W(r) at r=a, that is, reduces $\bar{\eta}_L - \bar{\eta}_L^c$. Qualitatively, it is clear that the reduction will be significant for an increase of a from $k^{-1}(\pi-\theta)$ to $k^{-1}\pi$ if W(r) for $k^{-1}(\pi-\theta) < r$ $< k^{-1}\pi$ is not yet small and if π is rather larger than $\pi-\theta$. In order to obtain a more quantitative idea of the reduction that might be expected, we will study a particular problem. The "potential" given by Eq. (3.23) will again be considered, for L=0. The exact expression for $\bar{\eta}_0 - \bar{\eta}_0^c$ is given by

$$k \tan(\bar{\eta}_0 - \bar{\eta}_0^\circ) = \int_a^\infty W \bar{u}_0 \bar{u}_0^\circ dr, \qquad (3.25)$$

where \bar{u}_0 and $\bar{u}_0{}^{e}$ are the exact "absolute normalization" solutions for W and W^{e} , respectively. If a is sufficiently large, then $\bar{\eta}_0 \approx \bar{\eta}_0{}^{e}$, $\bar{u}_0{}^{e} \approx \bar{u}_0 \approx \sin(kr + \bar{\eta}_0)$, and r can be replaced by a in the integrand except in the exponential. (The exponential is rapidly varying and $\bar{\eta}_0$ is not too close to a multiple of $\frac{1}{2}\pi$ for the values under

consideration.) Equation (3.25) becomes

$$\bar{\eta}_0 - \bar{\eta}_0^c \approx \sin^2(ka + \bar{\eta}_0) \lceil (ka)^{-1} + (ka_0)^{-1} \rceil \exp(-2a/a_0).$$

Since $\bar{\eta}_0 < \pi/2$ for all k for this "potential,"¹ it is permissible to set $\theta = \pi/2 = ka$ or, with the introduction of $_{2\beta_{00}}$, to set $\theta = 0$ and $ka = \pi$. Using the known values¹ of $\bar{\eta}_0$, one finds the results shown in Table II. It is clear that while either method is quite adequate for the values of ka_0 under consideration, accurate results can be obtained for somewhat larger values of ka_0 only with $\theta = 0$ normalization.

The advantage of cutting off W with $\theta = 0$ rather than $\theta = \frac{1}{2}\pi$ normalization, namely, the increase in a and the consequent reduction in $\overline{\eta}_L - \overline{\eta}_L^c$, is *not* offset by any increase in the complexity of the wave function or of the calculation. To see how the calculation proceeds for $\theta = 0$ normalization, consider for simplicity L=0. If $\overline{\eta}_0$ is less than π , we cut the potential off at $a = \pi k^{-1}$. For r > a, we must have an exact solution of the form

 $u_{00}(r) = \cot \eta_0 \sin kr + \cos kr,$

while for r < a we might for example choose

 $u_{00}(r) = \cot \eta_0 \sin kr - \sin \frac{1}{2}kr + \sum_n C_n \sin nkr.$

 $\cot \eta_0$ is arbitrary, but the C_n must satisfy

$$\sum_{n}(-1)^{n}C_{n}=0,$$

in order to satisfy continuity in slope and value. This trial function is relatively simple and, generally, should be expected to give reasonably accurate bounds without too much work.

As a concrete case, consider

$$W(r) = W_0 \exp(-r/r_0)$$

for $kr_0 = W_0 r_0^2 = 1$. The exact value of $\cot \bar{\eta}_0$, which follows from the known analytic solution, is 2.37. Comparison with the solvable Hulthèn potential shows¹ that $\bar{\eta}_0$ is less than $\frac{1}{2}\pi$, and we can therefore use the above trial function. If we simply set $C_n = 0$ for all n, variation of $\cot \eta_0$ leads to $\cot \bar{\eta}_0 \le \cot \bar{\eta}_0 \le 2.79$, while setting $C_2 = \frac{1}{2}C_1$ and $C_n = 0$ for n > 2 leads by variation of $\cot \eta_0$ and of C_1 to $\cot \bar{\eta}_0 \le \cot \bar{\eta}_0 \le 2.56$. Further improvement on the bound could of course be effected by the inclusion of more nonvanishing coefficients C_n .

E. $_{2}\mathcal{G}_{\theta L}$ Infinite While $\mathcal{G}_{\theta L}$ Finite

The cases treated thus far have specifically assumed that W(r) is non-negative and that it can be shown that the phase shift of the angular momentum under

⁵ See references 1 and 2. To generalize to $L \neq 0$, replace $-ka \equiv \overline{\eta}_0^{\infty}$ by $\overline{\eta}_L^{\infty} = \cot^{-1}[n_L(ka)/j_L(ka)]$, the *L*th phase shift for an infinitely repulsive square well of range *a*.

consideration is less than π . The following two examples will show that these are not inherent limitations of the method. These examples will at the same time show that, as was asserted previously, there are in fact cases for which $_{2}\beta_{\theta L}$ is infinite while $\beta_{\theta L}$ is finite.

Thus, assume again that W(r) is positive for $r \leq a$ and vanishes for r > a, but let it only be known that $\theta < \bar{\eta}_L < \pi + \theta$ and that $-\pi + \theta < \bar{\eta}_L^{\infty}$. For the choice $\rho = W$, $\beta_{\theta L}$ is finite and one cannot solve for $\phi_{m'L} = \phi_{0L}$ so that one cannot introduce $_2\beta_{\theta L}$, and the difficult second-order error integral would have to be evaluated. We can however choose $\rho = W - W^s$, where $W^s \ge 0$ is a square well (with range less than a) and where $W \ge W^s$. The associated differential equation introduced by Kato is readily solvable for $\mu = -1$, being simply the equation for a square well potential. For those cases for which it is possible to choose a W^s which satisfies $W^s \le W$ and for which the phase shift associated with W^s and therefore with the then known function ϕ_{0L} is θ , the choice of a trial function which satisfies

$$b_{m'L} = b_{0L} = k^{-1} \int \phi_{\theta L} \mathfrak{L}_L u_{\theta L} dr = 0$$

enables us to introduce ${}_{2}\beta_{\theta L}$, which is now infinite, thereby avoiding the difficult integration.

As an example of a case for which W(r) need not be non-negative, let the only condition on W(r) be that it vanish for r > a. Let it be known that $\theta - \pi$ $< \bar{\eta}_L < \theta$, and that

$$\theta - 2\pi < \bar{\eta}_L^{\infty} < \theta - \pi.$$

Choose $\rho = W + W^s$, where $W^s \ge 0$ is a square well of range $\le a$ such that $W + W^s \ge 0$. For those cases for which it is possible to choose W^s such that the *L*th phase shift associated with $(-W^s)$ is $\theta - \pi$, $\phi_{-1, L}$ is known, and if $u_{\theta L}$ is chosen such that

$$b_{m'L} = b_{-1,L} = k^{-1} \int \phi_{-1,L} \mathfrak{L}_L u_{\theta L} dr = 0,$$

we have ${}_{2}\beta_{\theta L} = \infty$. [If $W(r) \ge 0$, it will always be possible to choose such a W^{s} .]

Formally, one can impose two subsidiary conditions on the trial function, namely, $b_{m'L}=0$ and $b_{m'-1, L}=0$, and introduce $_{3}\beta_{\theta L}$. While this would be very useful, the subsidiary conditions can be satisfied only if one can determine both $\phi_{m'L}$ and $\phi_{m'-1, L}$, and this does not seem to be possible.

It will occasionally be useful to introduce ${}_{2}\alpha_{\theta L}$, the advantage being of the kind discussed in subsection C above. Unlike the case of ${}_{2}\beta_{\theta L}$, however, this will never produce the major improvement of eliminating the difficult second-order error integral for one can never have ${}_{2}\alpha_{\theta L} = \infty$.

4. PHASE-SHIFT INEQUALITIES

It is an unfortunate feature of the Kato formalism that a certain amount of (crude) information about $\bar{\eta}_L$ is required before one can proceed to the determination of close and useful bounds on $\cot(\bar{\eta}_L - \theta)$. (The information is essential to the evaluation of $\alpha_{\theta L}$ and $\beta_{\theta L}$. Roughly speaking, $\bar{\eta}_L$ must be known to within an interval of π .) This can be quite disturbing, for the Kato method is potentially most useful for precisely those very difficult problems for which one is not likely to have the requisite information, crude as that information need be. It is therefore satisfying to note that at least limited use can be made of the Kato formalism even when there is no such prior information; in particular, one will often be able to obtain a bound on $\bar{\eta}_L$ even when one cannot obtain a bound on $\cot(\bar{\eta}_L - \theta)$.

Assume, for example, that W(r) is non-negative, so that $\bar{\eta}_L \geq 0$. Kato showed then that if $\bar{\eta}_L < \pi$, one obtains

$$\cot \bar{\eta}_L \le \cot \eta_L(S), \tag{4.1}$$

where $\cot \eta_L(S)$ is the Schwinger variational expression defined by the right side of Eq. (2.1) and by Eq. (2.2). This definition of $\cot \eta_L(S)$ determines $\eta_L(S)$ only to within modulo π . We will choose $\eta_L(S)$ to lie between 0 and π ; it is then uniquely determined. If we know that $\bar{\eta}_L$ is less than π , Eq. (4.1) is valid and it then follows from our definition of $\eta_L(S)$ that $\bar{\eta}_L \geq \eta_L(S)$. But the point which we want to make is that this last relationship follows whether or not we know that $\bar{\eta}_L$ is less than π . To see this, we note that obviously, either $\bar{\eta}_L \geq \pi$ or $\bar{\eta}_L < \pi$. In the latter case, Eq. (4.1) is valid, and it follows that $\bar{\eta}_L \geq \eta_L(S)$. In the former case, it is certainly true that $\bar{\eta}_L \geq \eta_L(S)$. It therefore follows for $W(r) \geq 0$, without any prior knowledge of $\bar{\eta}_L$, that

$$\bar{\eta}_L \ge \eta_L(S). \tag{4.2}$$

On the other hand, one can *not* say that Eq. (4.1) is valid unless one knows that $\bar{\eta}_L < \pi$.

Equation (4.2) is in itself useless with regard to immediate application to a cross-section calculation, for it places no limit on $\sin \bar{\eta}_L$. However, it can be of interest in and of itself. Further, it raises the lower bound on $\bar{\eta}_L$ from 0 to $\eta_L(S)$, so that if one has some upper bound on $\bar{\eta}_L$, one may in fact have narrowed the range of possible values of $\bar{\eta}_L$ to a width less than π ; finally, if the width is still not less than π , it will be shown in Sec. 5 that a modified reapplication of the above technique will often enable one to raise the lower bound still more.

Equation (4.1) is a very special result of the Kato formalism, corresponding to $\theta=0$ normalization and essentially to a particular form of trial function. More generally, it follows for $W(r) \ge 0$, if $\bar{\eta}_L < \theta < \pi$, in which case the choice $\rho=W$ leads to $\beta_{\theta L} \ge 1$, that

$$k \cot(\bar{\eta}_L - \theta) \leq k \cot(\eta_L - \theta) - \int u_{\theta L} \mathfrak{L}_L u_{\theta L} dr + \int W^{-1} (\mathfrak{L}_L u_{\theta L})^2 dr. \quad (4.3)$$

Again, it may be possible to deduce a useful bound on $\bar{\eta}_L$ without the knowledge that $\bar{\eta}_L < \theta < \pi$, for either $\bar{\eta}_L \geq \theta$ or $\bar{\eta}_L < \theta$. In the latter case, Eq. (4.3) is valid, and since $-\pi < \bar{\eta}_L - \theta < 0$, we are led to a result of the form $\bar{\eta}_L - \theta \geq -B$, where $0 < B < \pi$. (This is a useful result only if B is less than θ , for we knew at the outset that $\bar{\eta}_L$ was positive.) If $\bar{\eta}_L$ is greater than θ , then certainly $\bar{\eta}_L \geq \theta - B$. We then have the general result for $W(r) \geq 0$, without any prior knowledge of $\bar{\eta}_L$, that

$$\bar{\eta}_L \geq \theta - B, \quad 0 < B < \pi,$$
(4.4)

where B is determined by setting $-k \cot B$ equal to the right side of Eq. (4.3). Again, while the consequence of Eq. (4.3), namely, Eq. (4.4), is in any event valid, Eq. (4.3) itself does *not* follow unless one knows that $\bar{\eta}_L < \theta$.

The above technique is clearly not restricted to the two special cases thus far considered. It is almost always possible to obtain a lower bound on the phase shift; one can, for example, compare the potential under consideration with a repulsive inverse square law potential. Provided that one can evaluate $\beta_{\theta L}$ if it is known that the phase shift lies within an interval θ of the lower bound, where θ is less than π , one can use this value of $\beta_{\theta L}$ in an attempt to raise the lower bound without the knowledge that the phase shift lies within the interval. If the lower bound can be raised in this manner, one can then proceed anew from the improved lower bound. Of course, at each step it must be possible to evaluate $\beta_{\theta L}$ under the assumption, which need not be true, that the phase shift lies within an interval θ of the new lower bound.

5. ITERATIVE PROCEDURE

To examine the iterative procedure in more detail, and to develop it further, we consider again the case $W(r) \ge 0$. It is then of course true that $\bar{\eta}_L \ge \eta_L^{(0)} \equiv 0$. We can, however, do much better. In particular, it was shown in Sec. 4 that one can deduce from the Kato method a bound of the form $\bar{\eta}_L \ge \eta_L^{(1)}$, where $0 < \eta_L^{(1)} < \pi$. [For $\theta = 0$, $\eta_L^{(1)}$ was the Schwinger phase shift $\eta_L(S)$.] It will be the purpose of the present section to raise still higher the lower bound on $\bar{\eta}_L$. In order to do so, it will be necessary to digress for a moment; we will find bounds on $\delta_L(\mu)$ for all $\mu \ge -1$.

For $\rho = W$, $\delta_L(\mu)$ is simply the *L*th phase shift associated with $(1+\mu)W$. It is then of course true that

$$\delta_L(\mu) \ge \delta_L^{(0)}(\mu) \equiv 0, \quad \mu \ge -1;$$
 (5.1)

the more significant point is that this bound can be raised for arbitrary $\mu \ge -1$ exactly as was done in Sec. 4 for $\mu=0$. [It will be recalled that $\bar{\eta}_L = \delta_L(0)$.] In particular, if we think of $(1+\mu)W$ rather than W as the "potential," and if we choose $\rho = (1+\mu)W$, we have for $\theta=0$

$$k \cot \delta_{L}(\mu) \leq k \cot \delta_{tL}(\mu) - \int u_{0L}(\mathcal{L}_{L} + \mu W) u_{0L} dr$$
$$+ \int [(1+\mu)W]^{-1} [(\mathcal{L}_{L} + \mu W) u_{0L}]^{2} dr \bigg\}. \quad (5.2)$$

We now define $\delta_L^{(1)}(\mu)$ by setting $k \cot \delta_L^{(1)}$ equal to the right side of (5.2) and choosing that solution for $\delta_L^{(1)}(\mu)$ which lies between 0 and π . We then have

$$\delta_L(\mu) \ge \delta_L^{(1)}(\mu). \tag{5.3}$$

The trial function u_{0L} in (5.2) satisfies the usual boundary conditions but is a function of μ as well as of r, while $\delta_{iL}(\mu)$ is the trial *L*th phase shift associated with $(1+\mu)W$ and is determined by the choice of u_{0L} . The curly brackets around (5.2) signify that while (5.2), which involves $\cot \bar{\eta}_L$, may or may not be valid, the bound on $\bar{\eta}_L$ itself deduced from (5.2) and stated in (5.3) *is* nevertheless valid. [The condition for the validity of (5.2) for any specified value of μ is obviously that $\delta_L(\mu)$ be less than π , and we do not know if this is the case.] The curly bracket notation will be adhered to from now on; a bound surrounded by curly brackets will be referred to as a "conditional bound."

We now have a lower bound, $\delta_L^{(1)}(\mu) \ge 0$, on $\delta_L(\mu)$ for all $\mu \ge -1$. If $\bar{\eta}_L = \delta_L(0)$ is greater than $\frac{1}{2}\pi$, it will often be possible to determine a negative value of μ , to be called $\mu_{\frac{1}{2}\pi}$, L, for which

$$\delta_L^{(1)}(\mu_{\frac{1}{2}\pi, L}) = \frac{1}{2}\pi. \tag{5.4}$$

(The value $\frac{1}{2}\pi$ is a convenient but not necessary choice, as will be seen shortly.) We consider a case for which such a μ can be found. With $\theta' = \frac{1}{2}\pi$ normalization, it follows, since $\bar{\eta}_L$ is now known to be greater than $\frac{1}{2}\pi$, that

$$\beta_{\frac{1}{2}\pi, L} \ge -\mu_{\frac{1}{2}\pi, L}, \quad \text{if} \quad \bar{\eta}_L < \frac{3}{2}\pi.$$
 (5.5)

But this is exactly the type of relationship which is required in order to utilize the results of Sec. 4 and therby improve the lower bound on $\bar{\eta}_L$ (see Fig. 2). [The sole purpose in deducing bounds on $\delta_L(\mu)$ was to obtain (5.5).] In particular, we have from Sec. 4 and Eq. (5.5)

$$\left\{-k \tan \bar{\eta}_L \leq -k \tan \eta_L - \int u_{\frac{1}{2}\pi, L} \mathfrak{L}_L u_{\frac{1}{2}\pi, L} dr + (-\mu_{\frac{1}{2}\pi, L})^{-1} \int W^{-1} (\mathfrak{L}_L u_{\frac{1}{2}\pi, L})^2 dr \right\}, \quad (5.6)$$

and

 $\bar{\eta}_L \ge \eta_L^{(2)}; \tag{5.7}$

 $\eta_L^{(2)}$ is determined by setting $-k \tan \eta_L^{(2)}$ equal to the right side of (5.6) and choosing that solution for $\eta_L^{(2)}$ which lies between $\frac{1}{2}\pi$ and $\frac{3}{2}\pi$. Equation (5.6) is guaranteed to be valid only if $\bar{\eta}_L$ is less than $\frac{3}{2}\pi$, but Eq. (5.7) is valid whether or not this is the case.



FIG. 2. A schematic representation of the iterative procedure for raising the lower bound on $\bar{\eta}_L$. The sequence of curves $\delta_L^{(0)}(\mu)$, $\delta_L^{(1)}(\mu)$, etc., represent successively better lower bounds on $\delta_L(\mu)$. The bound on $\bar{\eta}_L$ is determined from the relationship $\bar{\eta}_L = \delta_L(0)$.

As a concrete example, consider L=0 scattering by

$$W(r) = W_0 \exp(-r/r_0).$$

With $\theta = 0$, and with the choice

$$u_{00}(\mu,r) = \cos kr + \cot \delta_{t0}(\mu) \sin kr - y(\mu,r),$$

where $y(\mu,0)=0$ and where $y(\mu,r)\rightarrow 0$ as $r\rightarrow\infty$, Eq. (5.2) reduces to

$$\begin{cases} k \cot \delta_0(\mu) \leq -\int (y'^2 - k^2 y^2) dr \\ + \int [(1+\mu)W]^{-1} (y'' + k^2 y)^2 dr \end{cases}.$$

Choosing

$$y(\mu,r) = [1+C(r/r_0)+D(r/r_0)^2] \exp(-r/r_0),$$

where C and D can be functions of μ , we find, for $kr_0 \rightarrow 0$,

$$\{ kr_0 \operatorname{cot\delta}_0(\mu) \leq f(C,D) \langle 1 - g(C,D) \\ \times [(1+\mu)W_0r_0^2]^{-1} \rangle \},$$
 (5.8) where

$$f(C,D) = -\frac{1}{4}(2 - 2C + C^2 - 2D + D^2 + CD), \quad (5.9)$$

and where

$$g(C,D) = -(1 - 2C + 2C^2 + 4D^2)/f(C,D). \quad (5.10)$$

It follows from Eqs. (5.3) and (5.4) that $\mu_{\frac{1}{2}\pi,0}$ is that value of μ for which the right side of Eq. (5.8) vanishes. (It is the fact that the right side then vanishes which is the convenience, mentioned earlier, associated with the choice $\theta = \frac{1}{2}\pi$.) From Eqs. (5.5) and (5.8), we then find

$$\beta_{\frac{1}{2}\pi, 0} \ge -\mu_{\frac{1}{2}\pi, 0} = 1 - 1.456 (W_0 r_0^2)^{-1},$$
 (5.11)

where 1.456 was obtained by maximizing g(C,D), defined by Eqs. (5.9) and (5.10). Equation (5.11) has meaning only if $\beta_{\frac{1}{2}\pi,0}$ is greater than 0, that is, only if $W_0r_0^2 > 1.456$.

We now fix our attention upon the particular numerical value $W_0 r_0^2 = 25/4$. The exact solution for $kr_0 \rightarrow 0$ is then⁶ $\bar{\eta}_0 \rightarrow \pi + 2.470 \ kr_0$, so that $\tan \bar{\eta}_0/(kr_0)$ $\rightarrow 2.470$. Equation (5.11) gives $\beta_{\frac{1}{2}\pi,0} \geq 0.76704$. [The exact value of $\beta_{\frac{1}{2}\pi,0}$, which in this case is that value of β for which the phase shift associated with $(1-\beta)W_0$ is $\frac{1}{2}\pi$, is 0.7686.] Note, incidentally, that we now know that $\bar{\eta}_0 = \delta_0(0) > \delta_0(\mu_{\frac{1}{2}\pi,0}) \geq \frac{1}{2}\pi$. We take a trial function of the form used for example by Huang,⁷ but with $kr_0 \rightarrow 0$, and normalized to $\theta = \frac{1}{2}\pi$, that is,

$$(-kr_0)^{-1}u_{\frac{1}{2}\pi, 0} = X + C_1 - (C_1 + C_2 X + C_3 X^2 + C_4) \\ \times \exp(-X) + C_4 \exp(-2X), \quad (5.12)$$

where $X=r/r_0$, and where C_1 is to be thought of as $(1/kr_0)$ times the tangent of the trial phase shift. This trial function was used in Eq. (5.6), first neglecting and then including the $-1/\mu_{\frac{1}{2}\pi,0}$ term, that is, in an ordinary variational calculation, and in a calculation which gives a conditional lower bound on $\tan \bar{\eta}_0/(kr_0)$. The bound is conditional because we proved that $\bar{\eta}_0$ was greater than $\frac{1}{2}\pi$, but simply assumed that $\bar{\eta}_0$ was less than $\frac{3}{2}\pi$. The bound deduced on $\bar{\eta}_0$ is of course nevertheless guaranteed to be correct.

The coefficients in the calculation of the bound were determined by minimizing the entire expression for the bound rather than by minimizing ϵ^2 . There is no point to the latter procedure here, for it is not any simpler than the former and must give a poorer bound on $\tan \bar{\eta}_0/(kr_0)$. Further, that procedure negates one of the very pleasant features associated with the appropriate use of the Kato formalism; in particular, if one minimizes the entire expression for the bound, the inclusion of more parameters in the trial function can only improve the bound, while if one minimizes ϵ^2 , the inclusion of more parameters may make the bound worse. (The situation in the latter case is then of the same nature as that of the usual variational calculation.) Of course, one might still minimize ϵ^2 if one were primarily interested in an accurate wave function rather than in an accurate bound.

The results, shown in Table III, are about as might be expected. Since the true value of $\bar{\eta}_0$ is greater than π , a number of coefficients are required even for the variational calculation to give accurate results; the bound, arising from a rigorous expression, is rather conservative. (On the other hand, for somewhat smaller values of $W_0 r_0^2$, quite accurate results are obtained for the bound as well as for the variational

⁶ P. M. Morse and H. Feshbach, *Methods of Theoretical Physics* (McGraw-Hill Book Company, Inc., New York, 1953), p. 1688. Note, however, that they are not concerned with multiples of π , while we are.

⁷ S. Huang, Phys. Rev. 76, 1878 (1949).

TABLE III. Variational calculation of $\tan \bar{\eta}_0$ and calculation of bound on $\bar{\eta}_0$. Scattering by $W(r) = W_0 \exp(-r/r_0)$ for L=0, $kr_0 \to 0$, $W\sigma r_0^2 = 25/4$. The trial function is given in Eq. (5.11). The calculation does not use *any* solvable comparison potentials. The coefficients C_1 through C_4 for cases (b) through (e) were calculated from the Kato variational principle with $\theta = \pi/2$; this is precisely the Kohn variational principle. The coefficients for cases (f) through (i) were chosen by minimizing the bound. The true values are $\tan \bar{\eta}_0/(kr_0) \to 2.470$ and $(\bar{\eta}_0 - \pi)/(kr_0) \to 2.470$.

(1)	(2)	(3)	(4)	(5)	(6) Variational	(7) Lower	(8)
Case	C_1	C_2 and	C_3	<i>C</i> 4	$\tan \overline{\eta}_0/(kr_0)$	$(\bar{\eta}_0 - \pi)/(kr_0)$	$\epsilon^{2} \frac{1}{2} \pi_{,0} / (k^{2} r_{0}^{2})$
(a)	• • •		• • •	• • •	+12.500	-3.7964	+12.500
(b)	-2.9603				-1.377		
(c)	+0.72659	+9.4581			+1.147		
(d)	+2.3834	+10.041	+2.6548		+1.761		
(e)	+2.2944	+35.178	-4.8426	-26.281	+2.45		
(f)	-3.1886					-3.4140	+1.6252
(g)	+16.122	+10.324				-0.835	+276.68
(h)	+10.772	+8.2011	+0.76605			-0.651	+125.96
(i)	+1.0480	+28.541	-2.9300	-20.715		+2.08	+1.26

result with three or even two parameters in the trial function.)

The only rigorous statement that follows from the calculations is that $\bar{\eta}_0$ is greater than $\pi + 2.08kr_0$. In practice, however, the four-parameter calculations show, through the fair degree of consistency of the four values of C_1 , C_1 , the variational value of $\tan \bar{\eta}_0/(kr_0)$ and the bound on $\tan \bar{\eta}_0/(kr_0)$, and through the smallness of ϵ^2 , that in fact one could be fairly certain that the true value of $\tan \bar{\eta}_0/(kr_0)$ or $(\bar{\eta}_0 - \pi)/(kr_0)$ is close to 2.45, the variational estimate. This would be the case even if we could not obtain some supper bound on $\bar{\eta}_0$.

From the point of view of this section, however, the most interesting result of these calculations is that it has been possible to raise the lower bound significantly, in particular above π , without recourse to a knowledge of the phase shifts associated with *any* other potential. In effect, we have used as our comparison potential

the potential under consideration, but with varying strength.

In principle, one can introduce $\delta_L^{(2)}(\mu)$ and higher curves, but in practice this would probably not be a reasonable procedure.

The discussion of Secs. 4 and 5 can also be immediately applied to the case in which one has an upper bound on $\bar{\eta}_L$ and $\alpha_{\theta L}$ is determinable under the assumption that $\bar{\eta}_L$ lies within an interval θ of this upper bound, where θ is less than π .

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